# Supplementary Material: Minimum Volume Multi-Task Learning

Bo Liu\* Ji Liu<sup>†</sup> Sridhar Mahadevan<sup>‡</sup> Yong Ge<sup>§</sup> Deguang Kong<sup>¶</sup>

First we define the operators necessary for the theoretical analysis.

## 1 Operators

**Definition 1**: (Operator P) Given a matrix  $\Gamma \in \mathbb{R}^{m \times n}$  with the following representation

$$\Gamma = U \left[ \begin{array}{cc} \Gamma_{11} & \Gamma_{12} \\ \Gamma_{21} & \Gamma_{22} \end{array} \right] V^T,$$

where  $U \in \mathbb{R}^{m \times m}$ ,  $V \in \mathbb{R}^{n \times n}$  are two orthonormal matrix, define the operator  $(P, P_c)$  pair as follows

$$\begin{split} & \Gamma_1 & := & \mathbf{P}(\Gamma) = U \left[ \begin{array}{cc} \Gamma_{11} & \Gamma_{12} \\ \Gamma_{21} & 0 \end{array} \right] V^T \\ & \Gamma_2 & := & \mathbf{P_c}(\Gamma) = U \left[ \begin{array}{cc} 0 & 0 \\ 0 & \Gamma_{22} \end{array} \right] V^T \end{split}$$

**Lemma 1**: Given an arbitrary matrix pair  $(\Phi, \Gamma) \in \mathbb{R}^{m \times n}$  with rank $(\Phi) = r$ , and the SVD of  $\Phi$  is

$$\Phi = U \left[ \begin{array}{cc} \Sigma & 0 \\ 0 & 0 \end{array} \right] V^T,$$

where  $\Sigma$  is the diagonal matrix where the diagonal elements are the non-zero singular values of  $\Phi$ . Let  $\Gamma \in \mathbb{R}^{m \times n}$  represented as

$$\Gamma = U \left[ \begin{array}{cc} \Gamma_{11} & \Gamma_{12} \\ \Gamma_{21} & \Gamma_{22} \end{array} \right] V^T,$$

where  $\Gamma_{11} \in \mathbb{R}^{r \times r}$ ,  $\Gamma_{12} \in \mathbb{R}^{(m-r) \times r}$ ,  $\Gamma_{21} \in \mathbb{R}^{r \times (n-r)}$ ,  $\Gamma_{22} \in \mathbb{R}^{(m-r) \times (n-r)}$ , and for  $\Gamma_{1} := P(\Gamma), \Gamma_{2} := P_{c}(\Gamma)$ , the following hold for  $\Gamma_{1}, \Gamma_{2}$  respectively:

1. For 
$$\Gamma_1$$
, rank $(\Gamma_1) \leq 2r$ ,  $\Phi \Gamma_2^T = 0$ ,  $\Phi^T \Gamma_2 = 0$ 

- 2. For  $\Gamma_2$ , there is additive relation of the trace norm of  $(\Phi, \Gamma_2)$  pair as  $||\Phi + \Gamma_2||_* = ||\Phi||_* + ||\Gamma_2||_*$
- 3. for the matrix pair  $(\Phi, \Gamma) \in \mathbb{R}^{m \times n}$ , there is  $||\Gamma||_* + ||\Phi||_* ||\Phi + \Gamma||_* \le 2||\Gamma_1||_*$

**Definition 2**: (Operator Q) Given a matrix  $\Gamma \in \mathbb{R}^{m \times n}$ ,  $Q(\Gamma)$  is defined as

$$Q(\Gamma) = \Gamma(:, s_i), s_i = \{i | \forall j, \Gamma[j, i] \neq 0\}$$

namely,  $Q(\Gamma)$  is composed of the nonzero columns of  $\Gamma$ , and thus Q is used to extract the nonzero columns of a matrix. Q has the following property.

**Lemma 2**[1]: Given an arbitrary matrix pair  $(\Psi, \Lambda) \in \mathbb{R}^{m \times n}$ , there is

$$||\Psi||_{2,1} + ||\Lambda||_{2,1} - ||\Psi + \Lambda||_{2,1} \le ||Q(\Psi)||_{2,1}$$

We then present Assumption 1, which is the foundation of later theoretical analysis. We will denote our solution W by the pair (U, V), where in Algorithm 1, W = U = V, and in Algorithm 2, W = U + V.

**Assumption 1:** For the solution (U, V) pair, and a constant pair p, q satisfying  $p \leq \min(T, d), q \leq T$ , there exists a constant pair  $(\kappa(p), \tau(q))$  such that

(1.1) 
$$\kappa(p) = \min_{U,V \in \mathcal{R}(p,q)} \frac{||L(U+V)||_F}{\sqrt{N}||P(U)||_*} > 0$$
$$\tau(q) = \min_{U,V \in \mathcal{R}(p,q)} \frac{||L(U+V)||_F}{\sqrt{N}||Q(V)||_{2,1}} > 0$$

where the restricted set  $\mathcal{R}(p,q)$  is defined as (1.2)

$$\mathcal{R}(p,q) = \{U, V | 0 < \text{rank}(P(U) \le p, 0 < |Q(V)| \le q\}$$

### 2 Matrix Inversion

To cache the factorization for speeding up computation, we use the matrix inversion lemma stated as follows (2.3)

$$(P + \rho A^T A)^{-1} = P^{-1} - \rho P^{-1} A^T (I + \rho A P^{-1} A^T)^{-1} A P^{-1}$$

In our computation, as in Algorithm 1,  $\left(\rho_1 D^2 + \rho_3 \mathbf{I}\right)^{-1}$  and  $\left(\frac{1}{Tn_i} X_i^T X_i + (\rho_2 + \rho_3) I\right)^{-1}$  can be computed likewise, and in Algorithm 2,  $\left(\rho_1 D^2 + \rho_2 \mathbf{I}\right)^{-1}$  and  $\left(\frac{1}{Tn_i} X_i^T X_i + \rho_2 I\right)^{-1}$  can be computed likewise.

<sup>\*</sup>School of Computer Science, University of Massachusetts, boliu@cs.umass.edu

<sup>&</sup>lt;sup>†</sup>Department of Computer Sciences, University of Rochester, jliu@cs.rochester.edu

 $<sup>^{\</sup>ddagger}$  School of Computer Science, University of Massachusetts, mahadeva@cs.umass.edu

<sup>§</sup>Department of Computer Science, University of North Carolina at Charlotte, yong.ge@uncc.edu

<sup>¶</sup>Samsung Research America, San Jose, CA, 95134, doogkong@gmail.com

#### 3 Measurements

nMSE, aMSE, WMSE and WRSE are defined as follows,

WMSE = 
$$\frac{1}{T} \sum_{i=1}^{T} \frac{1}{n_i} \sum_{j=1}^{n_i} (y_{i,j} - x_{i,j} W_i)^2$$
  
WRSE =  $\frac{1}{N} \sum_{i=1}^{T} \left( n_i \sqrt{\sum_{j=1}^{n_i} (y_{i,j} - x_{i,j} W_i)^2} \right)$   
nMSE =  $\frac{1}{T} \sum_{i=1}^{T} \frac{1}{\text{var}(y_i) n_i} \sum_{j=1}^{n_i} (y_{i,j} - x_{i,j} W_i)^2$   
 $a$ MSE =  $\frac{1}{T} \sum_{i=1}^{T} \frac{1}{||y_i||_2^2 n_i} \sum_{j=1}^{n_i} (y_{i,j} - x_{i,j} W_i)^2$   
(3.4)

where for (data, label) pair  $(X_i, Y_i)$  of the *i*-th task,  $x_{i,j}$  is the *j*-th row of  $X_i$ , and  $y_{i,j}$  is the *j*-th entry of  $Y_i$ .

### References

[1] Jianhui Chen, Jiayu Zhou, and Jieping Ye. Integrating low-rank and group-sparse structures for robust multitask learning. In *KDD*, pages 42–50, 2011.