

MAT4220 FA22 HW09

Haoran Sun (haoransun@link.cuhk.edu.cn)

Problem 1 (P197 Q11).

- (a) Easy to verify that (18) satisfies $\Delta G = 0$ except at $\mathbf{x} = \mathbf{x}_0$, $G(\mathbf{x})|_{\partial D} = 0$, $G(\mathbf{x}) - \log |\mathbf{x} - \mathbf{x}_0|/2\pi$ finite at \mathbf{x}_0 .
- (b) Note that

$$\nabla G = \frac{1}{2\pi} \frac{1}{\rho} (\mathbf{x} - \mathbf{x}_0) - \frac{1}{2\pi} \frac{1}{\rho^*} (\mathbf{x} - \mathbf{x}_0^*)$$

Since $\mathbf{n} = \mathbf{x}/|\mathbf{x}|$, we have

$$\begin{aligned} \nabla G \cdot \mathbf{n} &= \frac{1}{2\pi} \frac{1}{\rho} (a - r_0 \cos \phi) - \frac{1}{2\pi} \frac{1}{\rho^*} (a - r_0^* \cos \phi) \\ &= \frac{1}{2\pi} \frac{a - r_0 a \cos \phi}{a^2 + r_0^2 - 2ar_0 \cos \phi} - \frac{1}{2\pi} \frac{a - \frac{a^2}{r_0} \cos \phi}{a^2 + \frac{a^4}{r_0^2} - 2\frac{a^3}{r_0} \cos \phi} \\ &= \frac{1}{2\pi} \frac{1}{a} \frac{a^2 - r_0 a \cos \phi - r_0^2 + r_0 a \cos \phi}{a^2 + r_0^2 - 2ar_0 \cos \phi} \\ &= \frac{a^2 - r_0^2}{2\pi a} \frac{1}{a^2 + r_0^2 - 2ar_0 \cos \phi} \end{aligned}$$

Therefore we have proved Poisson's formula since

$$u(\mathbf{x}_0) = \frac{a^2 - r_0^2}{2\pi a} \iint_{\partial D} d\sigma u(\mathbf{x}) \frac{\partial}{\partial \mathbf{n}} G(\mathbf{x}, \mathbf{x}_0) = \frac{a^2 - r_0^2}{2\pi a} \iint_{\partial D} d\sigma \frac{u(\mathbf{x})}{a^2 + r_0^2 - 2ar_0 \cos \phi}$$

Problem 2 (P197 Q13). The Green's function for the whole ball is

$$G(\mathbf{x}, \mathbf{x}_0) = -\frac{1}{2\pi\rho} + \frac{a}{|\mathbf{x}_0|} \frac{1}{4\pi\rho^*}$$

Reflect the green's function wrt xy plane, we have

$$G(\mathbf{x}, \mathbf{x}_0) = -\frac{1}{4\pi\rho} + \frac{a}{|\mathbf{x}_0|} \frac{1}{4\pi\rho^*} + \frac{1}{4\pi\rho_z} - \frac{a}{|\mathbf{x}_0|} \frac{1}{4\pi\rho_z^*}$$

where

$$\rho = |\mathbf{x} - \mathbf{x}_0| \quad \rho^* = |\mathbf{x} - \mathbf{x}_0^*| \quad \rho_z = |\mathbf{x} - \mathbf{x}_{0z}| \quad \rho_z^* = |\mathbf{x} - \mathbf{x}_{0z}^*|$$

where $x_0^* = a^2 \mathbf{x}_0 / |\mathbf{x}_0|^2$, and \mathbf{x}_{0z} is the reflection of \mathbf{x}_0 wrt xy plane, \mathbf{x}_{0z}^* is the reflection of \mathbf{x}_0^* wrt xy plane.

Problem 3 (P337 Q1). Easy to prove the linearity. To prove the continuity, since f integrable on Ω , then $\forall \phi_N \rightarrow \phi$, $\phi_N \in C^\infty(\Omega)$ compactly supported, let $F = |\langle f, 1 \rangle|$ on Ω (since $|f|$ also integrable), then $\forall \epsilon > 0$, $\exists N \in \mathbb{N}$ s.t. $\forall n > N$, we have $|\phi_N(x) - \phi(x)| < \epsilon/F$, and hence

$$\begin{aligned} |\langle f, \phi_n \rangle - \langle f, \phi \rangle| &= \left| \int_{\Omega} dx f(x) [\phi_n(x) - \phi(x)] \right| \\ &< \int_{\Omega} dx |f(x)| \frac{\epsilon}{F} = \epsilon \end{aligned}$$

which means the map is continuous.

Problem 4 (P337 Q2). *Linearity:* direct prove by definition

$$\begin{aligned}\langle f', a\phi + b\psi \rangle &= -\langle f, a\phi' + b\psi' \rangle = -\int_{\Omega} dx f(x)(a\phi'(x) + b\psi'(x)) = -a\langle f, \phi' \rangle - b\langle f, \psi' \rangle \\ &= a\langle f', \phi \rangle + b\langle f', \psi \rangle\end{aligned}$$

Continuity: since $\phi_N \rightarrow \phi$ uniformly and $\phi_N \in C^\infty(\Omega)$ compactly supported, then $\phi'_N \rightarrow \phi'$ uniformly and $\phi'_N \in C^\infty(\Omega)$ compactly supported, hence

$$\langle f, \phi'_N \rangle \rightarrow \langle f, \phi' \rangle \Rightarrow \langle f', \phi_N \rangle \rightarrow \langle f', \phi \rangle$$

Problem 5 (P337 Q5).

Claim. $-c\langle H_x, \phi \rangle = \langle H_t, \phi \rangle$.

Proof. Since

$$\begin{aligned}\langle H_x, \phi \rangle &= -\iint_{\Omega} dx dt H(x-ct)\phi_x(x,t) = -\int_0^\infty dt \int_{ct}^\infty dx \phi_x(x,t) = \int_0^\infty dt \phi(ct,t) \\ \langle H_t, \phi \rangle &= -\iint_{\Omega} dx dt H(x-ct)\phi_t(x,t) = -\int_0^\infty dx \int_0^{x/c} dt \phi_t(x,t) = -\int_0^\infty dx \phi(x,x/c) \\ &= -c \int_0^\infty du \phi(cu,u)\end{aligned}$$

Hence $c\langle H_x, \phi \rangle = \langle H_t, \phi \rangle$. □

Therefore

$$\begin{aligned}c^2\langle H_{xx}, \phi \rangle &= -c^2\langle H_x, \phi_x \rangle = c\langle H_t, \phi_x \rangle = -c\langle H, \phi_{xt} \rangle \\ \langle H_{tt}, \phi \rangle &= -\langle H_t, \phi_t \rangle = c\langle H_x, \phi_t \rangle = -c\langle H, \phi_{tx} \rangle\end{aligned}$$

Therefore we have $\langle H_{tt}, \phi \rangle = c^2\langle H_{xx}, \phi \rangle$, which means that $H(x-ct)$ is a weak solution.