Leg Angular Kinematics 400 350 Angle (Degrees) 300 250 200 150 100 50 0.2 0.4 0.6 0.8 1.0 1.0 Joint 0 0.5 Speed $\frac{rev}{sec}$ Joint 1 0.0 Joint 2 -0.5Joint 3 -1.0 $\underbrace{}_{0.0}$ 0.2 0.6 0.8 0.4 1.0 10 Acceleration $\frac{rev}{sec^2}$ 8 -6 ∟ 0.0 0.2 0.4 0.6 0.8 1.0 time (s)