# HAOTIAN HANG

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#### PERSONAL INFO

Birth Year: 1997 Address: 1247 W 30 St, Los Angeles, CA 90007

Citizenship: People's Republic of China Mobile: (213)462-5919 E-mail: haotianh@usc.edu Webpage: Personal Website

Social media: Github LinkedIn ResearchGate Google Scholar

#### **EDUCATION**

2020 - University of Southern California, Los Angeles, CA

Ph.D. Student, Mechanical Engineering

Master of Science, Mechanical Engineering, December 2021

2015 - 2019 Shanghai Jiao Tong University, Shanghai, China

B.S. Aeronautics and Astronautics Engineering, June 2019 (Average Score: 89.22/100)

## **EMPLOYMENT**

2020 - Research Assistant, Bio-Inspired Motion Lab at USC, PI: Prof. Eva Kanso

2019 Intern Algorithmic Engineer, Shanghai Hongpu Information Technology Co., Ltd.

Conduct flaw detection on images of photovoltaic cell using Faster R-CNN and yolov3

2016 - 2019 Research Assistant, J.C.Wu Center for Aerodynamics, PI: Prof. Hong Liu

#### **PUBLICATIONS**

3. Hang, H., Heydari, S., Costello, J., & Kanso, E. (2022). Active tail flexion in concert with passive hydrodynamic forces improves swimming speed and efficiency. Journal of Fluid Mechanics, 932, A35.

2021 2. Xiang, Y., Hang, H., Qin, S., and Liu, H. (2021). Scaling analysis of the circulation growth of leading-edge vortex in flapping flight. Acta Mech. Sin.

 Hang, H., Yu, B., Xiang, Y., Zhang, B., and Liu, H. (2020). An objective-adaptive refinement criterion based on modified ridge extraction method for finite-time Lyapunov exponent (FTLE) calculation. Journal of Visualization, 23(1), 81-95.

# TALKS/PRESENTATIONS

2022 So Cal Fluids XV, Learning to blindly follow hydrodynamic trails

APS Division of Fluid Dynamics Meeting, Active tail flexion in concert with passive hydrodynamic forces improves swimming speed and efficiency

2020 APS Division of Fluid Dynamics Meeting, Flowtaxis in the wakes of oscillating airfoils

2018 **APS Division of Fluid Dynamics Meeting**, Passive rotation of a flapping wing with an inhomogeneous mass distribution

#### RESEARCH INTERESTS/EXPERIENCE

2020 - Learning to blindly follow hydrodynamic trails, supervised by *Prof. Eva Kanso* 

joint with Sina Heydari, Yusheng Jiao

Employ reinforcement learning to follow vortical wakes based on local flow sensory

Find traveling wave characteristic of wakes is important for source seeking and our controller is stable in locating source

Compare performance between mechano- and chemo- sensing, and different sensory cues

2020 - Flexion in fish swimming, supervised by Prof. Eva Kanso, Prof. John H. Costello

joint with Sina Heydari

Analyze the role of active and passive flexion on swimming speed and efficiency of a self-propelling pitching plate using vortex sheet method

Parametric study on effects of flexion phase, flexion angle and flexion ratio on swimming performance

2016 - 2019 Mechanisms of high generation in insects flight, supervised by Prof. Hong Liu Dr. Yang Xiang

and Dr. Suyang Qing

Conduct experimental study using robotic flapping wing models in glycerin with Reynolds number similar to insects

Measure flow field using particle image velocimetry (PIV) and measure force and torque using 6-axis force sensor, analogue filter and NI data acquisition system

Study difference in formation of leading edge vortex(LEV) for different kinematic modes, and find advanced rotation can generate a lager LEV because of wake capture

Find a scaling law between passive rotation and active translation in flapping wing model

2016 - 2019 AMR for FTLE calculation, supervised by Prof. Hong Liu, Prof. Bin Zhang, Bin Yu and Dr. Yang Xiang

Develop a physics-based adaptive refinement method for finite-time Lyapunov exponent calculation

2015 - 2016 **VTOL pitch-changed quadrotor**, supported by National Students' Platform for Innovation and Entrepreneurship Training, supervised by *Prof. Junqi Wu* 

joint with Dongming Ding, Jihong Huang, Chaogun Li, Zhikang Qiu

Lead a team to make a quad rotor and fulfilled of pitch-changed technique and VTOL technique in terms of both mechanical and control

#### TEACHING EXPERIENCE

at University of Southern California

2021 Spring Teaching Assistant, AME-526, Introduction to mathematical methods in engineering II, Prof. Niema

Pahlevan

2020 Fall **Teaching Assistant**, AME-404, Computational Solutions to Engineering Problems, *Prof. Takahiro* 

Sakai

## SELECTED GRADUATE COURSEWORK

at University of Southern California

2021 PHYS-516, Methods of Computational Physics, A, Prof. Aiichiro Nakano

EE-556, Stochastic Systems and Reinforcement Learning, A , *Prof. Rahul Jain* AME-508, Machine Learning and Computational Physics, A , *Prof. Assad Oberai* CSCI-596, Scientific Computing and Visualization, A , *Prof. Aiichiro Nakano* 

class project: a C++ parallel reinforcement learning implementation Github Link

2020 AME-451, Linear Control Systems I, A , Prof. Henryk Flashner

AME-535A, Introduction to Computational Fluid Mechanics, A, Prof. Alejandra Uranga

# HONOR/AWARDS

2020 USC Viterbi felloship

2017-2018 Hui-Chun Chin and Tsung-Dao Lee Chinese Undergraduate Research Endowment of SJTU

2016 Honeywell Star Project

Second Place, Parts of the National College Students Physics Competition

Third Place, Chinese College Students' Mathematics Competition

2014 First Place, Chinese Chemistry Olympiad

First Place, Shanghai Adolescents Science and Technology Innovation Contest

#### SERVICE

2022 Judge, Undergraduate Symposium for Scholarly and Creative Work

### ONLINE COURSEWORK

at.	Udacity

2022 C++ Nanodegree

at Coursera

2021 Build a Modern Computer from First Principles: From Nand to Tetris (Project-Centered Course),

Hebrew University of Jerusalem

2019 Specialization, DeepLearning.AI TensorFlow Developer, DeepLearning.AI (containing 4 courses)

**Specialization**, Deep Learning, DeepLearning.AI (containing 5 courses)

Machine Learning, Stanford University,

2014 General Chemistry, Peking University

## TECHNICAL SKILLS

Programming Language: Python, Matlab, Fortran, C/C++ (from more familiar to less, same

below)

Machine learning framework: Pytorch, Tensorflow

Hardware: Arduino, Raspberry Pi, Pixhawk