HAOTIAN HANG

September, 2022

CONTACT INFOMATION

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EDUCATION

2020 - **University of Southern California**, Los Angeles, CA
Ph.D. Candidate, Mechanical Engineering, (2022/8 passed qualifying exam, 2024 anticipated)
Master of Science, Mechanical Engineering, December 2021

2015 - 2019 **Shanghai Jiao Tong University**, Shanghai, China
B.S. Aeronautics and Astronautics Engineering, June 2019 (Average Score: 89.22/100)

EMPLOYMENT

2020 - **Research Assistant**, Bio-Inspired Motion Lab at USC, PI: *Prof. Eva Kanso*

2019 **Intern Algorithmic Engineer**, Shanghai Hongpu Information Technology Co., Ltd.
Conduct flaw detection on images of photovoltaic cell using Faster R-CNN and yolov3

2016 - 2019 **Research Assistant**, J.C.Wu Center for Aerodynamics, PI: *Prof. Hong Liu*

PUBLICATIONS

2022 3. Hang, H., Heydari, S., Costello, J., & Kanso, E. (2022). *Active tail flexion in concert with passive hydrodynamic forces improves swimming speed and efficiency*. Journal of Fluid Mechanics, 932, A35.

2021 2. Xiang, Y., Hang, H., Qin, S., and Liu, H. (2021). *Scaling analysis of the circulation growth of leading-edge vortex in flapping flight*. Acta Mech. Sin.

2020 1. Hang, H., Yu, B., Xiang, Y., Zhang, B., and Liu, H. (2020). *An objective-adaptive refinement criterion based on modified ridge extraction method for finite-time Lyapunov exponent (FTLE) calculation*. Journal of Visualization, 23(1), 81-95.

TALKS/PRESENTATIONS

2022 **So Cal Fluids XV**, Learning to blindly follow hydrodynamic trails

2021 **APS Division of Fluid Dynamics Meeting**, Active tail flexion in concert with passive hydrodynamic forces improves swimming speed and efficiency

2020 **APS Division of Fluid Dynamics Meeting**, Flowtaxis in the wakes of oscillating airfoils

2018 **APS Division of Fluid Dynamics Meeting**, Passive rotation of a flapping wing with an inhomogeneous mass distribution

RESEARCH INTERESTS/EXPERIENCE

2020 - **Learning to blindly follow hydrodynamic trails**, supervised by *Prof. Eva Kanso*
joint with *Sina Heydari*, *Yusheng Jiao*
Employ reinforcement learning to follow vortical wakes based on local flow sensory
Find the importance of the wake's periodicity and traveling wave characteristic in source seeking
Analyze the controller in a simplified signal field and prove that stability of the controller depends on the location of sensor
Compare performance among different sensory cues, especially between mechano- and chemo- sensing

2020 - **Flexion in fish swimming**, supervised by *Prof. Eva Kanso*, *Prof. John H. Costello*
joint with *Sina Heydari*
Analyze the role of active and passive flexion on swimming speed and efficiency of a self-propelling pitching plate using vortex sheet method
Parametric study on effects of flexion phase, flexion angle and flexion ratio on swimming performance
Find overlap between biological data and the region we proposed to have hydrodynamic benefits in parameter space

2016 - 2019 **Mechanisms of high lift generation in insects flight**, supervised by *Prof. Hong Liu Dr. Yang Xiang* and *Dr. Suyang Qing*
Conduct experimental study using robotic flapping wing models in glycerin with Reynolds number similar to insects

Measure flow field using particle image velocimetry (PIV) and measure force and torque using 6-axis force sensor, analogue filter and NI data acquisition system
Study difference in formation of leading edge vortex(LEV) for different kinematic modes, and find advanced rotation can generate a lager LEV because of wake capture
Find a scaling law between passive rotation and active translation in flapping wing model

2016 - 2019 **AMR for FTLE calculation**, supervised by *Prof. Hong Liu*, *Prof. Bin Zhang*, *Bin Yu* and *Dr. Yang Xiang*
Develop a physics-based adaptive refinement method for finite-time Lyapunov exponent calculation

2015 - 2016 **VTOL pitch-changed quadrotor** , supported by National Students' Platform for Innovation and Entrepreneurship Training , supervised by *Prof. Junqi Wu*
joint with *Dongming Ding*, *Jihong Huang*, *Chaoqun Li*, *Zhikang Qiu*
Lead a team to make a quadrotor and implement pitch-changed technique and VTOL technique in terms of both mechanical and control

TEACHING EXPERIENCE

at University of Southern California

2021 Spring **Teaching Assistant**, AME-526, Introduction to mathematical methods in engineering II, *Prof. Niema Pahlevan*

2020 Fall **Teaching Assistant**, AME-404, Computational Solutions to Engineering Problems, *Prof. Takahiro Sakai*

SELECTED GRADUATE COURSEWORK

at University of Southern California

2021 PHYS-516, Methods of Computational Physics, A , *Prof. Aiichiro Nakano*
EE-556, Stochastic Systems and Reinforcement Learning, A , *Prof. Rahul Jain*
AME-508, Machine Learning and Computational Physics, A , *Prof. Assad Oberai*
CSCI-596, Scientific Computing and Visualization, A , *Prof. Aiichiro Nakano*
class project: a C++ parallel reinforcement learning implementation *Github Link*

2020 AME-451, Linear Control Systems I, A , *Prof. Henryk Flashner*
AME-535A, Introduction to Computational Fluid Mechanics, A , *Prof. Alejandra Uranga*

HONOR/AWARDS

2020 USC Viterbi felloship
2017-2018 Hui-Chun Chin and Tsung-Dao Lee Chinese Undergraduate Research Endowment of SJTU
2016 Honeywell Star Project
Second Place , Parts of the National College Students Physics Competition
Third Place , Chinese College Students' Mathematics Competition
2014 **First Place**, Chinese Chemistry Olympiad
First Place, Shanghai Adolescents Science and Technology Innovation Contest

SERVICE

2022 Judge, Undergraduate Symposium for Scholarly and Creative Work

ONLINE COURSEWORK

at Udacity

2022 C++ Nanodegree

at Coursera

2021 Build a Modern Computer from First Principles: From Nand to Tetris (Project-Centered Course), Hebrew University of Jerusalem

2019 **Specialization**, DeepLearning.AI TensorFlow Developer , DeepLearning.AI (containing 4 courses)
Specialization, Deep Learning, DeepLearning.AI (containing 5 courses)
Machine Learning, Stanford University,

2014 General Chemistry, Peking University

TECHNICAL SKILLS

Programming Language:	Python, Matlab, Fortran, C/C++ (from more familiar to less, same below)
Machine learning framework:	Pytorch, Tensorflow
Hardware:	Arduino, Raspberry Pi, Pixhawk