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浙江大学 2015-16 学年春夏学期 《高级数据结构与算法分析》课程期末考试试卷 A

判断题

1-1

Let S be the set of activities in Activity Selection Problem. Then the earliest finish activity a_m must be included in all the maximum-size subset of mutually compatible activities of S. (2 %)

C _T **C** _F

If we translate a serial algorithm into a reasonably efficient parallel algorithm, the work load and the worst-case running time are usually reduced. (2 %)

C_T **C**_F

An AVL tree with the balance factors of all the non-leaf nodes being 0 must be a perfect binary tree. (2 %)

C_T C_F

With the same operations, the resulting skew heap is always more balanced than the leftist heap. (2 %)

The worst-case running time is equal to the expected running time within constant factors for any randomized algorithm. (2 %)

C _T C _F

The decision problem HALTING returns TRUE, if, for a given input I and a given (deterministic) algorithm A, A terminates, otherwise it loops forever. The HALTING problem is NP-complete. (2 %)

C_T C_F

For a binomial queue, delete-min takes a constant time on average. (2 分)

C _T C _F

In the 4-queens problem, (x_1, x_2, x_3, x_4) correspond to the 4 queens' column indices. During backtracking, (1, 3, 4, ?) will be checked before (1, 4, 2, ?), and none of them has any solution in their branches. (2 %)

When measuring the relevancy of the answer set of a search engine, the precision is low means that most of the retrieved documents are irrelevant. (2 %)

1-10 C F

In a red-black tree, if an internal black node is of degree 1, then it must have only 1 descendant node. (2 %)

C_T C_F

To merge 55 runs using 3 tapes for a 2-way merge, the original distribution (34, 21) is better than (27, 28). (2 %)

Suppose ALG is an α -approximation algorithm for an optimization problem Π whose approximation ratio is tight. Then for every $\epsilon > 0$ there is no $(\alpha - \epsilon)$ -approximation algorithm for Π unless P = NP. (2 β)

C_T C_F

Since finding a locally optimal solution is presumably easier than finding an optimal solution, we can claim that for any local search algorithm, one step of searching in neighborhoods can always be done in polynomial time. (2 %)

To solve a problem by dynamic programming instead of recursions, the key approach is to store the results of computations for the subproblems so that we only have to compute each different subproblem once. Those solutions can be stored in an array or a hash table. (2 \Re)

<u>C</u> T

Recall that the worst-case time complexities of insertions and deletions in a heap of size N are both $O(\log N)$. Then, without changing the data structure, the amortized time complexity of insertions in a heap is also $O(\log N)$, and that of deletions is O(1). (2 %)

C_T C_F

选择题

2-1

Given the distance set D= $\{1,1,2,2,2,2,3,3,3,4,5,5,6,6,8\}$ in a Turnpike Reconstruction problem, first it can be sure that x1=0 and x6=8. Which of the following possible solutions will be checked next? (3 %)

x2=1, x5=6

V2=2 V5=6

x3=3, x5=6

x2=1, x5=5

Insert $\{7, 8, 9, 2, 3, 5, 6, 4\}$ into an initially empty AVL tree. Which one of the following statements is FALSE? (4 %)

7 is the root

2 and 5 are siblings

there are 2 nodes with their balance factors being -1

3 is the parent of 4

Suppose that the replacement selection technique is used in external sorting to construct the initial runs. A priority queue of size 5 is used by the internal memory. Given input sequence $\{5, 19, 25, 45, 30, 24, 15, 60, 16, 27, 1\}$. Which of the following runs will be generated? (3 %)

```
run1: 5, 19, 25, 30, 45; run2: 15, 16, 24, 27, 60; run3: 1
```

- run1: 5, 19, 24, 25, 30, 45; run2: 1, 15, 16, 27, 60
- run1: 5, 19, 25, 30, 45; run2:1, 15, 16, 24, 27, 60
- run1: 5, 19, 24, 25, 30, 45, 60; run2:1, 15, 16, 27

2-4

When solving a problem with input size N by divide and conquer, if at each step, the problem is divided into 9 sub-problems and each size of these sub-problems is N/3, and they are conquered in $O(N^2logN)$. Which one of the following is the closest to the overall time complexity? (3 %)

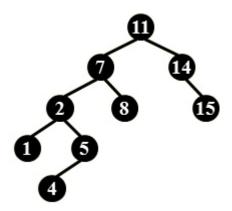
- $O(N^2 log 2N)$
- $O(N^2 log N)$
- $O(N^2)$
- $O(N^3 log N)$

2-5

Which one of the following statements about the Maximum Finding problem is true? (3 分)

- There exists a serial algorithm with time complexity being O(logN).
- No parallel algorithm can solve the problem in O(1) time.
- When partitioning the problem into sub-problems and solving them in parallel, compared with \sqrt{N} , choosing loglogN as the size of each sub-problem can reduce the work load and the worst-case time complexity.
- Parallel random sampling algorithm can run in O(1) time and O(N) work with very high probability.

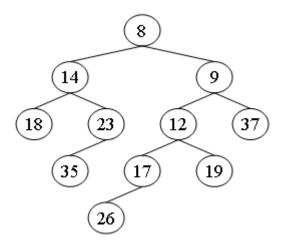
For the result of accessing the keys 4 and 8 in order in the splay tree given in the figure, which one of the following statements is FALSE? (4 %)



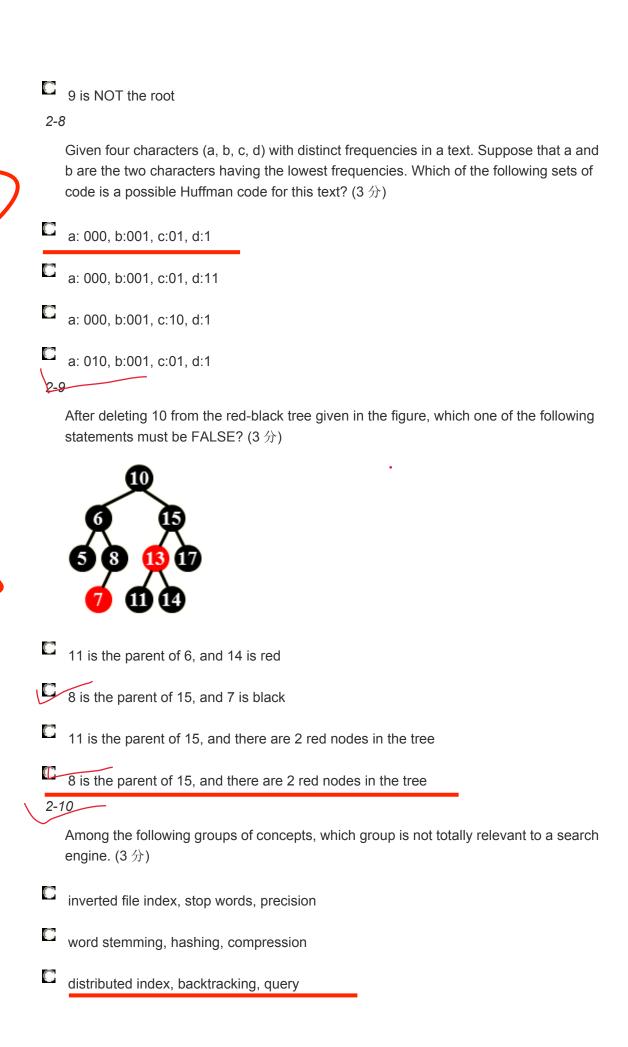
- 8 is the root
- 4 and 11 are siblings
- 7 and 14 are siblings
- 4 is the parent of 7

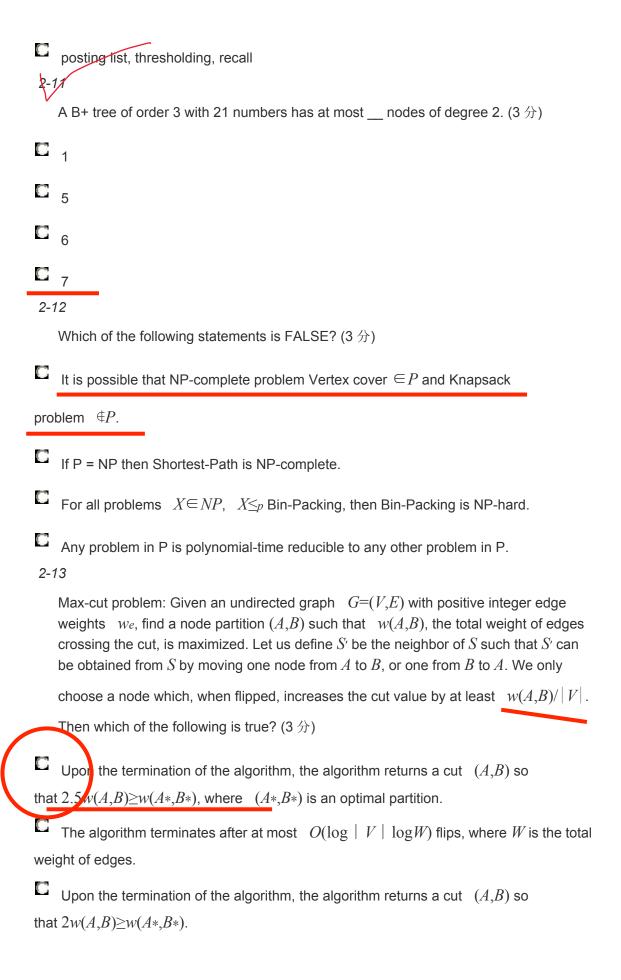
2-7

Delete the minimum number from the given leftist heap. Which one of the following statements is TRUE? (4 %)



- 23 is the left child of 14
- 12 is the right child of 9
- 37 is the left child of 23





The algorithm terminates after at most $O(\mid V \mid ^2)$ flips. 2-14 Suppose Q is a problem in NP, but not necessarily NP-complete. Which of the following is FALSE? (3分) A polynomial-time algorithm for SAT would necessarily imply a polynomial-time algorithm for Q. A polynomial-time algorithm for Q would necessarily imply a polynomial-time algorithm for SAT. If Q $\notin P$, then $P \neq NP$. If Q is NP-hard, then Q is NP-complete. In dynamic programming, we derive a recurrence relation for the solution to one subproblem in terms of solutions to other subproblems. To turn this relation into a bottom up dynamic programming algorithm, we need an order to fill in the solution cells in a table, such that all needed subproblems are solved before solving a subproblem. Among the following relations, which one is impossible to be computed. (3 %)A(i,j)=min(A(i-1,j),A(i,j-1),A(i-1,j-1)) $A(i,j)=F(A(min\{i,j\}-1,min\{i,j\}-1),A(max\{i,j\}-1,max\{i,j\}-1))$ A(i,j)=F(A(i,j-1),A(i-1,j-1),A(i-1,j+1))A(i,j) = F(A(i-2,j-2),A(i+2,j+2))2-16 You are to maintain a collection of lists and to support the following operations. (i) insert(item, list): insert item into list (cost = 1). (ii) sum(list): sum the items in list, and replace the list with a list containing one item that is the sum (cost = length of list). We show that the amortized cost of an insert operation is O(1) and the amortized cost of a sum operation is O(1). If we assume the potential function to be the number of elements in the list, which of the following is FALSE? (2 分) For insert, the actual cost is 1. For insert, the change in potential is 1. The amortized cost is 2.

For sum, the actual cost is k. For sum, the change cost is 2-k. The amortized cost is 2. To solve the optimal binary search tree problem, we have the recursive equation *cij* $=\min_{i \le l \le j} \{w_{ij} + c_{i,l-1} + c_{l+1,j}\}$. To solve this equation in an iterative way, we must fill up a table as follows:(3 分) Α. for i = 1 to n-1 do; for j= i to n do; В. С. for l= i to j do D. for j=1 to n-1 do; Ε. for i= 1 to j do; for l= i to j do F. G. for k= 1 to n-1 do; Н. for i= 1 to n-k do; I. set j = i+k; for l= i to j do J. Κ. for k= 1 to n-1 do; L. for i= 1 to n do; set j = i+k;Μ. for l= i to j do N. 2-1/8 Which one of the following statements is FALSE about a skew heap? (3 %) Skew heaps do not need to maintain the null path length of any node Comparing to leftist heaps, skew heaps are always more efficient in space Skew heaps have O(logN) worst-case cost for merging f C Skew heaps have O(logN) amortized cost per operation

Which of the following statement is true ? (2 $\ensuremath{\mathcal{H}})$

Let A and B be optimization problems where it is known that A reduces to B in
polynomial time. Additionally, suppose that there exists a polynomial-time 2-approximation for B . Then there must exist a polynomial time 2-approximation for A .
Ioi D . Then there must exist a polynomial time 2-approximation for A .
There exists a polynomial-time 2-approximation algorithm for the general Traveling
Salesman Problem.
Suppose that you have two deterministic online algorithms, A_1 and A_2 , with a
competitive ratios c_1 and c_2 respectively. Consider the randomized algorithm $A*$ that flips a fair coin once at the beginning; if the coin comes up heads, it runs A_1 from then on: if the coin comes up tails, it runs A_2 from then on. Then the expected competitive ratio of $A*$ is at least $\min\{c_1,c_2\}$.
A randomized algorithm for a decision problem with one-sided-error and correctness
probability 1/3 (that is, if the answer is YES, it will always output YES, while if the answer is NO, it will output NO with probability 1/3) can always be amplified (放大) to a correctness probability of 99%. 2-20
Given a 3-SAT formula with k clauses, in which each clause has three variables, the MAX-3SAT problem is to find a truth assignment that satisfies as many clauses as possible. A simple randomized algorithm is to flip a coin, and to set each variable true with probability $1/2$, independently for each variable. Which of the following statements is FALSE?(2 $\%$)
The expected number of clauses satisfied by this random assignment is $7k/8$.
The probability that a random assignment satisfies at least $7k/8$ clauses is at
πιοεί 1/(οκ).
For every instance of 3-SAT, there is a truth assignment that satisfies at least
a $7/8$ fraction of all clauses.
If we repeatedly generate random truth assignments until one of them
satisfies $\geq 7k/8$ clauses, then this algorithm is a $8/7$ -approximation algorithm.

程序填空题

3-1

The function BinQueue_Merge is to merge two binomial queues H1 and H2, and return H1 as the resulting queue.

```
BinQueue BinQueue_Merge( BinQueue H1, BinQueue H2 )
{ BinTree T1, T2, Carry = NULL;
   int i, j;
   H1->CurrentSize += H2-> CurrentSize;
   for ( i=0, j=1; j<= H1->CurrentSize; i++, j*=2 ) {
       T1 = H1->TheTrees[i]; T2 = H2->TheTrees[i];
       switch( 4*!!Carry + 2*!!T2 + !!T1 ) {
       case 0:
       case 1: break;
       case 2: H1->TheTrees[i]=T2;H2->TheTrees[i]=N以身); break;
       case 4: H1->TheTrees[i] = Carry; Carry = NULL; break;
       case 3: Carry = CombineTrees( T1, T2 );
              H1->TheTrees[i] = H2->TheTrees[i] = NULL; break;
       case 5: Carry = CombineTrees( T1, Carry );
              H1->TheTrees[i] = NULL; break;
       case 6: Carry = CombineTrees( T2, Carry );
              H2->TheTrees[i] = NULL; break;
       case 7: H1->TheTrees[i] = Carry;
              Carry=CombineTrees(T1, T2)
                                                         (3分);
              H2->TheTrees[i] = NULL; break;
       } /* end switch */
   } /* end for-loop */
   return H1;
}
```

函数题

```
4-1 Quick Power (4分)
```

The function Power calculates the exponential function N^{k} . But since the exponential function grows rapidly, you are supposed to return $(N^{k})\%10007$ instead.

Format of function:

```
int Power(int N, int k);
```

Both N and k are integers, which are no more than 2147483647.

Sample program of judge:

```
#include <stdio.h>

int Power(int, int);

const int MOD = 10007;
int main()
{
    int N, k;
    scanf("%d%d", &N, &k);
    printf("%d\n", Power(N, k));
    return 0;
}

/* Your function will be put here */
```

Sample Input 1:

```
2 3
```

Sample Output 1:

```
8
```

Sample Input 2:

```
128 2
```

Sample Output 2:

```
6377
```