

# Gauss quadrature

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These notes derive Gauss quadrature using Hermite interpolation.  
We would like to approximate the integral

$$I[f] = \int_a^b f(x) dx,$$

of a real function  $f : [a, b] \rightarrow \mathbb{R}$  by an  $n$ -point rule of the form

$$I_n[f] = \sum_{i=1}^n w_i f(x_i), \tag{1}$$

for certain points  $a \leq x_1 < x_2 < \cdots < x_n \leq b$  and weights  $w_i \in \mathbb{R}$ .

We say that  $I_n$  has degree of precision  $d$  if it is exact for polynomials of degree  $\leq d$ , i.e., for polynomials in  $\pi_d$ .

For any choice of points  $x_i$  we can find weights  $w_i$  for which  $I_n$  has degree of precision  $\geq n - 1$ . We do this by integrating the Lagrange interpolant  $p \in \pi_{n-1}$  to  $f$  at these points. Since

$$p(x) = \sum_{i=1}^n L_i(x) f(x_i),$$

where

$$L_i(x) = \prod_{j \neq i} \frac{x - x_j}{x_i - x_j},$$

we have

$$I[p] = \sum_{i=1}^n w_i f(x_i),$$

where  $w_i = I[L_i]$ . This gives us the rule

$$I_n[f] = I[p], \quad (2)$$

and it has degree of precision at least  $n - 1$  because if  $f \in \pi_{n-1}$  then  $p = f$ .

The idea of Gauss quadrature is to choose the  $n$  points  $x_i$  in the rule (2) in such a way as to raise its degree of precision to  $2n - 1$ . We note that there is no hope of raising its degree of precision to  $2n$  or higher because for any points  $x_i$  if

$$s(x) = (x - x_1)(x - x_2) \cdots (x - x_n), \quad (3)$$

then  $s^2 \in \pi_{2n}$  but

$$I_n[s^2] = 0, \quad I[s^2] > 0.$$

One way to derive the Gauss rule is to integrate the Hermite interpolant  $q$  to  $f$ , the polynomial  $q \in \pi_{2n-1}$  such that

$$q(x_i) = f(x_i), \quad q'(x_i) = f'(x_i), \quad i = 1, \dots, n.$$

If we set

$$I_n[f] = I[q]$$

then  $I_n$  clearly has degree of precision  $2n - 1$ , which is what we want. At the same time, it turns out that it is possible to choose the  $x_i$  in such a way that the integral of  $q$  is independent of the derivatives  $f'(x_i)$ . To see this define the inner product of two functions  $f$  and  $g$  on  $[a, b]$  by

$$\langle f, g \rangle = \int_a^b f(x)g(x) dx.$$

**Theorem 1** *If  $s$  in (3) is orthogonal to  $\pi_{n-1}$  then*

$$I[q] = I[p].$$

*Proof.* Since  $q - p$  is a polynomial in  $\pi_{2n-1}$  which is zero at  $x_i$ ,  $i = 1, \dots, n$ , there must be some polynomial  $r \in \pi_{n-1}$  such that

$$q = p + sr.$$

Therefore,

$$I[q] = I[p] + \langle s, r \rangle,$$

and since  $r$  is orthogonal to  $s$ , the inner product on the right is zero.  $\square$

Thus if  $x_1, \dots, x_n$  are the roots of a polynomial in  $\pi_n$  that is orthogonal to  $\pi_{n-1}$  the rule (2) has degree of precision  $2n-1$ , and this is what we call the  $n$ -point Gauss quadrature rule. Fortunately there is a solution. We have shown earlier that we can construct a sequence of polynomials  $\phi_k$ ,  $k = 0, 1, 2, \dots$  such that  $\phi_k \in \pi_k$  and  $\langle \phi_j, \phi_k \rangle = 0$  for  $j \neq k$  and  $\langle \phi_k, \phi_k \rangle \neq 0$ . These are known as Legendre polynomials.

**Theorem 2** *The Legendre polynomial  $\phi_n$  has real, distinct roots and they are all in  $(a, b)$ .*

*Proof.* Let  $a < x_1 < x_2 < \dots < x_m < b$  be the  $m$  sign-changes of  $\phi_n$  in  $(a, b)$ ,  $m \leq n$ , and let  $q(x) = (x - x_1) \cdots (x - x_m)$ . Then the product  $q\phi_n$  is a function of one sign in  $[a, b]$ , and so  $\langle q, \phi_n \rangle \neq 0$ , and thus  $\phi_n$  is not orthogonal to  $q$ . Therefore, the degree of  $q$  must be at least  $n$ , i.e.,  $m = n$ .  $\square$

If  $\phi_n$  is normalized to have leading coefficient 1, we can thus set  $s = \phi_n$ , so that  $x_1, \dots, x_n$  are the roots of  $\phi_n$ . In addition to its high degree of precision, Gauss quadrature also has positive weights which gives it numerical stability.

**Theorem 3** *The weights in the Gauss rule are positive because  $w_i = I[L_i^2]$ .*

*Proof.* By definition,  $w_i = I[L_i]$ . Therefore,

$$w_i = I[L_i^2] + I[L_i(1 - L_i)].$$

Since  $L_i(1 - L_i)$  has degree  $2n - 2$  and zeros  $x_1, \dots, x_n$ , there is some polynomial  $r_i \in \pi_{n-2}$  such that

$$L_i(1 - L_i) = sr_i,$$

and since  $\langle s, r_i \rangle = 0$ ,

$$I[L_i(1 - L_i)] = 0.$$

$\square$

We also obtain the error in the Gauss rule from the Newton form of  $q$ .

**Theorem 4** *If  $f \in C^{2n}[a, b]$  then there is some  $\xi \in (a, b)$  such that*

$$I[f] - I_n[f] = \frac{f^{(2n)}(\xi)}{(2n)!} I[s^2].$$

*Proof.* The Newton error formula for Hermite interpolation gives

$$f(x) - q(x) = s^2(x)[x_1, \dots, x_n, x_1, \dots, x_n, x]f,$$

and integrating this equation over  $[a, b]$  gives

$$I[f] - I_n[f] = \int_a^b s^2(x)[x_1, \dots, x_n, x_1, \dots, x_n, x]f \, dx,$$

and since  $s^2$  is a function of one sign in  $[a, b]$  and

$$[x_1, \dots, x_n, x_1, \dots, x_n, x]f$$

is a continuous function of  $x$ , the mean value theorem for integrals implies there is some  $\eta \in [a, b]$  such that

$$I[f] - I_n[f] = [x_1, \dots, x_n, x_1, \dots, x_n, \eta]f \int_a^b s^2(x) \, dx,$$

which gives the result. □

*Example 1.*  $I_1$  is the midpoint rule,  $I_1[f] = 2f(0)$ .

*Example 2.* To derive  $I_2$  recall that  $\phi_2(x) = x^2 - 1/3$ , and so  $x_1 = -1/\sqrt{3}$  and  $x_2 = 1/\sqrt{3}$ . Then

$$L_1(x) = (1 - \sqrt{3}x)/2, \quad L_2(x) = (1 + \sqrt{3}x)/2,$$

and  $I[L_1] = I[L_2] = 1$ , and so

$$I_2[f] = f\left(-\frac{1}{\sqrt{3}}\right) + f\left(\frac{1}{\sqrt{3}}\right).$$