

# Beyond the Theoretical Limits of Language Modeling: A Distributional Perspective

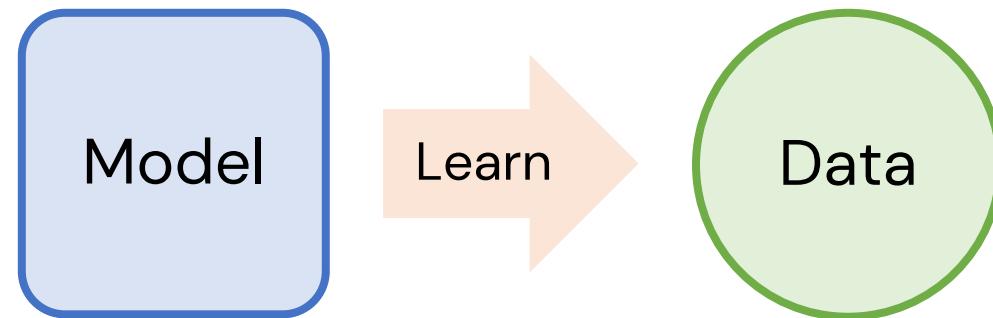
Haozhe Ji

Tsinghua University

# Introduction



- Components of language modeling:



- ◆ **Language data:**  $\mathcal{D} = \{x^{(i)}\}_{i=1}^N$  drawn from data distribution
- ◆ **Probabilistic Model:**  $p_\theta(x)$  map data point to probability
- ◆ **Learning objective:**  $\mathcal{L}(\theta, \mathcal{D})$  learn model distribution from data
- Choice of model and objective seems not important nowadays. **Really?**

# Introduction



- Modern recipe of language modeling:

**Model:** Neural language model

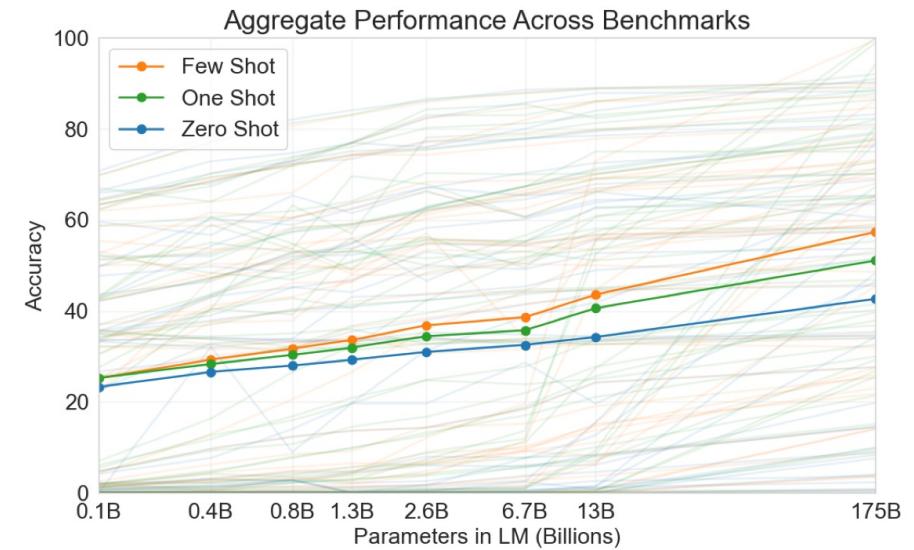
- Auto-Regressive (AR) model of sequence probability

$$p_{\theta}(\mathbf{x}) = \underbrace{\prod_{t=1}^T p_{\theta}(x_t | x_1, \dots, x_{t-1})}_{\text{Auto-Regressive Modeling}}$$

**Objective:** Next token prediction

- Maximize the likelihood of samples in the dataset

$$\mathcal{L}_{\text{MLE}}(\theta; \mathcal{D}) = \underbrace{\mathbb{E}_{\mathbf{x} \sim \mathcal{D}} \left[ -\log p_{\theta}(\mathbf{x}) \right]}_{\text{Maximum Likelihood Estimation}}$$



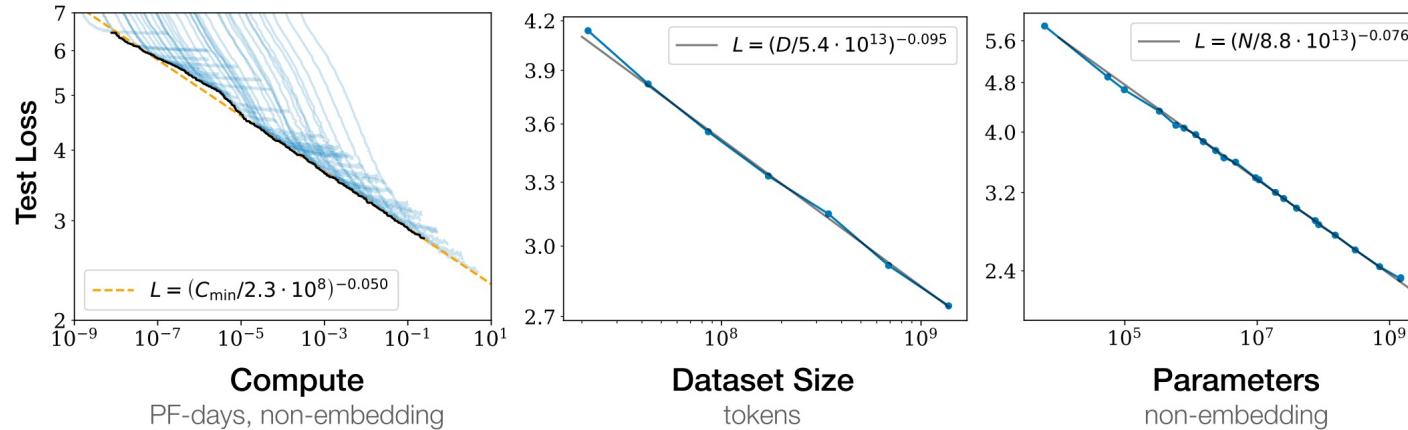
Averaged performance across tasks scales with model sizes

- Language modeling is shown to be the ultimate task towards “intelligence”

# Introduction



- Empirical law for scaling AR language model (LMs) on the MLE loss



$$L(X) \propto X^{\alpha_X}$$

$X$  is one factor from  $\{C, D, N\}$

MLE loss has a **power-law** relationship with  $C, D, N$

- The power law of scaling one factor depends on the **unbounded value** of the other two factors.
- The return becomes diminished when we **run out of the available human text data** or **cannot afford to increase the model size!**

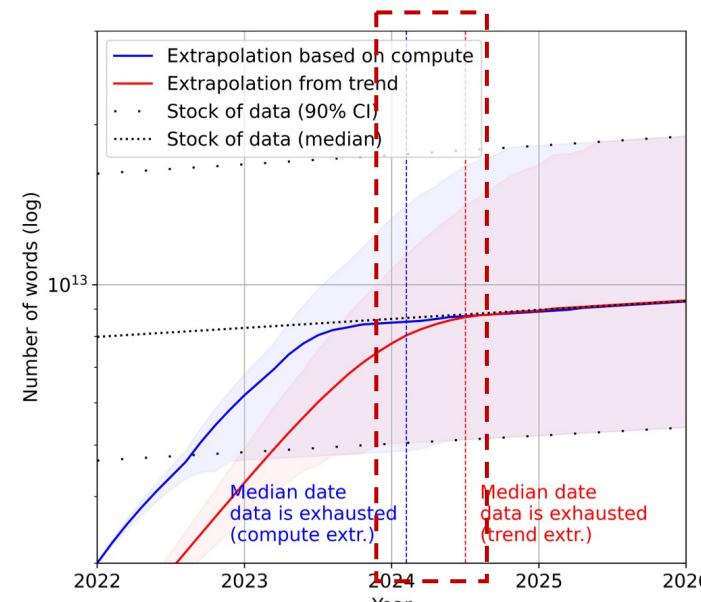
# Introduction



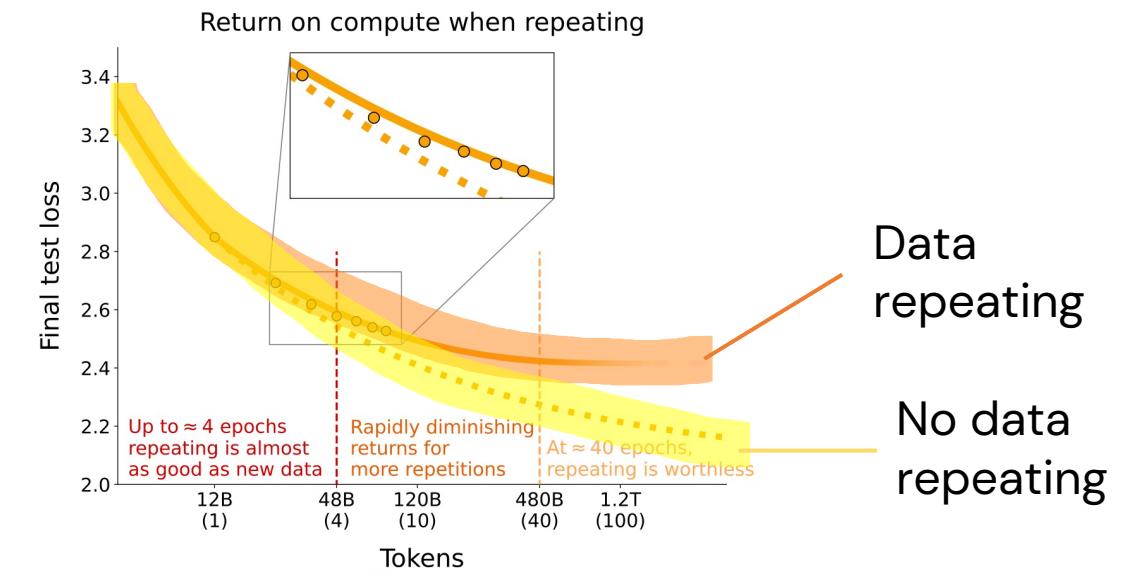
## #1 What will happen when we run out of the available human text data?

- ◆ Llama3 was trained on 15T tokens, roughly the scale of the quality filtered subsets of Common Crawl, i.e., the high-quality English texts on the Internet.

Data will be “ran out” around 2024 (estimated in 2022)



language data on web



Data-Constrained Scaling law

Muennighoff, Niklas, et al. "Scaling Data-Constrained Language Models." *NeurIPS* (2024).

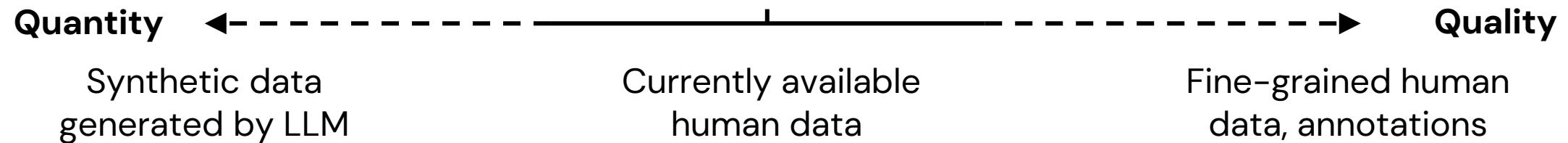
Villalobos, Pablo, et al. "Will we run out of data? an analysis of the limits of scaling datasets in machine learning." *arXiv preprint* (2022).

# Introduction



## #1 What will happen when we run out of the available human text data?

- ◆ The data spectrum

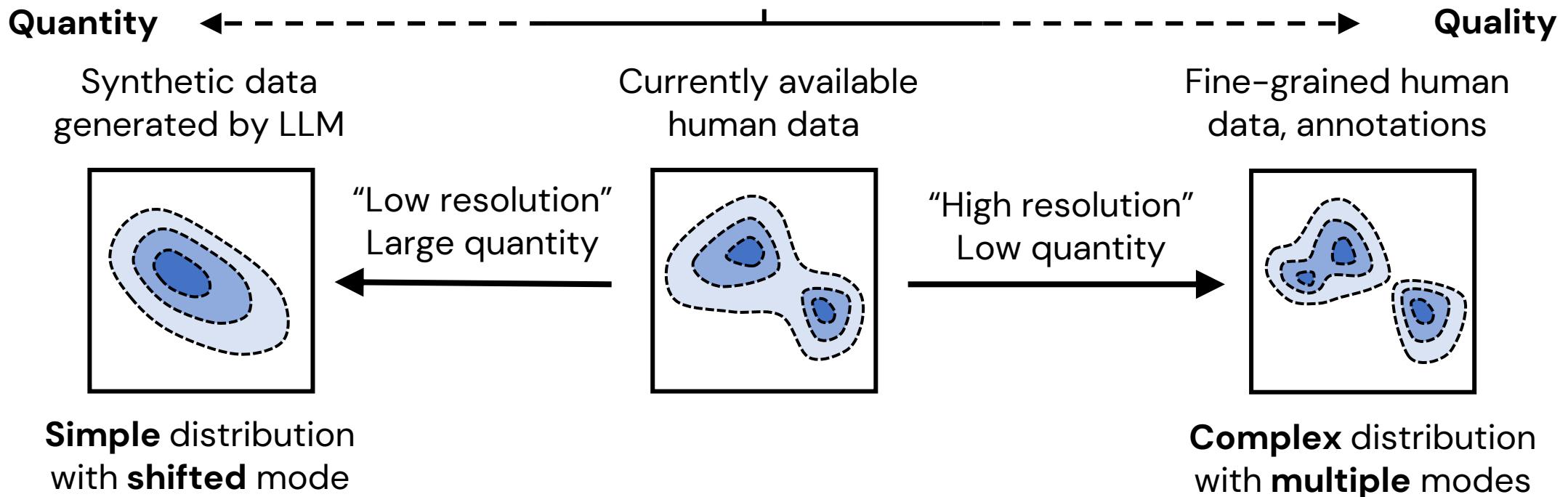


# Introduction



## #1 What will happen when we run out of the available human text data?

- ◆ The data spectrum from a **distributional** perspective

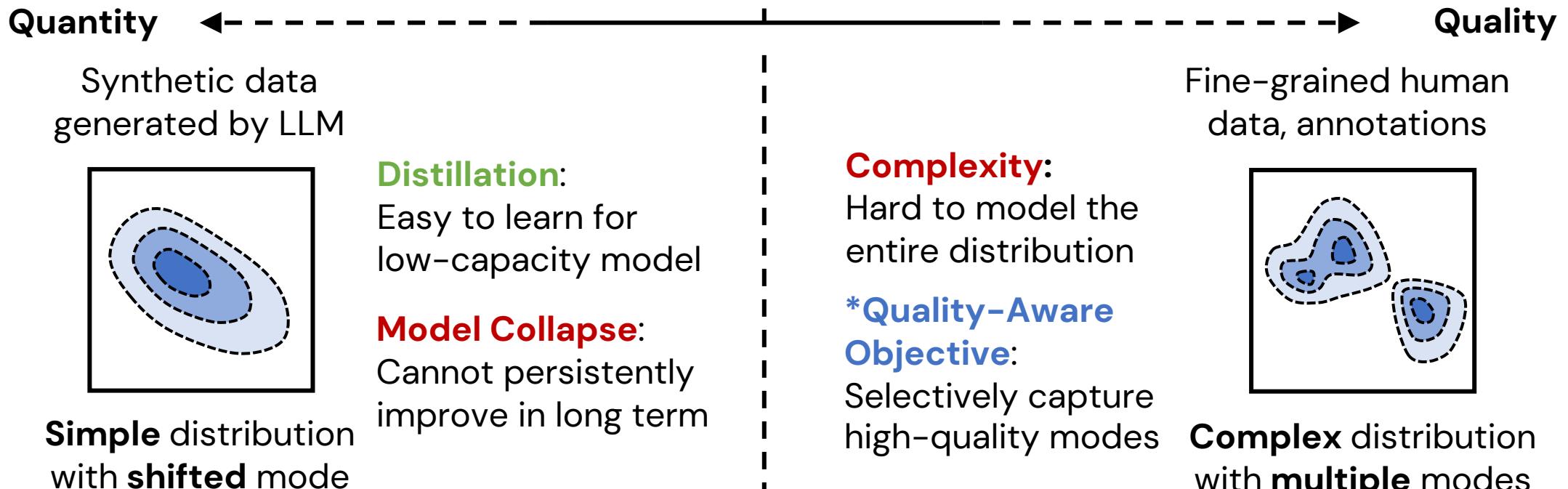


# Introduction



## #1 What will happen when we run out of the available human text data?

- ◆ The data spectrum from a **distributional** perspective



- ◆ MLE is **not** aware of quality but coverage (likelihood)!

# Introduction



## #2 What is the parameter complexity of AR LMs to fit the growing data?

- ◆ **Theory (Informal):** AR LMs must be **large enough** to **efficiently compute** the probability of **arbitrary** sequence of length up to  $n$  under the complexity assumption of  $P \neq NP$ .
- ◆ **Large parameter:**

$$|\theta_n^{\text{AR}}| = O(\text{Superpoly}(n))$$

- ◆ **Efficient computation:**

$$p_{\theta_n}(\mathbf{x}) = \prod_{t=1}^n p_{\theta_n}(x_t | x_1, \dots, x_{t-1})$$

$$p_{\theta_n}(x_t | \mathbf{x}_{<t}) = \frac{\sum_{\mathbf{x}'_{>t}} p_{\theta_n}(\mathbf{x}_{\leq t}, \mathbf{x}'_{>t})}{\sum_{\mathbf{x}'_{\geq t}} p_{\theta_n}(\mathbf{x}_{<t}, \mathbf{x}'_{\geq t})}$$

**Assumption by AR:**  
Efficiently predict the **present** based on the **past** in time  $O(\text{poly}(n))$

The **present** is predicted by marginalizing out **all possible futures** (Bayesian view)

# Introduction



## #2 What is the parameter complexity of AR LMs to fit the growing data?

- ◆ **Theory (Informal):** AR LMs must be **large enough** to **efficiently compute** the probability of **arbitrary** sequence of length up to  $n$  under the complexity assumption of  $P \neq NP$ .
- ◆ **Large parameter (space):**

$$|\theta_n^{\text{AR}}| = O(\text{Superpoly}(n))$$

- ◆ **Efficient computation (time):**

$$p_{\theta_n}(\mathbf{x}) = \prod_{t=1}^n p_{\theta_n}(x_t | x_1, \dots, x_{t-1})$$

**Assumption by AR:**  
Efficiently predict the **present** based on the **past** in time  $O(\text{poly}(n))$

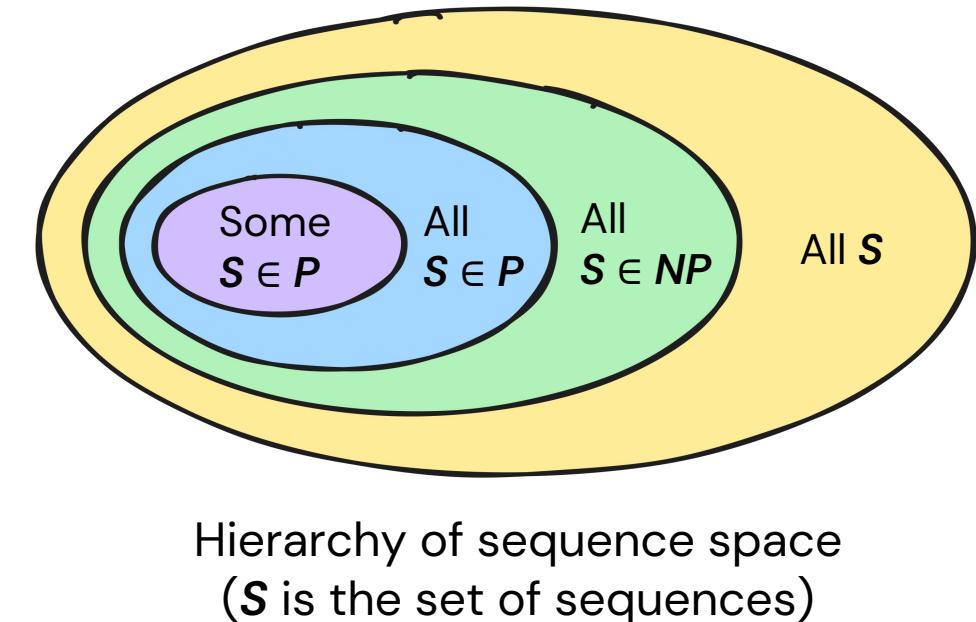
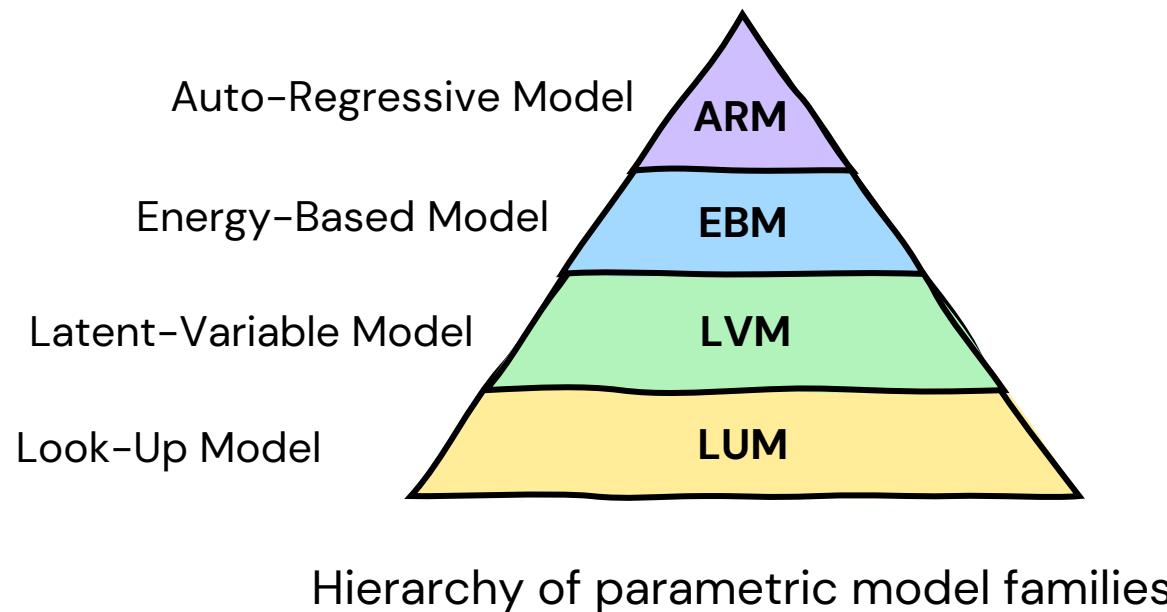
- ◆ **Intuition (Space-Time Tradeoff):** To accurately compute the probability of any sequence, the AR LM must have either **exponential-size computation** or **exponential-size parameters**.

# Introduction



## #2 What is the parameter complexity of AR LMs to fit the growing data?

- ◆ **Corollary:** AR LMs with **compact parameters** grow as  $O(\text{poly}(n))$  can only efficiently compute the probability of **a limited subset** of sequences of length up to  $n$ .
- ◆ Exist more **complex sequence spaces** captured by more **expressive model families**.





- **Beyond MLE:** Quality-aware objective
  - ◆ **Reverse KL [ICML' 24]:** quality assessed by reward that captures human preference
  - ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory
  
- **Beyond AR:** Expressive model family
  - ◆ **Energy-based model [ICLR' 24]:** Augment AR model with a residual energy model
  - ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
  - ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up



## ○ Beyond MLE: Quality-aware objective

- ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
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## ○ Beyond AR: Expressive model family

- ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
- ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
- ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up

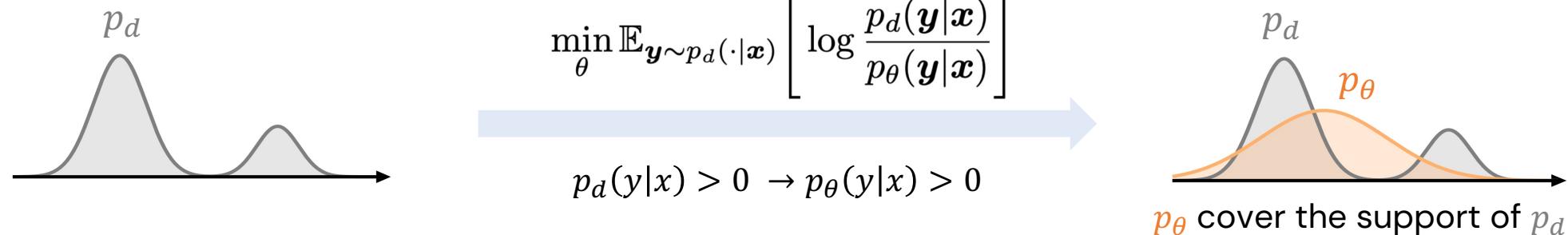
- Learning as divergence minimization from a distributional perspective

- MLE minimizes the **forward-KL (FKL) divergence** from model dist.  $p_\theta$  to data dist.  $p_d$

$$\mathbb{E}_{p_d(\mathbf{y}|\mathbf{x})} \left[ -\log p_\theta(\mathbf{y}|\mathbf{x}) \right] = \underbrace{\mathbb{D}_{\text{KL}}(p_d \| p_\theta)[\mathbf{x}]}_{\text{forward KL}} + \underbrace{H(p_d)[\mathbf{x}]}_{\text{entropy}}$$

- Minimize FKL under **model misspecification**:

- $p_d$  comes from a more expressive distribution family than  $p_\theta$
- Example:**  $p_d$  is a mixture of Gaussians,  $p_\theta$  is a single Gaussian



# MLE for AR LM



## Is MLE a universal objective for LM training?

### Pre-training stage:

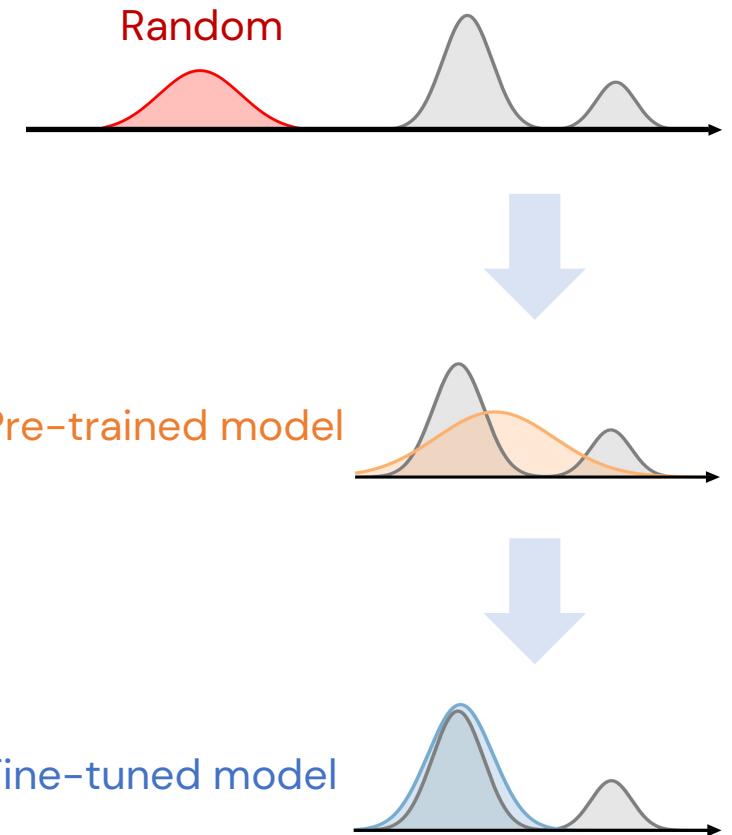
- Initialization: Random
- Data: large amount, diverse while noisy
- Goal: Learn basic knowledge (**coverage**)

### Fine-tuning stage:

- Initialization: Pre-trained model
- Data: limited amount, high-quality
- Goal: Learn fine-grained ability (**quality**)

## MLE is not desirable when:

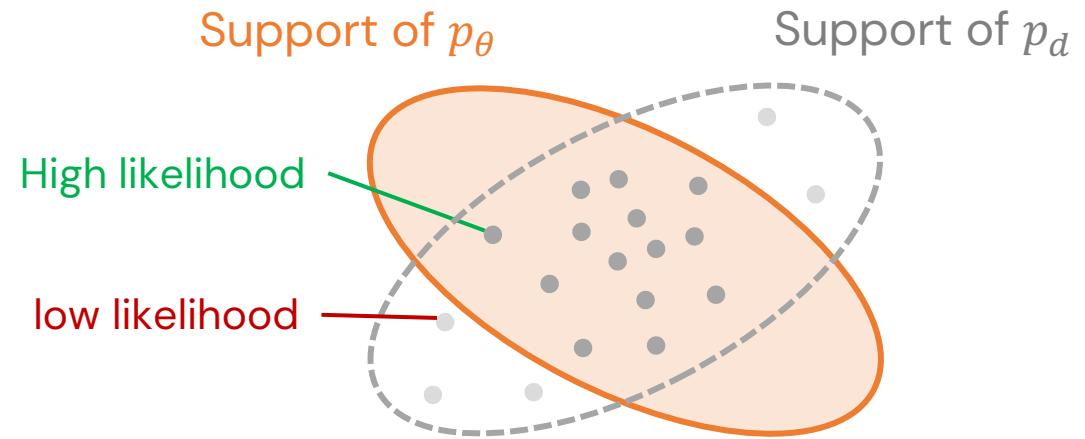
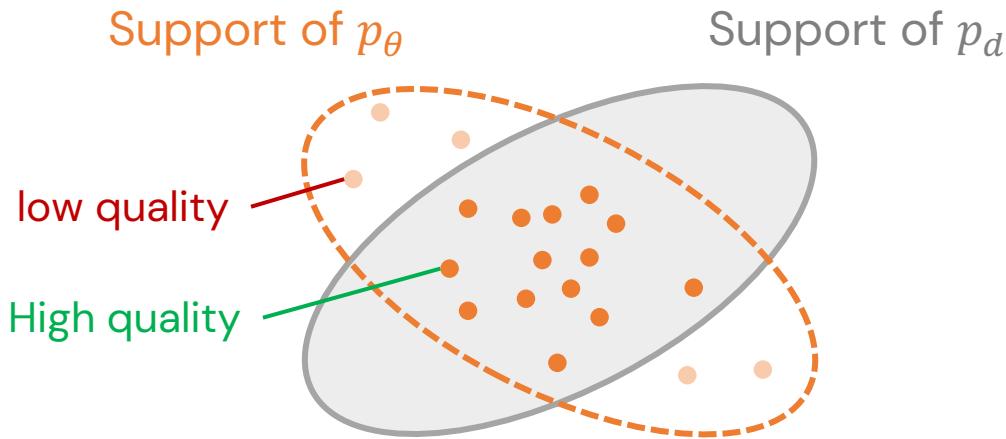
- Evaluation focuses on quality not coverage
- Model is mis-specified for the data distribution



# Beyond MLE for AR LM



- Forward KL is not informative about the behavior of model on **quality**
- quality vs coverage**
  - Quality: Evaluate **samples** generated by model
  - Coverage (likelihood): Evaluate model's **scores** on data samples



- Challenge of quality-aware objective:** Samples are hard to evaluate than scores!



- ⦿ **Beyond MLE:** Quality-aware objective

- ◆ **Reverse KL [1]:** quality assessed by reward that captures human preference
- ◆ Total variation distance [2]: quality assessed by the “optimal classifier” in theory

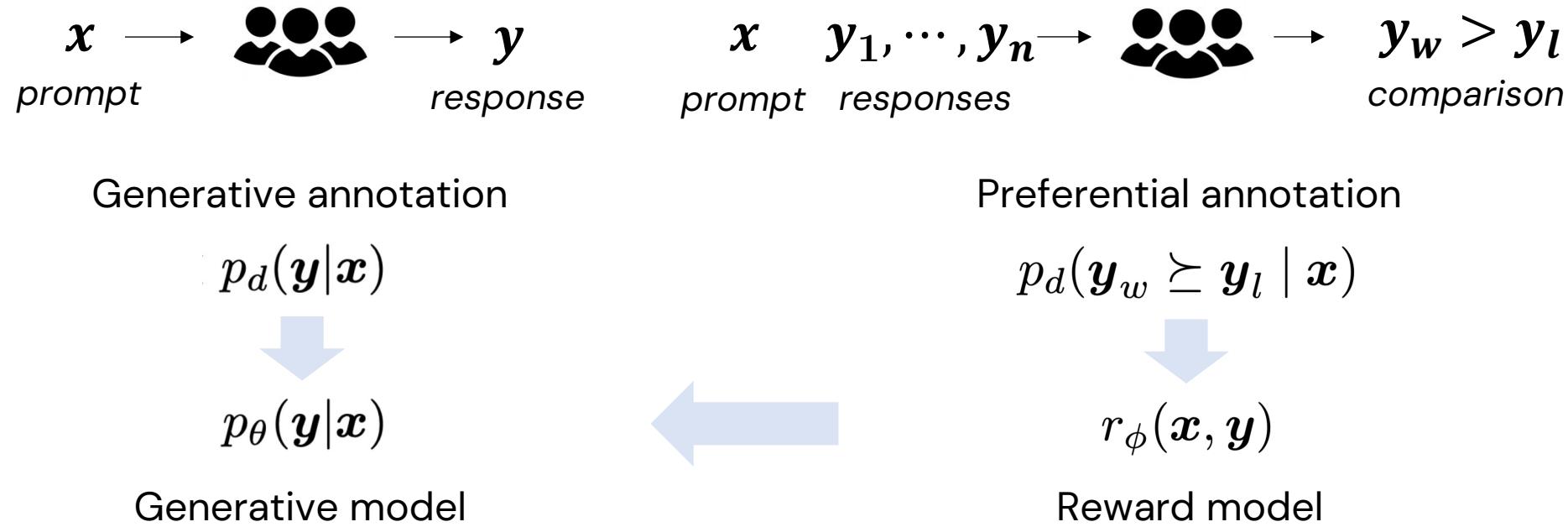
- ⦿ **Beyond AR:** Expressive model family

- ◆ Energy-based model [3]: Augment AR model with a residual energy model
- ◆ Latent-variable model [4]: Condition AR model with a latent plan
- ◆ Look-up model [5]: Extend AR model with a parallel database look-up

# Beyond MLE for AR LM



- Controlled assessment of quality by additional human annotation



- Preference data: Fine-grained signal of **quality** to shape the target distribution
- Discrimination vs Generation: EBM can capture more complex distribution than ARM

# LM Alignment



- LM alignment with human preference [Ouyang et al., 2022]:

- ◆ Alignment objective (RLHF): KL-regularized reward maximization

$$\mathcal{J}_{\text{lfh}}^{\beta}(\pi_{\theta}) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \left( \mathbb{E}_{\pi_{\theta}(\mathbf{y}|\mathbf{x})} [r_{\phi}(\mathbf{x}, \mathbf{y})] - \beta \mathbb{D}_{\text{KL}}[\pi_{\theta}(\mathbf{y}|\mathbf{x}) \| \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})] \right)$$

*Reward model*  
*(proxy human preference)*      *reference LM*  
*(initialized by MLE)*

$$R(\mathbf{x}, \mathbf{y}) = r_{\phi}(\mathbf{x}, \mathbf{y}) - \beta \log \frac{\pi_{\theta}(\mathbf{y}|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})}$$

↓

$$\nabla_{\theta} \mathcal{J}_{\text{lfh}}^{\beta}(\pi_{\theta}) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}, \mathbf{y} \sim \pi_{\theta}(\mathbf{y}|\mathbf{x})} \left[ R(\mathbf{x}, \mathbf{y}) \nabla_{\theta} \log \pi_{\theta}(\mathbf{y}|\mathbf{x}) \right]$$

*Policy gradient, Actor-Critic, e.g., PPO [Schulman et al., 2017]*

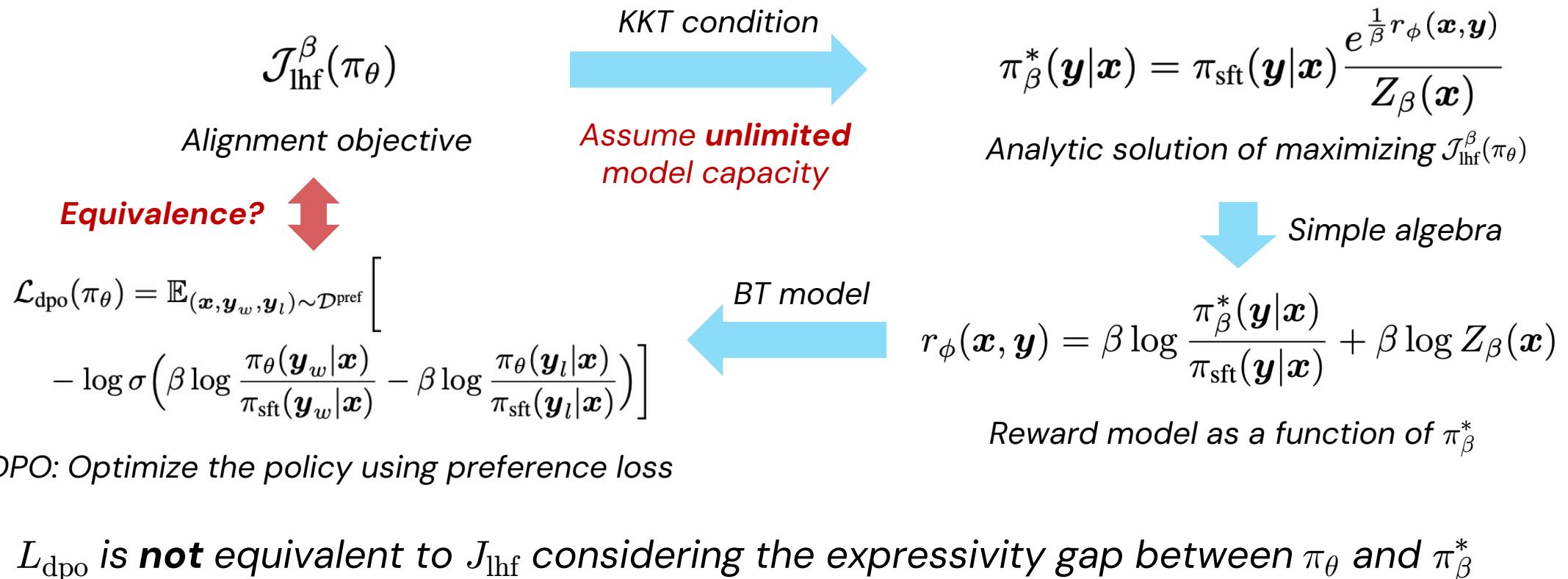
RL has **high variance** in policy gradient estimation  
RL needs to **sample in training loop** ] **Inefficiency** of convergence

# LM Alignment



- Direct Preference Optimization (DPO) [Rafailov et al., 2023]:

- ◆ Key intuition: Policy optimization as reward modeling.



# LM Alignment



- What does the solution of RLHF look like under this practical constraint?
    - ◆ KL-regularized RL as probability matching [Korbak et al., 2021].

$$\mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \left( \mathbb{E}_{\pi_\theta(\mathbf{y}|\mathbf{x})} [r_\phi(\mathbf{x}, \mathbf{y})] - \beta \mathbb{D}_{\text{KL}}[\pi_\theta(\mathbf{y}|\mathbf{x}) \| \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})] \right) \xrightarrow{\text{equivalent}} \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} [\mathbb{D}_{\text{KL}}(\pi_\theta(\mathbf{y}|\mathbf{x}) \| \pi_{\beta_r}^*(\mathbf{y}|\mathbf{x}))]$$

*Maximize reward with KL penalty*      *Minimize reverse KL divergence*

- ### ◆ The asymmetry of KL divergence:

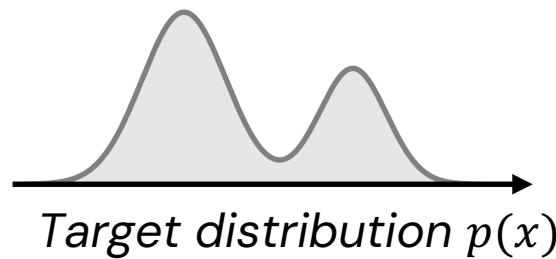
- Estimate the density of  $p$

Forward KL

$$\mathbb{D}_{\text{KL}}(p \parallel \hat{p}) = \mathbb{E}_{x \sim p} \left[ \log \frac{p(x)}{\hat{p}(x)} \right]$$

Reverse KL

$$\mathbb{D}_{\text{KL}}(\hat{p} \| p) = \mathbb{E}_{x \sim \hat{p}} \left[ \log \frac{\hat{p}(x)}{p(x)} \right]$$



# Reverse KL for LM Alignment



- Policy optimization as probability matching under Reverse KL [Ji et al., 2023] (ICML' 24):
  - ◆ Without loss of generality, consider the generalized alignment objective:

$$\mathcal{J}_{\text{lfh}}^{\beta_r}(\pi_{\theta}^{\beta_{\pi}}) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \left( \mathbb{E}_{\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x})} [r_{\phi}(\mathbf{x}, \mathbf{y})] - \beta_r \mathbb{D}_{\text{KL}}[\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x}) \| \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})] \right)$$

- ◆  $\pi_{\theta}^{\beta_{\pi}}$  is the geometric mean of  $\pi_{\theta}$  and  $\pi_{\text{sft}}$

$$\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x}) \propto \pi_{\theta}(\mathbf{y}|\mathbf{x})^{\beta_{\pi}} \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})^{1-\beta_{\pi}}$$

- ◆ Decompose the KL regularization

$$\beta = \beta_r \cdot \beta_{\pi}$$

regularize    regularize  
reward            policy

- ◆ Analytic solution is also  $\pi_{\beta}^*$ .
- ◆ Unify the regularization setting of PPO ( $\beta_{\pi} = 1, \beta_r = \beta$ ) and DPO ( $\beta_{\pi} = \beta, \beta_r = 1$ )

# Reverse KL for LM Alignment



- Deriving the probability matching objective of  $\mathcal{J}_{\text{lfh}}^{\beta_r}(\pi_\theta^{\beta_\pi})$

$$\mathbb{D}_{\text{KL}}(\pi_\theta^{\beta_\pi} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_\theta^{\beta_\pi}(\mathbf{y}|\mathbf{x})} \left[ \log \frac{\pi_\theta^{\beta_\pi}(\mathbf{y}|\mathbf{x})}{\pi_{\beta_r}^*(\mathbf{y}|\mathbf{x})} \right]$$



Importance Sampling (IS)  
 $\pi_{\text{sft}}$  as the proposal distribution

$$\mathbb{D}_{\text{KL}}(\pi_\theta^{\beta_\pi} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \left[ \frac{\pi_\theta^{\beta_\pi}(\mathbf{y}|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \log \frac{\pi_\theta^{\beta_\pi}(\mathbf{y}|\mathbf{x})}{\pi_{\beta_r}^*(\mathbf{y}|\mathbf{x})} \right]$$



Define  $f_\theta(\mathbf{x}, \mathbf{y}) = \log \pi_\theta^{\beta_\pi}(\mathbf{y}|\mathbf{x}) - \log \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})$   
as the log policy ratio

$$\mathbb{D}_{\text{KL}}(\pi_\theta^{\beta_\pi} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \left[ e^{f_\theta(\mathbf{x}, \mathbf{y})} \log \frac{e^{f_\theta(\mathbf{x}, \mathbf{y})}}{\frac{1}{Z_{\beta_r}(\mathbf{x})} e^{\frac{r_\phi(\mathbf{x}, \mathbf{y})}{\beta_r}}} \right]$$

# Reverse KL for LM Alignment



- Deriving the probability matching objective of  $\mathcal{J}_{\text{lfh}}^{\beta_r}(\pi_\theta^{\beta_\pi})$

$$\mathbb{D}_{\text{KL}}(\pi_\theta^{\beta_\pi} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \left[ e^{f_\theta(\mathbf{x}, \mathbf{y})} \log \frac{e^{f_\theta(\mathbf{x}, \mathbf{y})}}{\frac{1}{Z_{\beta_r}(\mathbf{x})} e^{\frac{r_\phi(\mathbf{x}, \mathbf{y})}{\beta_r}}} \right]$$

- The partition function  $Z_{\beta_r}(\mathbf{x})$  is intractable.
- Inspiration from Self-Normalized Importance Sampling (SNIS)
- Sample  $K$  i.i.d. continuations  $\mathbf{y}_{1:K} = \{\mathbf{y}_1, \dots, \mathbf{y}_K\}$  from  $\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})$

$$Z_{\beta_r}(\mathbf{x}) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} [\exp(\frac{r_\phi(\mathbf{x}, \mathbf{y})}{\beta_r})]$$

$$\mathbb{D}_{\text{KL}}(\pi_\theta^{\beta_\pi} \parallel \pi_{\beta_r}^*) = \lim_{K \rightarrow \infty} \sum_{k=1}^K \frac{e^{f_\theta(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K e^{f_\theta(\mathbf{x}, \mathbf{y}_j)}} \log \frac{\frac{e^{f_\theta(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K e^{f_\theta(\mathbf{x}, \mathbf{y}_j)}}}{\frac{e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K \frac{1}{\beta_r} e^{r_\phi(\mathbf{x}, \mathbf{y}_j)}}}$$

*Distribution of log policy ratio*

$p_{f_\theta}(i|\mathbf{y}_{1:K}, \mathbf{x})$

*Distribution of reward model*

# Reverse KL for LM Alignment



- Deriving the probability matching objective of  $\mathcal{J}_{\text{lfh}}^{\beta_r}(\pi_\theta^{\beta_\pi})$

$$\mathbb{D}_{\text{KL}}(\pi_\theta^{\beta_\pi} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \left[ e^{f_\theta(\mathbf{x}, \mathbf{y})} \log \frac{e^{f_\theta(\mathbf{x}, \mathbf{y})}}{\frac{1}{Z_{\beta_r}(\mathbf{x})} e^{\frac{r_\phi(\mathbf{x}, \mathbf{y})}{\beta_r}}} \right]$$

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Reverse KL  $\mathbb{D}_{\text{KL}}(p_{f_\theta} \parallel p_{r_\phi})$  of  $p_{f_\theta}$  and  $p_{r_\phi}$

# Reverse KL for LM Alignment



- Efficient Exact Optimization (**EXO**) of the alignment objective

- Learning from the reward model

$$\mathcal{L}_{\text{exo}}(\pi_\theta) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}_{1:K} | \mathbf{x})} \left[ \mathbb{D}_{\text{KL}}(p_{f_\theta}(\cdot | \mathbf{y}_{1:K}, \mathbf{x}) \| p_{r_\phi}(\cdot | \mathbf{y}_{1:K}, \mathbf{x})) \right]$$

- Where we define: *regularize policy*

$$p_{f_\theta}(i | \mathbf{y}_{1:K}, \mathbf{x}) = \frac{e^{\beta_\pi \log \frac{\pi_\theta(\mathbf{y}_i | \mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}_i | \mathbf{x})}}}{\sum_{j=1}^K e^{\beta_\pi \log \frac{\pi_\theta(\mathbf{y}_j | \mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}_j | \mathbf{x})}}}$$

*regularize reward*

$$p_{r_\phi}(i | \mathbf{y}_{1:K}, \mathbf{x}) = \frac{e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_i)}}{\sum_{j=1}^K e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_j)}}$$

- Learning from the preference data ( $K=2$ )

$$\mathcal{L}_{\text{exo-pref}}(\pi_\theta) = \mathbb{E}_{(\mathbf{x}, \mathbf{y}_w, \mathbf{y}_l) \sim \mathcal{D}^{\text{pref}}} \left[ \mathbb{D}_{\text{KL}}(p_{f_\theta}(\cdot | \mathbf{y}_w, \mathbf{y}_l, \mathbf{x}) \| p_{r_h}(\cdot | \mathbf{y}_w, \mathbf{y}_l, \mathbf{x})) \right]$$

- Where the preference probability  $p_{r_h}(\cdot | \mathbf{y}_w, \mathbf{y}_l, \mathbf{x})$  is a label-smoothed one-hot distribution.

# Reverse KL for LM Alignment



## ◎ Analysis

◆ Unbiased gradient ( $K \rightarrow \infty$ ):

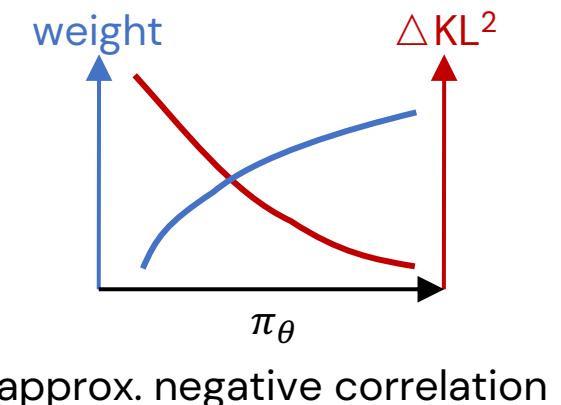
$$\begin{aligned}\nabla_{\theta} \mathcal{L}_{\text{exo}}(\pi_{\theta}) &= \nabla_{\theta} \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} [\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x}) \| \pi_{\beta_r}^{*}(\mathbf{y}|\mathbf{x}))] \\ &= -\frac{1}{\beta_r} \nabla_{\theta} \mathcal{J}_{\text{lhf}}^{\beta_r}(\pi_{\theta}^{\beta_{\pi}}).\end{aligned}$$

- In practice, a finite  $K$  slightly introduces bias while reduces variance.

◆ Asymptotic variance comparison:

$$\text{Var}[\hat{\text{KL}}_{\text{exo}}] = \mathbb{E}_{\mathbf{y} \sim \pi_{\theta}} \left[ \frac{w(\mathbf{x}, \mathbf{y})}{\mathbb{E}_{\mathbf{y}' \sim \pi_{\theta}} [w(\mathbf{x}, \mathbf{y}')]} \left( \log \frac{\pi_{\theta}(\mathbf{y}|\mathbf{x})}{\pi_{\beta}^{*}(\mathbf{y}|\mathbf{x})} - \text{KL} \right)^2 \right] \quad w(\mathbf{x}, \mathbf{y}) = \frac{\pi_{\theta}(\mathbf{y}|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})}$$

$$\text{Var}[\hat{\text{KL}}_{\text{ppo}}] = \mathbb{E}_{\mathbf{y} \sim \pi_{\theta}} \left[ \left( \log \frac{\pi_{\theta}(\mathbf{y}_i|\mathbf{x})}{\pi_{\beta}^{*}(\mathbf{y}_i|\mathbf{x})} - \text{KL} \right)^2 \right]$$



# Comparison with DPO



## ◎ Generalizing DPO:

- ◆ Sample  $K$  completions  $\mathbf{y}_{1:K} = \{\mathbf{y}_1, \dots, \mathbf{y}_K\}$  from  $\pi_{\text{sft}}(y|x)$
- ◆ Generalize hard label to soft label

$$\mathcal{L}_{\text{dpo-rw}}(\pi_\theta) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}_{1:K}|\mathbf{x})} \left[ - \sum_{i=1}^K \frac{e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_i)}}{\sum_{j=1}^K e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_j)}} \log \frac{e^{\beta_\pi \log \frac{\pi_\theta(\mathbf{y}_i|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}_i|\mathbf{x})}}}{\sum_{j=1}^K e^{\beta_\pi \log \frac{\pi_\theta(\mathbf{y}_j|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}_j|\mathbf{x})}}} \right]$$

Forward KL  $\mathbb{D}_{\text{KL}}(p_{f_\theta} || p_{r_\phi})$  of  $p_{f_\theta}$  and  $p_{r_\phi}$  (up to a constant)

- ◆ The gradient of DPO-rw aligns with the gradient of the forward KL asymptotically for policy with **arbitrary**  $\theta$  when  $K \rightarrow \infty$ .

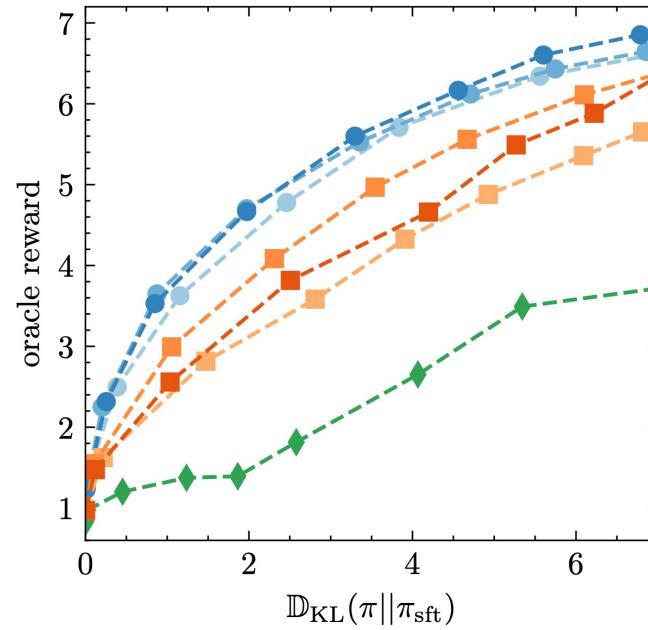
$$\nabla_\theta \mathcal{L}_{\text{dpo-rw}}(\pi_\theta) = \nabla_\theta \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} [\mathbb{D}_{\text{KL}}(\pi_{\beta_r}^*(\mathbf{y}|\mathbf{x}) || \pi_\theta^{\beta_\pi}(\mathbf{y}|\mathbf{x}))]$$

- ◎ **Inexactness:** DPO minimizes the forward KL, while RLHF, e.g., PPO minimizes the reverse KL.

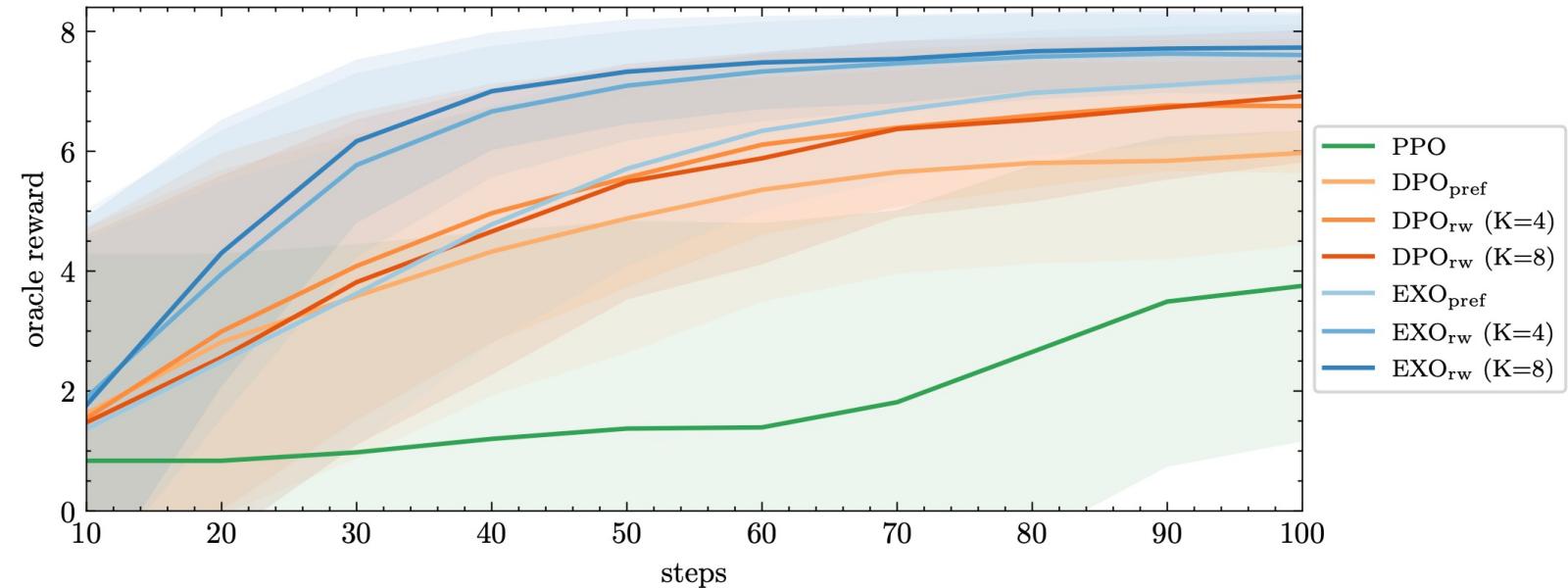
# Experiments



- Synthetic experiment: Generate IMDB review with positive sentiment
  - ◆ Oracle reward (Human labeler): Classifier trained on IMDB review classification dataset



**Oracle reward vs  $KL$**



**Oracle reward vs Training steps**

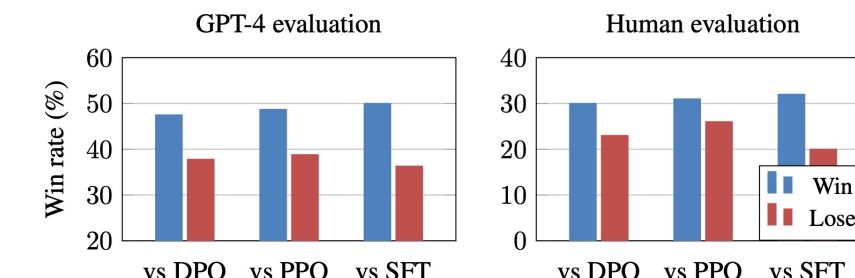
# Experiments



- Alignment on real human preferences:
  - Text summarization: TL;DR preference dataset
  - Dialogue generation: Anthropic-HH dataset (helpfulness subset)
  - Instruction following: Filtered real user query from an online API

Method	Reward Model (%)		GPT-4 (%)	
	vs SFT	vs Chosen	vs SFT	vs Chosen
w/ Preferences				
DPO <sub>pref</sub>	68.3	23.7	57.0	30.5
EXO <sub>pref</sub>	<b>92.5</b>	<b>60.1</b>	<b>83.0</b>	<b>55.0</b>
w/ Reward Model				
Best-of- $N$	99.3	75.8	83.5	60.0
PPO	93.2	58.3	77.0	52.0
DPO <sub>rw</sub>	82.7	39.8	70.0	41.0
EXO <sub>rw</sub>	<b>97.3</b>	<b>76.4</b>	<b>88.5</b>	<b>64.0</b>

Method	Reward Model (%)		GPT-4 (%)	
	vs SFT	vs Chosen	vs SFT	vs Chosen
w/ Preferences				
DPO <sub>pref</sub>	66.3	65.1	58.0	37.0
EXO <sub>pref</sub>	<b>76.4</b>	<b>76.7</b>	<b>73.0</b>	<b>51.0</b>
w/ Reward Model				
Best-of- $N$	94.6	98.2	86.0	63.0
PPO	75.0	74.0	66.5	52.0
DPO <sub>rw</sub>	79.9	81.3	75.5	49.0
EXO <sub>rw</sub>	<b>85.6</b>	<b>87.2</b>	<b>83.5</b>	<b>60.0</b>



- Outperforms DPO and PPO in both settings of learning from preferences & reward model.
- On par with Best-of- $N$  ( $N=128$ ) but much more computationally efficient in inference.
- Scaling to realistic instruction-following dataset with consistent improvement.

# Experiments



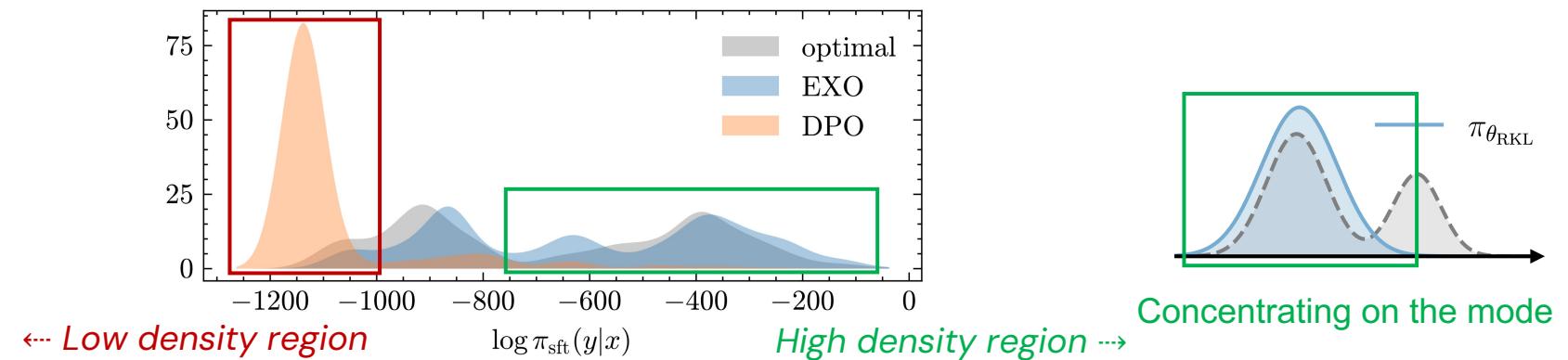
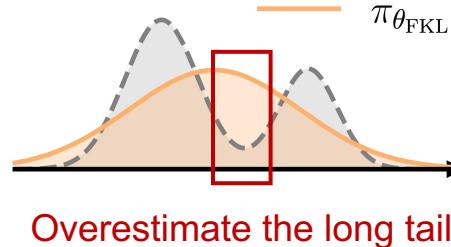
- Visualization: Compare the density of DPO and EXO with the optimal policy

- Given a test prompt "**This Fox spectacle was a big hit when released in**"
- Estimate the empirical policy distribution of  $\pi_\theta$  and  $\pi_\beta^*$  by SNIS:

$$\hat{\pi}_\theta(\mathbf{y}_i|\mathbf{x}) = \frac{M\pi_\theta(\mathbf{y}_i|\mathbf{x})}{\sum_{j=1}^M \pi_\theta(\mathbf{y}_j|\mathbf{x})/\pi_{\text{sft}}(\mathbf{y}_j|\mathbf{x})}$$

$$\hat{\pi}_\beta^*(\mathbf{y}_i|\mathbf{x}) = \frac{M\pi_{\text{sft}}(\mathbf{y}_i|\mathbf{x}) \exp(r(\mathbf{x}, \mathbf{y}_i)/\beta)}{\sum_{j=1}^M \exp(r(\mathbf{x}, \mathbf{y}_j)/\beta)}$$

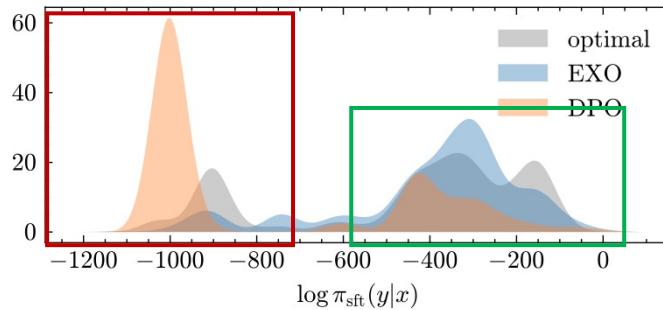
- Use Kernel Density Estimation to estimate the density and plot the ratio  $\rho_{\hat{\pi}}(\mathbf{y}|\mathbf{x}) = \frac{\hat{\pi}(\mathbf{y}|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})}$



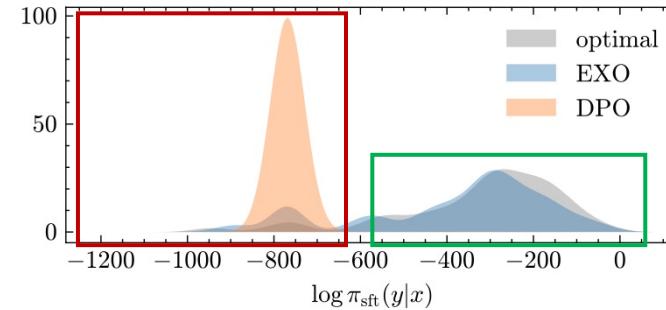
# Experiments



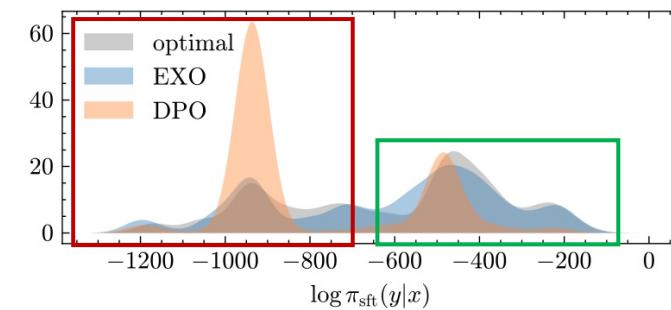
- More visualization cases: (*prevailing phenomenon, no cherry-picking*)



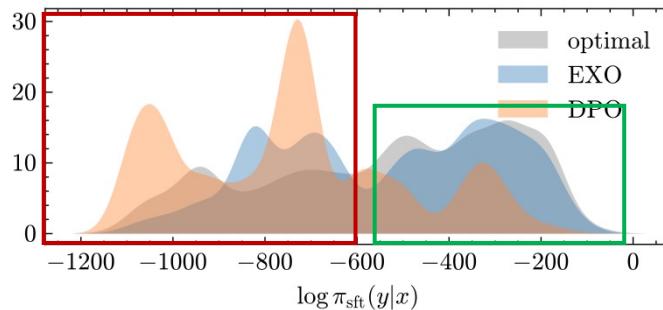
Estimated density ratio of the EXO, DPO and optimal policy given the prompt “*Is this supposed to be serious? I hope not*”.



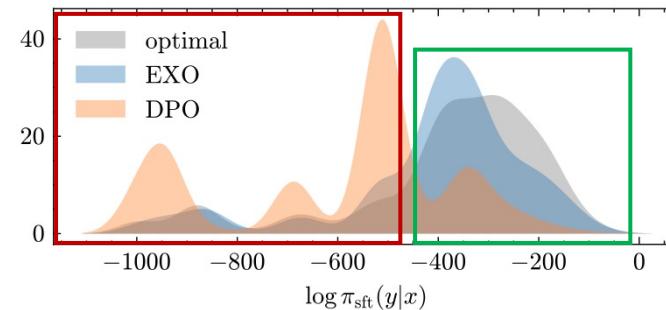
Estimated density ratio of the EXO, DPO and optimal policy given the prompt “*Great book, great movie, great soundtrack. Frank*”.



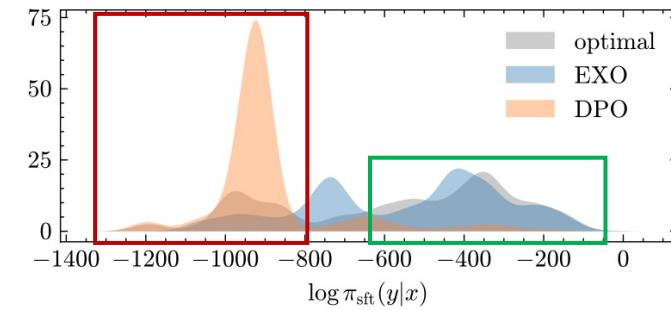
Estimated density ratio of the EXO, DPO and optimal policy given the prompt “*What we have here is the standard Disney direct to DVD*”.



Estimated density ratio of the EXO, DPO and optimal policy given the prompt “*This is indeed the film that popularized kung*”.



Estimated density ratio of the EXO, DPO and optimal policy given the prompt “*This movie is about a group of people who are*”.



Estimated density ratio of the EXO, DPO and optimal policy given the prompt “*Once the slow beginning gets underway, the film kicks*”.



## ◎ Beyond MLE: Quality-aware objective

- ◆ Reverse KL [**ICML' 24**]: quality assessed by reward that captures human preference
- ◆ **Total variation distance [ICLR' 23]**: quality assessed by the “optimal classifier” in theory

## ◎ Beyond AR: Expressive model family

- ◆ Energy-based model [**ICLR' 24**]: Augment AR model with a residual energy model
- ◆ Latent-variable model [**EMNLP' 21**]: Condition AR model with a latent plan
- ◆ Look-up model [**EMNLP' 20**]: Extend AR model with a parallel database look-up

# Beyond MLE for AR LM



- Total variation distance (TVD): quality assessed by “**optimal classifier**”
  - ◆ TVD reflects the “accuracy” of an optimal classifier that try to discriminate true data and model generated data

$$c \sim p(c) = \text{Bernoulli}\left(\frac{1}{2}\right) \quad \text{Prior label distribution}$$

$$\mathbf{y} \sim p(\mathbf{y}|\mathbf{x}, c) = \begin{cases} p_d(\mathbf{y}|\mathbf{x}) & \text{if } c = 1 \\ p_\theta(\mathbf{y}|\mathbf{x}) & \text{if } c = 0 \end{cases} \quad \begin{array}{ll} \text{True data} & \\ \text{Model generated data} & \end{array}$$

$$\|p_d - p_\theta\|_{\text{TV}} = 1 - 2 \inf_f \underbrace{\mathbb{P}\left(f(\mathbf{x}, \mathbf{y}) \neq c\right)}_{\text{error rate}} \quad \text{TVD defined by optimal error rate}$$

- ◆ **Intuition:** The closer  $p_\theta$  and  $p_d$  is, the harder for the optimal classifier to discriminate.  
(The upper-bound of error rate is 50%, i.e., by chance)

# TVD for LM Fine-Tuning



- Learning objective for LM based on TVD [Ji et al., 2023] (ICLR'23 Oral):

- Measuring the distance in discrete sequence space:

$$\begin{aligned}\|p_d - p_\theta\|_{\text{TV}} &= \frac{1}{2} \sum_{\mathbf{y} \in \mathcal{Y}} |p_d(\mathbf{y}|\mathbf{x}) - p_\theta(\mathbf{y}|\mathbf{x})| \quad \text{L1-distance} \\ &= 1 - \sum_{\mathbf{y} \in \mathcal{Y}} \min(p_d(\mathbf{y}|\mathbf{x}), p_\theta(\mathbf{y}|\mathbf{x}))\end{aligned}$$

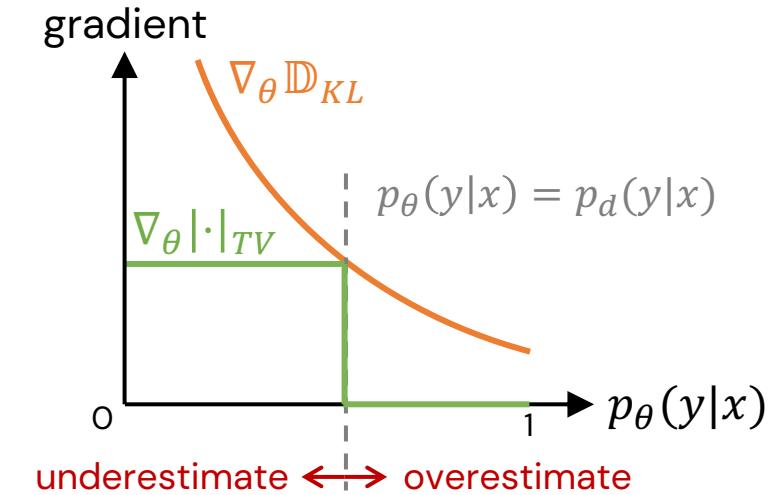
- Gradient analysis:  $y \sim p_d$

- Gradient of FKL

$$\nabla_\theta \mathbb{D}_{\text{KL}}(p_d \| p_\theta) \approx -\frac{\nabla_\theta p_\theta(\mathbf{y}|\mathbf{x})}{p_\theta(\mathbf{y}|\mathbf{x})} \quad \text{Assign non-zero } p_\theta \text{ to every data point}$$

- Gradient of TVD

$$\nabla_\theta \|p_d - p_\theta\|_{\text{TV}} \approx \begin{cases} -\frac{\nabla_\theta p_\theta(\mathbf{y}|\mathbf{x})}{p_d(\mathbf{y}|\mathbf{x})}, & p_\theta(\mathbf{y}|\mathbf{x}) < p_d(\mathbf{y}|\mathbf{x}) \\ 0, & p_\theta(\mathbf{y}|\mathbf{x}) \geq p_d(\mathbf{y}|\mathbf{x}) \end{cases}$$



# TVD for LM Fine-Tuning



- Learning objective for LM based on TVD [Ji et al., 2023] (ICLR'23 Oral):

- Measuring the distance in discrete sequence space:

$$\begin{aligned}\|p_d - p_\theta\|_{\text{TV}} &= \frac{1}{2} \sum_{\mathbf{y} \in \mathcal{Y}} |p_d(\mathbf{y}|\mathbf{x}) - p_\theta(\mathbf{y}|\mathbf{x})| \\ &= 1 - \sum_{\mathbf{y} \in \mathcal{Y}} \min(p_d(\mathbf{y}|\mathbf{x}), p_\theta(\mathbf{y}|\mathbf{x}))\end{aligned}$$

L1-distance

- Gradient analysis:  $y \sim p_d$

- Gradient of FKL

Learning objective for LM based on TVD [Ji et al., 2023] (ICLR'23 Oral)

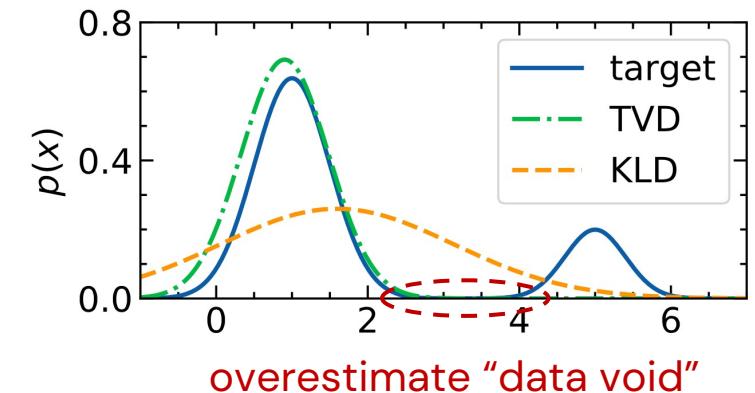
Measuring the distance in discrete sequence space:

Gradient analysis:  $y \sim p_d$   
Gradient of FKL  
Gradient of TVD

Assign non-zero  $p_\theta$  to every data point

- Gradient of TVD

$$\nabla_\theta \|p_d - p_\theta\|_{\text{TV}} \approx \begin{cases} -\frac{\nabla_\theta p_\theta(\mathbf{y}|\mathbf{x})}{p_d(\mathbf{y}|\mathbf{x})}, & p_\theta(\mathbf{y}|\mathbf{x}) < p_d(\mathbf{y}|\mathbf{x}) \\ 0, & p_\theta(\mathbf{y}|\mathbf{x}) \geq p_d(\mathbf{y}|\mathbf{x}) \end{cases}$$



# TVD for LM Fine-Tuning

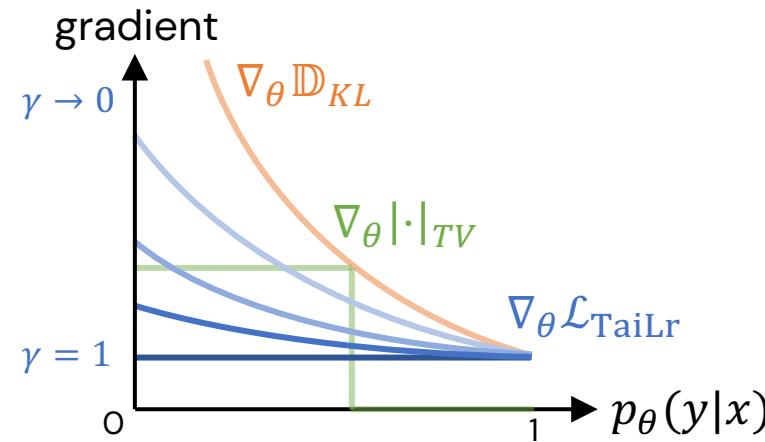


- Learning objective for LM based on TVD [Ji et al., 2023] (ICLR'23 Oral):

- TaiLr objective

$$\mathcal{L}_{\text{TaiLr}}(w; \theta) = - \underbrace{\left( \frac{p_{\theta}^{<t}(w)}{\gamma + (1 - \gamma)p_{\theta}^{<t}(w)} \right)}_{\text{stop gradient}} \log p_{\theta}^{<t}(w)$$

- $\gamma$  trade-offs bias and variance:  $\gamma = 1$  (unbiased TVD)  $\gamma \rightarrow 0$  (bias to KLD)



# Experiments



## Experiments: Various text generation tasks

Other MLE variants

TVD-based

Method	Dev BLEU	Test BLEU
MLE	35.81 <sup>‡</sup>	34.27 <sup>‡</sup>
Unlikelihood	33.92 <sup>‡</sup>	32.82 <sup>‡</sup>
D2GPo	36.09 <sup>‡</sup>	34.50 <sup>‡</sup>
Loss truncation	35.63 <sup>†</sup>	34.48 <sup>‡</sup>
GOLD	35.74 <sup>‡</sup>	34.68 <sup>†</sup>
TaiLr	<b>36.44</b>	<b>35.05</b>

One-way Training		Test BLEU
BiBERT (Table 2, Xu et al. 2021)		37.58
BiBERT (Our implementation)		38.01
<b>BiBERT + TaiLr</b>		<b>39.12</b>
Dual-directional Training + Fine-Tuning		Test BLEU
BiBERT (Table 3, Xu et al. 2021)		38.61
BiBERT (Our implementation)		38.73
<b>BiBERT + TaiLr</b>		<b>39.23</b>

Machine translation: Improve over the **2022 SOTA (BiBERT)** on IWSLT14

Method	B-1↑	D-4↑	rep-8↓	Mauve↑
MLE	27.85	84.28	10.31 <sup>†</sup>	56.42 <sup>‡</sup>
Unlikelihood	27.88	85.46	10.06	59.35 <sup>‡</sup>
D2GPo	22.73 <sup>‡</sup>	84.10	10.04	53.35 <sup>‡</sup>
Loss truncation	19.49 <sup>‡</sup>	76.51 <sup>‡</sup>	13.41 <sup>‡</sup>	45.35 <sup>‡</sup>
GOLD	25.25 <sup>‡</sup>	46.98 <sup>‡</sup>	28.23 <sup>‡</sup>	15.44 <sup>‡</sup>
TaiLr	<b>28.62</b>	<b>85.56</b>	<b>9.73</b>	<b>64.64</b>

Long text generation

Method	R-1	R-2	R-L
MLE	38.24 <sup>‡</sup>	19.12	35.70 <sup>†</sup>
Unlikelihood	37.80 <sup>‡</sup>	18.34 <sup>‡</sup>	34.84 <sup>‡</sup>
D2GPo	38.52 <sup>†</sup>	18.92 <sup>†</sup>	35.64 <sup>‡</sup>
Loss truncation	38.62	19.29	35.85 <sup>†</sup>
GOLD	38.57 <sup>†</sup>	19.27	35.79 <sup>†</sup>
TaiLr	<b>38.82</b>	<b>19.50</b>	<b>36.24</b>

Text summarization

- **Takeaway & Future:**
- The desired learning goal should capture quality, which might not always have a tractable form.
- Effectiveness and efficiency of learning: Bias-variance tradeoff
  - ◆ Variance: Sparsity and complexity of data
  - ◆ Bias: Inductive bias of estimation method
- **Principle:** Reduce variance with controlled bias



- Beyond MLE: Quality-aware objective

- ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
- ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory

- **Beyond AR: Expressive model family**

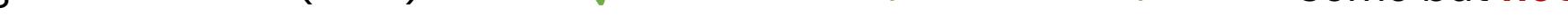
- ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
- ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
- ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up

# Beyond Auto-Regressive Model



- Parametric sequence model families [Lin et al., 2020]

Model Family	Compact parameters	Efficient scoring	Efficient sampling	Support of distribution
Auto-Regressive Model (ARM)	✓	✓	✓	Some but <b>not all</b> $S \in P$
Energy-Based Model (EBM)	✓	✓	✗	All $S \in P$
Latent-Variable Model (LVM)	✓	✗	✓	All $S \in NP$
Look-Up Model (LUM)	✗	✓	✓	All $S$



- ◆ **Compact parameters**: Parameter complexity grow in  $O(\text{poly}(n))$
  - ◆ **Efficient scoring**: Score a sequence in time of  $O(\text{poly}(n))$
  - ◆ **Efficient sampling**: Sample a sequence in time of  $O(\text{poly}(n))$

\* $n$ : sequence length

# Beyond the theoretical limits of language modeling



- **Beyond MLE:** Quality-aware objective
  - ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
  - ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory
  
- **Beyond AR:** Expressive model family
  - ◆ **Energy-based model [ICLR' 24]:** Augment AR model with a residual energy model
  - ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
  - ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up

# Energy-Based Model



- **Definition:** Assign low energy to sequence with high probability

$$p(\mathbf{y}|\mathbf{x}) = \frac{e^{-E_\theta(\mathbf{x}, \mathbf{y})}}{\sum_{\mathbf{y}'} e^{-E_\theta(\mathbf{x}, \mathbf{y}')}} = \frac{e^{-E_\theta(\mathbf{x}, \mathbf{y})}}{Z(\mathbf{x})}$$

- ◆ Energy function:  $E_\theta(\mathbf{x}, \mathbf{y})$  scores the complete sequence  $\mathbf{y}$
- ◆ Partition function:  $Z(\mathbf{x})$  is the normalizing constant which is intractable

- **Advantage:** Conditional probability implicitly marginalizing out the future

$$p(y_t | \mathbf{y}_{<t}, \mathbf{x}) = \frac{\sum_{\mathbf{y}'_{>t}} e^{-E_\theta(\mathbf{x}, \mathbf{y}_{<t}, y_t, \mathbf{y}'_{>t})}}{\sum_{\mathbf{y}'_{\geq t}} e^{-E_\theta(\mathbf{x}, \mathbf{y}_{<t}, \mathbf{y}'_{\geq t})}} = \frac{Z(\mathbf{x}, \mathbf{y}_{<t}, y_t)}{Z(\mathbf{x}, \mathbf{y}_{<t})}$$

- ◆ **Intuition:** EBM shows that **exactly computing** the conditional probability requires considering **all possibilities** in the future. Local normalization is insufficient (AR model)

# Energy-Based Model



- ⦿ **Disadvantage:** MLE, sampling for EBM is expensive due to intractable  $Z(\mathbf{x})$
- ⦿ **Noise-Contrastive Estimation (NCE):** Sampling-free method
  - ◆ **Intuition:** Reducing energy **only** on correct data points does not guarantee increasing their probability. Need to “push them down wrong points”.
  - ◆ **Ranking objective:**
$$\min_{\theta} \mathbb{E}_{\mathbf{y}_+ \sim p_d, \mathbf{y}_-^{(1:K)} \sim p_N} \left[ -\log \frac{e^{s_{\theta}(\mathbf{x}, \mathbf{y}_+)}}{e^{s_{\theta}(\mathbf{x}, \mathbf{y}_+)} + \sum_{k=1}^K e^{s_{\theta}(\mathbf{x}, \mathbf{y}_-^{(k)})}} \right]$$
  - ◆ **Score function:**
$$s_{\theta}(\mathbf{x}, \mathbf{y}) = -E_{\theta}(\mathbf{x}, \mathbf{y}) - \log p_N(\mathbf{y}|\mathbf{x})$$
  - ◆ It is critical to choose an **appropriate noise distribution** which is useful for fine-grained characterization of the energy landscape.

# Energy-Based Model



- **Residual EBM:** Leverage the inductive bias of local normalized AR model

$$p(\mathbf{y}|\mathbf{x}) = p_\theta(\mathbf{y}|\mathbf{x}) \frac{\exp[-E_\phi(\mathbf{x}, \mathbf{y})]}{Z(\mathbf{x})}$$

- ◆ NCE improves over the base AR model by setting  $p_N = p_\theta$
- ◆ **Facilitate sampling from EBM:**

(1) **Sampling** from AR proposal

$$\{\mathbf{y}^{(k)}\}_{k=1}^K \sim p_\theta(\mathbf{y}|\mathbf{x})$$

(2) **Resampling** with energy function

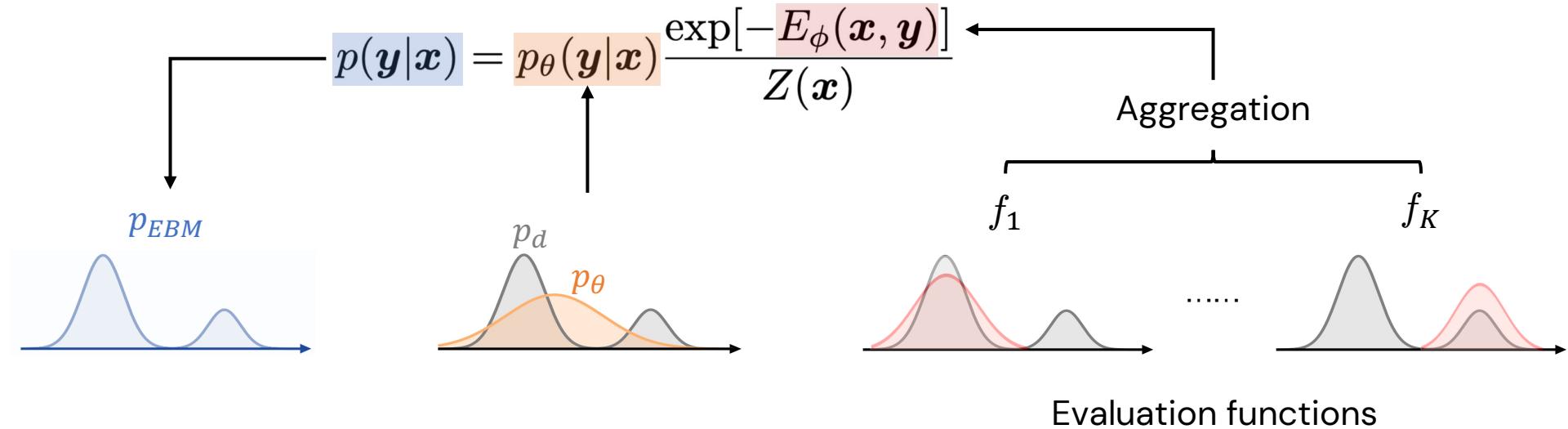
$$\mathbf{y} \sim \text{Cat}\left(\text{softmax}[-E_\theta(\mathbf{x}, \mathbf{y}^{(k)})]\right)$$

- ◆ Training a new EBM using NCE every time is **costly** and **restrictive**, considering a large number of available **evaluation metrics**, **reward model**, **classifiers**, etc.
- ◆ Can we leverage those evaluation functions to build EBM?

# Energy-Based Model



- Build EBM by aggregating evaluation functions [Ji et al., 2024] (ICLR' 24):



- ◆  $\{f_k\}_{k=1}^K$  evaluate different aspect of the distribution
- ◆ How to aggregate different evaluation functions?

# Energy-Based Model



- ⦿ Build EBM by aggregating evaluation functions [Ji et al., 2024] (ICLR' 24):
  - ◆ Aggregation criteria for unconditional LM decoding:
    - Overall quality: Samples drawn from EBM are “good” on **all** evaluation functions

$$\mathbb{E}_{\mathbf{y} \sim p}[f_k(\mathbf{y})] = \mathbb{E}_{\mathbf{y} \sim p_d}[f_k(\mathbf{y})], \forall k \in [1, K]$$

- Regularization: Explore within the support of AR LM distribution:

$$\min_p \mathbb{D}_{\text{KL}}(p \| p_\theta)$$

- ◆ The optimal solution is exactly EBM:

$$p^*(\mathbf{y}) \propto p_\theta(\mathbf{y}) \exp \left[ - \sum_{k=1}^K \mu_k^* f_k(\mathbf{y}) \right]$$

- Energy function is the **linear combination** of evaluation functions  $\{f_k\}_{k=1}^K$
- $K$  optimal weights  $\{\mu_k^*\}_{k=1}^K$  are automatically determined by solving the constraints.

# Energy-Based Model

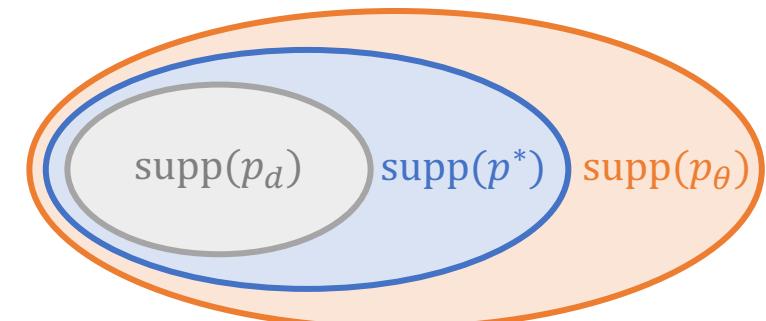


- Build EBM by aggregating evaluation functions [Ji et al., 2024] (ICLR' 24):

- Theoretical results:  $p^*$  is a better approximation of  $p_d$

- #1  $p^*$  close the **gap of support** to  $p_d$

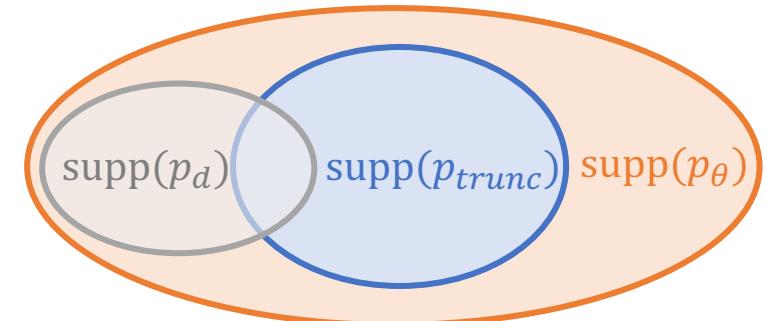
$$\text{supp}(p_d) \subseteq \text{supp}(p^*) \subseteq \text{supp}(p_\theta)$$



- Iterating the process effectively approaches  $p_d$

- Theoretical results:  $p^*$  is a better approximation of  $p_d$

$$\text{supp}(p_d) \not\subseteq \text{supp}(p_{\text{trunc}}) \subseteq \text{supp}(p_\theta)$$



- Lead to a biased distribution
- Lose coverage to the complete  $p_d$

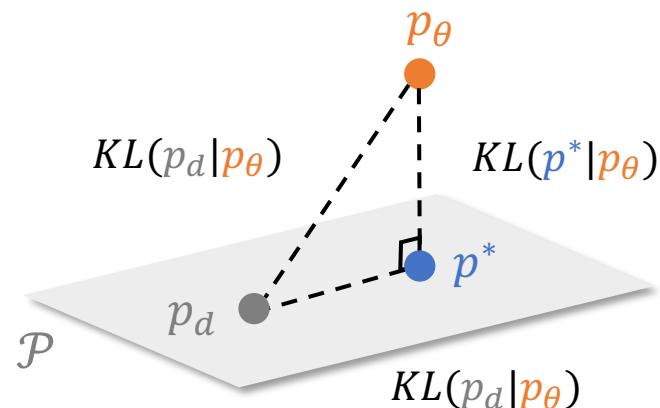
# Energy-Based Model



- Build EBM by aggregating evaluation functions [Ji et al., 2024] (ICLR' 24):
  - Theoretical results:  $p^*$  is a better approximation of  $p_d$
  - #2  $p^*$  is guaranteed to improve **perplexity** ( $2^H$ ) on  $p_d$

$$H(p_d, p^*) = H(p_d, p_\theta) - \underbrace{\mathbb{D}_{\text{KL}}(p^* \| p_\theta)}_{\text{non-negative}}$$

- Pythagorean theorem of KL divergence:



$p^*$  is the **projection** of  $p_\theta$  on the hyperplane:

$$\mathcal{P} = \{p \mid \mathbb{E}_{\mathbf{y} \sim p}[f_k(\mathbf{y})] = \mathbb{E}_{\mathbf{y} \sim p_d}[f_k(\mathbf{y})], \forall k \in [1, K]\}$$

# Experiments



## ○ Experiments: Unconditional LM decoding

- ◆ Evaluation functions: automatic metrics, e.g., coherence, repetition, diversity, etc.

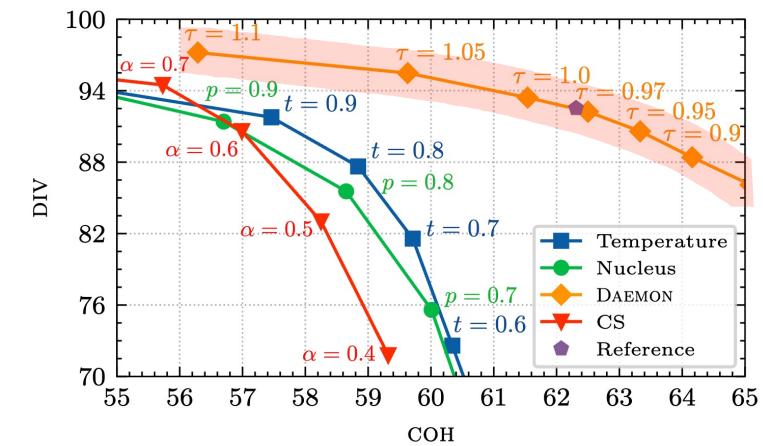
Truncated Sampling  
Contrastive Search  
Sample from EBM

Method	Wikipedia					MAU
	SR-4	TR-32	COH	DIV	$e^{\text{ENT}}$	
Reference	0.48	21.3	62.3	92.5	23.2	-
Greedy	60.9	65.5	60.2	8.03	2.29	59.7
GPT-2 XL	2.11	23.4	60.9	87.8	10.1	77.8
	1.19	20.0	57.3	92.4	17.3	78.3
	0.81	17.4	54.9	94.5	30.1	78.7
	1.31	28.2	68.7	85.9	7.55	77.8
	1.78	23.0	56.9	90.6	5.25	83.3
	0.42	22.5	62.5	92.2	22.8	88.1
	54.8	60.4	62.0	0.12	2.78	64.8
OPT-6.7B	2.44	24.1	61.3	86.6	13.9	77.5
	2.33	21.9	59.1	88.6	18.9	80.1
	1.06	19.6	57.0	92.9	31.9	77.7
	2.90	26.5	68.6	82.3	11.7	78.6
	1.13	21.7	57.7	91.8	8.72	83.3
	0.38	21.6	62.3	92.6	22.7	90.7
	54.8	60.4	62.0	0.12	2.78	64.8

Performance on various metrics

Model	Wikipedia		News	
	ori	imp	ori	imp
GPT-2 XL	23.1	22.0	13.9	13.1
OPT-6.7B	16.4	16.2	10.8	10.2

(Tuning-free) Perplexity improvement



coherence-diversity tradeoff

# Experiments



## Experiments: Multi-objective alignment

- ◆ **Evaluation functions:** reward models, e.g., helpfulness, harmless, etc.
- ◆ Conditional EBM:

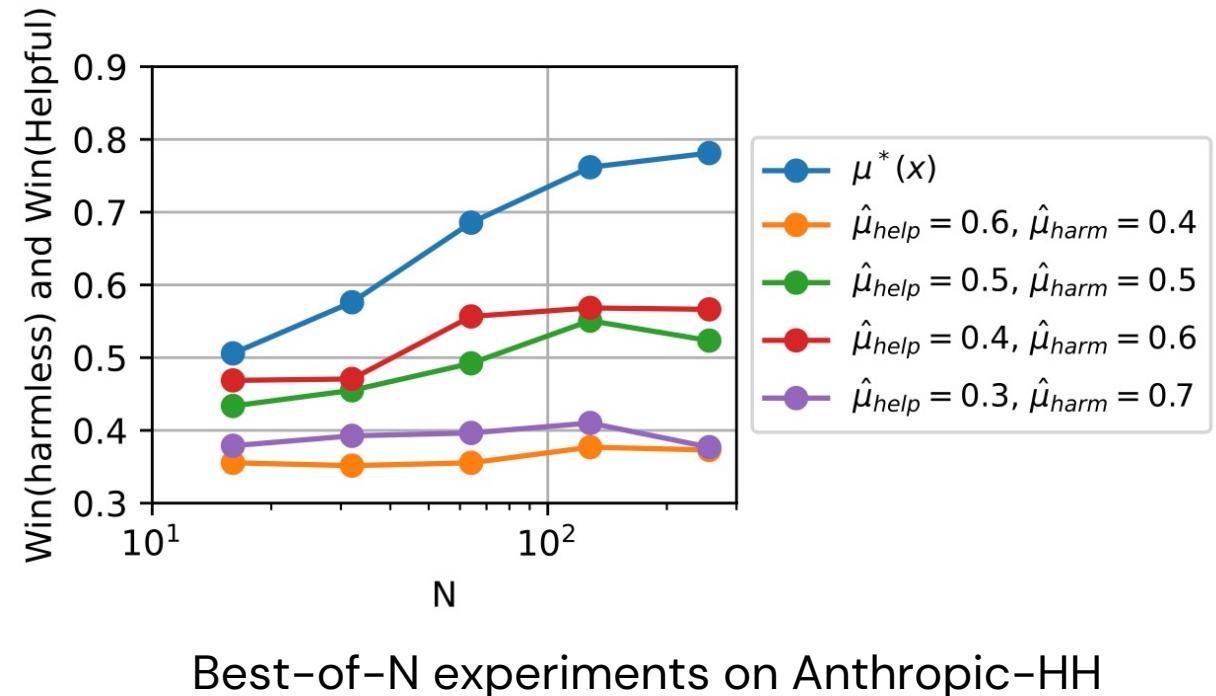
$$p^*(\mathbf{y}|\mathbf{x}) \propto p_\theta(\mathbf{y}|\mathbf{x}) \exp \left[ -E(\mathbf{x}, \mathbf{y}) \right]$$

- Optimal **instance-level** weight:

$$E(\mathbf{x}, \mathbf{y}) = \sum_{k=1}^K \mu_k^*(\mathbf{x}) f_k(\mathbf{x}, \mathbf{y})$$

- Empirical **global** weight:

$$E(\mathbf{x}, \mathbf{y}) = \sum_{k=1}^K \hat{\mu}_k f_k(\mathbf{x}, \mathbf{y})$$



# Energy-Based Model



- **Takeaway & Future:**
- EBM Learning: reward modeling
  - ◆ Aggregation: Compositionality of EBM
  - ◆ Calibration: Uncertainty-Awareness
- EBM Inference: Acceleration
  - ◆ Re-sampling / Rejection sampling
  - ◆ MCMC method: Langevin Dynamics
  - ◆ Score-guided sampling (learn a score function as in diffusion)
  - ◆ Learn tractable AR sampler (lossy due to capacity gap between ARM and EBM)



- **Beyond MLE:** Quality-aware objective

- ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
- ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory

- **Beyond AR:** Expressive model family

- ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
- ◆ **Latent-variable model [EMNLP' 21]:** Condition AR model with a latent plan
- ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up

# Latent-Variable Model



- **Advantage:** Model the unobserved as latent variable increases capacity

$$p(\mathbf{y}|\mathbf{x}) = \int p_{\theta}(\mathbf{y}|\mathbf{x}, \mathbf{z})p_{\theta}(\mathbf{z}|\mathbf{x})d\mathbf{z}$$

- ◆ Theorem [Lin et al., 2020]: Latent-variable AR model has support  $\mathbf{S} \in NP$
- ◆ Intuition: Marginalizing over the **latent “compression”  $\mathbf{z}$**  of the future output  $\mathbf{y}$
- **Disadvantage:** No tractable exact inference of likelihood due to integral over  $\mathbf{z}$ !
- **Variational inference:**

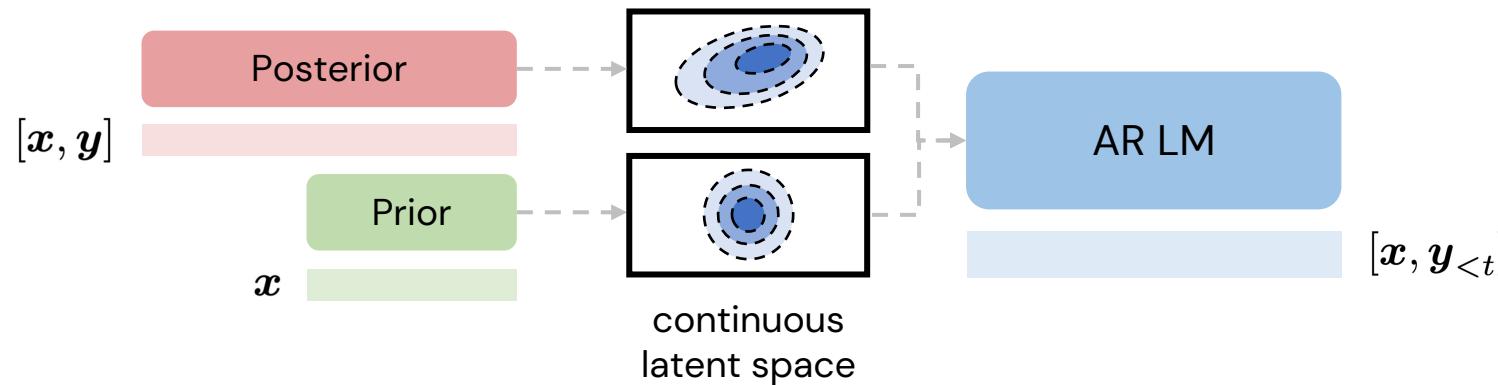
$$p(\mathbf{y}|\mathbf{x}) = \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y})} \left[ \frac{p_{\theta}(\mathbf{y}|\mathbf{x}, \mathbf{z})p_{\theta}(\mathbf{z}|\mathbf{x})}{q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y})} \right]$$

- ◆ The inference is “amortized” by first finding a **good approximated posterior**  $q_{\phi}$  which later facilitates inferring  $\mathbf{y}$  from  $\mathbf{z}$ .

# Latent-Variable Model



- AR model with continuous latent variable [Bowman et al., 2015]:



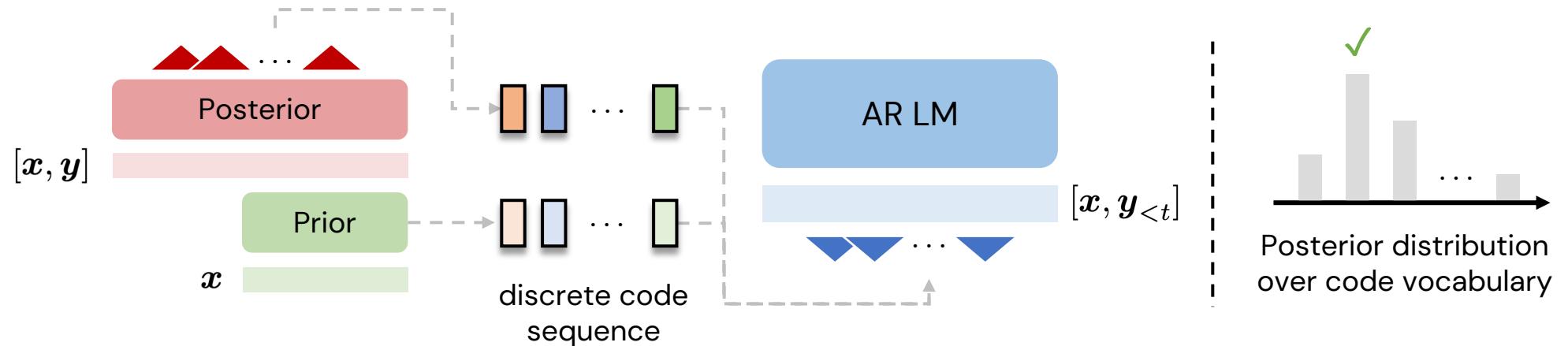
$$\underbrace{-\log p(\mathbf{y}|\mathbf{x})}_{\text{NLL}} \geq \underbrace{\mathbb{E}_{q_\phi(z|\mathbf{y}, \mathbf{x})}[-\log p_\theta(\mathbf{y}|\mathbf{x}, z)]}_{\text{negative reconstruction error}} + \underbrace{\mathbb{D}_{\text{KL}}(q_\phi||p_\theta)[\mathbf{x}]}_{\text{posterior-prior gap}}$$

- ◆ **Posterior collapse:** Posterior distribution collapses to prior distribution ( $\text{KL} \approx 0$ )
- ◆ **Losing long-term dependence:** AR generation ignores  $z$  in the long term

# Latent-Variable Model



- AR model with structural discrete latent codes [Ji et al., 2021] (*EMNLP' 21 Oral*):



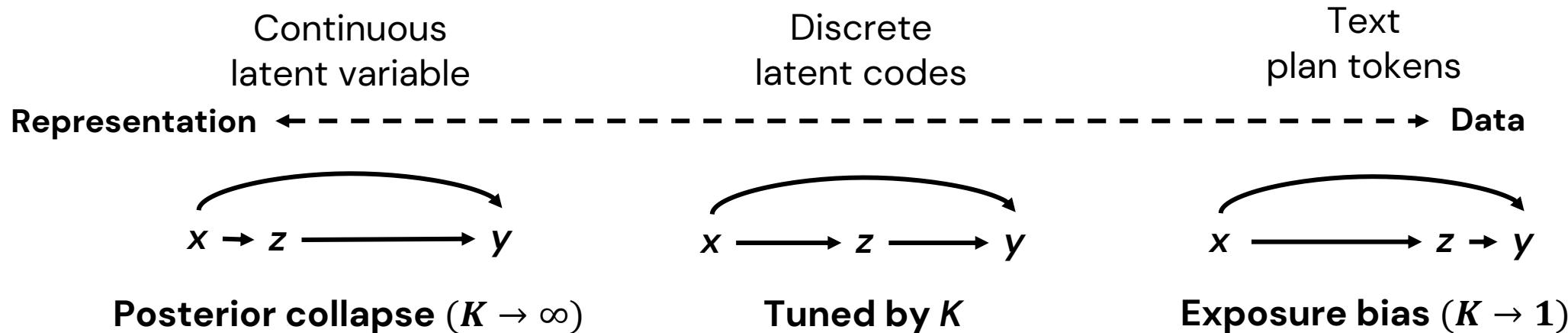
- ◆ Discrete code sequence as “latent plan” that captures the long-term structure of  $y$
- ◆ **Controlled latent capacity:** # latent codes ( $L$ )  $\times$  # code vocabulary ( $K$ )
- ◆ **Decoupling ELBO learning** (due to discretization):
  - Obtain code by argmax over posterior distribution
  - Prior AR model learn the code by MLE

# Latent-Variable Model



## ○ Takeaway & Future :

- ◆ A good latent representation control **amortization** of the “bottleneck”



- ◆ Hierarchical latent-variable model: diffusion model
  - Amortize sampling into multiple stages
  - Diffusion for AR LM



## ○ Beyond MLE: Quality-aware objective

- ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
- ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory

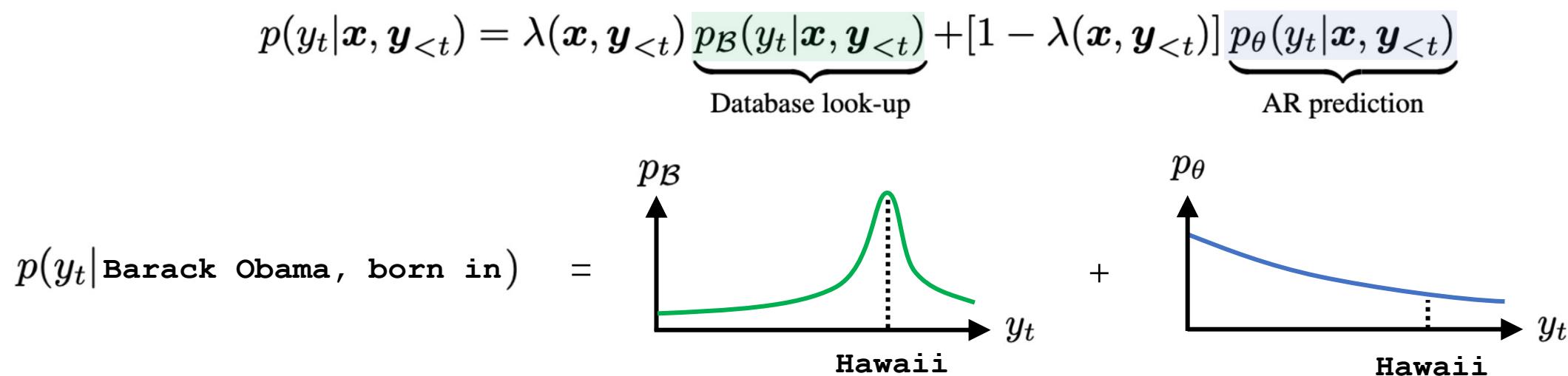
## ○ Beyond AR: Expressive model family

- ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
- ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
- ◆ **Look-up model [EMNLP' 20]**: Extend AR model with a parallel database look-up

# Look-Up Model



- ⦿ **Advantage:** Retrieve low-frequency “items” from the distribution long tail
- ⦿ **Disadvantage:** Naïve look-up model has exploding parameters that stores “all” sequences.
- ⦿ **Practical look-up model:** Semi-parametric models
  - ◆  $\mathcal{B}$ : Database, e.g., text documents, knowledge graphs, etc.
  - ◆  $\theta$ : AR parameters



# Look-Up Model



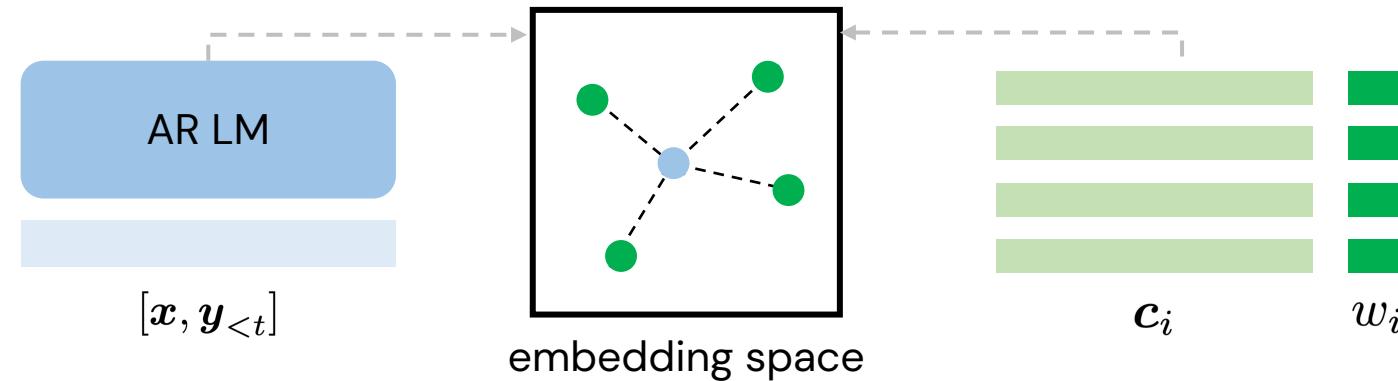
- **Advantage:** Retrieve low-frequency “items” from the distribution long tail
- **Disadvantage:** Naïve look-up model has exploding parameters that stores “all” sequences.
- **Practical look-up model:** Semi-parametric models
  - ◆  $\mathcal{B}$ : Database, e.g., text documents, knowledge graphs, etc.
  - ◆  $\theta$ : AR parameters

$$p(y_t | \mathbf{x}, \mathbf{y}_{<t}) = \lambda(\mathbf{x}, \mathbf{y}_{<t}) \underbrace{p_{\mathcal{B}}(y_t | \mathbf{x}, \mathbf{y}_{<t})}_{\text{Database look-up}} + [1 - \lambda(\mathbf{x}, \mathbf{y}_{<t})] \underbrace{p_{\theta}(y_t | \mathbf{x}, \mathbf{y}_{<t})}_{\text{AR prediction}}$$

- **Parametric vs Non-parametric:**
  - ◆ Parametric AR model is effective at learning local text continuity
  - ◆ Non-parametric database is efficient in capturing sparse relationship

# Look-Up Model

- Semi-parametric model with text-based  $\mathcal{B}$  (kNN-LM) [Khandelwal et al., 2020]:
  - ◆ **key-value** from text documents  $\mathcal{D}$ :  $\mathcal{B} = \{(\mathbf{c}^i, w^i) | (\mathbf{c}^i, w^i) \in \mathcal{D}\}$

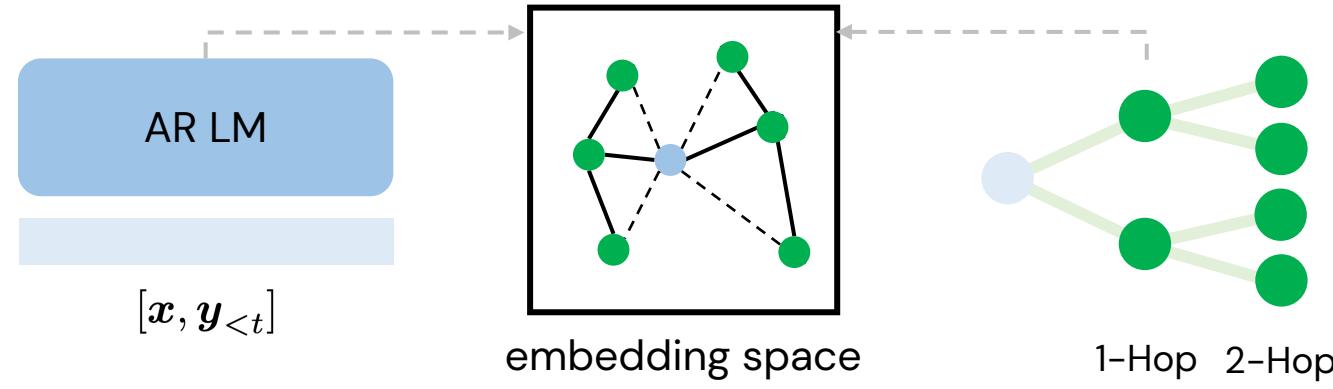


$$p_{\mathcal{B}}(y_t | \mathbf{y}_{<t}, \mathbf{x}) \propto \sum_{(\mathbf{c}^i, w^i)} \mathbb{1}[y_t = w^i] \exp \left( \text{sim}(\mathbf{c}^i, [\mathbf{x}, \mathbf{y}_{<t}]) \right)$$

- ◆ Soft matching by context similarity (legacy of text representation learning)
- ◆ The complexity of database grows linearly with the size of training data!

# Look-Up Model

- Semi-parametric model with graph-based  $\mathcal{B}$  [Ji et al., 2020] (EMNLP' 20 Oral):
  - ◆ Trie from knowledge graph  $\mathcal{G} = (\mathcal{E}, \mathcal{R})$ :  $\mathcal{B} = \{\tau^i = (\dots, e_j^i, r_{j,j+1}^i, e_{j+1}^i, \dots) | e_j^i, e_{j+1}^i \in \mathcal{E}, r_{j,j+1}^i \in \mathcal{R}\}$



$$p_{\mathcal{B}}(y_t | \mathbf{y}_{<t}, \mathbf{x}) \propto \exp \left( \sum_{\tau^i} \sum_{j=1}^H \mathbb{1}[y_t = \tau_j^i] \text{sim}(\tau_{<j}^i, [\mathbf{x}, \mathbf{y}_{<t}]) \right)$$

- ◆ Gain of structure:
  - Accumulate and reuse evidence along the branch of the tree
  - The complexity of tree grows linearly with the context length ( $\ll \# \text{docs}$ )
- ◆ Build graph from documents to increase connectivity (followed by future works)

# Look-Up Model

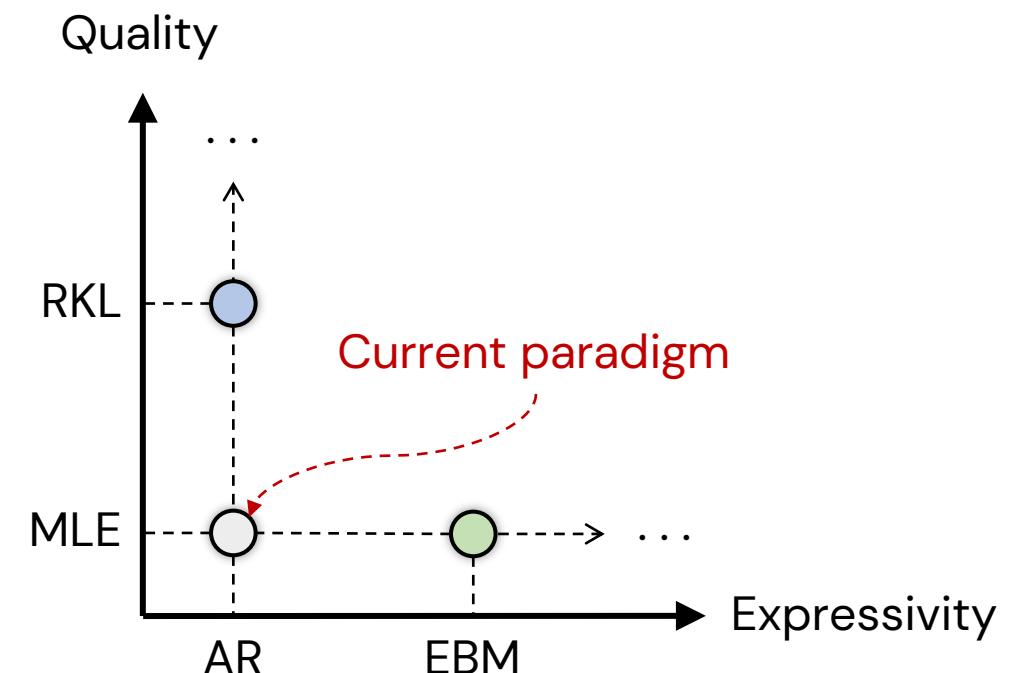


- ◎ **Takeaway & Future :**
- ◎ Look-up at decoding phase:
  - ◆ Semi-parametric model: Merging look-up probability with LM probability
  - ◆ Induce noise, need dynamic balancing the intensity
- ◎ Look-up at encoding phase:
  - ◆ Retrieve-Augmented Generation (RAG): LM performing implicit look-up
  - ◆ High fluency with hallucination

# Conclusion & Future



- Push the boundary of language modeling in a **principled** and **scalable** way:
- **#1** Learn from Data in high quality
  - ◆ Fine-grained annotations:  
**Generative** → **Preferential** → **Process** → ?
  - ◆ **Solution:** Quality-aware objective
    - **Key:** quality evaluation
- **#2** Increase model expressivity
  - ◆ Data growing slows down
    - Need to increase data utilization
  - ◆ **Solution:** Expressive model families
    - **Key:** Scaling up upon AR model



# Thanks for Attention!



## Q & A

Homepage: <https://haozheji.github.io>

Email: [jihaozhe@gmail.com](mailto:jihaozhe@gmail.com)