MONOSTABLE RELAY FIRMWARE **UNIV 3.2.1.0**

1. Features

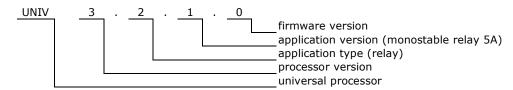
- Firmware for 6 monostable relay module
- 3 control instructions (on, off, toggle)
- 3 blocking instructions
- 6 timers (1 for each relay) for instruction execution delay 1s-24h
- Allows defining up to 128 CAN messages which can indirectly control the module
- Settable relay power up state
- Uptime counter
- Health check monitor
- Transmit (42 messages) and receive (42 messages) FIFO buffers



2. Compatibility

- Firmware for **UNIV 3.2.1.x** module
- Firmware can be uploaded into processor with bootloader version 3.1 or compatible.

3. Firmware version



4. Communication Frames (messages)

4.1. Relay message

The module sends message to the bus, when the status of relays changes.

Table 1. RELAY frame (0x302)

| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 D4 | | D5 | D6 | D7 |
|------------|---------|---------|----------|------|------|---------|--------|------|--------|--------|-------|
| 0x302 | 3 2 1 0 | Node Nr | Group Nr | 0xFF | 0xFF | CHANNEL | STATUS | 0xFF | INSTR1 | INSTR2 | TIMER |

Ox302 - universal module frame, relay

3 - not used flag, read as "0"
- response flag, flag is equal "1" if node was requested. If flag is equal "0" it means that status of output has just changed.

Node Nr - message sender node number
Group Nr - message sender group number

CHANNEL - output channel

STATUS - actual status of outputs 0x00 - relay off, 0xFF - relay on

INSTR1 - instruction that is waiting for execution, or 0xFF if none instruction

INSTR2 - second byte of instruction that is waiting for execution, or 0xFF

TIMER - delay value of waiting instruction, or 0x00 if none waiting



4.2. Status request

Status of module can be checked by sending from computer STATUS REQUEST frame (0x109) (Table 2).

Table 2. STATUS REQUEST frame (0x109).

| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
|------------|-------|----------|----------|------|------|---------|----------|------|------|------|------|
| 0x109 | 0x0 | COMP ID1 | COMP ID2 | 0xXX | 0xXX | Node Nr | Group Nr | 0xXX | 0xXX | 0xXX | 0xXX |

0x1090 - STATUS REQUEST frame

> - computer identifier (must be unique on the network)
>
> COMP ID2 - computer identifier (must be unique on the network) COMP ID1

Node Nr - node number of requested module

Group Nr - group number of requested module

0xXX - inessential data

As response the module will send RELAY frames. The meaning of bytes is the same as in Table 1.

Table 3, Response to STATUS REQUEST

| Table 5. Ke | sponse | to STATE | S KLQULS | · I | | | | | | | |
|-------------|--------|----------|----------|------|------|------|--------|------|--------|--------|--------|
| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| 0x302 | 0x1 | Node Nr | Group Nr | 0xFF | 0xFF | 0x01 | STATUS | 0xFF | INSTR1 | INSTR2 | TIMER1 |
| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| 0x302 | 0x1 | Node Nr | Group Nr | 0xFF | 0xFF | 0x02 | STATUS | 0xFF | INSTR1 | INSTR2 | TIMER2 |
| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| 0x302 | 0x1 | Node Nr | Group Nr | 0xFF | 0xFF | 0x03 | STATUS | 0xFF | INSTR1 | INSTR2 | TIMER3 |
| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| 0x302 | 0x1 | Node Nr | Group Nr | 0xFF | 0xFF | 0x04 | STATUS | 0xFF | INSTR1 | INSTR2 | TIMER4 |
| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| 0x302 | 0x1 | Node Nr | Group Nr | 0xFF | 0xFF | 0x05 | STATUS | 0xFF | INSTR1 | INSTR2 | TIMER5 |
| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| 0x302 | 0x1 | Node Nr | Group Nr | 0xFF | 0xFF | 0x06 | STATUS | 0xFF | INSTR1 | INSTR2 | TIMER6 |

4.3. Uptime request

Table 4. UPTIME REQUEST (0x113)

| Table II e | ,, , <u>,, ,, , , , , , , , , , , , , , ,</u> | LQULU. | (OKIIO). | | | | | | | | |
|------------|---|----------|----------|------|------|---------|----------|------|------|------|------|
| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| 0x113 | 0x0 | COMP ID1 | COMP ID2 | 0xXX | 0xXX | Node Nr | Group Nr | 0xXX | 0xXX | 0xXX | 0xXX |

0x1130 - UPTIME REQUEST frame

> - computer identifier (must be unique on the network)
>
> COMP ID2 - computer identifier (must be unique on the network) COMP ID1

Node Nr - node number of requested module Group Nr - group number of requested module

0xXX - inessential data

Table 5. Response to UPTIME REQUEST (0x113).

| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
|------------|-------|---------|----------|------|------|------|------|---------|---------|---------|---------|
| 0x113 | 0x1 | Node Nr | Group Nr | 0xFF | 0xFF | 0xFF | 0xFF | UPTIME3 | UPTIME2 | UPTIME1 | UPTIME0 |

0x1131 - Response to UPTIME REQUEST frame

> - node number on the network
> | Group Nr | - group number of the node on the network Node Nr

> > UPTIME - (UPTIME3*256³+UPTIME2*256²+UPTIME1*256¹+UPTIME3*256¹) in seconds



4.4. Health check request

Table 6. HEALTH CHECK - STATUS REQUEST (0x115).

| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
|------------|-------|----------|----------|------|------|---------|----------|------|------|------|------|
| 0x115 | 0x0 | COMP ID1 | COMP ID2 | 0x01 | 0xXX | Node Nr | Group Nr | 0xXX | 0xXX | 0xXX | 0xXX |

0x1150

- HEALTH CHECK REQUEST frame

- computer identifier (must be unique on the network)

COMP ID2 - computer identifier (must be unique on the network)

0x01 - status request

Node Nr - node number of requested module

Group Nr - group number of requested module

- inessential data

As response the module will send two frames (Table 7).

Table 7 Response to HEALTH CHECK - STATUS REQUEST (0x115)

| _ | | (CC) | | | 0 17 11 0 0 | Q | · (0/1220) | • | | | | |
|---|------------|-------|---------|----------|-------------|--------------|------------|---------|---------|-----------|----------|----------|
| Г | Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| Г | 0x115 | 0x1 | Node Nr | Group Nr | 0x01 | RXCNT | TXCNT | RXCNTMX | TXCNTMX | CANINTCNT | RXERRCNT | TXERRCNT |

0x1151

- Response to HEALTH CHECK REQUEST frame

Node Nr - node number on the network
Group Nr - group number of the node on the network

0x01 - frame 1 (current values)

RXCNT - current level of receive FIFO buffer

TXCNT - current level of transmit FIFO buffer

RXCNTMX - maximum level of receive FIFO buffer since power up

TXCNTMX - maximum level of transmit FIFO buffer since power up

CANINTCNT - number of CAN interface restarts since power up

RXERRCNT - current receive errors register

TXERRCNT - current transmit errors register

| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
|------------|-------|---------|----------|------|------|------|----------|----------|------------|-----------|-----------|
| 0x115 | 0x1 | Node Nr | Group Nr | 0x02 | 0xFF | 0xFF | RXCNTMXE | TXCNTMXE | CANINTCNTE | RXERRCNTE | TXERRCNTE |

0x1151

- Response to HEALTH CHECK REQUEST frame

Node Nr - node number on the network
Group Nr - group number of the node on the network

0x02 - frame 2 (maximum values saved in eeprom memory)

RXCNTMXE - maximum ever level of receive FIFO buffer

TXCNTMXE - maximum ever level of transmit FIFO buffer

CANINTCNTE - maximum ever number of CAN interface restarts

RXERRCNTE - maximum ever receive errors

TXERRCNTE - maximum ever transmit errors

To clear maximum values saved in eeprom memory the frame shown in Table 8 must be sent. There is no response to this message.

Table 8. HEALTH CHECK - CLEAR REQUEST (0x115)

| Tubic 0. I | | CITECI | CLL/ III IIL | 20131 (0 | , X I I J J . | | | | | | |
|------------|-------|----------|--------------|---------------------|---------------|---------|----------|------|------|------|------|
| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
| 0x115 | 0x0 | COMP ID1 | COMP ID2 | 0x02 | 0xXX | Node Nr | Group Nr | 0xXX | 0xXX | 0xXX | 0xXX |

0x1150

- HEALTH CHECK REQUEST frame

COMP ID1

- computer identifier (must be unique on the network)

COMP ID2 - computer identifier (must be unique on the network)

0x02 - clear request

Node Nr - node number of requested module

Group Nr - group number of requested module

0xXX - inessential data



5. Module control

The module can be controlled directly from PC, or indirectly by other modules. In both situation all instructions in the table below can be used. Blocking instructions can't be used in direct control.

5.1. Control instruction

The Table 9 shows instructions, which can be executed by the module.

Table 9. Module control instructions

| Tubic 3. Hoddic control | | | | | | | | | • | | |
|-------------------------|--------|---------|--------|------------|-----------|--------|--------|--------|---|----|----------|
| | | | | Instructio | n Codding | | | | | Со | ntrol |
| Instruction | INSTR1 | INSTR2 | INSTR3 | INSTR4 | INSTR5 | INSTR6 | INSTR7 | INSTR8 | Note 3 | | Indirect |
| TURN OFF RELAY | 0x00 | CHANNEL | TIMER | 0xXX | 0xXX | 0xXX | 0xXX | 0xXX | It will turn off chosen relays, and the rest will stay unchanged. | | |
| TURN ON RELAY | 0x01 | CHANNEL | TIMER | 0xXX | 0xXX | 0xXX | 0xXX | 0xXX | It will turn on chosen relays, and the rest will stay unchanged. | √ | √ |
| TOGGLE RELAY | 0x02 | CHANNEL | TIMER | 0xXX | 0xXX | 0xXX | 0xXX | 0xXX | It will toggle chosen relays, and the rest will stay unchanged. | | |

0xXX - inessential data

| CHANNEL | Note |
|---------|---|
| 0x01 | - <0000001> - only relay K1 |
| 0x02 | - <0000010> - only relay K2 |
| 0x03 | - <0000011> - relay K1 & K2 |
| 0x04 | - <00000100> - only relay K3 |
| | |
| 0x3F | - <00111111> - relays K1,K2,K3,K4,K5,K6 |

bit <0> - relay K1, bit <1> - relay K2, bit <2> - relay K3 bit <3> - relay K4, bit <4> - relay K5, bit <5> - relay K6

| TIMER | Note |
|-------|---|
| 0x00 | - instruction will be executed immediately |
| 0x01 | - instruction will be executed with 1s delay |
| | |
| 0xFF | - instruction will be executed with 24h delay |

| ENABLE BOX | 0xDD | BoxX | BoxY | Y 0xXX 0xXX 0xXX 0xXX 0xXX It enables chosen boxes – these boxes will be comwith next received message from the bus. | | It enables chosen boxes – these boxes will be compared with next received message from the bus. | | ν | | | |
|-------------|------|------|------|--|------|---|------|------|---|--|---|
| DISABLE BOX | 0xDE | BoxX | BoxY | 0xXX | 0xXX | 0xXX | 0xXX | 0xXX | It disables chosen boxes – these boxes will be passed when next message arrives from the bus. | | ν |
| TOGGLE BOX | 0xDF | BoxX | BoxY | 0xXX | 0xXX | 0xXX | 0xXX | 0xXX | It toggles boxes – enables when they are disabled and vice versa | | ν |

0xXX – inessential data

| BoxX | Note |
|------|----------------|
| 0x00 | - from Box 1 |
| 0x01 | - from Box 2 |
| | |
| 0x7F | - from Box 128 |

| BoxY | Note |
|------|----------------------------|
| 0x00 | + 0 -(and not anyone else) |
| 0x01 | + 1 -(and 1 following) |
| | |
| 0x7F | +127 -(and 127 following) |

5.2. Timer

Each relay has its own timer which can delay execution of the instruction. Delay can be chosen between 1s-24h set in TIMER register. Drawing below shows delay dependence of TIMER register.

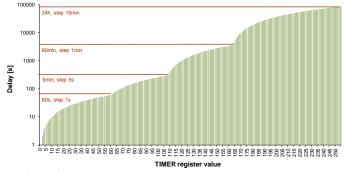


Figure 1. Delay/timer register relationship



5.3. Direct control

It is possible to control module by sending DIRECT CONTROL message. The message contains instruction, which will be executed by the module. The module can be also controlled from HAPCAN Programmer.

Table 10. DIRECT CONTROL frame (0x10A).

| Frame type | Flags | Module | Group | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
|------------|-------|----------|----------|--------|--------|---------|----------|--------|--------|--------|--------|
| 0x10A | 0x0 | COMP ID1 | COMP ID2 | INSTR1 | INSTR2 | Node Nr | Group Nr | INSTR3 | INSTR4 | INSTR5 | INSTR6 |

0x10A - DIRECT CONTROL frame

COMP ID1 - computer identifier (must be unique on the network)

COMP ID2 - computer identifier (must be unique on the network)

Node Nr - node number of requested module

Group Nr - group number of requested module

INSTR1-6 - instruction to be executed (byte1)

5.4. Indirect control

Indirect control means that module will react to messages sent by other modules on the network. It depends on configuration programmed into the module boxes (memory cells).

This firmware has feature to set simple conditions of executing instruction. To do so, you can use blocking instruction (0xDD - 0xDF) shown in Table 9.

6. Configuration

Parameters that can be configured with this firmware:

- Module identifier (module number and group number);
- Module description (16 chars);
- Relay names;
- Power up values;
- Text notes;
- Linking device with other modules (indirect control of module).

Configuration process can be done using HAPCAN Programmer.

6.1. Module identifier

Every module on the network must have unique identifier. The identifier is made of two bytes, module number (1 byte) and group number (1 byte). Identifier of the Ethernet Interface can be changed in HAPCAN Programmer in software settings.

6.2. Module description

Every module can have 16 char description, which makes easier for user (programmer) to distinguish nodes.

6.3. Relay Names

Each relay can be named with 32 chars.

6.4. Power up values

It is possible to configure relay states at startup after power loss. At startup relays can be set to ON, OFF or to the last set value. The last set value must be unchanged for at least 6s before power failure.

6.5. Text notes.

Up to 1024 characters can be written into processor's memory.

6.6. Linking devices

The module has 128 memory cells (boxes). Each box can contain information about message sent by other node, and instruction which will be executed when that message is received.

7. License



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8. Document version

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