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The whole problem is to choose the correct specifications for the filter. 3 , since the purpose of this filter is to stop the frequency artifacts generated by the upsampling operation. The passband has to be decided on the basis of the bandwirdth of the signal we want to pass and the desired complexity of the filter.

Chapter 6: Problem Solutions - Naval Postgraduate School
Week7 Lab. Signal Processing First. Lab 07: Sampling, Convolution, and FIR Filtering. 1.4 Sampling and Aliasing Demo. In this demo, you can change the frequency of an input signal that is a sinusoid, and you can change the sampling frequency.

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Solution to Exercise 5.10.3. These numbers are powers-of-two, and the FFT algorithm can be exploited with these lengths. To compute a longer transform than the input signal's duration, we simply zero-pad the signal. Solution to Exercise 5.11.1. In discrete-time signal processing, an amplifier amounts to a multiplication, a very easy operation ...

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EL 713: Digital Signal Processing Extra Problem Solutions Prof. Ivan Selesnick, Polytechnic University. 4.5 For the transfer function $H(z) = z-1 +z-6$ of an FIR linear-phase filter, (a) sketch the impulse response (b) what is the type of the filter (I, II, III, or IV)?

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Hence, $\lambda = 4,-1$ and $yh(n) = c1(n)4n +c2(-1)n$. Since 4 is a characteristic root and the excitation is $x(n) = 4nu(n)$, we assume a particular solution of the form $yp(n) = kn4nu(n)$. Then $kn4nu(n)-3k(n-1)4n-1u(n-1)-4k(n-2)4n-2u(n-2) = 4nu(n)+2(4)n-1u(n-1)$. For n = 2, $k(32-12) = 42 +8 = 24 \rightarrow k = 6 5$.

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1.2.7 The impulse response of a discrete-time LTI system is h(n)=2(n)+3(n1)+(n2). Find and sketch the output of this system when the input is the signal

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