

Jikai Wang

<https://happywj.github.io/> (607) 319-2699 · jw2777@cornell.edu

EDUCATION

Cornell University

M.Eng in Electrical and Computer engineering

Relevant Coursework: Computer Architecture; Design with Embedded Operating Systems

Ithaca, US

Expected Dec 2025

The University of Manchester

BSc (Hons) in Physics GPA 3.91/4.0

Relevant Coursework: Quantum Computing; Condensed Matter Physics; Semiconductor Quantum Structures; Electrodynamics(M)

Manchester, UK

Sept 2020 - June 2023

PROJECT EXPERIENCE

Accelerator Design and Exploration using Allo and Xilinx Vivado/Vitis

Sept 2024 - Now

- Explored the design of FPGA accelerators using Allo, a Python-based domain-specific language, for high-performance workloads such as machine learning, genomics, and robotics.
- Developed simple polybench algorithm (floyd_warshall, jacobi) and mapped them to an Alveo U250 FPGA card using Xilinx Vivado/Vitis for comparison with host Intel Xeon CPU performance.
- Target the Allo-to-ASIC flow using Mentor CatapultC, gaining insights into FPGA-to-ASIC migration.
- Prepared for an individual design project focusing on a complex accelerator in the areas of machine learning or genomics.

Pipelined Processor Design and Evaluation using Verilog and PyMTL3

Sept 2024 - Now

- Designed and implemented a five-stage pipelined processor supporting the TinyRV2 instruction set architecture (ISA) using Verilog and PyMTL3.
- Developed both stalling and fully bypassed processor microarchitectures that can correctly handle different hazard.
- Implemented a comprehensive testing strategy, including unit testing for individual instructions and parameterized integration tests for instruction sets. Leveraged pytest for automated test generation and validation.
- Performed detailed performance evaluations using simulation-based tools, analyzing cycles-per-instruction (CPI), instruction throughput, and memory latency under different benchmark scenarios.

Robot Platform and GPIO Control with Raspberry Pi

Sept 2024

- Developed an autonomous robot platform using Raspberry Pi and integrated piTFT screen, focusing on GPIO output for motor control and feedback display.
- Designed and implemented a Python-based control system for DC motors using Pulse Width Modulation (PWM) with the RPi.GPIO library.
- Built and programmed a robot capable of untethered movement with full speed control and automatic startup via a shell script in crontab.

Raspberry Pi 4 Motion Detection and Surveillance System

June 2024

- Implemented a motion detection system using a PIR sensor and indicator light on a Raspberry Pi 4.
- Developed a photo capture and upload feature using a V2 Pi Camera, with automatic email notifications containing photo timestamp and location.
- Designed a user-friendly webpage to view new photos, latest capture details, and to configure photo/video settings, including manual and scheduled captures.

RESEARCH EXPERIENCE

Investigation of the Electrical Properties of Graphene

Research Mentor: Prof. Alexander Grigorenko

Feb 2023 - May 2023

- Prepared a CVD graphene sample and employed the van der Pauw method to measure its sheet resistance and hall resistance.
- Determined the density of charge carriers inside the graphene sample at different gate voltages by using the modified Hall coefficient equations and making reasonable assumptions.
- Investigated the electric properties of the graphene sample under various conditions, including undoped, doped with water vapor, and doped with ammonia.
- Discovered a zero hall resistance and a very low charge carrier concentration of graphene sample at the Dirac point, which is attributed to its distinctive electron band structure.

SKILL

Programming: C, python, Verilog, PyMTL3, High Level Synthesis.

Tool: Xilinx Vivado, STM32CubeIDE, VSCode, Github.

OS: Ubuntu linux.

