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Personal

Date of Birth: 18/07/1994

Research Interests: Humanoid, Biomimetics, Machine Learning

Education

Ph.D. Candidate in Dept. of Mechano-Informatics, The University of University, Japan, with Prof. Masayuki Inaba (JSK Robotics Laboratory), 2019-current

M.S. in Dept. of Mechano-Informatics, Graduate School of Information Science and Technology, The University of Tokyo, Japan, 2017-2019

B.S. in Dept. of Mechano-Informatics, Faculty of Engineering, The University of Tokyo, Japan, 2013-2017

Experience

Internship at Preferred Networks, Robotics Engineer, Japan, 2018-current

Internship at Works Applications Co. Ltd., Software Engineer, Japan, 2016

Internship at Future Standard, Software Engineer, Japan, 2016

Internship at HIOKI, E.E. CORPORATION, Software Engineer, Japan, 2015

Skills

Software Skills

Basic: Java, JavaScript, Android, Haskell

Intermediate: Ruby, Lisp, Statistics

Advanced: C, C++, Python, Machine Learning, Algorithms

Hardware Skills

Basic: Electorinics, Machining

Intermediate: 3D CAD, 3D Printer

Publications

Journal Articles (Peer Reviewed)

1. **K. Kawaharazuka**, K. Tsuzuki, Y. Koga, Y. Omura, T. Makabe, K. Shinjo, M. Onitsuka, Y. Nagamatsu, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Toward Autonomous Driving by Musculoskeletal Humanoids (in press)", *IEEE Robotics and Automation Magazine (RAM)*, 2020
2. **K. Kawaharazuka**, K. Tsuzuki, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Musculoskeletal AutoEncoder: A Unified Online Acquisition Method of Intersensory Networks for State Estimation Control and Simulation of Musculoskeletal Humanoids", *IEEE Robotics and Automation Letters (RAL)*, vol. 5, no. 2, pp. 2411-2418, 2020, **(presented at ICRA2020)**
3. **K. Kawaharazuka**, S. Makino, M. Kawamura, S. Nakashima, Y. Asano, K. Okada, M. Inaba: "Human Mimetic Forearm and Hand Design with a Radioulnar Joint and Flexible Machined Spring Finger for Human Skillful Motions", *Journal of Robotics and Mechatronics (JRM)*, vol. 32, no. 2, pp. 445-458, 2020, **(The first two authors contributed equally to this work)**
4. **K. Kawaharazuka**, K. Tsuzuki, S. Makino, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Long-time Self-body Image Acquisition and its Application to the Control of Musculoskeletal Structures", *IEEE Robotics and Automation Letters (RAL)*, vol. 4, no. 3, pp. 2965-2972, 2019, **(presented at IROS2019)**
5. **K. Kawaharazuka**, S. Makino, M. Kawamura, Y. Asano, K. Okada, M. Inaba: "Online Learning of Joint-Muscle Mapping using Vision in Tendon-driven Musculoskeletal Humanoids", *IEEE Robotics and Automation Letters (RAL)*, vol. 3, no. 2, pp. 772-779, 2018, **(presented at ICRA2018)**
6. **K. Kawaharazuka**, M. Kawamura, S. Makino, Y. Asano, K. Okada, M. Inaba: "Antagonist Inhibition Control in Redundant Tendon-driven Structures Based on Human Reciprocal Innervation for Wide Range Limb Motion of Musculoskeletal Humanoids", *IEEE Robotics and Automation Letters (RAL)*, vol. 2, no. 4, pp. 2119-2126, 2017, **(presented at IROS2017)**

International Conference Proceedings (Peer Reviewed)

1. **K. Kawaharazuka**, K. Tsuzuki, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Stable Tool-Use with Flexible Musculoskeletal Hands by Learning the Predictive Model of Sensor State Transition (in press)", *Proceedings of the 2020 IEEE International Conference on Robotics and Automation (ICRA2020)*, 2020
2. **K. Kawaharazuka**, S. Makino, K. Tsuzuki, M. Onitsuka, Y. Nagamatsu, K. Shinjo, T. Makabe, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Component Modularized Design of Musculoskeletal Humanoid Platform Musashi to Investigate Learning Control Systems", *Proceedings of the 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2019)*, pp. 7294-7301, 2019
3. **K. Kawaharazuka**, K. Tsuzuki, S. Makino, M. Onitsuka, K. Shinjo, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Task-specific Self-body Controller Acquisition by Musculoskeletal Humanoids: Application to Pedal Control in Autonomous Driving", *Proceedings of the 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2019)*, pp. 813-818, 2019
4. **K. Kawaharazuka**, T. Ogawa, C. Nabeshima: "Dynamic Task Control Method of a Flexible Manipulator Using a Deep Recurrent Neural Network", *Proceedings of the 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2019)*, pp. 7689-7695, 2019

5. K. Shinjo, **K. Kawaharazuka**, Y. Asano, S. Nakashima, S. Makino, M. Onitsuka, K. Tsuzuki, K. Okada, K. Kawasaki, M. Inaba: "Foot with a Core-shell Structural Six-axis Force Sensor for Pedal Depressing and Recovering from Foot Slipping during Pedal Pushing Toward Autonomous Driving by Humanoids", *Proceedings of the 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2019)*, pp. 3049-3054, 2019
6. S. Nakashima, T. Shirai, **K. Kawaharazuka**, Y. Asano Y. Kakiuchi, K. Okada, M. Inaba: "An Approach of Facilitated Investigation of Active Self-healing Tension Transmission System Oriented for Legged Robots", *Proceedings of the 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2019)*, pp. 2567-2572, 2019, **SICE International Young Authors Award (2019)**
7. T. Makabe, T. Shirai, Y. Nagamatsu, **K. Kawaharazuka**, S. Fumihito, K. Okada, M. Inaba: "Development of Joint Module with Two-Speed Gear Transmission and Joint Lock Mechanism during Driving for Task Adaptable Robot", *Proceedings of the 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2019)*, pp. 5123-5130, 2019
8. **K. Kawaharazuka**, K. Tsuzuki, M. Onitsuka, Y. Koga, Y. Omura, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Reflex-based Motion Strategy of Musculoskeletal Humanoids under Environmental Contact Using Muscle Relaxation Control", *Proceedings of the 2019 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2019)*, pp. 114-119, 2019
9. Y. Koga, **K. Kawaharazuka**, M. Onitsuka, T. Makabe, K. Tsuzuki, Y. Omura, Y. Asano, K. Okada, M. Inaba: "Modification of Muscle Antagonistic Relations and Hand Trajectory on the Dynamic Motion of Musculoskeletal Humanoid", *Proceedings of the 2019 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2019)*, pp. 632-637, 2019
10. Y. Asano, S. Nakashima, I. Yanokura, M. Onitsuka, **K. Kawaharazuka**, K. Tsuzuki, Y. Koga, Y. Omura, K. Okada, M. Inaba: "Ankle-Hip-Stepping Stabilizer on Tendon-Driven Humanoid Kengoro by Integration of Muscle-Joint-Work Space Controllers for Knee-Stretched Humanoid Balance", *Proceedings of the 2019 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2019)*, pp. 397-402, 2019
11. **K. Kawaharazuka**, K. Tsuzuki, S. Makino, Y. Asano, K. Okada, M. Inaba: "Modeling and On-line Learning of Musculoskeletal Intersensory Networks for Static Controls of Tendon-driven Humanoids", *Proceedings of 9th International Symposium on Adaptive Motion of Animals and Machines (AMAM2019)*, 2019, **Company of Biologists Early Career Researcher Grant (500 GBP)**
12. **K. Kawaharazuka**, T. Ogawa, J. Tamura, C. Nabeshima: "Dynamic Manipulation of Flexible Objects with Torque Sequence Using a Deep Neural Network", *Proceedings of the 2019 IEEE International Conference on Robotics and Automation (ICRA2019)*, pp. 2139-2145, 2019
13. **K. Kawaharazuka**, T. Makabe, S. Makino, K. Tsuzuki, Y. Nagamatsu, Y. Asano, T. Shirai, F. Sugai, K. Okada, K. Kawasaki, M. Inaba: "TWIMP: Two-Wheel Inverted Musculoskeletal Pendulum as a Learning Control Platform in the Real World with Environmental Physical Contact", *Proceedings of the 2018 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2018)*, pp. 784-790, 2018, **(The first two authors contributed equally to this work)**
14. **K. Kawaharazuka**, S. Makino, M. Kawamura, Y. Asano, K. Okada, M. Inaba: "A Method of Joint Angle Estimation Using Only Relative Changes in Muscle Lengths for Tendon-driven Humanoids with Complex Musculoskeletal Structures", *Proceedings of the 2018 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2018)*, pp. 1128-1135, 2018
15. T. Makabe, **K. Kawaharazuka**, K. Tsuzuki, K. Wada, S. Makino, M. Kawamura, A. Fujii, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Development of Movable Binocular High-Resolution

- Eye-Camera Unit for Humanoid and the Evaluation of Looking Around Fixation Control and Object Recognition”, *Proceedings of the 2018 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2018)*, pp. 840-845, 2018
16. **K. Kawaharazuka**, S. Makino, M. Kawamura, A. Fujii, Y. Asano, K. Okada, M. Inaba: “Online Self-body Image Acquisition Considering Changes in Muscle Routes Caused by Softness of Body Tissue for Tendon-driven Musculoskeletal Humanoids”, *Proceedings of the 2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2018)*, pp. 1711-1717, 2018
 17. S. Makino, **K. Kawaharazuka**, M. Kawamura, A. Fujii, T. Makabe, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Five-Fingered Hand with Wide Range of Thumb Using Combination of Machined Springs and Variable Stiffness Joints”, *Proceedings of the 2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2018)*, pp. 4562-4567, 2018, **IEEE RAS Japan Joint Chapter Young Award (2018), IROS ICROS Best Application Paper Award 2018 Finalists**
 18. A. Fujii, S. Nakashima, M. Kawamura, **K. Kawaharazuka**, S. Makino, Y. Asano, K. Okada, M. Inaba: “Development and Functional Evaluation of a Deformable Membrane Capsule for an Open Ball Glenohumeral Joint”, *Proceedings of The 2018 IEEE RAS/EMBS International Conference on Biomedical Robotics and Biomechanics (BIOROB2018)*, pp. 853-858, 2018
 19. **K. Kawaharazuka**, S. Makino, M. Kawamura, Y. Asano, Y. Kakiuchi, K. Okada, M. Inaba: “Human Mimetic Forearm Design with Radioulnar Joint using Miniature Bone-muscle Modules and its Applications”, *Proceedings of the 2017 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2017)*, pp. 4956-4962, 2017, **IEEE RAS Japan Joint Chapter Young Award (2017)**
 20. S. Makino, **K. Kawaharazuka**, M. Kawamura, Y. Asano, K. Okada, M. Inaba: “High-power flexible robust hand: Development of musculoskeletal hand using machined springs and realization of self-weight supporting motion with humanoid”, *Proceedings of the 2017 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2017)*, pp. 1187-1192, 2017
 21. Y. Asano, T. Kozuki, S. Ookubo, M. Kawamura, S. Nakashima, T. Katayama, Y. Iori, H. Toshinori, **K. Kawaharazuka**, S. Makino, Y. Kakiuchi, K. Okada, M. Inaba: “Human Mimetic Musculoskeletal Humanoid Kengoro toward Real World Physically Interactive Actions”, *Proceedings of the 2016 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2016)*, pp. 876-883, 2016, **Best Interactive Paper Award Finalist**

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