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Personal

Research Interests: Humanoid, Biomimetics, Machine Learning

Education

Project Assistant Professor in Dept. of Mechano-Informatics, The University of University, Japan, JSK Robotics Laboratory, 2022-

Ph.D. in Dept. of Mechano-Informatics, The University of University, Japan, with Prof. Masayuki Inaba (JSK Robotics Laboratory), 2019-2022

M.S. in Dept. of Mechano-Informatics, Graduate School of Information Science and Technology, The University of Tokyo, Japan, 2017-2019

B.S. in Dept. of Mechano-Informatics, Faculty of Engineering, The University of Tokyo, Japan, 2013-2017

Experience

Internship at Preferred Networks, Robotics Engineer, Japan, 2018-2020

Internship at Works Applications Co. Ltd., Software Engineer, Japan, 2016

Internship at Future Standard, Software Engineer, Japan, 2016

Internship at HIOKI, E.E. CORPORATION, Software Engineer, Japan, 2015

Skills

Software Skills

Advanced: C, C++, Python, Machine Learning, Algorithms

Intermediate: Ruby, Lisp, Statistics

Basic: Java, JavaScript, Android, Haskell

Hardware Skills

Intermediate: 3D CAD, 3D Printer

Basic: Electorinics, Machining

Publications

Journal Articles (Peer Reviewed)

1. **K. Kawaharazuka**, T. Matsushima, A. Gambardella, J. Guo, C. Paxton, A. Zeng: “Real-World Robot Applications of Foundation Models: A Review”, *Advanced Robotics (AR)*, 2024, **(The first two authors contributed equally to this work)**
2. N. Kanazawa, **K. Kawaharazuka**, Y. Obinata, K. Okada, M. Inaba: “Real-world cooking robot system from recipes based on food state recognition using foundation models and PDDL”, *Advanced Robotics (AR)*, pp. 1-17, 2024
3. **K. Kawaharazuka**, Y. Obinata, N. Kanazawa, N. Tsukamoto, K. Okada, M. Inaba: “Reflex-Based Open-Vocabulary Navigation without Prior Knowledge Using Omnidirectional Camera and Multiple Vision-Language Models”, *Advanced Robotics (AR)*, pp. 1-12, 2024
4. S. Wakabayashi, **K. Kawaharazuka**, K. Okada, M. Inaba: “Behavioral Learning of Dish Rinsing and Scrubbing based on Interruptive Direct Teaching Considering Assistance Rate”, *Advanced Robotics (AR)*, pp. 1-14, 2024
5. **K. Kawaharazuka**, K. Okada, M. Inaba: “GeMuCo: Generalized Multisensory Correlational Model for Body Schema Learning”, *IEEE Robotics and Automation Magazine (RAM)*, 2024, **(presented at ICRA2025)**
6. **K. Kawaharazuka**, Y. Obinata, N. Kanazawa, K. Okada, M. Inaba: “Robotic Environmental State Recognition with Pre-Trained Vision-Language Models and Black-Box Optimization”, *Advanced Robotics (AR)*, pp. 1-10, 2024
7. **K. Kawaharazuka**, N. Kanazawa, Y. Obinata, K. Okada, M. Inaba: “Continuous Object State Recognition for Cooking Robots Using Pre-Trained Vision-Language Models and Black-box Optimization”, *IEEE Robotics and Automation Letters (RAL)*, vol. 9, no. 5, pp. 4059-4066, 2024, **(presented at Humanoids2024)**
8. T. Suzuki, M. Bando, **K. Kawaharazuka**, K. Okada, M. Inaba: “SAQIEL: Ultra-Light and Safe Manipulator with Passive 3D Wire Alignment Mechanism”, *IEEE Robotics and Automation Letters (RAL)*, vol. 9, no. 4, pp. 3720-3727, 2024, **(presented at IROS2024)**
9. **K. Kawaharazuka**, S. Yoshimura, T. Suzuki, K. Okada, M. Inaba: “Design Optimization of Wire Arrangement With Variable Relay Points in Numerical Simulation for Tendon-Driven Robots”, *IEEE Robotics and Automation Letters (RAL)*, vol. 9, no. 2, pp. 1388-1395, 2024, **(presented at IROS2024)**
10. **K. Kawaharazuka**, K. Okada, M. Inaba: “Deep Predictive Model Learning with Parametric Bias: Handling Modeling Difficulties and Temporal Model Changes”, *IEEE Robotics and Automation Magazine (RAM)*, 2023, **(presented at ICRA2023)**
11. **K. Kawaharazuka**, N. Kanazawa, K. Okada, M. Inaba: “Self-Supervised Learning of Visual Servoing for Low-Rigidity Robots Considering Temporal Body Changes”, *IEEE Robotics and Automation Letters (RAL)*, vol. 7, no. 3, pp. 7881-7887, 2022, **SICE International Young Authors Award (SIYA-IROS2022)**, **(presented at IROS2022)**
12. Y. Omura, **K. Kawaharazuka**, Y. Nagamatsu, Y. Koga, M. Nishiura, Y. Toshimitsu, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Human-mimetic binaural ear design and sound source direction estimation for task realization of musculoskeletal humanoids”, *Robomech Journal*, vol. 9, no. 17, pp. 1-15, 2022

13. **K. Kawaharazuka**, A. Miki, M. Bando, K. Okada, M. Inaba: “Dynamic Cloth Manipulation Considering Variable Stiffness and Material Change Using Deep Predictive Model With Parametric Bias”, *Frontiers in Neurorobotics*, vol. 16, pp. 1-16, 2022
14. **K. Kawaharazuka**, M. Nishiura, Y. Toshimitsu, Y. Omura, Y. Koga, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Robust Continuous Motion Strategy Against Muscle Rupture using Online Learning of Redundant Intersensory Networks for Musculoskeletal Humanoids”, *Robotics and Autonomous Systems (RAS)*, vol. 152, pp. 1-14, 2022
15. **K. Kawaharazuka**, A. Miki, Y. Toshimitsu, K. Okada, M. Inaba: “Adaptive Body Schema Learning System Considering Additional Muscles for Musculoskeletal Humanoids”, *IEEE Robotics and Automation Letters (RAL)*, vol. 7, no. 2, pp. 3459-3466, 2022, **(presented at ICRA2022)**
16. **K. Kawaharazuka**, K. Okada, M. Inaba: “Adaptive Robotic Tool-Tip Control Learning Considering Online Changes in Grasping State”, *IEEE Robotics and Automation Letters (RAL)*, vol. 6, no. 3, pp. 5992-5999, 2021, **(presented at IROS2021)**
17. **K. Kawaharazuka**, Y. Kawamura, K. Okada, M. Inaba: “Imitation Learning with Additional Constraints on Motion Style using Parametric Bias”, *IEEE Robotics and Automation Letters (RAL)*, vol. 6, no. 3, pp. 5897-5904, 2021, **(presented at IROS2021)**
18. Y. Koga, **K. Kawaharazuka**, Y. Toshimitsu, M. Nishiura, Y. Omura, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Self-Body Image Acquisition and Posture Generation with Redundancy using Musculoskeletal Humanoid Shoulder Complex for Object Manipulation”, *IEEE Robotics and Automation Letters (RAL)*, vol. 6, no. 4, pp. 6686-6692, 2021, **(presented at IROS2021)**
19. **K. Kawaharazuka**, M. Nishiura, Y. Koga, Y. Omura, Y. Toshimitsu, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Automatic Grouping of Redundant Sensors and Actuators Using Functional and Spatial Connections: Application to Muscle Grouping for Musculoskeletal Humanoids”, *IEEE Robotics and Automation Letters (RAL)*, vol. 6, no. 2, pp. 1981-1988, 2021, **(presented at ICRA2021)**
20. **K. Kawaharazuka**, K. Tsuzuki, Y. Koga, Y. Omura, T. Makabe, K. Shinjo, M. Onitsuka, Y. Nagamatsu, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Toward Autonomous Driving by Musculoskeletal Humanoids: Study of Developed Hardware and Learning-Based Software”, *IEEE Robotics and Automation Magazine (RAM)*, vol. 27, no. 3, pp. 84-96, 2020, **(presented at ICRA2021)**
21. **K. Kawaharazuka**, K. Tsuzuki, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Object Recognition, Dynamic Contact Simulation, Detection, and Control of the Flexible Musculoskeletal Hand Using a Recurrent Neural Network With Parametric Bias”, *IEEE Robotics and Automation Letters (RAL)*, vol. 5, no. 3, pp. 4580-4587, 2020, **(presented at IROS2020)**
22. **K. Kawaharazuka**, N. Hiraoka, K. Tsuzuki, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Estimation and Control of Motor Core Temperature with Online Learning of Thermal Model Parameters: Application to Musculoskeletal Humanoids”, *IEEE Robotics and Automation Letters (RAL)*, vol. 5, no. 3, pp. 4273-4280, 2020, **(presented at IROS2020)**
23. **K. Kawaharazuka**, K. Tsuzuki, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Musculoskeletal AutoEncoder: A Unified Online Acquisition Method of Intersensory Networks for State Estimation, Control, and Simulation of Musculoskeletal Humanoids”, *IEEE Robotics and Automation Letters (RAL)*, vol. 5, no. 2, pp. 2411-2418, 2020, **(presented at ICRA2020)**
24. **K. Kawaharazuka**, S. Makino, M. Kawamura, S. Nakashima, Y. Asano, K. Okada, M. Inaba: “Human Mimetic Forearm and Hand Design with a Radioulnar Joint and Flexible Machined Spring Finger for Human Skillful Motions”, *Journal of Robotics and Mechatronics (JRM)*, vol. 32, no. 2, pp. 445-458, 2020, **(The first two authors contributed equally to this work)**

25. **K. Kawaharazuka**, K. Tsuzuki, S. Makino, M. Onitsuka, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: “Long-time Self-body Image Acquisition and its Application to the Control of Musculoskeletal Structures”, *IEEE Robotics and Automation Letters (RAL)*, vol. 4, no. 3, pp. 2965-2972, 2019, **(presented at IROS2019)**
26. **K. Kawaharazuka**, S. Makino, M. Kawamura, Y. Asano, K. Okada, M. Inaba: “Online Learning of Joint-Muscle Mapping using Vision in Tendon-driven Musculoskeletal Humanoids”, *IEEE Robotics and Automation Letters (RAL)*, vol. 3, no. 2, pp. 772-779, 2018, **(presented at ICRA2018)**
27. **K. Kawaharazuka**, M. Kawamura, S. Makino, Y. Asano, K. Okada, M. Inaba: “Antagonist Inhibition Control in Redundant Tendon-driven Structures Based on Human Reciprocal Innervation for Wide Range Limb Motion of Musculoskeletal Humanoids”, *IEEE Robotics and Automation Letters (RAL)*, vol. 2, no. 4, pp. 2119-2126, 2017, **(presented at IROS2017)**

International Conference Proceedings (Peer Reviewed)

1. **K. Kawaharazuka**, S. Inoue, T. Suzuki, S. Yuzai, S. Sawaguchi, K. Okada, M. Inaba: “MEVIUS: A Quadruped Robot Easily Constructed through E-Commerce with Sheet Metal Welding and Machining”, *Proceedings of the 2024 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2024)*, 2024
2. **K. Kawaharazuka**, Y. Obinata, N. Kanazawa, K. Okada, M. Inaba: “Robotic State Recognition with Image-to-Text Retrieval Task of Pre-Trained Vision-Language Model and Black-Box Optimization”, *Proceedings of the 2024 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2024)*, 2024
3. S. Inoue, **K. Kawaharazuka**, T. Suzuki, S. Yuzaki, Y. Ribayashi, Y. Sahara, K. Okada: “CubiX-Musashi: Fusion of Wire-Driven CubiX and Musculoskeletal Humanoid Musashi toward Unlimited Performance”, *Proceedings of the 2024 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2024)*, 2024
4. Y. Iwata, S. Hasegawa, **K. Kawaharazuka**, K. Okada, M. Inaba: “Integrative Wrapping System for a Dual-Arm Humanoid Robot”, *Proceedings of the 2024 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2024)*, 2024
5. Y. Obinata, H. Jia, **K. Kawaharazuka**, N. Kanazawa, K. Okada: “Remote Life Support Robot Interface System for Global Task Planning and Local Action Expansion Using Foundation Models”, *Proceedings of the 2024 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2024)*, 2024
6. S. Sawaguchi, T. Suzuki, A. Miki, **K. Kawaharazuka**, S. Yuzaki, S. Yoshimura, Y. Ribayashi, K. Okada, M. Inaba: “Vlimb: A Wire-Driven Wearable Robot for Bodily Extension, Balancing Powerfulness and Reachability”, *Proceedings of the 2024 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2024)*, 2024
7. Y. Ribayashi, Y. Sahara, S. Sawaguchi, K. Miyama, A. Miki, **K. Kawaharazuka**, K. Okada, M. Inaba: “Fundamental Three-Dimensional Configuration of Wire-Wound Muscle-Tendon Complex Drive”, *Proceedings of the 2024 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2024)*, 2024
8. **K. Kawaharazuka**, K. Okada, M. Inaba: “Robot Design Optimization with Rotational and Prismatic Joints Using Black-Box Multi-Objective Optimization”, *Proceedings of the 2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2024)*, 2024

9. S. Inoue, **K. Kawaharazuka**, T. Suzuki, S. Yuzaki, K. Okada, M. Inaba: “CubiX: Portable Wire-Driven Parallel Robot Connecting to and Utilizing the Environment”, *Proceedings of the 2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2024)*, 2024
10. S. Yoshimura, A. Miki, K. Miyama, Y. Sahara, **K. Kawaharazuka**, K. Okada, M. Inaba: “Patterned Structure Muscle : Arbitrary Shaped Wire-Driven Artificial Muscle Utilizing Anisotropic Flexible Structure for Musculoskeletal Robots”, *Proceedings of the 2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2024)*, 2024
11. Y. Sahara, A. Miki, Y. Ribayashi, S. Yoshimura, **K. Kawaharazuka**, K. Okada, M. Inaba: “Construction of Musculoskeletal Simulation for Shoulder Complex with Ligaments and Its Validation via Model Predictive Control”, *Proceedings of the 2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2024)*, 2024
12. **K. Kawaharazuka**, K. Okada, M. Inaba: “Robotic Constrained Imitation Learning for the Peg Transfer Task in Fundamentals of Laparoscopic Surgery”, *Proceedings of the 2024 IEEE International Conference on Robotics and Automation (ICRA2024)*, 2024
13. **K. Kawaharazuka**, K. Okada, M. Inaba: “Adaptive Whole-body Robotic Tool-use Learning on Low-rigidity Plastic-made Humanoids Using Vision and Tactile Sensors”, *Proceedings of the 2024 IEEE International Conference on Robotics and Automation (ICRA2024)*, 2024
14. A. Tang, T. Hiraoka, N. Hiraoka, F. Shi, **K. Kawaharazuka**, K. Kojima, K. Okada, M. Inaba: “HumanMimic: Learning Natural Locomotion and Transitions for Humanoid Robot via Wasserstein Adversarial Imitation”, *Proceedings of the 2024 IEEE International Conference on Robotics and Automation (ICRA2024)*, 2024
15. K. Shirai, C. C. Beltran-Hernandez, M. Hamaya, A. Hashimoto, S. Tanaka, **K. Kawaharazuka**, K. Tanaka, Y. Ushiku, S. Mori: “Vision-Language Interpreter for Robot Task Planning”, *Proceedings of the 2024 IEEE International Conference on Robotics and Automation (ICRA2024)*, 2024
16. Open X-Embodiment Collaboration: “Open X-Embodiment: Robotic Learning Datasets and RT-X Models”, *Proceedings of the 2024 IEEE International Conference on Robotics and Automation (ICRA2024)*, 2024, **Best Conference Paper Award, Finalists of Best Paper Award in Robot Manipulation**
17. S. Inoue, **K. Kawaharazuka**, K. Okada, M. Inaba: “Body Design and Gait Generation of Chair-Type Asymmetrical Tripedal Low-rigidity Robot”, *Proceedings of the 2024 IEEE International Conference on Soft Robotics (ROBOSOFT2024)*, 2024
18. A. Miki, Y. Sahara, K. Miyama, Y. Ribayashi, **K. Kawaharazuka**, S. Hasegawa, K. Okada, M. Inaba: “Designing Fluid-Exuding Cartilage for Biomimetic Robots Mimicking Human Joint Lubrication Function”, *Proceedings of the 2024 IEEE International Conference on Soft Robotics (ROBOSOFT2024)*, 2024
19. **K. Kawaharazuka**, Y. Obinata, N. Kanazawa, K. Okada, M. Inaba: “Robotic Applications of Pre-Trained Vision-Language Models to Various Recognition Behaviors”, *Proceedings of the 2023 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2023)*, pp. 458-465, 2023
20. **K. Kawaharazuka**, N. Kanazawa, Y. Obinata, K. Okada, M. Inaba: “Daily Assistive View Control Learning of Low-Cost Low-Rigidity Robot via Large-Scale Vision-Language Model”, *Proceedings of the 2023 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2023)*, pp. 452-457, 2023
21. S. Yoshimura, S. Yuzaki, **K. Kawaharazuka**, K. Okada, M. Inaba: “Optimization of Muscle Arrangement Extraction from Human Waist Structure for Biomimetic Humanoid Implementation”, *Proceedings of the 2023 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2023)*, pp. 583-590, 2023

22. Y. Ribayashi, K. Miyama, A. Miki, **K. Kawaharazuka**, K. Okada, M. Inaba: “Development of a Wire-Wound Muscle-Tendon Complex Drive and Its Application to a Two-Dimensional Robot Configuration”, *Proceedings of the 2023 IEEE-RAS International Conference on Humanoid Robots (HUMANOID2023)*, pp. 758-764, 2023
23. S. Yuzaki, A. Miki, M. Bando, S. Yoshimura, T. Suzuki, **K. Kawaharazuka**, K. Okada, M. Inaba: “Fusion of Body and Environment with Movable Carabiners for Wire-Driven Robots Toward Expansion of Physical Capabilities”, *Proceedings of the 2023 IEEE-RAS International Conference on Humanoid Robots (HUMANOID2023)*, pp. 679-685, 2023
24. **K. Kawaharazuka**, T. Makabe, K. Okada, M. Inaba: “Daily Assistive Modular Robot Design Based on Multi-Objective Black-Box Optimization”, *Proceedings of the 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2023)*, pp. 9970-9977, 2023
25. Y. Matsuura, **K. Kawaharazuka**, N. Hiraoka, K. Kojima, K. Okada, M. Inaba: “Development of a Whole-Body Work Imitation Learning System by a Biped and Bi-Armed Humanoid”, *Proceedings of the 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2023)*, pp. 10374-10381, 2023
26. Y. Obinata, **K. Kawaharazuka**, N. Kanazawa, N. Yamaguchi, N. Tsukamoto, I. Yanokura, S. Kitagawa, K. Shinjo, K. Okada, M. Inaba: “Semantic Scene Difference Detection in Daily Life Patrolling by Mobile Robots Using Pre-Trained Large-Scale Vision-Language Model”, *Proceedings of the 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2023)*, pp. 3228-3233, 2023, **IEEE RAS Japan Joint Chapter Young Award (2023), SICE International Young Authors Award (SIYA-IROS2023)**
27. K. Miyama, **K. Kawaharazuka**, K. Okada, M. Inaba: “Development of a Five-Fingerd Biomimetic Soft Robotic Hand by 3D Printing the Skin and Skeleton As One Unit”, *Proceedings of the 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2023)*, pp. 6624-6630, 2023, **SICE International Young Authors Award (SIYA-IROS2023)**
28. S. Yoshimura, T. Suzuki, M. Bando, S. Yuzaki, **K. Kawaharazuka**, K. Okada, M. Inaba: “Design Method of a Kangaroo Robot with High Power Legs and an Articulated Soft Tail”, *Proceedings of the 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2023)*, pp. 6631-6638, 2023
29. A. Ichikura, **K. Kawaharazuka**, Y. Obinata, K. Okada, M. Inaba: “A Method for Selecting Scenes and Emotion-Based Descriptions for a Robot’s Diary”, *Proceedings of the 32nd IEEE International Conference on Robot and Human Interactive Communication (ROMAN2023)*, pp. 1683-1688, 2023
30. A. Miki, **K. Kawaharazuka**, M. Bando, K. Okada, K. Kawasaki, M. Inaba: “System Architecture and Real-World Task Realization of Musculoskeletal Wheeled Robot Musashi-W with Various Hardware Components”, *Proceedings of the 18th International Conference on Intelligent Autonomous Systems (IAS2023)*, pp. 109-122, 2023
31. L. Wu, **K. Kawaharazuka**, S. Hasegawa, K. Okada, M. Inaba: “Workspace-Based Precision Grasp Pose Generator for Multi-Fingered Robotic Hands”, *Proceedings of the 18th International Conference on Intelligent Autonomous Systems (IAS2023)*, pp. 379-392, 2023
32. N. Kanazawa, **K. Kawaharazuka**, Y. Obinata, K. Okada, M. Inaba: “Recognition of Heat-Induced Food State Changes by Time-Series Use of Vision-Language Model for Cooking Robot”, *Proceedings of the 18th International Conference on Intelligent Autonomous Systems (IAS2023)*, pp. 547-560, 2023
33. A. Ichikura, **K. Kawaharazuka**, Y. Obinata, K. Shinjo, K. Okada, M. Inaba: “Automatic Diary Generation System Including Information on Joint Experiences between Humans and Robots”, *Proceedings of the 18th International Conference on Intelligent Autonomous Systems (IAS2023)*, pp. 399-412, 2023

34. **K. Kawaharazuka**, Y. Obinata, N. Kanazawa, K. Okada, M. Inaba: "VQA-based Robotic State Recognition Optimized with Genetic Algorithm", *Proceedings of the 2023 IEEE International Conference on Robotics and Automation (ICRA2023)*, pp. 8306-8311, 2023
35. H. Sato, **K. Kawaharazuka**, T. Makabe, K. Okada, M. Inaba: "Online Estimation of Self-Body Deflection with Various Sensor Data Based on Directional Statistics", *Proceedings of the 2023 IEEE/SICE International Symposium on System Integration (SII2023)*, pp. 1-8, 2023
36. **K. Kawaharazuka**, A. Miki, M. Bando, T. Suzuki, Y. Ribayashi, Y. Toshimitsu, Y. Nagamatsu, K. Okada, M. Inaba: "Hardware Design and Learning-Based Software Architecture of Musculoskeletal Wheeled Robot Musashi-W for Real-World Applications", *Proceedings of the 2022 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2022)*, pp. 413-419, 2022, **Best Interactive Paper Award Finalist**
37. **K. Kawaharazuka**, T. Suzuki, K. Okada, M. Inaba: "Continuous Jumping of a Parallel Wire-Driven Monopedal Robot RAMIEL Using Reinforcement Learning", *Proceedings of the 2022 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2022)*, pp. 759-764, 2022
38. **K. Kawaharazuka**, N. Kanazawa, K. Okada, M. Inaba: "Learning-Based Wiping Behavior of Low-Rigidity Robots Considering Various Surface Materials and Task Definitions", *Proceedings of the 2022 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2022)*, pp. 919-924, 2022
39. Y. Ribayashi, **K. Kawaharazuka**, Y. Toshimitsu, D. Kusuyama, A. Miki, K. Shinjo, M. Bando, T. Suzuki, Y. Kojio, K. Okada, M. Inaba: "Design of Robot Foot with Outer Edge Measurement Structure and Chair Rotation Motion by Friction Control", *Proceedings of the 2022 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2022)*, pp. 314-321, 2022, **(Top 7 Best Oral Paper Presentation)**
40. K. Miyama, S. Hasegawa, **K. Kawaharazuka**, N. Yamaguchi, K. Okada, M. Inaba: "Design of a Five-Fingered Hand with Full-Fingered Tactile Sensors Using Conductive Filaments and Its Application to Bending after Insertion Motion", *Proceedings of the 2022 IEEE-RAS International Conference on Humanoid Robots (HUMANOIDS2022)*, pp. 780-785, 2022
41. **K. Kawaharazuka**, K. Okada, M. Inaba: "Realization of Seated Walk by a Musculoskeletal Humanoid with Buttock-Contact Sensors From Human Constrained Teaching", *Proceedings of the 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2022)*, pp. 5774-5780, 2022
42. **K. Kawaharazuka**, K. Okada, M. Inaba: "Online Learning Feedback Control Considering Hysteresis for Musculoskeletal Structures", *Proceedings of the 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2022)*, pp. 5767-5773, 2022
43. **K. Kawaharazuka**, Y. Ribayashi, A. Miki, Y. Toshimitsu, T. Suzuki, K. Okada, M. Inaba: "Learning of Balance Controller Considering Changes in Body State for Musculoskeletal Humanoids", *Proceedings of the 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2022)*, pp. 5809-5816, 2022
44. Y. Toshimitsu, **K. Kawaharazuka**, A. Miki, K. Okada, M. Inaba: "DIJE: Dense Image Jacobian Estimation for Robust Robotic Self-Recognition and Visual Servoing", *Proceedings of the 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2022)*, pp. 2219-2226, 2022
45. Y. Ribayashi, **K. Kawaharazuka**, Y. Toshimitsu, D. Kusuyama, A. Miki, K. Shinjo, M. Bando, T. Suzuki, Y. Kojio, K. Okada, M. Inaba: "Imitation Behavior of the Outer Edge of the Foot by Humanoids Using a Simplified Contact State Representation", *Proceedings of the 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2022)*, pp. 4243-4249, 2022

46. T. Suzuki, Y. Toshimitsu, Y. Nagamatsu, **K. Kawaharazuka**, A. Miki, Y. Ribayashi, M. Bando, K. Kojima, Y. Kakiuchi, K. Okada, M. Inaba: "RAMIEL: A Parallel-Wire Driven Monopedal Robot for High and Continuous Jumping", *Proceedings of the 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2022)*, pp. 5017-5024, 2022, **SICE International Young Authors Award (SIYA-IROS2022)**
47. **K. Kawaharazuka**, K. Shinjo, Y. Kawamura, K. Okada, M. Inaba: "Environmentally Adaptive Control Including Variance Minimization Using Stochastic Predictive Network with Parametric Bias: Application to Mobile Robots", *Proceedings of the 2021 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2021)*, pp. 8381-8387, 2021
48. **K. Kawaharazuka**, Y. Toshimitsu, M. Nishiura, Y. Koga, Y. Omura, Y. Asano, K. Okada, K. Kawasaki, M. Inaba: "Design Optimization of Musculoskeletal Humanoids with Maximization of Redundancy to Compensate for Muscle Rupture", *Proceedings of the 2021 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2021)*, pp. 3204-3210, 2021
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