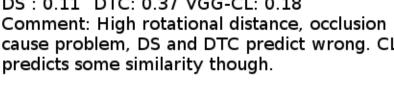
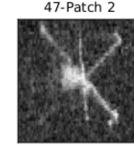
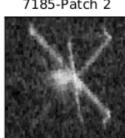
## **Matching Pair Predictions**

47-Patch 1	
1.	DS: 0.11 DTC: 0.37 VGG-CL: 0.18 Comment: High rotational distance, occlusion cause problem, DS and DTC predict wrong. CL predicts some similarity though.



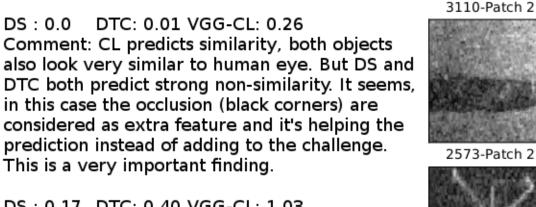


7185-Patch 2





worst cases.



DS: 0.17 DTC: 0.40 VGG-CL: 1.03 Comment: All three predict correctly, CL predicts very big distance between two images, DTC does find bit of similarity though.

Comment: All three networks very strongly

object in first image has sharp edges, which other two test objects does not. So the object-

object non-matching is easier in this case.

predict non-matching. It is observed that the

Comment: This object-object non-matching pair

is more challenging as both objects have round

Comment: All three network predict correctly.

edges. All three networks predict matching

quite strongly, which is wrong. One of the

DS: 0.0 DTC: 0.03 VGG-CL: 1.10

DS: 0.79 DTC: 0.90 VGG-CL: 0.23

DS: 0.0 DTC: 0.04 VGG-CL: 0.97

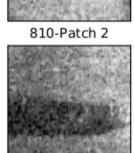
Non-matching Pair Predictions

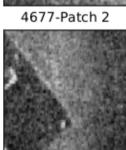


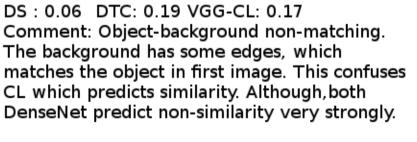


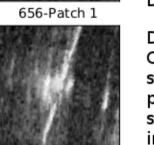












DS: 0.02 DTC: 0.34 VGG-CL: 0.12 Comment: Object-background non-matching. Cl strongly predicts the pair is matching, DTC predicts non-matching but there is some similarity. DS is very accurate. DS performance in non-matching pairs are very good. Which is benefitting the ensemble prediction too.

Comment: Object-background non-matching is

does not contain any feature. All three predicts

correctly. Though CL prediction is in the middle.

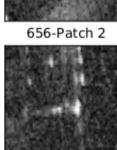
Comment: CL prediction is generally weak if

there are noisy features in the background. It

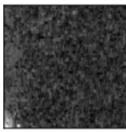
easier to predict accurately if the background

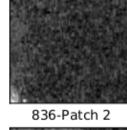
DS: 0.0 DTC: 0.02 VGG-CL: 0.51

DS: 0.24 DTC: 0.14 VGG-CL: 0.17

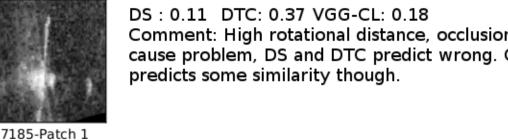


1417-Patch 2









DS: 1.0 DTC: 0.98 VGG-CL: 0.11 Comment: There is very little rotation and translation between two frames, hence all three networks predict very accurately.

Comment: Difference in contrast and lot of

noise, DS and DTC predict matching pair, very

DS: 0.99 DTC: 0.98 VGG-CL: 0.61

strongly, but CL predicts wrongly.

DS: 0.99 DTC: 0.98 VGG-CL: 0.20

DS: 0.89 DTC: 0.96 VGG-CL: 0.05

DS: 0.06 DTC: 0.47 VGG-CL: 0.37

DS: 0.58 DTC: 0.57 VGG-CL: 0.28

DS: 0.0 DTC: 0.11 VGG-CL: 1.17

contrast. One of the worst samples.

DS: 0.73 DTC: 1.0 VGG-CL: 0.04

strong similarity.

difference in contrast. Though all three

Comment: DS predicts non-matching, DTC

predicts similar pair but very high distance.

prediction shows there is some similarity and CL

Comment: Very big rotation is there along with

networks predict correctly but not very strongly.

Comment: CL predicts very big distance and

non-matching. DS and DTC also predict non-

matching strongly. All three are very wrong in

this case. The image has all kind of challenges

Comment: CL and DTC predict very strongly

that this is a matching pair. DS also predicts

though, rotation, translation, noise, poor

networks are very accurate.

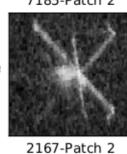
Comment: Very high rotation and some

occlusion, but prediction from all three

three are correct.

Comment: Inspite of a lot of noise and

unwanted reflections, the prediction for all





506-Patch 2

6126-Patch 2

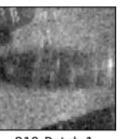
3364-Patch 2

1481-Patch 2

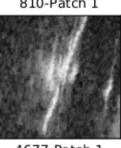
2026-Patch 2

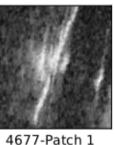
5108-Patch 2

4202-Patch 2

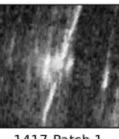


810-Patch 1





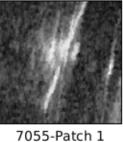




1417-Patch 1



836-Patch 1

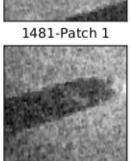






DS: 0.0 DTC: 0.01 VGG-CL: 1.53 Comment: All three predict correctly.

to-pixel comparison is not sufficient.

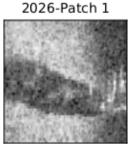


2167-Patch 1

506-Patch 1

6126-Patch 1

3364-Patch 1



5108-Patch 1



4202-Patch 1



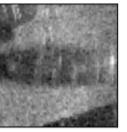
DS: 0.23 DTC: 0.84 VGG-CL: 0.27 Comment: DTC prediction is correct. DTC performance in matching pair prediction has been very good. In this case DS prediction is very false., though CL also predicts correctly.

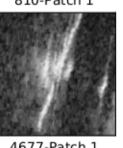


3110-Patch 1



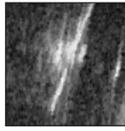
3291-Patch 1













finds similarity between the object-background non-matching pair. It might be that DenseNet is better in hard-feature extraction than VGG. Because of high noise, in sonar, doing just pixel-

