Notes from nearly draining pursuits of mastery in Leetcode problems

Hardik Rajpal

March 14, 2023

Contents

1	STL	2
	1.1 Sets and Maps	
	1.2 Iterators	2
	Graph Algorithms 2.1 BFS—DFS	3
	Misc. Algorithms	3
	3.1 Binary Search	3

1 STL

1.1 Sets and Maps

These (set and map) are ordered data structures; helpful when it is efficient to retain the ordering of a collection of elements during execution. Their unordered counterparts (unordered_set and unorderd_map) prioritize access time and maintain no order of their elements.

Declaration syntaxes

Listing 1: Sets and Maps

```
struct U{
    bool operator()(T t1, T t2)const{
        //logic comparing t1<t2.
    }
};
set<T,struct U> myset;
map<T,V,struct U> mymap;
```

The ordering parameter U is crucial in cases where order between T is not inferable.

Listing 2: Unordered sets and maps

```
struct T{
    ...
    bool operator == (T t2) const {
        //return logic for t2 == this.
    }
};
struct hashT{
    size_t operator()(T t) const {
        //std::hash<string or int or double>()(string or int or double)
        //return logic for hashing t. Use ^ << >> ~ | &
    }
};
unordered_set<T,struct hashT> uset;
unordered_map<T,V,struct hashT> umap;
```

1.2 Iterators

An iterator pointing at an element is "corrupted" on removing the element. Hence, any useful data should be copied over the iterator before removing the element.

Listing 3: Undefined behaviour

```
lists.erase(*minit);//minit is corrupted
lists.insert((*minit)->next);
```

Listing 4: Working code

```
lists.insert((*minit)->next);//first use the data.
lists.erase(*minit);//then erase.
```

2 Graph Algorithms

2.1 BFS—DFS

I prefer writing both of these iteratively. In the immortal intonation of Ashish Mishra,

BFS - Queue DFS - Stack

Here's a sample of both algorithms.

Listing 5: BFS

```
Ts;
unordered_map <T, vector <T>> edges;
                                                   Listing 6: DFS
queue <T> q;
                                      Ts;
unordered_map <T, bool > visited;
                                      unordered_map <T, vector <T>> edges;
unordered_map <T,T> prev;
                                      stack <T> s;
int steps = 0;
                                      unordered_map <T, bool > visited;
q.push(s);
                                      unordered_map <T,T> prev;
visited[s] = true;
                                      s.push(s);
while(!q.empty()){
                                      visited[s] = true;
    int sz = q.size();
                                      while(!s.empty()){
    while(sz--){
                                                                             The notes
                                          T u = s.top();
        T u = q.front();
                                          s.pop();
        q.pop();
                                          for(nb:edges[u]){
         for(nb:edges[u]){
                                               if(!visited[nb]){
             if(!visited[nb]){
                                                   visited[nb] = true;
                visited[nb] = true;
                                                   prev[nb] = u;
                prev[nb] = u;
                                                   q.push(nb);
                q.push(nb);
                                               }
                                          }
                                      }
    }
    steps++;
```

should be reduced from the abstract type T, to int whenever possible; thereby reducing the unordered_maps to vectors which can sometimes get you under the time limit. Click here for Why?

Optimizations

• If the list of neighbours is a shared data structure, consider clearing it after having visited the neighbours using any one owner. Since, all elements in the shared field are visited and running them through the loop for other owners of the field is redundant. (Leetcode)

3 Misc. Algorithms

3.1 Binary Search

While the idea of binary search is clear, opportunities for its application may not be easily identified (yet). Some common places where it may be applied:

Optimization Problems

Problems involving the evaluation of the min/max of an expression, while its constituents satisfy a constraint that is straightforward to check. Consider the problem below:

```
Given x_1, x_2, ...x_n and T, find min_{a_1, a_2, ...a_n}(max_i(a_ix_i)) such that \sum_{i=0}^n a_i \ge T (Leetcode)
```

The binary search algorithm is:

Listing 7: BinSearch

```
int n = x.size();
int mine = *min_element(x.begin(),x.end());
int maxe = *max_element(x.begin(),x.end());
unsigned long long lb = mine, ub = T*(unsigned long long)maxe;
unsigned long long del = (ub - 1b)/2;
auto numtrips = [x,n](unsigned long gt){
    unsigned long long nt = 0;
        for(int i=0;i<n;i++){</pre>
            nt += (gt/x[i]);
        return nt;
};
while(del>0){
   if (numtrips(lb+del)>=T){
        ub = 1b + del;
    else{
       1b = 1b + del;
    del = (ub-lb)/2;
if (numtrips(lb)>=T){
   return lb;
return lb+1;
```