

GAME2001 Data Structures and Algorithms

Fall 2020



Week 11

Advanced Sorting

Advanced Sorting

- Shellsort
 - Quicksort
 - Radix sort
-
- Much faster than simple sorts
 - Do not require extra memory

Shellsort

- Great for medium size data
 - Quicksort can outperform it for larger data
- Based on insertion sort
- It minimizes the number of copies to increase performance

Shellsort

- Performs insertion sort on a few widely spread elements
- During each pass the range (gap) is reduced until all elements are in their correct position
- Gets the array close to being partially sorted
 - Causes later passes to execute faster
- When the range is 1, insertion sort is applied

Shellsort

- How do you choose a good initial range?
 - Knuth method $h = h * 3 + 1$
 - h starts out as 1 and keeps going until its larger than the array size, at that point the previous size is used as the gap sequence

Array size = 500 \square 1, 4, 13, 40, 121, 364, 1093

Shellsort

- You can use the inverse algorithm to figure out the previous gaps
 - $h = (h - 1) / 3$

Shellsort

```
1 void Shellsort()
2 {
3     assert(m_array != NULL);
4
5     T temp;
6     int i = 0, k = 0;
7
8     // Sequence...
9     int seq = 1;
10
11     while(seq <= m_numElements / 3)
12         seq = seq * 3 + 1;
13
14     while(seq > 0)
15     {
16         for(k = seq; k < m_numElements; k++)
17         {
18             temp = m_array[k];
19             i = k;
20
21             while(i > seq - 1 && m_array[i - seq] >= temp)
22             {
23                 m_array[i] = m_array[i - seq];
24                 i -= seq;
25             }
26
27             m_array[i] = temp;
28         }
29
30         seq = (seq - 1) / 3;
31     }
32 }
```

```
1 template<typename T>
2 class UnorderedArray
3 {
4     public:
5         void InsertionSort()
6         {
7             assert(m_array != NULL);
8
9             T temp;
10            int i = 0;
11
12            for(int k = 1; k < m_numElements; k++)
13            {
14                // item to be placed in the right slot
15                temp = m_array[k];
16                i = k;
17
18                while(i > 0 && m_array[i - 1] >= temp)
19                {
20                    // switch the bigger value up
21                    m_array[i] = m_array[i - 1];
22                    i--;
23                }
24                // place item in correct slot
25                m_array[i] = temp;
26            }
27        }
28};
```


Shellsort Example

```
2 #include "ShellsortArray.h"
3
4 using namespace std;
5
6 int main(int args, char *arg[])
7 {
8     cout << "Shellsort Algorithm" << endl << endl;
9
10    const int size = 10;
11    int i = 0;
12
13    UnorderedArray<int> array(size);
14
15    for(i = 0; i < size; i++)
16        array.push(rand() % 100);
17
18    cout << "Before shellsort sort:";
19
20    for(i = 0; i < size; i++)
21        cout << " " << array[i];
22
23    cout << endl;
```

```
25    array.Shellsort();
26
27    cout << " After shellsort sort:";
28
29    for(i = 0; i < size; i++)
30        cout << " " << array[i];
31
32    cout << endl << endl;
33
34    return 1;
35}
```

Shellsort Algorithm

```
Before shellsort sort: 41 67 34 0 69 24 78 58 62 64
After shellsort sort: 0 24 34 41 58 62 64 67 69 78
```

Partitioning

- Used as the basis for quicksort
- Sole purpose is to split data into two sections
- Partitioning Algorithm
 - Takes a data set that needs to be partitioned and a condition by which it is split up
- Pivot value: value used in the comparison
- Pivot index: the position in the container where the first section ends and the second begins

Partitioning

Pivot value = 10

32	2	16	9	1	5	11
----	---	----	---	---	---	----

				Section 2			
5	2	1		9	16	32	11
Section 1							

Partitioning

- not a sorting algorithm
- it is one step closer to being sorted
- $O(N)$

Partitioning

```
int Partition(int lIndex, int rIndex, T pivot)
{
    int currentLeft = lIndex;
    int currentRight = rIndex;

    while(1)
    {
        while(currentLeft < rIndex && m_array[currentLeft] < pivot)
        {
            // Searching left for val bigger than pivot.
            // This will break when it finds it or moves to the end.
            currentLeft++;
        }

        while(currentRight > lIndex && m_array[currentRight] > pivot) {
            // Same as left side.
            currentRight--;
        }

        if(currentLeft >= currentRight)
        {
            // Done with partition (no more to search).
            break;
        }

        // Swap elements if we get here.
        SwapElements(currentLeft, currentRight);
    }

    // Returns position of the pivot.
    return currentLeft;
}
```

```
void SwapElements(int index1, int index2)
{
    assert(index1 >= 0 && index1 < m_numElements);
    assert(index2 >= 0 && index2 < m_numElements);
    assert(m_array != NULL);

    T temp = m_array[index1];
    m_array[index1] = m_array[index2];
    m_array[index2] = temp;
}

int Partition(T pivot)
{
    return Partition(0, m_numElements - 1, pivot);
}
```

Partitioning Example

```
1#include <iostream>
2#include "PartitioningArray.h"
3
4using namespace std;
5
6int main(int args, char *arg[])
7{
8    cout << "Partitioning Algorithm" << endl;
9    cout << endl;
10
11    const int size = 10;
12    int i = 0;
13    int pivotValue = 60;
14
15    UnorderedArray<int> array(size);
16
17    // Insert elements and print basic stats.
18    for(i = 0; i < size; i++)
19        array.push(rand() % 100);
20
21    cout << "Array size - " << size << " pivot value - "
22        << pivotValue << "." << endl << endl;
23
24    // Display elements.
25    cout << "Before partitioning:";
26
27    for(i = 0; i < size; i++)
28        cout << " " << array[i];
29
30    cout << endl << endl;
31
32    // Partition then display results.
33    int pivot = array.Partition(pivotValue);
34
35    cout << "After partitioning (pivot index - "
36        << pivot << "):";
37
38    for(i = 0; i < size; i++)
39        cout << " " << array[i];
40
41    cout << endl << endl;
42
43    return 1;
44}
```

Partitioning Algorithm

Array size - 10 pivot value - 60.

Before partitioning: 41 67 34 0 69 24 78 58 62 64

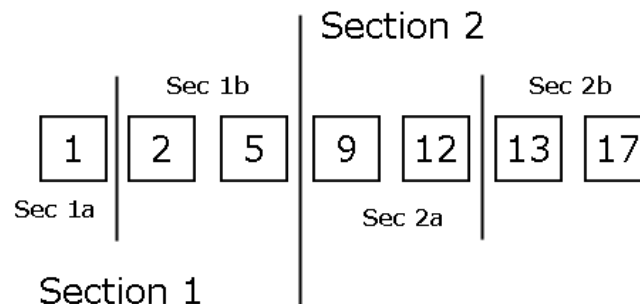
After partitioning (pivot index - 5): 41 58 34 0 24 69 78 67 62 64

Quicksort

- Very popular for large data sets
- Based on the partitioning algorithm
- Uses recursion and partitioning to partition data sections until the lowest level is reached
 - Data is sorted

Quicksort

- 1) Pick a pivot value and partition the array into two sections
 - 2) Recursively partition the two sections further until there is only one element left
- The key is to choose a good pivot value

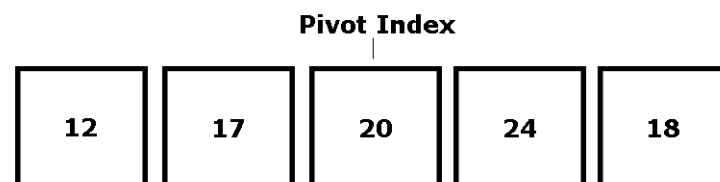


Quicksort

```
1 template<typename T>
2 class UnorderedArray
3 {
4     public:
5         void SwapElements(int index1, int index2)
6         {
7             assert(index1 >= 0 && index1 < m_numElements);
8             assert(index2 >= 0 && index2 < m_numElements);
9             assert(m_array != NULL);
10
11             T temp = m_array[index1];
12             m_array[index1] = m_array[index2];
13             m_array[index2] = temp;
14         }
15
16         void Quicksort()
17         {
18             QuickSort(0, m_numElements - 1);
19         }
20
21     private:
22         void QuickSort(int lVal, int rVal)
23         {
24             if((rVal - lVal) <= 0)
25                 return;
26
27             int pivotIndex = Partition(lVal, rVal,
28                                     m_array[rVal]);
29
30             QuickSort(lVal, pivotIndex - 1);
31             QuickSort(pivotIndex + 1, rVal);
32         }
```

Quicksort

```
34 int Partition(int lIndex, int rIndex, T pivot)
35 {
36     int currentLeft = lIndex;
37     int currentRight = rIndex - 1;
38
39     while(1)
40     {
41         while(m_array[currentLeft] < pivot)
42         {
43             // Searching left for val bigger than pivot.
44             // This will end when it finds it.
45             currentLeft++;
46         }
47
48         while(currentRight > 0 && m_array[currentRight] > pivot)
49         {
50             // Same as left side.
51             currentRight--;
52         }
53
54         if(currentLeft >= currentRight)
55         {
56             // Done with partition (no more to search).
57             break;
58         }
59
60         // Swap elements if we get here.
61         SwapElements(currentLeft, currentRight);
62     }
63
64     SwapElements(currentLeft, rIndex);
65
66     // Returns position of the pivot.
67     return currentLeft;
68 }
69};
```



Quicksort Example

```
1#include <iostream>
2#include "QuicksortArray.h"
3
4using namespace std;
5
6int main(int args, char *arg[])
7{
8    cout << "Quicksort Algorithm" << endl << endl;
9
10    const int size = 10;
11    int i = 0;
12    UnorderedArray<int> array(size);
13
14    // Insert elements and print basic stats.
15    for(i = 0; i < size; i++)
16        array.push(10 + rand() % 90);
17
18    // Display elements.
19    cout << "Before Quicksort:";
20
21    for(i = 0; i < size; i++)
22        cout << " " << array[i];
23
24    cout << endl << endl;
```

```
26    // Sort then display results.
27    array.Quicksort();
28
29    cout << " After Quicksort:";
30
31    for(i = 0; i < size; i++)
32        cout << " " << array[i];
33
34    cout << endl << endl;
35
36    return 1;
37}
```

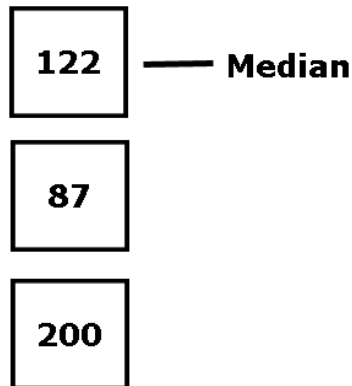
Quicksort Algorithm

Before Quicksort: 51 27 44 50 99 74 58 28 62 84

After Quicksort: 27 28 44 50 51 58 62 74 84 99

Quicksort: Median-of-three

- A method for quickly picking a good pivot value
- The first, middle and last element are examined and the median is chosen as the pivot value



Quicksort: Median-of-three

- Problem:
 - Cant use it with less than three items
 - We can fall back to another simpler searching algorithm in this case

Quicksort: Median-of-three

```
1 #define QUICKSORT_CUTOFF    4
2
3 template<typename T>
4 class UnorderedArray
5 {
6     public:
7         void InsertionSort()
8         {
9             InsertionSort(0, m_numElements - 1);
10        }
11
12        void SwapElements(int index1, int index2)
13        {
14            assert(index1 >= 0 && index1 < m_numElements);
15            assert(index2 >= 0 && index2 < m_numElements);
16            assert(m_array != NULL);
17
18            T temp = m_array[index1];
19            m_array[index1] = m_array[index2];
20            m_array[index2] = temp;
21        }
22
23        void Quicksort()
24        {
25            Quicksort(0, m_numElements - 1);
26        }
```

```
28     private:
29         void QuickSort(int lVal, int rVal)
30         {
31             if((rVal - lVal + 1) < QUICKSORT_CUTOFF)
32             {
33                 InsertionSort(lVal, rVal);
34                 return;
35             }
36
37             int center = (lVal + rVal) / 2;
38
39             if(m_array[lVal] > m_array[center])
40                 SwapElements(lVal, center);
41
42             if(m_array[lVal] > m_array[rVal])
43                 SwapElements(lVal, rVal);
44
45             if(m_array[center] > m_array[rVal])
46                 SwapElements(center, rVal);
47
48             int pivotIndex = Partition(lVal, rVal, center);
49
50             QuickSort(lVal, pivotIndex - 1);
51             QuickSort(pivotIndex, rVal);
52        }
```

Quicksort: Median-of-three

```
54 int Partition(int lIndex, int rIndex, int pivot)
55 {
56     while(1)
57     {
58         while(m_array[++lIndex] < m_array[pivot]);
59         while(m_array[--rIndex] > m_array[pivot]);
60
61         if(lIndex >= rIndex)
62             break;
63
64         SwapElements(lIndex, rIndex);
65     }
66
67     // Returns position of the pivot.
68     return lIndex;
69 }
```

```
71 void InsertionSort(int lVal, int rVal)
72 {
73     assert(m_array != NULL);
74
75     T temp;
76     int i = 0;
77
78     for(int k = lVal + 1; k <= rVal; k++)
79     {
80         temp = m_array[k];
81         i = k;
82
83         while(i > lVal && m_array[i - 1] >= temp)
84         {
85             m_array[i] = m_array[i - 1];
86             i--;
87         }
88
89         m_array[i] = temp;
90     }
91 }
92};
```

Quicksort: Median-of-three Example

```
1#include <iostream>
2#include "Quicksort3Array.h"
3
4using namespace std;
5
6int main(int args, char *arg[])
7{
8    cout << "Median-Of-Three Quicksort Algorithm"
9        << endl << endl;
10
11    const int size = 10;
12    int i = 0;
13    UnorderedArray<int> array(size);
14
15    // Insert elements and print basic stats.
16    for(i = 0; i < size; i++)
17        array.push(10 + rand() % 90);
18
19    // Display elements.
20    cout << "Before Quicksort:";
21
22    for(i = 0; i < size; i++)
23        cout << " " << array[i];
24
25    cout << endl << endl;
```

```
27    // Sort then display results.
28    array.Quicksort();
29
30    cout << " After Quicksort:";
31
32    for(i = 0; i < size; i++)
33        cout << " " << array[i];
34
35    cout << endl << endl;
36
37    return 1;
38}
```

```
Median-Of-Three Quicksort Algorithm
Before Quicksort: 51 27 44 50 99 74 58 28 62 84
After Quicksort: 27 28 44 50 51 58 62 74 84 99
```


Radix sort

- Quickly sorts the elements in a container without performing comparisons of internal elements
- Creates a number of internal containers that it uses to perform its job

Radix sort

- sort numbers that use the decimal system

Unordered Array

13	8	11	6	19	2
----	---	----	---	----	---

Array of link list for 0 to 9

Inserted elements from array into matching node

0	1	2	3	4	5	6	7	8	9
		11	2	13		6		8	19

Radix sort

Unordered Array

13	8	11	6	19	2
----	---	----	---	----	---

After 1's Pass

11	2	13	6	8	19
----	---	----	---	---	----

After 10's Pass

2	6	8	11	13	19
---	---	---	----	----	----

GAME 2001

Data Structures and Algorithms



```
1#include <iostream>
2#include <deque>
3
4using namespace std;
5
6#define BASE          10
7#define MAX_POSITIONS  2
8
9void RadixSort(int *array, int size)
10{
11    // Base index, radix index, counter.
12    int b = 0, r = 0, i = 0;
13    // Container conter, base factor.
14    int index = 0, factor = 0;
15
16    // List of containers for the sort.
17    deque<int> qList[BASE];
18
19    // Place in containers then take them off for every base.
20    for(b = 1, factor = 1; b <= MAX_POSITIONS; factor *= BASE, b++)
21    {
22        for(r = 0; r < size; r++)
23        {
24            index = (array[r] / factor) % BASE;
25            qList[index].push_back(array[r]);
26        }
27        for(r = 0, i = 0; r < BASE; r++)
28        {
29            while(qList[r].empty() != true)
30            {
31                array[i++] = qList[r].front();
32                qList[r].pop_front();
33            }
34        }
35    }
36}
```

Radix Sort Example

Array contents before sort: 51 54 25 77 44 70 96 87 94 88

Array contents after sort: 25 44 51 54 70 77 87 88 94 96

```
38int main(int args, char **argc)
39{
40    cout << "Radix Sort Example"
41         << endl << endl;
42
43    const int size = 10;
44    int array[size];
45    int i = 0;
46
47    // Populate array.
48    for(i = 0; i < size; i++)
49        array[i] = 10 + rand() % 89;
50
51    // Display array contents.
52    cout << "Array contents before sort: ";
53
54    for(i = 0; i < size; i++)
55        cout << " " << array[i];
56
57    cout << endl;
58
59    // Radix sorting.
60    RadixSort(array, size);
61
62    // Display array contents.
63    cout << " Array contents after sort: ";
64
65    for(i = 0; i < size; i++)
66        cout << " " << array[i];
67
68    cout << endl << endl;
69
70    return 1;
71}
```