



# Week 1 Introduction Big-O Custom Data Structures vs STL



#### Introduction

- Data structures
  - building blocks of game development
  - not that useful by themselves
    - but combined with algorithms they become extremely powerful



#### **DATA STRUCTURES**

- defines how data is arranged in memory
- can be operated on by using various algorithms

- Array
  - defines how data is arranged in memory
    - variables or objects of a specific type
  - can be operated on by various algorithms
    - insertion into the array, deletion, searching, sorting



#### **DATA STRUCTURES**

- Arrays
- Link lists
- Queues
- Stacks
- Heaps
- Graphs
- Scene graphs
- Octrees

- Quad-trees
- Binary trees
- Minimax trees
- kd trees
- Sphere trees
- Bounding volume hierarchies
- Hash tables
- Portals and sectors



#### **DATA STRUCTURES**

- Another way to look at a data structure
  - a structure that is often user-defined and represents some kind of physical object.

Data structures are also objects that contain objects.



#### **ALGORITHMS**

- code that manipulates data in data structures
  - inserting items into a data structure, deleting items, sorting, and iterating
- Recursion
- Insertions
- Deletions
- Merging
- Sorting algorithms
- Searching algorithms

- Transversal
- Balancing algorithms
- Data compression
- Texture compression
- Data encryption
- Texture filters



- Topics we will be addressing:
  - How to store data efficiently in the computer's memory
  - How to process data efficiently
  - What algorithms work best under what situations and why
  - How various popular algorithms compare to one another in specific situations
  - What data structures can help the processing of game data in certain situations



- Scene Management
  - Virtual environments more complex than hardware can handle
  - Thousands of polygons rendered, special effects are updated and drawn and physics processed. Can overwhelm a system.
  - Data structures used since the beginning of 3D games to speed up rendering of scenes
    - Otherwise performance would be down to a noninteractive rate.
  - Examples:
    - Determining which geometry is visible and only rendering that
    - Avoiding or minimizing bottlenecks during state changes in the system
    - Managing static and dynamic objects



#### Artificial Intelligence

- Drives many gaming experiences. Can be simple or complex.
- Data structures used to control behavior of dynamic game elements.
- More complex AI becomes an issue of speed. Higher complexity means longer processing times to complete its operations.
  - Combine that with multiple objects needing to execute AI algorithms.
- Often find yourself balancing realism vs performance
- Al in games often not as complex as Al used in robotics and other similar technologies.



- Physics Dynamics and Collisions
  - Standard feature in 3D games
  - Represents how game objects interacts with the environment.
    - Forces (gravity, wind, etc..)
    - Collisions (and what happens after 2 things collide)
  - Will have their own specific data structures and algorithms specific to physics (point masses, rigid bodies, etc)
  - Physics so expensive to calculate, other data structures and algorithms for scene managements are also used in physics to help eliminate unnecessary calculations.



#### The C++ STL

- a standard set of template classes
- used for both code reuse and maintainability
- composed of many efficiently designed components and algorithms
- composed of containers, iterators, and algorithms
  - containers are the template classes that represent a data structure
  - iterator is used to transverse through a data structure
- main goal
  - to be abstract while maintaining efficiency



#### The C++ STL

- vector
- queue
- priority\_queue
- list
- deque
- stack
- map

- multimap
- set
- multiset
- hash\_set
- hash\_multiset
- hash\_map
- hash\_multimap
- Part of C++ standard
  - bitset, string, valarray



#### **Custom Data Structured vs STL**

- STL Advantages
  - The STL is standard.
  - The STL is widely used.
  - The STL is optimized and efficient.
  - Using the STL saves time and effort.
  - The STL comes with C++.



#### **Custom Data Structured vs STL**

- STL Disadvantages
  - Debugging
  - Compiler error messages
  - Memory allocation
  - Code bloat (templates)
  - Compile times (templates)



#### **Custom Data Structured vs STL**

- Tools
  - Can almost always use STL
- Game code
  - Start with STL
  - Switch to custom data structures if STL cannot do the job



#### **Templates**

- a way to create code that is evaluated during compile time rather than runtime
- allow for the same code to be used with different data and user-defined types
  - minimizes the need to write duplicate code
- Function templates
  - allow programmers to specify function parameters to the template
- Class templates
  - allows programmers to specify the type for the template



#### **Template Example**

```
1 #include<iostream>
    using namespace std;
    template<class T>
 5 ☐ T min func(T lVal, T rVal)
 6
        if(lVal > rVal)
 8
            return rVal:
        return lVal:
10
11
    template<class T>
13 T max func(T lVal, T rVal)
14
15
        if(lVal < rVal)</pre>
            return rVal;
16
      return lVal;
18
19 L
```

```
template<class T>
21 class TemplateClass
23
        public:
             TemplateClass(T val)
25
                 m val = val;
28
29白
            bool operator < (TemplateClass &rVal)
30
                 return m val < rVal.GetVal();
32
33
34 向
            bool operator>(TemplateClass &rVal)
35
36
                 return m val > rVal.GetVal();
37
38
39
             T GetVal()
40
41
                 return m val;
43
        private:
             T m val;
45 | };
```



#### **Template Example**

```
47 int main(int args, char **argc)
48
        cout << "Template Example" << endl << endl;
49
50
51
        cout << "Min = " << min func(32, 54) << endl;
52
        cout << "Max = " << max func(49.3, 38.98) << endl;
        cout << "Max (objects) = "
53
54
             << max func(TemplateClass<int>(7),
                          TemplateClass<int>(4)).GetVal()
56
             << endl:
        TemplateClass<int> obj(10);
58
59
        cout << "obj = " << obj.GetVal() << endl;</pre>
        cout << endl << endl;
60
61
62
        return 1:
```



#### **Template Drawbacks**

- Complexity
  - Difficult to read
  - Difficult to modify and update
  - Difficult to debug
- Dependencies
  - Increased coupling and compile times since the definition has to be with the declaration
- Code Bloat
  - Since it creates the class and functions at compile time for each type
- Compiler Support
  - Different compilers have different type of template support



- used to describe the theoretical performance of an algorithm
- measures the time or memory consumption used by an algorithm
- create a representation of the performance of an algorithm to compare it to others



- Problem
  - performance of algorithms can fluctuate depending on the number of items that were inserted and are present in a data structure
  - Example: if algorithm A runs faster than algorithm B with
     1,000 items but runs slower with 100,000 items, it can be hard
     to get an accurate picture when comparing the two
- Big-O notation gives an idea of an algorithm's performance based on the number of items in the structure (its growth).



- Example
  - Line 3 and 8 (2)
    - Count for one unit each
  - Line 6 (4N)
    - Four units per time executed
      - 2 multiplications
      - 1 addition
      - 1 assignment
    - And is executed N times
  - Line 4 (2N + 2)
    - Initializing (1)
    - Comparing (N + 1)
    - Incrementing (N)
  - Total = 6N + 4



- Big-O notation is identified as the term in the function that increases fastest relative to the size of the problem
  - $-N^4 + 100N^2 + 10N + 50$ 
    - Big-O notation = O(N<sup>4</sup>)
    - Other terms can be ignored
      - They are insignificant as N gets larger



- O(1)
  - Constant or bounded time
  - Assigning a value to the i<sup>th</sup> element in an array of N elements
- O(log<sub>2</sub>N)
  - Logarithmic time
  - Algorithms that successfully cut the amount of data in half typically fall into this category
- O(N)
  - Linear time
  - Printing all elements is a list of N elements



- O(N log<sub>2</sub>N)
  - N log<sub>2</sub>N time
  - Applying a logarithmic algorithm N times
    - better sorting algorithms (Quicksort, Heapsort, Merge sort)
- O(N<sup>2</sup>)
  - Quadratic time
  - Applying a linear algorithm N times
  - Simple sorting algorithms (Bubble sort, Insertion sort)

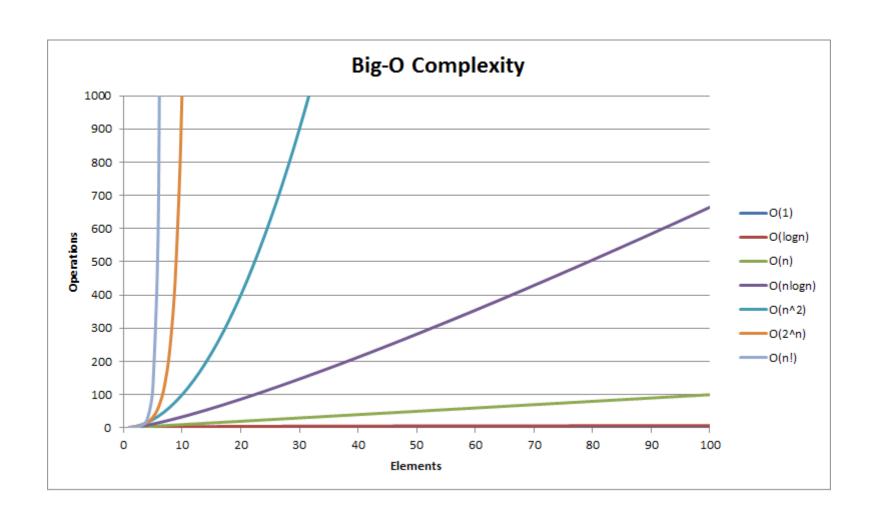


- O(N<sup>3</sup>)
  - Cubic time
  - A routine that increments every element in a three dimensional table of integers
- O(2<sup>N</sup>)
  - Exponential time
  - VERY COSTLY, increases exponentially



N	log <sub>2</sub> N	N log <sub>2</sub> N	N <sup>2</sup>	$N^3$	2 <sup>N</sup>
1	0	1	1	1	2
2	1	2	4	8	4
4	2	8	16	64	16
8	3	24	64	512	256
16	4	64	256	4,096	65,536
32	5	160	1,024	32,768	4,294,967,296
64	6	384	4,096	262,114	1.8 x 10 <sup>19</sup>
128	7	896	16,384	2,097,152	$3.4 \times 10^{38}$
256	8	2,048	65,536	16,777,216	1.1 x 10 <sup>77</sup>







- Example
  - Calculate the sum of integers from 1 to N

- What is Big-O?
- Is there a better algorithm?



#### **Big-O Notation**

Consider the following calculation when N = 5

- We pair up each number from 1 to N with another, such that each pair adds up to N + 1
- There are N such pairs, giving us a total of (N+1)\*N
- Since each number is included twice, we divide the product by 2

$$-[(5+1)*5]/2 = 15$$



- Example
  - Calculate the sum of integers from 1 to N
    - Using formula

- What is Big-O?
- Is this always faster?



- General Rules
  - Rule 1 FOR loops
    - Running time of the statements of the for loop times the number of iterations
  - Rule 2 Nested loops
    - Analyze these inside out
    - Running time of the statement multiplied by the product of the sizes of all the loops

```
- O(n^2)
```



- Rule 3 Consecutive Statements
  - These just add

```
- O(n^2)
```

- Rule 4 If/Else
  - Never more than the running time of the test plus the larger of the running times of statement 1 and statement2

• Can be over estimated in some cases, but never underestimated



#### **Big-O Notation**

```
1 = #include <time.h>
    #include <iostream>
    using namespace std;
    const int n = 500;
    float TestData[n][n][n];
 8 double diffclock(clock t clock1,clock t clock2)
 9
10
        double diffticks=clock1-clock2:
        double diffms=(diffticks*10)/CLOCKS PER SEC;
11
12
        return diffms:
13
14
15 □ void column ordered()
16 {
17
        for (int k = 0; k < n; ++k)
18
            for (int j = 0; j < n; ++j)
19
                for (int i = 0; i < n; ++i)
20
                    TestData[i][j][k] = 0;
21
23 □ void row ordered()
24 {
25
        for (int i = 0; i < n; ++i)
26
            for (int j = 0; j < n; ++j)
                for (int k = 0; k < n; ++k)
28
                    TestData[i][j][k] = 0;
29
30 6
```

Not the only thing we need to worry about

```
31 mint main()
32
   -{
        clock t begin=clock();
33
        row ordered();
34
        clock t end=clock();
35
36
        cout << "Time elapsed (row): "
37
             << diffclock(end,begin)
             << " ms" << endl;
38
39
40
        begin=clock();
        column ordered();
41
        end=clock();
43
        cout << "Time elapsed (column): "
44
             << diffclock(end,begin)
45
             << " ms" << endl:
46
47
        return 0:
48
```