# **ROBOTICS EVENTS**

# EVENT - SUB EVENT: ROBO-SOCCER

- EVENT NAME Robo-Soccer
- EVENT DESCRIBTION -

### **OBJECTIVE:**

• Construct one manually/wireless controlled robot that could play soccer against a two opponent.

# TRACK SPECIFICATIONS:

### **ROBOT SPECIFICATIONS:**

- Starting &Working Condition: 30cm\*35cm\*30cm (I\*b\*h)
- Max. Weight: 2kg
- Max. Voltage: 12V d.c
- Robot Type: 1 Manual/wireless robot (as a goalkeeper and player).
- Voltage: 12V.

## **RULES:**

- 1. The robot would be required to make a goal within a preset time limit.
- 2. Two teams will participate in the event simultaneously. Both the teams will start from their respective homes.
- 3. At the centre of the arena there will be a small plastic ball. The robots are required to make as many goals as possible in the opponent's goal post.
- 4. Robot is not allowed to hold the ball (either directly or if the ball is lying inside the periphery of the bot) for more than 5 seconds or else the team will have to face a penalty.
- 5. A complete match will be divided into two rounds of 3 minutes duration each. At the end of the match, the team having the maximum number of goals will be declared as the winner .In case of a tie, a third round will be conducted.
- 6. During the match, if there is any technical fault with any of the robots, the team can ask for a timeout of 3min. A team can go for a MAXIMUM OF 1 TIMEOUTS.

- 7. If robot causes damage to the arena in anyway, the team will be disqualified immediately.
- 8. Participants should ensure that their wires do not tangle with each other or anywhere with the arena.
- 9. In case the ball bounces off the arena, a timeout will be called by the coordinators.
- 10.In case of any dispute or controversy, the decision of the Coordinators would be considered as the final.
- 11. The rules are subjected to change. You will be informed accordingly.