

Ultrasound-guided Vascular Navigation using Deep Learning

Hareem Nisar^{1,2}, Patrick K. Carnahan^{1,2}, David Hocking³, Terry Peters^{1,2}, and Elvis C.S. Chen^{1,2}

Robarts Research Institute, Western University, Canada Department of Biomedical Engineering, Western University, Canada London Health Sciences Centre, Canada



INTRODUCTION

During transcatheter cardiac and endovascular interventions, the guidewire navigate the vessels to reach the target area.

Current standards for vascular navigation include 2D fluoroscopic imaging & pre-operative CT mapping, which have some disadvantages:

- Radiation exposure to the patient and clinicians.
- "Interventionalist's disc diseases" i.e. back and neck pain due to wearing heavy led shielding.
- 2D projected views only
- Expensive, non-portable specialized room and equipment

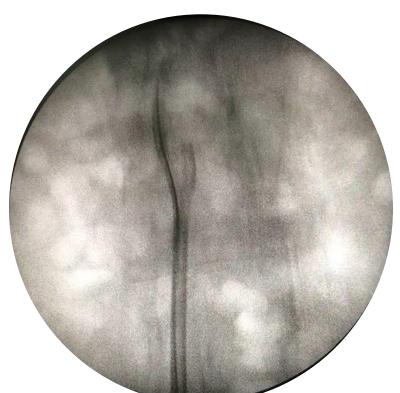
PROPOSED SOLUTION – An ultrasound-based vessel navigation system

Proposed procedural workflow:

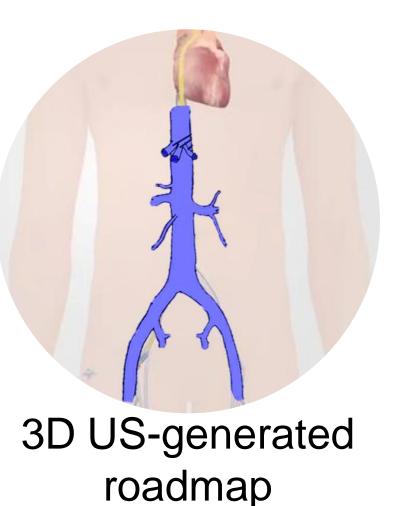
Generate in real-time a 3D vascular Roadmap, using a tracked intracardiac ultrasound (ICE) probe, which can then be employed as a GPS map to allow safe traversal by a tracked guidewire to reach the target organ or vessel.

OBJECTIVE

To reconstruct vascular access pathways using ICE imaging, tracking technology and deep learning based methods.

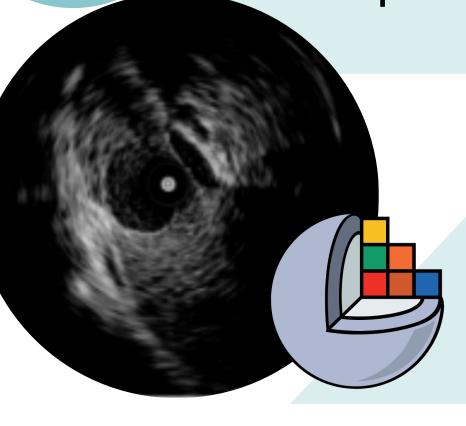


2D projected fluoroscopy



METHODS

Magnetically tracked and calibrated end-firing 3D ICE probe scans a vessel via the pull-back method to acquire vascular lumen data for reconstruction.



Imaging & tracking data are recorded using a frame-grabber and PLUS² application

Vessel lumen is segmented from each 2D image via pre-trained U-net model¹



Training: 70 images of animal vena cava

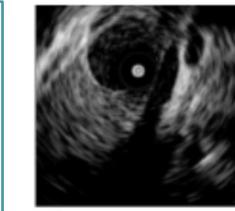
Ground truth label: manually annotated & verified by expert clinician

Pre-processing: crop to central 300x300 px

Data augmentation: random 90° rotation & elastic deformation

Post-processing: keeping largest connected island & hole filling

Validation: 9 images of animal vessels



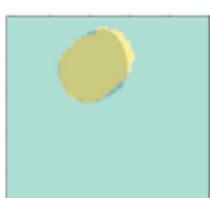
Pre-processed image



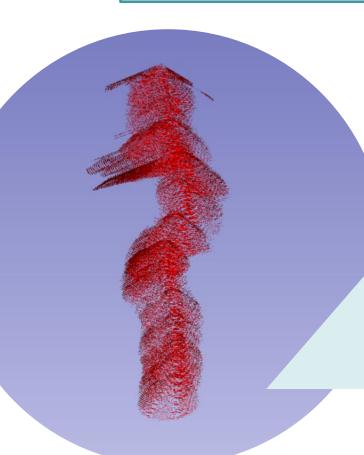
U-net model generated label



Post-processed label

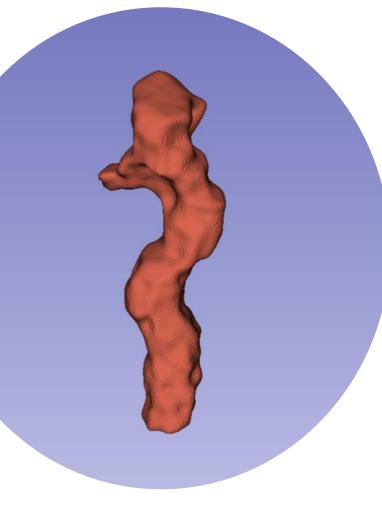


Comparison with ground truth



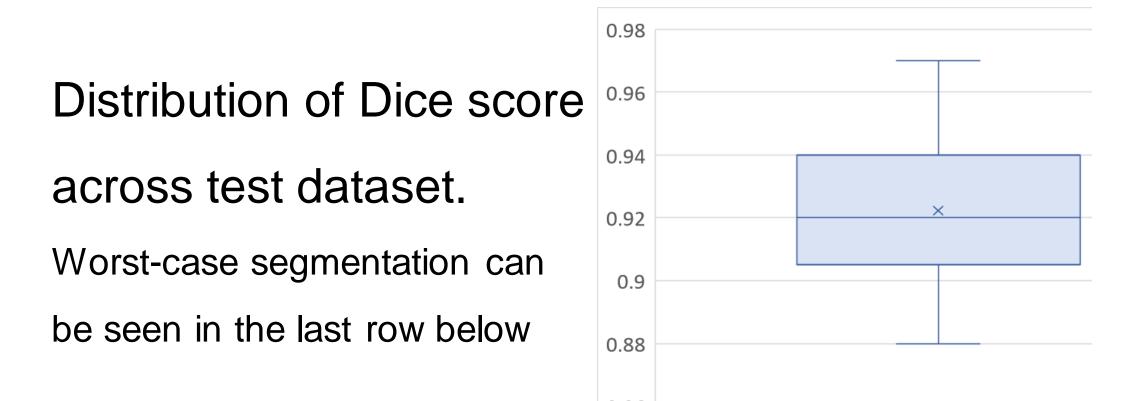
Segmented vessel lumens are placed at their true locations in 3D space using the calibration and tracking information

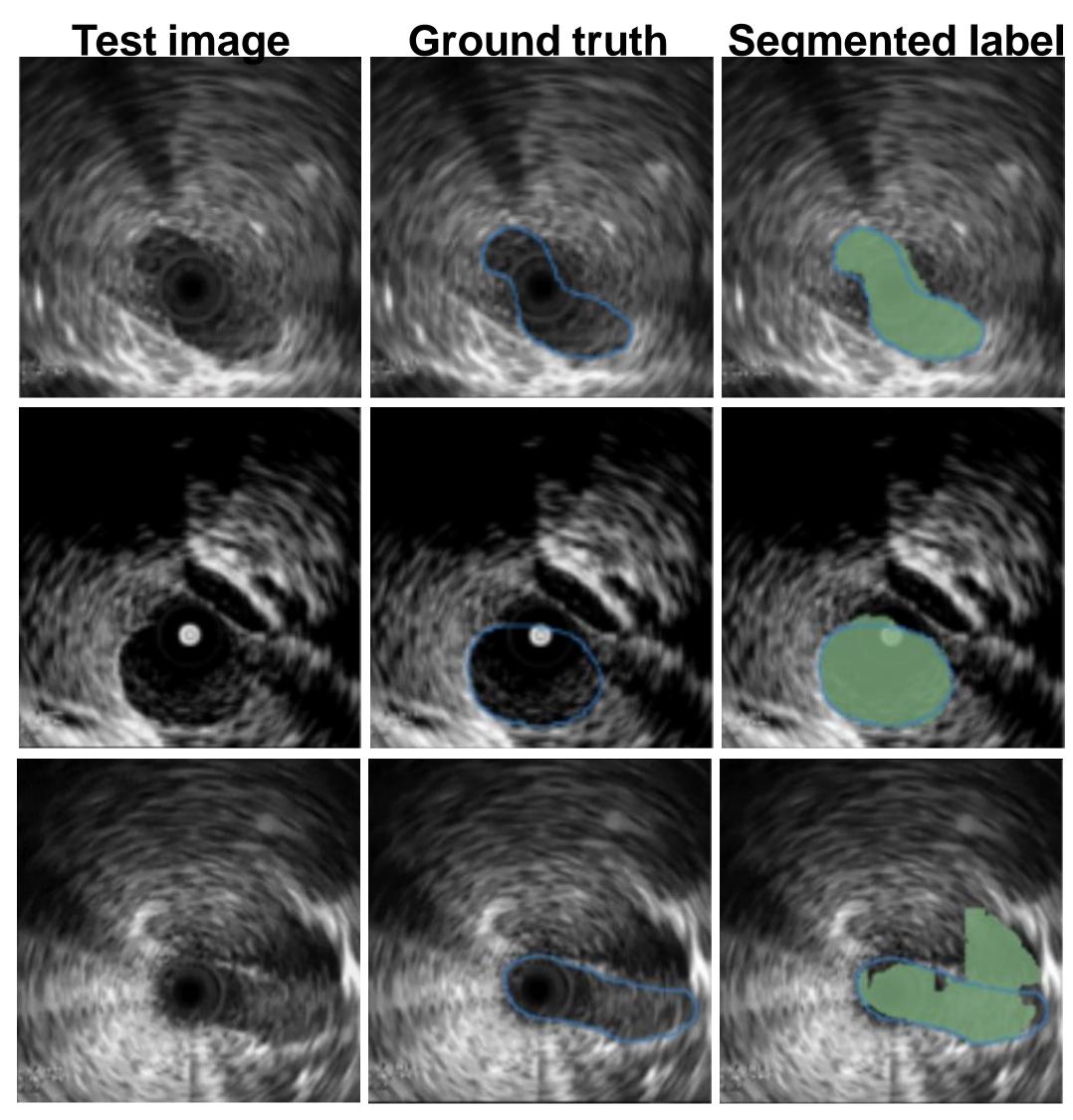
Vessel surface is reconstructed by applying binary morphological closing & Gaussian blur operations

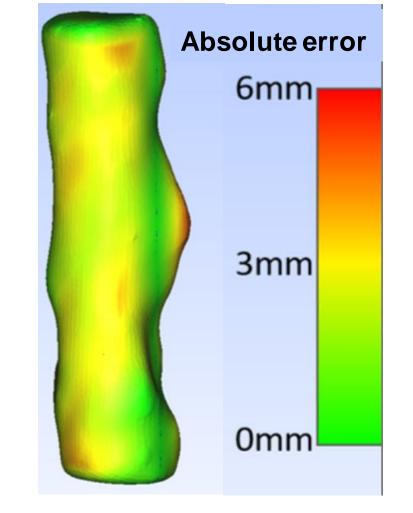


RESULTS

Testing: average Dice score 0.92







To validate the reconstruction pipeline, a straight vessel phantom was reconstructed using tracked US imaging and compared to a CT-derived vessel in terms of absolute distance error

CONCLUSIONS

Reconstruction accuracy deemed clinically acceptable for navigation.

Limitation: Limited size and scope of training data

Tracked ICE ultrasound can generate a vascular path for guidewire navigation

REFERENCES

- Ronneberger et al., U-Net: Convolutional Networks for Biomedical Image Segmentation,
- LNCS (2015) 2. Lasso et al., PLUS: Open-Source Toolkit for Ultrasound-Guided Intervention Systems,
- IEEE-TBME (2014) 3. Groves et al., Automatic segmentation of the carotid artery and internal jugular vein from 2D ultrasound images for 3D vascular reconstruction, IJCARS (2020)

