

# Artificial Intelligence

Deep Dive into Neural Networks









02 Use Case 1

Feedforward Neural Network

04 Multi-layer Perceptron

05 Use Case 2

06 Backpropagation Algorithm

07 Gradient Descent

08 Stochastic Gradient Descent

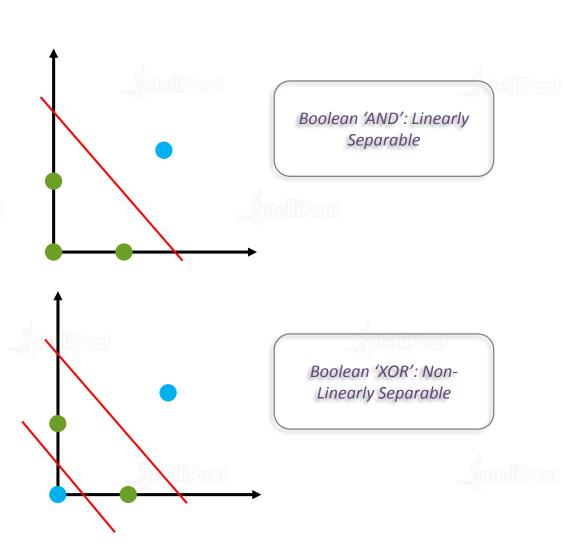
09 Adam Optimization Algorithm

10 Demo

# Limitations of a Single-layer Perceptron



- A single-layer perceptron can only learn linearly separable problems
- If the problem is not linearly separable, the learning process of a perceptron will never reach a point where all points are classified correctly
- Boolean 'AND' and 'OR' functions are linearly separable,
   whereas Boolean 'XOR' is not



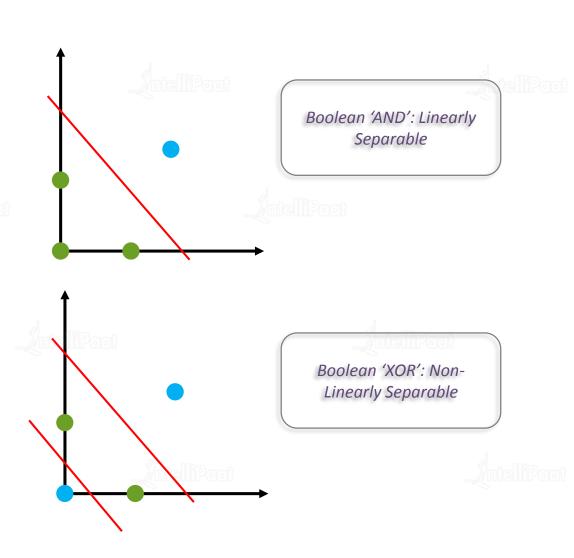
# Limitations of a Single-layer Perceptron



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For solving this problem, we can use a multi-layer perceptron



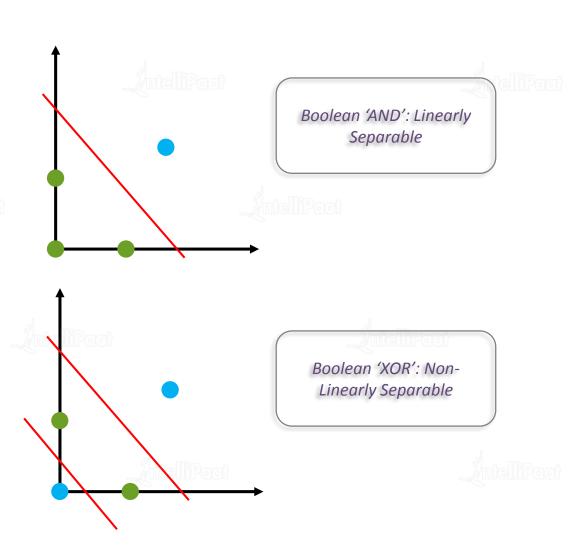
# Limitations of a Single-layer Perceptron





For solving this problem, we can use a multi-layer perceptron

- A single-layer perceptron won't be able to solve complex problems
   such as *Image Classification*
- In such kinds of problems, the dimensionality and complexity of the classification is very high





Let us see some real-life problems
which cannot be solved by singlelayer perceptron



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### **Use Case 1**



#### Complex problems that involve a lot of parameters cannot be solved by a single-layer perceptron

- Consider a case where you own an e-commerce firm. You have planned to increase traffic on your site by providing a special discount on the products and services. Now, you want to create awareness among people regarding this end-season sale by marketing on different portals like:
  - Google ads
  - Personal emails
  - Sales advertisements on relevant sites
  - YouTube ads
  - Ads on different sites
  - linkedin
  - Blogs and so on
- This task is too complex for a human to analyze, as you can see that the number of parameters is quite high
- Let us try to solve it using Deep Learning

### **Use Case 1**



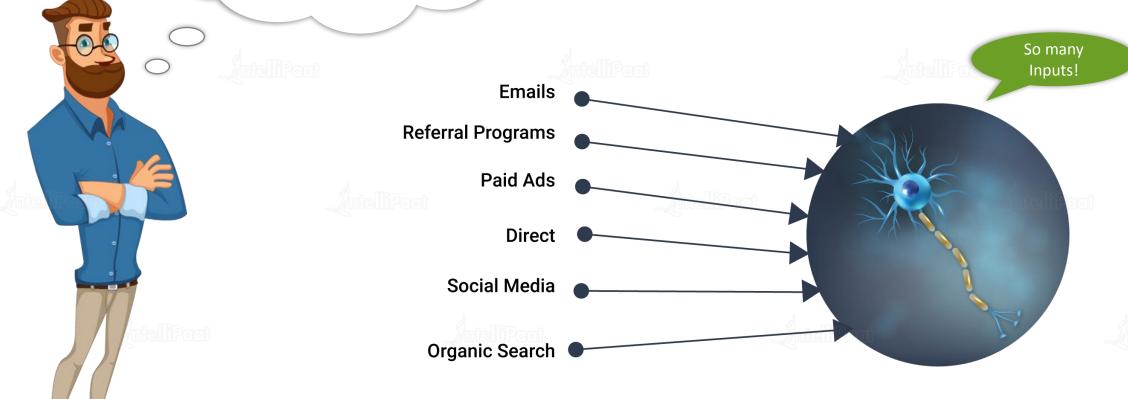


- You can either use just one platform for publicity or use a variety of them
- Each of them has its own advantages and disadvantages, but lots of factors would have to be considered
- The increased traffic on your portal or the number of sales that would happen is dependent on different categorical inputs, their sub-categories, and their parameters

Computing and calculating profit in terms of popularity and sales, from so many inputs and their sub-categories, is not possible just through one perceptron



So now, you know why a single perceptron cannot be used for complex non-linear problems





Before getting into the actual solution to our problem, let us recall one of the previously discussed topics: Feedforward Neural Network



### Feedforward Neural Network



Feedforward neural network is the most simple artificial neural network containing multiple nodes arranged in multiple layers.

Adjacent layer nodes have connections or edges where all connections are weighted

### В. **Feedforward Network** Neuron **X**<sub>1</sub> **Activation function** а У Local field Output $a = \sum w_{ij} X_j + b$ **Neurons Input Layer** Layer of of Source Nodes Hidden Neurons

### Feedforward Neural Network



Feedforward neural network is the most simple artificial neural network containing multiple nodes arranged in multiple layers.

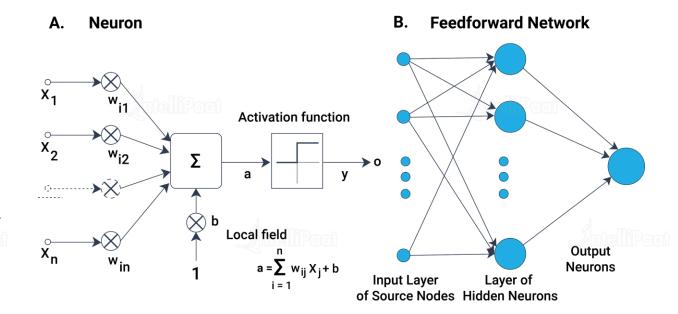
Adjacent layer nodes have connections or edges where all connections are weighted

"A feedforward neural network can contain two kinds of nodes"

Monolayer

Multi-layer Perceptron This is the simplest feedforward neural network that does not contain any hidden layers

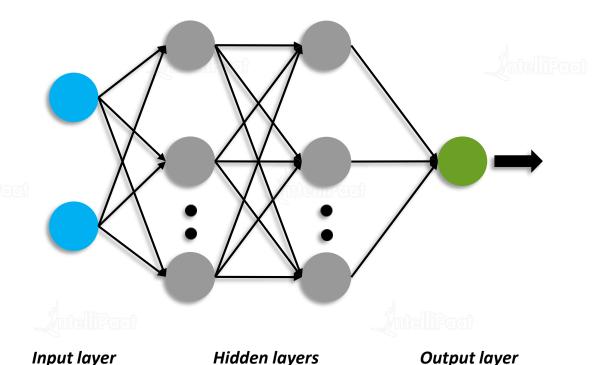
Multi-layer Perceptron (MLP) includes at least one hidden layer (except for one input layer and one output layer)







- A multi-layer perceptron (MLP) is a deep, artificial neural network
- It is composed of more than one perceptrons
- An MLP is comprised of:
  - An *input layer* to receive the signal
  - An output layer that makes a decision or prediction about the input
  - An arbitrary number of hidden layers
- Each node, apart from the input nodes, has a nonlinear activation function
- An MLP uses backpropagation as a supervised learning technique

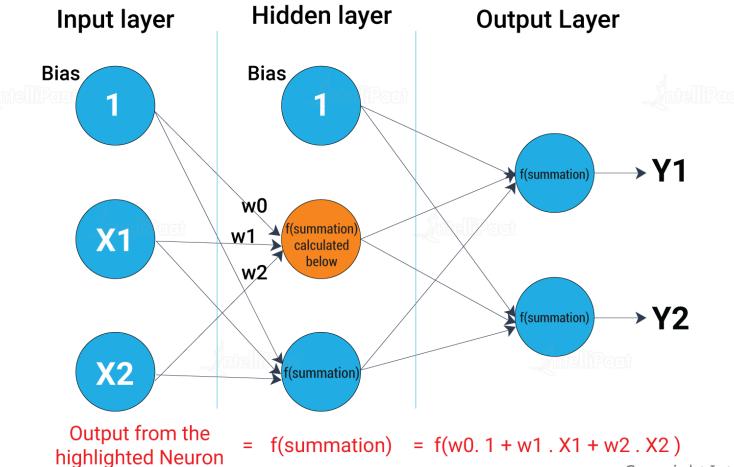


MLP is widely used for solving problems that require supervised learning and research into computational neuroscience and parallel distributed processing. Such applications include speech recognition, image recognition,

and machine translation



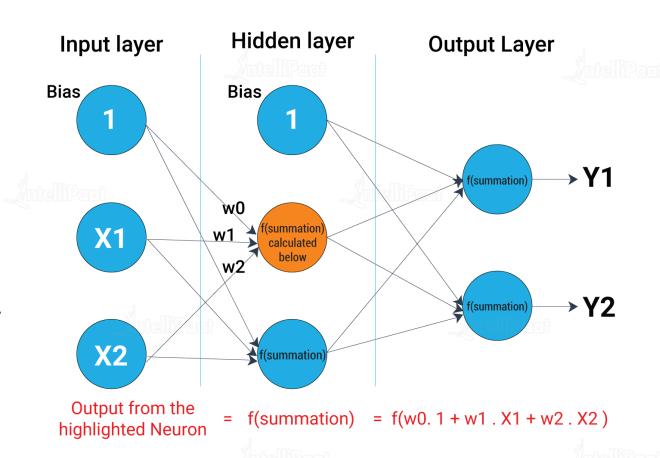
The figure shows a multi-layer perceptron with a single hidden layer. All connections have weights associated with them, but only three weights (w0, w1, and w2) are shown in the figure





#### **Input Layer:**

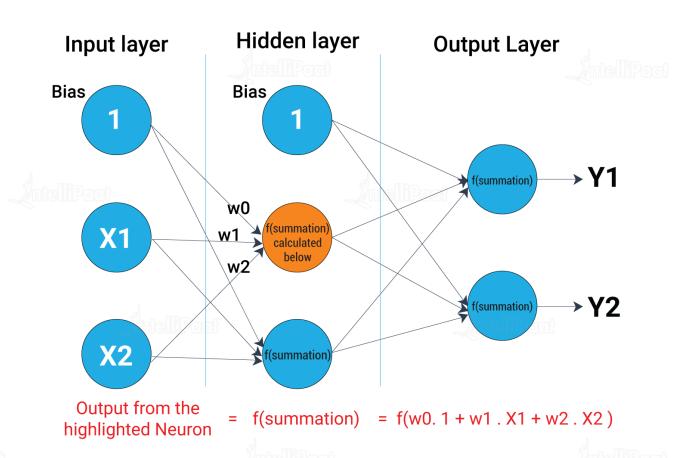
- It has three nodes
- Bias (offset) node has a value of 1
- The other two nodes take X1 and X2 as external inputs
- Outputs from nodes in the input layer are 1, X1, and X2, respectively, which are fed into the hidden layer





#### **Hidden Layer:**

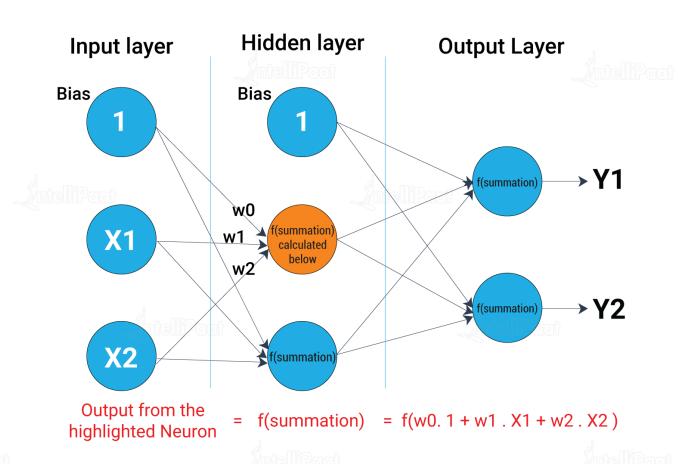
- It also has three nodes with the Bias node having an output of 1
- The output of the other two nodes in the hidden layer depends on the outputs from the input layer (1, X1, and X2) as well as the weights associated with the connections (edges)
- The figure shows the output calculation for one of the hidden nodes
- Similarly, the output from the other hidden node can be calculated
- Here, 'f' refers to the activation function. These outputs are then fed to the nodes in the output layer





#### **Output Layer:**

- The output layer has two nodes which take inputs from the hidden layer and perform similar computations as shown for the highlighted hidden node
- Values calculated (Y1 and Y2) as a result of these computations act as outputs of the multi-layer
   perceptron

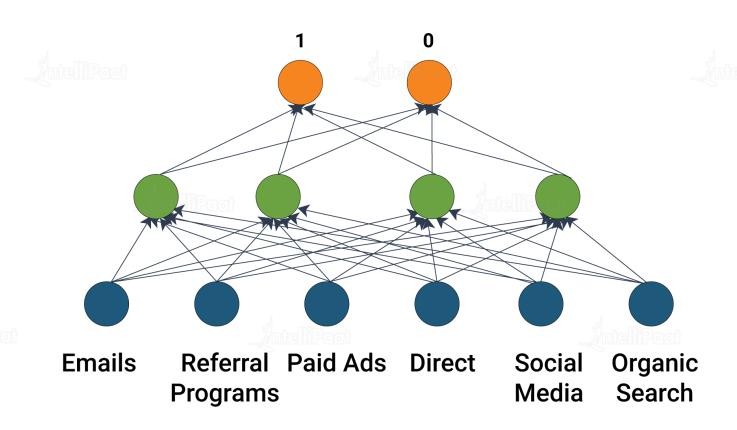




# **Use Case 1: Solution**



- Every source behaves as an input to the neural network
- Once all sources are fed into the system, the neural network calculates the output after the computation is done





### Use Case 2



Suppose, we have the following student-marks dataset

	Hours Studied	Mid-term Marks	Final Results
î	35	67	1
	12	75	0
	16	89	1
	45	56	
	10	90	0

- The two input columns show the number of hours each student has studied and the mid-term marks obtained by the student, respectively
- The Final Results column can have two values 1 or 0 indicating whether the student passed (1) in the final term or failed (0)



Now, suppose, we want to predict whether a student studying 25 hours and having 70 marks in the mid term will pass the final term



### Use Case 2



Hours Studied	Mid-term Marks	Final Results
25	70	Ş

This is a binary classification problem where a multi-layer perceptron can learn from the given examples (the training data) and make an informed prediction when given a new data point. We will see now, how a multi-layer perceptron learns such relationships



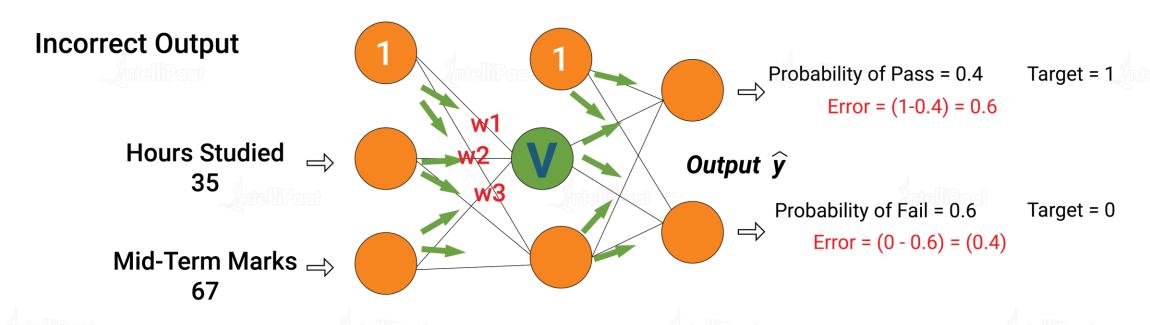
The process by which a multi-layer perceptron learns is called the *Backpropagation algorithm*.

We will discuss this in details after completing MLP!



# Use Case 2: Solution





- The figure has two nodes in the input layer (apart from the Bias node) which take the inputs *Hours Studied* and *Mid-term Marks*
- It also has a hidden layer with two nodes (apart from the Bias node)
- The output layer has two nodes as well: the upper node outputs the probability of 'Pass' while the lower node outputs the probability of 'Fail'



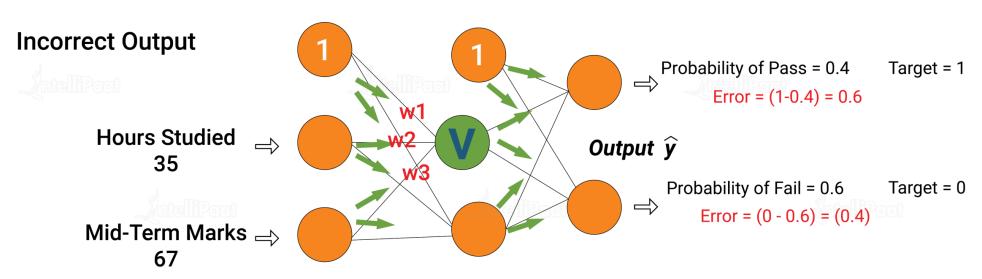
In classification, we generally use a Softmax function as the activation function to ensure that the outputs are probabilities and they add up to 1. So, in this case,

Probability (Pass) + Probability (Fail) = 1



# Use Case 2: Solution





#### Step 1: Forward Propagation

- Let's consider the hidden layer node, marked V, in the figure
- Assume that the weights of the connections from the inputs to that node are w1, w2, and w3 (as shown)
- The first training example as input:
  - Input to the network = [35, 67]
  - Desired output from the network (target) = [1, 0]
  - The output V from the node can be calculated as follows (where 'f' is an activation function): V = f (1\*w1 + 35\*w2 + 67\*w3)



Suppose, the output probabilities from the two nodes in the output layer are 0.4 and 0.6, respectively (since the weights are randomly assigned, outputs will also be random)



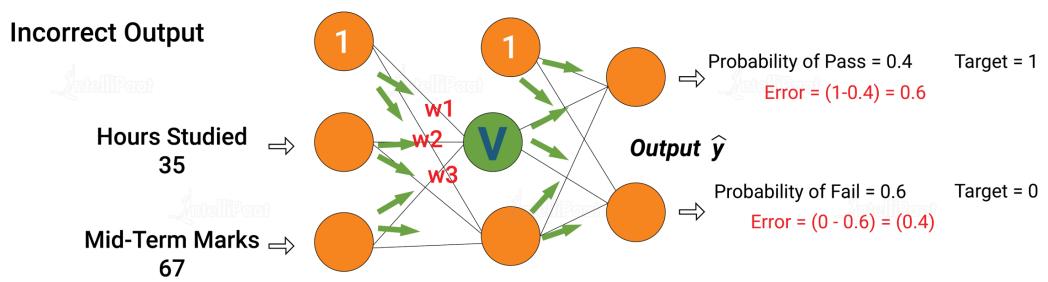


We can see that the calculated probabilities (0.4 and 0.6) are very far from the desired probabilities (1 and 0, respectively); hence, the network in the figure is said to have an 'Incorrect Output'



# Use Case 2: Solution





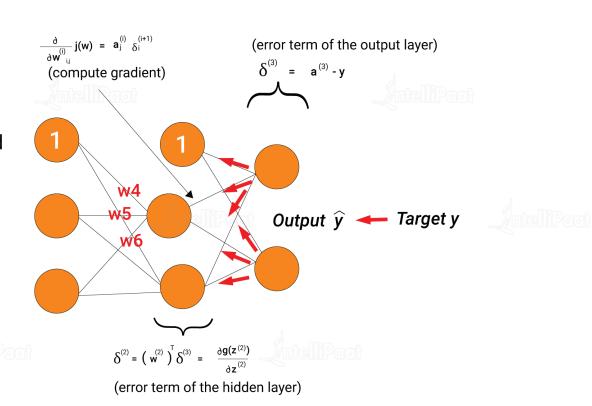
#### Step 2: Backpropagation and Weight Updates

- We calculate the total errors at the output nodes and propagate these errors back through the network using backpropagation to calculate the gradients
- Then, we use an optimization method such as gradient descent to 'adjust' all weights in the network with an aim of reducing errors at the output layer
- This is shown in the next figure

# Use Case 2: Solution



Backpropagation + Weights Adjusted



- Step 2: Backpropagation and Weight Updates
  - Suppose that the new weights associated with the node in consideration are w4, w5, and w6 (after backpropagation and adjusting weights)

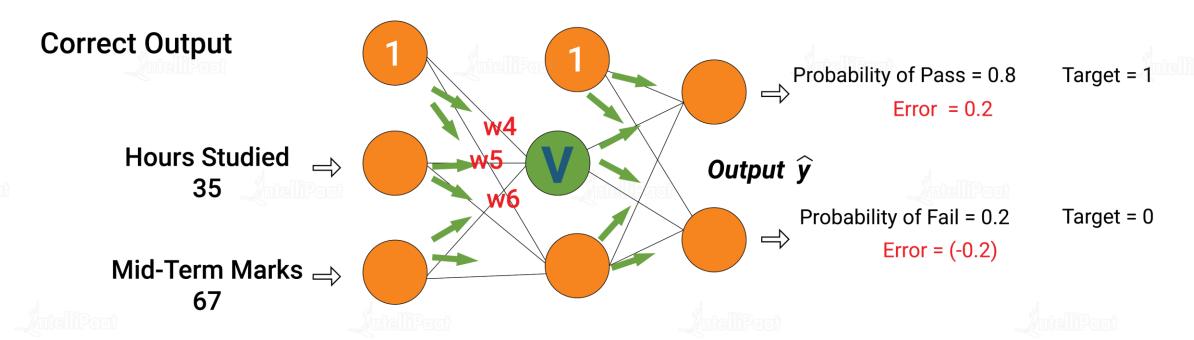


If we now input the same example to the network again, the network should perform better than before since the weights have now been adjusted to minimize errors in prediction



# Use Case 2: Solution





- As shown in Figure, errors at the output nodes have now reduced to [0.2, -0.2] as compared to [0.6, -0.4] earlier
- This means that our network has learned to correctly classify our first training example
- We repeat this process with all other training examples in our dataset. Then, our network will learn those examples as well



If we now want to predict whether a student studying 25 hours and having 70 marks in the mid term will pass the final term, we go through the forward propagation step and find the output probabilities for Pass and Fail





So now, let us understand backpropagation in detail as you have already heard a lot about it!

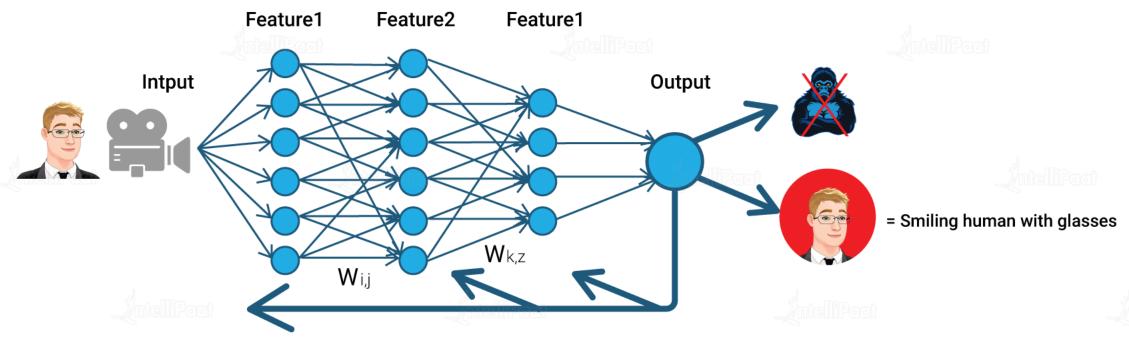


# **Backpropagation Algorithm**



The backpropagation algorithm is a supervised learning method for multi-layer feedforward networks from the field of Artificial

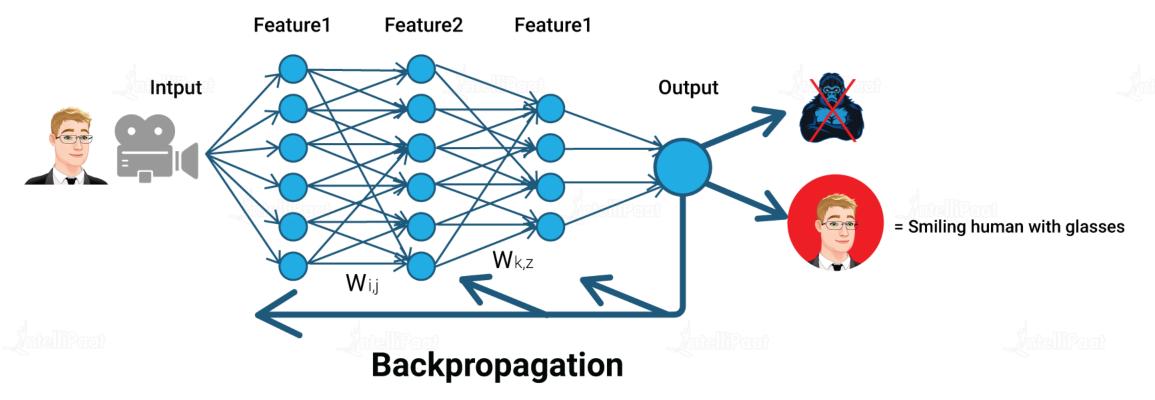
Neural Networks



**Backpropagation** 

# **Backpropagation Algorithm**





- The principle of this approach is to model a given function by modifying internal weightings of input signals to produce an expected output signal
- The system is trained using a supervised learning method, where the error between the system's output and a known expected output is presented to the system and used to modify its internal state



Let us understand its working with the help of an example!





Consider the following table

Input	Desired Output
0	0
1	2
AllPool 2	4



Consider the initial value of weight as 3

Input	Desired Output	Model Output (W=3)
0	0	0
1	2	3
2	4	6



Observe the difference between the actual output and the desired output

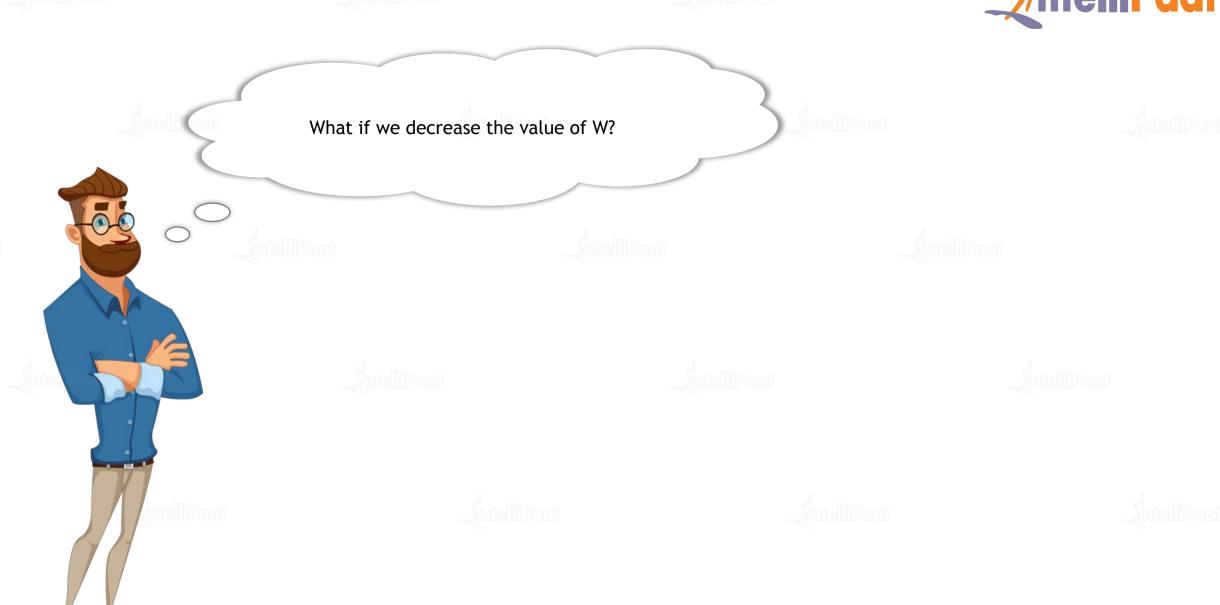
Input	Desired Output	Model Output (W=3)	Absolute Error	Square Error
0	0	0	0	0
1 -	2	3		1
2	4	6	2	4



Observe the error when changing the value of W to 4

Input	Desired Output	Model Output (W=3)	Absolute Error	Square Error	Model Output (W=4)	Square Error
0	0	0	0	0	0	0
1	2	3	1	1	4	4
2	4	6	2	4	8	16







Consider the value of weight as 2

Input	Desired Output	Model Output (W=3)	Absolute Error	Square Error	Model Output (W=2)	Square Error
0	0	0	0	0	0	0
1	2	3	1	1	3	Amtelli Loot
2	4	6	2	4	4	0



Consider the value of weight as 2

Input	Desired Output	Model Output (W=3)	Absolute Error	Square Error	Model Output (W=2)	Square Error
0	0	0	0	0	0	0
1	2	3	1		3	
2	4	6	2	4	4	0

We see that when the weight is reduced, the error also decreases



Consider the following graph

### **Backpropagation**



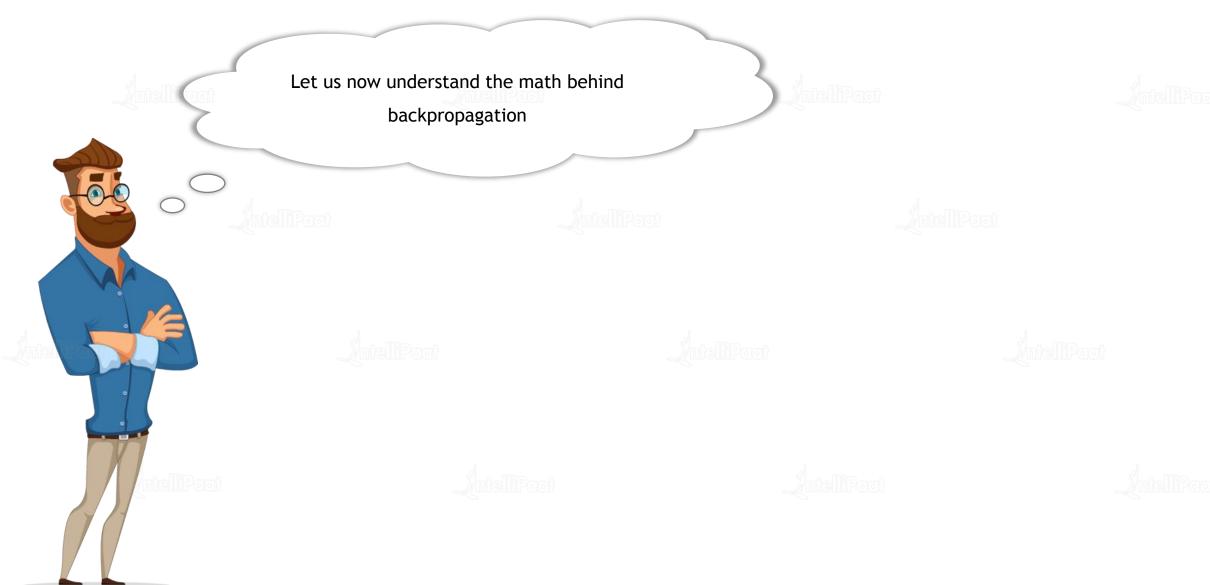


We need to reach the *Global Loss Minimum*. This is nothing but backpropagation

### **Backpropagation**

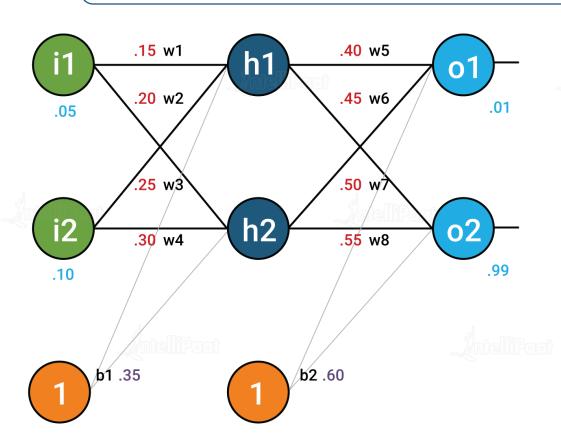






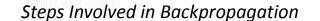


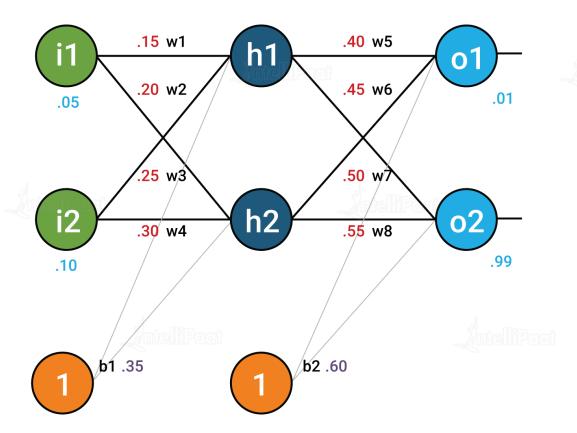
In order to have some numbers to work with, here are initial weights, biases, and training inputs/outputs



- The goal of backpropagation is to optimize the
   weights so that the neural network can learn how to
   correctly map arbitrary inputs to outputs
- We're going to work with a single training set: given inputs 0.05 and 0.10, we want the neural network to output 0.01 and 0.99







**Step 1: The Forward Pass** 

**Step 2: The Backward Pass** 



**Step 1: The Forward Pass** 

#### *The total net input for h1:*

net  $h1 = w_1 * i_1 + w_2 * i_2 + b_1 * 1$ net h1 = 0.15 \* 0.05 + 0.2 \* 0.1 + 0.35 \* 1 = 0.3775

#### *The output for h1:*

out  $h1 = 1/(1 + e^{-net h1}) = 1/(1 + e^{-0.3775}) = 0.593269992$ 

#### Carrying out the same process for h2:

out h2 = 0.596884378

\*\*We repeat this process for the output layer neurons, using the output from the hidden layer neurons as their input \*\*



**Step 1: The Forward Pass** 

#### The output for o1:

```
net o1 = w_5 * out h1 + w_6 * out h2 + b_2 * 1 net o1 = 0.4 * 0.593269992 + 0.45 * 0.596884378 + 0.6 * 1 = 1.105905967 out o1 = 1/(1 + e^{-net o1}) = 1/(1 + e^{-1.105905967}) = 0.75136507
```

#### Carrying out the same process for o2:

out o2 = 0.772928465



**Calculating the Total Error** 

We can now calculate the error for each output neuron using the squared error function and sum them to

get the total error: E total =  $\Sigma 1/2$  (target - output)<sup>2</sup>

The target output for o1 is 0.01, but the neural network output is 0.75136507; therefore, its error is:

E o1 = 1/2 (target o1 - out o1)<sup>2</sup> = 1/2 (0.01 - 0.75136507)<sup>2</sup> = 0.274811083

By repeating this process for o2 (remembering that the target is 0.99), we get:

 $E \circ 2 = 0.023560026$ 

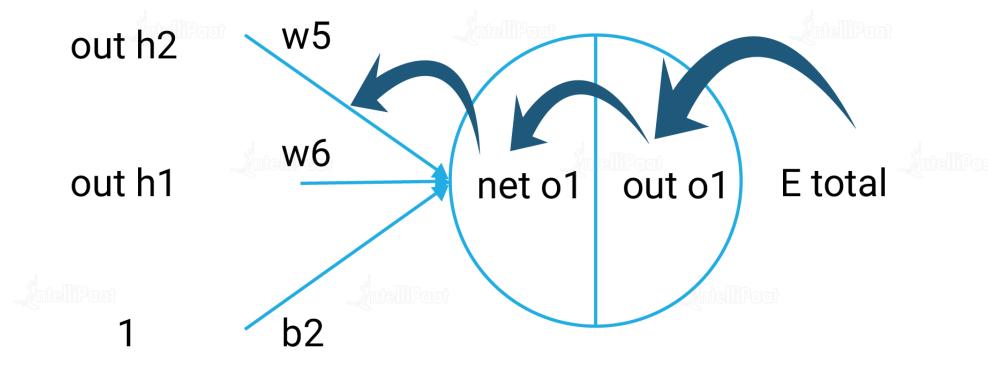
*The total error for the neural network is the sum of these errors:* 

E total = E o1 + E o2 = 0.274811083 + 0.023560026 = 0.298371109



**Step 2: The Backward Pass** 

Our goal with backpropagation is to update each of the weights in the network so that the actual output is closer to the target output, thereby minimizing the error for each output neuron and the network as a whole





**Step 2: The Backward Pass** 

Our goal with backpropagation is to update each of the weights in the network so that the actual output is closer to the target output, thereby minimizing the error for each output neuron and the network as a whole

```
Consider w5, we will calculate the rate of change of error w.r.t the change in weight w5: (\partial E \ total)/\partial w_5 = (\partial E \ total)/(\partial \text{out ol}) * (\partial \text{out ol})/(\partial \text{net ol}) * (\partial \text{net ol})/\partial w_5 Since we are propagating backwards, the first thing we need to do is to calculate the change in total errors w.r.t. the outputs o1 and o2: E \ \text{total} = (1/2) * (\text{target ol} - \text{out ol})^2 + (1/2) * (\text{target o2} - \text{out o2})^2 \\ (\partial E \ total)/(\partial \text{out ol}) = -(\text{target ol} - \text{out ol}) = -(0.01 - 0.75136507) = 0.74136507 Now, we will propagate further backward and calculate the change in the output o1 w.r.t to its total net input: out o1 = 1/(1 + e^{-\text{net ol}}) (\partial \text{out ol})/(\partial \text{net ol}) = out o1(1-out o1) = 0.75136507(1 - 0.75136507) = 0.186815602 How much does the total net input of o1 change w.r.t. w5? net o1 = w_5*out h1 + w_6*out h2 +b2*1 (\partial \text{net ol})/ \partial w_5 = 1*out h1*w_5(1-1) +0+0 = out h1 = 0.593269992
```



**Step 2: The Backward Pass** 

Putting all values together and calculating the updated weight value

#### *let's put all values together:*

 $(\partial E \ total)/\partial w_5 = (\partial E \ total)/(\partial out \ o1) * (\partial out \ o1)/(\partial net \ o1) * (\partial net \ o1)/\partial w_5 = 0.082167041$ 

#### *Calculate the updated value of w5:*

 $W_5^+ = W_5 - n*(\partial E total)/\partial w_5 = 0.4 - 0.5 * 0.082167041 = 0.35891648$ 

#### We can repeat this process to get the new weights w6, w7, and w8

 $W_6^+ = 0.408666186$ 

 $W_7^+ = 0.511301270$ 

 $W_8^+ = 0.561370121$ 

We perform the actual updates in the neural network after we have the new weights leading into the hidden layer neurons



Step 2: The Backward Pass
Hidden Layer

We'll continue the backward pass by calculating new values for w<sub>1</sub>, w<sub>2</sub>, w<sub>3</sub>, and w<sub>4</sub>

#### Start with w<sub>1</sub>:

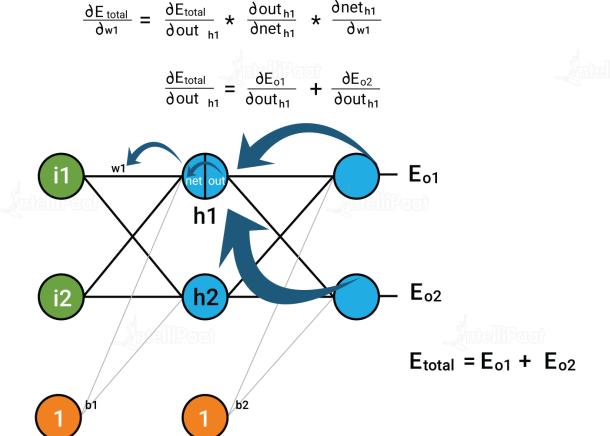
```
(\partial E \ total)/\partial w_1 = (\partial E \ total)/(\partial out \ h1) * (\partial out \ h1)/(\partial net \ h1) * (\partial net \ h1)/\partial w_1
(\partial E \ total)/(\partial out \ h1) = (\partial E \ o1)/(\partial out \ h1) + (\partial E \ o2)/(\partial out \ h1)
```

We're going to use a similar process as we did for the output layer, but slightly different to account for the fact that the output of each hidden layer neuron contributes to the output. Thus, we need to take E o1 and E o2 into consideration



Step 2: The Backward Pass Hidden Layer

We can visualize it as:





Step 2: The Backward Pass Hidden Layer

```
Starting with:

(∂E total) / (∂out h1) = (∂E o1) / (∂out h1) + (∂E o2) / (∂out h1)

(∂E o1) / (∂out h1) = (∂E o1) / (∂net o1) * (∂net o1) / (∂out h1)

We can calculate (∂E o1) / (∂net o1) using values calculated earlier:

(∂E o1) / (∂net o1) = (∂E o1) / (∂out h1) * (∂out h1) / (∂net o1) = 0.74136507 * 0.186815602 = 0.138498562

net o1 = w<sub>5</sub>*out h1 + w<sub>6</sub>*out h2 + b<sub>2</sub>*1 (∂net o1) / (∂out h1) = w<sub>5</sub> = 0.40
```



Step 2: The Backward Pass Hidden Layer

#### Put the values in the equation:

```
(\partial E o1)/(\partial out h1) = (\partial E o1)/(\partial net o1) * (\partial net o1)/(\partial out h1)
= 0.138498562 * 0.40 = 0.055399425
```

Following the same process for  $(\partial E \circ 2) / (\partial \text{out h1})$ , we get:

```
(\partial E \circ 2) / (\partial out h1) = -0.019049119
```



Step 2: The Backward Pass Hidden Layer

#### We can calculate:

```
(\partial E \text{ total}) / (\partial \text{out h1}) = (\partial E \text{ o1}) / (\partial \text{out h1}) + (\partial E \text{ o2}) / (\partial \text{out h1})
= 0.055399425 + (-0.019049119) = 0.036350306
```

Now that we have  $(\partial E \text{ total})/(\partial \text{out h1})$ , we need to figure out  $(\partial \text{out h1})/(\partial \text{net h1})$  and  $(\partial \text{net h1})/(\partial \text{net h1})$  out  $(\partial \text{net h1})/(\partial \text{net h1})$ 

```
(\partial \text{out h1})/(\partial \text{net h1}) = \text{out h1}(1-\text{out h1}) = 0.59326999(1-0.59326999) = 0.241300709
```

We calculate the partial derivative of the total net input to h1 with respect to  $w_1$  the same as we did for the output neuron:

```
net h1 = w_1 * i_1 + w_3 * i_2 + b_1 * 1
(\partial \text{net h1}) /\partial w_1 = i_1 = 0.05
```



Step 2: The Backward Pass Hidden Layer

#### Put it all together:

```
(\partial E \ total)/\partial w_1 = (\partial E \ total)/(\partial out \ h1) * (\partial out \ h1)/(\partial net \ h1) * (\partial net \ h1)/\partial w_1
(\partial E \ total)/\partial w_1 = 0.036350306 * 0.241300709 * 0.05 = 0.000438568
```

#### We can now update $w_1$ :

```
w_1^+ = w_1 - n^* (\partial E total)/\partial w_1 = 0.15 - 0.5 * 0.000438568 = 0.149780716
```

#### Update other weights similarly:

```
w_2^+ = 0.19956143

w_3^+ = 0.24975114

w_4^+ = 0.29950229
```

- When we fed forward 0.05 and 0.1 inputs originally, the error on the network was 0.298371109
- After this first round of backpropagation, the total error is now down to 0.291027924



It might not seem like much, but after repeating this process 10,000 times, for example, the error plummets to 0.0000351085. At this point, when we feed forward 0.05 and 0.1, the two output neurons generate 0.015912196 (vs. 0.01 target) and 0.984065734 (vs. 0.99 target)





Optimization is a big part of Machine Learning.

Almost every Machine Learning algorithm has
an optimization algorithm at its core





- Gradient descent is by far the most popular optimization strategy, used in Machine Learning and Deep Learning at the moment
- It is used while training your model, can be combined with every algorithm, and is easy to understand and implement

Gradient measures how much the output of a function changes if you change the inputs a little bit

• You can also think of a gradient as the slope of a function. The higher the gradient, the steeper the slope and the faster the model learns



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**How Does it Work?** 



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Gradient measures how much the output of a function changes if you change the inputs a little bit

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**How Does it Work?** 

$$b = a - \gamma \nabla f(a)$$

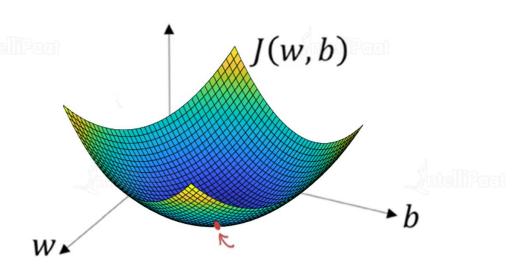
- b = next value
- a = current value
- '-' refers to the minimization part of the gradient descent
- $\gamma$  in the middle is the learning rate, and the gradient term  $\nabla f(a)$  is simply the direction of the steepest descent

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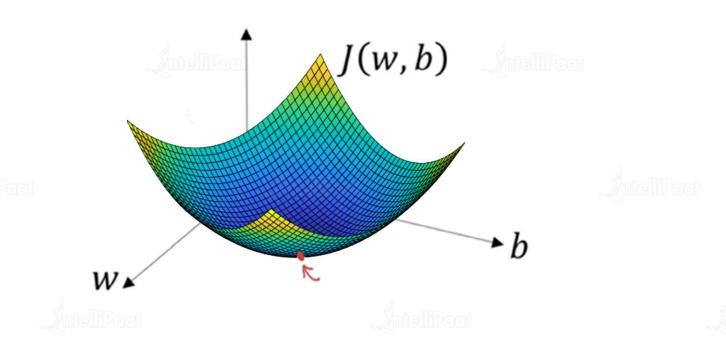


$$b = a - \gamma \nabla f(a)$$

- This formula basically tells you the next position where you need to go, which is the direction of the steepest descent
- Gradient descent can be thought of climbing down to the bottom of a valley, instead of climbing up a hill. This is because it is a *minimization algorithm* that minimizes a given function
- Consider the graph below where we need to find the *values of w and b* that correspond to the *minimum of the cost function* (marked with the red arrow)





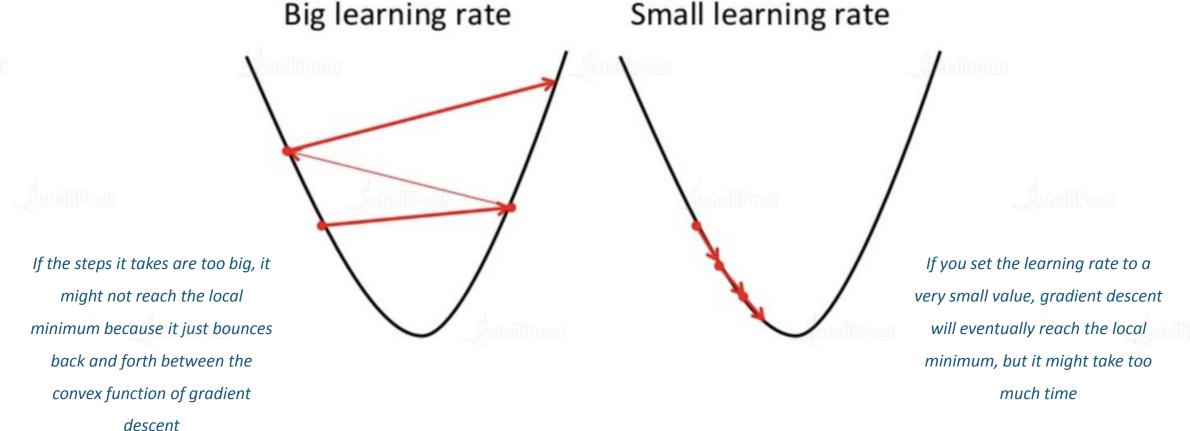


- To start with finding the right values, we initialize the values of w and b with some random numbers, and gradient descent then starts at that point (somewhere around the top)
- Then, it takes one step after the other in the steepest downside direction (e.g., from top to bottom) till it reaches the point where the cost function is as small as possible

## Importance of the Learning Rate



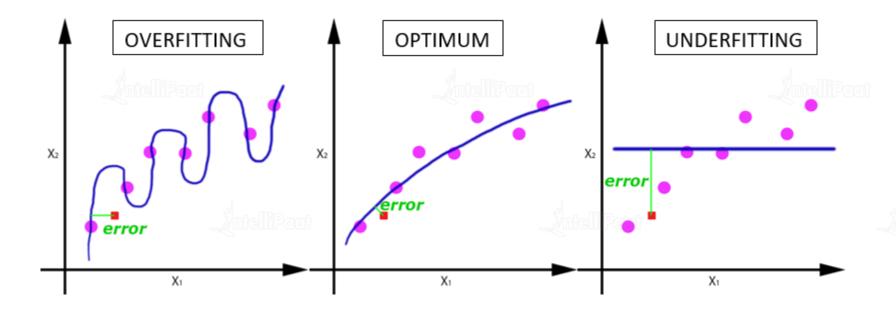
- Learning rate determines how fast or slow we will move toward the optimal weights
- In order for gradient descent to reach the local minimum, we have to set the learning rate to an appropriate value, which is neither too low nor too high



# **Understanding Epoch**



- One epoch is when an ENTIRE dataset is passed forward and backward through the neural network only ONCE
- One epoch leads to underfitting of the curve in the graph



As the number of epochs increases, more number of times the weights are changed in the neural network and the curve goes
 from underfitting to optimal to overfitting

#### **Batches and Iterations**



#### Batch Size

- Total number of training examples present in a single batch is referred to as the batch size
- Since we can't pass the entire dataset into the neural net at once, we divide the dataset into number of batches or sets or parts

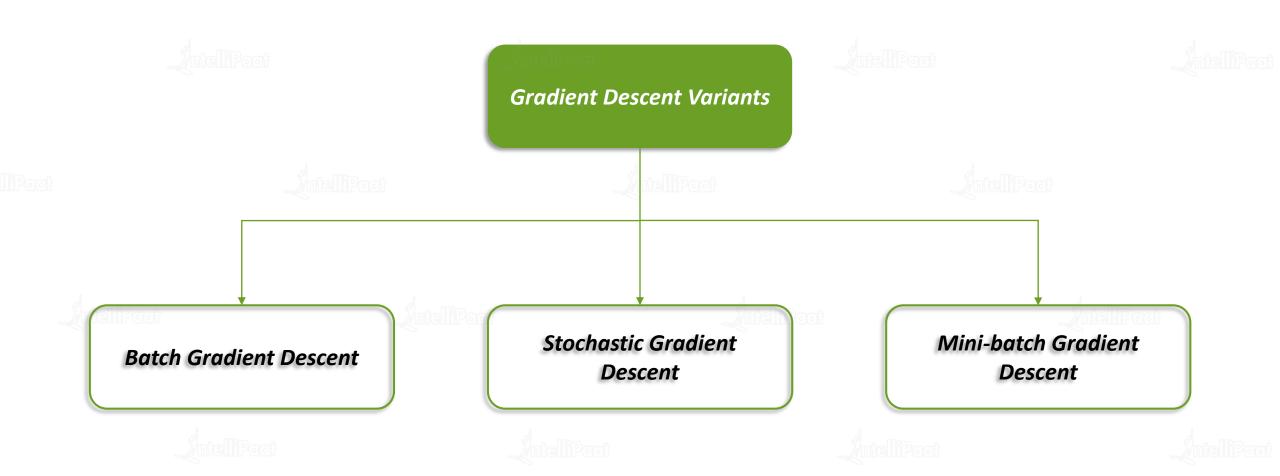
#### **Iterations**

Iteration is the number of batches needed to complete one epoch

Let's say, we have 2,000 training examples that we are going to use. We can divide the dataset of 2,000 examples into batches of 500, and then it will take four iterations to complete one epoch

#### **Gradient Descent Variants**





#### **Gradient Descent Variants**



Assume you have a dataset of 6 images











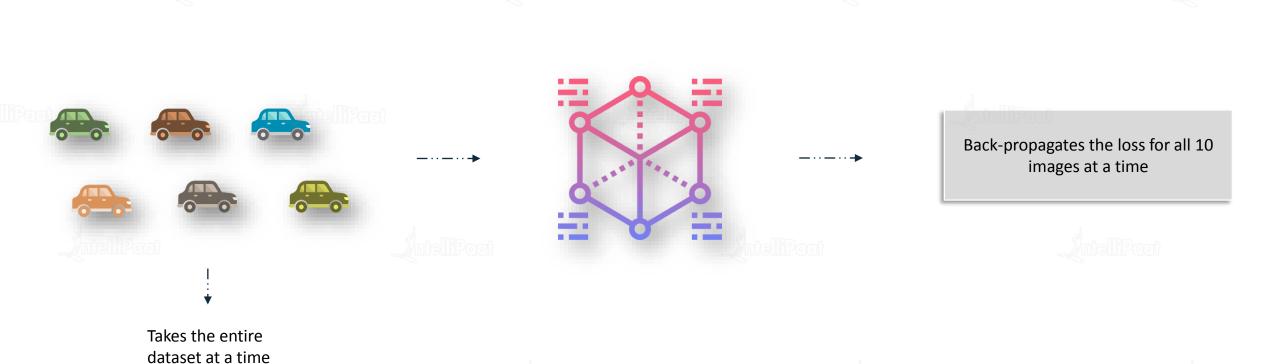






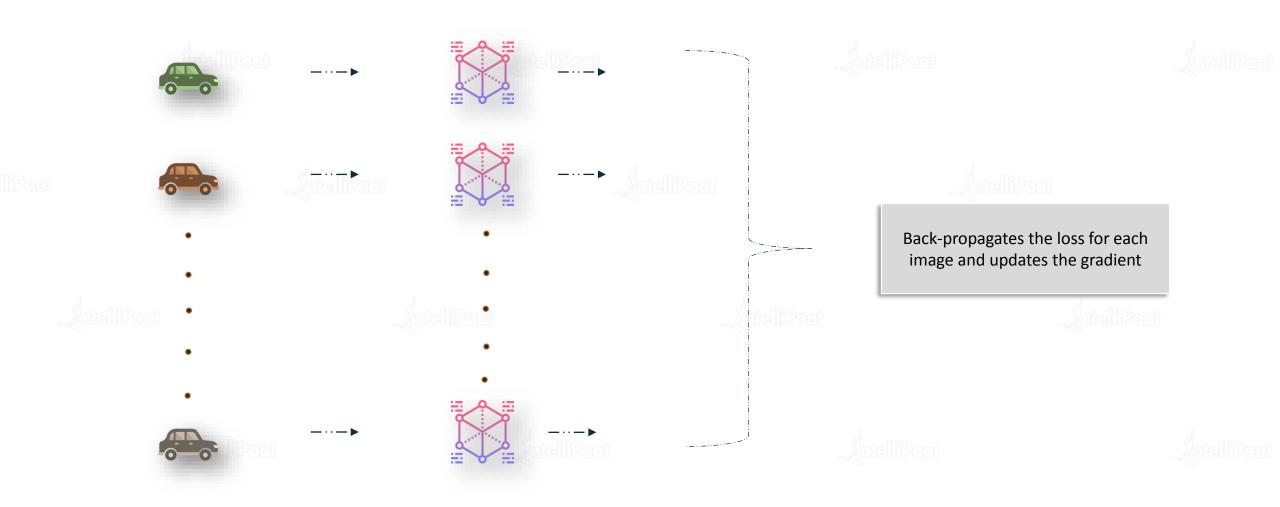
#### **Batch Gradient Descent**





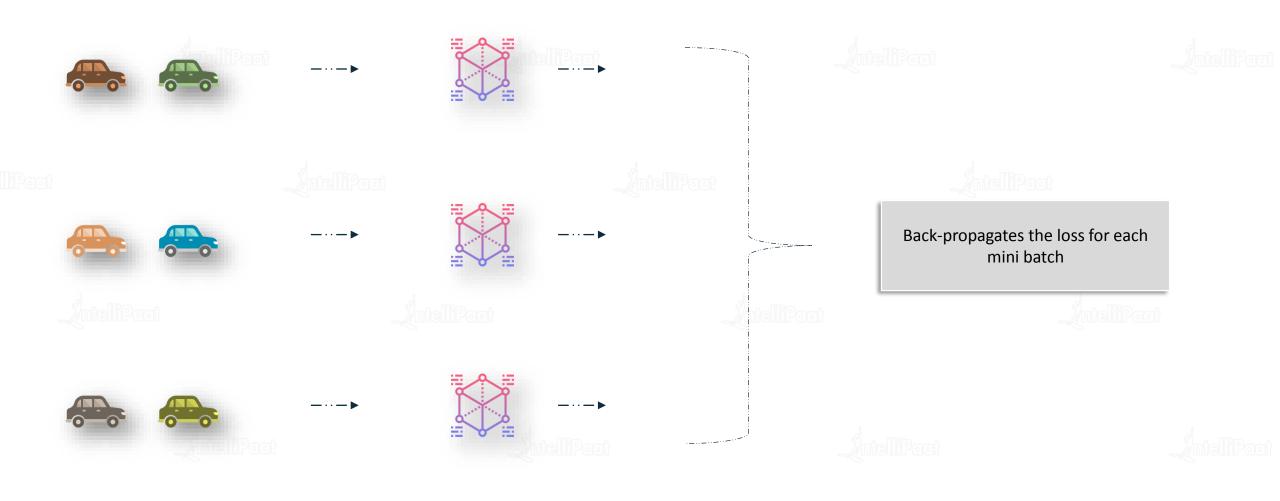
#### **Stochastic Gradient Descent**





#### Mini-Batch Gradient Descent





## Tips for Gradient Descent

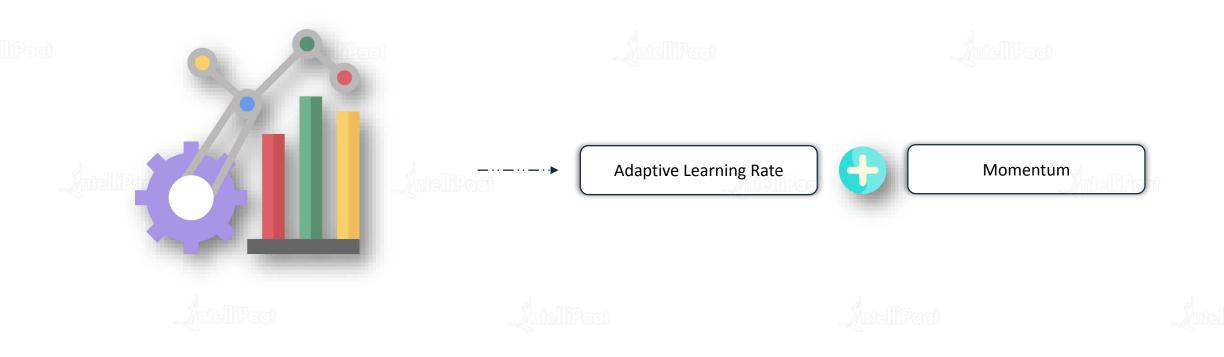


- **Plot Cost versus Time:** Collect and plot the cost values calculated by the algorithm for each iteration. The expectation for a well-performing gradient descent run is a decrease in cost at every iteration. If it does not decrease, try reducing your learning rate
- Learning Rate: The learning rate value is a small real value such as 0.1, 0.001, or 0.0001. Try different values for your problem and see which works best
- Rescale Inputs: The algorithm will reach the minimum cost faster if the shape of the cost function is not skewed and distorted. You can achieve this by rescaling all of the input variables (X) to the same range, such as [0, 1] or [-1, 1]

## **Adam Optimization Algorithm**



- The Adaptive Moment Estimation or Adam optimization algorithm is a combination of gradient descent with momentum and RMSprop algorithms
- Adam is an adaptive learning rate method, which means that it computes individual learning rates for different parameters





## Implementing a Simple Neural Network

## Implementing a Simple Neural Network





*Initializing the values of x1, x2, and y:* 

In [8]: x1=2 x2=5 y=31

## Implementing a Simple Neural Network



#### Implementing forward propagation and backpropagation:

```
Value of w1 - 8.12 Value of w2 - 4.8 Error is -
Value of w1 - 7.75039999999999 Value of w2 - 3.87600000000000 Error is - 85.3775999999999
Value of w1 - 7.595167999999999 Value of w2 - 3.4879200000000004 Error is -
Value of w1 - 7.529970559999999 Value of w2 - 3.3249264000000003 Error is - 2.656691364096002
Value of w1 - 7.484227712716696 Value of w2 - 3.210569281791744 Error is - 0.002572381794042668
Value of w1 - 7.483375639341012 Value of w2 - 3.208439098352533 Error is - 0.0004537681484689692
Value of w1 - 7.483017768523224 Value of w2 - 3.2075444213080644 Error is - 8.00447013899338e-05
Value of w1 - 7.482867462779753 Value of w2 - 3.2071686569493876 Error is - 1.4119885325192866e-05
Value of w1 - 7.482777820434347 Value of w2 - 3.2069445510858725 Error is - 4.3936790686730787e-07
Value of w1 - 7.482766684582424 Value of w2 - 3.2069167114560666 Error is - 7.750449877198654e-08
Value of w1 - 7.4827620075246175 Value of w2 - 3.2069050188115487 Error is
Value of w1 - 7.482760043160338 Value of w2 - 3.206900107900851 Error is - 2.411704387857833e-09
Value of w1 - 7.482759218127341 Value of w2 - 3.2068980453183578 Error is - 4.254246540708817e-10
Value of w1 - 7.482758871613482 Value of w2 - 3.206897179033711 Error is - 7.504490893870946e-11
Value of w1 - 7.48275862849764 Value of w2 - 3.2068965712441053 Error is - 7.266337750799056e-14
Value of w1 - 7.482758623969008 Value of w2 - 3.2068965599225243 Error is - 1.2817819245385772e-14
Value of w1 - 7.482758622066982 Value of w2 - 3.206896555167461 Error is - 2.261062929716986e-15
Value of w1 - 7.482758621268132 Value of w2 - 3.206896553170334 Error is - 3.988515178306028e-16
```

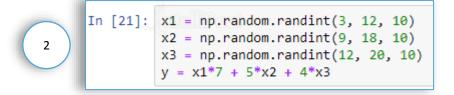




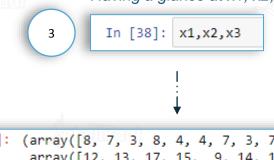
#### Loading the NumPy package:



#### Setting initial values for x1, x2, x3, and y:



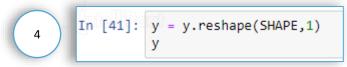
#### Having a glance at x1, x2, x3, and y:



Out[40]: (array([8, 7, 3, 8, 4, 4, 7, 3, 7, 7]), array([12, 13, 17, 15, 9, 14, 12, 15, 15, 10]), array([13, 12, 19, 12, 15, 19, 16, 15, 18, 13]))



#### Reshaping 'y':



Creating a NumPy array from 'x1', 'x2', and 'x3':

```
5 In [32]: X = np.array([x1, x2, x3])
```

#### Transposing 'X':

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Setting the learning rate value and initializing random values:

Implementing forward propagation and backpropagation:

8

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## Quiz 1



Single Layer Perceptron is easy to use than Multi Layer Perceptron

**A** True

**B** False

#### **Answer 1**



Single Layer Perceptron is easy to use than Multi Layer Perceptron

**A** True

**B** False



#### The variants of Gradient Descent are...

A Batch Gradient Descent

B Adams Optimizer

C Ada-Delta Optimizer

**D** All of these

#### Answer 2



The variants of Gradient Descent are...

A Batch Gradient Descent

B Adams Optimizer

**C** Ada-Delta Optimizer

**D** All of these

## Quiz 3



The backpropagation algorithm is a supervised learning method for multi-layer feedforward networks

**Y**es

B No

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#### Answer 3



The backpropagation algorithm is a supervised learning method for multi-layer feedforward networks

A Yes

B No

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Thank you!

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