

DLCV04

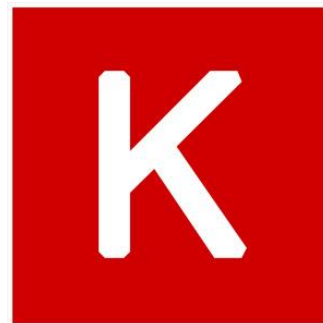


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[Visit our GitHub page here](#)

Task 1: + Resources

- Software used:
 - Keras with GPU accelerated Tensor Flow as backend, using python 2.7.
- Hardware used:
 - PC with GPU (NVIDIA 970)

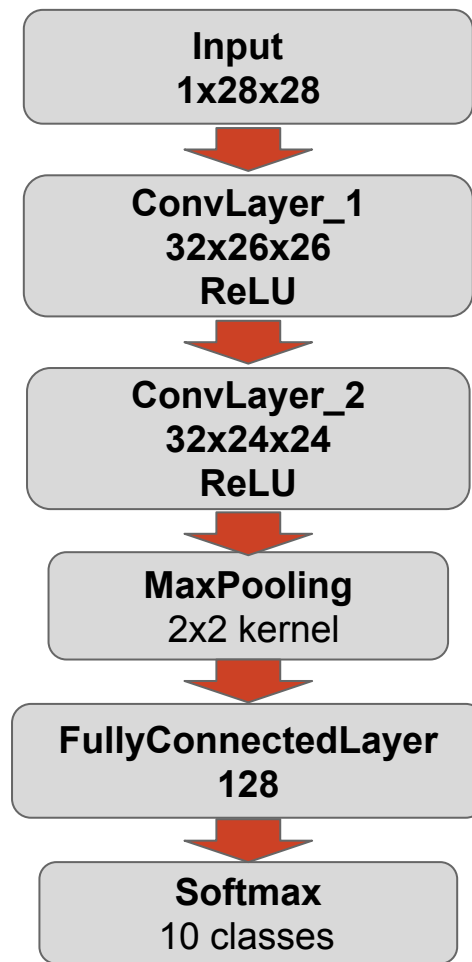


Task 1: Architecture

For the first task, we modified a convent designed for the MNIST dataset.

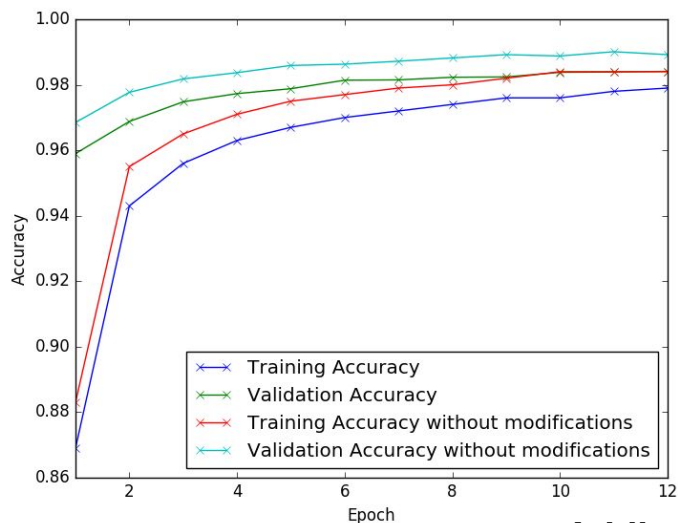


epoch time 18s parameters:600810



Task 1: Architecture

Removing one Conv layer

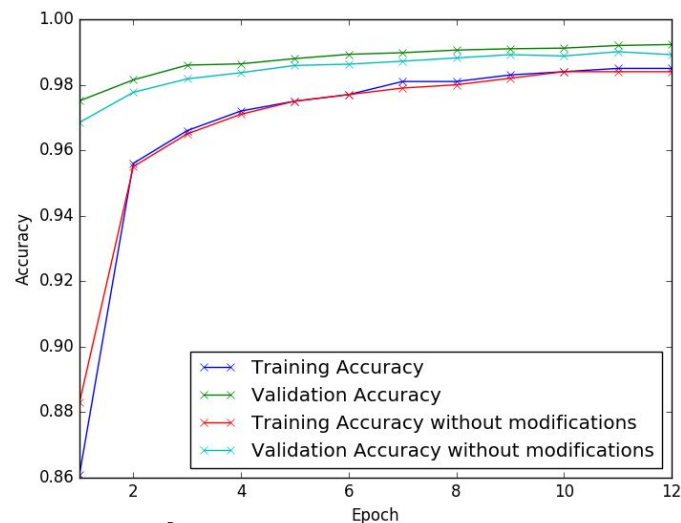


Epoch time: 11s

Total parameters: 693962

**Adding new Conv layers results
expensive in terms of total run
time!**

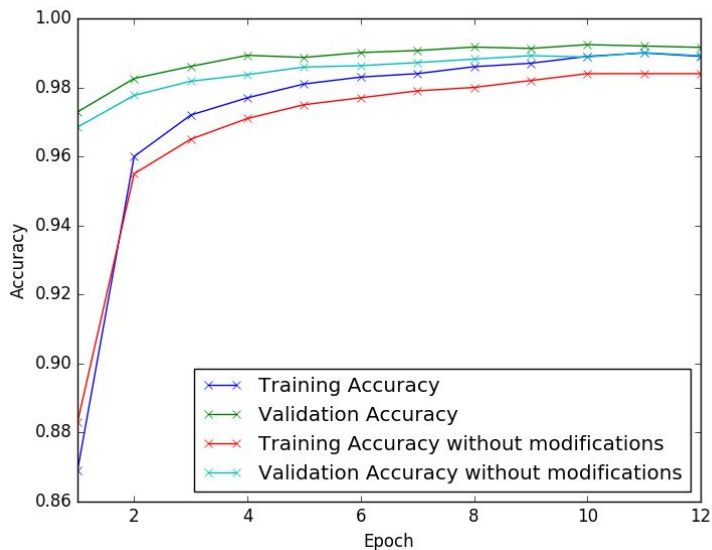
Adding 3 more Conv layers



Epoch time: 39s

Total parameters: 370506

Task 1: Architecture



Adding a new FC layer with output size 1024 between the Conv layers and the original FC layer

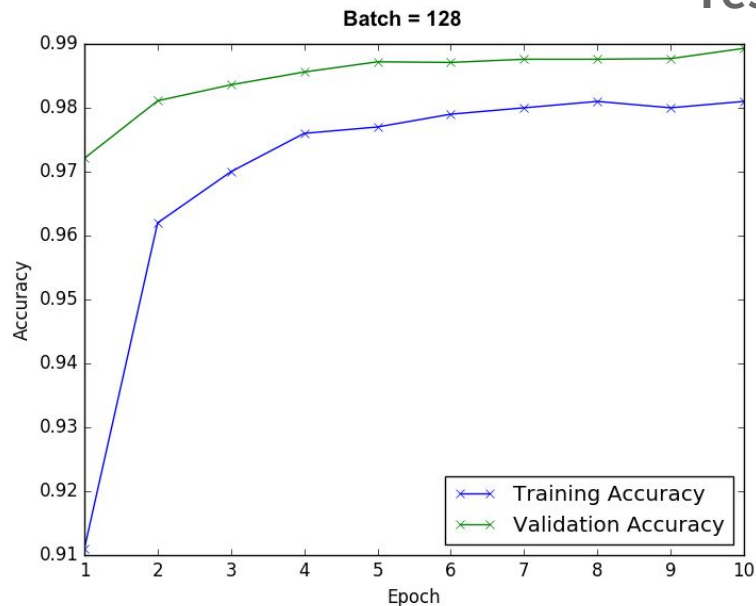
Adding new FC layers is expensive in terms of memory consumption!

Epoch time: 28 sec

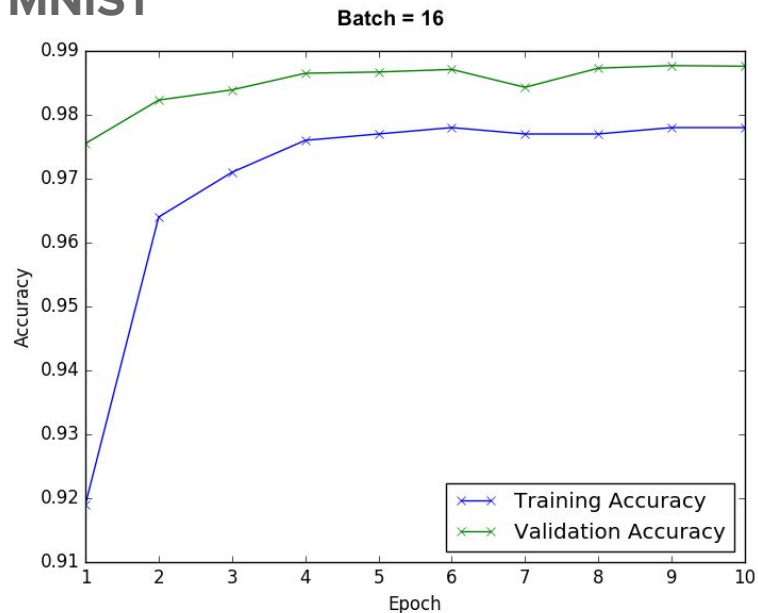
Total Parameters: 4861674

Task 2: Batch Size

Test with MNIST



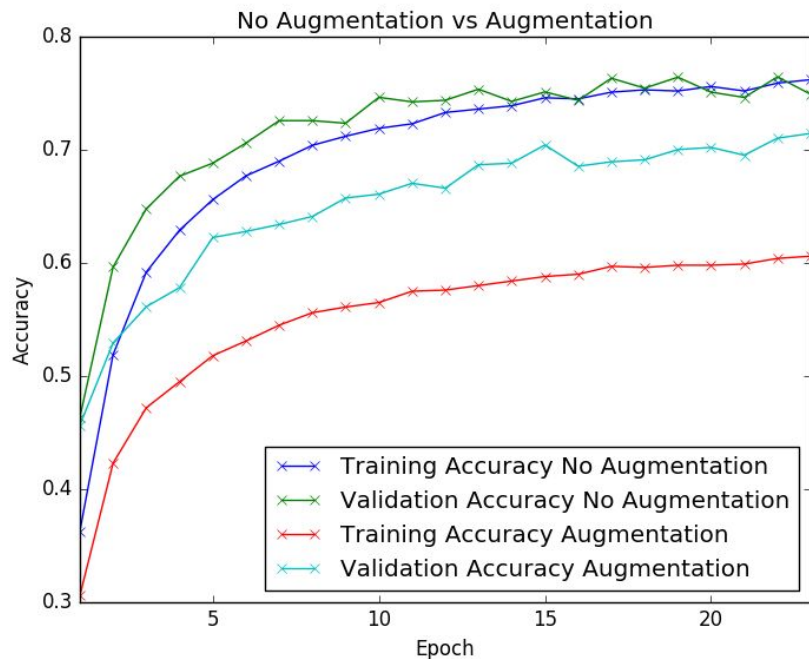
Epoch time = 28 s



Epoch time = 40 s

Only 10 classes → no perceptible difference changing the batch (same happened with CIFAR10)

Task 2: Data Augmentation

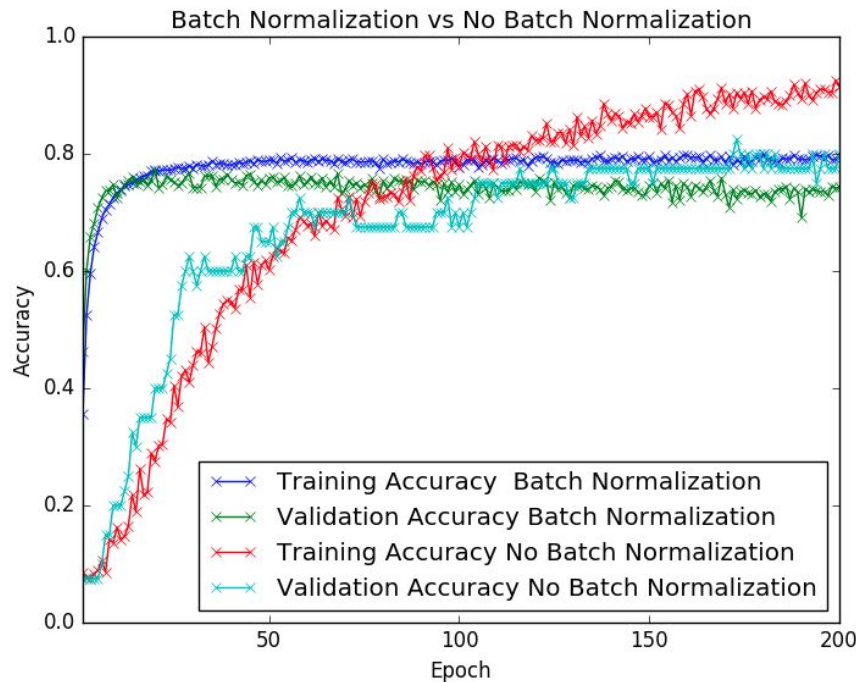


- Trained with **CIFAR10**
- Results worse with Augmentation than without Augmentation.

Possible causes:

- Not enough epochs
- This is real-time augmentation, so images are randomly flipped / translated, etc, but the amount of images per epochs is the same

Task 2: Batch Normalization



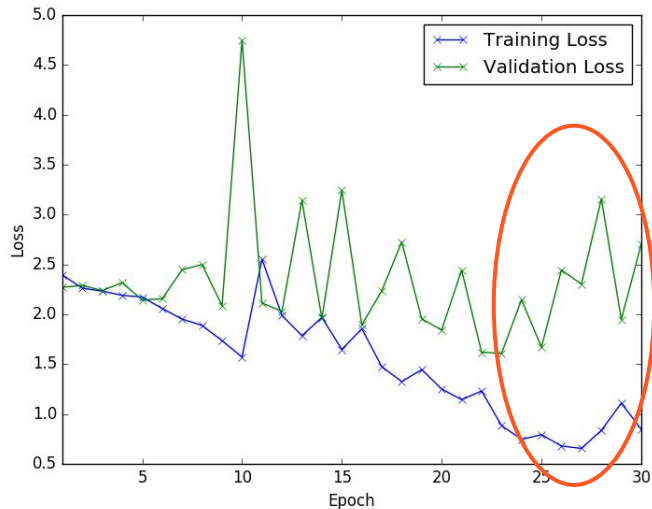
- Trained with **CIFAR10**
- **With Batch Normalization** the model learns **faster**, with fewer epochs

Task 2: Overfitting

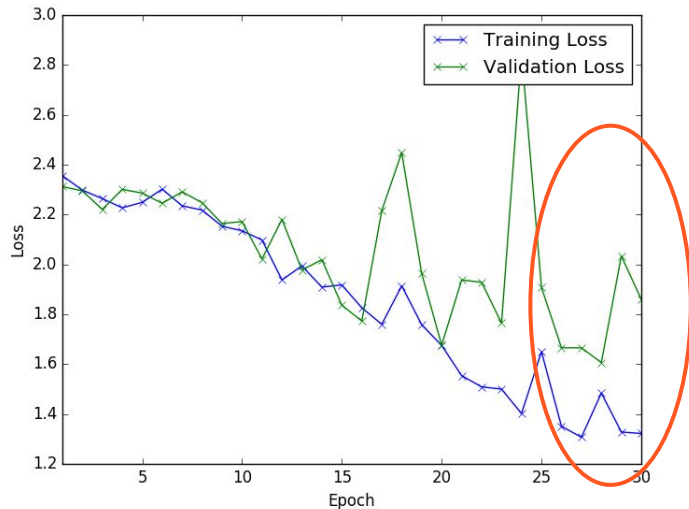
We have trained a network with 2 conv layers and 1 fully connected layer

Database: Terrassa, only 450 training images, no data augmentation

without dropout

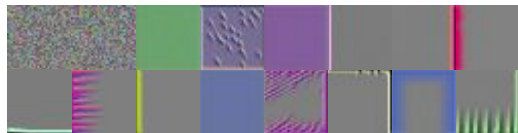


with dropout



Task 3 - Filter Visualization

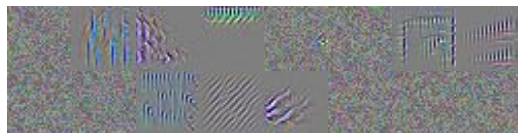
Conv
Layer 1



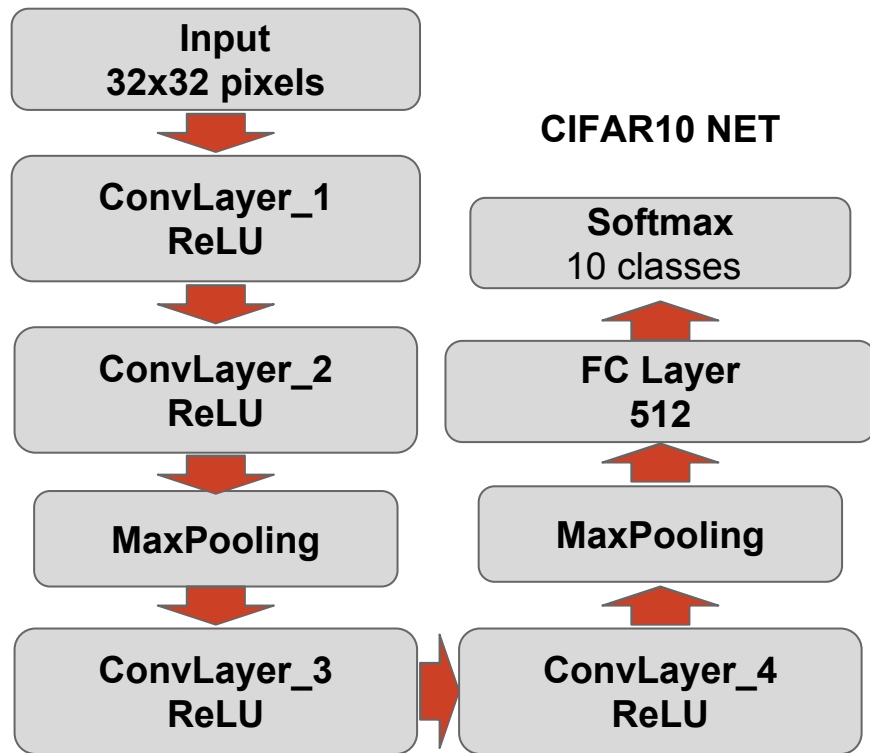
Conv
Layer 2



Conv
Layer 3



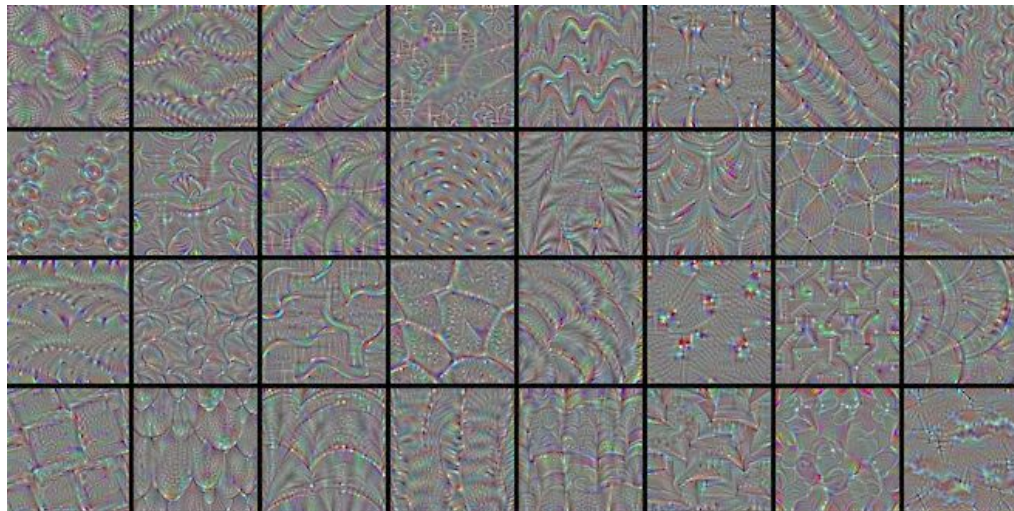
Conv
Layer 4



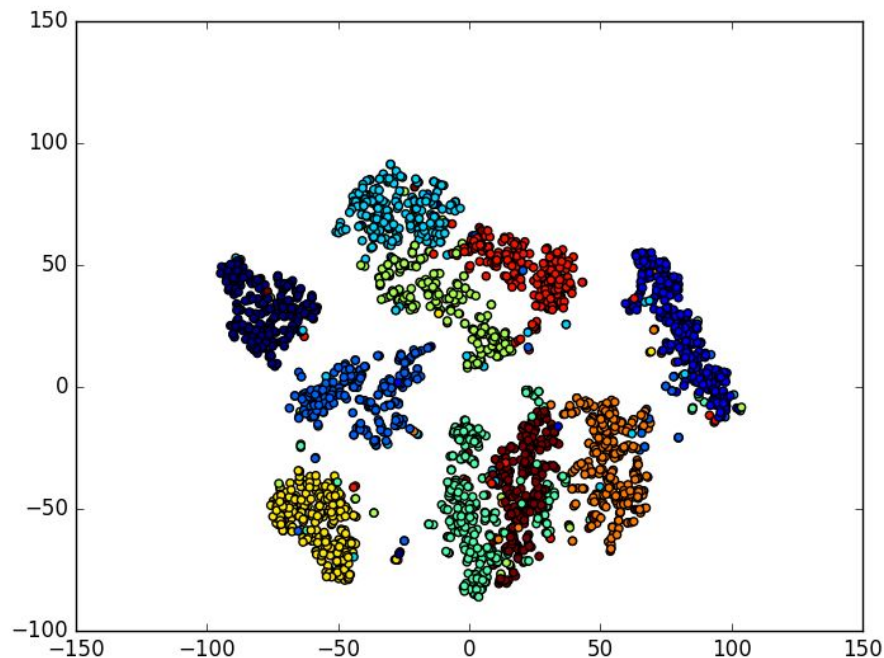
Task 3 - Filter Visualization

Filters of **pre-trained VGG16** 'conv5_1'

They are calculated defining a loss function that maximizes the activation of a specific filter in a specific layer. We have simply executed a keras/example on the following [link](#)



Task 3 - T-SNE



The T-SNE is a tool to visualize high-dimensional data.

Converts similarities between data points to joint probabilities and tries to minimize the KL divergence.

In this example we used the **MNIST** dataset with 2500 images.

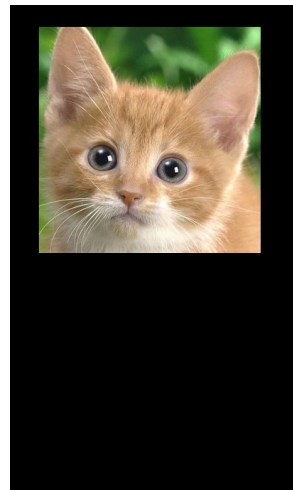
Task 3 - Off-the-shelf VGG-16 Local Classification



prob: 0.113



prob: 0.0493

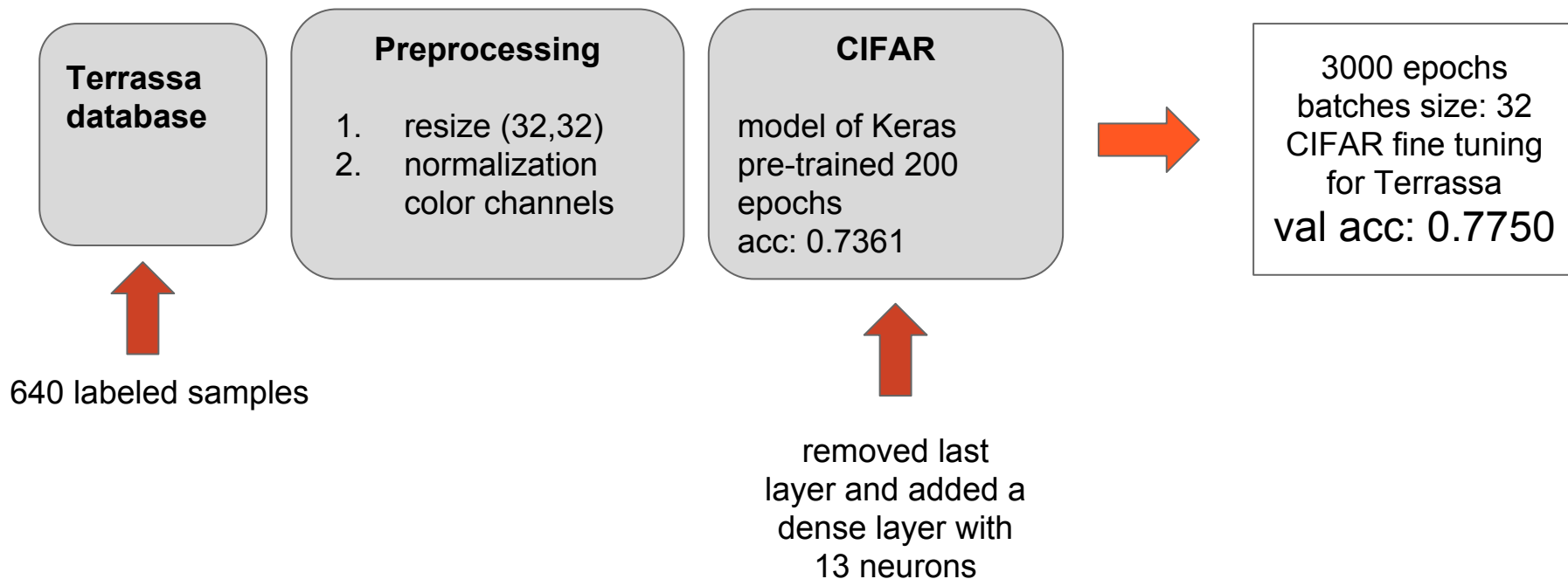


prob: 0.25

We did these tests using a trained VGG16 network for the Imagenet dataset, the probability displayed is the value for the class of the original image.

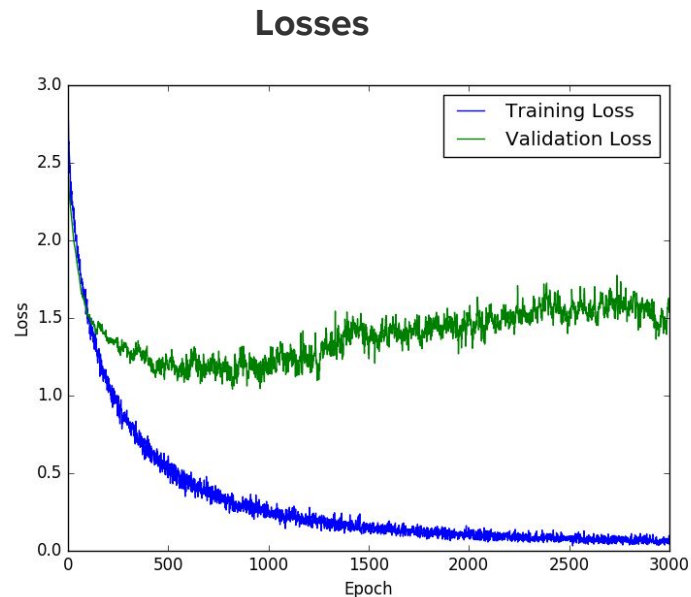
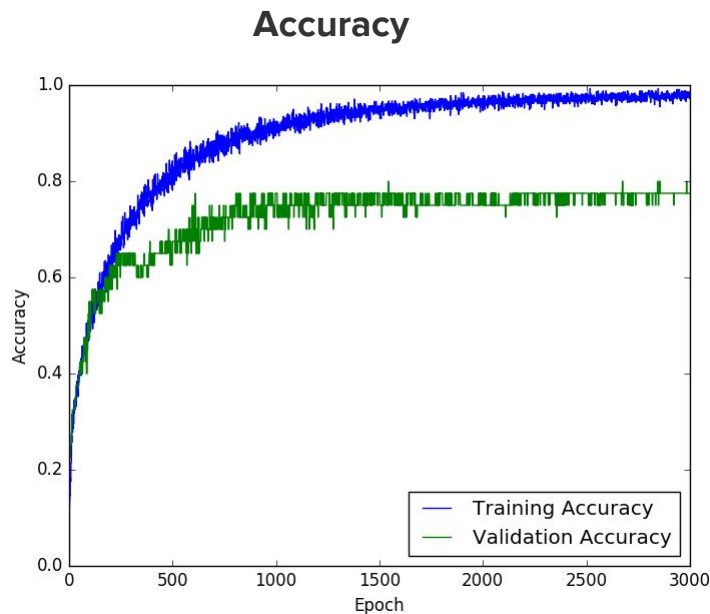
Task 4 - Fine tuning

1. Train network on CIFAR10 and fine-tune for Terrassa Buildings 900 2



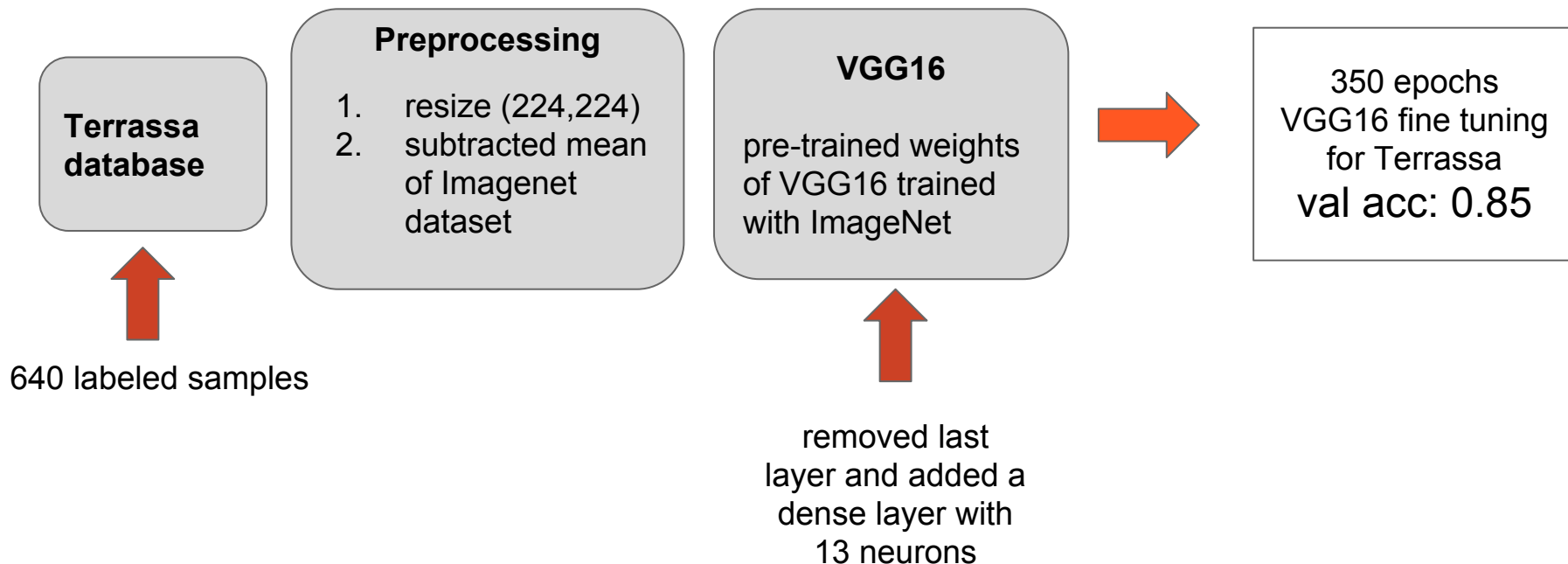
Task 4 - Fine tuning

1. Train network on CIFAR10 and fine-tune for Terrassa Buildings 900 2



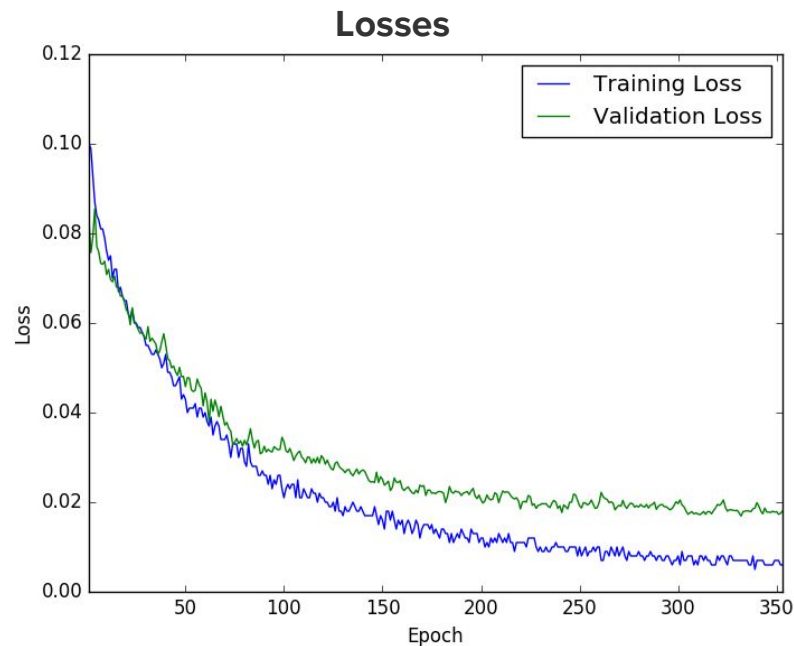
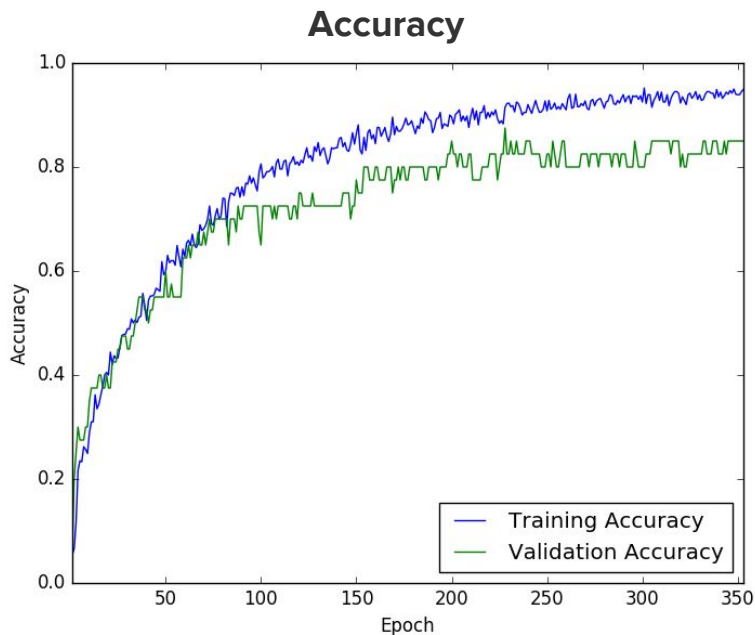
Task 4 - Fine tuning

2. Use pre-trained weights of VGG16 and train on top a classifier for Terrassa Buildings 900 2



Task 4 - Fine tuning

2. Use pre-trained weights of VGG16 and train on top a classifier for Terrassa Buildings 900 2



Task 5 - Open Project

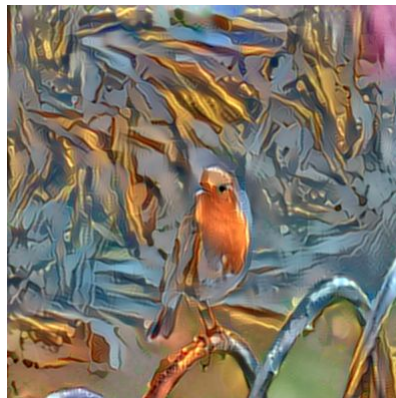
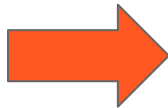
Neural Style

Goal: Generate a new image with the **content** of image1 and the **style** of image2

base image



style



How to encode content? ['conv4_2'] of VGG16

How to encode style? Gram matrix ['conv1_1', 'conv2_1', 'conv3_1', 'conv4_1', 'conv5_1'] of VGG16

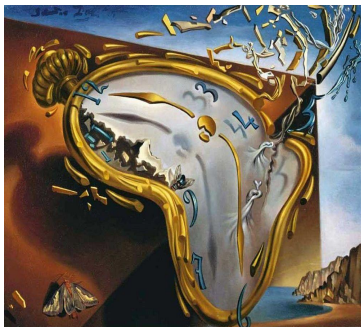
Task 5 - Open Project

Neural Style

base image

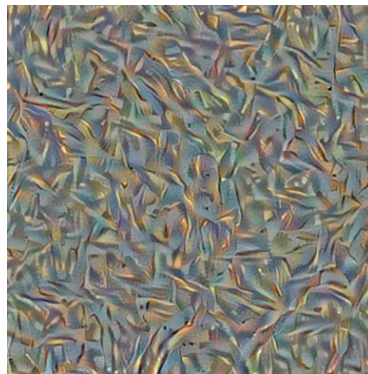


style

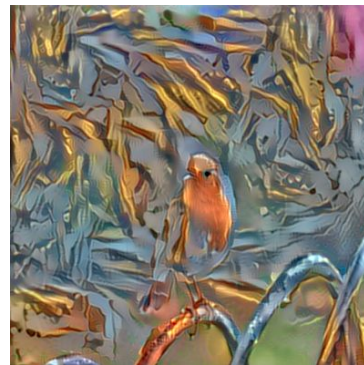


default style and content features

1 iteration



10 iterations



5 iterations

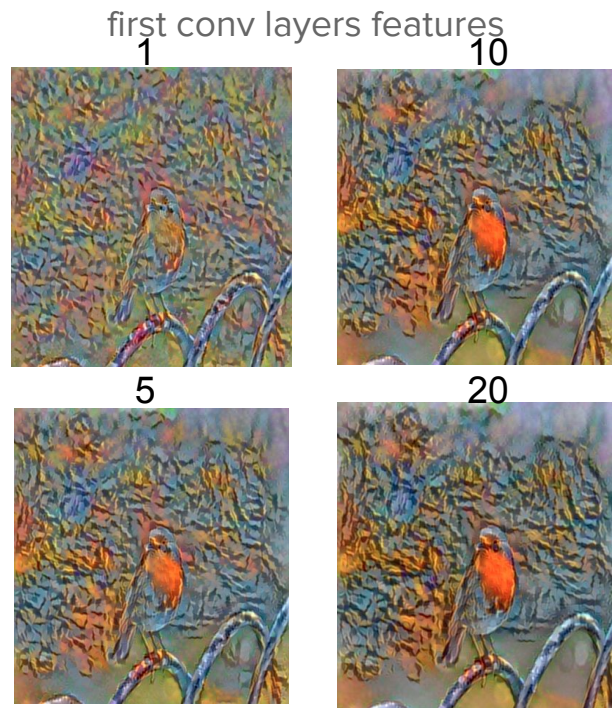
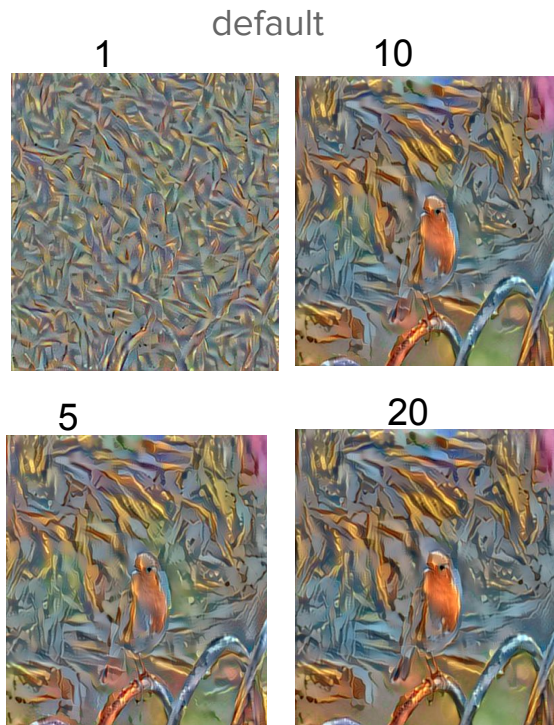


20 iterations



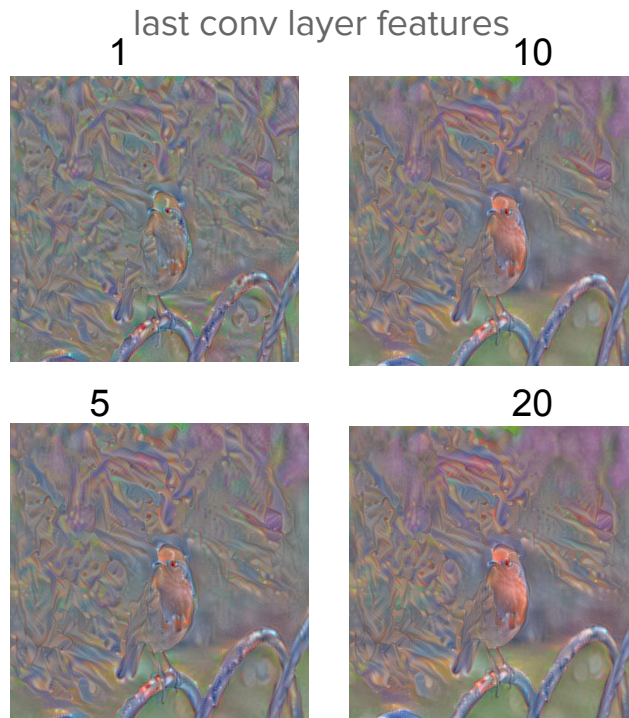
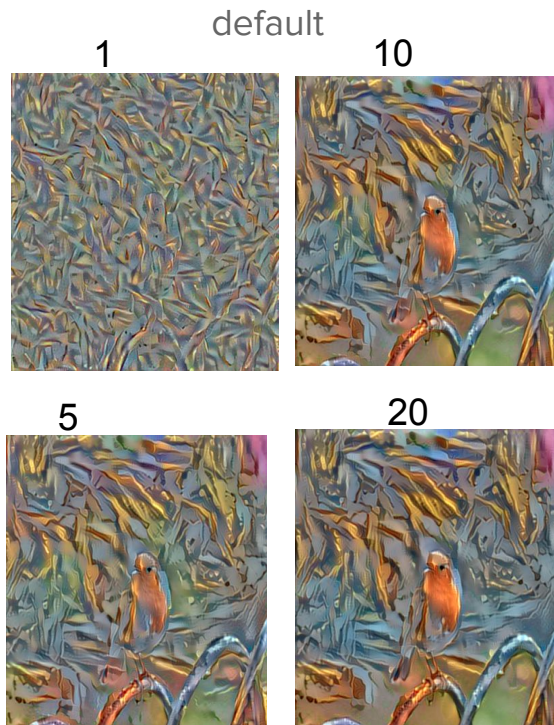
Task 5 - Open Project

Test 1: Only first conv style features feature_layers = ['conv1_1', 'conv2_1']



Task 5 - Open Project

Test 2: Only last conv style features feature_layers = ['conv4_1', 'conv5_1']



Thanks!! Questions?



References

Keras

[Keras repository](#)

[Keras Documentation](#)

[Visualization tool for VGG16 blog](#)

Neural Style

[A Neural Algorithm of Artistic Style](#)

https://github.com/fchollet/keras/blob/master/examples/neural_style_transfer.py

t-SNE

[Implementations on different languages](#)