# C66x CorePac: Achieving **High Performance**

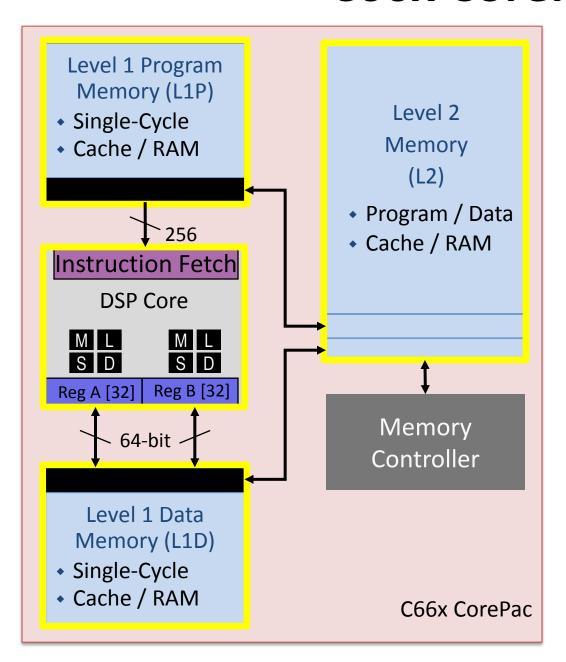
## **Agenda**

- 1. CorePac Architecture
- 2. Single Instruction Multiple Data (SIMD)
- 3. Memory Access
- 4. Pipeline Concept

#### **CorePac Architecture**

- 1. CorePac Architecture
- 2. Single Instruction Multiple Data (SIMD)
- 3. Memory Access
- 4. Pipeline Concept

#### C66x CorePac



#### CorePac includes:

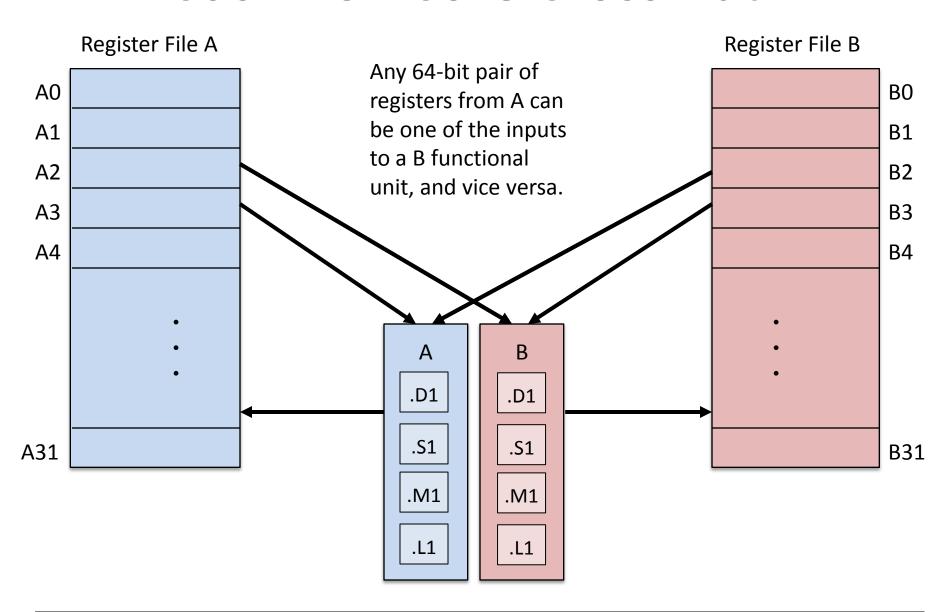
- DSP Core
  - Two registers
  - Four functional units per register side
- L1P memory (Cache/RAM)
- L1D memory (Cache/RAM)
- L2 memory (Cache/RAM)

#### Memory **A0** B<sub>0</sub> .D1 .D2 .S1 .S2 MACs .M1 .M2 **A31 B31** Controller/Decoder

#### C66x DSP Core

- Four functional units per side:
  - Multiplier (.M)
  - ALU (.L)
  - Data (.D)
  - Control (.S)
- These independent functional units enable efficient execution of parallel specialized instructions:
  - Multiplier (.M1and.M2) and ALU (.L1 and .L2) provide MAC (multiple accumulation) operations.
  - Data (.D) provides data input/output.
  - Control (.S) provides control functions (loop, branch, call).
- Each DSP core dispatches up to eight parallel instructions each cycle.
- All instructions are conditional, which enables efficient pipelining.
- The optimized C compiler generates efficient target code.

#### **C66x DSP Core Cross-Path**



#### **Partial List of .D Instructions**

Table C-1 Instructions Executing in the .D Functional Unit

Instruction	Instruction			
ADD	OR			
ADDAB	STB			
ADDAD	STB <sup>1</sup> (15-bit offset)			
ADDAH	STDW			
ADDAW	STH			
ADD2	STH <sup>1</sup> (15-bit offset)			
AND	STNDW			
ANDN	STNW			
LDB and LDB(U)	STW			
LDB and LDB(U)1 (15-bit offset)	STW¹ (15-bit offset)			
LDDW	SUB			
LDH and LDH(U)	SUBAB			
LDH and LDH(U) <sup>1</sup>	SUBAH			
LDNDW	SUBAW			
LDNW	SUB2			
LDW	XOR			
LDW¹ (15-bit offset)	ZERO			
MV				
MVK				

1. D2 only

#### **Partial List of .L Instructions**

Table D-1 Instructions Executing in the .L Functional Unit

Instruction	Instruction	Instruction	Instruction		
ABS	DPACK2	NORM	SPTRUNC		
ABS2	DPACKX2	NOT	SSUB		
ADD	DPINT	OR	SSUB2		
ADDDP	DPSP	PACK2	SUB		
ADDSP	DPTRUNC	PACKH2	SUBABS4		
ADDSUB	INTDP	PACKH4	SUBC		
ADDSUB2	INTDPU	PACKHL2	SUBDP		
ADDU	INTSP	PACKLH2	SUBSP		
ADD2	INTSPU	PACKL4	SUBU		
ADD4	LMBD	SADD	SUB2		
AND	MAX2	SADDSUB	SUB4		
ANDN	MAXU4	SADDSUB2	SWAP2		
CMPEQ	MIN2	SAT	SWAP4		
CMPGT	MINU4	SHFL3	UNPKHU4		
CMPGTU	MV	SHLMB	UNPKLU4		
CMPLT	MVK	SHRMB	XOR		
CMPLTU	NEG	SPINT	ZERO		

#### **Partial List of .M Instructions**

Table E-1 Instructions Executing in the .M Functional Unit

Instruction	Instruction	Instruction	Instruction		
AVG2	DOTPUS4	MPYIL	MPY32 (32-bit result)		
AVGU4	DOTPU4	MPYILR	MPY32 (64-bit result)		
BITC4	GMPY	MPYLH	MPY32SU		
BITR	GMPY4	MPYLHU	MPY32U		
CMPY	MPY	MPYLI	MPY32US		
CMPYR	MPYDP	MPYLIR	MVD		
CMPYR1	MPYH	MPYLSHU	ROTL		
DDOTP4	MPYHI	MPYLUHS	SHFL		
DDOTPH2	MPYHIR	MPYSP	SMPY		
DDOTPH2R	MPYHL	MPYSPDP	SMPYH		
DDOTPL2	MPYHLU	MPYSP2DP	SMPYHL		
DDOTPL2R	MPYHSLU	MPYSU	SMPYLH		
DEAL	MPYHSU	MPYSU4	Multiply Signed by Signed, 16 LSB × 16 LSB and 16 MSB × 16 MSB With Left Shift and Saturation		
DOTP2	MPYHU	MPYU	SMPY32		
DOTPN2	MPYHULS	MPYU4	SSHVL		
DOTPNRSU2	MPYHUS	MPYUS	SSHVR		
DOTPNRUS2	MPYI	MPYUS4	XORMPY		
DOTPRSU2	MPYID	MPY2	XPND2		
DOTPRUS2	MPYIH	MPY2IR	XPND4		
DOTPSU4	MPYIHR				

#### **Partial List of .S Instructions**

Table F-1 Instructions Executing in the .S Functional Unit

Instruction	Instruction	Instruction	Instruction	
ABSDP	CMPEQ2	MVKH/MVKLH	SET	
ABSSP	CMPEQ4	MVKL	SHL	
ADD	CMPEQDP	MVKH/MVKLH	SHLMB	
ADDDP	CMPEQSP	NEG	SHR	
ADDK	CMPGT2	NOT	SHR2	
ADDKPC1	CMPGTDP	OR	SHRMB	
ADDSP	CMPGTSP	PACK2	SHRU	
ADD2	CMPGTU4	PACKH2	SHRU2	
AND	CMPLT2	PACKHL2	SPACK2	
ANDN	CMPLTDP	PACKLH2	SPACKU4	
B displacement	CMPLTSP	RCPDP	SPDP	
B register <sup>1</sup>	CMPLTU4	RCPSP	SSHL	
B IRP1	DMPYU4	RPACK2	SUB	
B NRP1	EXT	RSQRDP	SUBDP	
BDEC	EXTU	RSQRSP	SUBSP	
BNOP displacement	MAX2	SADD	SUB2	
BNOP register	MIN2	SADD2	SWAP2	
BPOS	MV	SADDSU2	UNPKHU4	
CALLP	MVC1	SADDUS2	UNPKLU4	
CLR	MVK	SADDU4	XOR	
			ZERO	

1. S2 only

#### Single Instruction Multiple Data (SIMD)

- 1. CorePac Architecture
- 2. Single Instruction Multiple Data (SIMD)
- 3. Memory Access
- 4. Pipeline Concept

### **C66x SIMD Instructions: Examples**

- ADDDP Add Two Double-Precision Floating-Point Values
- DADD2 4-Way SIMD Addition, Packed Signed 16-bit
  - Performs 4 additions of two sets of 4 16-bit numbers packed into 64bit registers.
  - The 4 results are rounded to 4 packed 16-bit values
  - unit = .L1, .L2, .S1, .S2
- FMPYDP Fast Double-Precision Floating Point Multiply
- QMPY32 4-Way SIMD Multiply, Packed Signed 32-bit.
  - Performs 4 multiplications of two sets of 4 32-bit numbers packed into 128-bit registers.
  - The 4 results are packed 32-bit values.
  - unit = .M1 or .M2

#### **C66x SIMD Instruction: CMATMPY**

Many applications use complex matrix arithmetic.

- CMATMPY 2x1 Complex Vector Multiply 2x2 Complex Matrix
  - Results in 1x2 signed complex vector.
  - All values are 16-bit (16-bit real/16-bit Imaginary)
  - unit = .M1 or .M2
- How many multiplications are complex multiplication, where each complex multiplication has the following?
  - 4 complex multiplications (4 real multiplications each)
  - Two M units (16 multiplications each) = 32 multiplications
  - Core cycles per second (1.25 G)
  - Total multiplications per second = 40 G multiplications
  - 8 cores = 320 G multiplications

The issue here is, can we feed the functional units data fast enough?

### **Feeding the Functional Units**

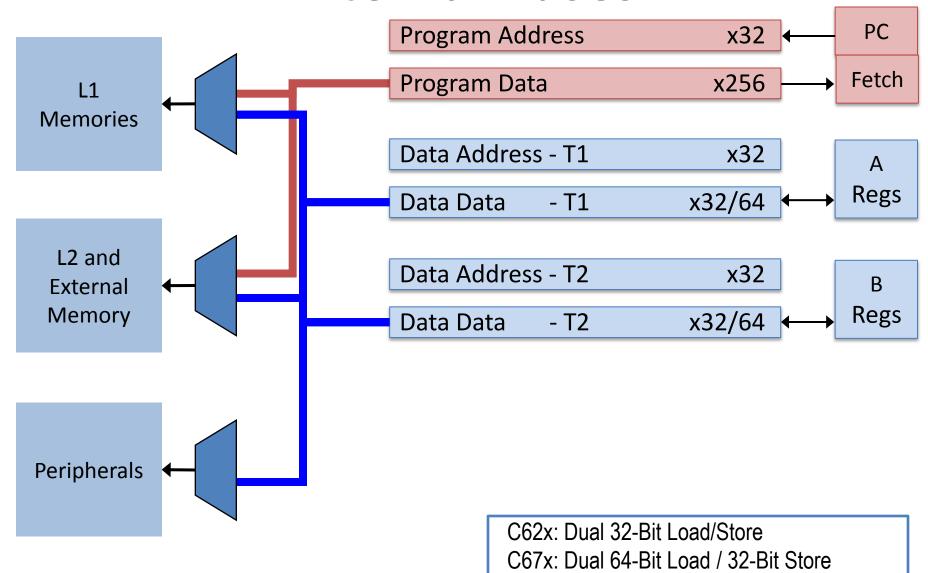
#### There are two challenges:

- How to provide enough data from memory to the core
  - Access to L1 memory is wide (2 x 64 bit) and fast (0 wait state)
  - Multiple mechanisms are used to efficiently transfer new data to L1 from L2 and external memory.
- How to get values in and out of the functional units
  - Hardware pipeline enables execution of instructions every cycle.
  - Efficient instruction scheduling maximizes functional unit throughput.

### **Memory Access**

- 1. CorePac Architecture
- 2. Single Instruction Multiple Data (SIMD)
- 3. Memory Access
- 4. Pipeline Concept

#### **Internal Buses**

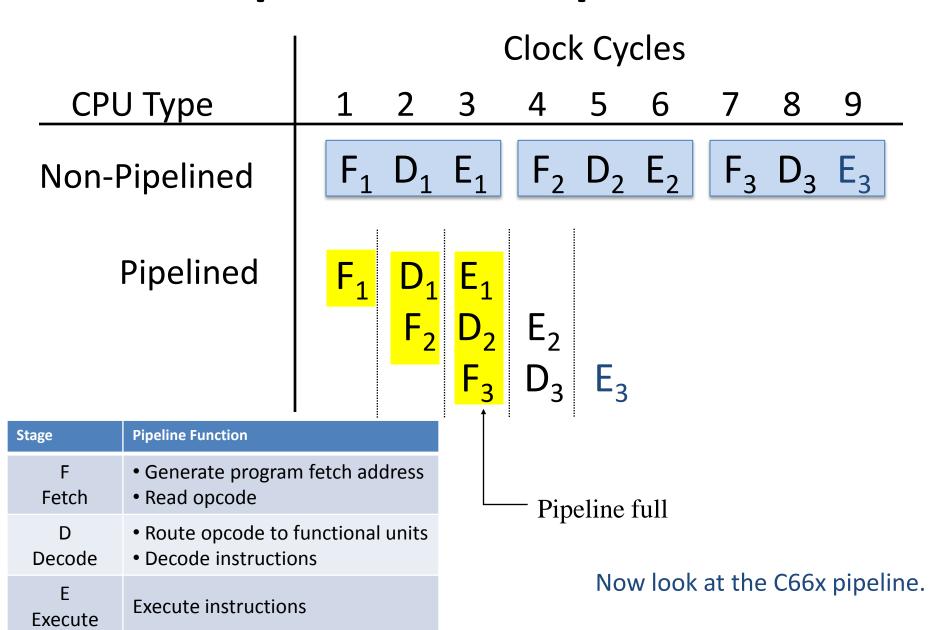


C64x, C674x, C66x: Dual 64-Bit Load/Store

## **Pipeline Concept**

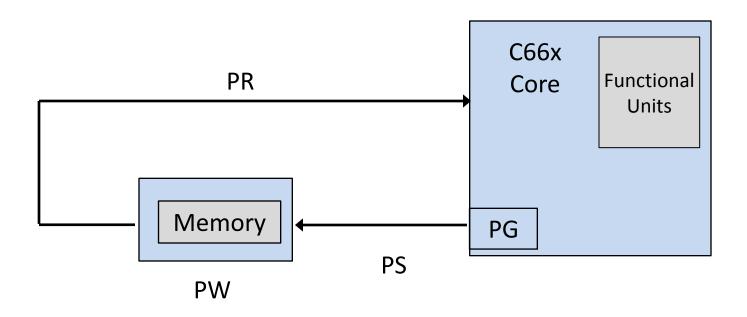
- 1. CorePac Architecture
- 2. Single Instruction Multiple Data (SIMD)
- 3. Memory Access
- 4. Pipeline Concept

### Non-Pipelined vs. Pipelined CPU

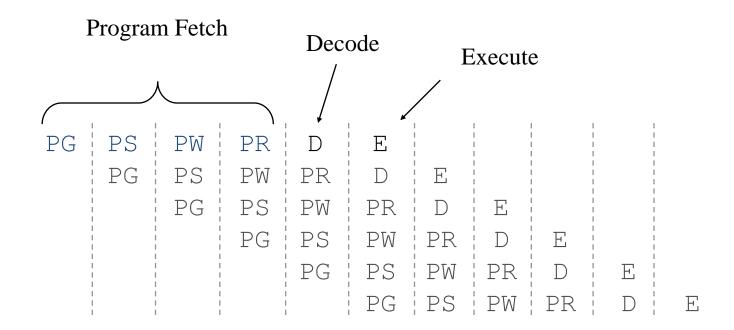


## **Program Fetch Phases**

Phase	Description
PG	Generate fetch address
PS	Send address to memory
PW	Wait for data ready
PR	Read opcode



### **Pipeline Phases - Review**

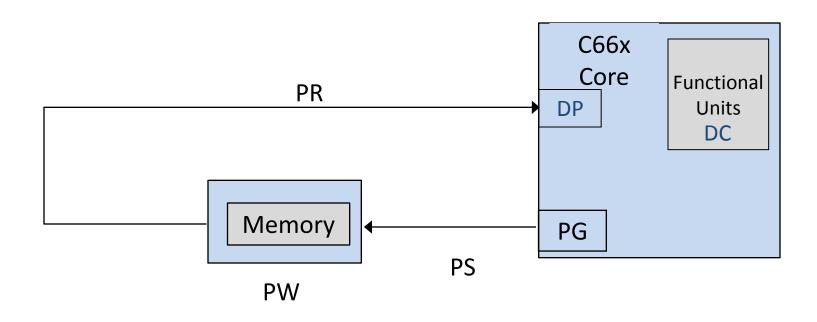


- Single-cycle performance is not affected by adding three program fetch phases.
- That is, there is still an execute every cycle.

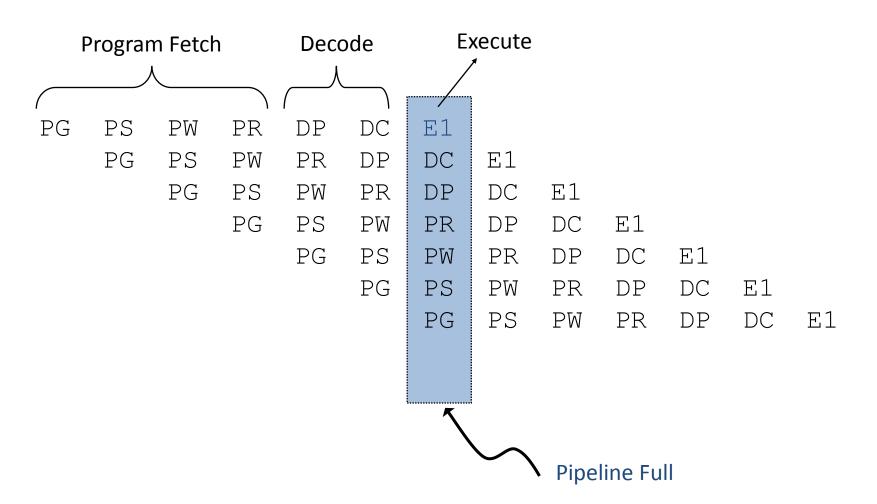
How about decode? Is it only one cycle?

#### **Decode Phases**

Decode Phase	Description
DP	Intelligently routes instruction to functional unit (dispatch)
DC	Instruction decoded at functional unit (decode)



## **Pipeline Phases**



How many cycles does it take to execute an instruction?

### **Instruction Delays**

All C66x instructions require only one cycle to execute, but some results are delayed.

Description	Instruction Example	Delay
Single Cycle	All instructions except	0
Integer multiplication and new floating point	MPY, FMPYSP	1
Legacy floating point multiplication	MPYSP	2
Load	LDW	4
Branch	В	5

## Software Pipeline Example

Dot product; A typical DSP MAC operation.

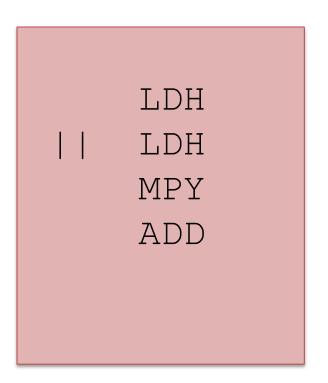
LDH || LDH MPY ADD

How many cycles would it take to perform this loop five times? (Disregard delay slots).

\_\_\_\_cycles

### Software Pipeline Example

A typical DSP MAC operation- dot product

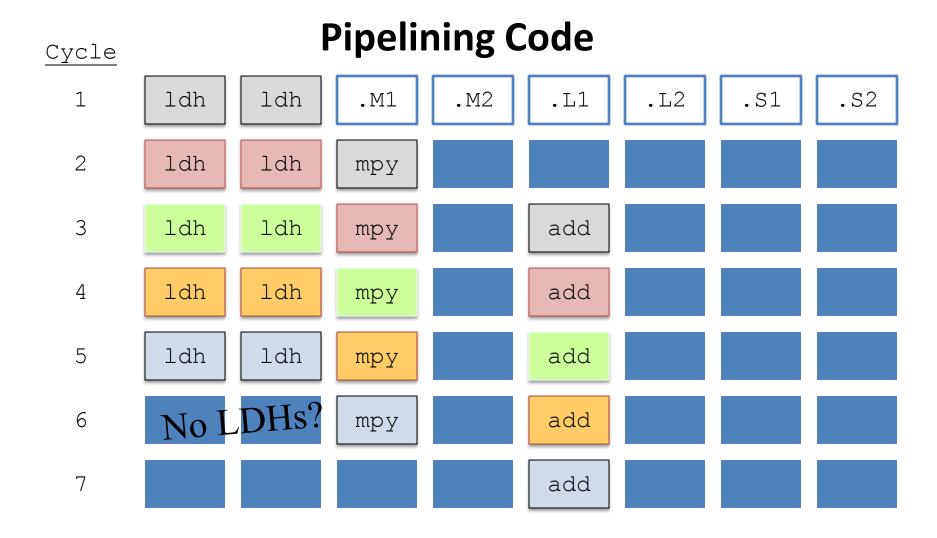


How many cycles would it take to perform this loop 5 times? (Disregard delay-slots).

 $5 \times 3 = 15 \text{ cycles}$ 

#### **Non-Pipelined Code**

Cycle	Non-Pipelinea Coae							
1	ldh	ldh	.M1	.M2	.L1	.L2	.S1	.S2
2			mpy					
3					add			
4	ldh	ldh						
5			mpy					
6					add			
7	ldh	ldh						
8			mpy					
9					add			



Pipelining these instructions took 1/2 the cycles!

### **Software Pipeline Support**

- The compiler is smart enough to schedule instructions efficiently.
- DSP algorithms are typically loop intensive.
- Generally speaking, servicing of interrupts is not allowed in the middle of the loop because fixed timing is essential.
- The C66x hardware SPLOOP enables servicing of interrupts in the middle of loops.

NOTE: For more information on SPLOOP, refer to Chapter 8 of the C66x CPU and Instruction Set Reference Guide.

#### For More Information

- For more information, refer to the <u>C66x CPU</u> and Instruction Set Reference Guide.
- For questions regarding topics covered in this training, visit the support forums at the TI E2E Community website.