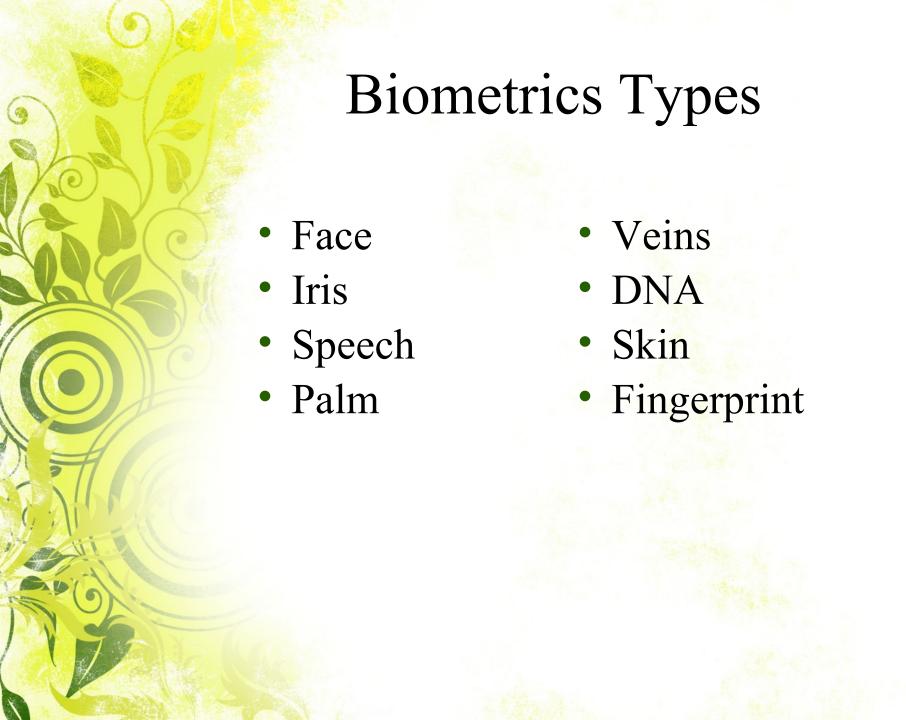
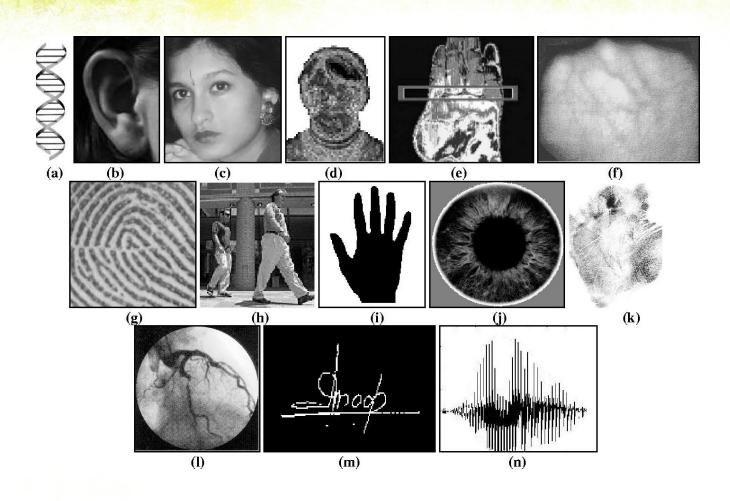


Biometrics

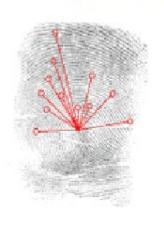
Biometrics are automated methods of recognizing a person based on a physiological or behavioral characteristics



Types of Biometrics







- Reliable
- Non Intrusive
- Needs co-operation of the individual



Face Recognition

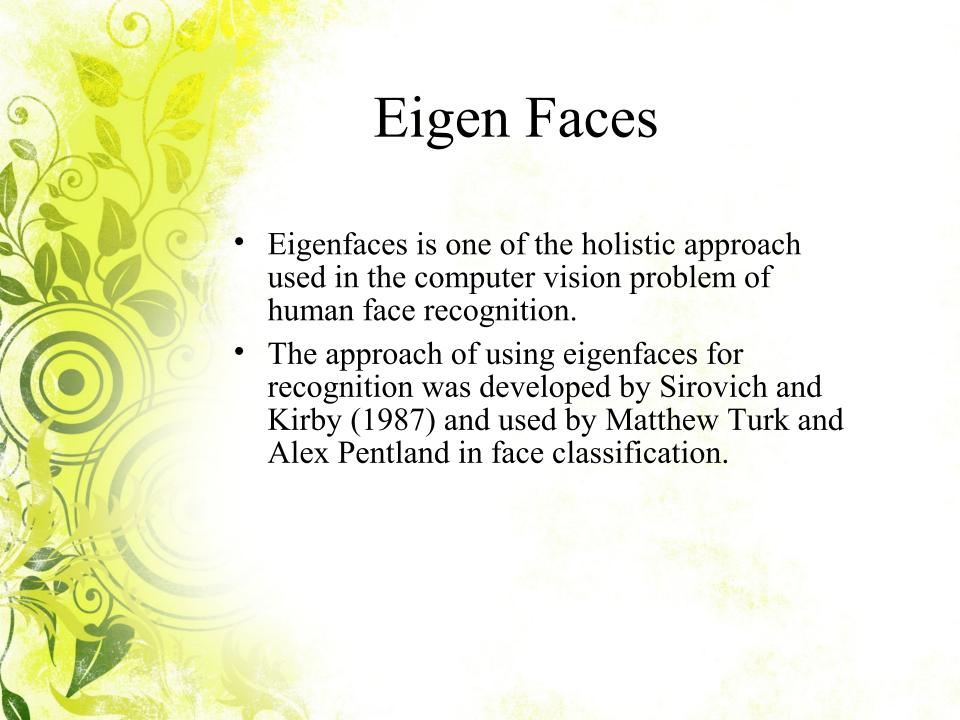
- The facial recognition process involves applying a mathematical algorithm to an image and then either storing or retrieving a match for that image from a database.
- Face recognition has recently received significant attention as one of the most successful applications of image analysis and understanding, especially during the past several years.

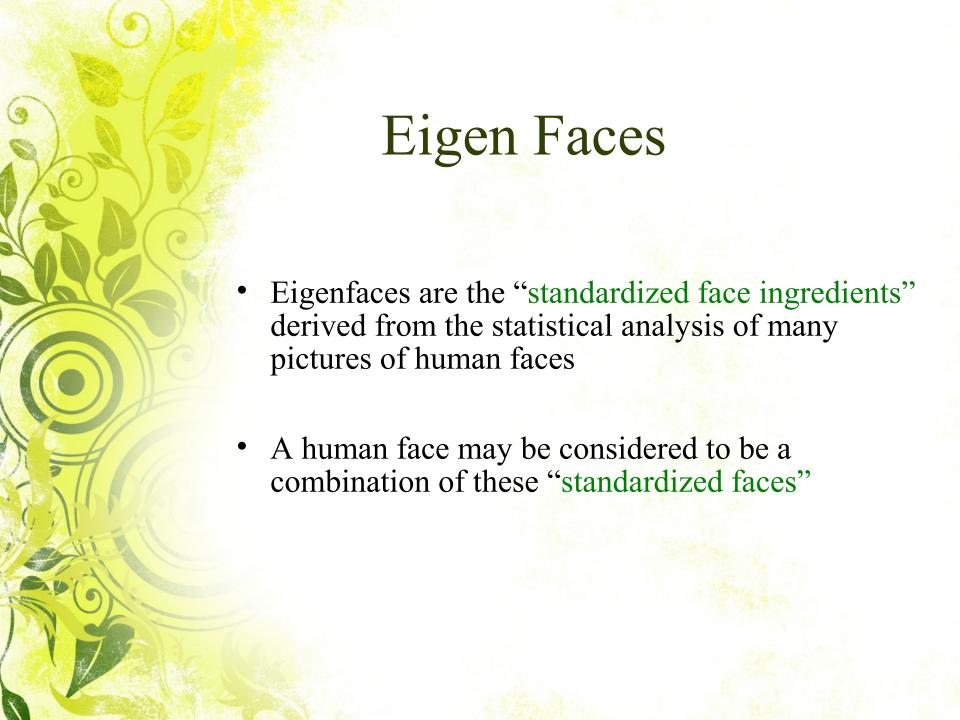
Face Recognition

It is a Good compromise between reliability & social acceptance & balances security & privacy well.

Various Face Recognition Models

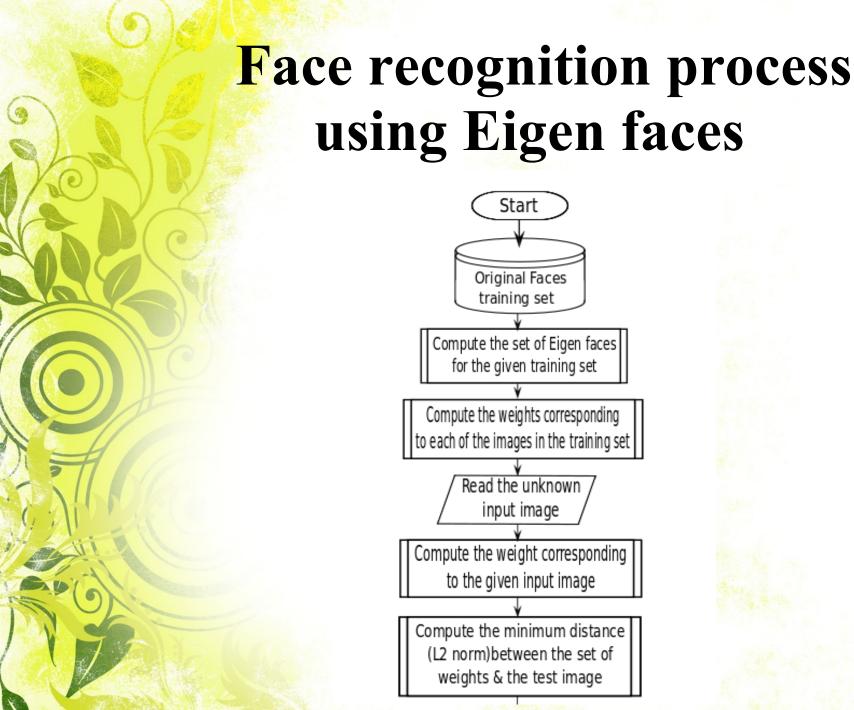
- Holistic Approach
 - Considers the whole face image
- Feature based Approach
 - -Local features of face are used
- Hybrid Approach
 - Human vision Both local feature and whole face



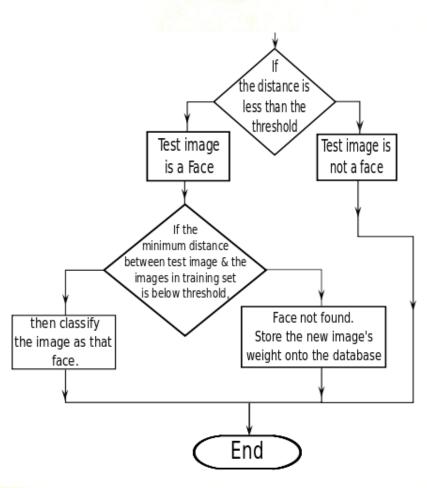


Generating Eigenfaces

- Large set of images of human faces is taken.
- The images are normalized to line up the eyes, mouths and other features.
- The eigenvectors of the covariance matrix of the face image vectors are then extracted.
- These eigenvectors are called eigenfaces.





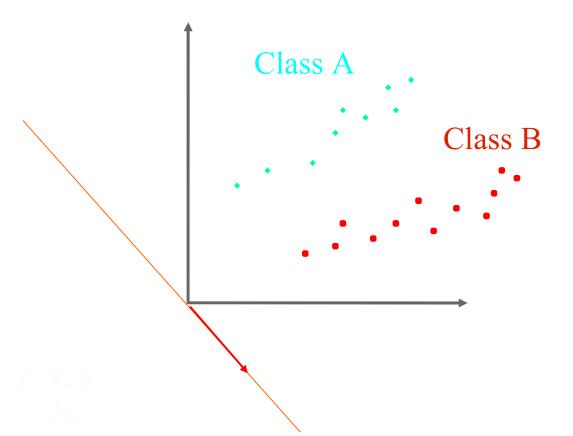


Fisher faces

Developed in 1997 by P.Belhumeur et al. Based on Fisher's LDA Faster than eigenfaces, in some cases. Has lower error rates Works well even if different illumination Works well even if different facial express.

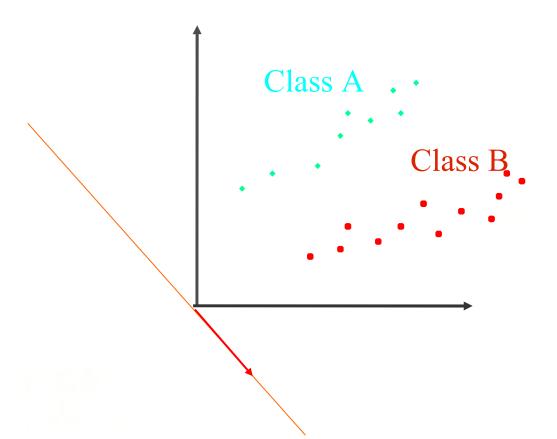
Fisherfaces

- LDA maximizes the between-class scatter
- LDA minimizes the within-class scatter



Fisherfaces

- LDA maximizes the between-class scatter
- LDA minimizes the within-class scatter





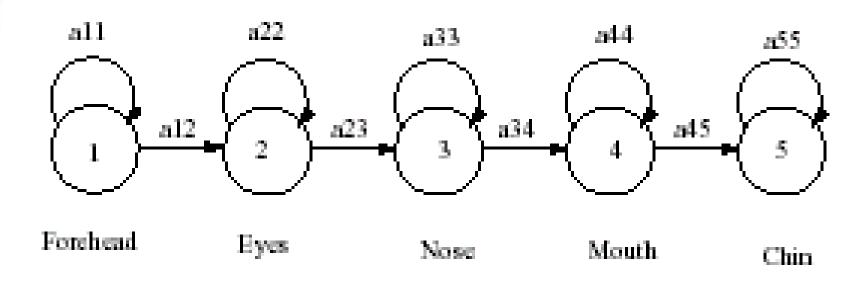
Hidden Markov Model

HMM is a Markov chain with finite number of unobservable states. These states has a probability distribution associated with the set of observation vectors.

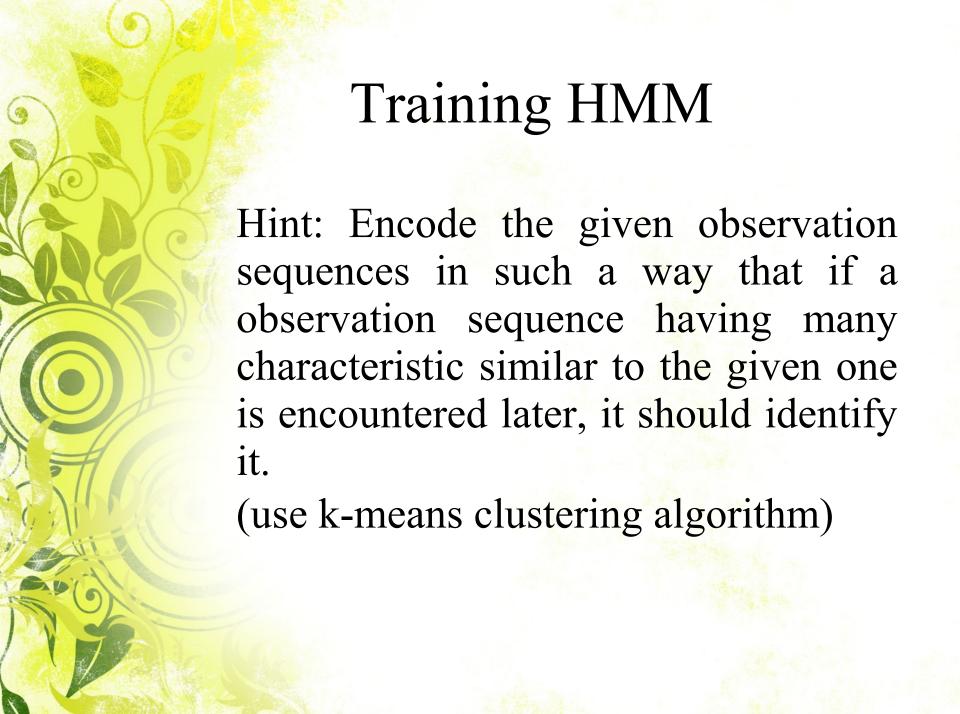
Things necessary to characterize HMM are::

- State transition probability matrix.
- Initial state probability distribution.
- Probability density function associated with observations for each of state.

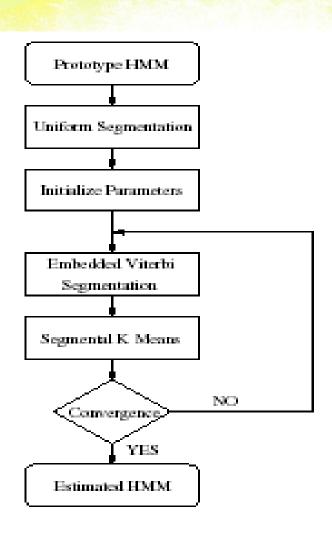
HMM Model



Face recognition using HMM



Training of Images



HMM based Face recognition

- Get the observation sequence of test image. (obs_test)
- Given $(\lambda 1, \ldots, \lambda 40)$
- Find likely hood of obs_test with each λi.
- The best likely hood identifies the person.
- Likely Hood = $P(obs_test | \lambda i)$
- Hint:use viterbi algorithm again to get the sequence state for this obs_test sequence.

Dynamic Link Architecture

The most successful feature-based structural matching approach has been the use of Elastic Bunch Graph Matching (EBGM) systems which is based on DLA.

Local features represented by "jets" Which are derived from Gabor wavelet transformation.

As use synaptic plasticity to from sets of neurons grouped into structured graphs in a neural network.

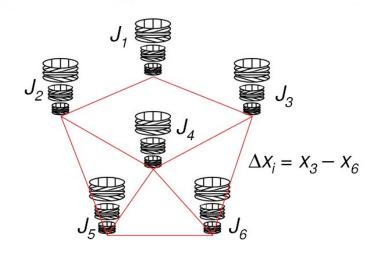
DLA Overview

- Human faces share a similar topological structure
- Labeled graph as basic object representation
 - Nodes positioned at fiducial points (eyes, nose...)
 - Jets at each node
 - Edges labeled with distance information
- Stored model graph matched to new images I Image graph (can become model graph)
- Model graphs easily translated, scaled, orientated

Why bunch graphs?

- Different poses impose problems
- Labeled graphs useful for handling any kind of coherent object
- Face recognition is in-class discrimination of objects necessary to have information specific to the structure common to all objects in the class
 - too costly to generate own graph for each combination of features Class specific information has the form of bunch graphs (one for each pose).

Image Graph



$$\Delta X_e = X_n - X_{n'}$$

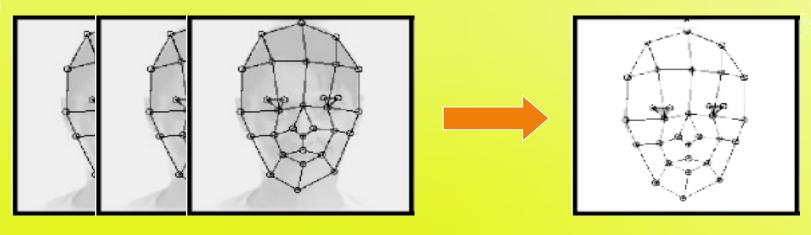
- Image Graph G: N nodes, E edges
- Labeling of nodes:

Jets J_n at positions x_n , n = 1,..., N

Labeling of edges:

Distances between nodes n and n'

Bunch Graph

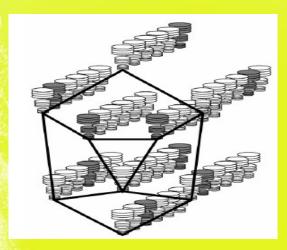


Representative of a class:

Bunch graph

- General representation
- Combine Image graphs
 - Image graphs with same structure
- Stack like structure
- Same grid structure; nodes refer to identical fiducial points

Bunch Graph



Constructing a Bunch graph B from M Image graphs G^{BM}:

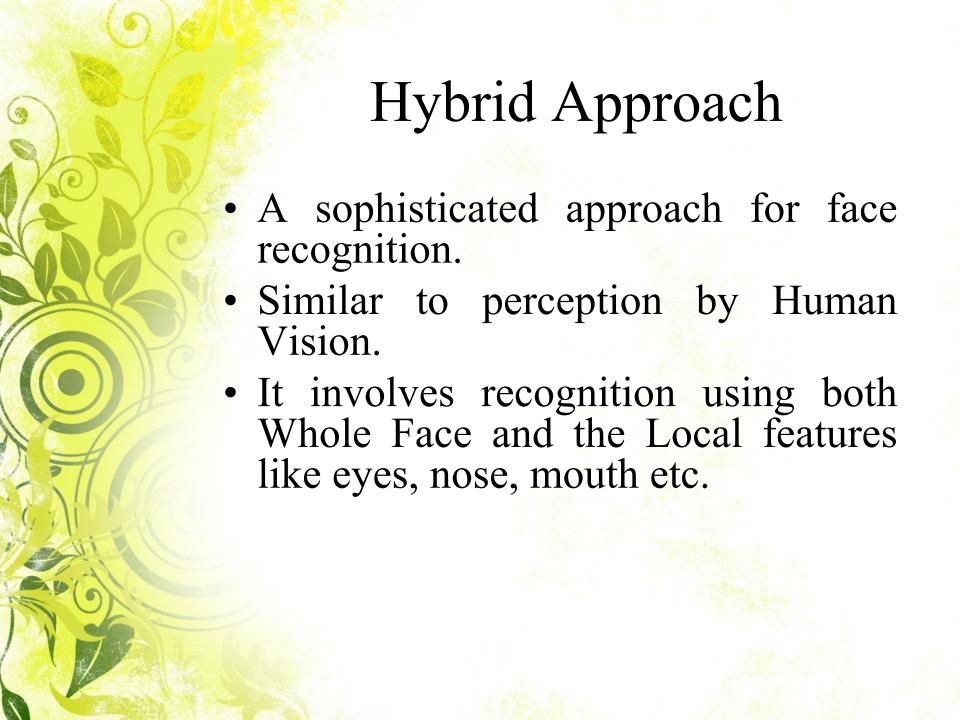
- Summarize the jets from a node
 → Set of jets → "Bunch"
- Label nodes with Bunches
- Label edges with average distance

$$\Delta \mathbf{x}_e^{\mathcal{B}} = \frac{1}{M} \sum_m \Delta \mathbf{x}_e^{\mathcal{B}m}$$

DLA: Principle

- Based on dynamic link architecture
 - Extract facial feature by Gabor wavelet transform
 - Face is represented by a graph consists of nodes of jets
- Compare graphs by cost function
 - Edge similarity S_e and vertex similarity S_v
 - Cost function

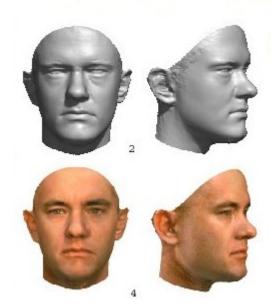
$$C_{total}(G^I, G^M) = \lambda S_e(G^I, G^M) - S_v(G^I, G^M)$$



Component Based Method 3D Morphable Model



It represents each face by a set of model coefficients and generates new, natural looking faces from any novel set of coefficients.



3D Morphable Model

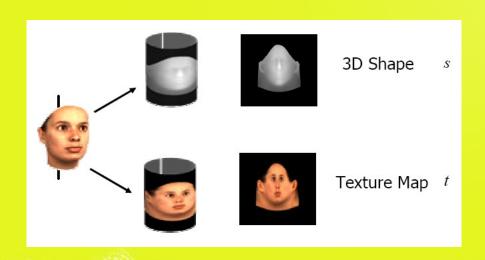
- A novel approach to pose and illumination invariant face recognition.
- No need of a large number of training images.
- Given a large database of generated 3D face models any arbitrary face can be generated by morphing between the ones in the database.
- The method used to create a 3D model from a set of 2D images is called ANALYSIS BY SYNTHESIS LOOP.

3D Morphable Model

• The actual 3D structure of known faces is captured in the shape vector

$$S = (x_1, y_1, z_1, x_2, ..., y_n, z_n)^T,$$

containing the (x, y, z) coordinates of the n vertices of a face, and the texture vector $\mathbf{T} = (R_1, G_1, B_1, R_2, ..., G_n, B_n)^T$, containing the color values at the corresponding vertices.



3D Morphable Model

Again, assuming that we have m such vector pairs in full correspondence, we can form new shapes S_{model} and new textures T_{model} as:

$$S_{model} = \sum_{i=1}^{m} a_i S_i \qquad T_{model} = \sum_{i=1}^{m} b_i T_i$$

$$s = \alpha_1 \cdot \mathbf{v} + \alpha_2 \cdot \mathbf{v} + \alpha_3 \cdot \mathbf{v} + \alpha_4 \cdot \mathbf{v} + \dots = \mathbf{S} \cdot \mathbf{a}$$

$$t = \beta_1 \cdot \mathbf{P} + \beta_2 \cdot \mathbf{P} + \beta_3 \cdot \mathbf{P} + \beta_4 \cdot \mathbf{P} + \dots = \mathbf{T} \cdot \mathbf{B}$$