# Congratulations! You passed!

Grade received 100% Latest Submission Grade 100%

To pass 80% or higher

Go to next item

 $\textbf{1.} \ \ \text{Suppose your training examples are sentences (sequences of words)}. \ \text{Which of the following refers to the} \ j^{th} \ \text{word}$ in the  $i^{th}$  training example?

1/1 point

x<sup>(i)<j></sup>

 $\bigcirc \quad x^{< i > (j)}$ 

 $\bigcirc x^{(j) < i >}$ 

 $\bigcirc \quad x^{< j > (i)}$ 

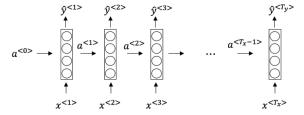
∠<sup>7</sup> Expand

**⊘** Correct

Correct We index into the  $i^{th}$  row first to get the  $i^{th}$  training example (represented by parentheses), then the  $j^{th}$  column to get the  $j^{th}$  word (represented by the brackets).

2. Consider this RNN:

1/1 point



True/False: This specific type of architecture is appropriate when Tx>Ty

○ True

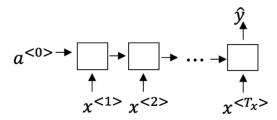
False

Z Expand

 ${\tt Correct!\ This\ type\ of\ architecture\ is\ for\ applications\ where\ the\ input\ and\ output\ sequence\ length\ is\ the}$ same.

3. To which of these tasks would you apply a many-to-one RNN architecture? (Check all that apply).

1/1 point



Sentiment classification (input a piece of text and output a 0/1 to denote positive or negative sentiment)

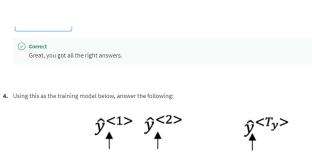
✓ Correct Correct!

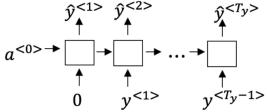
Image classification (input an image and output a label)

 $\ensuremath{\overline{\bigcup}}$  Gender recognition from speech (input an audio clip and output a label indicating the speaker's gender)

✓ Correct

Correct!





True/False: At the  $t^{th}$  time step the RNN is estimating  $P(\boldsymbol{y}^{< t>})$ 

○ True

False

Z Expand

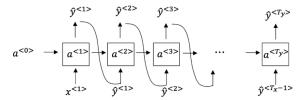
**⊘** Correct

No, in a training model we try to predict the next steps based on the knowledge of all prior steps.

5. You have finished training a language model RNN and are using it to sample random sentences, as follows:

1/1 point

1/1 point



 $\label{thm:continuous} True/False: In this sample sentence, step t uses the probabilities output by the RNN to pick the highest probability word for that time-step. Then it passes the ground-truth word from the training set to the next time-step.$ 

False

○ True

Z Expand

⊘ Correct

The probabilities output by the RNN are not used to pick the highest probability word and the ground-truth word from the training set is not the input to the next time-step.

6. True/False: If you are training an RNN model, and find that your weights and activations are all taking on the value of NaN ("Not a Number") then you have a vanishing gradient problem.

1/1 point

False

○ True

∠ Expand

**⊘** Correct

Vanishing and exploding gradients are common problems in training RNNs, but in this case, your weights and activations taking on the value of NaN implies you have an exploding gradient problem.

7. Suppose you are training an LSTM. You have a 10000 word vocabulary, and are using an LSTM with 100-dimensional activations  $a^{<t>}$ . What is the dimension of  $\Gamma_u$  at each time step?

1/1 point

) 1

100

300

#### Z Expand

Correct,  $\Gamma_u$  is a vector of dimension equal to the number of hidden units in the LSTM.

8. Here are the update equations for the GRU.

1/1 point

### GRU

$$\begin{split} \tilde{c}^{< t>} &= \tanh(W_c[\Gamma_r * c^{< t^{-1}>}, x^{< t^{>}}] + b_c) \\ \Gamma_u &= \sigma(W_u[c^{< t^{-1}>}, x^{< t^{>}}] + b_u) \\ \Gamma_r &= \sigma(W_r[c^{< t^{-1}>}, x^{< t^{>}}] + b_r) \\ c^{< t>} &= \Gamma_u * \tilde{c}^{< t^{>}} + (1 - \Gamma_u) * c^{< t^{-1}>} \\ a^{< t>} &= c^{< t>} \end{split}$$

Alice proposes to simplify the GRU by always removing the  $\Gamma_u$ . i.e., setting  $\Gamma_u$  = 0. Betty proposes to simplify the GRU by removing the  $\Gamma_r$ . I. e., setting  $\Gamma_r$  = 1 always. Which of these models is more likely to work without vanishing gradient problems even when trained on very long input sequences?

- $\bigcirc$  Alice's model (removing  $\Gamma_u$  ), because if  $\Gamma_r\approx 0$  for a timestep, the gradient can propagate back through that timestep without much decay.
- O Alice's model (removing  $\Gamma_{u}$ ), because if  $\Gamma_{r}\approx 1$  for a timestep, the gradient can propagate back through that timestep without much decay.
- igl( Betty's model (removing  $\Gamma_r$  ), because if  $\Gamma_u pprox 0$  for a timestep, the gradient can propagate back through that timestep without much deca
- $\bigcirc$  Betty's model (removing  $\Gamma_{r}$ ), because if  $\Gamma_{u}\approx 1$  for a timestep, the gradient can propagate back through that timestep without much decay.

### ∠<sup>7</sup> Expand

✓ Correct Yes. For the signal to backpropagate without vanishing, we need  $c^{< t>}$  to be highly dependent on  $c^{< t-1>}$ .

9. True/False: Using the equations for the GRU and LSTM below the Update Gate and Forget Gate in the LSTM play a different role to Γu and 1- Γu.

1/1 point

### GRU

GRU	LSTM
$\tilde{c}^{< t>} = \tanh(W_c[\Gamma_r * c^{< t-1>}, x^{< t>}] + b_c)$	$\tilde{c}^{< t>} = \tanh(W_c[a^{< t-1>}, x^{< t>}] + b_c)$
$\Gamma_u = \sigma(W_u[c^{< t-1>},x^{< t>}] + b_u)$	$\Gamma_u = \sigma(W_u[a^{< t-1>},x^{< t>}] + b_u)$
$\Gamma_r = \sigma(W_r[c^{< t-1>},x^{< t>}] + b_r)$	$\Gamma_f = \sigma(W_f[a^{< t-1>},x^{< t>}] + b_f)$
$c^{< t>} = \Gamma_u * \tilde{c}^{< t>} + (1 - \Gamma_u) * c^{< t - 1>}$	$\Gamma_o = \sigma(W_o[a^{< t-1>},x^{< t>}] + b_o)$
$a^{< t>} = c^{< t>}$	$c^{< t>} = \ \Gamma_u * \tilde{c}^{< t>} + \Gamma_f * c^{< t-1>}$
	$a^{< t>} = \Gamma_o * c^{< t>}$

○ False

True

## Z Expand

 $Correct!\ Instead\ of\ using\ \Gamma u\ to\ compute\ 1-\Gamma u, LSTM\ uses\ 2\ gates\ (\Gamma u\ and\ \Gamma f)\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ value\ of\ using\ T u\ to\ compute\ the\ final\ u\ to\ comput$ the hidden state. So, Ff is used instead of 1 - Fu.

10. Your mood is heavily dependent on the current and past few days' weather. You've collected data for the past 365 days on the weather, which you represent as a sequence as  $x^{<1>},\ldots,x^{<365>}$ . You've also collected data on your mood, which you represent as  $y^{<1>},\ldots,y^{<365>}$ . You'd like to build a model to map from  $x\rightarrow y$ . Should you use a Unidirectional RNN or Bidirectional RNN for this problem?

1/1 point

- Bidirectional RNN, because this allows the prediction of mood on day t to take into account
- Bidirectional RNN, because this allows backpropagation to compute more accurate
- n . Unidirectional RNN, because the value of  $y^{<\!t>}$  depends only on  $x^{<\!1>},\dots,x^{<\!t>}$  , but not on  $x^{<\!1>},\dots,x^{<\!385>}$  .
- O Unidirectional RNN, because the value of  $y^{<\!t>}$  depends only on  $x^{<\!t>}$ , and not other days'

∠ Expand

**⊘** Correct