CS584 – MACHINE LEARNING FALL 2016

Predicting occurrence of major accident Group Members: Hariharan Devarajan

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Predicting occurrence of a major accident

Group Members: Hariharan Devarajan

Task

The task is to create a model which could predict whether major accident would occur. Here major accident is defined as more than one vehicle colliding. The motivation behind this task is the fact that accidents in Illinois state are generally major and these are only increasing every year. So analyze and come up with a model which could predict and hence could describe patterns which help reduce accidents by proactive measures. The Problem is a classification problem to identify whether major accident would occur or not. The fact that it will need to analyze both conditions of roads and also driving make this an interesting problem.

Dataset

I have got the crash data of 2014 year. It has a lot of columns like place where accident occur. The conditions and so on. The dataset has 292019 records with 80 features. Here is a summary of each feature and the target variable.

Features

OBJECTID : Identifier of each record
 geodb_oid : Geographical db id
 ROUTE : Route in the state
 Case_Id : Case Identifier

YEAR
 MONTH
 month when crash happened
 DAY
 Day when crash happened
 HOUR
 Hour when crash happened

o DAY_O_WEEK: Day of the week when crash happened

INJURIES : No of injuries occurred

FATALITIES : No of fatalities from the incident

COLL_TYPE : Type of Collision
 WEATHER : Whether Type
 LIGHTING : Type of Lightening
 SURF_COND : Condition of the surface

RD_DEFECT : Road DefectsRD_FEATURE : Road Feature

TRAF_CNTRL : Traffic Control was present or not
 COUNTY : Country where this happened
 TOWNSHIP : Township where this occurred

o TS_ROUTE : Route info

MILE : How many miles the accident was spread

O CITY : City where this happened

DRIVER_1 : Condition of Driver

VEH1 TYPE : Type of Vehicle 1 involved in accident

VEH1_SPECL : Vehicle ownership

VEH1_DIR : Vehicle was heading which directionVEH1_MANUV : Type of maneuver performed by vehicle

VEH1 EVNT1 : Exact event with vehicle 1

VEH1_LOC1 : Location where vehicle 1 was found

VEH1 EVNT2 : Second event with vehicle 1

VEH1 LOC2 : Second location where vehicle 1 was found

o VEH1_EVNT3 : Third event with vehicle 1

VEH1 LOC3 : Third location where vehicle 1 was found

o DRIVER_2 : Condition of Driver

VEH2_TYPE : Type of Vehicle 2 involved in accident

VEH2 SPECL : Vehicle ownership

VEH2_DIR : Vehicle was heading which directionVEH2_MANUV : Type of maneuver performed by vehicle

VEH2_EVNT1 : Exact event with vehicle 2

VEH2_LOC1 : Location where vehicle 2 was found

VEH2 EVNT2 : Second event with vehicle 2

VEH2 LOC2 : Second location where vehicle 2 was found

VEH2_EVNT3 : Third event with vehicle 2

VEH2 LOC3 : Third location where vehicle 1 was found

DRIVER_3 : Condition of Driver

VEH3_TYPE : Type of Vehicle 3 involved in accident

VEH3_SPECL : Vehicle ownership

VEH3_DIR : Vehicle was heading which directionVEH3_MANUV : Type of maneuver performed by vehicle

VEH3_EVNT1 : Exact event with vehicle 3

VEH3_LOC1 : Location where vehicle 3 was found

VEH3 EVNT2 : Second event with vehicle 3

VEH3_LOC2 : Second location where vehicle 3 was found

VEH3_EVNT3 : Third event with vehicle 3

o VEH3 LOC3 : Third location where vehicle 3 was found

DRIVER_4 : Condition of Driver

VEH4_TYPE : Type of Vehicle 4 involved in accident

VEH4_SPECL : Vehicle ownership

VEH4_DIR : Vehicle was heading which direction
 VEH4_MANUV : Type of maneuver performed by vehicle

VEH4 EVNT1 : Exact event with vehicle 4

VEH4_LOC1 : Location where vehicle 4 was found

VEH4_EVNT2 : Second event with vehicle 4

O VEH4 LOC2 : Second location where vehicle 4 was found

O VEH4 EVNT3 : Third event with vehicle 4

VEH4_LOC3 : Third location where vehicle 4 was found

O DUP_CD : No Idea

REC_TYPE : Type of Injury

XCOORD : X Coordinate where accident occurYCOORD : Y Coordinate where accident occur

INTERSEC : Was it an intersectionSFE : Vehicle Number

O AGENCY_NUM: Agency Identifier
O RUNDATE: Date when it was run
O WorkZone: Was are a workzone
O WorkZoneTy: Work Zone type

WorkersPre : Were workers present
 ExceedSpee : Was speed exceeded
 CellPhoneU : Was cell phone used.

NUM_VEH : This is the Target variable. Number of vehicle(s) involved

Data source

The Data source was IDOT intern. I has asked him to check with his manager to get some data on crash. As the data shared was not sensitive they were ready to share the data.

Target variable

The number of vehicles involved in Crash ("NUM_VEH")

Features

There are 80 features and I have described then in the dataset region

Data size

I have 292019 instances

Preprocessing

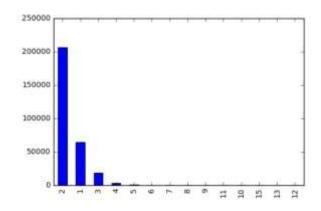
I have done the following preprocessing on the data:

- 1. Filled mean in the NA columns of numerical data.
- 2. Removed the columns which were effects of accident not cause like injuries, fatalities, etc.
- 3. I removed all the Identifier columns.
- 4. I converted categorical data to numerical data.
- 5. I converted NUM_VEH my target to binary by rule 1 if >1 else 0

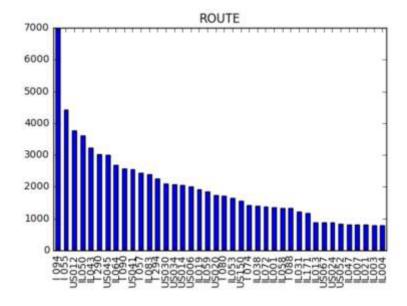
Visualization

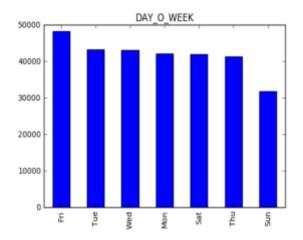
Target

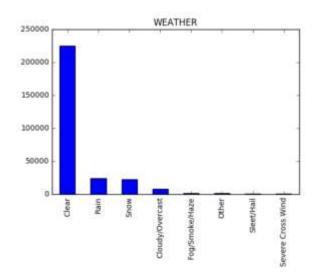
count	292019.000000
mean	1.869991
std	0.580815
min	1.000000
25%	2.000000
50%	2.000000
75%	2.000000
max	15.000000

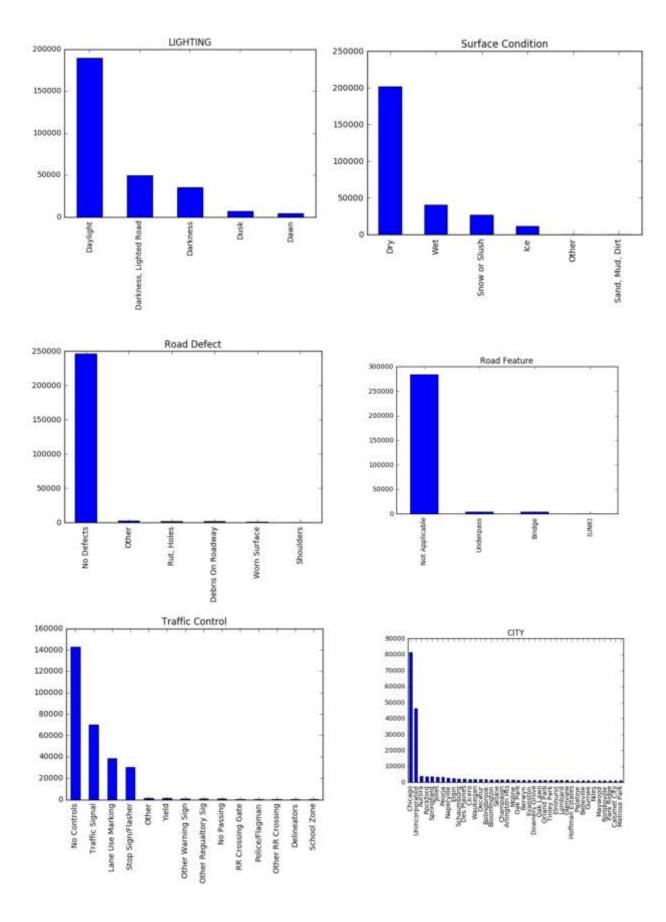


Features









Evaluation

Performance Measure

The performance measure for this I chose is accuracy and AUC because this model predicts whether major accident would occur or not and for this reason evaluating on the basis of its accuracy is most important.

Classifiers

I used a number of Classifier but finally chose Gradiant Boosting Classifier. The parameters I fined tuned on were

0	Number of trees	:	500	as change after that is little and Smaller number of trees means Simpler Model
0	Loss	:	deviance	gives maximum accuracy and auc
0	Learning Rate	:	.3	gives Peak AUC with almost best Accuracy
0	Max Depth	:	3	Both Accuracy and AUC reach maximum
0	Sample Split	:	2	Both Accuracy and AUC reach maximum
0	Min Sample Leafs	:	10	Both Accuracy and AUC reach maximum
0	Sub Sample	:	1	Both Accuracy and AUC reach maximum
0	Max Features	:	auto	

Evaluation Strategy

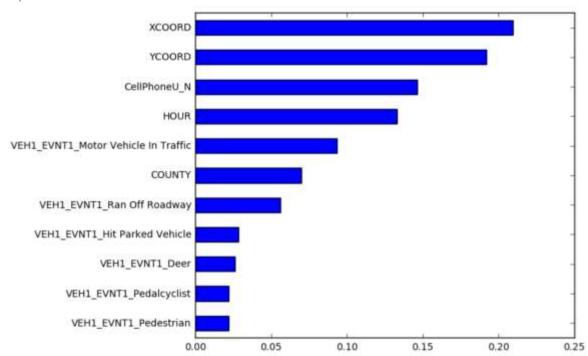
I used train-validation-test as I had a huge dataset and running cross validation on it would take a lot of time.

Performance Results

Model	Parameters	Performance(Accuracy)	Performance(AUC)
Baseline	majority class	78%	
Logistic regression		78.28%	64.14
Random Forest Classifier		84.75	76.45
Ada Classifier		87.47	88.094
Bagging Classifier		87.34	86.73
Extra Trees Classifier		86.5	84.79
Gradient Boosting		87.73	88.45
Gradient Boosting	Number of trees:500 Loss:deviance Learning Rate:.3 Max Depth: 3 Sample Split:2	88.4	89.41

Min Sample Leafs:10	
Sub Sample:1	
Max Features:auto	

Top Features



Discussion

The results wrt to a random guess look good. The classifier I tried to optimized did not show much performance improvement. Maybe I should have tried optimizing other classifiers which were close to it without any optimization.

Interesting/Unexpected Results

The interesting observation from this model was that major accidents are located over particular region. This was derived as the top important features were coordinates. This could help analyze an mark certain zone for careful driving and limits.

Contributions of Each Group Member

I did it alone

Conclusion

The overall project was interesting and was fun to apply the learning got from class also some of my learning from Data Science knowledge before. This also gave an amazing insight on how major accidents and their cause are co related. What causes these what hour of the day and so on.