

PROBLEM SET - 5

1) Given:

$$\left(\frac{1-\phi}{\phi}\right) \frac{c_t}{l_t} = (1-\alpha) \frac{y_t}{n_t}$$

$$E_{t-1} \left[\beta \frac{u(c_t, l_t)}{c_t} \left(\alpha \frac{y_t}{k_t} + (1-\delta) \right) \right] = \frac{u(c_{t-1}, l_{t-1})}{c_{t-1}}$$

$$y_t = z_t \cdot k_t^\alpha n_t^{1-\alpha}$$

①

$$1 = n_t + l_t$$

$$y_t = c_t + i_t$$

$$k_t = i_{t-1} + (1-\delta) k_{t-1}$$

$$u(c, l) = \frac{(c^\phi l^{1-\phi})^{1-\beta}}{1-\beta}$$

$$\ln(z_t) = (1-\beta) \ln \bar{z} + \beta \ln z_{t-1} + e_t$$

Performing steady state calculations:

$$\textcircled{1} \rightarrow \left(\frac{1-\phi}{\phi}\right) \frac{\bar{c}}{\bar{l}} = (1-\alpha) \frac{\bar{y}}{\bar{n}}$$

$$\therefore \left(\frac{1-\phi}{\phi}\right) \frac{\bar{c}}{\bar{n}} = \frac{\bar{l}}{\bar{n}} (1-\alpha) \frac{\bar{y}}{\bar{n}}$$

$$\textcircled{2} \rightarrow \beta \bar{c}^{-1} \left(\alpha \frac{\bar{y}}{\bar{k}} + (1-\delta) \right) = \bar{c}^{-1}$$

$$\frac{\bar{y}}{\bar{n}} \cdot \frac{\bar{k}}{\bar{n}} = \frac{\left(\frac{1}{\beta} - 1 + \delta\right)}{\alpha}$$

$$(3) \Rightarrow \frac{\bar{y}}{\bar{n}} = \left(\frac{\bar{k}}{\bar{n}} \right)^\alpha$$

$$\therefore \frac{\bar{k}}{\bar{n}} = \left[\frac{\frac{1}{\beta} - 1 + \delta}{\alpha} \right]^{\frac{1}{\alpha-1}} = \omega$$

$$(4) \Rightarrow 1 = \bar{n} + \bar{l}$$

$$(5) \Rightarrow \bar{y} = \bar{c} + \bar{l} = \bar{c} + \bar{i}$$

$$\frac{\bar{y}}{\bar{n}} = \frac{\bar{c}}{\bar{n}} + \frac{\bar{i}}{\bar{n}}$$

$$\therefore \omega^\alpha = \frac{\bar{c}}{\bar{n}} + \frac{\bar{i}}{\bar{n}}$$

$$(6) \Rightarrow \bar{y} = \bar{c} + \bar{l}$$

$$(6) \Rightarrow \bar{k} = \bar{i} + (1-\delta)\bar{k}$$

$$\therefore \bar{k} = \delta \frac{\bar{i}}{\bar{n}} = \frac{\bar{i}}{\bar{n}}$$

Solving the above 6 equations,

$$\left(\frac{\bar{k}}{\bar{i}} \right) = \left[\frac{1 - (1-\delta)}{\alpha\beta} \right]^{\frac{1}{\alpha-1}}$$

$$\frac{\bar{k}}{\bar{n}} = \left[\frac{\frac{1}{\beta} - 1 + \delta}{\alpha} \right]^{\frac{1}{\alpha-1}} = \omega \quad \text{--- I}$$

$$\frac{\bar{y}}{\bar{n}} = \left(\frac{\bar{k}}{\bar{n}} \right)^\alpha = \omega^\alpha \quad \text{--- II}$$

$$\bar{z} = \omega^\alpha - \delta \omega \quad \text{--- III}$$

$$\bar{z} = \delta \omega \quad \text{--- IV}$$

$$\frac{\bar{z}}{\bar{n}} = \frac{(1-\phi)}{\phi} \frac{\omega^\alpha - \delta \omega}{(1-\alpha)\omega^\alpha} = \tau \beta \quad \text{--- V}$$

$$\bar{k} = \omega \quad \text{--- VI I}$$

$$\textcircled{1} \rightarrow \bar{z} + \bar{k} = \bar{k}^\alpha \bar{n}^{(1-\alpha)} + (1-\delta)\bar{k}$$

$$\frac{1}{\beta} = (\alpha \bar{k}^{\alpha-1} \bar{n}^{1-\alpha} + 1 - \delta) \quad \text{--- (a)}$$

log linearization:

Now,

$$y_t = z_t k_t^\alpha n_t^{1-\alpha}$$

Applying log: $\ln y_t = \ln z_t + \alpha \ln k_t + (1-\alpha) \ln n_t$

Taylor Series: $\ln \bar{y} + \left(\frac{y_t - \bar{y}}{\bar{y}} \right)$
 $= \ln \bar{z} + \left(\frac{z_t - \bar{z}}{\bar{z}} \right) + \alpha \ln \bar{k} + \frac{\alpha}{\bar{k}} (k_t - \bar{k})$
 $+ (1-\alpha) \ln \bar{n} + \left(\frac{1-\alpha}{\bar{n}} \right) (n_t - \bar{n})$

In steady state:

$$\ln \bar{y} = \ln \bar{z} + \alpha \ln \bar{k} + (1-\alpha) \ln \bar{n}$$

Cancelling these terms in above eqⁿ:

$$\frac{y_t - \bar{y}}{\bar{y}} = \left(\frac{z_t - \bar{z}}{\bar{z}} \right) + \alpha \left(\frac{k_t - \bar{k}}{\bar{k}} \right) + (1-\alpha) \left(\frac{n_t - \bar{n}}{\bar{n}} \right)$$

$$\tilde{y}_t = \tilde{z} + \alpha \tilde{k}_t + (1-\alpha) \tilde{n}_t \quad \text{--- T3}$$

where $\tilde{y}_t = \frac{y_t - \bar{y}}{\bar{y}} = \text{Percentage deviation from steady state}$

Applying same steps as above,

$$\log: y_t = c_t + i_t$$

$$\log: \ln y_t = \ln(c_t + i_t)$$

$$\text{Applying Taylor} \Rightarrow \frac{y_t - \bar{y}}{\bar{y}} = \left(\frac{\bar{c}}{\bar{c} + \bar{i}} \right) \left(\frac{c_t - \bar{c}}{\bar{c}} \right) + \left(\frac{\bar{i}}{\bar{c} + \bar{i}} \right) \left(\frac{i_t - \bar{i}}{\bar{i}} \right)$$

$$\text{Steady state } \bar{y} = \bar{c} + \bar{i}$$

$$\tilde{y}_t = \frac{\bar{c}}{\bar{y}} \tilde{c}_t + \frac{\bar{i}}{\bar{y}} \tilde{i}_t \quad \text{--- T5}$$

$$\Rightarrow k_t = i_{t-1} + (1-\delta) k_{t-1}$$

$$\log: \ln k_t = \ln(i_{t-1} + (1-\delta) k_{t-1})$$

$$\text{Taylor: } \ln \bar{k} + \left(\frac{k_t - \bar{k}}{\bar{k}} \right) = \ln(i + (1-\delta)\bar{k}) + \frac{1}{(i + (1-\delta)\bar{k})} (i_{t-1} - i) + \frac{(1-\delta)}{(i + (1-\delta)\bar{k})} (k_{t-1} - \bar{k})$$

simplifying,

$$\tilde{k}_t = \frac{i}{\bar{k}} \tilde{i}_{t-1} + (1-\delta) \tilde{k}_{t-1} \quad \text{--- T6}$$

$$\Rightarrow 1 = n_t + l_t$$

$$\log: \ln(1) = \ln(n_t + l_t)$$

$$\ln(n_t + l_t) = 0$$

$$\text{Taylor: } \ln(\bar{n} + \bar{l}) + \frac{1}{(\bar{n} + \bar{l})} (n_t - \bar{n})$$

$$\text{At steady: } \bar{n} + \bar{l} = 1 \Rightarrow \ln(\bar{n} + \bar{l}) = \ln(1) = 0$$

$$\therefore \left(\frac{n_t - \bar{n}}{\bar{n}} \right) \cdot \left(\frac{\bar{n}}{\bar{n} + \bar{l}} \right) = \left(\frac{l_t - \bar{l}}{\bar{l}} \right) \times \frac{\bar{l}}{\bar{n} + \bar{l}} = 0$$

$$\therefore \bar{n} \tilde{n}_t + \bar{l} \tilde{l}_t = 0 \quad \longrightarrow \text{T4}$$

$$\Rightarrow \frac{(1-\phi)}{\phi} \frac{c_t}{l_t} = (1-\alpha) \frac{y_t}{n_t}$$

By following the same approach,

$$\frac{c_t - \bar{c}}{\bar{c}} = \frac{(l_t - \bar{l})}{\bar{l}} = \left(\frac{y_t - \bar{y}}{\bar{y}} \right) - \left(\frac{n_t - \bar{n}}{\bar{n}} \right)$$

$$\therefore \tilde{c}_t + \tilde{n}_t = \tilde{y}_t + \tilde{l}_t \quad \longrightarrow \text{T1}$$

$$\Rightarrow \ln(z_t) = (1-\delta) \ln \bar{z} + \beta \ln z_{t-1} + l_t$$

Removing steady states from both sides

$$\tilde{z}_t = \beta \tilde{z}_{t-1} + l_t \quad \longrightarrow \text{T8}$$

Now, from the above equations

$$E_{t-1} \left[\beta \cdot \left(\frac{1-\phi}{\phi} \right)^{-1} l_t^{(1-\phi)(1-\beta)} \left(\alpha z_t k_t^{\alpha-1} n_t^{1-\alpha} + 1 - \delta \right) \right]$$

$$= c_t \phi (1-\rho)^{-1} l_{t-1}^{(1-\phi)(1-\beta)}$$

Assume: $\phi(1-\delta) - 1 = \gamma$ & $(1-\phi)(1-\delta) = \lambda$

log: $\gamma \ln c_{t-1} + \lambda \ln l_{t-1} = \ln \beta + E_{t-1} [\gamma \ln c_t + \lambda \ln l_t + \ln(\alpha z_t + K_t^{\alpha-1} n_t^{1-\alpha} + 1-\delta)]$

Applying Taylor Series,

$$\begin{aligned} \ln(\alpha z_t K_t^{\alpha-1} n_t^{1-\alpha} + 1-\delta) &\approx \ln(\alpha \bar{K}^{\alpha-1} \bar{n}^{1-\alpha} + 1-\delta) \\ &+ \frac{\alpha \bar{K}^{\alpha-1} \bar{n}^{1-\alpha} (z_t - \bar{z})}{\alpha \bar{K}^{\alpha-1} \bar{n}^{1-\alpha} + 1-\delta} + \frac{\alpha(\alpha-1) \bar{K}^{\alpha-1} \bar{n}^{1-\alpha} (K_t - \bar{K})}{\alpha \bar{K}^{\alpha-1} \bar{n}^{1-\alpha} + 1-\delta} \\ &+ \frac{\alpha(\alpha-1) \bar{K}^{\alpha-2} \bar{n}^{1-\alpha} (n_t - \bar{n})}{\alpha \bar{K}^{\alpha-1} \bar{n}^{1-\alpha} + 1-\delta} \end{aligned}$$

$$\begin{aligned} \gamma \ln \bar{c} + \gamma \frac{(c_t - \bar{c})}{\bar{c}} + \lambda \ln \bar{l} + \lambda \frac{(l_t - \bar{l})}{\bar{l}} \\ = \ln \beta + E_{t-1} \left[\gamma \ln \bar{c} + \gamma \frac{(c_t - \bar{c})}{\bar{c}} + \lambda \ln \bar{l} + \lambda \frac{(l_t - \bar{l})}{\bar{l}} \right] \end{aligned}$$

Cancelling similar terms,

$$\begin{aligned} \gamma \tilde{c}_{t-1} + \lambda \tilde{l}_{t-1} &= E_{t-1} [\gamma \tilde{c}_t + \lambda \tilde{l}_t + (1 - (1-\delta)\beta) \tilde{z}_t \\ &+ (\alpha-1)(1-(1-\delta)\beta) \tilde{K}_t \\ &+ (1-\alpha)(1-(1-\delta)\beta) \tilde{n}_t] \end{aligned}$$

T1 T2

T1 to T8 are the log linearized system of eqⁿ using 1st order Taylor Series Expansion