# Harikrishna Dev HXD220000

```
In []: # If in Colab, then import the drive module from google.colab
        import sys
        if 'google.colab' in str(get_ipython()):
          from google.colab import drive
          # Mount the Google Drive to access files stored there
          drive.mount('/content/drive')
          # Install the latest version of torchtext library quietly without showing
          !pip install torchtext -qq
          # Install the torchinfo library quietly
          !pip install torchinfo -qq
          # !pip install torchtext --upgrade -qq
          !pip install torchmetrics -qq
          !pip install torchinfo -qq
          !pip install fast_ml -qq
          !pip install joblib -qq
          !pip install sklearn -qq
          !pip install pandas -qq
          !pip install numpy -qq
          !pip install scikit-multilearn -qq
          !pip install transformers evaluate wandb accelerate -U -qq
          !pip install pytorch-ignite -qq -U
          basepath = '/content/drive/MyDrive/Colab Notebooks/BUAN 6342 Applied Natur
          sys.path.append('/content/drive/MyDrive/Colab_Notebooks/BUAN_6342_Applied_
        else:
          basepath = '/Users/harikrishnadev/Library/CloudStorage/GoogleDrive-harikri
          sys.path.append('/Users/harikrishnadev/Library/CloudStorage/GoogleDrive-ha
          # !pip install torchtext -qq
          # # Install the torchinfo library quietly
          # !pip install torchinfo -qq
          # !pip install torchtext --upgrade -qq
          # !pip install torchmetrics -qq
          # !pip install torchinfo -qq
          # !pip install fast_ml -qq
          # !pip install joblib -qq
          # !pip install sklearn -qq
          # !pip install pandas -qq
          # !pip install numpy -qq
          # !pip install scikit-multilearn -qq
          # !pip install transformers evaluate wandb accelerate -U -qq
```

Drive already mounted at /content/drive; to attempt to forcibly remount, cal l drive.mount("/content/drive", force\_remount=True). error: subprocess-exited-with-error x python setup.py egg\_info did not run successfully. exit code: 1 See above for output. note: This error originates from a subprocess, and is likely not a problem

with pip.

Preparing metadata (setup.py) ... error

error: metadata-generation-failed

× Encountered error while generating package metadata. See above for output.

note: This is an issue with the package mentioned above, not pip. hint: See above for details.

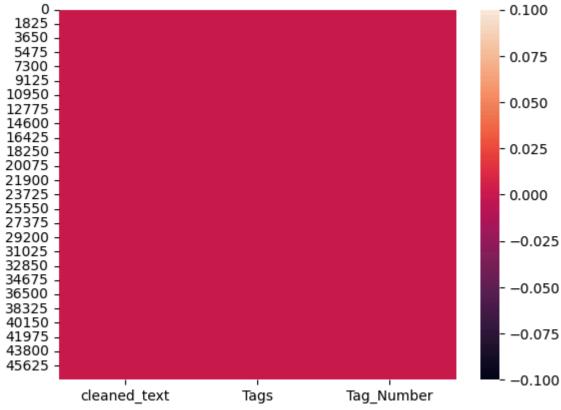
Import Libraries

```
In [ ]: # Importing PyTorch library for tensor computations and neural network modul
        import torch
        import torch.nn as nn
        # For working with textual data vocabularies and for displaying model summar
        from torchtext.vocab import vocab
        from torchinfo import summary
        # General-purpose Python libraries for random number generation and numerica
        import random
        import numpy as np
        # Utilities for efficient serialization/deserialization of Python objects an
        import joblib
        from collections import Counter
        # For creating lightweight attribute classes and for partial function applic
        from functools import partial
        # For filesystem path handling, generating and displaying confusion matrices
        from pathlib import Path
        from sklearn.metrics import confusion matrix
        from datetime import datetime
        # For plotting and visualization
        import matplotlib.pyplot as plt
        import seaborn as sns
        # Printing: Import the pprint function from the pprint module for formatted
        from pprint import pprint
```

```
In [ ]: # Set the base folder path using the Path class for better path handling
         base_folder = Path(basepath)
         # Define the data folder path by appending the relative path to the base fol
         # This is where the data files will be stored
         data_folder = base_folder / '0_Data_Folder'
         # Define the model folder path for saving trained models
         # This path points to a specific folder designated for NLP models related to
         model_folder = data_folder
         custom_functions = base_folder / '0_Custom_files'
In []: # Create the model folder directory. If it already exists, do nothing.
         # The 'parents=True' argument ensures that all parent directories are create
         model_folder.mkdir(exist_ok=True, parents=True)
         # Create the data folder directory in a similar manner.
         data_folder.mkdir(exist_ok=True, parents=True)
In [ ]: X_train_cleaned_file = data_folder / 'df_multilabel_hw_cleaned.joblib'
         data = joblib.load(X_train_cleaned_file)
In [ ]: data.head()
Out[]:
                                           cleaned_text
                                                                  Tags Tag_Number
         0 asp guery stre dropdown webpage follow control...
                                                             c# asp.net
                                                                               [0, 9]
         1
              run javascript code server java code want run ...
                                                         java javascript
                                                                               [1, 3]
         2
                ling sql throw exception row find change hi li...
                                                             c# asp.net
                                                                               [0, 9]
         3
              run python script php server run nginx web ser...
                                                                               [2, 7]
                                                             php python
         4
               advice write function m try write function res... javascript jquery
                                                                               [3, 5]
In [ ]: data.describe()
Out[]:
                                          cleaned_text
                                                                 Tags Tag_Number
          count
                                                 47427
                                                                47427
                                                                              47427
         unique
                                                 36481
                                                                  176
                                                                                176
            top cause error targetcontrolid valid value null... javascript jquery
                                                                              [3, 5]
                                                     3
                                                                19989
                                                                             19989
           freq
In [ ]: import seaborn as sns
```

sns.heatmap(data.isnull())

Out[]: <Axes: >



```
In [ ]: data['Tag_Number'].info()
       <class 'pandas.core.series.Series'>
       RangeIndex: 47427 entries, 0 to 47426
       Series name: Tag_Number
       Non-Null Count Dtype
       47427 non-null object
       dtypes: object(1)
       memory usage: 370.6+ KB
In [ ]: data.columns
Out[]: Index(['cleaned_text', 'Tags', 'Tag_Number'], dtype='object')
In [ ]: # def extract_and_combine(row):
              langs = row['Tags'].split()
              tags = row['Tag_Number']
              return [f'{lang} {tag}' for lang, tag in zip(langs, tags)]
        # result = data.apply(extract and combine, axis=1)
        # result
In [ ]: import ast
        y_{tag} = []
        x = []
        for i in range(data.shape[0]):
            y_tag.append(ast.literal_eval(data['Tag_Number'][i]))
            x.append(str(data['cleaned_text'][i]))
```

```
x = np.array(x).reshape(-1,1)
In [ ]: x[:5]
Out[]: array([['asp query stre dropdown webpage follow control relevance
                                                                              dropdo
        wnlist value hyperlink redirect page call
                                                    page cancel button redirect use
        r menu page like user click hyperlink edit page index dropdownlist preserve
        query string page follow aspx code sure proceed < asp hyperlink
                   navigateurl=\'<% + eval("userid + sure > < /asp hyperlink >
                               id="mydropdown
                                                  < asp listitems/ > < /asp dropdow</pre>
        asp dropdownlist
        nlist >
                  edit clarify m navigateurl query string eval determine user id'],
                ['run javascript code server java code want run javascript code serv
        er want manipulate result return javascript inside java code'],
                ['ling sql throw exception row find change hi ling sql get error row
        find change update table help ling query show error unable figure problem w
        ork get permanent solution fix problem twtmob campainincomedetails tb incom
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        empt briefly work sure file < body >
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                                        print hello world
                                                            clue appreciate"],
        ('python > 
                            < /body >
                ["advice write function m try write function resize css width elemen
        t browser window resize right not get thing right love help m go wrong code
        far function windowresize
                                                $ content').css('width $ windowwidth
        $ div.mysection').css('width $ windowwidth
                                                                 $ div.mysection .st
        ory').css('width $ windowwidth
                                                   $ document).ready(function
        var $ windowwidth = $ window).width
                                                                          $ window).
        resize(function
                                         windowresize
                                                                                m su
        re place correct place advise code well great thank kyle"]],
              dtype='<U30141')
In [ ]: y_tag[:5]
Out[]: [[0, 9], [1, 3], [0, 9], [2, 7], [3, 5]]
In [ ]: from sklearn.preprocessing import MultiLabelBinarizer
        mlb = MultiLabelBinarizer()
        y = mlb.fit transform(y tag)
        print(type(y) , y.shape)
        print(type(x) , x.shape)
       <class 'numpy.ndarray'> (47427, 10)
       <class 'numpy.ndarray'> (47427, 1)
```

```
In []: y[:5]
Out[]: array([[1, 0, 0, 0, 0, 0, 0, 0, 0, 1],
                [0, 1, 0, 1, 0, 0, 0, 0, 0, 0],
                [1, 0, 0, 0, 0, 0, 0, 0, 0, 1],
                [0, 0, 1, 0, 0, 0, 0, 1, 0, 0],
                [0, 0, 0, 1, 0, 1, 0, 0, 0, 0]]
In [ ]: |type(x)
Out[]: numpy.ndarray
In [ ]: from sklearn.model_selection import train_test_split
        # Split the data into training and testing sets
        X_train, X_test, y_train, y_test = train_test_split(x, y, test_size=0.2, ran
        # Further split the testing set into validation and testing sets
        X_valid, X_test, y_valid, y_test = train_test_split(X_test, y_test, test_siz
In [ ]: class CustomDataset(torch.utils.data.Dataset):
            Custom Dataset class for loading text and labels.
            Attributes:
                X (numpy.ndarray): Feature data, an array of texts.
                y (list or array-like): Target labels.
            def __init__(self, X, y):
                Initialize the dataset with feature and target data.
                Args:
                    X (list or array-like): The feature data (texts).
                    y (list or array-like): The target labels.
                # Storing feature data (texts)
                self.X = X
                # Storing the target labels
                self.y = y
            def __len__(self):
                Return the number of samples in the dataset.
                Returns:
                    int: The total number of samples.
                return len(self.X)
            def __getitem__(self, idx):
                Fetch and return a single sample from the dataset at the given index
```

```
Args:
                    idx (int): Index of the sample to fetch.
                Returns:
                    tuple: A tuple containing the label and the text for the sample.
                # Retrieve the text and corresponding label from the dataset using t
                texts = self.X[idx]
                labels = self.y[idx]
                # Packing them into a tuple before returning
                sample = (labels, texts)
                return sample
In [ ]: # Create an instance of the CustomDataset class for the training set
        # This uses the cleaned training data and corresponding labels
        trainset = CustomDataset(X_train, y_train)
        # Create an instance of the CustomDataset class for the validation set
        # This uses the cleaned validation data and corresponding labels
        validset = CustomDataset(X_valid, y_valid)
        # Create an instance of the CustomDataset class for the test set
        # This uses the cleaned test data and corresponding labels
        testset = CustomDataset(X_test, y_test)
In [ ]: def get_vocab(dataset, min_freq=1):
            Generate a vocabulary from a dataset.
            Args:
                dataset (list of tuple): List of tuples where each tuple contains a
                min_freq (int): The minimum frequency for a token to be included in
            Returns:
                torchtext.vocab.Vocab: Vocabulary object.
            # Initialize a counter object to hold token frequencies
            counter = Counter()
            # Update the counter with tokens from each text in the dataset
            for (_, text) in dataset:
                counter.update(str(text).split())
            # Create a vocabulary using the counter object
            # Tokens that appear fewer times than `min_freq` are excluded
            my_vocab = vocab(counter, min_freq=min_freq)
            # Insert a '<unk>' token at index 0 to represent unknown words
            my vocab.insert token('<unk>', 0)
            # Set the default index to 0
            # This ensures that any unknown word will be mapped to '<unk>'
```

```
my_vocab.set_default_index(0)
            return my vocab
In [ ]: | code_vocab = get_vocab(trainset,min_freq=2)
In [ ]: len(code_vocab)
Out[]: 123505
In [ ]: code_vocab.get_itos()[0:5]
Out[]: ['<unk>', "['javascript", 'operator', 'puzzle', 'friend']
In [ ]: # Creating a function that will be used to get the indices of words from voc
        def tokenizer(x, vocab):
            """Converts text to a list of indices using a vocabulary dictionary"""
            return [vocab[token] for token in str(x).split()]
In [ ]: def collate batch(batch, my vocab):
            Collates a batch of samples into tensors of labels, texts, and offsets.
            Parameters:
                batch (list): A list of tuples, each containing a label and a text.
            Returns:
                tuple: A tuple containing three tensors:
                       - Labels tensor
                       - Concatenated texts tensor
                       - Offsets tensor indicating the start positions of each text
            # Unpack the batch into separate lists for labels and texts
            labels, texts = zip(*batch)
            # Convert the list of labels into a tensor of dtype int32
            labels = torch.tensor(labels, dtype=torch.float32)
            # Convert the list of texts into a list of lists; each inner list contai
            list_of_list_of_indices = [tokenizer(text, my_vocab) for text in texts]
            # Compute the offsets for each text in the concatenated tensor
            offsets = [0] + [len(i) for i in list of list of indices]
            offsets = torch.tensor(offsets[:-1]).cumsum(dim=0)
            # Concatenate all text indices into a single tensor
            texts = torch.cat([torch.tensor(i, dtype=torch.int64) for i in list_of_l
            return (texts, offsets), labels
In [ ]: batch size = 2
        collate_partial = partial(collate_batch, my_vocab = code_vocab)
        check loader = torch.utils.data.DataLoader(dataset=trainset,
                                                   batch_size=batch_size,
```

```
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0,
          157, 29591]) tensor([ 0, 39]) tensor([[0., 0., 0., 1., 0., 1., 0.,
0., 0., 0.],
         [0., 0., 0., 1., 0., 1., 0., 0., 0., 0.]])
```

```
<ipython-input-26-23e46644e366>:18: UserWarning: Creating a tensor from a li
st of numpy.ndarrays is extremely slow. Please consider converting the list
to a single numpy.ndarray with numpy.array() before converting to a tensor.
(Triggered internally at ../torch/csrc/utils/tensor_new.cpp:261.)
    labels = torch.tensor(labels, dtype=torch.float32)
```

```
In [ ]: class CustomBlock(nn.Module):
            def __init__(self, input_dim, output_dim, drop_prob):
                super().__init__()
                self.layers = nn.Sequential(
                    nn.Linear(input_dim, output_dim),
                    nn.BatchNorm1d(num features=output dim),
                    nn.ReLU(),
                    nn.Dropout(p=drop_prob),
                )
            def forward(self, x):
              return self.layers(x)
        class EmbeddingBagWrapper(nn.Module):
            def __init__(self, vocab_size, embedding_dim):
                super(). init ()
                self.embedding_bag = nn.EmbeddingBag(vocab_size, embedding_dim)
            def forward(self, input tuple):
                data, offsets = input tuple
                return self.embedding_bag(data, offsets)
```

```
In [ ]: from functools import partial
        # Define hyperparameters
        EMBED_DIM = 300
        VOCAB SIZE = len(code vocab)
        OUTPUT DIM = 10
        HIDDEN_DIM1 = 200
        HIDDEN DIM2 = 100
        OUTPUT DIM = 10
        EPOCHS = 5
        BATCH_SIZE = 128
        LEARNING RATE = 0.001
        WEIGHT DECAY = 0.0001
        CLIP TYPE = 'value'
        CLIP_VALUE = 10
        PATIENCE = 5
        dropout p = 0.3
        # Define collate function
        collate fn = partial(collate batch, my vocab=code vocab)
```

```
In []: import torch.optim as optim
    from torch.utils.data import DataLoader
    from tqdm import tqdm
# Define the model
```

```
# Define the sequential model
       vocab size = len(code vocab)
       model = nn.Sequential(
           EmbeddingBagWrapper(vocab_size, EMBED_DIM),
           CustomBlock(EMBED_DIM , HIDDEN_DIM1, 0.5),
           CustomBlock(HIDDEN_DIM1, HIDDEN_DIM2, 0.5),
           nn.Linear(HIDDEN_DIM2, OUTPUT_DIM)
           )
In [ ]: summary(model)
Out[]: =========
        Layer (type:depth-idx)
                                              Param #
        Sequential
        -EmbeddingBagWrapper: 1-1
             └─EmbeddingBag: 2-1
                                              37,051,500
         -CustomBlock: 1-2
             └─Sequential: 2-2
                 └Linear: 3-1
                                             60,200
                 └─BatchNorm1d: 3-2
                                             400
                 └─ReLU: 3-3
                 └─Dropout: 3-4
         -CustomBlock: 1-3
                                              __
             └─Sequential: 2-3
                 Linear: 3-5
                                             20,100
                 └─BatchNorm1d: 3-6
                                              200
                 └─ReLU: 3-7
                                              ___
                 └─Dropout: 3-8
                                              __
        —Linear: 1-4
                                              1,010
        ______
        Total params: 37,133,410
        Trainable params: 37,133,410
        Non-trainable params: 0
In [ ]: # torch.cuda.empty_cache()
In [ ]: # Define the device
       device = torch.device('cuda:0' if torch.cuda.is_available() else 'cpu')
       # Move the model to the device
       model = model.to(device)
       # Generate some dummy input data and offsets, and move them to the device
       data = torch.randint(0, 10, (5,), dtype=torch.int32, device=device)
       offsets = torch.randint(0, 10, (3,), dtype=torch.int32, device=device)
In [ ]: output = model((data, offsets))
       print(output)
```

```
In []: from torchmetrics import HammingDistance
        def step(inputs, targets, model, device, loss_function=None, optimizer=None)
            Performs a forward and backward pass for a given batch of inputs and tar
            Parameters:
            - inputs (torch.Tensor): The input data for the model.
            - targets (torch.Tensor): The true labels for the input data.
            - model (torch.nn.Module): The neural network model.
            - device (torch.device): The computing device (CPU or GPU).
            - loss_function (torch.nn.Module, optional): The loss function to use.
            - optimizer (torch.optim.Optimizer, optional): The optimizer to update m
            Returns:
            - loss (float): The computed loss value (only if loss_function is not No
            - outputs (torch. Tensor): The predictions from the model.
            - train hamming distance (torchmetrics.HammingDistance): The Hamming dis
            # Move the model and data to the device
            model = model.to(device)
            inputs, targets = tuple(input_tensor.to(device) for input_tensor in input
            # Step 1: Forward pass to get the model's predictions
            outputs = model(inputs)
            # Step 2a: Compute the loss using the provided loss function
            if loss function:
                loss = loss function(outputs, targets)
            # Step 2b: Update Hamming Distance metric
            train_hamming_distance = HammingDistance(task="multilabel", num_labels=1
            y pred = (outputs > 0.5).float()
            train_hamming_distance.update(y_pred, targets)
            # Step 3 and 4: Perform backward pass and update model parameters if an
            if optimizer:
                optimizer.zero grad()
                loss.backward()
                optimizer.step()
            # Return relevant metrics
            if loss function:
                return loss, outputs, train_hamming_distance
            else:
                return outputs, train_hamming_distance
In [ ]: def train_epoch(train_loader, model, device, loss_function, optimizer):
            Trains the model for one epoch using the provided data loader and update
            Parameters:
            - train loader (torch.utils.data.DataLoader): DataLoader object for the
            - model (torch.nn.Module): The neural network model to be trained.
```

device (torch.device): The computing device (CPU or GPU).

```
Returns:
            - train_loss (float): Average training loss for the epoch.
            - epoch hamming distance (float): Hamming distance for the epoch.
            # Set the model to training mode
            model.train()
            # Initialize variables to track running training loss and correct predic
            running train loss = 0.0
            running train correct = 0
            # Initialize Hamming Distance metric
            hamming = HammingDistance(task="multilabel", num_labels=10).to(device)
            # Iterate over all batches in the training data
            for inputs, targets in train_loader:
                # Move data to the appropriate device
                inputs, targets = tuple(input_tensor.to(device) for input_tensor in
                # Perform a forward and backward pass, updating model parameters
                loss, _, _ = step(inputs, targets, model, device, loss_function, opt
                # Update running loss
                running_train_loss += loss.item()
                # Compute Hamming Distance for the epoch
                y_pred = (model(inputs) > 0.5).float()
                hamming.update(y pred, targets)
            # Compute average loss for the entire training set
            train loss = running train loss / len(train loader)
            # Compute Hamming Distance for the epoch
            epoch hamming distance = hamming.compute()
            return train_loss, epoch_hamming_distance
In [ ]: from torchmetrics import HammingDistance
        def val_epoch(valid_loader, model, device, loss_function):
            Validates the model for one epoch using the provided data loader.
            Parameters:
            - valid loader (torch.utils.data.DataLoader): DataLoader object for the
            - model (torch.nn.Module): The neural network model to be validated.
            - device (torch.device): The computing device (CPU or GPU).

    loss function (torch.nn.Module): The loss function to evaluate the mod

            Returns:
            - val loss (float): Average validation loss for the epoch.
            - val_hamming_distance (float): Hamming distance for the epoch.
```

loss\_function (torch.nn.Module): The loss function to use for trainingoptimizer (torch.optim.Optimizer): The optimizer to update model param

```
# Set the model to evaluation mode
model.eval()
# Initialize variables to track running validation loss and Hamming Dist
running_val_loss = 0.0
val hamming distance = HammingDistance(task="multilabel", num labels=10)
# Disable gradient computation
with torch.no grad():
    # Iterate over all batches in the validation data
    for inputs, targets in valid_loader:
        # Move data to the appropriate device
        inputs, targets = tuple(input tensor.to(device) for input tensor
        # Perform a forward pass to get loss and number of correct predi
        outputs = model(inputs)
        loss = loss_function(outputs, targets)
        # Update running loss
        running val loss += loss.item()
        # Update Hamming Distance metric
        val_hamming_distance.update(torch.round(torch.sigmoid(outputs)),
# Compute average loss and Hamming Distance for the entire validation se
val loss = running val loss / len(valid loader)
val_hamming_distance = val_hamming_distance.compute()
return val_loss, val_hamming_distance
```

# 7.4. train() function

```
In [ ]: def train(train_loader, valid_loader, model, optimizer, loss_function, epoch
            Trains and validates the model, and returns history of train and validat
            Parameters:
            - train loader (torch.utils.data.DataLoader): DataLoader for the training
            valid loader (torch.utils.data.DataLoader): DataLoader for the validat
            - model (torch.nn.Module): Neural network model to train.
            optimizer (torch.optim.Optimizer): Optimizer algorithm.
            - loss_function (torch.nn.Module): Loss function to evaluate the model.
            - epochs (int): Number of epochs to train the model.
            - device (torch.device): The computing device (CPU or GPU).
            - patience (int): Number of epochs to wait for improvement before early
            Returns:
            - train_loss_history (list): History of training loss for each epoch.
            - train_hamm_history (list): History of training Hamming distance for ea
            - valid loss history (list): History of validation loss for each epoch.
            - valid_hamm_history (list): History of validation Hamming distance for
            # Initialize lists to store metrics for each epoch
```

```
valid_loss_history = []
            train hamm history = []
            valid_hamm_history = []
            # Initialize variables for early stopping
            best_valid_loss = float('inf')
            no_improvement = 0
            # Loop over the number of specified epochs
            for epoch in range(epochs):
                # Train model on training data and capture metrics
                train_loss, train_hamm = train_epoch(
                    train_loader, model, device, loss_function, optimizer)
                # Validate model on validation data and capture metrics
                valid_loss, valid_hamm = val_epoch(
                    valid_loader, model, device, loss_function)
                # Store metrics for this epoch
                train_loss_history.append(train_loss)
                valid_loss_history.append(valid_loss)
                train_hamm_history.append(train_hamm)
                valid_hamm_history.append(valid_hamm)
                # Output epoch-level summary
                print(f"Epoch {epoch+1}/{epochs}")
                print(f"Train Loss: {train_loss:.4f} | Train Hamming Distance: {trai
                print(f"Valid Loss: {valid_loss:.4f} | Valid Hamming Distance: {vali
                print()
                # Check for early stopping
                if valid_loss < best_valid_loss:</pre>
                    best_valid_loss = valid_loss
                    no_improvement = 0
                else:
                    no_improvement += 1
                    if no improvement == patience:
                        print(f"No improvement for {patience} epochs. Early stopping
                        break
            return train_loss_history, train_hamm_history, valid_loss_history, valid
In [ ]: # training
        EPOCHS=5
        BATCH SIZE=128
        LEARNING_RATE=0.001
        WEIGHT DECAY=0.0
        PATIENCE=10
In [ ]: # Fixing the seed value for reproducibility across runs
        SEED = 2345
        random.seed(SEED)
                                              # Set seed for Python's 'random' modul
        np.random.seed(SEED)
                                             # Set seed for NumPy's random number g
        torch.manual seed(SEED)
                                             # Set seed for PyTorch's CPU operation
```

train\_loss\_history = []

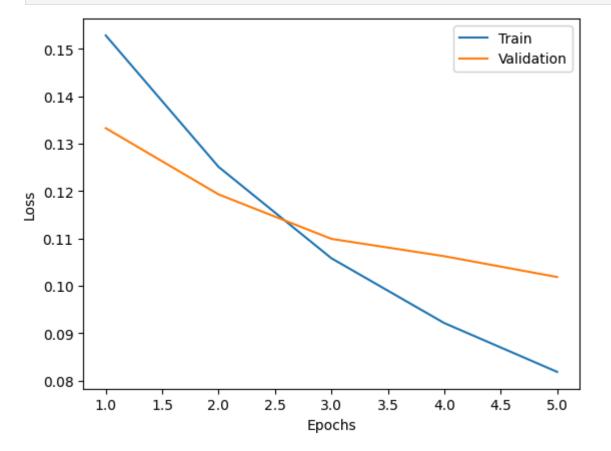
```
torch.cuda.manual_seed(SEED) # Set seed for PyTorch's CUDA (GPU) op
        torch.backends.cudnn.deterministic = True # Ensure deterministic behavior i
        # Define collate function with a fixed vocabulary using the 'partial' functi
        collate_fn = partial(collate_batch, my_vocab=code_vocab)
        # Define the device for model training (use CUDA if available, else CPU)
        device = torch.device('cuda:0' if torch.cuda.is_available() else 'cpu')
        # Data Loaders for training, validation, and test sets
        # These loaders handle batching, shuffling, and data processing using the cu
        train loader = torch.utils.data.DataLoader(trainset, batch size = BATCH SIZE
                                                   collate fn=collate fn, num worker
        valid loader = torch.utils.data.DataLoader(validset, batch size=BATCH SIZE,
                                                   collate fn=collate fn, num worker
        test_loader = torch.utils.data.DataLoader(testset, batch_size=BATCH_SIZE, sh
                                                  collate_fn=collate_fn, num_workers
        # Define the loss function for the model, using cross-entropy loss
        loss_function = nn.BCEWithLogitsLoss()
        # Define the model with specified hyperparameters
        vocab_size = len(code_vocab)
        model = nn.Sequential(
            EmbeddingBagWrapper(vocab size, EMBED DIM),
            CustomBlock(EMBED DIM , HIDDEN DIM1, 0.5),
            CustomBlock(HIDDEN_DIM1, HIDDEN_DIM2, 0.5),
            nn.Linear(HIDDEN_DIM2, OUTPUT_DIM)
        model = model.to(device)
        # Define the optimizer
        optimizer = optim.AdamW(model.parameters(), lr=LEARNING_RATE, weight_decay=W
In [ ]: for inputs, targets in train loader:
            # Move inputs and targets to the CPU.
            inputs = tuple(input_tensor.to(device) for input_tensor in inputs)
            targets = targets.to(device)
            model = model.to(device)
            model.eval()
            # Forward pass
            with torch.no grad(): # Ensure no gradients are calculated since this i
                output = model(inputs)
                loss = loss_function(output, targets)
                print(f'Actual loss: {loss.item()}')
            break
        print(f'Expected Theoretical loss: {np.log(2)}')
       Actual loss: 0.6948241591453552
       Expected Theoretical loss: 0.6931471805599453
In [ ]: CLIP VALUE = 10
        # Call the train function to train the model
        train_losses, train_hamm, valid_losses, valid_hamm = train(
```

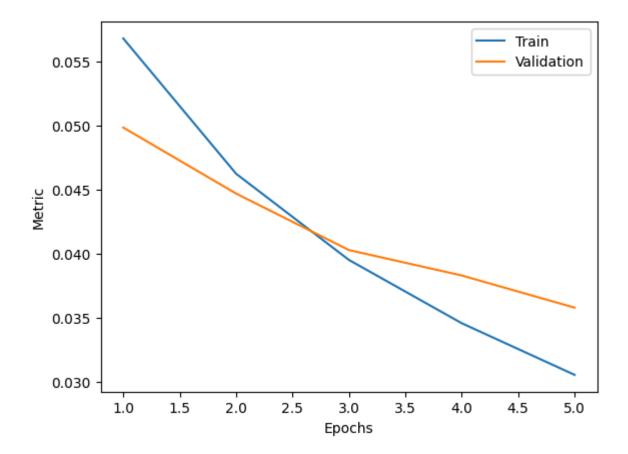
```
train_loader, valid_loader, model, optimizer, loss_function, EPOCHS, dev
Epoch 1/5
Train Loss: 0.1528 | Train Hamming Distance: 0.0568
Valid Loss: 0.1332 | Valid Hamming Distance: 0.0498
Epoch 2/5
Train Loss: 0.1251 | Train Hamming Distance: 0.0462
Valid Loss: 0.1193 | Valid Hamming Distance: 0.0447
Epoch 3/5
Train Loss: 0.1058 | Train Hamming Distance: 0.0395
Valid Loss: 0.1099 | Valid Hamming Distance: 0.0403
Epoch 4/5
Train Loss: 0.0921 | Train Hamming Distance: 0.0346
Valid Loss: 0.1062 | Valid Hamming Distance: 0.0383
Epoch 5/5
Train Loss: 0.0818 | Train Hamming Distance: 0.0305
Valid Loss: 0.1018 | Valid Hamming Distance: 0.0358
```

#### Plot losses and metrics

```
In [ ]: def plot_history(train_losses, train_metrics, val_losses=None, val_metrics=N
            Plot training and validation loss and metrics over epochs.
            Args:
                train_losses (list): List of training losses for each epoch.
                train_metrics (list): List of training metrics (e.g., accuracy) for
                val_losses (list, optional): List of validation losses for each epoc
                val metrics (list, optional): List of validation metrics for each ep
            Returns:
                None
            # Determine the number of epochs based on the length of train losses
            epochs = range(1, len(train losses) + 1)
            # Plotting training and validation losses
            plt.figure()
            plt.plot(epochs, train_losses, label="Train") # Plot training losses
            if val losses: # Check if validation losses are provided
                plt.plot(epochs, val_losses, label="Validation") # Plot validation
            plt.xlabel("Epochs")
            plt.ylabel("Loss")
            plt.legend()
            plt.show()
            # Plotting training and validation metrics
            if train_metrics[0] is not None: # Check if training metrics are availa
                plt.figure()
                plt.plot(epochs, train_metrics, label="Train") # Plot training metri
```

```
import numpy as np
# Plot the training and validation losses and metrics
train_hamm_np = [ham.cpu().numpy() for ham in train_hamm]
valid_hamm_np = [ham.cpu().numpy() for ham in valid_hamm]
plot_history(train_losses, train_hamm_np, valid_losses, valid_hamm_np)
```





### **Model Checkpointing**

```
In []: # Get the current timestamp in the format "YYYY-MM-DD_HH-MM-SS"
    timestamp = datetime.now().strftime("%Y-%m-%d_%H-%M-%S")

# Define a suffix for the file name
    suffix = 'twolayer'

# Combine the timestamp and suffix to create the file path
    path = model_folder / f'{timestamp}_{suffix}.pt'
    path

Out[]: PosixPath('/content/drive/MyDrive/Colab_Notebooks/BUAN_6342_Applied_Natural
    _Language_Processing/0_Data_Folder/2024-03-04_01-26-38_twolayer.pt')
In []: # Save the model's state dictionary to the specified file path
```

### **Evaluate model on validation dataset**

torch.save(model.state\_dict(), path)

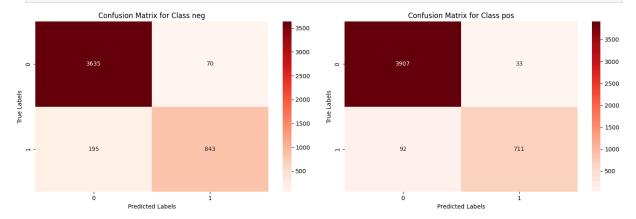
We will now plot the confusion matrix to understand the performance of our model in more detail, particularly how well it classifies each class. For thet, we first need to get the predictions and labels.

```
Output: predictions and accuracy for the given dataset
            model = model.to(device)
            # Set model to evaluation mode
            model.eval()
            # Create empty tensors to store predictions and actual labels
            predictions = torch.Tensor().to(device)
            y = torch.Tensor().to(device)
            # Iterate over batches from data iterator
            with torch.no grad():
                for inputs, targets in data_loader:
                    # Process the batch to get the loss, outputs, and correct predic
                    outputs, _ = step(inputs, targets, model,
                                      device, loss function=None, optimizer=None)
                    # Choose the label with maximum probability
                    # Correct prediction using thresholding
                    y pred = (outputs.data>0.5).float()
                    # Add the predicted labels and actual labels to their respective
                    predictions = torch.cat((predictions, y_pred))
                    y = torch.cat((y, targets.to(device)))
            # Calculate accuracy by comparing the predicted and actual labels
            accuracy = (predictions == y).float().mean()
            # Return tuple containing predictions and accuracy
            return predictions, accuracy, y
In [ ]: # Get the prediction and accuracy
        predictions_test, acc_test, y_test = get_acc_pred(test_loader, model, device
        predictions_train, acc_train, y_train = get_acc_pred(train_loader, model, de
        predictions valid, acc valid, y valid = get acc pred(valid loader, model, de
In [ ]: # Print Test Accuracy
        print('Valid accuracy', acc_valid * 100)
       Valid accuracy tensor(96.3040, device='cuda:0')
In [ ]: from sklearn.metrics import multilabel confusion matrix
        def plot_confusion_matrix(valid_labels, valid_preds, class_labels):
            Plots a confusion matrix.
            Args:
                valid labels (array-like): True labels of the validation data.
                valid_preds (array-like): Predicted labels of the validation data.
                class_labels (list): List of class names for the labels.
            # Compute the confusion matrix
            cm = multilabel_confusion_matrix(valid_labels, valid_preds)
            # Plot the confusion matrix using Seaborn
```

```
fig, axs = plt.subplots(1, len(class_labels), figsize=(15, 5))
for i, (label, matrix) in enumerate(zip(class_labels, cm)):
    sns.heatmap(matrix, annot=True, fmt="d", cmap="Reds", xticklabels=['
    axs[i].set_title(f"Confusion Matrix for Class {label}")
    axs[i].set_xlabel('Predicted Labels')
    axs[i].set_ylabel('True Labels')

# Display the plot
plt.tight_layout()
plt.show()
```

In []: plot\_confusion\_matrix(y\_test.cpu().numpy(), predictions\_test.cpu().numpy(),



```
In [ ]: test_hamming_distance = HammingDistance(task="multilabel", num_labels=10).to
    test_hamming_distance.update(y_test, predictions_test)
```

```
In [ ]: test_hamming_distance.compute()
```

Out[]: tensor(0.0356, device='cuda:0')