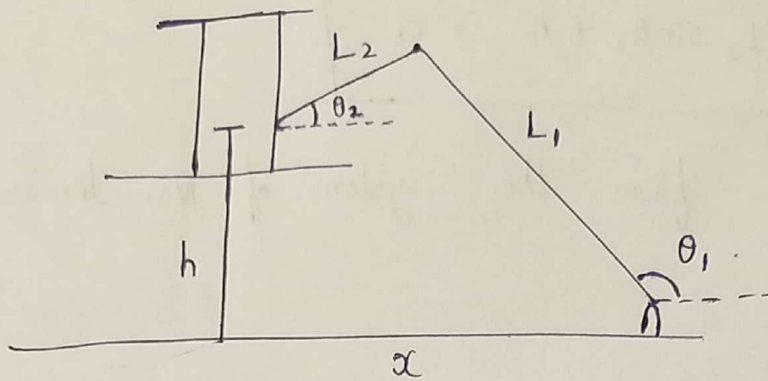


2.)

a.)



Develop the non linear system of equations for the position of the bars.

$$\bar{L}_1 + \bar{L}_2 + \bar{h} + \bar{x} = 0 \quad (\text{Vector Addition})$$

$$\bar{L}_1 = L_1 \cdot e^{i\theta_1}, \quad \bar{L}_2 = L_2 \cdot e^{i\theta_2}$$

$$\bar{h} = h \cdot e^{i\pi/2}, \quad \bar{x} = x \cdot e^{i0}$$

$$\text{Therefore, } L_1 \cdot e^{i\theta_1} + L_2 \cdot e^{i\theta_2} + h \cdot e^{i\pi/2} + x \cdot e^{i0} = 0.$$

$$L_1 (\cos \theta_1 + i \sin \theta_1) + L_2 (\cos \theta_2 + i \sin \theta_2) + h (\cos \frac{\pi}{2} + i \sin (\frac{\pi}{2})) + x (\cos 0 + i \sin 0) = 0.$$

$$\left[L_1 (\cos \theta_1) + L_2 \cos \theta_2 + h \cos \frac{\pi}{2} + x \cos 0 \right] + i \left[L_1 \sin \theta_1 + L_2 \sin \theta_2 + h \sin \frac{\pi}{2} + x \sin 0 \right] = 0$$

$$\left[L_1 \cos \theta_1 + L_2 \cos \theta_2 + x \right] + i \left[L_1 \sin \theta_1 + L_2 \sin \theta_2 + h \right] = 0$$

$$\Rightarrow \begin{cases} L_1 \cos \theta_1 + L_2 \cos \theta_2 + x = 0 \\ L_1 \sin \theta_1 + L_2 \sin \theta_2 + h = 0 \end{cases}$$

These form the system of Non-linear equations