

School of Physics, Engineering and Computer Science

# Research Methods in Data Science 7PAM2015-0509-2024

Department of Physics, Astronomy and Mathematics

# **Assignment Title:**

**Image Segmentation** 

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GitHub address: <a href="https://github.com/harimagar/Research-Methods-in-Data-Science-Image-segmentation">https://github.com/harimagar/Research-Methods-in-Data-Science-Image-segmentation</a>

Kaggle Colab Link: <a href="https://www.kaggle.com/code/harighartimagar/image-segmentation">https://www.kaggle.com/code/harighartimagar/image-segmentation</a>

Google Colab Link: <a href="https://colab.research.google.com/drive/1q-MItcd4lrOIHDsJ">https://colab.research.google.com/drive/1q-MItcd4lrOIHDsJ</a> c8xggaKSpmiqwN4?usp=sharing

## Introduction

Image segmentation is the field of computer vision that breaks images into several segments to minimize the complexity of the image and allow further processing (Yu et al., 2023). It uses a pixel-by-pixel approach that seeks segmentation masks, making it easy to analyze the images. Instance segmentation, which is a type of image segmentation, is used in this assignment. Instance segmentation sorts each pixel of an image into a category and also differentiates between individual objects of the same class. For image segmentation, a subset of the COCO-2017 dataset is used, which is a popular dataset for instance segmentation due to its diverse content, large-scale annotations and complexity (Pan et al., 2024). It is applicable and best suited for many modern technologies and innovations, including autonomous driving, smart surveillance, augmented reality, robotics and medical imaging.

The method that is being used in this assignment is Mask R-CNN. Mask R-CNN is built by extending Faster R-CNN, which also predicts object masks in parallel (He et al., 2018). Its advantage is that it is easier to train and implement, and does not add much computational overhead. Therefore, it achieves state-of-the-art results on the COCO dataset and has many adaptations in the research field and industry (Wu et al. 2020).

The data collection and processing is a tedious task. Creating a high-quality dataset requires higher skill and human effort. Further, inconsistent object scales, noisy labels and other factors are important to consider while processing the data before performing the analysis.

Thus, the assignment focuses on applying instance segmentation techniques using the Mask R-CNN model to a subset of the COCO-2017 dataset. The EDA (Exploratory Data Analysis) is performed to analyze the dataset and identify data quality issues. Only four classes, cake, car, dog and person are used to model training, validation and testing purposes.

# Data and EDA (Exploratory Data Analysis)

As mentioned earlier, a subset of the COCO-2017 dataset is used in this assignment. The folder structure of the dataset with three different folders is shown below:

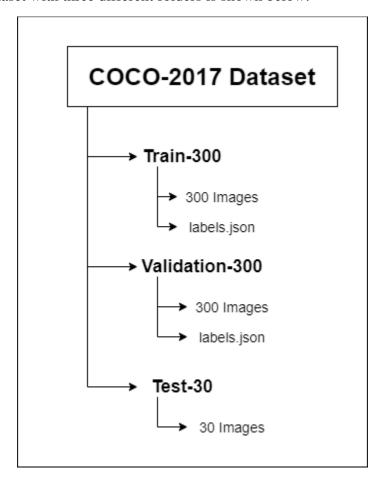


Figure 1 Folder Structure

The JSON file contains image information along with segmentation masks and object bounding boxes for both the train and validation datasets. The dataset is focused on only four target classes: cake, car, dog and person. The instances of these target classes in train dataset is shown by the image below:

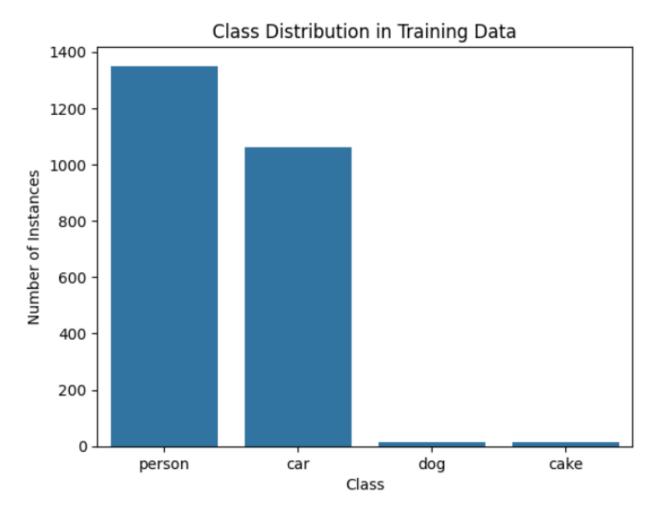


Figure 2 Instances of Target Classes

The diagram shows the class imbalances where instances of person and car are much higher than those of dog and cake. This might have effects on the model training and evaluation.

The variation in image dimensions is shown by the diagrams below:

# Distribution of Image Widths 400 - 300 - 100 -

Figure 3 Image Widths Distribution

Image Width (pixels)

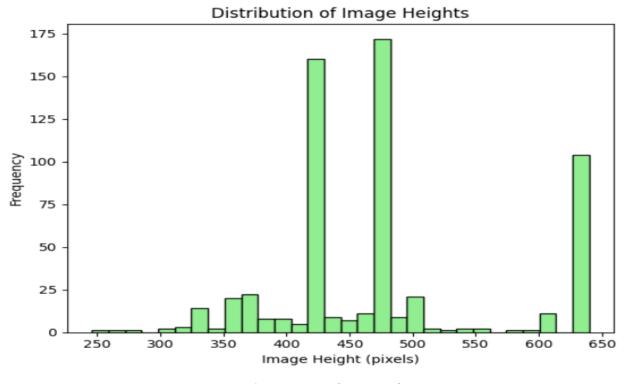


Figure 4 Image Heights Distribution

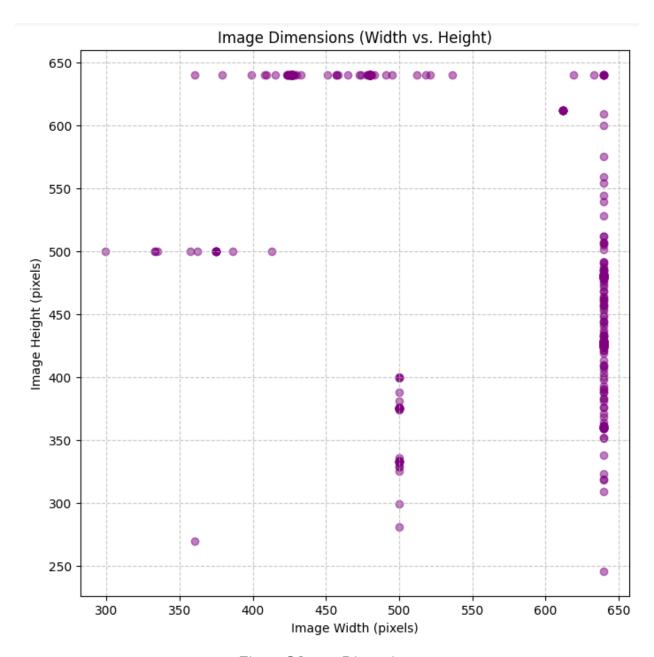


Figure 5 Image Dimensions

The above images show that there is a diverse range of aspect ratios of images with a wide distribution in width and height. These dimensions are analyzed to perform an image resizing technique for better model training and evaluation.

The polygons created for segmentation ground truth encoding are shown below:

```
Total segmentation ground truths: 3870
Segmentation is encoded as polygons (list of coordinates).

Annotation ID: 1
Segmentation: [[392.0, 335.5, 388.0, 323.5, 393.0, 323.5, 392.5, 328.0, 395.5, 330.0, 395.5, 334.0, 392.0, 335.5]]

Annotation ID: 2
Segmentation: [[344.0, 328.5, 340.5, 327.0, 338.5, 320.0, 342.0, 315.5, 345.5, 317.0, 344.0, 328.5]]

Annotation ID: 3
Segmentation: [[336.0, 328.5, 332.5, 321.0, 334.0, 314.5, 337.5, 315.0, 336.0, 328.5]]
```

Figure 6 Segmentation Encoding

Further, data preprocessing is done by removing duplicate images, labelling categories, registering the dataset with Detectron2, and more.

# Methodology

The methodology employed in the analysis is Mask R-CNN, a deep learning model. It is a supervised learning algorithm that requires labelled training data provided via the labels.json file. It is implemented using Detectron2, which offers a flexible approach to training segmentation models. The ResNet-FPN serves as the backbone network for detecting objects of varying sizes. Mask R-CNN is implemented in this assignment because it provides state-of-the-art performance, which provides high accuracy on instance segmentation. Detectron2 is implemented as it offers a robust implementation of the Mask R-CNN model and is flexible (C and P, 2023).

The model is implemented by training the Mask R-CNN using the COCO-2017 dataset that utilizes transfer learning. The Detectron2 model is applied, and the dataset is registered using the register\_coco\_instances() method. A customized training configuration is provided trainer.train() is used for the fine-tuning process. The CUDA or GPU is used for faster training of the model, and when it is not available CPU is used. The COCOEvaluator is implemented for the evaluation of the validation dataset. Finally, using three images from the test dataset, the model results are tested.

Various challenges are faced during method implementation, including the need for a GPU as training on CPU was slow, the need for further computational resources, limited training images resulting in overfitting and a need for data augmentation and class imbalance.

The metric used to assess the model is Average Precision (AP). It is the average of the maximum precision at different recall levels across multiple IoU (Intersection over Union) thresholds (Bharati and Pramanik, 2019). Further, Ap50, Ap75, APs, APm and APl are also used.

# Results

Despite having limited training data, the Mask R-CNN model showed competitive performance. The results of the evaluation is shown below:

AP	AP50	AP75	APs	APm	APl	
::	::	::	::	::	::	
22.338	39.544	21.657	11.676	23.015	36.623	

Figure 7 Evaluation Results

category	AP	category	AP	category	AP	
:	:	:	:	:	:	
cake	0.297	car	37.867	dog	16.618	
person	34.571					

Figure 8 AP of the 4 Categories

The evaluation results show that the model performed well, as it has 22.338 AP and 39.544 AP50 and can accurately locate and segment objects. However, lower AP75 suggests the pixel-level mask precision needs improvement. The model can accurately segment a cat, a dog and a person. However, the AP of cake is just 0.297, which suggests the model struggles with cake segmentation, and there is a need for more labelled training data for cake.

The result of three test images are:

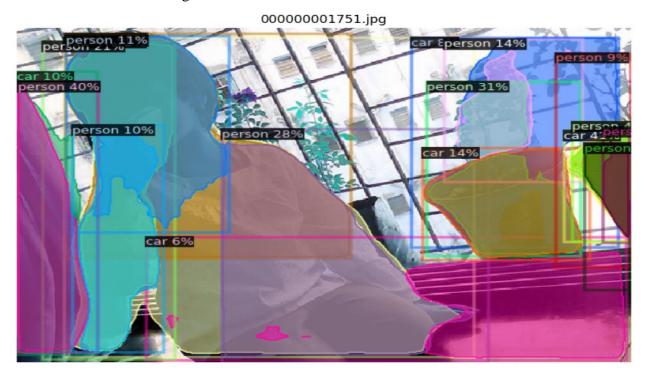


Figure 9 Test-Image-1

Figure 10 Test-Image-2



Figure 11 Test-Image-3

The above results show that it can detect objects in the images. The person, dog and car are detected well, but not the cake.

Compared to the literature review, the Mask R-CNN model detected segmentation of all four target classes well, and the AP, which is 30s and higher, are similar to that of the literature mentioned. However, for better results, a bigger dataset with correctly labelled data is required (Tong and Wu, 2023).

# References

Bharati, P., & Pramanik, A. (2019). Deep Learning Techniques—R-CNN to Mask R-CNN: A survey. In Advances in intelligent systems and computing (pp. 657–668). https://doi.org/10.1007/978-981-13-9042-5\_56

C, A., V., & P, K. (2023). Deep Learning-Based Instance Segmentation of Aircraft in Aerial Images using Detectron2. SSRN Electronic Journal. https://doi.org/10.2139/ssrn.4485468

He, K., Gkioxari, G., Dollar, P., & Girshick, R. (2018). Mask R-CNN. IEEE Transactions on Pattern Analysis and Machine Intelligence, 42(2), 386–397. <a href="https://doi.org/10.1109/tpami.2018.2844175">https://doi.org/10.1109/tpami.2018.2844175</a>

Pan, H., Guan, S., & Zhao, X. (2024). LVD-YOLO: An efficient lightweight vehicle detection model for intelligent transportation systems. Image and Vision Computing, 151, 105276. https://doi.org/10.1016/j.imavis.2024.105276

Tong, K., & Wu, Y. (2023). Rethinking PASCAL-VOC and MS-COCO dataset for small object detection. Journal of Visual Communication and Image Representation, 93, 103830. <a href="https://doi.org/10.1016/j.jvcir.2023.103830">https://doi.org/10.1016/j.jvcir.2023.103830</a>

Wu, M., Yue, H., Wang, J., Huang, Y., Liu, M., Jiang, Y., Ke, C., & Zeng, C. (2020). Object detection based on RGC mask R-CNN. IET Image Processing, 14(8), 1502–1508. https://doi.org/10.1049/iet-ipr.2019.0057

Yu, Y., Wang, C., Fu, Q., Kou, R., Huang, F., Yang, B., Yang, T., & Gao, M. (2023). Techniques and Challenges of Image Segmentation: A review. Electronics, 12(5), 1199. https://doi.org/10.3390/electronics12051199

# **Appendix**

# Environment Setup and Data Loading and Exploration

```
# Importing relevant modules.
import random
import numpy as np
import matplotlib.pyplot as plt
# official COCO dataset Python API
from pycocotools.coco import COCO
# for reading and writing images
import skimage.io as io
%matplotlib inline
# # Import and mount Google Drive.
from google.colab import drive
drive.mount("/content/drive")
# # Unzip the dataset file and store it in a folder called images.
# !unzip "/content/drive/MyDrive/Colab
Notebooks/coco2017/RM Segmentation Assignment dataset.zip" -d
"/content/drive/MyDrive/Colab Notebooks/coco2017/"
```

```
# Defining location of training data.
train data path = "/content/drive/MyDrive/Colab Notebooks/coco2017/train-
300"
train annotation file = f"{train data path}/labels.json"
```

```
# Defining location of validation data.
validation data path = "/content/drive/MyDrive/Colab
Notebooks/coco2017/validation-300"
validation annotation file = f"{validation data path}/labels.json"
coco_validation = COCO(validation_annotation_file)
```

```
# Initialising COCO API for instance annotations.
coco = COCO(train annotation file)
```

### Dataset Analysis

```
# Extract and display COCO categories and supercategories for the training
dataset.
category IDs = coco.getCatIds()
categories = coco.loadCats(category IDs)
```

```
print(categories)

names_cats = [cats["name"] for cats in categories]
print(len(names_cats), "COCO categories:", " ".join(names_cats))

names_scats = set([cats["supercategory"] for cats in categories])
print(len(names_scats), "COCO supercategories:", " ".join(names_scats))

# Define function to extract category name from ID.
def get_category_name(class_ID, categories):
    for i in range(len(categories)):
        if categories[i]["id"] == class_ID:
            return categories[i]["name"]
    return "None"
```

```
# examples of categories
category_name_41 = get_category_name(41, categories)
print(f"The category name is {category_name_41}.")
category_name_15 = get_category_name(15, categories)
print(f"The category name is {category_name_15}.")
```

### Filtering and Displaying Example Images

```
# Get all training images containing a given object category or
categories.
filter_class = ["cat"]
category_IDs = coco.getCatIds(catNms=filter_class)
image_IDs = coco.getImgIds(catIds=category_IDs)

print(f"Number of images containing specified category(ies):
{len(image_IDs)}.")
print(f"IDs of images containing specified category(ies): {image_IDs}.")

# Load and display one of the example images.
example_image = coco.loadImgs(image_IDs[0])[0]
print(example_image)

image = io.imread(f'{train_data_path}/data/{example_image["file_name"]}')
plt.axis("off")
plt.imshow(image)
```

```
# Get COCO annotation IDs and content of annotations, i.e., bounding boxes
and segmentation masks.
test_image_annotations_ID = coco.getAnnIds(
    imgIds=example image["id"], catIds=category IDs, iscrowd=None
print(test image annotations ID)
test_image_annotations = coco.loadAnns(test_image_annotations_ID)
print(test image annotations)
# Load and display test image with instance annotations.
plt.imshow(image)
plt.axis("off")
coco.showAnns(test image annotations, draw bbox=True)
# Extract the training images that contain any combination of the four
target classes.
target_classes = ["cake", "car", "dog", "person"]
target classes IDs = coco.getCatIds(catNms=target classes)
print("Target class IDs:", target_classes_IDs)
training images = []
# Iterate over each individual class in the list.
for class name in target classes:
    # Get all images containing target class.
    print(class name)
    training images categories = coco.getCatIds(catNms=class name)
    training images IDs =
coco.getImgIds(catIds=training images categories)
    training images += coco.loadImgs(training images IDs)
print(
    f"Number of images with target classes including repetitions:
{len(training images)}."
# Filter out repeated images.
```

unique training images = []

for i in range(len(training images)):

if training images[i] not in unique training images:

```
unique training images.append(training images[i])
# Shuffle the training data.
random.seed(0)
random.shuffle(unique training images)
print(
    f"Number of unique images in training data containing the target
classes: {len(unique training images)}"
# Load and display example training image with segmentation masks.
training image = unique training images[10]
print(training image)
image = io.imread(f'{train data path}/data/{training image["file name"]}')
plt.axis("off")
plt.imshow(image)
training image annotations ID = coco.getAnnIds(
    imgIds=training image["id"], catIds=target classes IDs, iscrowd=None
training image annotations = coco.loadAnns(training image annotations ID)
coco.showAnns(training image annotations, draw bbox=False)
plt.show()
# Generating and Plotting Segmentation Masks
mask example = coco.annToMask(training image annotations[0])
print(type(mask example))
print(mask example)
print(mask example.shape)
print(np.max(mask example))
print(np.min(mask example))
# Plotting the segmentation masks with different colours.
mask = np.zeros((training image["height"], training image["width"]))
for i in range(len(training image annotations)):
    # Get object category name.
    object category = get category name(
     training image annotations[i]["category id"], categories
```

```
# Assign pixel value based on location in target_classes list.
pixel_value = target_classes.index(object_category) + 1
# Assign pixel value to mask based on annToMask output.
mask = np.maximum(coco.annToMask(training_image_annotations[i]) * 3,
mask)

print(f"Unique pixel values in the mask: {np.unique(mask)}")

plt.imshow(mask)
plt.show()
```

```
# How many images are in our training/validation/test datasets?
# How many images are in the downloaded data folders?
import os
def count images in folder(folder path):
    return len([f for f in os.listdir(folder path) if
f.lower().endswith((".jpg", ".jpeg", ".png"))])
train image count = count images in folder("/content/drive/MyDrive/Colab
Notebooks/coco2017/train-300/data")
val image count = count images in folder("/content/drive/MyDrive/Colab
Notebooks/coco2017/validation-300/data")
test image count = count images in folder("/content/drive/MyDrive/Colab
Notebooks/coco2017/test-30")
print(f"Train Images: {train image count}")
print(f"Validation Images: {val image count}")
print(f"Test Images: {test image count}")
print(f"Total Images in downloaded data folders: {train image count +
val image count + test image count}")
```

### Data Statistics and Visualization

```
# Load annotations
import json
with open("/content/drive/MyDrive/Colab Notebooks/coco2017/train-
300/labels.json") as f:
    coco_json = json.load(f)

# Count category occurrences
from collections import Counter
target ids = [15, 16, 25, 41]
```

```
counter = Counter()
for ann in coco json["annotations"]:
    if ann["category id"] in target ids:
        counter[ann["category id"]] += 1
print("Instances of each target class in train-300:")
for cid in target ids:
    print(f"Class ID {cid}: {counter[cid]} instances")
anns = coco.loadAnns(coco.getAnnIds(catIds=target classes IDs))
from collections import Counter
label names = [coco.loadCats(ann["category id"])[0]["name"] for ann in
annsl
label counts = Counter(label names)
import seaborn as sns
sns.barplot(x=list(label counts.keys()), y=list(label counts.values()))
plt.title("Class Distribution in Training Data")
plt.ylabel("Number of Instances")
plt.xlabel("Class")
plt.show()
```

```
# How often does each COCO/target class appear?
from collections import defaultdict

# Define your target classes
target_classes = ["cake", "car", "dog", "person"]

# Get COCO category IDs for those target classes
target_category_ids = coco.getCatIds(catNms=target_classes)

# Create a mapping from category ID to name
category_id_to_name = {cat["id"]: cat["name"] for cat in
coco.loadCats(target_category_ids)}

# Count instances
target_category_counts = defaultdict(int)

for ann in coco.dataset["annotations"]:
    cat_id = ann["category_id"]
    if cat_id in target_category ids:
        target category counts[category id to name[cat id]] += 1
```

```
# Print result
print("Target class frequencies in train-300:")
for category in target classes:
print(f"{category}: {target category counts[category]}")
# How large are the images? What is their distribution?
# Function to collect image sizes
def collect image sizes(coco obj):
    img ids = coco obj.getImgIds()
    images info = coco obj.loadImgs(img ids)
    widths = []
    heights = []
    for img info in images info:
        widths.append(img info['width'])
        heights.append(img info['height'])
    return widths, heights
# Collect sizes for training and validation
train widths, train heights = collect image sizes(coco)
val widths, val heights = collect image sizes(coco validation)
all widths = train widths + val widths
all heights = train heights + val heights
print(f"\n--- Image Size Distribution (Train & Val) ---")
print(f"Total images analyzed for size: {len(all widths)}")
print(f"Min Width: {min(all widths)}, Max Width: {max(all widths)}, Avg
Width: {np.mean(all widths):.2f}")
print(f"Min Height: {min(all heights)}, Max Height: {max(all heights)},
Avg Height: {np.mean(all heights):.2f}")
# Plotting histograms for width and height
plt.figure(figsize=(12, 5))
plt.subplot(1, 2, 1)
plt.hist(all widths, bins=30, color='lightcoral', edgecolor='black')
plt.xlabel("Image Width (pixels)")
plt.ylabel("Frequency")
plt.title("Distribution of Image Widths")
plt.subplot(1, 2, 2)
plt.hist(all heights, bins=30, color='lightgreen', edgecolor='black')
```

```
plt.xlabel("Image Height (pixels)")
plt.ylabel("Frequency")
plt.title("Distribution of Image Heights")

plt.tight_layout()
plt.show()

# Plotting scatter plot for width vs height
plt.figure(figsize=(8, 8))
plt.scatter(all_widths, all_heights, alpha=0.5, color='purple')
plt.xlabel("Image Width (pixels)")
plt.ylabel("Image Height (pixels)")
plt.title("Image Dimensions (Width vs. Height)")
plt.grid(True, linestyle='--', alpha=0.7)
plt.show()
```

```
# How many segmentation ground truths are given? How are these encoded?
annotations = coco.dataset["annotations"]
total segmentations = len(annotations)
print(f"Total segmentation ground truths: {total segmentations}")
# Check format of segmentation
example seg = annotations[0]["segmentation"]
if isinstance(example seg, list):
   print("Segmentation is encoded as polygons (list of coordinates).")
elif isinstance(example seg, dict) and "counts" in example seg:
   print("Segmentation is RLE encoded (Run Length Encoding).")
else:
   print("Unknown segmentation format.")
# Show some example segmentations
for i in range(3):
   print(f"\nAnnotation ID: {annotations[i]['id']}")
print(f"Segmentation: {annotations[i]['segmentation']}")
```

```
import torch
import torchvision
import torchaudio

print("Torch version:", torch.__version__)
print("Torchvision version:", torchvision.__version__)
print("Torchaudio version:", torchaudio.__version__)
```

```
# Checking CUDA version compatibility
print("CUDA available:", torch.cuda.is_available())
print("Torch CUDA version:", torch.version.cuda)
```

### **Data Preprocessing**

```
# filter dataset (only 4 classes)
def filter coco by classes (json file, classes to keep):
   with open (json file) as f:
        data = json.load(f)
    class name to id = {cat["name"]: cat["id"] for cat in
data["categories"]}
    keep ids = set(class name to id[name] for name in classes to keep)
   filtered anns = [a for a in data["annotations"] if a["category id"] in
keep ids]
    image ids = set([a["image id"] for a in filtered anns])
    filtered imgs = [i for i in data["images"] if i["id"] in image ids]
    filtered cats = [c for c in data["categories"] if c["id"] in keep ids]
   filtered = {
        "images": filtered imgs,
        "annotations": filtered anns,
        "categories": filtered cats
    return filtered
input path = f"/content/drive/MyDrive/Colab Notebooks/coco2017/train-
300/labels.json"
output path = f"/content/drive/MyDrive/Colab
Notebooks/coco2017/filtered labels train.json"
filtered = filter coco by classes(input path, target classes)
with open (output path, "w") as f:
    json.dump(filtered, f)
input path2 = f"/content/drive/MyDrive/Colab
Notebooks/coco2017/validation-300/labels.json"
output path2 = f"/content/drive/MyDrive/Colab
Notebooks/coco2017/filtered labels validation.json"
filtered2 = filter coco by classes(input path2, target classes)
with open (output path2, "w") as f:
json.dump(filtered2, f)
```

```
!pip install 'git+https://github.com/facebookresearch/detectron2.git'
!pip install pycocotools opency-python matplotlib seaborn albumentations

import torch, torchvision
import numpy as np
import os, json, random
import cv2
import matplotlib.pyplot as plt
from pycocotools.coco import COCO
```

## **Model Training**

```
# model training using Detectron2
from detectron2.engine import DefaultTrainer
from detectron2.config import get_cfg
from detectron2.data.datasets import register_coco_instances
from detectron2.utils.logger import setup_logger
setup_logger()

# Register dataset
register_coco_instances("coco_train2", {}, "/content/drive/MyDrive/Colab
Notebooks/coco2017/filtered_labels_train.json",
   "/content/drive/MyDrive/Colab Notebooks/coco2017/train-300/data")
register_coco_instances("coco_val2", {}, "/content/drive/MyDrive/Colab
Notebooks/coco2017/filtered_labels_validation.json",
   "/content/drive/MyDrive/Colab Notebooks/coco2017/validation-300/data")
```

```
from detectron2.config import get_cfg
from detectron2 import model_zoo
import torch

cfg = get_cfg()
cfg.merge_from_file(model_zoo.get_config_file("COCO-
InstanceSegmentation/mask_rcnn_R_50_FPN_3x.yaml"))

cfg.DATASETS.TRAIN = ("coco_train2",)
cfg.DATASETS.TEST = ("coco_val2",)
cfg.DATALOADER.NUM_WORKERS = 2
cfg.OUTPUT_DIR = "/content/output"
cfg.MODEL.WEIGHTS = "detectron2://COCO-
InstanceSegmentation/mask_rcnn_R_50_FPN_3x/137849600/model_final_f10217.pk
l"
cfg.SOLVER.IMS_PER_BATCH = 2
```

```
cfg.SOLVER.BASE_LR = 0.00025
cfg.SOLVER.MAX_ITER = 1000
cfg.MODEL.ROI_HEADS.BATCH_SIZE_PER_IMAGE = 128
cfg.MODEL.ROI_HEADS.NUM_CLASSES = 4

os.makedirs(cfg.OUTPUT_DIR, exist_ok=True)

if torch.cuda.is_available():
    print("CUDA available.")
    cfg.MODEL.DEVICE = "cuda"
else:
    print("CUDA not available. Training will run on CPU.")
    cfg.MODEL.DEVICE = "cpu"

from detectron2.engine import DefaultTrainer

trainer = DefaultTrainer(cfg)
trainer.resume_or_load(resume=False)
trainer.train()
```

### **Evaluation and Testing**

```
# Evaluation on Validation set
from detectron2.evaluation import COCOEvaluator, inference_on_dataset
from detectron2.data import build_detection_test_loader

evaluator = COCOEvaluator("coco_val2", output_dir="./output")
val_loader = build_detection_test_loader(cfg, "coco_val2")
print(inference_on_dataset(trainer.model, val_loader, evaluator))
```

```
from detectron2.engine import DefaultPredictor
from detectron2.utils.visualizer import Visualizer, ColorMode
from detectron2.data import MetadataCatalog
import random
import os
import cv2
import matplotlib.pyplot as plt

# Set weights and create predictor
cfg.MODEL.WEIGHTS = os.path.join(cfg.OUTPUT_DIR, "model_final.pth")
predictor = DefaultPredictor(cfg)

test_images_path = "/content/drive/MyDrive/Colab Notebooks/coco2017/test-30"
```

```
test images = [f for f in os.listdir(test images path) if
f.endswith(".jpg") or f.endswith(".png")]
# Get metadata for dataset (this contains category names)
metadata = MetadataCatalog.get(cfg.DATASETS.TEST[0])
for img name in random.sample(test images, 3):
    path = os.path.join(test images path, img name)
   img = cv2.imread(path)
   outputs = predictor(img)
    v = Visualizer(img[:, :, ::-1], metadata=metadata, scale=1.2,
instance mode=ColorMode.SEGMENTATION)
    out = v.draw instance predictions(outputs["instances"].to("cpu"))
   plt.figure(figsize=(10, 7))
   plt.imshow(out.get image()[:, :, ::-1])
   plt.title(img name)
   plt.axis("off")
  plt.show()
```