

UNIT-3

1. Design a Turing Machine to recognize the language $\{1^n 2^n 3^n \mid n \geq 1\}$. Specify its transition diagram and table. Show the moves of the TM for the input string 112233.

To design a Turing Machine (TM) that recognizes the language $\{1^n 2^n 3^n \mid n \geq 1\}$, we can follow these steps:

1. Start in the initial state q_0 .
2. Read a 1 and push it onto the stack. Move to state q_1 .
3. Read another 1, push it onto the stack, and stay in state q_1 .
4. Continue this process for any number of 1s.
5. Once you read a 2, start popping 1s from the stack and move to state q_2 for each 1 popped.
6. When you run out of 1s to pop and you read a 3, move to state q_3 .
7. In state q_3 , continue reading 3s and popping 1s for each 3.
8. If there are no more 3s to read and the stack is empty, accept the input. Otherwise, reject it.

Here's the transition diagram and table for this Turing Machine:

States: q_0, q_1, q_2, q_3, q_4 (q_4 is the accepting state)

Input symbols: 1, 2, 3, blank (B)

Transition Table:

Current State	Input Symbol	New Symbol	Move Direction	Next State
q_0	1	B	R	q_1
q_1	1	1	R	q_1
q_1	2	B	L	q_2
q_2	1	B	L	q_2
q_2	3	B	L	q_2
q_2	B	B	R	q_0
q_0	3	B	R	q_3
q_3	3	B	R	q_3
q_3	B	B	R	q_4

Start state: q_0

Accept state: q_4

Now, let's show how this Turing Machine processes the input string "112233":

1. Start in state q_0 with the input tape containing "112233" and the tape head positioned at the first character, which is '1'.

2. The TM reads '1', replaces it with a blank (B), moves right to state q1, and pushes 'B' onto the stack. The tape now looks like this: "B12233".

3. In state q1, the TM continues to read and push 1s onto the stack. After reading two more '1's, the tape looks like this: "BBB233".

4. Now, the TM reads '2', replaces it with a blank, moves left to state q2, and pops '1's from the stack. The tape now looks like this: "BB2B33".

5. In state q2, the TM continues to pop '1's from the stack as it reads '3's. After reading two '3's, the tape looks like this: "BB2BBB".

6. With no more '3's to read and an empty stack, the TM accepts the input in state q4.

The Turing Machine successfully recognized the string "112233" as a member of the language $\{1^n 2^n 3^n \mid n \geq 1\}$ and reached the accepting state q4.

2. **Design a TM for a set of all strings over {a,b} with equal number of a's and b's. Specify its transition diagram and table. Show the moves of the TM for the input string ababba.**

To design a Turing Machine (TM) that recognizes a language consisting of strings with an equal number of 'a's and 'b's over the alphabet {a, b}, we can follow these steps:

1. Start in the initial state q0.
2. Read an 'a' and move to state q1 while pushing an 'X' onto the stack to mark the 'a'.
3. Read a 'b' and move to state q2 while pushing a 'Y' onto the stack to mark the 'b'.
4. Continue this process for any number of 'a's and 'b's.
5. When the input tape is empty, move to state q3.
6. In state q3, start popping 'X' and 'Y' symbols from the stack.

7. If at any point the stack becomes empty and there are no more symbols to read on the input tape, accept the input. If the stack is not empty or there are remaining symbols on the tape, reject the input.

Here's the transition diagram and table for this Turing Machine:

States: q0, q1, q2, q3, q4 (q4 is the accepting state)

Input symbols: a, b, blank (B)

Stack symbols: X, Y, Z (Z is the initial stack symbol)

Transition Table:

Current State	Input Symbol	Stack Symbol	New Symbol	Move Direction	Next State
---------------	--------------	--------------	------------	----------------	------------

q0	a	Z	X	R	q1
q0	b	Z	Y	R	q2
q1	a	Z	X	R	q1
q1	b	X	X	L	q1
q1	B	Z	Z	R	q3
q2	a	Y	Y	L	q2
q2	b	Z	Y	R	q2
q2	B	Z	Z	R	q3
q3	B	Z	Z	R	q3
q3	X	X	Z	L	q3
q3	Y	Y	Z	L	q3
q3	B	Z	B	R	q4

Start state: q0

Accept state: q4

Now, let's show how this Turing Machine processes the input string "ababba":

1. Start in state q0 with the input tape containing "ababba" and the tape head positioned at the first character, which is 'a'.
2. The TM reads 'a', replaces it with a blank (B), moves right to state q1, and pushes 'X' onto the stack. The tape now looks like this: "Bbabba".
3. In state q1, the TM continues to read 'a's and push 'X' symbols onto the stack. After reading three 'a's, the tape looks like this: "BBBbba".
4. Now, the TM reads 'b', replaces it with a blank, moves right to state q2, and pushes 'Y' onto the stack. The tape now looks like this: "BBBYba".
5. In state q2, the TM continues to read 'b's and push 'Y' symbols onto the stack. After reading two 'b's, the tape looks like this: "BBBYYa".
6. The TM continues moving to the right, reading blanks, and pushing blanks onto the stack until the input tape is empty: "BBYYB".
7. Now in state q3, the TM starts popping symbols from the stack. It pops 'Y' and 'B' until the stack is empty, and the input tape has only blanks.
8. With an empty stack and an empty input tape, the TM accepts the input in state q4.

The Turing Machine successfully recognized the string "ababba" as having an equal number of 'a's and 'b's and reached the accepting state q4.

3. Design Turing machine to accept all set of palindromes over $\{0, 1\}^*$. And also write the transition diagram and Instantaneous description on the string 10101.

To design a Turing Machine (TM) that accepts all sets of palindromes over the alphabet $\{0, 1\}^*$, you can follow these steps:

1. Start in the initial state q0.
2. Read the leftmost symbol, which is either '0' or '1', and move to state q1.
3. In state q1, write a blank symbol and move to the right.
4. Continue moving right, skipping over any blank symbols, until you encounter the end of the input string.
5. Once you reach the end of the input, move to the left and go to state q2.
6. In state q2, compare the symbol under the tape head to the symbol at the beginning of the string.
 - a. If they are the same, erase both symbols and move right.
 - b. If they are different, reject the input.
7. Repeat the process until you reach the middle of the string (the midpoint of the palindrome). At this point, all symbols should have been erased.
8. If you reach the end of the input string, move to the accepting state q3 and accept the input.

Here's the transition diagram and table for this Turing Machine:

States: q0, q1, q2, q3 (q3 is the accepting state)

Input symbols: 0, 1, blank (B)

Transition Table:

Current State	Input Symbol	New Symbol	Move Direction	Next State
q0	0	B	R	q1
q0	1	B	R	q1
q1	0	0	R	q1

q1	1	1	R	q1
q1	B	B	L	q2
q2	0	B	L	q2
q2	1	B	L	q2
q2	B	B	R	q3

Start state: q0

Accept state: q3

Now, let's show how this Turing Machine processes the input string "10101":

1. Start in state q0 with the input tape containing "10101" and the tape head positioned at the leftmost character, which is '1'.
2. The TM reads '1', replaces it with a blank (B), and moves right to state q1. The tape now looks like this: "B0101".
3. In state q1, the TM continues moving right, skipping over blanks, and erases '0's and '1's as it goes. The tape is transformed to "BBB".
4. Once it reaches the end of the input, the TM moves left and enters state q2
5. In state q2, it compares the symbols under the tape head to the symbols at the beginning of the string. It finds that they match (both are blanks), so it erases both symbols and continues moving left.
6. The TM repeats this process until all symbols have been erased.
7. When it reaches the end of the input string, it moves to the accepting state q3.

The Turing Machine successfully recognized the string "10101" as a palindrome and reached the accepting state q3.

UNIT-4

4. **What is a compiler? Describe the logical phases of a compiler with a neat sketch, and show the output of each phase, using the example of the following statement**
position: = initial + rate * 60

A compiler is a software tool that translates high-level programming source code into an equivalent lower-level code (e.g., machine code or intermediate code) that can be executed by a computer. Compilers perform several logical phases to process and translate source code, making it executable. These phases are typically divided into several stages. Let's describe the logical phases of a compiler and illustrate each phase using the example statement "position: = initial + rate * 60."

1. Lexical Analysis (Scanning):

- This is the first phase of a compiler.
- The source code is divided into tokens such as keywords, identifiers, operators, and constants.
- Each token is labeled with its respective category.
- Example Output for "position: = initial + rate * 60":

Token Stream:

[IDENTIFIER: position] [ASSIGN] [IDENTIFIER: initial] [ADD] [IDENTIFIER: rate] [MULTIPLY] [INTEGER: 60] [SEMICOLON]

2. Syntax Analysis (Parsing):

- In this phase, the compiler checks the syntax of the source code and builds a syntax tree or an abstract syntax tree (AST).
- The grammar of the programming language is used to ensure that the code adheres to the language's rules.

- Example Output (Simplified AST):

Assignment

└─ Identifier: position

└─ Addition

└─ Identifier: initial

└─ Multiplication

└─ Identifier: rate

└─ Integer: 60

3. Semantic Analysis:

- This phase verifies that the source code is semantically correct.
- It checks for type compatibility, undeclared variables, and other semantic errors.
- Example Output: No semantic errors found.

4. Intermediate Code Generation:

- In this phase, the compiler generates an intermediate representation of the source code.
- The intermediate code is often machine-independent and used as an intermediary step before generating machine code.
- Example Output (simplified intermediate code):

t1 = initial

t2 = rate * 60

position = t1 + t2

5. Optimization:

- Some compilers perform optimization on the intermediate code to improve the efficiency of the generated code.
- Example Output: Optimized intermediate code.

6. Code Generation:

- The compiler generates target machine code or assembly code based on the intermediate code and the target architecture.
- Example Output (machine code or assembly code for a specific target architecture):

LOAD initial, R1

MUL rate, 60, R2

ADD R1, R2, position

7. Symbol Table Management:

- Throughout the compilation process, the compiler manages a symbol table, which stores information about identifiers, their types, and memory locations.

8. Error Handling:

- The compiler reports any errors encountered in the previous phases, such as syntax errors, semantic errors, or code generation errors.

The example statement "position: = initial + rate * 60" has been successfully processed by the compiler, going through each of these logical phases, and the resulting machine code or assembly code can be executed on the target architecture.

Please note that the actual implementation and output may vary depending on the programming language, compiler, and target platform used.

5. Construct predictive parser for the following grammar

$S \rightarrow (L)/a$

$L \rightarrow L, S/S$

To construct a predictive parser for a given grammar, we need to create a parsing table that specifies the production rule to be used for each non-terminal and terminal symbol combination. In this case, we have the following grammar:

1. $S \rightarrow (L) / a$

2. $L \rightarrow L, S / S$

First, we need to find the FIRST and FOLLOW sets for the non-terminals in the grammar:

FIRST sets:

- $\text{FIRST}(S) = \{ (\}$

- $\text{FIRST}(L) = \{ (, a \}$

FOLLOW sets:

- $\text{FOLLOW}(S) = \{), \$ \}$

- $\text{FOLLOW}(L) = \{), \$, , \}$

Now, let's construct the predictive parsing table:

		()		a		,	

	S		$S \rightarrow (L)$				$S \rightarrow a$		

	L		$L \rightarrow L, S$		$L \rightarrow \epsilon$				$L \rightarrow , S$

In the table, rows correspond to non-terminals, and columns correspond to terminal symbols (including ϵ for an empty string).

The table entries indicate the production rule to be used when a specific non-terminal can derive the given terminal symbol or ϵ . For example, if you're in state S and you read '(', you should use the production $S \rightarrow (L)$. If you're in state L and you read ')', you should use the production $L \rightarrow \epsilon$ (which means L derives an empty string).

Now, let's use this predictive parsing table to parse an example string, such as "(a, a)".

Parsing steps for "(a, a)":

1. Initialize a stack with the start symbol S (i.e., push S onto the stack) and set the input string to "(a, a)".

2. Start parsing by reading the first symbol from the input (which is '(') and check the top of the stack (which is 'S').

3. According to the parsing table, we see that $S \rightarrow (L)$. So, we replace 'S' on the stack with '(L)'.

4. We move to the next symbol in the input, which is 'a', and it matches the 'a' in the production $(L \rightarrow L, S)$.

5. Continue this process until you've successfully parsed the entire input string, making replacements on the stack according to the parsing table.

6. At the end of parsing, the stack should be empty, indicating a successful parse.

In this way, the predictive parser can parse strings according to the given grammar.

6. Construct LL(1) parsing table for the following grammar. Find the moves made by the LL(1) parser on the input string: id+ id*id

$E \rightarrow E+T/T$

$T \rightarrow T*F/F$

$F \rightarrow (E)/id$

To construct an LL(1) parsing table for a grammar, you need to find the FIRST and FOLLOW sets for the non-terminals and then use those sets to fill in the table. Here's the grammar you provided:

1. $E \rightarrow E + T \mid T$

2. $T \rightarrow T * F \mid F$

3. $F \rightarrow (E) \mid id$

Let's calculate the FIRST and FOLLOW sets:

FIRST sets:

- FIRST(E):

- $\text{FIRST}(E) = \{ (, id \}$

- FIRST(T):

- $\text{FIRST}(T) = \{ (, id \}$

- FIRST(F):

- $\text{FIRST}(F) = \{ (, id \}$

FOLLOW sets:

- FOLLOW(E):

- $\text{FOLLOW}(E) = \{ \$,), id \}$

- FOLLOW(T):
 - FOLLOW(T) = { \$,), +, id }

- FOLLOW(F):
 - FOLLOW(F) = { \$,), *, +, id }

Now, let's construct the LL(1) parsing table:

		()	+	*	id	\$	
E	E → E+T					E → T		
T	T → T*F		T → ε		T → F			
F	F → (E)				F → id			

In the parsing table:

- Rows correspond to non-terminals.
- Columns correspond to terminal symbols (including ε for an empty string).

Table entries indicate the production rule to be used when a specific non-terminal can derive the given terminal symbol or ε. For example, if you're in state E and you read '(', you should use the production E → E+T. If you're in state T and you read '+', you should use the production T → ε, which represents an empty string.

Now, let's parse the input string "id+id*id" using the LL(1) parser with the parsing table:

1. Start with the parsing stack containing only the start symbol: `<E>`.
2. Initialize the input pointer at the beginning of the input string: `id+id*id`.
3. Look at the top of the stack (E) and the input symbol ('i' in "id+id*id").
4. Using the LL(1) parsing table, find the corresponding production. In this case, E → T.
5. Replace the top of the stack with the right-hand side of the chosen production: `<T>`.
6. The new stack: `<T>`
7. Continue parsing, reading 'd' from the input, and looking at the stack (now `<T>`).

8. Using the table, find the production $T \rightarrow F$.
9. Replace the top of the stack with the right-hand side: $\langle F \rangle$.
10. The new stack: $\langle F \rangle$
11. Continue parsing by reading 'i' from the input. Now, the stack: $\langle F \rangle$ and the input: "id*id".
12. Using the table, find the production $F \rightarrow id$.
13. Replace the top of the stack with the right-hand side: $\langle id \rangle$.
14. The new stack: $\langle id*id \rangle$ and the input: "id*id".
15. Continue parsing by reading '+' from the input, resulting in the stack: $\langle +T*id \rangle$ and the input: "id*id".
16. Using the table, find the production $T \rightarrow F$.
17. Replace the top of the stack with the right-hand side: $\langle +F*id \rangle$.
18. The new stack: $\langle +F*id \rangle$ and the input: "id*id".
19. Continue parsing by reading 'i' from the input, resulting in the stack: $\langle +F*id \rangle$ and the input: "*id".
20. Using the table, find the production $F \rightarrow id$.
21. Replace the top of the stack with the right-hand side: $\langle +id*id \rangle$.
22. The new stack: $\langle +id*id \rangle$ and the input: "*id".
23. Continue parsing by reading '*' from the input, resulting in the stack: $\langle +T*id \rangle$ and the input: "id".
24. Using the table, find the production $T \rightarrow F$.
25. Replace the top of the stack with the right-hand side: $\langle +F*id \rangle$.
26. The new stack: $\langle +F*id \rangle$ and the input: "id".
27. Finally, continue parsing by reading 'id' from the input, resulting in the stack: $\langle +id \rangle$ and the input: "" (end of input).

28. Using the table, find the production $F \rightarrow id$.

29. Replace the top of the stack with the right-hand side: ``+id``.

30. The new stack: ``+id`` and the input: `""` (end of input).

At this point, the stack contains only the start symbol, and the input is empty, indicating a successful parse. The LL(1) parser has successfully parsed the input string "id+id*id" using the given parsing table.

UNIT-5

8. a) What is role of intermediate code generator in compilation process? Explain various forms of Intermediate codes used by compiler.

The intermediate code generator plays a crucial role in the compilation process as an intermediary step between the front end and the back end of a compiler. Its primary function is to translate the high-level programming language source code into an intermediate representation that is both more abstract than the source code and closer to the machine code. The role and significance of the intermediate code generator can be understood as follows:

Role of Intermediate Code Generator:

1. Abstraction and Simplification: The intermediate code serves as an abstraction of the source code, simplifying complex high-level language constructs into a form that is easier to analyze and optimize. It removes language-specific details, making it more amenable to analysis and optimization algorithms.

2. Platform Independence: Intermediate code is typically designed to be platform-independent, meaning it does not depend on the specific architecture of the target machine. This allows for portability and the ability to generate machine code for different platforms from the same intermediate code.

3. Code Optimization: The intermediate code generator can perform some simple optimizations such as constant folding, common subexpression elimination, and dead code elimination. These optimizations can improve the efficiency of the generated machine code.

4. Separation of Concerns: By breaking down the compilation process into multiple phases, the intermediate code generator separates the concerns of the front end (which focuses on syntax and semantics) from the back end (which focuses on code generation for a specific target machine). This separation simplifies the development of compilers and facilitates modular design.

5. Code Generation and Target Independence: The intermediate code can be translated into machine-specific code by the code generator of the compiler, allowing the compiler to target different machines by changing only the back end while keeping the same intermediate representation.

Various Forms of Intermediate Codes:

There are various forms of intermediate codes used by compilers, each designed for different purposes and levels of abstraction. Some common forms of intermediate code include:

1. Three-Address Code (TAC): This is a simple form of intermediate code that uses a set of three-address instructions. Each instruction typically contains an operator, two source operands, and one destination operand. For example, an assignment statement " $x = y + z$ " can be represented as TAC: " $x = y + z$."

2. Abstract Syntax Tree (AST): The AST is a hierarchical data structure that represents the syntactic structure of the source code. While not a typical intermediate code, it is often used as a convenient intermediate representation during the parsing phase of a compiler.

3. Quadruples: Quadruples are similar to TAC but are designed to be more suitable for optimization. They use four fields: operator, operand1, operand2, and result. For example, " $x = y + z$ " can be represented as a quadruple: $(+, y, z, x)$.

4. Bytecode: Bytecode is used in virtual machines and interpreted languages. It's a low-level representation of code that can be executed by a virtual machine. Examples include Java bytecode and Python bytecode.

5. Static Single Assignment (SSA) Form: SSA is an intermediate representation that represents a program in a form where each variable is assigned only once. SSA simplifies many optimization techniques.

6. Intermediate Representation for Code Optimization (IRCO): IRCO is a form of intermediate code specifically designed for code optimization. It includes additional information to assist in optimizing the code.

7. Low-Level Intermediate Code: Some compilers use lower-level intermediate representations closer to the assembly language of the target machine. Examples include RTL (Register Transfer Language) and LIR (Low-Level Intermediate Representation).

The choice of intermediate code form depends on the goals of the compiler and the specific optimizations and transformations it aims to perform. Different compilers and programming languages may use different intermediate representations based on their specific requirements and design goals.

b) Illustrate various loop optimization techniques with suitable examples

Loop optimization techniques are crucial for improving the performance of programs with loops. They aim to reduce the execution time and improve the efficiency of loops. Here are some common loop optimization techniques along with suitable examples:

1. Loop Unrolling:

Loop unrolling is a technique where the loop body is duplicated, and loop control variables are incremented by a larger step. This reduces the overhead of loop control and allows for better utilization of processor resources.

Example:

Original loop:

```
for (int i = 0; i < 5; i++) {  
    // Loop body  
}
```

After loop unrolling:

```
for (int i = 0; i < 5; i += 2) {  
    // Loop body  
    // Loop body  
}
```

2. Loop Fusion:

Loop fusion combines multiple loops into a single loop. This reduces loop overhead and improves data locality.

Example:

Original code with two separate loops:

```
for (int i = 0; i < N; i++) {  
    // Loop 1 body  
}  
for (int i = 0; i < N; i++) {  
    // Loop 2 body  
}
```

```
}
```

After loop fusion:

```
for (int i = 0; i < N; i++) {  
    // Loop 1 body  
    // Loop 2 body  
}
```

3. Loop-Invariant Code Motion (LICM):

LICM identifies code that doesn't change within the loop and moves it outside of the loop. This reduces redundant calculations.

Example:

Original code with redundant calculation inside the loop:

```
for (int i = 0; i < N; i++) {  
    result = a + b; // Invariant code  
    // Loop body using 'result'  
}
```

After LICM:

```
result = a + b; // Invariant code  
for (int i = 0; i < N; i++) {  
    // Loop body using 'result'  
}
```

4. Loop Tiling (Loop Nesting):

Loop tiling divides a large loop into smaller tiles. This can improve data locality and cache performance.

Example:

Original nested loop:

```
for (int i = 0; i < M; i++) {  
    for (int j = 0; j < N; j++) {  
        // Loop body  
    }  
}
```

After loop tiling:

```

int tileSize = 16;
for (int i = 0; i < M; i += tileSize) {
    for (int j = 0; j < N; j += tileSize) {
        for (int ii = i; ii < i + tileSize; ii++) {
            for (int jj = j; jj < j + tileSize; jj++) {
                // Loop body
            }
        }
    }
}

```

5. Loop Interchange:

Loop interchange changes the order of nested loops to improve data locality or to enable other optimizations.

Example:

Original nested loops:

```

for (int i = 0; i < N; i++) {
    for (int j = 0; j < M; j++) {
        // Loop body
    }
}

```

After loop interchange:

```

for (int j = 0; j < M; j++) {
    for (int i = 0; i < N; i++) {
        // Loop body
    }
}

```

6. Parallelization:

Parallelization techniques like OpenMP or CUDA can be used to execute loop iterations concurrently, making use of multi-core processors or GPUs.

Example (using OpenMP):

```

#pragma omp parallel for
for (int i = 0; i < N; i++) {
    // Parallel loop body
}

```

These loop optimization techniques aim to reduce execution time, improve cache utilization, and enable the compiler to generate more efficient code. The choice of

optimization depends on the specific code and the hardware architecture on which it will run. Compiler optimizations, manual code modifications, and profiling tools are often used to apply these techniques effectively.

9. a) Translate the expression $-(a + b) * (c + d) + (a + b + c)$ into the following

i) Quadruples

ii) Triples

iii) Indirect triples

To translate the expression $-(a+b)*(c+d)+(a+b+c)$ into different forms of intermediate code, let's start by breaking down the expression into its constituent operations:

1. $a + b$
2. $-(\text{result of 1})$
3. $c + d$
4. $(\text{result of 2}) * (\text{result of 3})$
5. $a + b + c$
6. $(\text{result of 4}) + (\text{result of 5})$

Now, we can represent these operations in different intermediate code forms:

i) Quadruples:

A quadruple typically consists of four elements: operator, operand1, operand2, and result.

1. $(+), a, b, T1$
2. $UMINUS, T1, , T2$
3. $(+), c, d, T3$
4. $(*), T2, T3, T4$
5. $(+), a, b, T5$
6. $(+), T4, T5, T6$

The intermediate code in quadruples form:

1. $(+), a, b, T1$
2. $UMINUS, T1, , T2$
3. $(+), c, d, T3$
4. $(*), T2, T3, T4$
5. $(+), a, b, T5$
6. $(+), T4, T5, T6$

ii) Triples:

A triple consists of three elements: operator, operand1, and operand2.

1. `+`, `a`, `b`
2. `UMINUS`, `(result of 1)`
3. `+`, `c`, `d`
4. `*`, `(result of 2)`, `(result of 3)`
5. `+`, `a`, `b`
6. `+`, `(result of 4)`, `c`

The intermediate code in triples form:

1. +, a, b
2. UMINUS, (result of 1)
3. +, c, d
4. *, (result of 2), (result of 3)
5. +, a, b
6. +, (result of 4), c

iii) Indirect Triples:

Indirect triples are similar to triples but use temporary variables to store intermediate results.

1. `+`, `a`, `b`
2. `UMINUS`, `temp1`, `(result of 1)`
3. `+`, `c`, `d`
4. `*`, `temp2`, `(result of 3)`
5. `+`, `a`, `b`
6. `+`, `temp3`, `(result of 5)`

The intermediate code in indirect triples form:

1. +, a, b
2. UMINUS, temp1, (result of 1)
3. +, c, d
4. *, temp2, (result of 3)
5. +, a, b
6. +, temp3, (result of 5)

In the above representations, `temp1`, `temp2`, and `temp3` are temporary variables used to store intermediate results. The exact representation of these temporary variables may vary depending on the context and implementation of the compiler.

b) Explain various methods to handle peephole optimization.

Peephole optimization is a local optimization technique that focuses on improving small, contiguous sections of assembly code or intermediate code. These optimizations typically involve a limited number of instructions or a small "window" of code, and they aim to make code more efficient by replacing or reordering instructions. Here are various methods and strategies used to handle peephole optimization:

1. Pattern Matching and Substitution:

One common approach in peephole optimization is to identify specific patterns or sequences of instructions and replace them with more efficient or equivalent sequences. For example:

- Substituting a sequence of multiple arithmetic operations with a single optimized operation.
- Replacing redundant load and store operations with fewer instructions.

2. Dead Code Elimination:

Detect and eliminate code that has no effect on the program's output. This includes instructions that compute values that are never used or load values that are never used again.

3. Constant Folding:

Identify and evaluate expressions with constant values during compile time. For example, replacing `x = 2 + 3` with `x = 5`.

4. Strength Reduction:

Replacing costly operations with less costly ones. For instance, replacing multiplication with shifting for power-of-two values.

5. Common Subexpression Elimination:

Recognize and eliminate redundant calculations. If the same expression is computed multiple times, store the result and reuse it.

6. Peephole Code Motion:

Moving instructions out of loops when possible to reduce execution time. This includes moving loop-invariant instructions outside the loop.

7. Register Allocation:

Minimize the number of register operations by identifying cases where a value can be reused from a register rather than being reloaded from memory.

8. Loop Optimization:

Specific optimizations within loops include loop unrolling, loop fusion, loop interchange, and loop tiling.

9. Instruction Scheduling:

Reordering instructions for better pipelining or execution parallelism to reduce stalls in the instruction pipeline.

10. Tail Recursion Elimination:

Transform tail-recursive functions into iterative ones, reducing the function call overhead.

11. Code Compression:

Reducing code size by removing unnecessary instructions or replacing longer instructions with shorter ones when they are semantically equivalent.

12. Branch Optimization:

Optimizing branches by reducing the number of branch instructions, improving branch prediction, and making better use of conditional instructions.

13. Memory Access Optimization:

Reducing memory access overhead by optimizing data layout, reordering memory operations, or using prefetching.

14. Peephole Patterns for Security:

Identifying security vulnerabilities in code by looking for patterns that may lead to buffer overflows, injection attacks, or other security issues.

15. Profile-Guided Optimization (PGO):

Using runtime profiling information to make better-informed decisions during peephole optimization, especially for code paths that are frequently executed.

The effectiveness of peephole optimization depends on the specific code being analyzed and the compiler's ability to recognize and apply these optimizations. It's typically a part of the compiler's optimization pipeline, and multiple peephole optimization passes may be performed at different stages of compilation. The goal is to achieve a balance between code size and execution speed, taking into account the constraints and goals of the application and target platform.

10.a) Explain various methods of implementing three address statements with suitable examples.

Three-address statements are intermediate code representations that involve three operands: two source operands and one destination operand. These statements are commonly used in compilers for code generation and optimization. There are several methods to implement three-address statements, depending on the specific requirements of the compiler and the target architecture. Here are various methods with suitable examples:

1. Stack Machine Approach:

In a stack-based approach, you use a stack to store operands and perform operations. Each operation consumes the top elements from the stack and pushes the result back. This method is often used in virtual machines and interpreters.

Example:

```
t1 = a + b
t2 = c * t1
t3 = t2 - d
```

Implementation:

```
PUSH a
PUSH b
ADD      ; t1 = a + b
PUSH c
PUSH t1
MUL      ; t2 = c * t1
PUSH d
SUB      ; t3 = t2 - d
```

2. Register-Machine Approach:

In a register-based approach, you use a set of virtual registers to store values. Operations are performed on registers, and each register represents a variable.

Example:

```
t1 = a + b
t2 = c * t1
t3 = t2 - d
```

Implementation:

```
LOAD r1, a ; Load a into r1
LOAD r2, b ; Load b into r2
ADD r3, r1, r2 ; t1 = r1 + r2
LOAD r4, c ; Load c into r4
MUL r5, r4, r3 ; t2 = r4 * r3
LOAD r6, d ; Load d into r6
SUB r7, r5, r6 ; t3 = r5 - r6
```

3. Memory-Based Approach:

In a memory-based approach, you use memory locations to store values. Operations load values from memory, perform the operation, and store the result back in memory.

Example:

```
t1 = a + b
t2 = c * t1
t3 = t2 - d
```

Implementation:

```
LOAD t1, a ; Load a into t1
ADD t1, t1, b ; t1 = t1 + b
LOAD t2, c ; Load c into t2
MUL t2, t2, t1 ; t2 = t2 * t1
LOAD t3, d ; Load d into t3
SUB t3, t2, t3 ; t3 = t2 - t3
```

4. Linearized Memory-Based Approach:

In this approach, you maintain an array or a linearized representation of memory. Each memory location is assigned an index, and operations work with indices.

Example:

```
t1 = a + b
t2 = c * t1
t3 = t2 - d
```

Implementation:

```
t1 = a ; t1 points to the memory location of a
t1 = t1 + b ; t1 points to the memory location of a + b
t2 = c ; t2 points to the memory location of c
t2 = t2 * t1 ; t2 points to the memory location of (a + b) * c
t3 = t2 ; t3 points to the same memory location as t2
t3 = t3 - d ; t3 points to the memory location of (a + b) * c - d
```

Each method has its own advantages and is suitable for different contexts. The choice of implementation depends on factors like the target architecture, the available resources, and the specific goals of the compiler or code generator.

b) What is a basic block and flow graph? Explain how flow graph can be constructed for a given program.

In compiler design and optimization, a "basic block" and a "flow graph" are fundamental concepts used to represent the control flow of a program. Let's define each term and then explain how a flow graph can be constructed for a given program.

Basic Block:

A basic block is a sequence of consecutive instructions in a program where control enters at the beginning and exits at the end without any branching, except at the end. In other words, it is a straight-line sequence of code that does not contain any jumps, loops, or conditional branches. The end of a basic block is typically marked by a branch instruction or a return statement.

For example, consider the following code:

```
1. int sum = 0;
2. for (int i = 1; i <= 5; i++) {
3.   sum += i;
4. }
5. printf("Sum: %d", sum);
```

In this code, there are three basic blocks:

1. Basic Block 1: Contains instructions 1 and 2.
2. Basic Block 2: Contains instruction 3.
3. Basic Block 3: Contains instructions 4 and 5.

Flow Graph:

A flow graph, also known as a control flow graph (CFG), is a graphical representation of the control flow in a program. It is constructed by representing basic blocks as nodes and the flow of control between them as edges. A flow graph helps visualize how the program execution flows from one basic block to another.

To construct a flow graph for a given program, follow these steps:

1. Identify Basic Blocks: First, divide the program into basic blocks. Identify the entry and exit points for each basic block. Typically, basic blocks start at the beginning of the program or at the target of a branch instruction and end at the target of a branch instruction or at the end of the program.

2. Create Nodes: Create a node for each basic block. Each node represents a basic block, and it contains the instructions within that basic block.

3. Create Edges: Create edges between nodes to represent the flow of control from one basic block to another. If basic block A can be followed by basic block B in the program execution, then create an edge from A to B.

4. Connect Entry and Exit: Connect the entry node to the first basic block, and the exit node to the final basic block. These connections represent the program's entry and exit points.

Here's a simplified example flow graph for the previously mentioned code:

```
Entry
|
v
[Basic Block 1] ----> [Basic Block 2] ----> [Basic Block 3] ----> Exit
```

In this flow graph:

- "Entry" and "Exit" nodes represent the entry and exit points of the program.
- Basic Block 1 represents the initialization of the `sum` variable and the loop setup.
- Basic Block 2 represents the loop body.
- Basic Block 3 represents the printing of the result.

The edges between nodes show the order of execution and how control flows from one basic block to another.

Flow graphs are useful for various compiler optimizations and analyses, such as data-flow analysis, loop optimizations, and control flow analysis, as they provide a visual representation of program behavior.