

PCM, PWM & PPM

Staff: Dr. R.Kalidoss



Objective

1. To discuss about PWM and PPM modulation
2. To discuss about generation and detection of PWM and PPM modulation techniques
3. To discuss about digital pulse modulation-PCM-Pulse Code Modulation



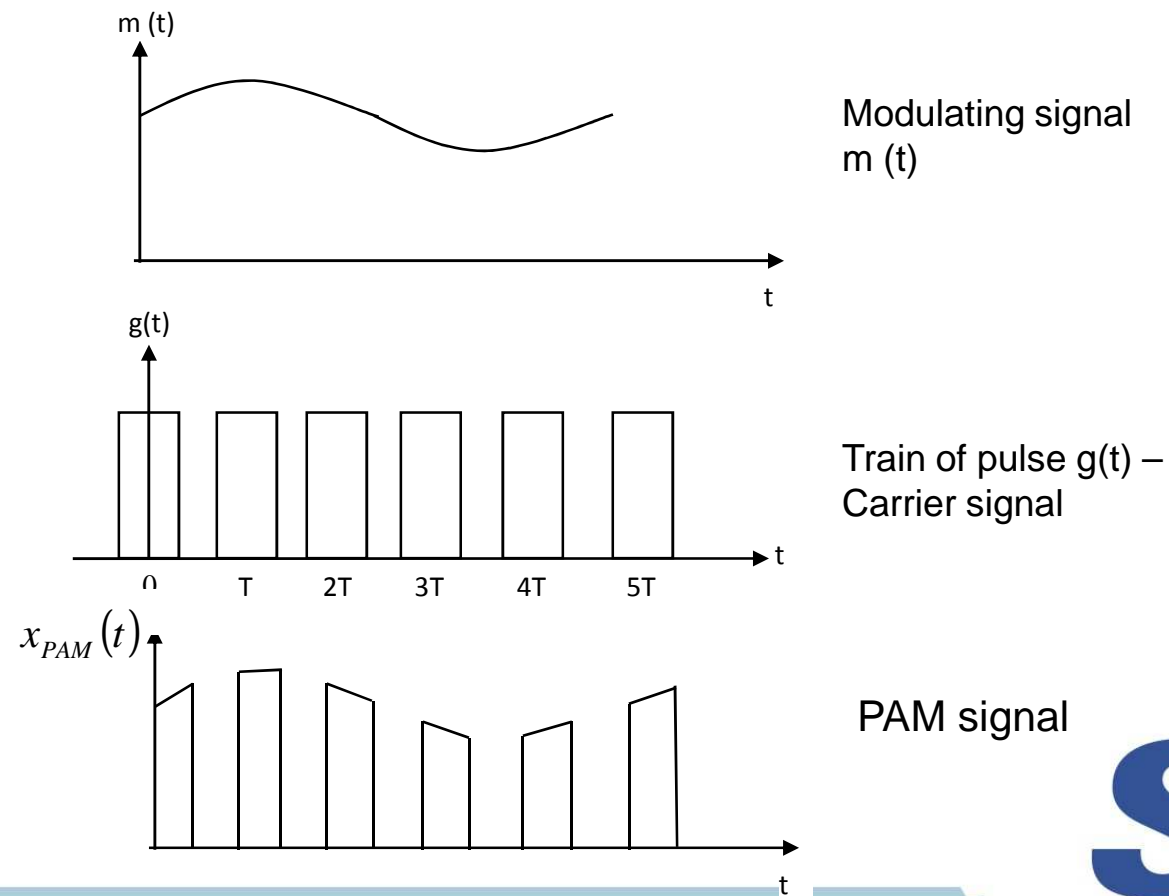
Pulse Width Modulation (PWM)

- Definition: In PWM, instantaneous pulse width at each pulse duration is proportional to the amplitude of modulating signal.
- Various steps involved in generation of PWM signal:
 - i) Generate PAM signal $x_{PAM}(t)$
 - ii) Generate saw tooth waveform $p(t)$
 - iii) Add $x_{PAM}(t) + p(t)$
 - iv) Slicing waveform at arbitrary threshold^(V)
 - v) Comparator circuit output is PWM



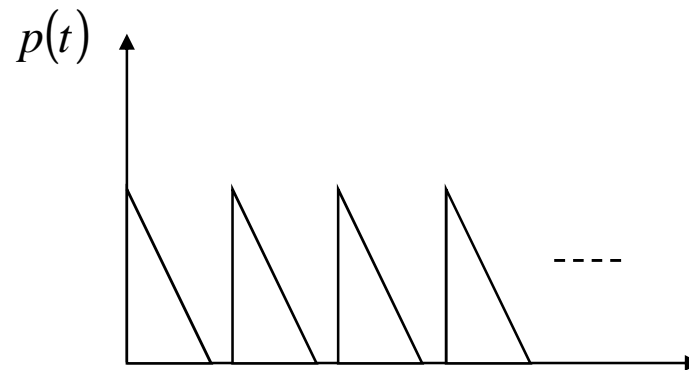
Step 1: Generate PAM signal

PAM signal $x_{PAM}(t)$ may be obtained when $x(t)$ and $g(t)$ is applied to PAM generation circuit.

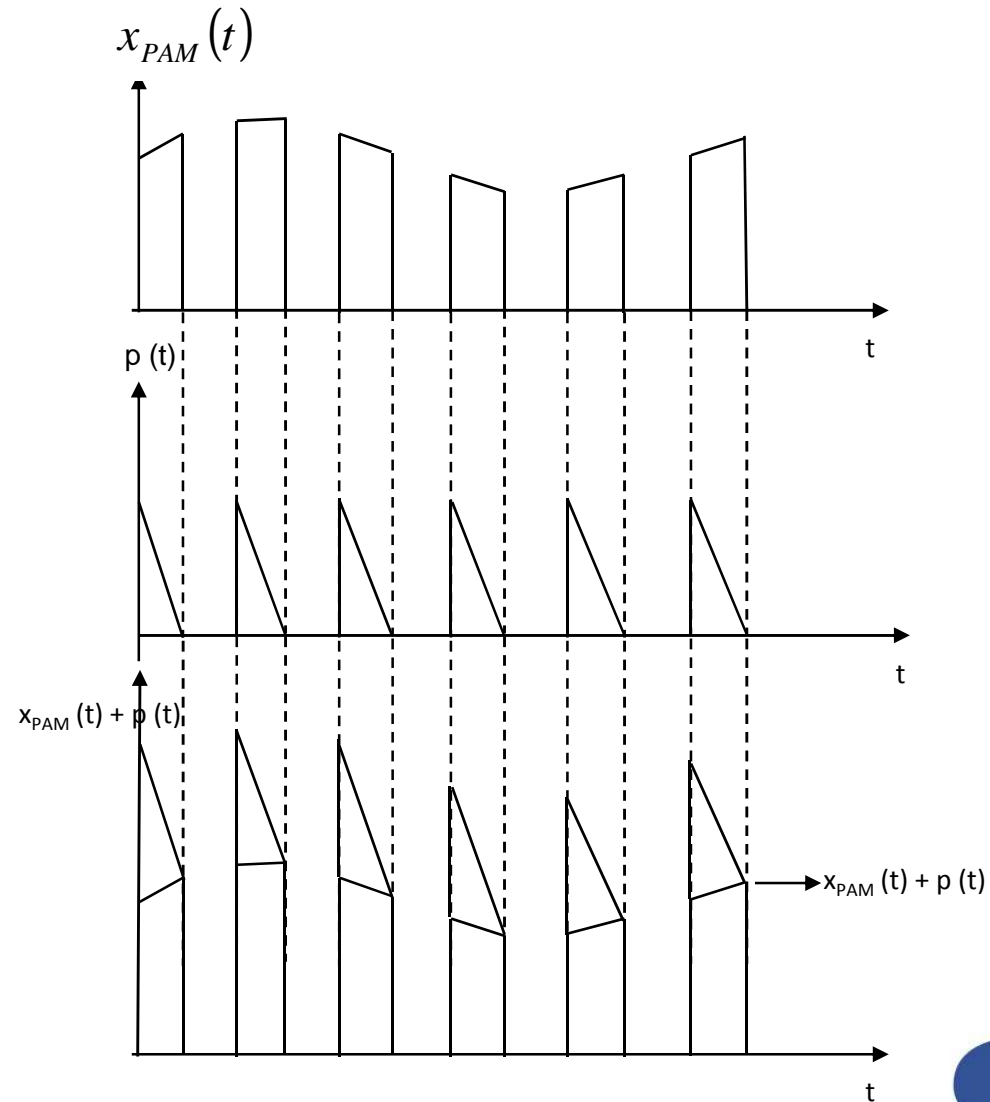


Generate saw tooth waveform

- Another set of pulses $p(t)$ with constant amplitude may now be generated, it has a triangular shape

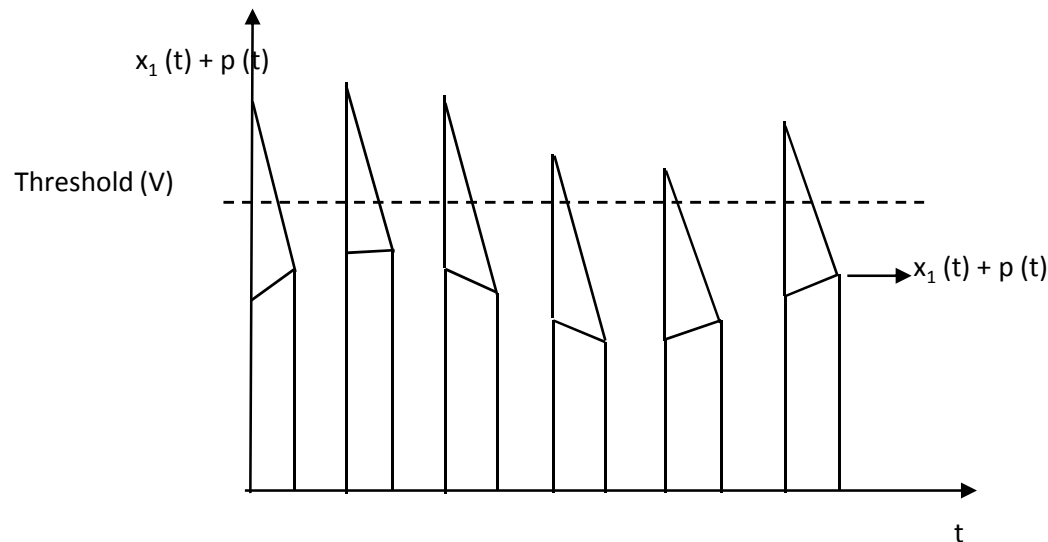


Step 3:- Add $x_{PAM}(t) + p(t)$



Step 4: Slicing waveform at arbitrary threshold

Step 4: This waveform (previous fig.) may now be sliced at some point, i.e. an arbitrary threshold (V) is to be chosen.

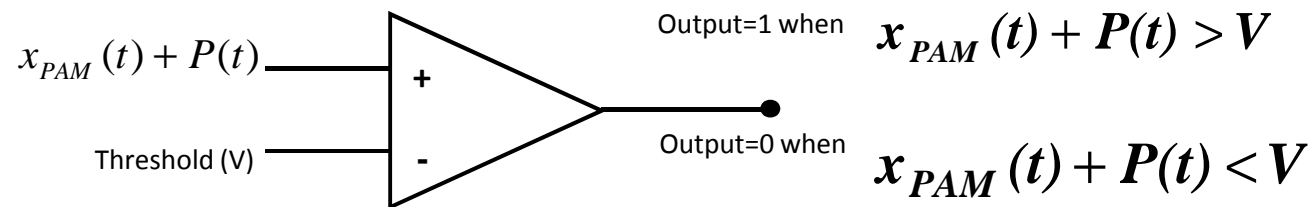


Step 5: Comparator circuit operation

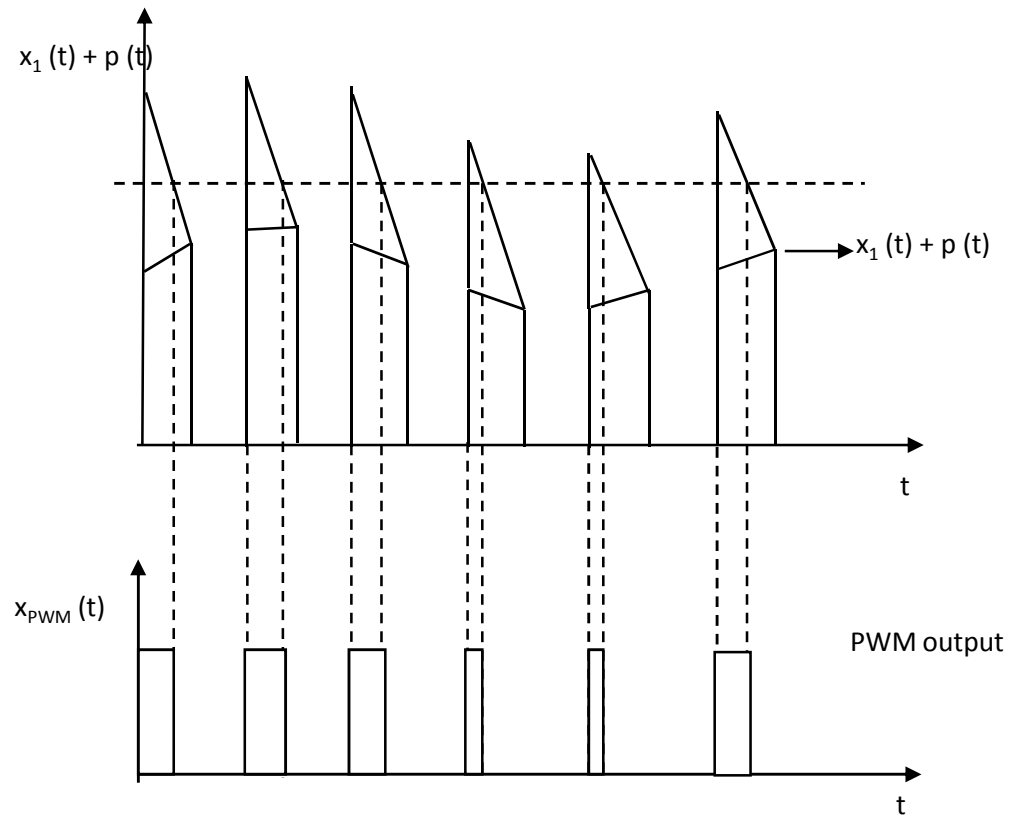
- A comparator circuit is taken as shown in figure. The input for the comparator are $x_{PAM}(t) + p(t)$ and threshold fixed (V) in the previous steps. The output of the comparators are,

$$x_{PAM}(t) + p(t) > \text{Threshold}(V) = 1$$

$$x_{PAM}(t) + p(t) < \text{Threshold}(V) = 0$$



Step 6 Comparator output



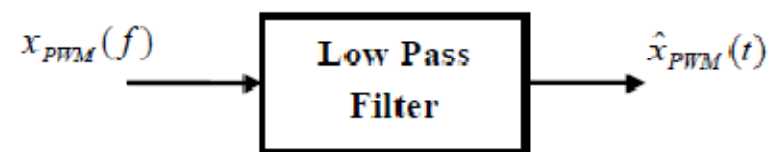
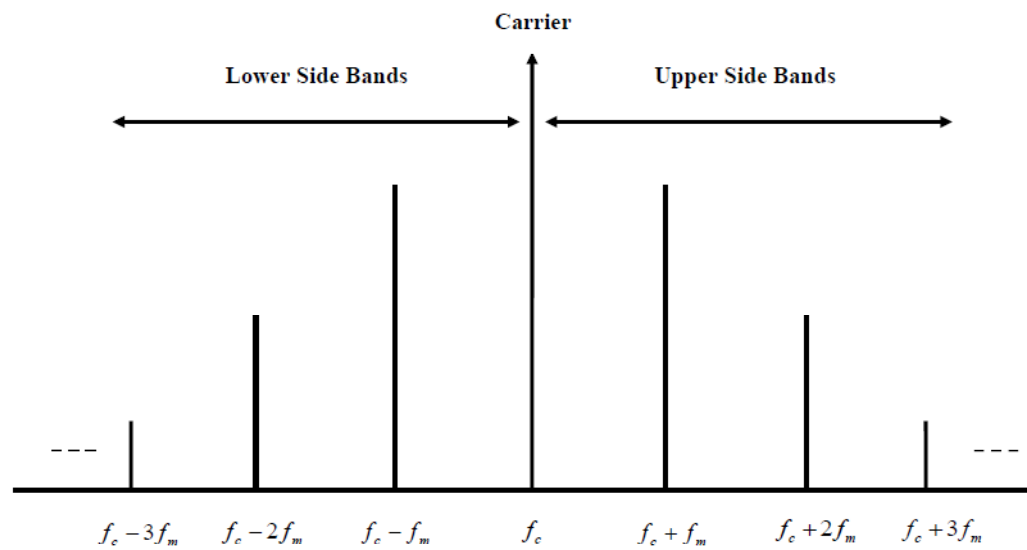
Detection of PWM signal

The spectrum of PWM signal is mathematically given as,

$$x_{PWM}(t) = -\frac{1}{\pi} h \sum \frac{1}{m} J_0(m\pi\beta) \left\{ \left[\sin 2\pi(mf_s + mf_m)t + \frac{m\pi}{2} \right] + \sin \left[\sin 2\pi(mf_s - mf_m)t + \frac{m\pi}{2} \right] \right\} + \dots$$

It shows that, similar to FM, PWM spectrum also consists of infinite sidebands around the desired modulating signal. This is shown in figure. Hence, with the help of a low pass filter the original signal at receiver side can be detected easily the spectrum of $x_{PWM}(f)$ may be passed to low pass filter for reconstruction. The low pass filter allows the spectrum from the band $-f_h$ to $+f_h$ and suppresses all other side bands.





Pulse Position Modulation (PPM)

- Definition: The position of the pulse in PPM is changed with respect to the position of the reference pulse.

- Generation of PPM:

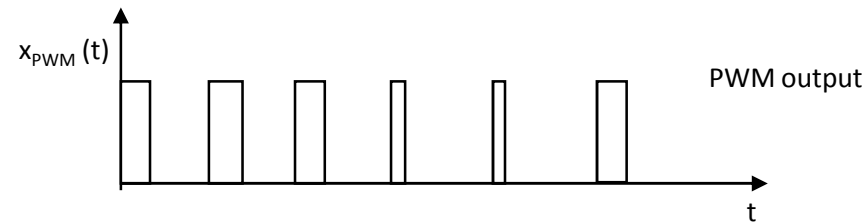
Step 1: Generate PWM signal.

Step 2: Arrow in the PWM signal indicates the trailing edge of the pulse.

Step 3: Operation of mono stable multi-vibrator gives PPM signal



Step 1:-Generation of PWM



Step 2: Arrow in the PWM signal indicates the trailing edge of the pulse.

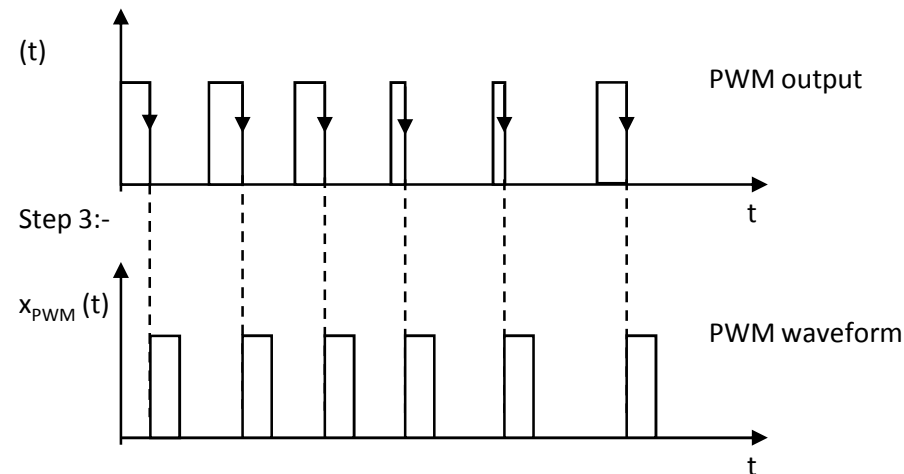
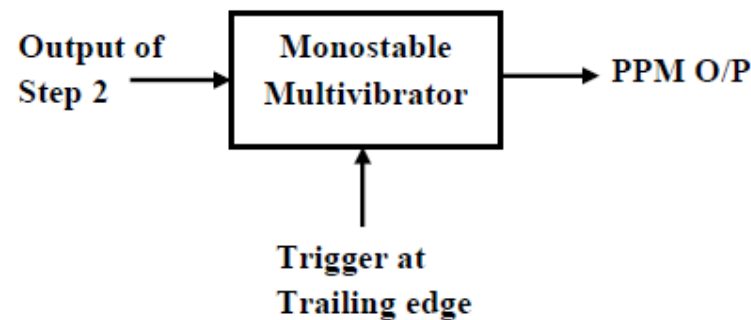


Fig. a) Trailing edge of PWM b) PPM waveform

Step 4: Operation of mono stable multi-vibrator

- Mono stable multivibrators are electronic circuits. When triggered by a triggering pulse, they go to a set or a stable state and come to the original state after a brief period.
- The output waveform has a constant width and amplitude but its positions differ or vary according to the triggering pulse.

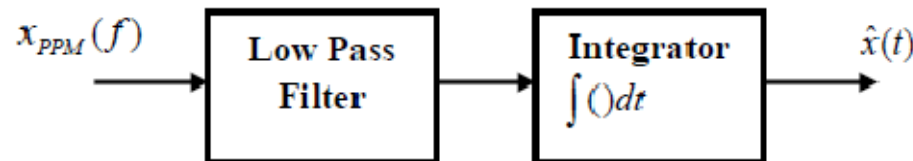


Detection of PPM

Let us assume the modulating signal as $m(t) = A \cos 2\pi f_m t$

The spectrum of PPM signal is given by the expression, $x_{PPM}(t) = f_s - \beta f_m \sin 2\pi f_m t + \sum \sum \dots$

- This expression shows the spectrum as consisting of a derivative of modulating signal and higher order terms.
- Hence the PPM signal can be detected by a low pass filter followed by an integrator circuit.



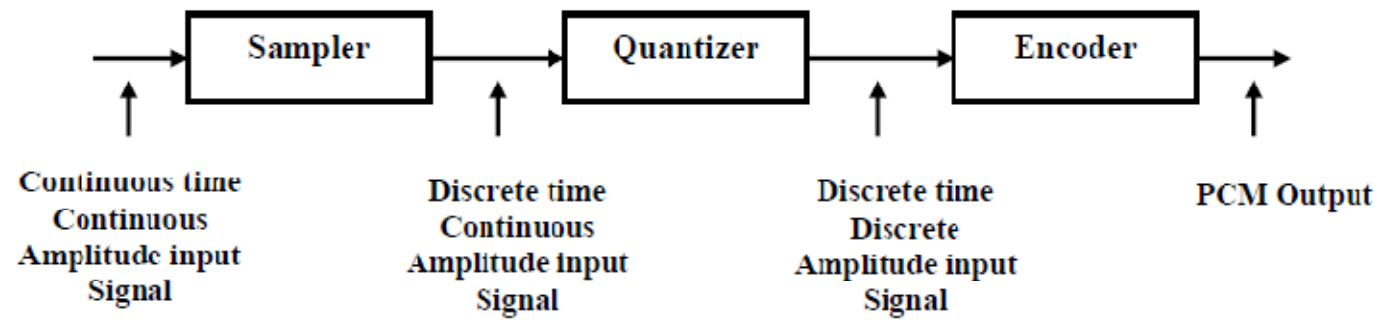
- The spectrum of $x_{PPM}(f)$ has to be passed on to a low pass filter for reconstruction of the signal. Low pass filter allows the spectrum from the band $-f_h$ to $+f_h$ and suppresses all other side bands. These outputs are then given to an integrator, which detects the original signal at the receiver side.



Comparison of Pulse modulation techniques

| S.No. | Parameter | PAM | PWM | PPM |
|-------|--|---------------------------------|---|--------------------|
| 1 | Type of carrier | Train of pulses | Train of pulses | Train of pulses |
| 2 | Variable characteristic of pulsed carrier | Amplitude | Width | Position |
| 3 | Bandwidth requirement | Low | High | High |
| 4 | Noise immunity | Low | High | High |
| 5 | Information is contained in | Amplitude variation | Width variation | Position variation |
| 6 | Transmitted power | Varies with amplitude of pulses | Varies with variation in width of pulse | Constant |
| 7 | Synchronization pulse | Not needed | Not needed | Necessary |
| 8 | Complexity level of generation and detection | Complex | Easy | Complex |





Quantiser

It converts a discrete-time, continuous-amplitude signal into an discrete time and discrete amplitude signal. Quantization is a process in which the amplitude of each sample is round off to the nearest permissible level. The process of quantization introduces a quantization error.

Quantization error:

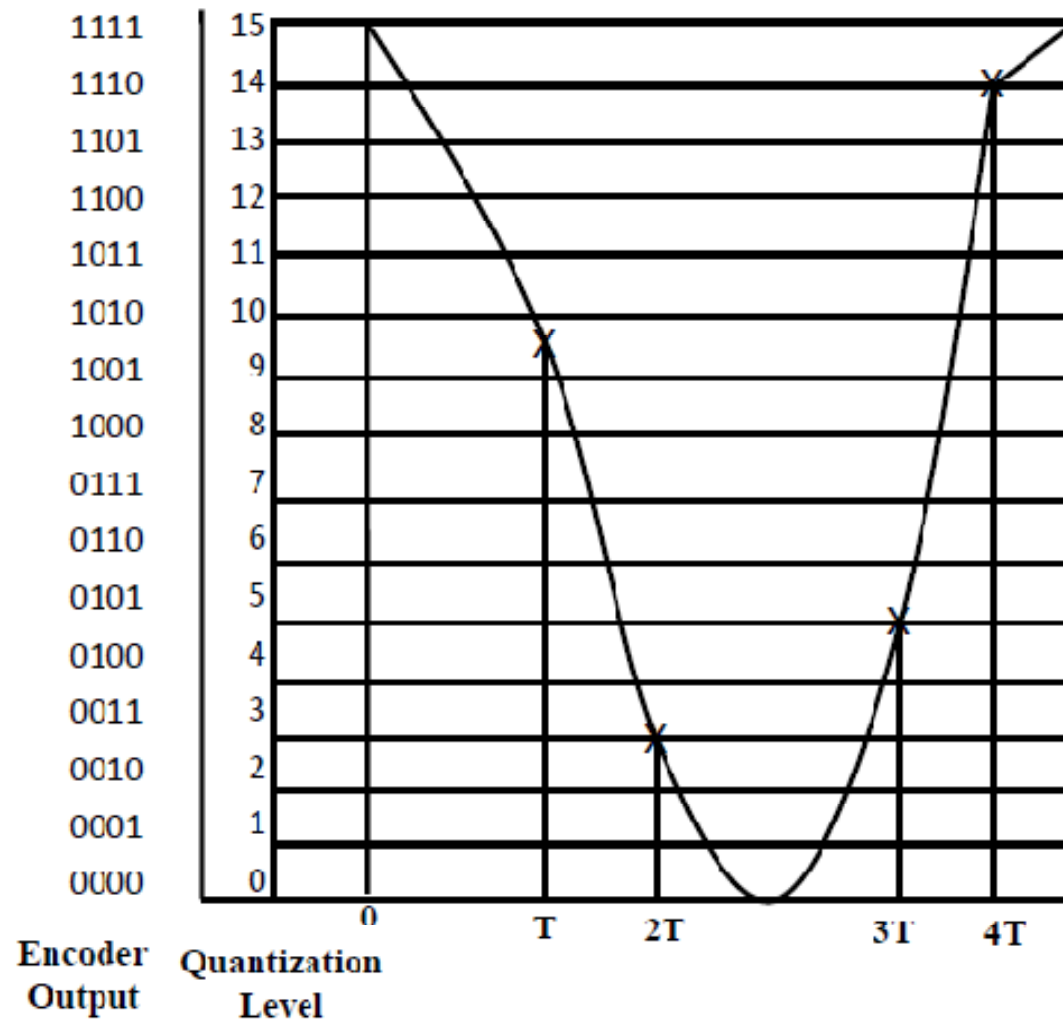
The difference between the original amplitude level to round off amplitude value.

For example in the figure, at time instant T, the original amplitude of signal is 9.8, but this value is round off to the nearest level in the quantization process as 10.

Now the quantization error= $10 - 9.8 = 0.2$.

Sampling interval is to be higher for reducing the error in quantization.





- *Encoder:* It represents each permissible level into an equivalent digital word. For example in the figure, at time instant $2T$, output of quantiser is $3V$. Now the equivalent digital word for $3V$ is 0011. This type of conversion is referred to as an encoder operation.
- The number of bits per encoder output is based on the number of quantization level. total number of quantization levels is 16. Hence the number of bits to represent the level is four.