Design and Implementation of resource-efficient light-weight CNN architecture

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Highlights of Proposed Model

- Designed a profile-based reconfigurable CNN accelerator using Vitis HLS 2023.1, synthesized in Vivado.
- Enabled dynamic profile selection based on input size (e.g., 28×28 , 32×32).
- Supported real-time CNN reconfiguration via AXI-stream, reducing logic redundancy.
- Achieved efficient resource usage (LUTs, DSPs, BRAM) through shared logic across profiles.

Challenges in Implementing CNNs for H/W Synthesis

- Mapping 2D convolutions to 1D streams suitable for FPGA processing.
- Adapting weights and biases dynamically without hardware re-synthesis.

Proposed Model for reconfigurable CNN

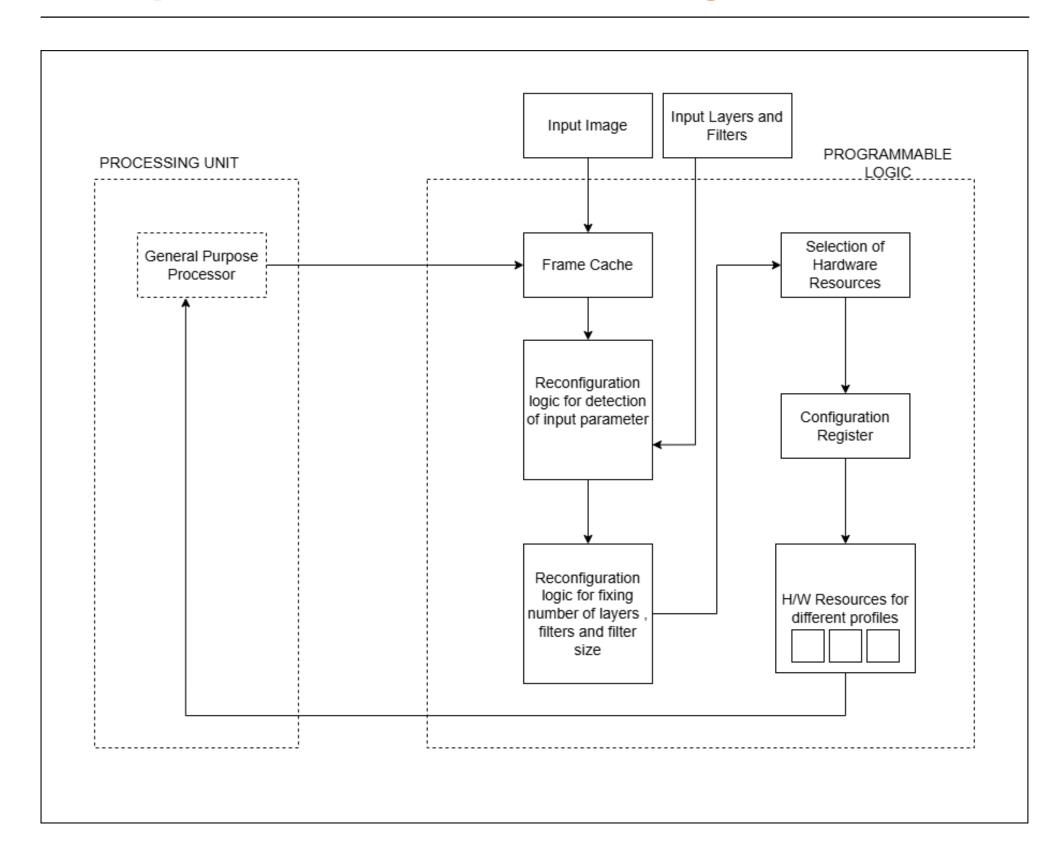


Figure 1. Proposed model Overview

Performance metrics of the wild animal detection

D		Dafila 2	FII Ct.a
Resource		Profile 2	Full System
LUT	24032	29007	33908
FF	27716	35621	32299
DSP	158	127	127
BRAM	70	58	184
SRL	412	373	2014
LUT Utilization	10.99%	13.27%	15.51%
DSP Utilization	17.56%	14.11%	14.11%
RAM Utilization	12.84%	10.64%	33.76%

Table 1. Comparison of Resource Utilization

Functional Modules and Dataset Description

Functional pipeline of Resource-Efficient Light-Weight CNN Architecture

Image Analysis & Configuration

- Input image acquisition and frame caching
- Parameter extraction (resolution, size, channels)
- Profile selection logic based on input metadata

CNN Configuration & Reconfiguration

- Dynamic configuration of layers, kernels, and pooling
 Activation of hardware resources from configuration profiles
- Register-based control for profile switching

CNN Processing

- Convolutional operations using streamed weights and image data
- Max pooling and activation layer operations
- Fully connected layer processing for classification

System Integration & Control

- AXI4-Stream interfacing for image, weight, and output data
- Processing System (PS) coordination and control (Zynq SoC)
- Synchronization, reset, and dataflow management

Dynamic Profile-Based CNN Configuration

- The MNIST dataset consists of grayscale images of handwritten digits (0–9), each with a size of 28x28 pixels, totaling 60,000 samples.
- It is used for digit recognition tasks and serves as the baseline for CNN profiling in Profile 1 configuration.
- For Profile 2, the images were upscaled to 32x32 pixels and trained with this modified resolution.

Hardware-Aware Deployment Using Vitis HLS and

- The system starts by analyzing the metadata of the input image (such as image size, resolution) to determine the most suitable CNN configuration.
- Based on the image characteristics, a profile is selected—Profile 1 for 28×28 images and Profile 2 for 32×32 images. Each profile has predefined convolutional layers, kernel sizes, and dense layers.
- This profiling enables dynamic reconfiguration of the CNN model at runtime without requiring multiple static hardware instances.
- Ensures resource efficiency and supports adaptive execution for varying datasets on FPGA using reconfigurable logic blocks.

- VivadoThe selected profile is compiled into an
- RTL-compatible block using Vitis HLS and integrated via Vivado Design Suite.
- Data flows through AXI4-Stream interfaces from input (image) to weight loaders, into CNN compute blocks, and finally to output streams.
- The FPGA performs convolution, pooling, activation, and fully connected operations using reconfigurable blocks controlled by a configuration register.
- A Zynq-7000 SoC integrates programmable logic with a general-purpose processor, ensuring low-latency, high-throughput inference on edge devices.

Input Image Input Image demographic data Profile 1 Weight and Bais Main Function Block-CNN-2 proc0 UO Reconfigurable CNN

Figure 2. Vitis HIs pipeline

Weight hls stream

Class1 : P1

Class2 : P2

Class3 : P3

Selected Weigh

CNN-based Digit/Object Classification

- Convolutional layers extract spatial and local features from input images (e.g., edges, curves, textures).
- Max pooling layers reduce spatial dimensions while retaining essential features, improving computational efficiency.
- Fully connected layers perform classification based on the extracted features, producing confidence scores across target classes.

Block Diagram - Vivado

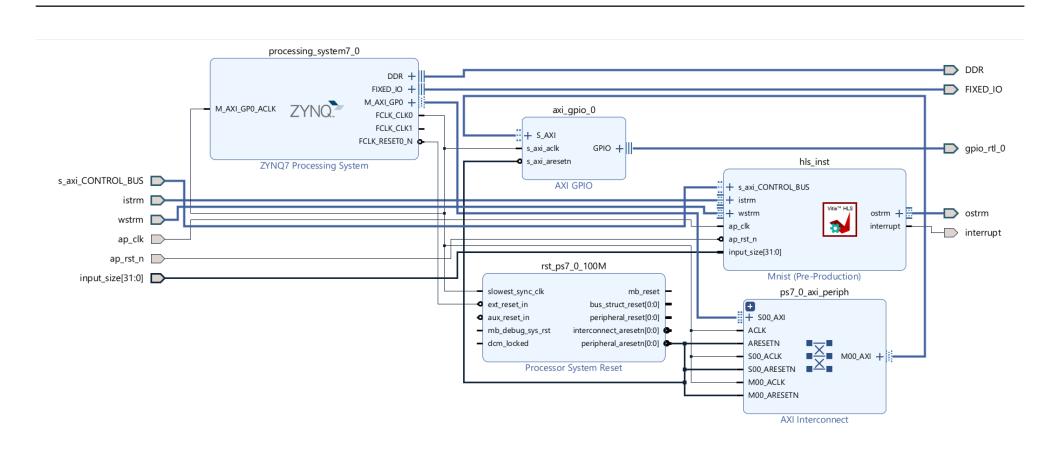


Figure 3. Species detected by YOLOV5

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