

# UART Tx and Rx Code in Keil

20 June 2025 17:12

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#include "stm32f429xx.h"

void delay()
{
    for(volatile int i=5000000;i--; );
}

void usart_init()
{
    //Enable gpio clk for port A (usart1), connected to AHB1 bus
    RCC->AHB1ENR |=RCC_AHB1ENR_GPIOAEN;
    //The USART1 is connected to the AP2 bus
    RCC->APB2ENR |= RCC_APB2ENR_USART1EN;

    //Configure Gpio ports
    GPIOA->MODER &=~((3<<(9*2)) | (3<<(10*2)));//clearing the 9th and 10th pin
    GPIOA->MODER |=((2<<(9*2)) | (2<<(10*2)));//setting the pins as AF
    // here we are using 3 (0b11) to clear the 2 bits in each pin
    // here we are using 2 (0b10) to set the alternate function mode in the pins

    GPIOA->OTYPER |=0x00000000;//setting type as push pull
    GPIOA->AFR[1] &= ~(0xFF << 4);//clearing the bits in the AFR register for pins 9 & 10
    GPIOA->AFR[1] |= ( ( 7 << (9-8)*4 ) | ( 7 << (10-8)*4 ) );

    /* In the above line, 2nd expression : 7 on LHS refers to the AF7 value in decimal,
       refer to rm-stm32f29, pg no. 289.
       (10 - 8) => 10th pin, - 8 because the AFRH starts from 8th bit, and *4 because we want to
       cover the bits
    */
    // The same expression could be done for clearing as well, since it was continuous 1s,
    // and the pins were next to each other i simply chose to give FF to clear out 8 bits
    countinously

    //clk is 16MHz, crystal oscillator (HIS)
    //USARTDIV=fclk/(16*Baud)
    //For baud rate 9600, mantissa = 104, fraction = .166 * 16 = 3
    USART1->BRR = (104<<4) | 3;

    USART1->CR1=0;
    USART1->CR1 |= USART_CR1_TE | USART_CR1_RE;//Setting TE and RE bit
    USART1->CR1 |= USART_CR1_UE; //(1 << 13)Setting the UE bit
    USART1->CR1 &= ~(USART_CR1_M);//(1<<12);//Setting(0) M bit as 8
    USART1->CR1 &= ~(USART_CR1_OVER8);//(1<<15);Setting OVER8 as oversampling by 16.
    USART1->CR2 &=~(3<<(12));//setting stop bits as 00

}

void send_char(char ch)
{
    while(!(USART1->SR & USART_SR_TXE));//Waits until the data is tranferred from TDR to shift
    register
    USART1->DR=ch;//Transmits the data to data register.
}
```

```

}
void send_string(char *str)
{
    while(*str)
    {
        send_char(*str++);
    }
}

unsigned char getc(void)
{
    while(!(USART1->SR & USART_SR_RXNE)); //Waits until a data is received, RXNE means Rx not
    Empty
    return USART1->DR;
}

int main()
{
    usart_init();
    delay();
    unsigned char c;

    while(1)
    {
        send_string("Hello stm32\n\r");
        //This is not working, but we comment the receive part, we can see this message
        delay();

        /* NOTE : Set the baud rate in Tera Term before connecting */

        c=getc(); //Type a character and it will be displayed
        send_string("\r\nInput is : ");
        send_char(c);

    }

}

```