# **GPU Programming**

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#### **CUDA Function Declarations**

	Executed on the:	Callable from only the:
device float DeviceFunc()	device	device
global void KernelFunc()	device	host
host float HostFunc()	host	host

- global defines a kernel. It must return void.
- A program may have several functions of each kind.
- The same function of any kind may be called multiple times.
- Host == CPU, Device == GPU.

# Function Types (1/2)

```
#include <stdio.h>
#include <cuda.h>
  printf("I can run on both CPU and GPU.\n");
  _device___ unsigned dfun(unsigned *vector, unsigned vectorsize, unsigned id) {
    if (id == 0) dhfun();
    if (id < vectorsize) {</pre>
         vector[id] = id;
         return 1:
    } else {
         return 0;
  global void dkernel(unsigned *vector, unsigned vectorsize) {
     unsigned id = blockldx.x * blockDim.x + threadIdx.x;
     dfun(vector, vectorsize, id);
  host__ void hostfun() {
     printf("I am simply like another function running on CPU. Calling dhfun\n");
     dhfun();
```

# Function Types (2/2)

```
#define BLOCKSI7F
                         1024
int main(int nn, char *str[]) {
     unsigned N = atoi(str[1]);
     unsigned *vector, *hvector;
     cudaMalloc(&vector, N * sizeof(unsigned));
     hvector = (unsigned *)malloc(N * sizeof(unsigned));
     unsigned nblocks = ceil((float)N / BLOCKSIZE);
     printf("nblocks = %d\n", nblocks);
     dkernel<<<nblocks, BLOCKSIZE>>>(vector, N);
     cudaMemcpy(hvector, vector, N * sizeof(unsigned), cudaMemcpyDeviceToHost);
     for (unsigned ii = 0; ii < N; ++ii) {
          printf("%4d ", hvector[ii]);
                                                              ► hostfun
                                                   main
                                                                                      U
     printf("\n");
                                                                         dhfun
                                                                                      G
     hostfun();
                                                                 dfun
                                                 dkernel
     dhfun();
                                                                                      U
     return 0;
```

What are the other arrows possible in this diagram?

### with HostAlloc'ed Memory

```
host__ __device__ void fun(int *counter) {
     ++*counter:
  _global__ void printk(int *counter) {
     fun(counter);
     printf("printk (after fun): %d\n", *counter);
int main() {
     int *counter:
     cudaHostAlloc(&counter, sizeof(int), 0);
     *counter = 0:
     printf("main: %d\n", *counter);
     printk <<<1, 1>>>(counter);
     cudaDeviceSynchronize();
     fun(counter);
     printf("main (after fun): %d\n", *counter);
     return 0;
```

What is the output of this code?

### with HostAlloc'ed Memory

```
host__ _device__ void fun(int *counter) {
     ++*counter;
       syncthreads();
  _global__ void printk(int *counter) {
     fun(counter);
     printf("printk (after fun): %d\n", *counter);
int main() {
     int *counter:
     cudaHostAlloc(&counter, sizeof(int), 0);
     *counter = 0;
     printf("main: %d\n", *counter);
     printk <<<1, 1>>>(counter);
     cudaDeviceSynchronize();
     fun(counter);
     printf("main (after fun): %d\n", *counter);
     return 0;
```

\_\_syncthreads() is not available on CPU.

### with HostAlloc'ed Memory

```
host__ __device__ void fun(int *counter) {
     ++*counter:
  _global___ void printk(int *counter) {
     fun(counter);
     printf("printk (after fun): %d\n", *counter);
int main() {
     int *counter:
     // cudaHostAlloc(&counter, sizeof(int), 0);
    cudaMalloc(&counter, sizeof(int));
     *counter = 0;
     printf("main: %d\n", *counter);
     printk <<<1, 1>>>(counter);
     cudaDeviceSynchronize();
     fun(counter);
     printf("main (after fun): %d\n", *counter);
     return 0;
```

counter cannot be accessed on CPU.

#### Global Variables

```
int counter;
  host
             _device___ void fun() {
     ++counter;
  _global__ void printk() {
     fun();
     printf("printk (after fun): %d\n", counter);
int main() {
     counter = 0;
     printf("main: %d\n", counter);
     printk <<<1, 1>>>();
     cudaDeviceSynchronize();
     fun();
     printf("main (after fun): %d\n", counter);
     return 0;
```

counter cannot be accessed on **GPU**.

#### Global Variables

```
host __ device __ int counter;
          __device__ void fun() {
  host
     ++counter;
  _global__ void printk() {
     fun();
     printf("printk (after fun): %d\n", counter);
int main() {
     counter = 0;
     printf("main: %d\n", counter);
     printk <<<1, 1>>>();
     cudaDeviceSynchronize();
     fun();
     printf("main (after fun): %d\n", counter);
     return 0;
```

Variables cannot be declared as host .

#### Global Variables

```
_device__ int counter;
             _device___ void fun() {
  host
     ++counter;
  _global___ void printk() {
     fun();
     printf("printk (after fun): %d\n", counter);
int main() {
     printk <<<1, 1>>>();
     cudaDeviceSynchronize();
     return 0;
```

Warning during compilation, but works fine.

### Classwork

Write a CUDA code to increment all elements in an array. Call this code from host as well as device.

**Homework:** Can you avoid the for loop in **fun**?

```
<u>host__</u> <u>__device__</u> void fun(int *arr) {
     for (unsigned ii = 0; ii < N; ++ii)
           ++arr[ii];
  _global__ void dfun(int *arr) {
     fun(arr);
int main() {
     int arr[N], *darr;
     cudaMalloc(&darr, N * sizeof(int));
     for (unsigned ii = 0; ii < N; ++ii)
           arr[ii] = ii;
     cudaMemcpy(darr, arr, N * sizeof(int),
                    cudaMemcpyHostToDevice);
     fun(arr);
     dfun<<<1, 1>>>(darr);
     cudaDeviceSynchronize();
     return 0;
```

#### **Thrust**

- Thrust is a parallel algorithms library (similar in spirit to STL on CPU).
- Supports vectors and associated transforms.
- Programmer is oblivious to where code executes
   on CPU or GPU.
- Makes use of C++ features such as functors.

```
#include <thrust/host vector.h>
#include <thrust/device vector.h>
#include <iostream>
int main(void) {
    // H has storage for 4 integers
    thrust::host vector<int> H(4);
    // initialize individual elements
    H[0] = 14; H[1] = 20; H[2] = 38; H[3] = 46;
    // H.size() returns the size of vector H
    std::cout << "H has size " << H.size() << std::endl;
    // print contents of H
    for(int i = 0; i < H.size(); i++) std::cout << "H[" << i << "] = " << H[i] << std::endl;
    // resize H
    H.resize(2);
    std::cout << "H now has size " << H.size() << std::endl;
    // Copy host vector H to device vector D
    thrust::device vector<int> D = H;
    // elements of D can be modified
    D[0] = 99; D[1] = 88;
    // H and D are automatically deleted when the function returns
    return 0;
                                                                                     13
```

```
#include <thrust/host_vector.h>
#include <thrust/device vector.h>
#include <thrust/copy.h>
#include <thrust/fill.h>
#include <thrust/sequence.h>
#include <iostream>
int main(void) {
     // initialize all ten integers of a device vector to 1
     thrust::device_vector<int> D(10, 1);
     // set the first seven elements of a vector to 9
     thrust::fill(D.begin(), D.begin() + 7, 9);
     // initialize a host vector with the first five elements of D
     thrust::host_vector<int> H(D.begin(), D.begin() + 5);
     // set the elements of H to 0, 1, 2, 3, ...
     thrust::sequence(H.begin(), H.end());
     // copy all of H back to the beginning of D
     thrust::copy(H.begin(), H.end(), D.begin());
     // print D
     for(int i = 0; i < D.size(); i++)
          std::cout << "D[" << i << "] = " << D[i] << std::endl;
     return 0;
```

### **Thrust**

```
thrust::host_vector<int> hnums(1024);
thrust::device_vector<int> dnums;
dnums = hnums; // calls cudaMemcpy
// initialization.
thrust::device_vector<int> dnum2(hnums.begin(), hnums.end());
hnums = dnum2; // array resizing happens automatically.
std::cout << dnums[3] << std::endl;
thrust::transform(dsrc.begin(), dsrc.end(), dsrc2.begin(),
                 ddst.begin(), addFunc);
```

### **Thrust Functions**

- find(begin, end, value);
- find\_if(begin, end, predicate);
- copy, copy\_if.
- count, count\_if.
- equal.
- min\_element, max\_element.
- merge, sort, reduce.
- transform.

# Thrust Algorithms

- Dual implementations: host and device
- Iterators as arguments must be on the same device
  - except *copy*, which can copy across devices
  - Otherwise, compiler issues error

```
#include <thrust/device vector.h>
#include <thrust/transform.h>
#include <thrust/sequence.h>
#include <thrust/copy.h>
#include <thrust/fill.h>
#include <thrust/replace.h>
#include <thrust/functional.h>
#include <iostream>
int main(void) {
    // allocate three device vectors with 10 elements
    thrust::device_vector<int> X(10);
    thrust::device_vector<int> Y(10);
    thrust::device vector<int> Z(10);
    // initialize X to 0,1,2,3, ....
    thrust::sequence(X.begin(), X.end());
    // compute Y = -X
    thrust::transform(X.begin(), X.end(), Y.begin(), thrust::negate<int>());
    // fill Z with twos
    thrust::fill(Z.begin(), Z.end(), 2);
    // compute Y = X \mod 2
    thrust::transform(X.begin(), X.end(), Z.begin(), Y.begin(), thrust::modulus<int>());
    // replace all the ones in Y with tens
    thrust::replace(Y.begin(), Y.end(), 1, 10);
    // print Y
    thrust::copy(Y.begin(), Y.end(), std::ostream iterator<int>(std::cout, "\n"));
    return 0;
```

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### Thrust User-Defined Functors

```
// calculate result[] = (a * x[]) + y[]
struct saxpy {
  const float _a;
  saxpy(int a) : _a(a) { }
  _host_ _device_
  float operator()(const float& x, const float& y) const {
    return a * x + y;
thrust::device_vector<float> x, y, result;
thrust::transform(x.begin(), x.end(), y.begin(), result.begin(), saxpy(a));
```

### Classwork

- Create two 32-element vectors:
  - X on host, Y on device
- Fill X with 10, fill Y with sequence 0..31
- Compute X = X Y
- Compute Z = X \* Y
  - // element-wise multiplication

#### **Thrust Reductions**

- Recall reductions in log(n) barriers
- No need to worry about blocks, synchronization.

```
int x, y;
thrust::host_vector<int> hvec;
thrust::device_vector<int> dvec;
// (thrust::reduce is a sum operation by default)
x = thrust::reduce(hvec.begin(), hvec.end()); // on CPU
y = thrust::reduce(dvec.begin(), dvec.end()); // on GPU
```

```
y = thrust::reduce(dvec.begin(), dvec.end(),
(int)0, thrust::plus<int>());
```

```
struct mycount {
     int a;
     mycount(int a): a(a){}
       host device
     int operator()(const int x, const int y) const {
          return (y == a ? x + 1 : x);
int main() {
     thrust::host vector<int> vec(10, 0);
     vec[1] = 5;
     vec[4] = 5;
     vec[9] = 5:
     int result = thrust::reduce(vec.begin(), vec.end(),
                                (int)0, mycount(5));
     std::cout << result << std::endl;
     return 0;
```

### Prefix Sum / Scan

```
#include <thrust/scan.h>
int data[6] = \{1, 0, 2, 2, 1, 3\};
// in-place scan
thrust::inclusive scan(data, data + 6, data);
// data is now {1, 1, 3, 5, 6, 9}
thrust::exclusive scan(data, data + 6, data);
// data is now {0, 1, 1, 3, 5, 6}
```

# Classwork: Find output

```
int main() {
    int data[] = \{-5, 0, 2, -3, 2, 4, 0, -1, 2, 8\};
    int sizedata = sizeof(data) / sizeof(*data);
    thrust::maximum<int> binop;
    thrust::exclusive scan(data, data + sizedata,
                              data, 1, binop);
    for (unsigned ii = 0; ii < sizedata; ++ii) {
         std::cout << data[ii] << " ";
    std::cout << std::endl;
    return 0;
```

### Sorting

```
#include <thrust/sort.h>
const int N = 6;
int A[N] = \{1, 4, 2, 8, 5, 7\};
thrust::sort(A, A + N);
// A is now {1, 2, 4, 5, 7, 8}
int keys[N] = \{1, 4, 2, 8, 5, 7\};
char values[N] = {'a', 'b', 'c', 'd', 'e', 'f'};
thrust::sort by key(keys, keys + N, values);
```

// keys is now { 1, 2, 4, 5, 7, 8}

// values is now {'a', 'c', 'b', 'e', 'f', 'd'}