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Vega: A Chatbot Platform for Development of Internet of Things and Embedded Systems

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ABSTRACT Large language models (LLMs) have revolutionized natural language processing, yet their potential in Internet of Things (IoT) applications remains largely untapped. Traditional IoT interfaces often require specialized knowledge, creating barriers for non-technical users. We present a modular system that leverages LLMs to enable intuitive, natural language control of IoT devices, specifically a Raspberry Pi (RPi) connected to various sensors and devices. Our solution comprises three key components: a physical circuit with input and output devices, an RPi integrating Control Server, and a web application integrating LLM logic. Users interact with the system through natural language commands, which the LLM interprets to call appropriate commands for the RPi. The RPi executes these instructions on the connected circuit, with outcomes communicated back to the user via LLM-generated responses. We empirically evaluate our system's performance across a range of task complexities and user scenarios, demonstrating its ability to handle complex, conditional logic without additional RPi-level coding. Our findings reveal that LLM-driven IoT control can effectively bridge the gap between complex device functionality and user-friendly interaction. We discuss the system's scalability, exploring its potential applications in diverse settings such as smart homes, industrial monitoring, and educational environments. By enabling natural language interaction with IoT devices, our approach not only enhances accessibility for non-technical users but also opens new avenues for creative and intelligent IoT applications. This research contributes to the growing body of work on interactive intelligent systems for IoT, offering insights into the design and implementation of LLM-integrated IoT interfaces.

INDEX TERMS Enter key words or phrases in alphabetical order, separated by commas. Autocorrelation, beamforming, communications technology, dictionary learning, feedback, fMRI, mmWave, multipath, system design, multipath, slight fault, underlubrication fault.

I. INTRODUCTION

THE evolution of large language models (LLM's) has led to rapid development in the realm of intelligent systems. However, the application of LLM's hasn't been thoroughly explored in internet of things (IoT) and embedded systems (ESys). Traditionally, the development of IoT systems that seamlessly adapt to the user's need and tasks poses a considerable challenge. Leveraging the capabilities of LLMs presents an opportunity to address this challenge and bridge the gap between technical intricacies and user accessibility.

II. BACKGROUND AND RELATED WORK

- A. PROGPROMPT
- B. TOD4IR
- C. CASIT

III. METHODOLOGY

A. OVERALL ARCHITECTURE

A

B. PHYSICAL CIRCUIT DESIGN

C. RASPBERRY PI DESIGN

D. WEB APP DESIGN

IV. EXPERIMENT AND RESULTS

- A. COMPLEX COMMANDS
- B. AUTOMATED EVALUATION
- C. RESULT ANALYSIS
- D. REAL LIFE APPLICABILITY

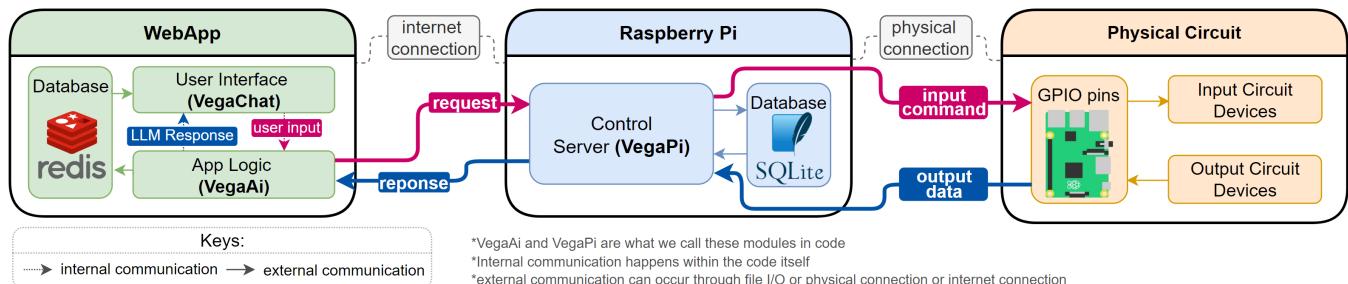


FIGURE 1. The overall architecture of the system.

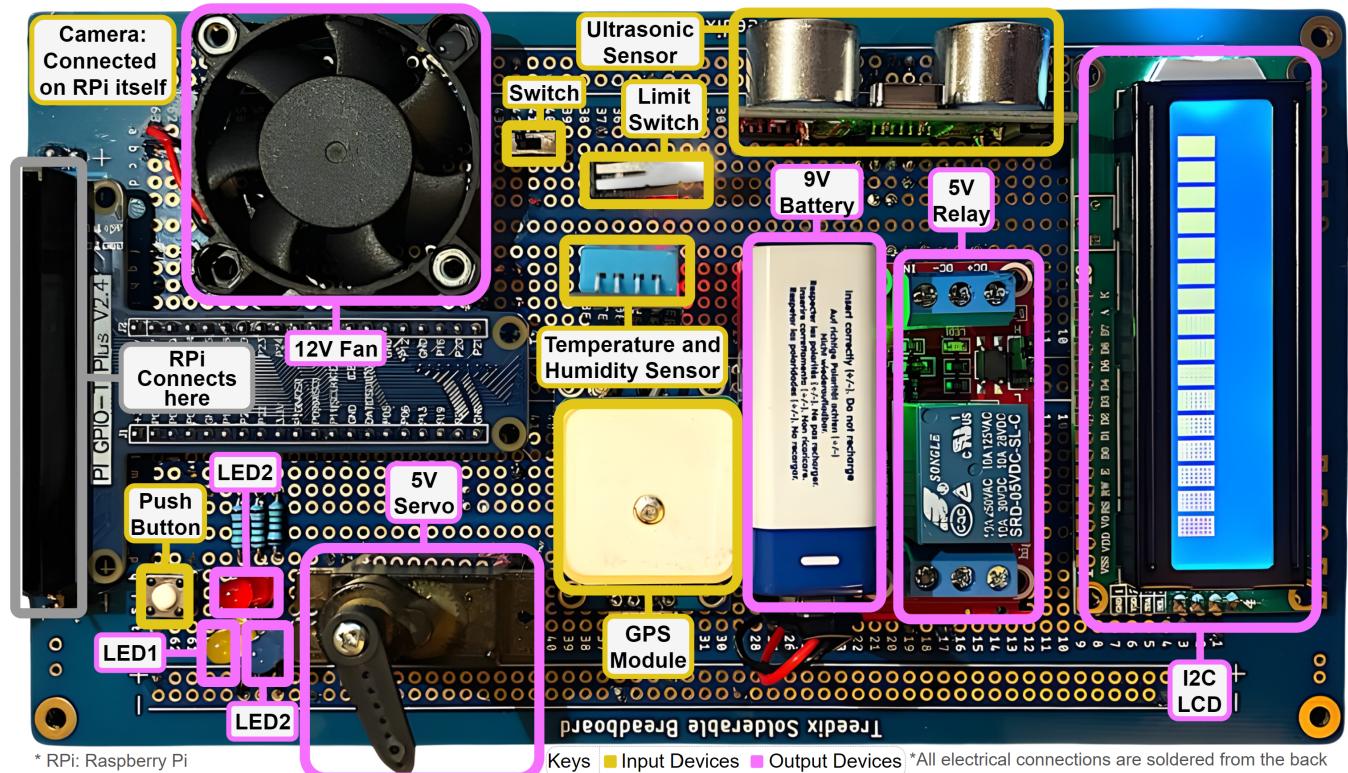


FIGURE 2. Soldered physical circuit connected to the RPi

TABLE 1. Physical devices defined on the Control Server, which are then supplied to the LLM

Symbol	Type	Description
ULTS	Input	Ultrasonic Distance Sensor in 'cm'
CAM	Input	Camera device for picture input
GPS	Input	GPS device for longitude and latitude coordinates
TMP	Input	Temperature sensor giving response in degree celcius
FAN	Output	12V fan controloed by a digital GPIO pin through a relay
LCD	Output	I2C LCD for displaying strings
SRV	Output	Servo motor rotates using PWM to a given angles
LED1	Output	Yellow LED light
LED2	Output	Red LED light
LED3	Output	Blue LED light

V. CONCLUSION

ACKNOWLEDGMENT

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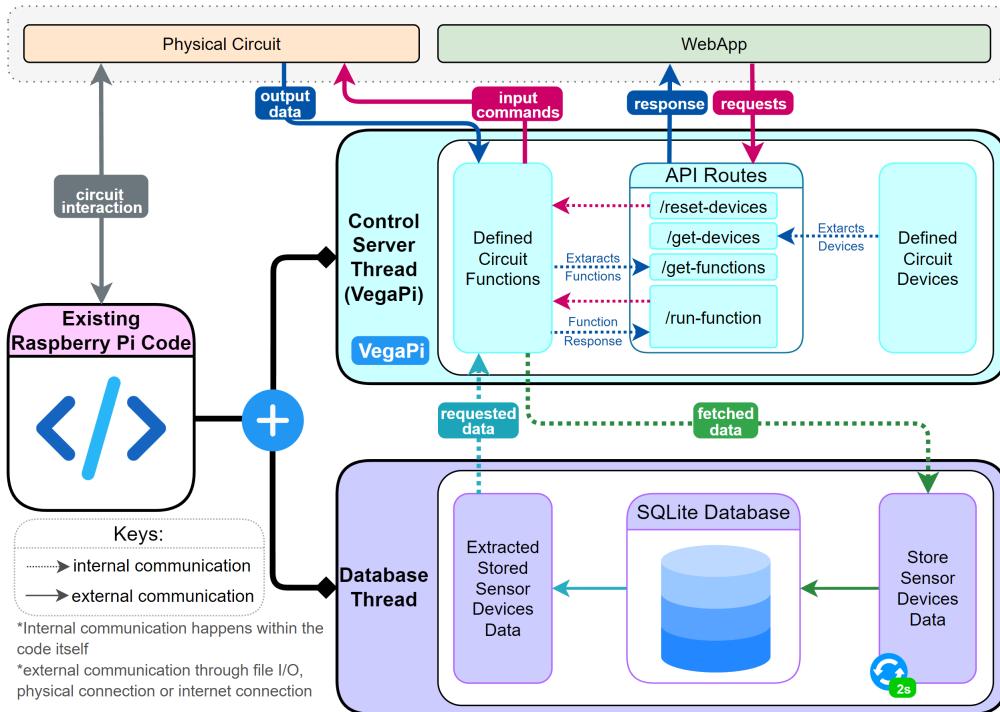


FIGURE 3. Architecture design of the RPi control server

TABLE 2. Defined functions on the Control Server, called by the LLM based on user input, executes on the RPi and processed on the webapp

Function	Description	Use Case
<code>set_led</code>	Toggles specific LED	"Turn on yellow LED"
<code>set_fan</code>	Toggles fan on or off	"Turn on the fan"
<code>get_recorded_sensor_data</code>	Gets interval sensor data from database	"Plot me the distance data in last 30 seconds"
<code>get_raspberry_stats</code>	Gets CPU, RAM, Disk of RPi	"What is the current disk usage"
<code>capture_image</code>	Captures an image and uploads it to Imgur	"Capture an image, does it contain a pen?"
<code>get_connected_devices</code>	Fetches the data of connected devices	"What is the current humidity and temperature"
<code>get_location_</code>	Gets the current location from GPS	"From the location are we currently in Leeds?"
<code>set_servo_angles</code>	Turn servo to certain angle	"Turn the servo to 10 then 180 degrees"

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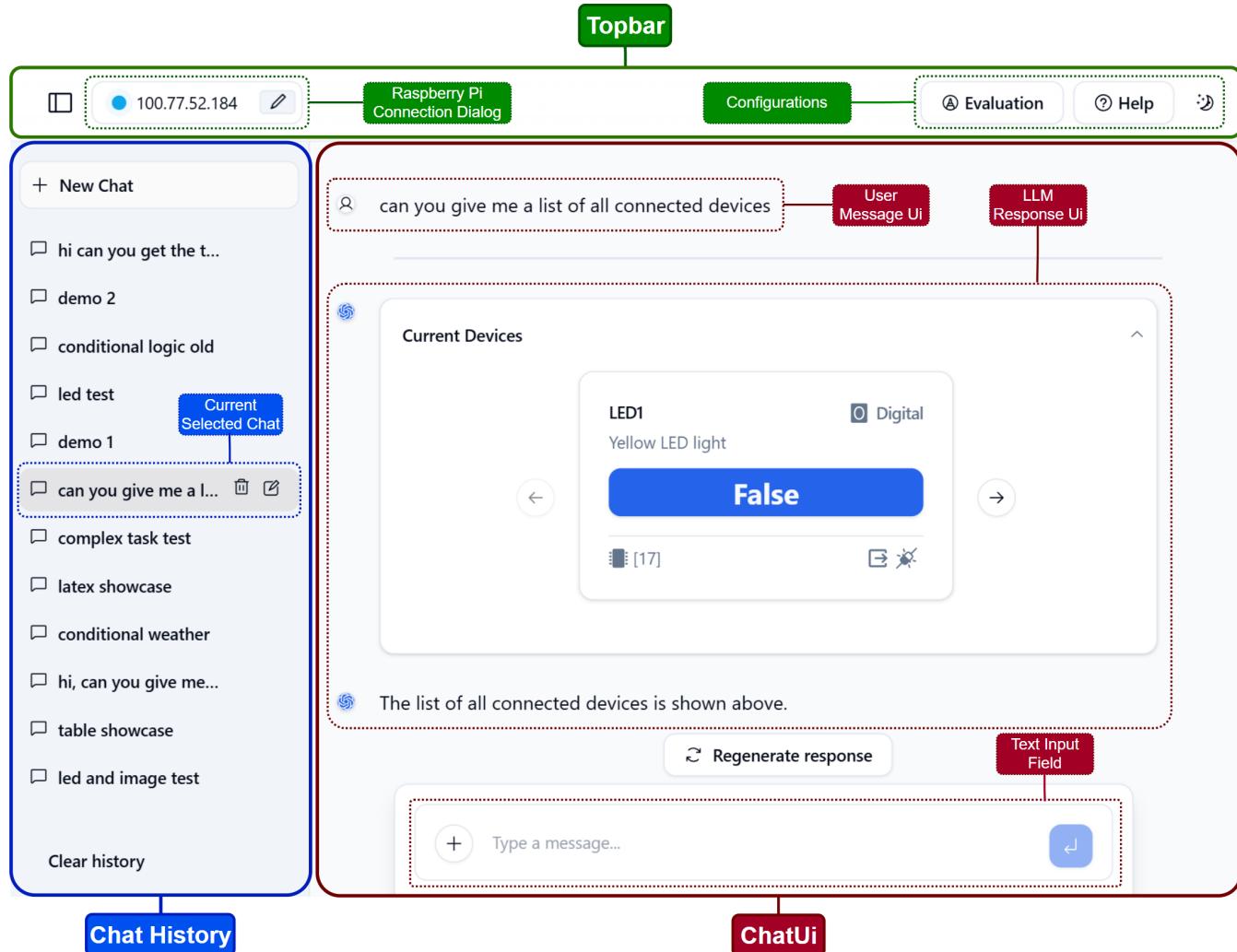
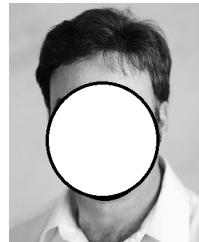


FIGURE 4. Webapp user interface implementation

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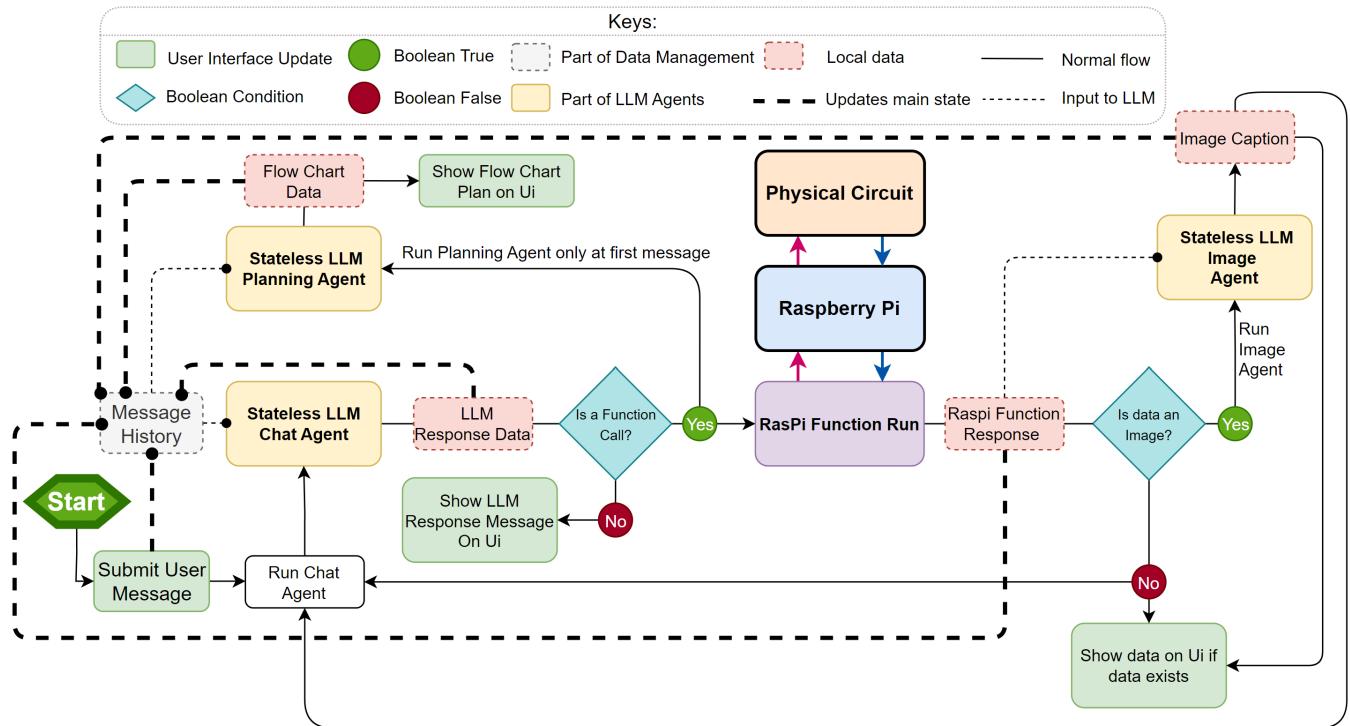


FIGURE 5. Webapp logic design



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WebApp - ChatUi - Case 1

- Get temperature. If more than 20°C, capture image. If image describes neon light, write 'hi everyone' on LCD. If both conditions fail, set red LED on.
- Gpt Flow Chart**

```

graph TD
    A["get_connected_devices {deviceNames: 'tmp'}"] -- "result > 20" --> B["capture_image"]
    B --> C["description does not contain 'neon light'"]
    C --> D["set_led {"name": "LED_RED", "value": "on"}"]
    C --> E["print_lcd {"text": "hi everyone"}"]
    E --> F["description contains 'neon light'"]
    F --> G["print_lcd {"text": "hi everyone"}"]
    
```
- Current Devices**
- Raspberry Pi Image**

The image depicts a bright white neon lightning bolt mounted on a wall, with the dark surroundings, creating a modern, minimalist mood
- The temperature is shown above, and based on the captured image description mentioning a neon light, "hi everyone" has been displayed on the LCD.

WebApp - ChatUi - Case 2

- If location is Leeds, check button click count. If more than 3, set servo to 45, 90 and get ULTS sensor data for last 30s. Else, turn on fan.
- Gpt Flow Chart**

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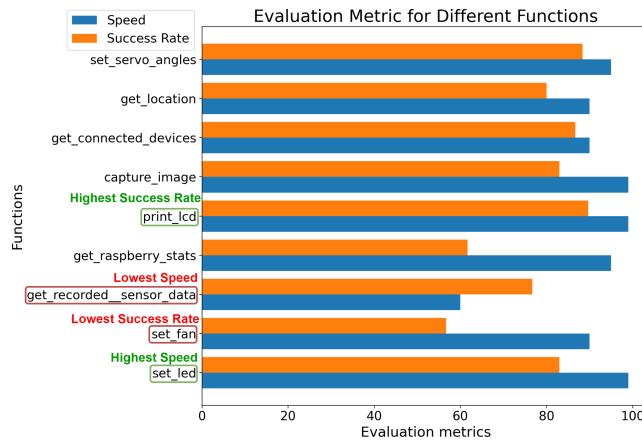
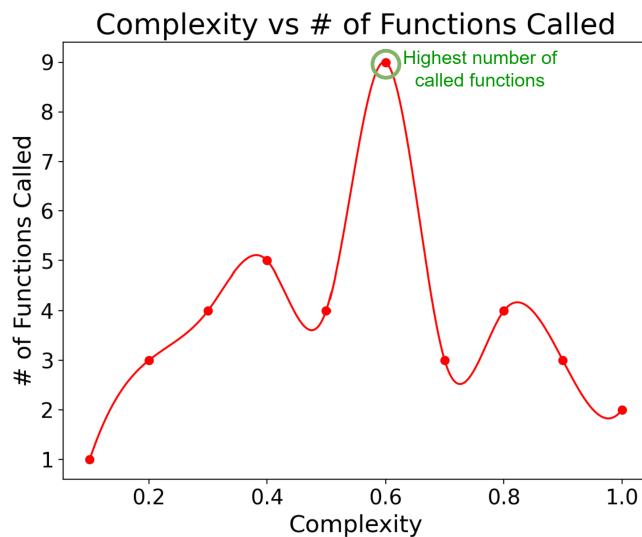
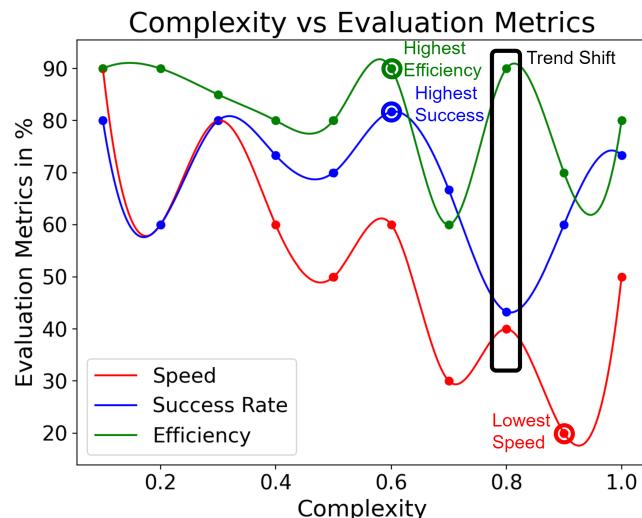
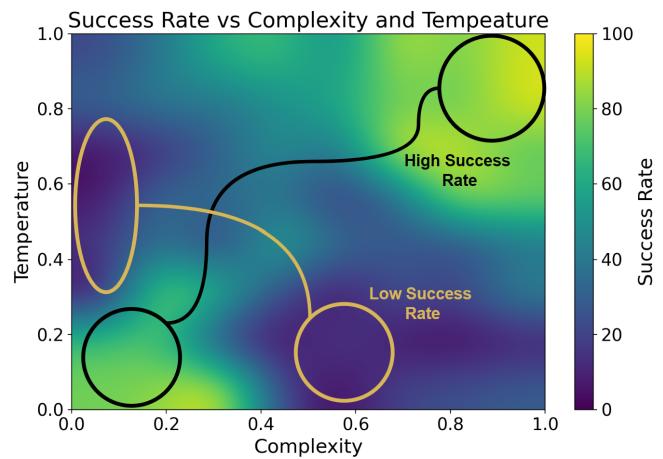
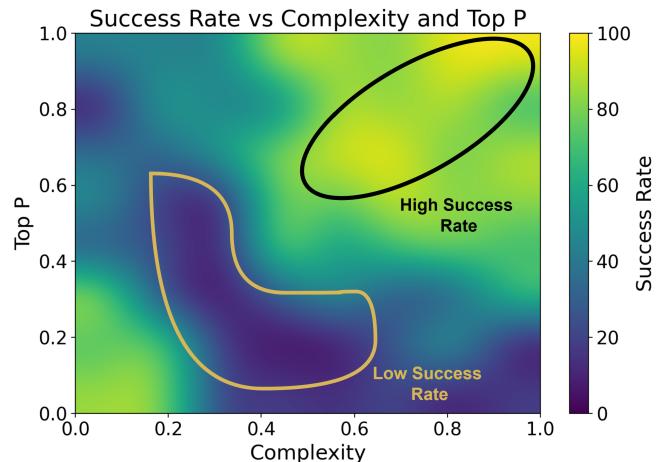
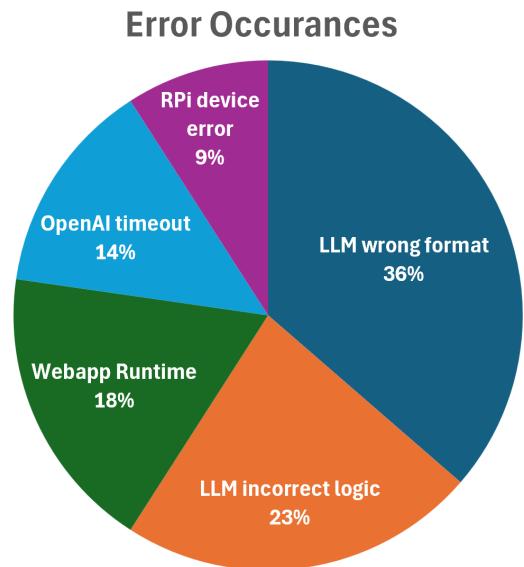
graph TD
    A["get_connected_devices {deviceNames: 'BUTTON'}"] --> B["clicks > 3"]
    B --> C["set_servo_angles {angles: '45, 90'}"]
    C --> D["after setting servo"]
    A --> E["get_location"]
    E --> F["location == leeds"]
    F --> G["set_fan {value: 'on'}"]
    F --> H["get_recorded_sensor_data {sensorNames: 'ULTS', interval: '30'}"]
    
```
- Map**
- Plot of ULTS (Time (s) vs Values)**

Time (s)	Values
390	2.34
392	2.34
394	2.34
396	2.34
398	2.34
400	2.34
402	1.94
404	2.34
406	2.34
408	2.34
410	2.34
412	2.34
414	2.34
416	2.35
418	2.34
- Button was clicked more than 3 times, Servo was set and data is displayed.

Physical Circuit - LCD

Physical Circuit - LCD

FIGURE 6. System case studies

**FIGURE 7.** Evaluation metrics for the functions defined earlier in .**FIGURE 8.** Message complexity against the number of functions called per message.**FIGURE 9.** Message complexity against all evaluation metrics and most importantly the success rate.**FIGURE 10.** Success rate against message complexity and temperature of the LLM.**FIGURE 11.** Success rate against message complexity and Top P of the LLM.**FIGURE 12.** What types of errors occurred throughout testing.

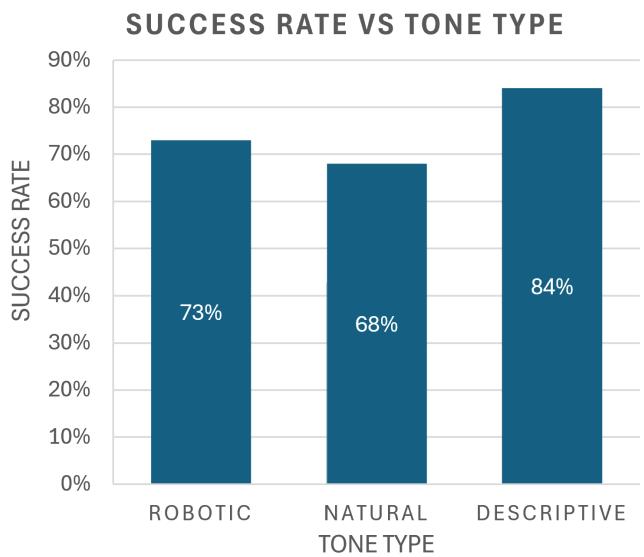


FIGURE 13. Success rate of different tones of the same message.