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Vega: Intelligent Chatbot Platform for Internet of Things and Embedded Systems Development

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ABSTRACT Large language models (LLMs) have revolutionized natural language processing, yet their potential in Internet of Things (IoT) and embedded systems (ESys) applications remains largely untapped. Traditional IoT interfaces often require specialized knowledge, creating barriers for non-technical users. We present a modular system that leverages LLMs to enable intuitive, natural language control of IoT devices, specifically a Raspberry Pi (RPI) connected to various sensors and devices. Our solution comprises three key components: a physical circuit with input and output devices, an RPi integrating a control server, and a web application integrating LLM logic. Users interact with the system through natural language commands, which the LLM interprets to call appropriate commands for the RPi. The RPi executes these instructions on the connected circuit, with outcomes communicated back to the user via LLM-generated responses. We empirically evaluate our system's performance across a range of task complexities and user scenarios, demonstrating its ability to handle complex, conditional logic without additional RPi-level coding. Our findings reveal that LLM-driven IoT control can effectively bridge the gap between complex device functionality and user-friendly interaction. We discuss the system's scalability, exploring its potential applications in diverse settings such as smart homes, industrial monitoring, and educational environments. By enabling natural language interaction with IoT devices, our approach not only enhances accessibility for non-technical users but also opens new avenues for creative and intelligent IoT applications. This research contributes to the growing body of work on interactive intelligent systems for IoT, offering insights into the design and implementation of LLM-integrated IoT interfaces.

INDEX TERMS Enter key words or phrases in alphabetical order, separated by commas. Autocorrelation, beamforming, communications technology, dictionary learning, feedback, fMRI, mmWave, multipath, system design, multipath, slight fault, underlubrication fault.

I. INTRODUCTION

Large language models (LLMs) have revolutionized natural language processing, demonstrating unprecedented capabilities in understanding and generating human-like text [1]. However, their potential in Internet of Things (IoT) and embedded systems (ESys) applications remains largely untapped. IoT systems have become increasingly prevalent across various domains, from smart homes to industrial automation [2]. Despite their widespread adoption, developing and interacting with IoT systems often requires specialized knowledge and programming skills, creating significant barriers for non-technical users [3].

Traditional IoT interfaces typically rely on graphical user interfaces (GUIs) or specific programming languages, which can be challenging for users without technical expertise [3].

This limitation hinders the widespread adoption and utilization of IoT technologies, particularly in scenarios where rapid deployment and intuitive interaction are crucial. While research has been conducted on natural language interfaces for IoT, the application of advanced language models to IoT control and interaction remains an underexplored area [4].

To address these challenges, we propose Vega, an intelligent chatbot platform that leverages LLMs to enable intuitive, natural language control of IoT devices. Our system focuses on a Raspberry Pi (RPI) connected to various sensors and devices as a representative IoT setup. By integrating LLMs with IoT infrastructure, we aim to bridge the gap between complex device functionality and user-friendly interaction, allowing users to control and query IoT systems using everyday language.

Our research builds upon recent advancements in LLMs, specifically OpenAI's GPT-based models [5], which utilize transformer neural network architectures to capture context and relationships within text data. By applying these powerful language understanding capabilities to IoT interaction, we aim to create a more accessible and flexible approach to device control and monitoring. Our approach not only enhances accessibility for non-technical users but also opens new avenues for creative and intelligent IoT applications, addressing the standardization challenges highlighted in the literature [6].

Vega's architecture comprises three key components: a physical circuit with input and output devices, an RPi integrating a control server, and a web application incorporating LLM logic. This modular design allows for flexibility and scalability, enabling the system to adapt to various IoT scenarios and user requirements [7]. By utilizing the RPi as a central hub, we can leverage its versatility and widespread adoption in the IoT community [8].

The main contributions of this paper are as follows:

- 1) We present a modular architecture that integrates LLMs with IoT systems, specifically designed for natural language interaction with RPi-based setups.
- 2) We develop a novel approach for translating natural language commands into executable instructions for IoT devices, capable of handling complex, conditional logic without additional RPi-level coding.
- 3) We implement and evaluate a prototype system demonstrating the feasibility and effectiveness of LLM-driven IoT control across a range of task complexities and user scenarios.
- 4) We provide insights into the scalability and potential applications of our approach in diverse settings such as smart homes, industrial monitoring, and educational environments.

The rest of this paper is organized as follows: Section II provides background information and discusses related work in IoT interfaces and natural language processing. Section III details our methodology, including the overall system architecture, physical circuit design, RPi configuration, and web application implementation. Section IV presents our experimental setup, results, and analysis, showcasing the system's performance in handling complex commands and its potential real-world applications. Finally, Section V concludes the paper and outlines directions for future research.

II. BACKGROUND AND RELATED WORK

A. NLP IN IOT AND ESYS

B. LLM'S IN INDUSTRIAL APPLICATIONS

C. ACCESSIBLE CHATBOT

III. METHODOLOGY

Hi [7] how are you

A. OVERALL ARCHITECTURE

B. PHYSICAL CIRCUIT DESIGN

TABLE 1. Physical devices defined on the Control Server, which are then supplied to the LLM

Symbol	Type	Description
ULTS	Input	Ultrasonic Distance Sensor in 'cm'
CAM	Input	Camera device for picture input
GPS	Input	GPS device for longitude and latitude coordinates
TMP	Input	Temperature sensor giving response in degree celcius
FAN	Output	12V fan controled by a digital GPIO pin through a relay
LCD	Output	I2C LCD for displaying strings
SRV	Output	Servo motor rotates using PWM to a given angles
LED1	Output	Yellow LED light
LED2	Output	Red LED light
LED3	Output	Blue LED light

TABLE 2. Defined functions on the Control Server, called by the LLM based on user input, executes on the RPi and processed on the webapp

Function	Description	Use Case
set_led	Toggles specific LED	"Turn on yellow LED"
set_fan	Toggles fan on or off	"Turn on the fan"
get_recorded_sensor_data	Gets interval sensor data from database	"Plot me the distance data in last 30 seconds"
get_raspberry_stats	Gets CPU, RAM, Disk of RPi	"What is the current disk usage"
capture_image	Capture and upload image to Imgur	"Capture an image, does it contain a pen?"
get_connected_devices	Fetches the data of connected devices	"What is the current humidity and temperature"
get_location_	Gets the current location from GPS	"From the location are we currently in Leeds?"
set_servo_angles	Turn servo to certain angle	"Turn the servo to 10 then 180 degrees"

C. RASPBERRY PI DESIGN

D. WEB APP USER INTERFACE

E. WEB APP LLM LOGIC

IV. EXPERIMENT AND RESULTS

A. COMPLEX COMMANDS IN ACTION

B. AUTOMATED EVALUATION

C. RESULT ANALYSIS

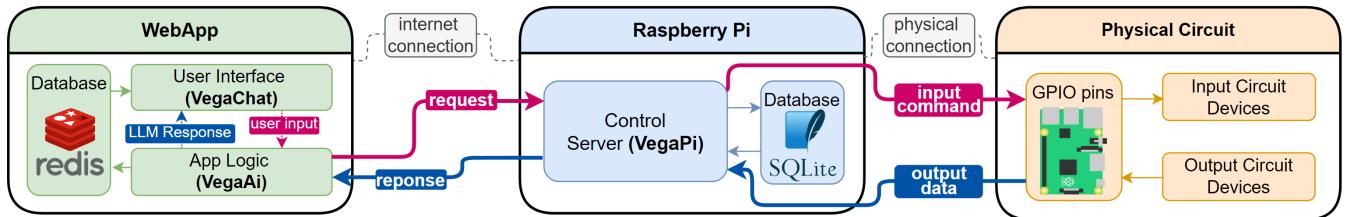
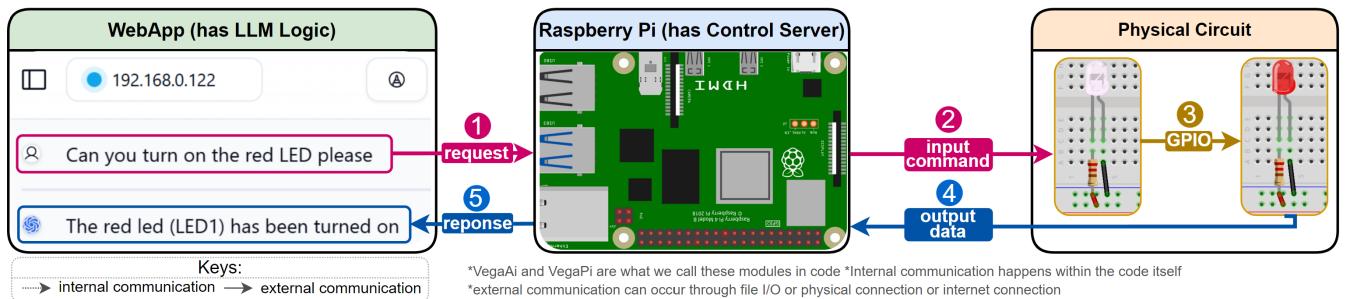
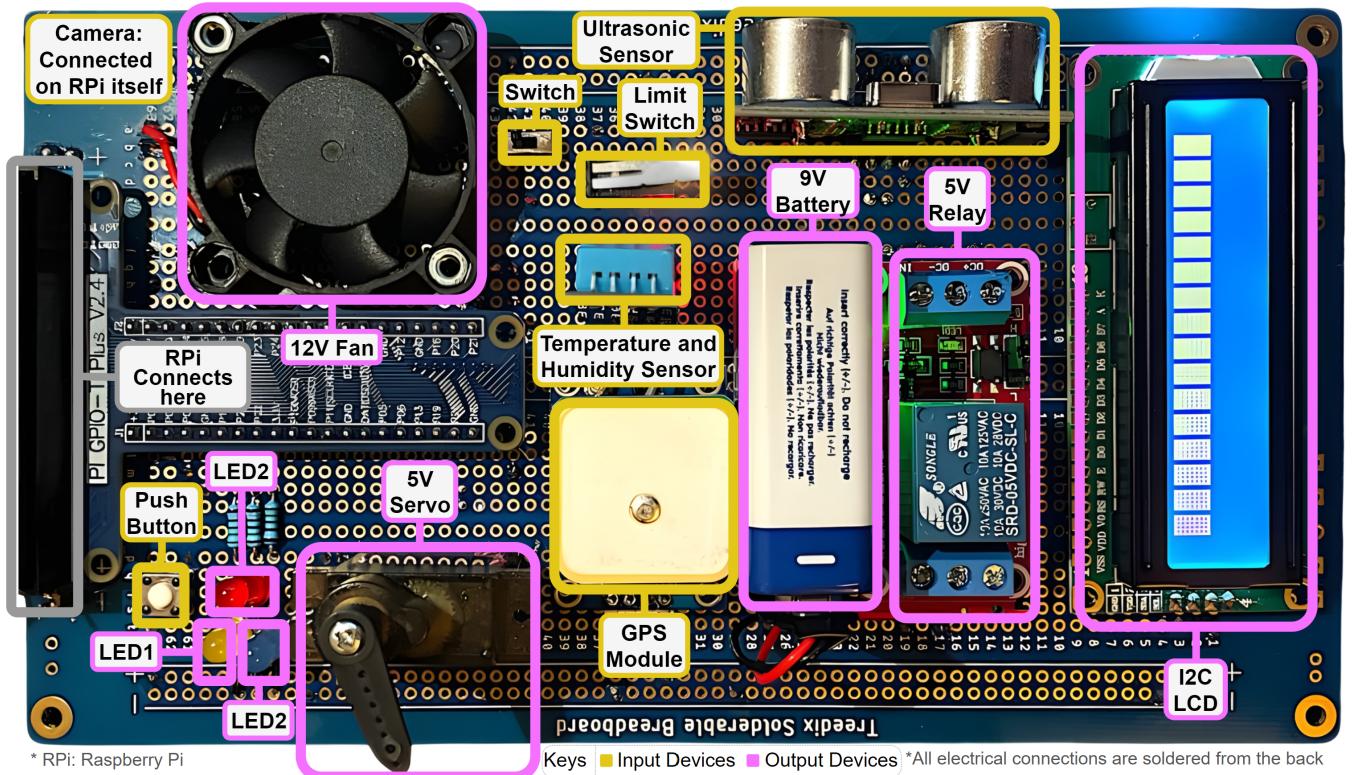
D. REAL LIFE APPLICABILITY

V. CONCLUSION AND FUTURE WORK

ACKNOWLEDGMENT

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a: Overall Architecture**b: Example Showcase****FIGURE 1.** Magnetization as a function of applied field. It is good practice to explain the significance of the figure in the caption.**FIGURE 2.** Soldered physical circuit connected to the RPi

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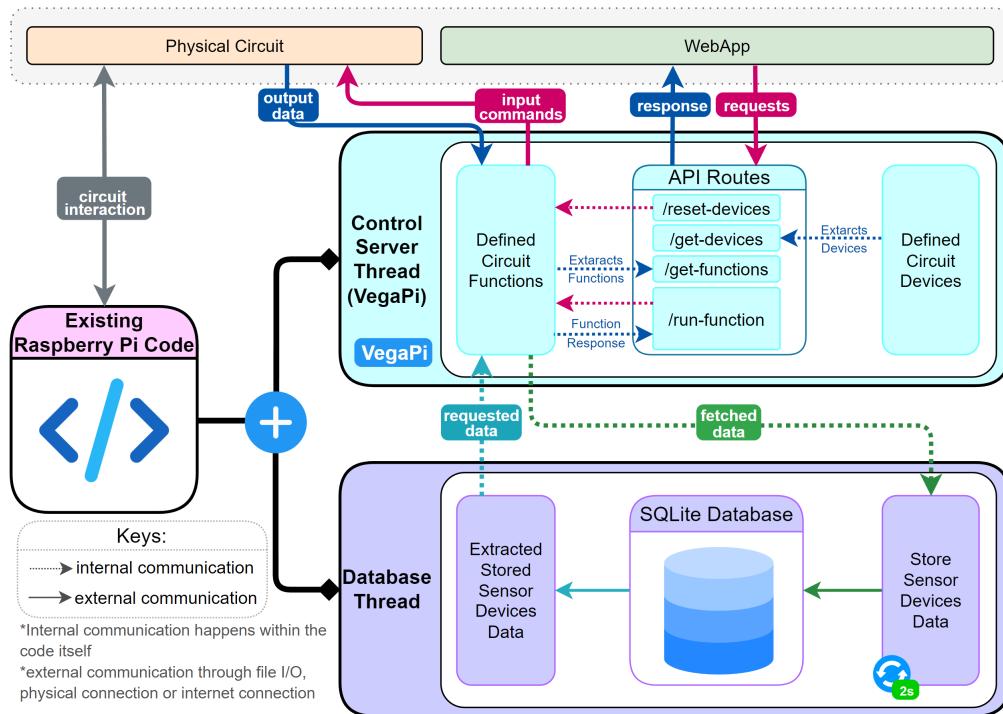


FIGURE 3. Architecture design of the RPi control server



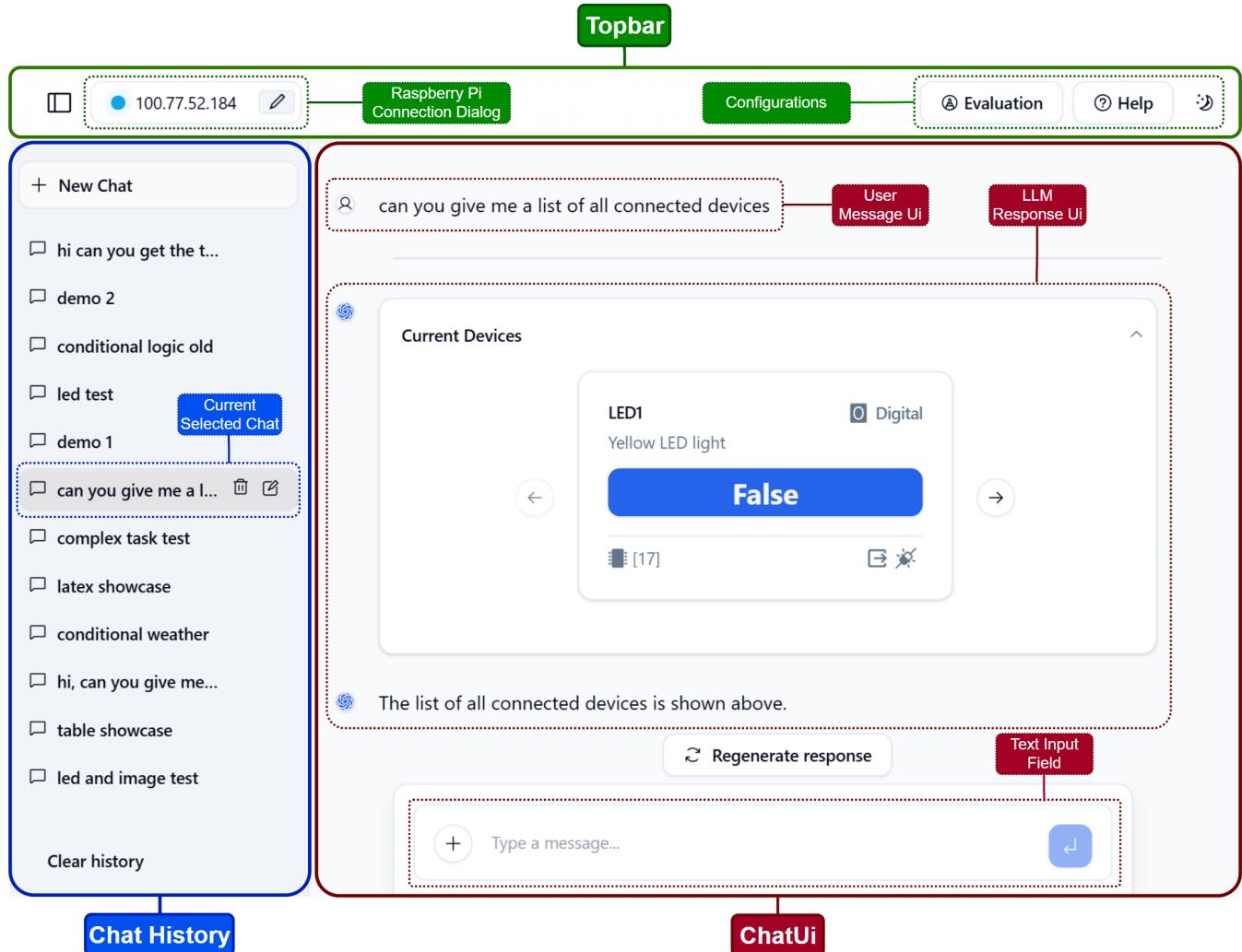
HARITH AL-SAFI received the BEng industrial degree in Electronics and Computer Engineering from the University of Leeds, Leeds, in 2024. From 2022 to 2023, he was an IoT Software Engineer at Johnson Controls. He is currently pursuing a Graduate Software Developer role at BT Group. His research interests include IoT, embedded systems, and machine learning.



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The second paragraph uses the pronoun of the person (he or she) and not the author's last name. It lists military and work experience, including summer and fellowship jobs. Job titles are capitalized. The current job must have a location; previous positions may be listed without one. Information concerning previous publications may be included. Try not to list more than three books or published articles. The format for listing publishers of a book within the biography is: title of book (publisher name, year) similar to a reference. Current and previous research interests end the paragraph.

The third paragraph begins with the author's title and last name (e.g., Dr. Smith, Prof. Jones, Mr. Kajor, Ms. Hunter). List any memberships in professional societies other than the IEEE. Finally, list any awards and work for IEEE committees and publications. If a photograph is provided, it should be of good quality, and professional-looking. Following are two examples of an author's biography.

**FIGURE 4.** Webapp user interface implementation

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Mr. Author's awards and honors include the Frew Fellowship (Australian Academy of Science), the I. I. Rabi Prize (APS), the European Frequency and Time Forum Award, the Carl Zeiss Research Award, the William F. Meggers Award and the Adolph Lomb Medal (OSA).

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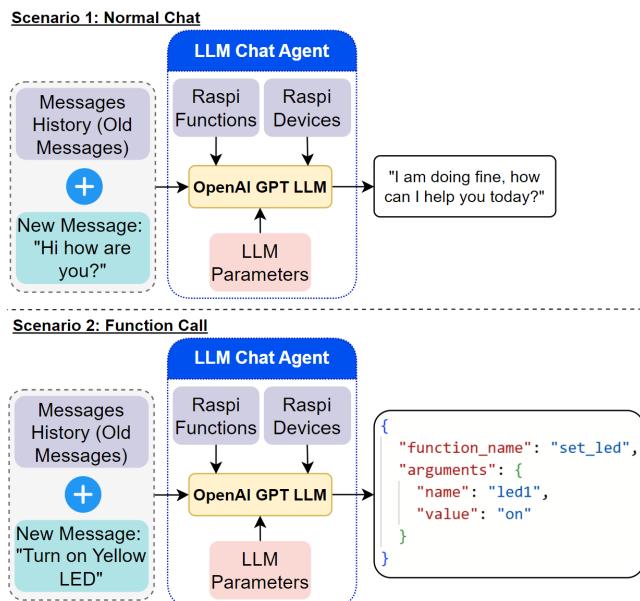
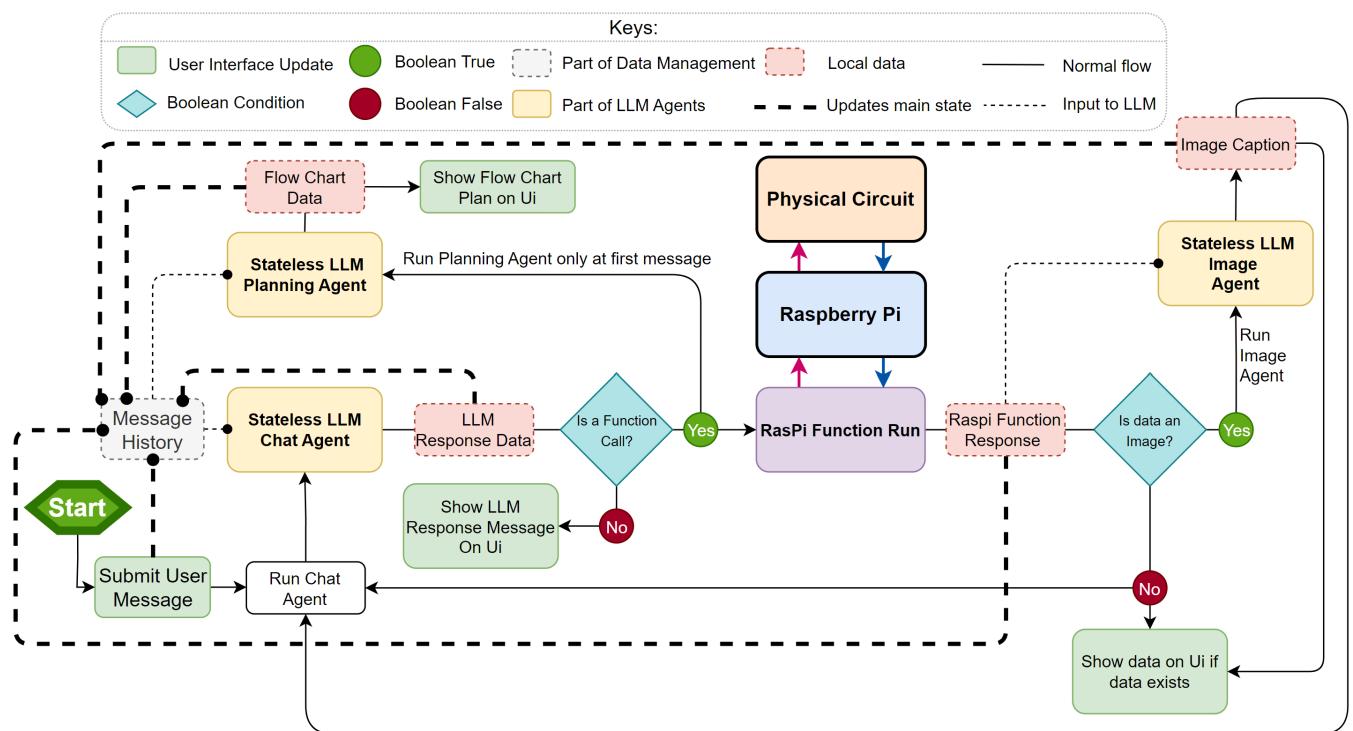


FIGURE 5. Evaluation metrics for the functions defined earlier in .

**FIGURE 6.** Webapp logic design

WebApp - ChatUi - Case 1

- Get temperature. If more than 20°C, capture image. If image describes neon light, write 'hi everyone' on LCD. If both conditions fail, set red LED on.
- Gpt Flow Chart**

```

graph TD
    A["get_connected_devices {deviceNames: 'tmp'}"] -- "result > 20" --> B["capture_image"]
    B --> C["description does not contain 'neon light'"]
    C --> D["set_led {"name": "LED_RED", "value": "on"}"]
    C --> E["print_lcd {"text": "hi everyone"}"]
    E --> F["description contains 'neon light'"]
    F --> G["set_led {"name": "LED_RED", "value": "off"}"]
    
```
- Current Devices**
- Raspberry Pi Image**

The image depicts a bright white neon lightning bolt mounted on a wall, with the dark surroundings, creating a modern, minimalist mood
- The temperature is shown above, and based on the captured image description mentioning a neon light, "hi everyone" has been displayed on the LCD.

WebApp - ChatUi - Case 2

- If location is Leeds, check button click count. If more than 3, set servo to 45, 90 and get ULTS sensor data for last 30s. Else, turn on fan.
- Gpt Flow Chart**

```

graph TD
    A["get_connected_devices {deviceNames: 'BUTTON'}"] --> B["clicks > 3"]
    B --> C["set_servo_angles {angles: '45, 90'}"]
    C --> D["after setting servo"]
    A --> E["get_location"]
    E --> F["location == leeds"]
    F --> G["set_fan {value: 'on'}"]
    F --> H["get_recorded_sensor_data {sensorNames: 'ULTS', interval: '30'}"]
    
```
- Map**
- Plot of ULTS (Time (s) vs Values)**

Time (s)	Values
390	2.34
392	2.34
394	2.34
396	2.34
398	2.34
400	2.34
402	1.94
404	2.34
406	2.34
408	2.34
410	2.34
412	2.34
414	2.34
416	2.35
418	2.34
- Button was clicked more than 3 times, Servo was set and data is displayed.

Physical Circuit - LCD

Physical Circuit - LCD

FIGURE 7. System case studies

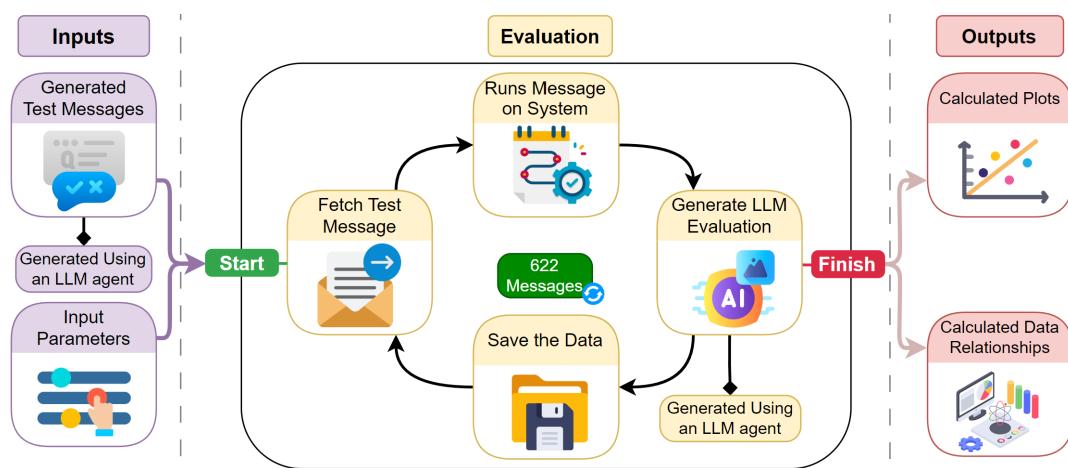
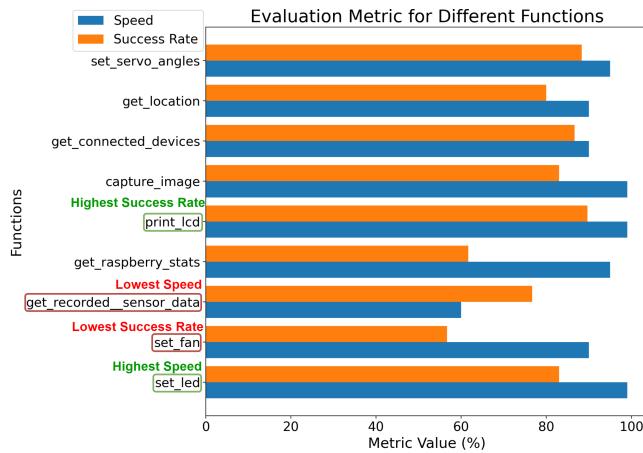
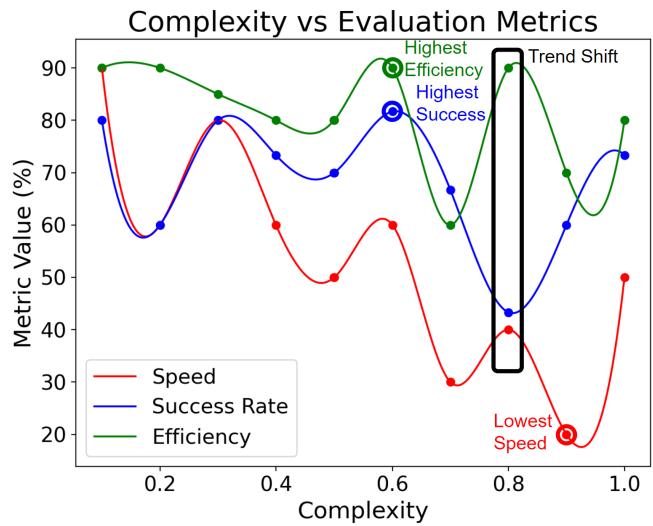
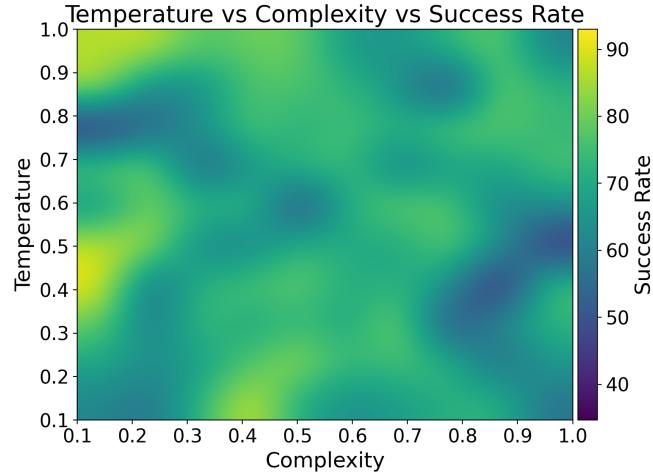
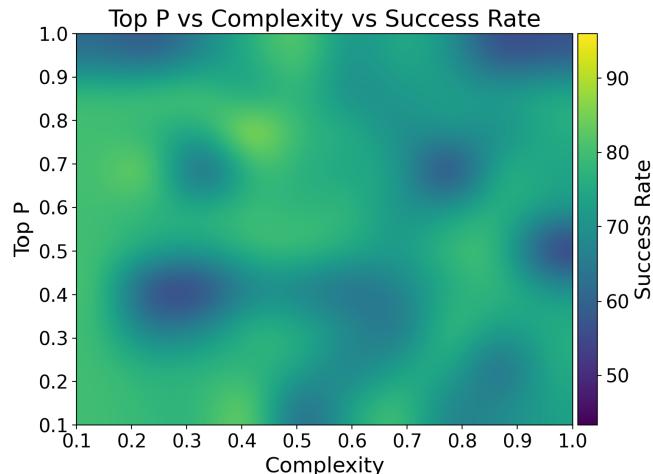


FIGURE 8. Magnetization as a function of applied field. It is good practice to explain the significance of the figure in the caption.

**FIGURE 9.** Evaluation metrics for the functions defined earlier in .**FIGURE 11.** Message complexity against all evaluation metrics and most importantly the success rate.**FIGURE 12.** Success rate against message complexity and temperature of the LLM.**FIGURE 13.** Success rate against message complexity and Top P of the LLM.

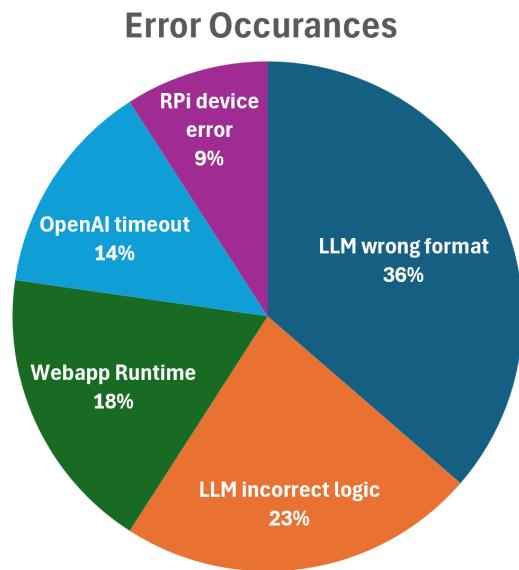


FIGURE 14. What types of errors occurred throughout testing.

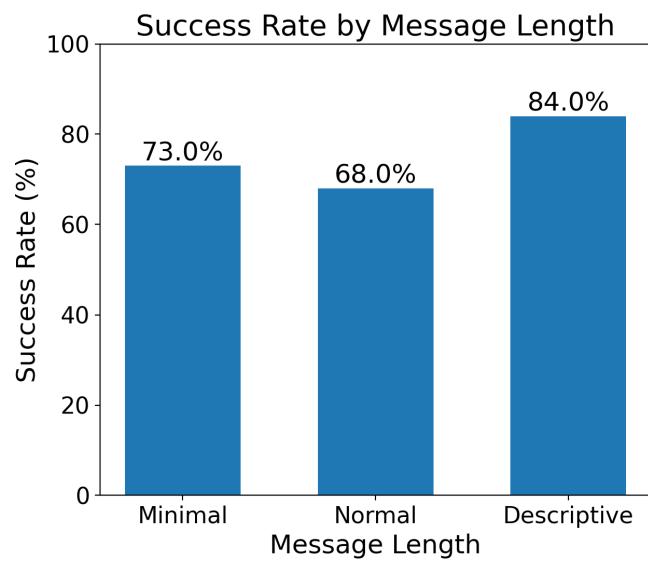


FIGURE 15. Success rate of different tones of the same message.