fig.1
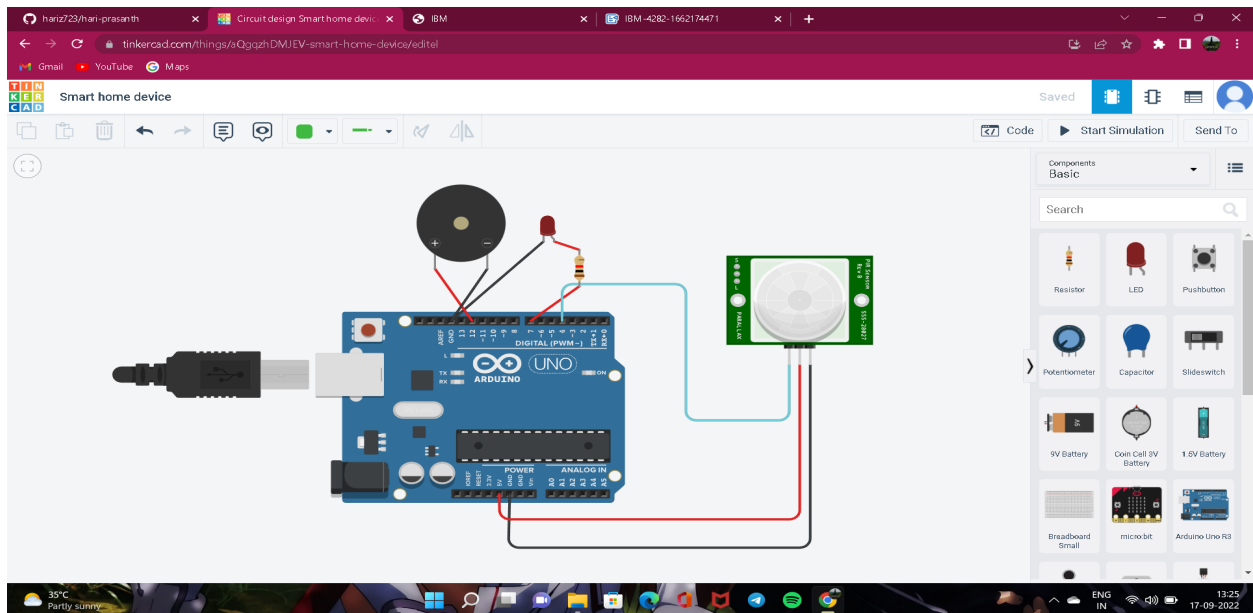

fig.2
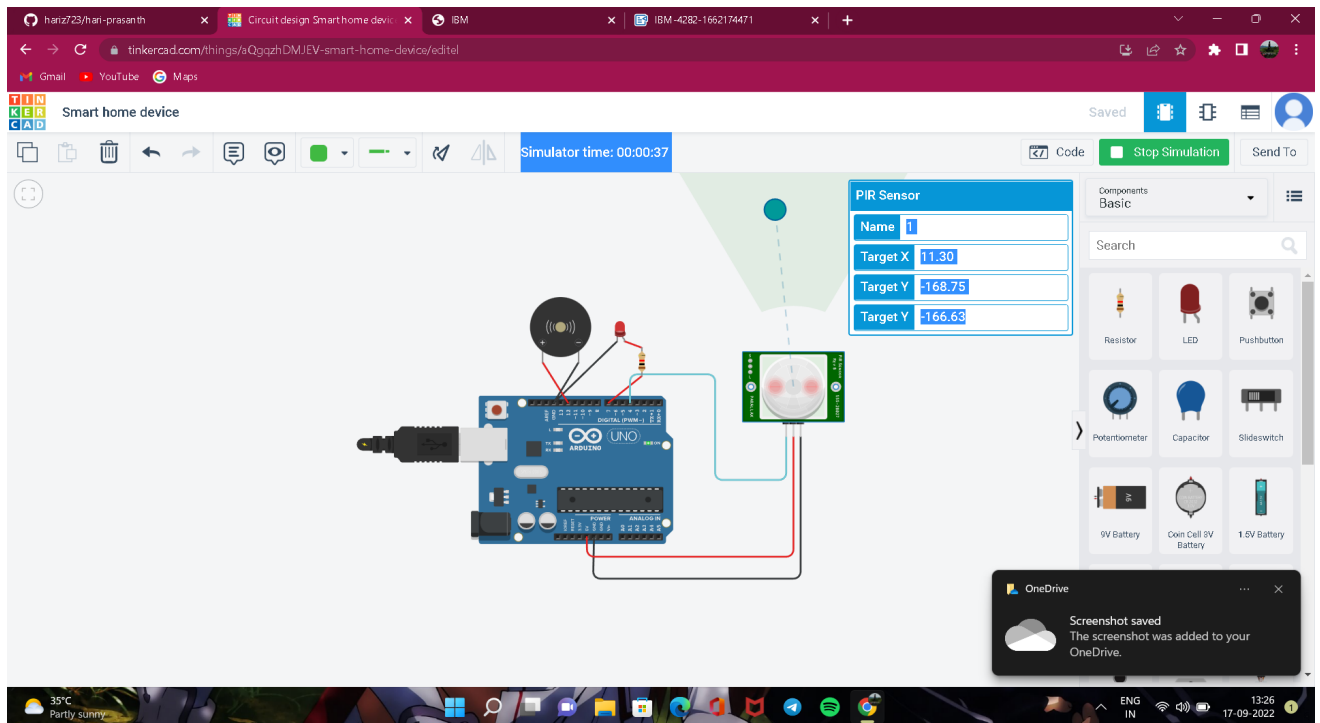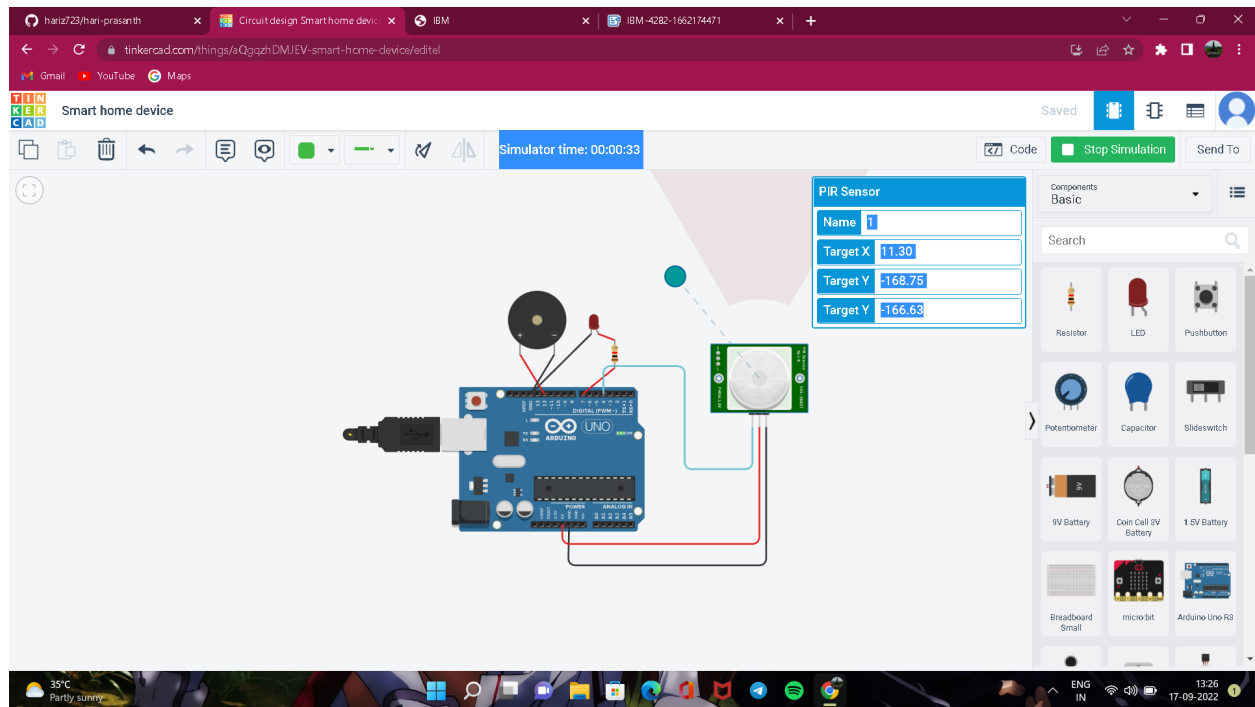

fig.3

Description:

 In this IOT board we use

- one pir sensor
- one piezo,
- one light,
- one resistor,
- one arduio board,

 As I mention above the fig.1 is our iot board, and fig.2 says if any object cross with in that particular sensing limit, it start working, and fig.3 says no object cross that range limit continuously working as well.