Unravelling Bayesian Inference A Journey Through MCMC, Rejection Sampling, and ABC Methods

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Introduction

Parameter of interest : p , Prior : $\pi(p) \sim Beta(1,1)$ (i.e. Unif(0,1)), Likelihood : $f(x|p) \sim Bin(n,p)$, n = 10 i.e. 10 coin-tosses, each coin toss has probability p of a head, $x_{obs} = 5$ (observed 5 heads when tossing 10 times)

Posterior:
$$\pi(p|x_{obs}) = \frac{\pi(p)f(x_{obs}|p)}{\int \pi(p)f(x_{obs}|p)dp} \sim Beta(6,6)$$
 [3]

Implemented MCMC, Rejection Sampling, ABC Rejection Sampling and ABC-MCMC for this example

AIM: samples from the posterior, or close enough to the posterior (e.g., to estimate expectation of posterior).

ABC - MCMC Pc = PEURR q(p)pc) -> Sampling distribution = g(R, P) f(xc/Pc) Proposal of Step 2 sampling Proposal of Step 2 sampling i.e 8 tep 1 sampling Acceptance: TTABC (pt). 9 (pour 1 pt) TABC (PCURR). Q (PT | PCURR) = Tr(p*)f(x*tp*) kn(u*)g(p*, Pe)f(xetpe) TT (Pc) Electro) Kn (uc) g (pc, pt) f (xtpt)

ABC-MCMC [2]

Initialise:

- 1. $p_{CURR} \sim \pi(p)$
- 2. $x_{CURR} \sim f(.|p_{CURR})$
- 3. $K_h(||x_{CURR} x_{obs}||) > 0$, move to sampling else repeat 1-2

Sampling:

For i = 1,, N:

- 1. $p^* \sim g(p, p^*)$
- 2. $x^* \sim f(.|p^*|)$
- 3. Accept p^* with probability

$$\min\{1, \frac{\pi(p^*)K_h(||x^*-x_{obs}||)g(p^*, p_{CURR})}{\pi(p_{CURR})K_h(||x_{CURR}-x_{obs}||)g(p_{CURR}, p^*)}\}$$

ABC-MCMC - Findings

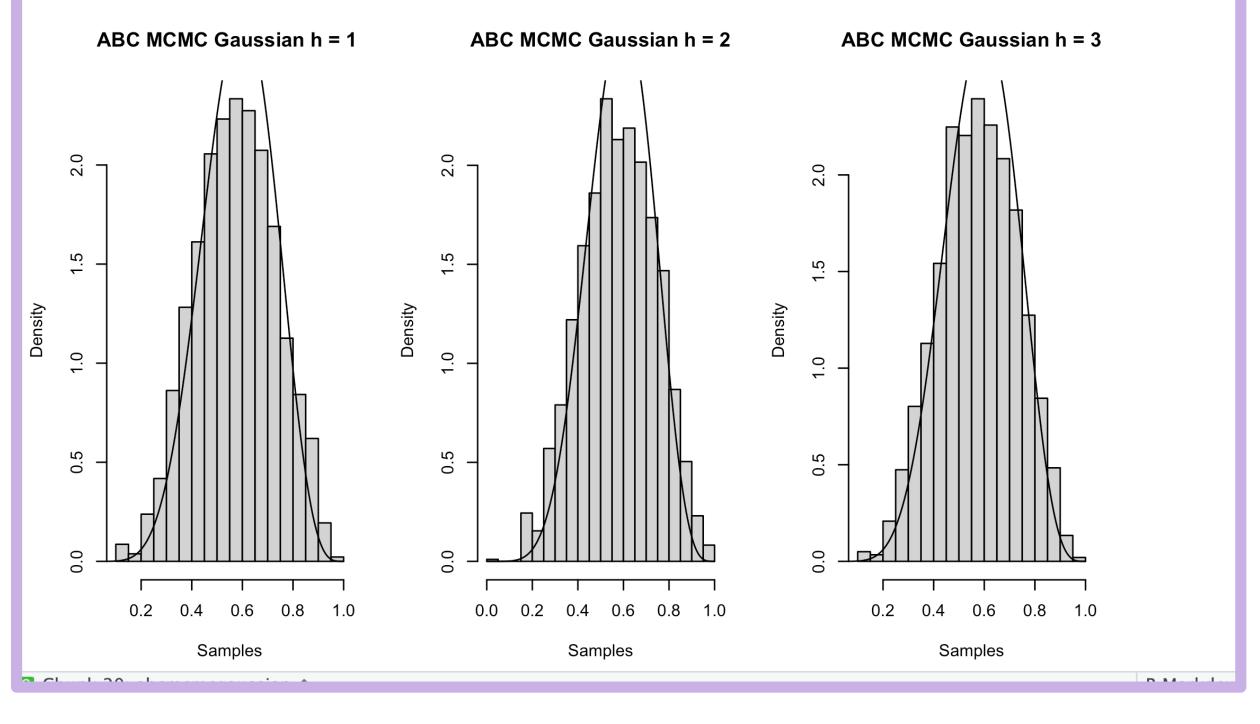
 $g(p_{CURR}, p^*)$ is a normal truncated at 0 and 1, mean p_{CURR} with fixed variation 0.01

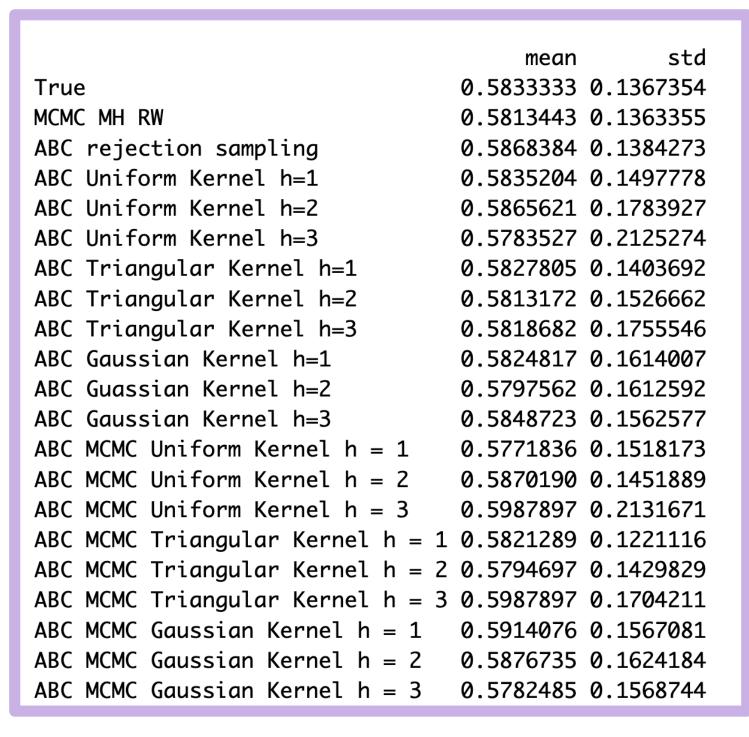
For smaller bandwidth: if end up in region of low posterior density, stuck there for a long time (sampled values nearby p_{CURR} more likely to be rejected)

Higher weight assigned to p_{CURR} , chain hence takes longer to converge

Larger bandwidth: easier to escape regions of low posterior density, however less accurate posterior achieves

Trade-off between convergence time and accuracy





ABC Rejection Sampling [1]

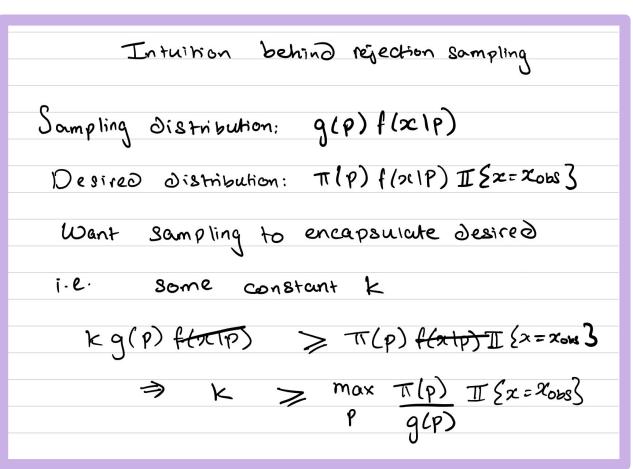
ABC Rejection Sampling [1], accept values 'close enough' to x_{obs} giving approximation to posterior:

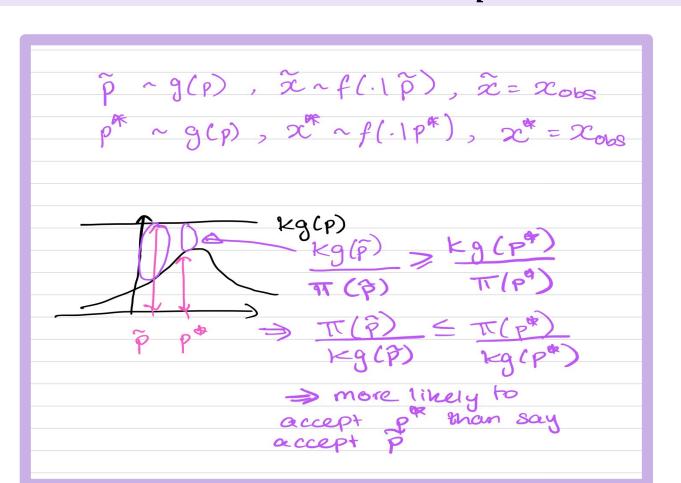
- 1. $p \sim g(p)$
- 2. $x \sim f(.|p)$
- 3. Accept p with probability $\frac{\pi(p)K_h(||x-x_{obs}||)}{Kg(p)}$, $K \ge$

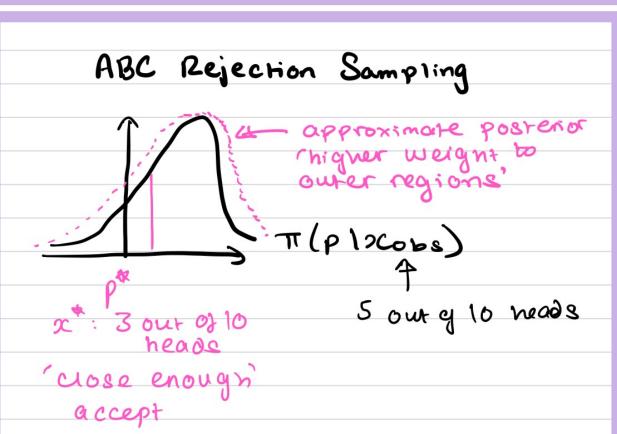
 $K_h(0) \max_p \frac{\pi(p)}{g(p)}$

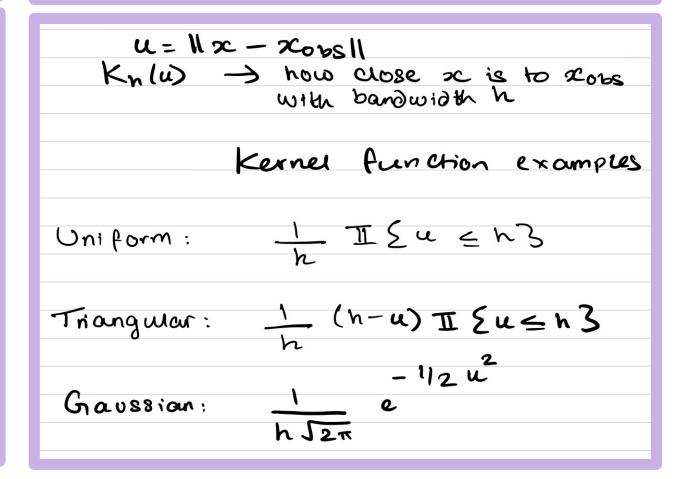
4. Repeat 1-3 until enough samples obtained

Rejection sampling is same, but step 3 is replaced by: If $x = x_{obs}$, accept p with probability $\frac{\pi(p)}{Kg(p)}$, $K \ge \max_{p} \frac{\pi(p)}{g(p)}$









ABC Rejection Sampling - Findings

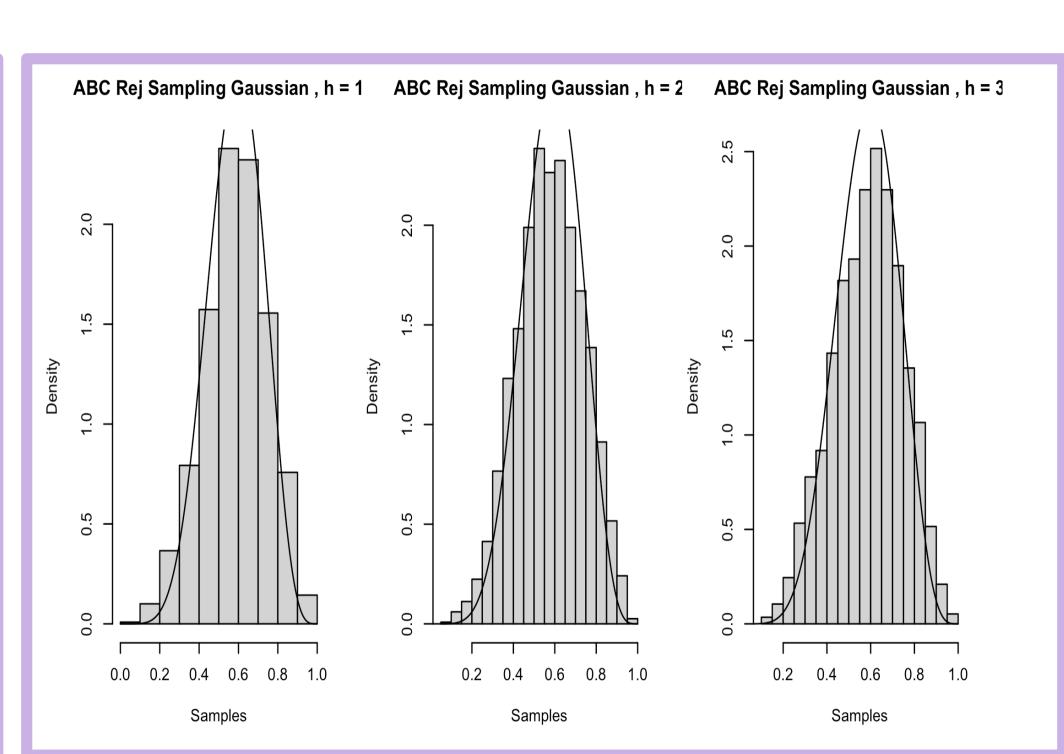
For $\pi(p) \sim Unif(0,1)$, $g(p) \sim Unif(0,1)$, $K = K_h(0)$ in theory:

h = 1: uniform and triangular give samples from posterior, gaussian gives approximation to the posterior

h = 2: triangular gives closest approximation to posterior, then gaussian then uniform

h = 3: gaussian gives closest approximation to posterior., then triangular then uniform

For $K = K_h(0)$, gaussian kernel independent of bandwidth (so h = 1, 2 and 3 should give similar approximations to the posterior)



- [1] Sisson, S.A., Fan, Y. and Beaumont, M.A., 2018. Overview of ABC. In Handbook of approximate Bayesian computation (pp. 3-54). Chapman and Hall/CRC.
- [2] Fan, Y. and Sisson, S.A., 2018. ABC samplers. arXiv preprint arXiv:1802.09650.
- [3] Jeremy Orloff and Jonathan Bloom. Conjugate priors: Beta and normal. https://math.mit.edu/~dav/05.dir/class15-prep.pdf