\bigcirc

K: dx = x(+st)-x(+) = 0 1x (f+bf) = vx(t) duz = vz (frst) - vz(t) = -9 vz (frot) = vz(f)gst c) dx = 1/2 = 1/2 $\frac{dx}{dt} = \frac{x(t+st) - x(t)}{st} = vx$ $\int x(t+st) = vx st + x(t) \int$ same for z! LZ(++Dt) = Vz At +Z(+) since 1/2 = const = 16 (X (+st) = 16 st + X (+) /

 $\frac{dv_{x}}{dt} = -Cv_{x}\sqrt{v_{x}^{2}+v_{z}^{2}}$ Vx (++++)-Vx(+) = -C Vx Vx2+v2 [Vx (++st) = - C vx (+) st (vx (+) 2+v2 (+) 2 + vx (+) Vz (++st)-vz(t) = -g-Cvz(t) [vx2+vz2] V2 (++++) = s+ (-g-C v2 (+) (x2+v2)) + V2 (+) e) $\frac{dx}{dt} = \frac{1}{x} \frac{dz}{dt} = \frac{1}{x}$ dz = vz (t) at $dx = V_X(t) dt (x)$ Sv= 1-9+1 dux = 0 V=(+)-V=(0) = -9+ Sdvx = 0 (Vz(t)-Vz(0)-gt 5d== 5(v2(0)-g+)d+ 1x(f)-1x(0)=0 (+x+) = 1/x(0) (+x+) = (+)-2(0)= (v=(0)+-1)+ (00) in (00) + fdx = [16+]o -> 2(+)= v2(0)++2(0)-1 gt x(+)-x(0)=10-0 (x(+)=16+x0

$$t_{1} & t_{2} \qquad given \qquad \phi = 45^{\circ} \wedge v_{8} = 24 \frac{m}{s}$$

$$t_{1} : v_{2}(t_{1}) = 0$$

$$v_{2}(t_{1}) = v_{2}(0) - gt \rightarrow t = -\left(v_{2}(t_{1}) - v_{2}(0)\right)$$

$$t = v_{2}(0) - v_{3}(t_{1})$$

$$g$$

$$t_{1} = v_{2}(0) - v_{3}(t_{1})$$

$$g$$

$$t_{2} = v_{2}(0) + v_{3}(0) = v_{3}(0)$$

$$t_{3} = v_{4}(0) + v_{4}(0) = v_{3}(0)$$

$$t_{4} = v_{4}(0) + v_{4}(0) = v_{4}(0)$$

sheet5

September 28, 2017

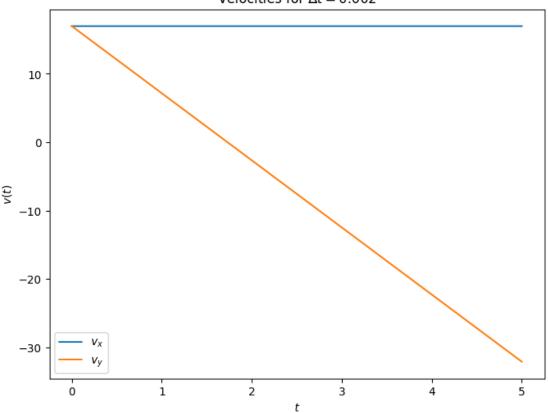
1 7. Motion of a ball in Earth's gravitational field

1.1 (a)

```
In [1]: using PyPlot
In [2]: #parameters
        g = 9.81
        v0 = 24
        #grad in radiant
        phi=45*pi/180
        dt=0.002
        #endtime in [s]
        tend=5
        #the velocities
        vx=Float64[]
        vy=Float64[]
        push!(vx,v0*cos(phi))
        push!(vy,v0*sin(phi))
        t=Float64[]
        push!(t,0)
        #i-iteration, tval-value in the interval
        for (i,tval) in enumerate(dt:dt:tend)
            #the derived formulas for the ef-scheme
            push!(vx,vx[i])
            push!(vy,vy[i]-g*dt)
            push!(t,tval)
        end
        #just the plot
        figure(1,figsize=(8,6))
        plot(t,vx,label=L"$v_x$")
        plot(t,vy,label=L"$v_y$")
        title(L"Velocities for $\Delta t=0.002$")
```

```
ylabel(L"$v(t)$")
xlabel(L"$t$")
legend()
```





Out[2]: PyObject <matplotlib.legend.Legend object at 0x7fc5f8742890>

1.2 (b)

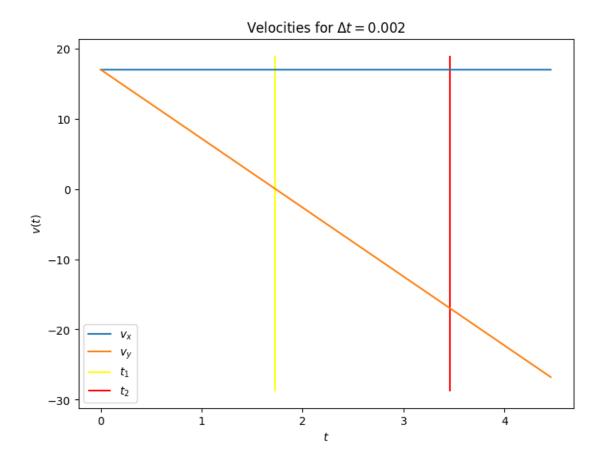
```
In [7]: #parameters
    g=9.81
    v0=24
    #grad in radiant
    phi=45*pi/180

dt=0.002

#wished vy values
    vt=[0.,-v0*sin(phi)]

#the velocities
```

```
vx=Float64[]
vy=Float64[]
#time
t=Float64[]
#tvals pos[1]-t1 & [2]-t2
tvals=Float64[]
#for both wished velocities
#since I do a "push" before the routine, the first array entry in julia is at "1" and
for val in vt
    push!(vy,v0*sin(phi))
    i=0
    #while the error is to high, do
    while (abs(vy[i+1]-val)>10e-3)
        push!(vy,vy[i+1]-g*dt)
    end
    push!(tvals,i*dt)
    vy=[]
end
push!(vx,v0*cos(phi))
push!(vy,v0*sin(phi))
push! (t,0)
#i-iteration, tval-value in the interval
#here i starts at 1, so the value t-1 is at i, not i+1
for (i,tval) in enumerate(dt:dt:tvals[2]+1)
    #the derived formulas for teh ef-scheme
    push!(vx,vx[i])
    push!(vy,vy[i]-g*dt)
    push!(t,tval)
end
#just the plot
figure(2,figsize=(8,6))
plot(t,vx,label=L"$v_x$")
plot(t,vy,label=L"$v_y$")
title(L"Velocities for $\Delta t=0.002$")
ylabel(L"$v(t)$")
xlabel(L"$t$")
vlines(tvals[1],vy[1]+2,vy[length(vy)]-2,label=L"$t_1$",color="yellow")
vlines(tvals[2], vy[1]+2, vy[length(vy)]-2,label=L"$t_2$",color="red")
legend()
println("t1= ",tvals[1])
println("t2= ",tvals[2])
```



t1= 1.73 t2= 3.46

t1 is the turning point of the ball, t2 is the point where the ball hits the ground again

1.3 (c)

```
In [9]: #parameters
    g=9.81
    v0=24
    #grad in radiant
    phi=45*pi/180

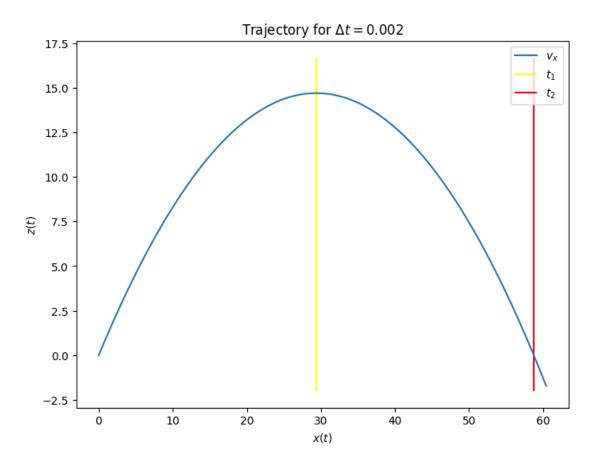
dt=0.002

#wished vy values
    vt=[0.,-v0*sin(phi)]

#the velocities
```

```
vx=Float64[]
vy=Float64[]
#the trajectories
x=Float64[]
y=Float64[]
#time
t=Float64[]
push!(vx,v0*cos(phi))
push!(vy,v0*sin(phi))
push!(x,0)
push!(y,0)
#I want the y values for t1 and the x-coordinate
maxima=Float64[]
maximax=Float64[]
#wished vy values
vt=[0.,-v0*sin(phi)]
#i-iteration, tval-value in the interval
#for the explanation of i look in b)
for (i,tval) in enumerate(dt:dt:tvals[2]+0.1)
    #the derived formulas for the ef-scheme
    push!(x,vx[i]*dt+x[i])
    push!(y,vy[i]*dt+y[i])
    push!(vx,vx[i])
    push!(vy,vy[i]-g*dt)
    if abs(vy[i+1]-vt[1])<10e-3 \mid \mid abs(vy[i+1]-vt[2])<10e-3
        #current calue
        push!(maxima,y[i+1])
        push! (maximax,x[i+1])
    end
end
#just the plot
figure(2,figsize=(8,6))
plot(x,y,label=L"$v_x$")
\#plot(t,vy,label=L"$v_y$")
title(L"Trajectory for $\Delta t=0.002$")
ylabel(L"$z(t)$")
xlabel(L"$x(t)$")
vlines(maximax[1], maxima[1]+2.,-2.,label=L"$t_1$",color="yellow")
vlines(maximax[2],maxima[1]+2.,-2.,label=L"$t_2$",color="red")
legend()
```

```
println("x-Coordinates calculated by EF-scheme for x(t):")
println("x1= ",maximax[1])
println("x2= ",maximax[2])
```



```
x-Coordinates calculated by EF-scheme for x(t): x1= 29.35907355486583 x2= 58.718147109729536
```

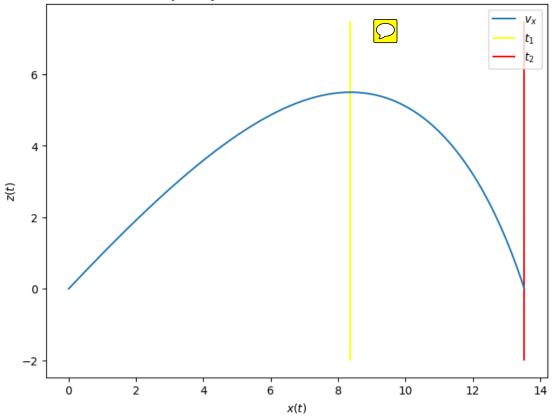
1.4 (d)

```
#wished vy values
vt=[0.,-v0*sin(phi)]
#the velocities
vx=Float64[]
vy=Float64[]
#the trajectories
x=Float64[]
y=Float64[]
#time
t=Float64[]
push!(vx,v0*cos(phi))
push!(vy,v0*sin(phi))
push!(x,0)
push! (y,0)
#I want the y values for t1 and the x-coordinate
maxima=Float64[]
maximax=Float64[]
#wished vy values
vt=[0.,-v0*sin(phi)]
i=1
while(y[i]>=0)
    #the derived formulas for the ef-scheme
    push!(x,vx[i]*dt+x[i])
    push!(y,vy[i]*dt+y[i])
    push!(vx,-c*vx[i]*dt*sqrt(vx[i]^2+vy[i]^2)+vx[i])
    push!(vy,dt*(-g-c*vy[i]*sqrt(vx[i]^2+vy[i]^2))+vy[i])
    if abs(vy[i+1]-vt[1])<10e-3</pre>
        #current calue
        push!(maxima,y[i+1])
        push! (maximax,x[i+1])
    end
    i += 1
end
#just the plot
figure(2,figsize=(8,6))
plot(x,y,label=L"$v_x$")
\#plot(t,vy,label=L"$v_y$")
title(L"Trajectory with air resistance for $\Delta t=0.002$")
ylabel(L"$z(t)$")
```

```
xlabel(L"$x(t)$")
vlines(maximax[1],maxima[1]+2.,-2.,label=L"$t_1$",color="yellow")
vlines(x[length(x)-1],maxima[1]+2.,-2.,label=L"$t_2$",color="red")
legend()

println("x-Coordinates:")
println("x1= ",maximax[1])
println("x2= ",x[length(x)-1])
```

Trajectory with air resistance for $\Delta t = 0.002$

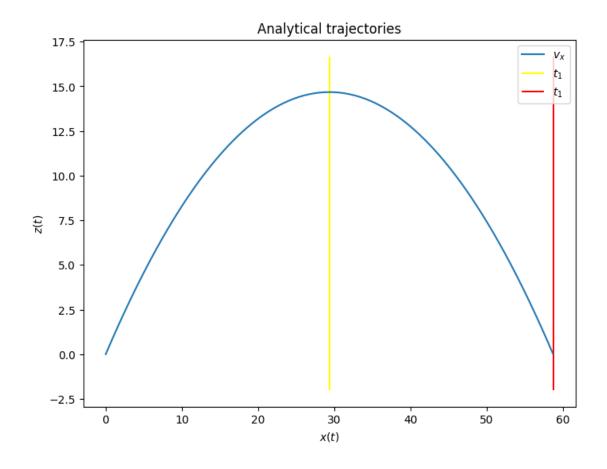


```
x-Coordinates:
x1= 8.363602196159704
x2= 13.524332727167792
```

1.5 (e)

In [6]: #parameters g=9.81

```
v0 = 24
#grad in radiant
phi=45*pi/180
dt=0.002
#wished vy values
vt=[0.,-v0*sin(phi)]
#the velocities
vx=Float64[]
vy=Float64[]
#wished vy values
vt=[0.,-v0*sin(phi)]
push!(vx,v0*cos(phi))
push!(vy,v0*sin(phi))
#analytical t1 & t2
tvals[1]=vy[1]/g
tvals[2]=2*vy[1]/g
#analytical trajectories
fx(t,v0,x0)=v0*t+x0
fy(t,v0,x0,g)=v0*t+x0-.5*g*t.^2.0
#the interval
t=0:dt:tvals[2]
#just the plot
figure(2,figsize=(8,6))
plot(fx(t,vx[1],0),fy(t,vy[1],0,g),label=L"$v_x$")
title("Analytical trajectories")
ylabel(L"$z(t)$")
xlabel(L"$x(t)$")
vlines(tvals[1]*vx[1],fy(tvals[1],vy[1],0,g)+2.,-2.,label=L"$t_1$",color="yellow")
vlines(tvals[2]*vx[1],fy(tvals[1],vy[1],0,g)+2.,-2.,label=L"$t_1$",color="red")
legend()
println("t-values:")
println("t1= ",tvals[1])
println("t2= ",tvals[2])
println("")
println("x-Coordinates:")
println("x1= ",tvals[1]*vx[1])
println("x2= ",tvals[2]*vx[1])
```



t-values:

t1= 1.7299248469395656

t2= 3.459849693879131

x-Coordinates:

x1= 29.357798165137616

x2= 58.71559633027523

As we see, the values are pretty much the same

In []: