

► Preamble

$x0 := ssimplify(E1 \cdot E2 \cdot E1) [\dots, -1] : X := simplify(\langle x0 | F1 \cdot x0 | F2 \cdot F1 \cdot x0 | F1 \cdot F2 \cdot F1 \cdot x0 \rangle) :$
 $Xplus := subs(t2=1, X) : Xminus := subs(t2=-1, X) :$

$$f1 := \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} : f2 := \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} : e1 := \begin{bmatrix} 0 & \frac{tI^2+1}{2tI} & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{2} \frac{(tI^2-1)}{tI} \\ 0 & 0 & 0 & 0 \end{bmatrix} : e2 :=$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -t2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} : k1 := \begin{bmatrix} ItI & 0 & 0 & 0 \\ 0 & -ItI & 0 & 0 \\ 0 & 0 & tI & 0 \\ 0 & 0 & 0 & -tI \end{bmatrix} : k2 := \begin{bmatrix} -t2 & 0 & 0 & 0 \\ 0 & -I \cdot t2 & 0 & 0 \\ 0 & 0 & I \cdot t2 & 0 \\ 0 & 0 & 0 & -t2 \end{bmatrix} : h1 :=$$

$$\begin{bmatrix} \lambda+1 & 0 & 0 & 0 \\ 0 & \lambda-1 & 0 & 0 \\ 0 & 0 & \lambda & 0 \\ 0 & 0 & 0 & \lambda-2 \end{bmatrix} : h2 := \begin{bmatrix} (\mu-2) & 0 & 0 & 0 \\ 0 & (\mu-1) & 0 & 0 \\ 0 & 0 & (\mu-3) & 0 \\ 0 & 0 & 0 & (\mu-2) \end{bmatrix} :$$

$e3 := simplify(-(e1 \cdot e2 + I \cdot e2 \cdot e1)) : f3 := simplify(-(f2 \cdot f1 - I \cdot f1 \cdot f2)) :$
 $check(br(e1, f1) - fl(k1)), check(br(e2, f2) - fl(k2)), check(br(e1, f2)), check(br(e2, f1)),$
 $check(k1 \cdot f1 + f1 \cdot k1), check(k2 \cdot f2 + f2 \cdot k2), check(k1 \cdot e1 + e1 \cdot k1), check(k2 \cdot e2 + e2 \cdot k2);$
 $check(e3^2), check(f3^2), check(k1 \cdot f2 - I \cdot f2 \cdot k1), check(k2 \cdot f1 - I \cdot f1 \cdot k2), check(k1 \cdot e2 + I \cdot e2$
 $\cdot k1), check(k2 \cdot e1 + I \cdot e1 \cdot k2), check(e1^2), check(f1^2), check(e2^2), check(f2^2), check(br(h1,$
 $e1) - 2 e1), check(br(h2, e1) + e1), check(br(h1, e2) + e2), check(br(h2, e2) - 2 e2),$
 $check(br(h1, f1) + 2 f1), check(br(h2, f1) - f1), check(br(h1, f2) - f2), check(br(h2, f2) + 2 f2)$

[illegible]

$$\begin{aligned}
R1 &:= \text{simplify}\left(\text{DiagonalMatrix}\left(\sim`_q\left(\text{Diagonal}\left(\frac{2}{3} \text{KP}(H1, H1) + \frac{2}{3} \text{KP}(H2, H2) + \frac{1}{3} \text{KP}(H2, \right.\right.\right.\right. \\
&\quad \left.\left.\left.\left.H1\right) + \frac{1}{3} \text{KP}(H1, H2)\right)\right)\right). \left(\text{IdentityMatrix}(64) + 2 \text{IKP}(E1, F1)\right) \cdot \left(\text{IdentityMatrix}(64) \right. \\
&\quad \left. + 2 \text{IKP}(E3, F3)\right) \cdot \left(\text{IdentityMatrix}(64) + 2 \text{IKP}(E2, F2)\right), \text{power}\Big): \\
R &:= \sim`\text{simplify}\left(\sim`\text{expand}\left(\text{subs}\left(\mu = -\frac{2 \text{I} \ln(t2)}{\pi}, \lambda = -\frac{2 \text{I} \ln(t1)}{\pi}, \frac{P \cdot R1}{R1_{8,8}}\right)\right)\right): \\
Rplus &:= \text{LinearSolve}(\text{KP}(Xplus, Xplus), \text{subs}\sim(t2 = 1, R) \cdot \text{KP}(Xplus, Xplus)) : Rplus := \\
&\quad \text{simplify}(\text{subs}(t1 = -1 \cdot t1, t2 = 1, Rplus)) : Rminus := \text{LinearSolve}(\text{KP}(Xminus, Xminus), \text{subs}\sim(t2 = \\
&\quad -1, R) \cdot \text{KP}(Xminus, Xminus)) : Rminus := \text{simplify}(\text{subs}(t1 = -1 \cdot t1, t2 = 1, Rminus)) : \\
&\quad \#weight \text{ relabel since } Xplus \text{ is weight } 1 \cdot t1, -t2 \\
de1 &:= \text{KroneckerProduct}(e1, k1) + \text{KroneckerProduct}(id, e1) : \\
de2 &:= \text{KroneckerProduct}(e2, k2) + \text{KroneckerProduct}(id, e2) : df1 := \text{KroneckerProduct}(f1, id) \\
&\quad + \text{KroneckerProduct}\left(\frac{1}{k1}, f1\right) : df2 := \text{KroneckerProduct}(f2, id) + \text{KroneckerProduct}\left(\frac{1}{k2}, \right. \\
&\quad \left.f2\right) : dk1 := \text{KroneckerProduct}(k1, k1) : dk2 := \text{KroneckerProduct}(k2, k2) : de3 := -de1 \cdot de2 \\
&\quad - (1 \cdot de2).de1 : df3 := -df2 \cdot df1 + (1 \cdot df1).df2 : \\
check &(\text{br}(de1, df1) - fl(dk1)), check(\text{subs}(t2 = 1, \text{br}(de2, df2) - fl(dk2))), check(\text{subs}(t2 = -1, \\
&\quad \text{br}(de2, df2) - fl(dk2))), check(\text{br}(de1, df2)), check(\text{br}(de2, df1)), check(dk1 \cdot df1 + df1 \cdot dk1), \\
&\quad check(dk2 \cdot df2 + df2 \cdot dk2), check(dk1 \cdot de1 + de1 \cdot dk1), \\
&\quad check(dk2 \cdot de2 + de2 \cdot dk2), check(dk1 \cdot df2 - 1 \cdot df2 \cdot dk1), check(dk2 \cdot df1 - 1 \cdot df1 \cdot dk2), check(dk1 \\
&\quad \cdot de2 + 1 \cdot de2 \cdot dk1), check(dk2 \cdot de1 + 1 \cdot de1 \cdot dk2), check(de1^2), check(df1^2), check(de2^2), \\
&\quad check(df2^2), check(de3^2), check(df3^2); \\
\text{Good, Good, Good, Good, Good, Good, Good, Good, Good, Good, Good, Good, Good, Good, Good,} & \quad (2) \\
\text{Good, Good, Good, Good, Good} &
\end{aligned}$$

$$\begin{aligned} de21 &:= de2 \cdot de1 : de1212 := de21^2 : dflist := [idd, df1, df2 \cdot df1, df1 \cdot df2 \cdot df1] : \\ longdflist &:= [idd, df1, df2, df1 \cdot df2, df2 \cdot df1, df1 \cdot df2 \cdot df1, df2 \cdot df1 \cdot df2, df2 \cdot df1 \cdot df2 \cdot df1] : \\ v1 &:= IdentityMatrix(16) \dots_1 : v2 := de1 \cdot de2 \cdot de1 \cdot KP(f1 \cdot f2 \cdot f1, f1 \cdot f2 \cdot f1) \dots_1 : \\ v3 &:= de1 \cdot KP(f1, f1) \dots_1 : \end{aligned}$$

$\text{GammaX} := \text{Matrix}(16) : \text{for } j \text{ to } 4 \text{ do}$

$\text{GammaX}_{\dots j} := \text{dflist}_j \cdot v1;$

$\text{GammaX}_{\dots j+4} := \text{dflist}_j \cdot v2$

end do: for j **to** 8 **do**

$\text{GammaX}_{\dots j+8} := \text{longdflist}_j \cdot v3$

end do: $\text{GammaX} := \text{simplify}(\text{GammaX}) : \text{GammaXinv} := \frac{1}{\text{GammaX}} :$

$\text{signsred} := \text{simplify}\left(\text{subs}\left(t1 = -I \cdot t1, \text{tr2}\left(\text{GammaXinv} \cdot \text{KP}\left(\text{id}, \left(\frac{1}{kI^2}\right) \cdot \left(\frac{1}{k2^2}\right)\right) \cdot \text{GammaX}\right)\right)\right);$

$$\text{signsred} := \left[\left[\frac{tI^2}{(tI^4 + 1) t2^2}, 0, \frac{-\frac{1}{2} tI (tI^2 - 1)}{(tI^2 + 1) (tI^4 + 1) t2^2}, 0 \right], \right. \quad (3)$$

$$\left[0, \frac{(-2 tI^4 + tI^2 - 1) t2^2 + tI^2 + 1}{2 (tI^4 + 1) (tI^2 t2^2 - 1) t2^2}, 0, \frac{I (tI^2 - 1)}{t2^3 (tI^4 + 1) (tI^2 t2^2 - 1) tI} \right],$$

$$\left[\frac{-I (tI^6 t2^2 - 2 tI^4 t2^2 + tI^4 - tI^2 t2^2 + 2 tI^2 - 1)}{(tI^2 t2^2 - 1) t2^2 tI (tI^8 - 1)}, 0, \frac{(-tI^2 + 1) t2^2 + tI^2 - 1}{2 (tI^4 + 1) (tI^2 t2^2 - 1) t2^2}, 0 \right],$$

$$\left[0, \frac{\frac{1}{2} tI t2}{(tI^2 t2^2 - 1) (tI^2 - 1)}, 0, 0 \right] \right]$$

$Rplusredrel := \text{simplify}\left(\text{subs}\left(t2 = 1, \text{tr2}\left(\text{subs}(t1 = -I \cdot t1, \text{GammaXinv}).\left(Rplus - \frac{1}{Rplus} - \left(tI^2 - \frac{1}{tI^2}\right) \text{IdentityMatrix}(16)\right).\text{subs}(t1 = -I \cdot t1, \text{GammaX})\right)\right)\right); \# \text{adjust for using subrep of shift}$

$$Rplusredrel := \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{-tI^4 + 1}{tI^2} & 0 \\ 0 & 0 & 0 & \frac{-tI^4 + 1}{tI^2} \end{bmatrix} \quad (4)$$

$Rminusredrel := \text{simplify}\left(\text{subs}\left(t2 = -1, \text{tr2}\left(\text{subs}(t1 = -I \cdot t1, \text{GammaXinv}).\left(Rminus - \frac{1}{Rminus} - \left(tI^2 - \frac{1}{tI^2}\right) \text{IdentityMatrix}(16)\right).\text{subs}(t1 = -I \cdot t1, \text{GammaX})\right)\right)\right); \# \text{using '+' in skein relation}$

$$R_{\text{minusredrel}} := \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{-tI^4 + 1}{tI^2} & 0 \\ 0 & 0 & 0 & \frac{-tI^4 + 1}{tI^2} \end{bmatrix} \quad (5)$$

simplify(subs~(t2=1, signsred • Rplusredrel)), simplify(subs~(t2=-1, signsred • Rminusredrel));

$$\begin{bmatrix} 0 & 0 & \frac{\frac{1}{2} (tI^2 - 1)^2}{(tI^4 + 1) tI} & 0 \\ 0 & 0 & 0 & \frac{-1 (tI^4 - 1)}{(tI^4 + 1) tI^3} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & \frac{\frac{1}{2} (tI^2 - 1)^2}{(tI^4 + 1) tI} & 0 \\ 0 & 0 & 0 & \frac{1 (tI^4 - 1)}{(tI^4 + 1) tI^3} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (6)$$

#any intertwiner multiplied with this gives zero, so it satisfies '+' Conway relation