ECE 544NA: Pattern Recognition

Lecture 4: Sep. 6, Sep. 18

Lecturer: Alexander Schwing Scribe: Jiaying Wu

1 Review

1.1 Optimal Problems that we have learned

1. Linear Regression:

$$\min_{w} \frac{1}{2} \sum_{(x^{(i)}, y^{(i)}) \in D} (y^{(i)} - \phi(x^{(i)})^{T} w)^{2}$$

2. Logistic Regression:

$$\min_{w} \sum_{(x^{(i)}, y^{(i)}) \in D} log(1 + exp(-y^{(i)}w^{T}\phi(x^{(i)})))$$

3. Ways to Find Optimum

• Analytic Solution: take derivative

• Gradient Descent

2 General Optimization Problem

Example: $\min_w f_0(w)$ such that $f_i \leq 0 \ \forall i \in \{1, 2 \cdots c\}$ In this example, we want to find w that can minimize $f_0(w^*)$ among all values that satisfy c different constrains.

2.1 When can we find the optimum

1. General Optimization Problem: Difficult to solve

2. Solvable Optimization Problem: Least square, linear, convex programs

• Least Square Program: $\min_{w} \frac{1}{2} \sum_{(x^{(i)}, y^{(i)}) \in D} (y^{(i)} - \phi(x^{(i)})^T w)^2$

• Linear Program: $\min_{w} c^T w$ such that $Aw \leq b$

• Convex Program: $\min_{w} f_0(w)$ such that $f_i \leq 0 \ \forall i \in \{1, 2 \cdots c\}$ when all f_i convex

3 Convexity

3.1 Convex Set

1. Definition: A set is convex if for any two points w_1 , w_2 in the set, the line segment $w_1 + w_2(1-\lambda)$ for $\lambda \in [0,1]$ also lies in the set.

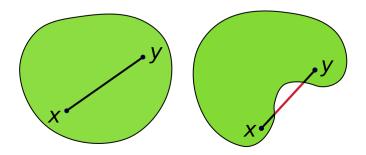


Figure 1: Convex and None-Convex Set Graph [6]

- 2. Special Case: Any empty set and a single point set are convex set.
- 3. Example: Polyhedron is convex. $P = \{w | Aw \le b, Cw = d\}$

Proof: (from [7])
Given
$$P = \{w | Aw \le b, Cw = d\}$$
, where $\lambda \in [0, 1]$ and $w_1, w_2 \in P$
 $A((1 - \lambda)w_1 + \lambda w_2) = (1 - \lambda)Aw_1 + \lambda Aw_2 \le (1 - \lambda)b + \lambda b = b$
 $C((1 - \lambda)w_1 + \lambda w_2) = (1 - \lambda)Cw_1 + \lambda Cw_2 \le (1 - \lambda)d + \lambda d = d$

3.2 Convex Function

1. Definition: A function is convex if its domain is a convex set and for any point w_1 , w_2 in the domain and any $\lambda \in [1,0]$:

$$f((1-\lambda)w_1 + \lambda w_2 \le (1-\lambda)f(w_1) + \lambda f(w_2)$$

2. Lemmas to Recognize Convex Function

Lemma 1 If f is differentiable, then f is convex if and only if its domain is convex and for all w_1, w_2 in the domain

$$f(w_2) \ge f(w_1) + \nabla f(w_1)^T (w_2 - w_1)$$

Proof: (from [9]) When n=1

$$f((1-\lambda)w_1 + \lambda w_2) \leq (1-\lambda)f(w_1) + \lambda f(w_2)$$

$$f(w_1 - \lambda w_1 + \lambda w_2) \leq f(w_1) - \lambda f(w_1) + \lambda f(w_2)$$

$$f(w_1 + \lambda (w_2 - w_1)) \leq f(w_1) + \lambda (f(w_2) - f(w_1))$$

$$\frac{f(w_1 + \lambda (w_2 - w_1)) - f(w_1)}{\lambda} \leq f(w_2) - f(w_1)$$

$$\frac{(f(w_1 + \lambda (w_2 - w_1)) - f(w_1))(w_2 - w_1)}{\lambda (w_2 - w_1)} \leq f(w_2) - f(w_1)$$

$$\nabla f(w_1)(w_2 - w_1) \leq f(w_2) - f(w_1)$$

$$(3.2.1)$$

To show sufficiency, assume the function satisfies equation 3.2.1. For all x and y in domain of f, choose any $w_1 \neq w_2$, $\lambda \in [0,1]$ and $z = \lambda w_1 + (1-\lambda)w_2$.

$$f(w_1) \ge f(z) + \nabla f(z)(w_1 - z)$$

$$\lambda f(w_1) \ge \lambda (f(z) + \nabla f(z)(w_1 - z)$$
(3.2.2)

$$f(w_2) \ge f(z) + \nabla f(z)(w_2 - z)$$

$$(1 - \lambda)f(w_2) \ge (1 - \lambda)(f(z) + \nabla f(z)(w_2 - z))$$
(3.2.3)

Let 3.2.1+3.2.2 get $\lambda f(w_1) + (1-\lambda)f(w_2) \ge f(z)$

General Case: Consider f restricted to the line passing through them.

$$g(\lambda) = f(\lambda w_1 + (1 - \lambda)w_2)$$
$$\nabla g(\lambda) = \nabla f(\lambda w_1 + (1 - \lambda)w_2)^T(w_1 - w_2)$$

Assume the f is convex, which implies g is convex, so by argument above, we have $g(1) \ge g(0) + \nabla g(0)$, which implies:

$$f(w_1) \ge f(w_2) + \nabla f(w_2)^T (w_1 - w_2)$$

Now assume that this inequality holds for any x and y, so if $\lambda w_1 + (1 - \lambda)w_2 \in \text{domain of } f$, and $\lambda w_1 + (1 - \lambda)w_2 \in \text{domain of } f$, we have

$$f(\lambda w_1 + (1 - \lambda)w_2) \ge f(\widetilde{\lambda}w_1 + (1 - \widetilde{\lambda})w_2) + \nabla f(\widetilde{\lambda}w_1 + (1 - \widetilde{\lambda})w_2)^T(w_1 - w_2)(\lambda - \widetilde{\lambda})$$

so $q(\lambda) \leq q(\widetilde{\lambda}) + \nabla q(\widetilde{\lambda})(\lambda - \widetilde{\lambda})$ which implies g is convex.

Lemma 2 If f is differentiable, then f is convex if and only if its domain is convex and $\forall w_1, w_2$ in the domain

$$(\nabla f(w_1) - \nabla f(w_2))^T (w_1 - w_2) \ge 0$$

Proof:

(from [1]) If f is convex, then:

$$f(w_1) \ge f(w_2) + \nabla f(w_2)(w_1 - w_2) \tag{3.2.3}$$

$$f(w_2) \ge f(w_1) + \nabla f(w_1)(w_2 - w_1) \tag{3.2.4}$$

Use 3.2.3 + 3.2.4, we get:

$$f(w_1) + f(w_2) \ge f(w_2) + f(w_1) + \nabla f(w_2)(w_1 - w_2) + \nabla (w_1)(w_2 - w_1)$$
$$0 \ge (\nabla f(w_2) - \nabla f(w_1))^T (w_1 - w_2)$$
$$0 \le (\nabla f(w_1) - \nabla f(w_2))^T (w_1 - w_2)$$

Assume that ∇f is momotone: Define $A = \{w | f(w) \leq a\}$ If A is not convex, then there are $w_1, w_2 \in A$ such that

$$\nabla f(w_1)(w_2 - w_1) > 0$$

$$\nabla f(w_2)(w_1 - w_2) > 0$$

Since ∇f is monotone, $sign(\nabla f(w_1)) = sign(\nabla f(w_2))$

So we have $(\nabla f(w_1) - \nabla f(w_2))^T(w_2 - w_1) > 0$ which has contradiction.

Lemma 3 If f is twice differentiable, then f is convex if and only if its domain is convex and $\nabla^2 f(w) \geq 0$ in domain

Proof: (from [2]) From definition of convex, we have:

$$f(\lambda w_1 + (1 - \lambda)w_2) \le \lambda f(w_1) + (1 - \lambda)f(w_2) \forall \lambda \in [0, 1]$$

Let $\lambda = \frac{1}{2}$ and w be the midpoint between w_1 and w_2 , so we have:

$$w_1 = w + h, w_2 = w - h$$

$$f(\lambda w_1 + (1 - \lambda)w_2) \le \lambda f(w_1) + (1 - \lambda)f(w_2) \forall \lambda \in [0, 1]$$

$$f(\frac{1}{2}(w+h) + \frac{1}{2}(w-h)) \le \frac{1}{2}f(w+h) + \frac{1}{2}f(w-h)$$

$$f(w) \le \frac{1}{2}f(w+h) + \frac{1}{2}f(w-h)$$

$$2f(w) \le f(w+h) + f(w-h)$$

$$f(w+h) + f(w-h) - 2f(w) \le 0$$

The second derivative can be written in to single limit form:

$$f \nabla^2(w) = \lim_{h \to 0} \frac{f(x+h) - 2f(x) + f(x-h)}{h^2}$$

Since we get $f(w+h)+f(w-h)-2f(w)\leq 0$ and h^2 is greater than $0, f\nabla^2(w)\geq 0$

Example of convex functions:

• Exponential function:

$$y = e^{ax}, x \in R, \forall a \in R$$

Proof:

$$y\nabla^2 = a^2 e^{ax} > 0$$

From Lemma3, we can know exponential function is convex.

• Negative Logarithm:

$$y = -log(x), x \in R_{++}$$

Proof:

$$y\nabla^2 = \frac{1}{r^2} > 0$$

From Lemma3, we can know negative logarithm function is convex.

• Negative Entropy:

$$-H(x) = xlog(x), x \in R_{++}$$

Proof: Let y = xlog(x)

$$y\nabla^2 = \frac{1}{x} > 0, \forall x \in R_{++}$$

From Lemma 3, we can know y is convex, so negative entropy function is convex.

• Norms:

$$y = ||w||_p, p \ge 1$$

Proof: (from [3]) When p=1, by triangle inequality and defintion of convex

$$||\lambda w_1 + (1 - \lambda)w_2|| \le ||\lambda w_1|| + ||(1 - \lambda)w_2|| = \lambda ||w_1|| + (1 - \lambda)||w_2||$$

When p;1, by Minkowski Inequality, triangle inequality still holds

• Log-Sum-Exp:

$$y = log(e^{w_1} + e^{w_2} + \dots + e^{w_d})$$

Proof: (from [5]) The Hessian of log-sum-exp function is:

$$\nabla^2 f(w) = \frac{1}{(e^T z)^2} ((e^T z) diag(z) - zz^T),$$

where $e = [1, \dots, 1]^T$ and $z = [e^{w_1}, e^{w_2}, \dots e^{w_n}]$. To verify that $\nabla^2 f(w) \geq 0$, we must show that $v^T \nabla^2 f(w) v \geq 0$ for all v, But

$$v^T \nabla^2 f(w) v = \frac{1}{(e^T z)^2} ((\sum_{i=1}^n z_i) (\sum_{i=1}^n v_i^2 z_i) - (\sum_{i=1}^n v_i z_i)^2) \ge 0$$

by Cauchy-Schwarz inequality.

3.3 Convex Operation

1. Non-negative weighted sum: for all $\alpha_i \geq 0$, if f_i is convex $\forall i$, so is

$$g = \alpha_1 f_1 + \alpha_2 f_2 + \dots + \alpha_n f_n$$

Proof: (from [4])

Let $f_1, \dots f_n$ be convex functions, $\alpha_1, \alpha_2, \dots, \alpha_n \geq 0, w_1, w_2 \in \mathbb{R}^n$, and $\lambda \in [0, 1]$. Then:

$$f(\lambda w_1 + (1 - \lambda)w_2) = \alpha_1 f_1(\lambda w_1 + (1 - \lambda)w_2) + \dots + \alpha_n f_n(\lambda w_1 + (1 - \lambda)w_2))$$

$$\leq \alpha_1 \cdot (\lambda f_1(w_1) + (1 - \lambda)f_1(w_2)) + \dots + \alpha_n \cdot (\lambda f_n(w_1) + (1 - \lambda)f_n(w_2))$$

$$= \lambda(\alpha_1 f_1(w_1) + \dots + \alpha_n f_n(w_1)) + (1 - \lambda)(\alpha_1 f_1(w_2) + \dots + \alpha_n f_n(w_2))$$

$$= \lambda f(w_1) + (1 - \lambda)f(w_2)$$

where the second line is obtained using convexity of f_1, \dots, f_n and the fact that the inequalities preserved as $\alpha_1, \dots, \alpha_n$ are non-negative.

2. Composition with an affine mapping: if f is convex, so is

$$q(w) = f(Aw + b)$$

Proof: (from [4])

Let $w_1, w_2 \in R^n$ and $\lambda \in [0, 1]$. Then:

$$g(\lambda w_1 + (1 - \lambda)w_2)) = f(A(\lambda w_1 + (1 - \lambda)w_2) + b)$$

$$= f(\lambda \cdot Aw_1 + (1 - \lambda) \cdot Aw_2 + \lambda b + (1 - \lambda)b)$$

$$= f(\lambda \cdot (Aw_1 + b) + (1 - \lambda) \cdot (Aw_2 + b))$$

$$\leq \lambda f(Aw_1 + b) + (1 - \lambda)f(Aw_2 + b)$$

$$= \lambda g(w_1) + (1 - \lambda)g(w_2)$$

So g is convex.

3. If f_1 , f_2 are convex, so is

$$g(w) = max\{f_1(w), f_2(w)\}$$

Proof: (from [9])

Let $0 \le \lambda \le 1$ and $w_1, w_2 \in$ domain of f, then:

$$f(\lambda w_1 + (1 - \lambda)w_2)) = \max\{f_1(\lambda w_1 + (1 - \lambda)w_2)), f_2(\lambda w_1 + (1 - \lambda)w_2))\}$$

$$\leq \max\{\lambda f_1(w_1) + (1 - \lambda)f_1(w_2), \lambda f_2(w_1) + (1 - \lambda)f_2(w_2)\}$$

$$\leq \lambda \max\{f_1(w_1), f_2(w_1)\} + (1 - \lambda)\max\{f_1(w_2), f_2(w_2)\}$$

$$= \lambda f(w_1)_i (1 - \lambda)f(w_2)$$

which establishes convexity of f. It is easily shown than if f_1, f_2, \dots, f_m are convex, then pointwise maximum

$$f(x) = max\{f_1(w), f_2(w), \dots, f_m(w)\}\$$

is also convex.

Note: Pointwise minimum of two convex functions may not be convex.(from [4])

3.4 Optimality of Convex Optimization

- 1. Local Optimal and Global Optimal
 - A point w^* is locally optimal if $f(w^*) \leq f(w) \forall w$ in a neighborhood of w^*
 - A point w^* is globally optimal if $f(w^*) \leq f(w) \forall w$
 - To find a local optimum of f, $\nabla f(w^*) = 0$ is sufficient, but it is hard to find global optimum.
- 2. Optimal of Convex function
 - Convex Optimization is special
 - For convex problems, global optimality follows directly from local optimality
 - For convex function f, $\nabla f(w^*) = 0$ is sufficient for global optimality.

4 Algorithm to Search Optimum

4.1 Overview of Descent Method

Algorithm 1: iterative algorithm start with some guess w, i = 0; while $\nabla f(w) \neq 0$, iterate k times do select direction d_k ; select step size α_k ; $w \longleftarrow w + \alpha_k \cdot d_k$; end while

4.2 Descent Direction

The direction of gradient vector is the greatest increase of f, so d_k must be negative gradient direction, which is $\nabla f(w)^T d_k < 0$. Some options of d_k are listed below

1. Steepest descent: $d_k = -\nabla f(w)$

2. Scaled gradient: $d_k = -D_k \nabla f(w)$ for some constant $D_k > 0$

4.3 Descent Step Size

1. Exact: $\alpha_k = argmin_{\alpha \geq 0} f(w_k + \alpha d_k)$

2. Constant: $\alpha_k = \frac{1}{L}$ for some suitable L

3. Diminishing: $\alpha_k \to 0$ but $\sum_k \alpha_k = \infty$ i.e., $\alpha_k = \frac{1}{k}$

4. Armijo Rule: Start with initial step size s, and continue with $\alpha = \beta s$, $\alpha = \beta^2 s$, $\alpha = \beta^m s$ till $\alpha = \beta^m s$ falls within the set of α with

$$f(w_k + \alpha d_k) - f(w_k) \le \sigma \alpha \nabla f(w_k)^T d_k$$

where $\sigma \in (0,1)$ Armijo rule allows us to choose suitable step size that makes every next step to be sufficient decrease such that every next step is smaller than $\sigma \alpha \nabla f(w_k)^T d_k$.

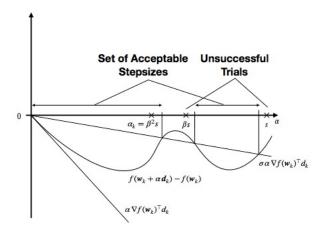


Figure 2: Constrain of Armijo Rule

However, Armijo rule is not sufficient to ensure every next step is a reasonable progress, the curvature condition bound the lower bound of every step size, so the step size will not be unacceptably short:

$$\nabla f(w_k + \alpha_k d_k)^T d_k \ge \epsilon \nabla f_k^T d_k$$

where $\epsilon \in (\sigma, 1)$ [8].

4.4 Convergence Rate

1. Lipschitz Continuous Gradient Definition: The gradient of f is Lipschitz continuous with parameter L > 0 if

$$\|\nabla f(w_1) - \nabla f(w_2)\|_2 \le L \|w_1 - w_2\|_2$$

for all $w_1, w_2 \in dom(f)$

Intuition: if have Lipschitz continuous gradient, then $g(w) = \frac{L}{2} \|w\|_2^2 - f(w)$ is convex **Proof:**

$$(\nabla f(w_1) - \nabla f(w_2))^T (w_1 - w_2) \le \|\nabla f(w_1) - \nabla f(w_2)\|_2 \|w_1 - w_2\|_2$$

$$\le L \|w_1 - w_2\|_2^2$$
(4.4.1)

Since $\nabla g(w) = L(w) - \nabla f(w)$

$$(\nabla g(w_1) - \nabla g(w_2))^T (w_1 - w_2) = (L(w_1 - w_2) - (\nabla f(w_1) - \nabla f(w_2)))^T (w_1 - w_2)$$

$$= L \|w_1 - w_2\|_2^2 - (\nabla f(w_1) - \nabla f(w_2))^T (w_1 - w_2)$$

$$\geq 0$$

$$(4.4.2)$$

We can get 4.4.2 from 4.4.1. Since

$$(\nabla g(w_1) - \nabla g(w_2))^T (w_1 - w_2) \ge 0$$

, by lemma 2 of convex function we get g(w) is convex

Intuition: if $g(w) = \frac{L}{2} \|w\|_2^2 - f(x)$ is convex, then:

$$g(w_2) \ge g(w_1) + \nabla g(w_1)^T (w_2 - w_1)$$

$$\frac{L}{2} \|w_2\|_2^2 - f(w_2) \ge \frac{L}{2} \|w_1\|_2^2 - f(w_1) + (L \cdot w_1 - \nabla f(w_1))(w_2 - w_1)$$

$$\frac{L}{2} \|w_2 - w_1\|_2^2 - f(w_2) \ge -f(w_1) - \nabla f(w_1)^T (w_2 - w_1)$$

$$f(w_2) \le f(w_1) + \nabla f(w_1)^T (w_2 - w_1) + fracL2 \|w_2 - w_1\|_2^2 \forall w_1, w_2$$
 (1)

2. Strong Convexity

$$f(w_2) \ge f(w_1) + \nabla f(w_1)^T (w_2 - w_1) + \frac{\sigma}{2} \|w_2 - w_1\|_2^2 \ \forall w_1, w_2$$

3. Convergence Rate of Lipschitz Continuous Rradient with Strong Convexity

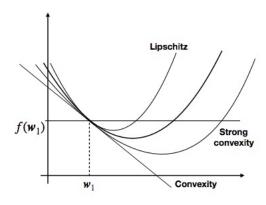


Figure 3: Lipschitz Continuous and Strong Convexity Bound

As shown in the picture, the strong convexity and Lipschitz continuous gradient work as lower bound and upper bound of f respectively. Note if f is twice differentiable,

$$\sigma I < \nabla^2 f(w) < LI \ \forall w$$

To know the convergence rate, we need to know how many iterations k such that

$$f(w_k) - f(w^*) \le \epsilon$$

for $w_{k+1} = w_k + \alpha d_k$, where the chosen αd_k can minimize w.r.t w_{k+1} right-hand-side of upper bound.

$$f(w_{k+1}) \le f(w_k) + \nabla f(w_k)^T (w_{k+1} - w_k) + \frac{L}{2} \|w_{k+1} - w_k\|_2^2$$

Take deivative can get $\nabla f(w_k) + L(\alpha d_k) = 0$ so $\alpha d_k = -\frac{1}{L} \nabla f(w_k)$.

$$f(w_{k+1}) \leq f(w_k) + \nabla f(w_k)^T (w_{k+1} - w_k) + \frac{L}{2} \|w_{k+1} - w_k\|_2^2$$

$$f(w_{k+1}) \leq f(w_k) + \nabla f(w_k)^T ((w_k - \frac{1}{L} \nabla f(w_k)) - w_k) + \frac{L}{2} \|w_k - \frac{1}{L} \nabla f(w_k) - w_k\|_2^2$$

$$f(w_{k+1}) \leq f(w_k) - \frac{1}{2L} \|\nabla f(w_k)\|_2^2$$

$$f(w_k) \leq f(w_{k-1}) - \frac{1}{2L} \|\nabla f(w_{k-1})\|_2^2$$

which implies guaranteed progress of step k is $f(w_{k-1}) - \frac{1}{2L} \|\nabla f(w_{k-1})\|_2^2$. Similarly, if we apply strong convexity, we can get the maximum sub-optimality is

$$f(w_*) \ge f(w_k) - \frac{1}{2\sigma} \|\nabla f(w_k)\|_2^2$$

The distance we need to go is

$$f(w_k) - f(w^*) \le \frac{1}{2\sigma} \| \nabla f(w_k)_2^2 \|$$

, so $(f(w_k) - f(w^*))2\sigma \leq \|\nabla f(w_k)_2^2\|$). Then we have in gauranteed progress:

$$f(w_k) - f(w^*) \le f(w_{k-1}) - f(w^*) - \frac{1}{2L} \|\nabla f(w_{k-1})\|_2^2$$

$$\le f(w_{k-1}) - f(w^*) - \frac{\sigma}{L} (f(w_{k-1}) - f(w^*))$$

$$= (1 - \frac{\sigma}{L}) (f(w_{k-1}) - f(w^*))$$

$$\le (1 - \frac{\sigma}{L})^k (f(w_{k-1}) - f(w^*))$$

So we can get:

$$C(1 - \frac{\sigma}{L})^k \le \epsilon$$
$$k \ge O(\log(\frac{1}{\epsilon}))$$

4. Lipschitz Continuous Gradient Without Strong Convexity Assumption Lipschitz bound and $w_2 = w_1 - \alpha \nabla f(w_1)$ yields

$$f(w_2) \le f(w_1) - (1 - \frac{L\alpha}{2})\alpha \|\nabla f(w_1)\|_2^2$$

Combined with convexity: $f(w_1) + \nabla f(w_1)^T(w^* - w_1) \leq f(w^*)$

$$f(w_2) \le f(w^*) + \nabla f(w_1)(w_1 - w^*) - \frac{\alpha}{2} \|\nabla f(w_1)\|_2^2$$

Using $w_2 - w_1 = -\alpha \nabla f(w_1)$ and rearranging terms gives

$$f(w_2) \le f(w^*) + \frac{1}{2\alpha} (\|w_1 - w^*\|_2^2 - \|w_2 - w^*\|_2^2)$$

Summing over all iterations

$$\sum_{i=1}^{k} (f(w_i) - f(w^*)) \le \frac{1}{2\alpha} \|w_0 - w^*\|_2^2$$

 $f(w_i)$ non-increasing:

$$f(w_k) - f(w^*) \le \frac{1}{k} \sum_{i=1}^k (f(w_i) - f(w^*)) \le \frac{1}{2\alpha} \|w_0 - w^*\|_2^2 \le \epsilon$$

Consequently:

$$k \ge O(\frac{1}{\epsilon})$$

4.5 Acceleration of Optimization

1. The convergence rates in section 4.4 are not optimal, we can add an extra momentum term to accelerate the convergence.

Intuition: if direction of current gradient step is same as direction of previous step, move further than previous step; if the direction of current gradient step is opposite to previous step direction, move less than previous step.

• Polyak's method(Aka heavy ball):

$$w_{k+1} = w_k - \alpha_k \nabla f(w_k) + \beta_k (w_k - w_k - 1)$$

• in deep learning

$$v_{k+1} = \beta v_k + \nabla f(w_k)$$

$$w_{k+1} = w_k - \alpha v_{k+1}$$

- 2. Another aspect we can make the convergence rate better is to reduce the time for computing the gradient. The iteration complexity is linear to the size of dataset, so a large dataset will make gradient computing slow. To deal with this problem, the stochastic gradient descent method is introduced. In stochastic gradient descent, a subset of samples are selected to approximate the gradient based on this batch of data.
 - (a) General Steps
 - Select a subset B_k from all samples
 - Gradient Update using Approximation

$$\nabla f(w) \approx \sum_{(x^i, y^i) \in B_k}$$

- (b) Convergence Rate
 - Lipschitz continuous gradient and strongly convex: $k \geq O(\frac{1}{\epsilon})$
 - Lipschitz continuous gradient: $k \ge O(\frac{1}{\epsilon^2})$

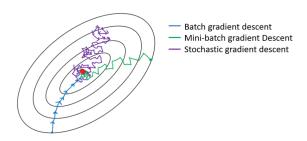


Figure 4: Stochastic, Min batch, Batch gradient descent [7]

References

- [1] Proof of Convexity and Monotone, 2016. Available at https://math.stackexchange.com/questions/1717542/a-function-is-convex-if-and-only-if-its-gradient-is-monotone.
- [2] Convexity and Second Derivative, 2017. Available at https://math.stackexchange.com/questions/1224955/proving-that-the-second-derivative-of-a-convex-function-is-nonnegative.
- [3] Why is every p-norm convex, 2017. Available at https://math.stackexchange.com/questions/2280341/why-is-every-p-norm-convex.
- [4] A. A. Ahmadi. Operations that preserve convexity, 2014. Available at http://www.princeton.edu/~amirali/Public/Teaching/ORF363_COS323/F14/ORF363_COS323_F14_Lec6.pdf.
- [5] N. Andrei. Convex Functions, 2005. Available at https://camo.ici.ro/neculai/convex.pdf.
- [6] CheCheDaWaff. Convex polygon illustration. Available at https://commons.wikimedia.org/w/index.php?curid=49543150.
- [7] G. Dahl. A mini-introduction to convexity, 2014. Available at https://www.uio.no/studier/emner/matnat/math/MAT-INF3100/v14/convmat-inf3100.pdf.
- [8] J. Nocedal and S. J. Wright. *Numerical Optimization*. Springer, New York, NY, USA, second edition, 2006.
- [9] L. V. Stephen Boyd. Convex Optimization). Campridge University Press, 2004.