# NM hw4 report

#### P1.

#### a. Divided difference table

```
      0
      0.15000 0.176091
      2.435467
      -5.750502

      1
      0.21000 0.322219
      1.975427
      -3.908814

      2
      0.23000 0.361728
      1.740898
      -2.946377

      3
      0.27000 0.431364
      1.475724
      -2.230693

      4
      0.32000 0.505150
      1.297269

      5
      0.35000 0.544068
```

#### b. For each 3 points, calculate with formula:

```
P_2'(x_i) = f[x_i, x_{i+1}] + f[x_i, x_{i+1}, x_{i+2}][(x - x_i) + (x - x_{i+1})]
```

```
for i in range(n-2):
    xs = data[i:i+3]
    ys = [f(x) for x in xs]
    # 差商表
    t = [[0 for _ in range(3)] for _ in range(3)]
    for k in range(3):
        t[k][0] = ys[k]
    for j in range(1, 3):
        for k in range(3-j):
        t[k][j] = (t[k+1][j-1] - t[k][j-1]) / (xs[k+j] - xs[k])
```

#### c. Result

```
連續三點組合、插值導數、真值、誤差:
[0.15, 0.21, 0.23] f'=1.423379 真值=1.620502 誤差=1.97e-01 [0.21, 0.23, 0.27] f'=1.600181 真值=1.620502 誤差=2.03e-02 [0.23, 0.27, 0.32] f'=1.634829 真值=1.620502 誤差=1.43e-02 [0.27, 0.32, 0.35] f'=1.596182 真值=1.620502 誤差=2.43e-02 最佳連續三點組合: [0.23, 0.27, 0.32] 對應插值導數: 1.634829 真值: 1.620502 最小誤差: 1.43e-02
```

 $\Rightarrow$  3 points with least error are [0.23, 027, 0.32]

## p2.

#### a. Function difference table

0	0.30	0.398507	0.261302	-0.006371	-0.002190	0.000341
1	0.50	0.659809	0.254931	-0.008561	-0.001849	0.000415
2	0.70	0.914739	0.246370	-0.010410	-0.001434	0.000472
3	0.90	1.161109	0.235960	-0.011843	-0.000961	
4	1.10	1.397069	0.224117	-0.012805		
5	1.30	1.621186	0.211312			
6	1.50	1.832498				

# b.對插值多項式微分去近似多項式的微分,套用funciton difference table的值去計算

```
(a) f'(0.72) 估計值: 1.2509594908521686 ,使用點: [0.7, 0.9, 1.1, 1.3]
(b) f'(1.33) 估計值: 1.078969516076625 ,使用點: [1.1, 1.3, 1.5]
(c) f'(0.50) 估計值: 1.2925483703540175 ,使用點: [0.3, 0.5, 0.7, 0.9, 1.1]
```

p3.

```
P(u) = ant + bus + cu2 + dy + e
 0 p(4) =1
   > f "(Xo) = (2+4 +6+ (1+6) = P'(6) =0
@ P(4) = 4
   f== 2h f==-h ,fo=0 ,f=h, f= -2h
 => f"(x0) = (2 (2h) + (1 (-h) + (1h) + (24) = 1"(0) =0
3 P(4)= 62
 +2=4h2, += h2, f=0, +(=h2, +)=4h2
 == f'(1/6) = (-2(4/2) + (-1(h2)+(-1)2+(-1(4/2) = p'(0) = 2
 @ p(4)=43
 to=817.f1=-13,f=13,f2=813
 f"(16) = (2(-8h3)+ (-(-h3)+ L1h3+(2(8h3)= P70)= 0
 5 P(4) = 44
  f== 16h+, f-1=-h4, f= h4, fz=16h4
 f"(X6)=(=(1644)+(-1(-44)+ (144 + (21644 = P"(0) =0
```

$$= \int ||(X)| = -\frac{1}{2} + 16 \cdot 6 - 1 - 70 \cdot 6 + 16 \cdot 6 \cdot 1 - 6$$

$$= ||(Z)| + ||(X)| = ||(Z)| + ||(X)| = ||(Z)| + ||(X)| = ||(Z)| + ||(X)| = ||(Z)| + ||(X)| +$$

#### **P4**

#### a. 全部使用 1/3 rule 作為基準

```
# 1. 全部用 1/3 rule

I_13_all = (
    simpson_13(y[0], y[1], y[2], h) +
    simpson_13(y[2], y[3], y[4], h) +
    simpson_13(y[4], y[5], y[6], h) +
    simpson_13(y[6], y[7], y[8], h)
)
print(f"全部用 1/3 rule (正確答案): {I_13_all:.6f}")
```

全部用 1/3 rule (正確答案): 1.766933

#### b. 2 組 3/8 + 1 組 1/3 (4,4,3), (4,3,4), (3,3,4)

```
# (a) 3/8 on [0:3], 3/8 on [3:6], 1/3 on [6:8]

I_a = simpson_38(y[0], y[1], y[2], y[3], h) + simpson_38(y[3], y[4], y[5], y[6], h) + simpson_13(y[6], y[7], y[8], h)

results.append(("3/8[0:3], 3/8[0:3], 3/8[0:3], 3/8 on [5:8]

I_b = simpson_38(y[0], y[1], y[2], y[3], h) + simpson_13(y[3], y[4], y[5], h) + simpson_38(y[5], y[6], y[7], y[8], h)

results.append(("3/8[0:3], 1/3[3:5], 3/8 on [5:8]

I_c = simpson_13(y[0], y[1], y[2], h) + simpson_38(y[2], y[3], y[4], y[5], h) + simpson_38(y[5], y[6], y[7], y[8], h)

results.append(("1/3[0:2], 3/8 on [2:5], 3/8 on [5:8]

I_c = simpson_13(y[0], y[1], y[2], h) + simpson_38(y[2], y[3], y[4], y[5], h) + simpson_38(y[5], y[6], y[7], y[8], h)

results.append(("1/3[0:2], 3/8[2:5], 3/8[5:8]", I_c, abs(I_c - I_13_all)))
```

#### c. 取誤差最小的一組

```
2 組 3/8 + 1 組 1/3 (連續分法) 與正確答案的誤差: 3/8[0:3],3/8[3:6],1/3[6:8]: 積分值=1.766946, 誤差=1.25e-05 3/8[0:3],1/3[3:5],3/8[5:8]: 積分值=1.766950, 誤差=1.67e-05 1/3[0:2],3/8[2:5],3/8[5:8]: 積分值=1.766946, 誤差=1.25e-05 最佳分法: 3/8[0:3],3/8[3:6],1/3[6:8], 誤差=1.25e-05
```

 $\Rightarrow$  3/8 rule on [1,4], [4,7] and 1/3 rule on [7,9]

#### **P5**

a. use trapezoidal rule with halving h on every iteration until the integral value does not differ more than 0.02

```
while True:
    n *= 2
    I_new = trapezoidal(f_trap, a, b, n)
    print(f"n={n:4d}, h={(b-a)/n:.5f}, integral={I_new:.6f}, diff={abs(I_new-I_old):.6f}")
    if abs(I_new - I_old) < 0.02:
        break
    I_old = I_new
h_final = (b - a) / n</pre>
```

#### b. Result

```
Adaptive Trapezoidal Rule for f(x) = 1/x^2 over [0.2, 1]:
n= 2, h=0.40000, integral=6.311111, diff=4.088889
n= 4, h=0.20000, integral=4.718056, diff=1.593056
n= 8, h=0.10000, integral=4.197677, diff=0.520378
n= 16, h=0.05000, integral=4.051043, diff=0.146635
n= 32, h=0.02500, integral=4.012876, diff=0.038166
n= 64, h=0.01250, integral=4.003227, diff=0.009650

Terminated at h = 0.01250, integral = 4.003227
```

 $\Rightarrow$  h = 0.0125, integral = 4.003227

### **P6**

先積y再積x,每次以panel width = h (0.1)去積分,並將[a,b]映射成[-1,1]再加上講義中給的3-term高斯節點以及權重,積分出面積。

```
nodes = np.array([-0.77459667,0,0.77459667])
weights = np.array([0.55555555,0.888888889,0.55555555])
x_{start}, x_{end} = -0.2, 1.4
y_start, y_end = 0.4, 2.6
h = 0.1
integral = 0.0
x_panels = np.arange(x_start, x_end, h)
y_panels = np.arange(y_start, y_end, h)
for i in range(len(x_panels)):
    for j in range(len(y_panels)):
        x_a, x_b = x_panels[i], x_panels[i] + h
        y_a, y_b = y_panels[j], y_panels[j] + h
        for xi in range(3):
            for yi in range(3):
                # 範圍映射到 [-1,1] -> [a,b]
x = 0.5 * (x_b - x_a) * nodes[xi] + 0.5 * (x_b + x_a)
                y = 0.5 * (y_b - y_a) * nodes[yi] + 0.5 * (y_b + y_a)
                w = weights[xi] * weights[yi]
                integral += w * f(x, y) * 0.25 * (x_b - x_a) * (y_b - y_a)
```

**P7** 

$$Q_{n} = \frac{1}{L} \int_{-L}^{L} f_{excn}(x) \cos\left(\frac{h\pi_{L}x}{L}\right) dx$$

$$= \frac{2}{L} \int_{0}^{L} f_{excn}(x) \cos\left(\frac{h\pi_{L}x}{L}\right) dx$$

$$= \frac{2}{L} \int_{0}^{L} f_{excn}(x) \cos\left(\frac{h\pi_{L}x}{L}\right) dx$$

$$= \frac{2}{L} \int_{0}^{L} f_{excn}(x) \cos\left(\frac{h\pi_{L}x}{L}\right) dx$$

$$\Rightarrow Q_{n} = \int_{0}^{L} f(x) \cos\left(\frac{h\pi_{L}x}{L}\right) dx$$

#