view_frames Result

Recorded at time: 1625453831.079

map

Broadcaster: /slamware_ros_sdk_server_node
Average rate: 19.933 Hz
Most recent transform: 1625453831.038 ( 0.041 sec old)
Buffer length: 4.866 sec

odom

Broadcaster: /slamware_ros_sdk_server_node
Average rate: 19.929 Hz
Most recent transform: 1625453831.041 ( 0.039 sec old)
Buffer length: 4.867 sec

base_link

Broadcaster: /slamware_ros_sdk_server_node
Average rate: 19.956 Hz
Most recent transform: 1625453831.092 ( -0.012 sec old)
Buffer length: 4.961 sec

laser

Broadcaster: /laser2foot
Average rate: 10.168 Hz
Most recent transform: 1625453831.135 ( -0.056 sec old)
Buffer length: 4.819 sec

base_footprint