

# Computer Vision – Identify Surgical Instrument

Challenge Rules & Guidelines

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# 1. Overview

**Computer vision** has advanced considerably but is still challenged in matching the precision of human intelligence. Could AI assist human to perform Surgical instrument counting go in and out of Hospital Operating Theatre – a task that take place over hundred thousand times per year!

In this competition, you are challenged to build a machine learning model that identifies the categories of Ophthalmology surgical instrument in an images dataset on HKSTP's latest service addition – Validation Platform where Optimal Performance Metrics can be formed. By automating this task, your participation will help spare enormous amount of health professional time for direct patient care and connection.

Phaco and Intraocular, two common instrument sets used in ocular surgery around 10,000 times annually, will be used for the competition.

## 2. Data

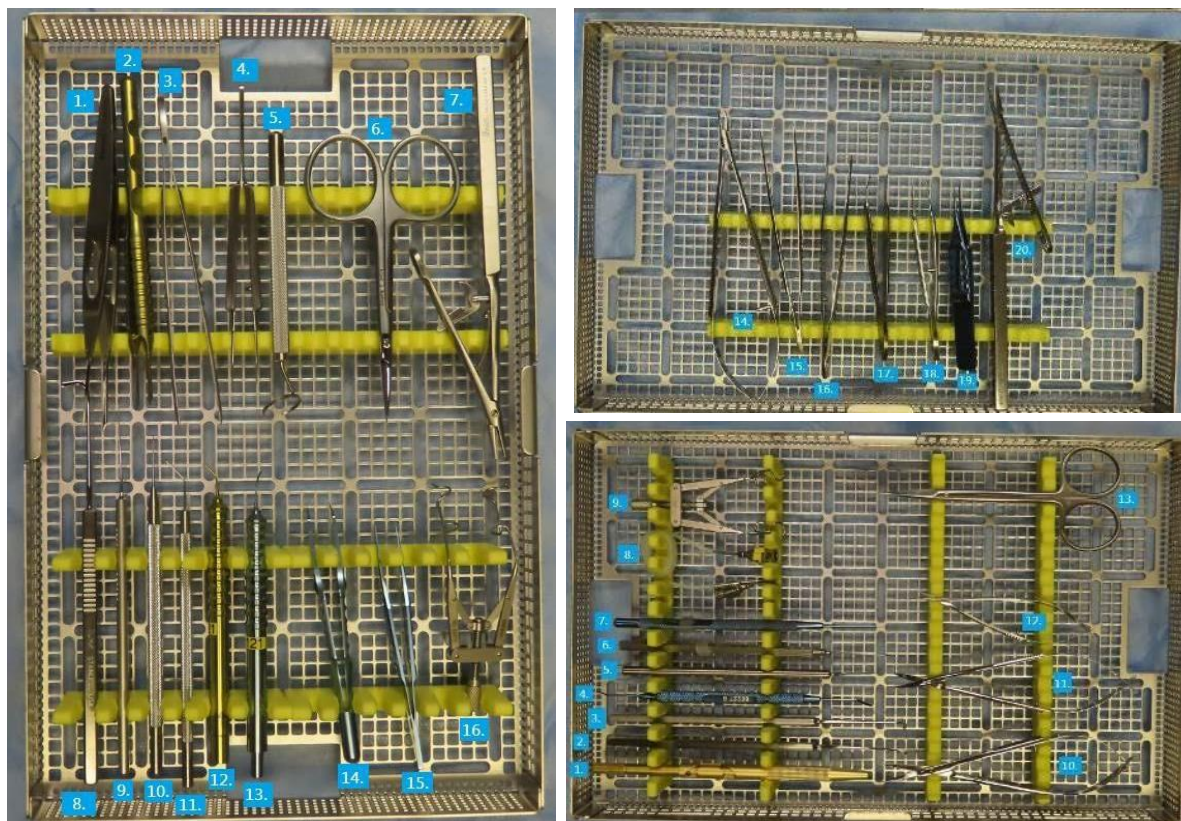
Contestants are expected to train their model to recognise surgical instruments on an instrument tray. Contestants are expected to find the data to train their model.

### Instrument Trays

The surgical instruments will be placed on an *ophthalmic instrument sterilization tray*. There will be around 100 questions in the Game, as shown in the following diagram.

There will be only 2 different sterilization trays used in the Game, as illustrated in the following diagram 1) left or right bottom photo (same tray) and 2) right top photo. Photo might be in horizontal or vertical.

Instruments will be arranged tidily on the yellow holders. However, the instrument type, the position and the orientation will be changed in different testing photos, e.g. item 8 in the left photo might be replaced with item 1, or item 8 will be taken out from the testing image, or item 8 will be displaced with 180-degree rotation and the needle is pointing downside.

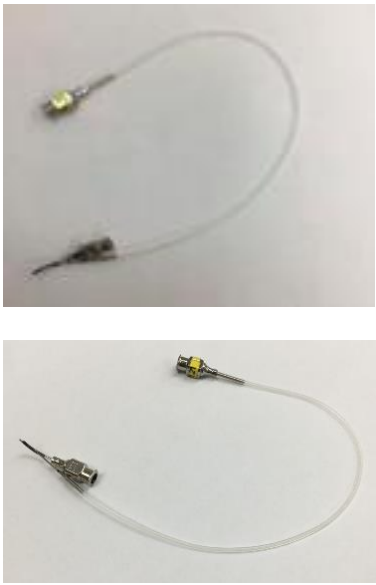





### Surgical Instruments













There are **15 categories of surgical instruments** that contestants are expected to annotate the position, identify the **category** name, and count.


There will be additional surgical instruments, **not included within the 15 categories**, that will be included in the trays and are intended to create false positives. These tools should be ignored and should not be identified.

Model names are provided below for each category to aid the data collection process:

Category Name	Model Name	Image
Cannula	<ul style="list-style-type: none"><li>• Simcoe IA, cannula simcoe I/A: katena K7-4300</li></ul>	
Chopper	<ul style="list-style-type: none"><li>• Nagahara Chop phaco, Chop, phaco: Asico AE-2515</li></ul>	
Dressing Forceps	<ul style="list-style-type: none"><li>• Alcon loading fx, Forceps IOL loading:alcon 560.01</li><li>• Fx. Conjunctival moorfields, Surtex FR-838-10</li></ul>	

Fixation Ring	<ul style="list-style-type: none"> <li>• Ring Nichamin ring, Ring globe fixation: Rheine 8-15217</li> </ul>	
Handpieces	<ul style="list-style-type: none"> <li>• Aspiration handpiece, Aspiration handpiece, 23G 0.65mm: D&amp;K 8-657</li> <li>• Irrigation handpiece, irrigation handpiece 23G 0.65mm: D&amp;K 8-652-1</li> </ul>	
Hook Surgical	<ul style="list-style-type: none"> <li>• Hook muscle, Hook muscle Graefe: storz E0592</li> <li>• Sinskey II lens hook round, hook manipulating lens, Sinskey: katena K3-5232</li> </ul>	
Iris Scissors	<ul style="list-style-type: none"> <li>• Sc Iris straight, Scissors iris: Storz E3404</li> <li>• Sc Iris straight, Scissors iris: katena K4-7400</li> </ul>	
Knife Scalpel Handles	<ul style="list-style-type: none"> <li>• Knife diamond 45o, Knife diamond: Meyco ME-600</li> <li>• Knife tooke's, Knife cornea: katena K2-3650</li> </ul>	
Micro Scissors	<ul style="list-style-type: none"> <li>• Scissors, Williamson Noble, Scissors conjunctiva: dixey D680,680a</li> <li>• Castroviejo corneal, Scissors cornea: storz E3220</li> <li>• Straight vannas, Scissors</li> </ul>	

	capsulotomy: storz E3386	
Needle Holders	<ul style="list-style-type: none"> <li>• Needle holder Castroviejo, Needle holder: Dixey D605M4</li> <li>• Needle holder Silcock, Needle holder: dixey D600</li> </ul>	 
Pusher	<ul style="list-style-type: none"> <li>• Pusher, lens (straight), Pusher, IOL , Aker: katena K3-2720</li> </ul>	
Spatula Surgical	<ul style="list-style-type: none"> <li>• Repositor iris, Repositor iris: shandeng 88227B</li> <li>• Repositor iris, Repositor iris: Storz E706</li> </ul>	 
Speculum	<ul style="list-style-type: none"> <li>• Speculum Lieberman, Speculum, k wire, 15mm: katena K1-5671/katena K1-5675</li> </ul>	 
Spoon Surgical	<ul style="list-style-type: none"> <li>• Vectus, lens loop: dixey D261</li> </ul>	 
Tissue Forceps	<ul style="list-style-type: none"> <li>• Mcpherson angled, Forceps tying: storz E1815A</li> <li>• Mcpherson straight, Forceps tying straight: Storz E1815S</li> <li>• Fx, notched st cornea, Forceps notched pierse 0.25mm: D&amp;K 2-100</li> </ul>	 

	<ul style="list-style-type: none"> <li>• Fx loading D&amp;K (AMO's), Forceps IOL loading: D&amp;K DK7726</li> <li>• Fx, capsulorhexis utrata, Forceps utrata capsulorhexis: katena K5- 5082</li> <li>• Mcpherson angled, Forceps tying: D&amp;K 2-522, 2-522E</li> <li>• Fx, notched st cornea, Forceps notched pierse 0.25mm: D&amp;K 2-100</li> </ul>	
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Additional reference websites are provided:

- <http://novosurgical.com/>
- <https://www.eyecareandcure.com/ECC-Products/Surgical-Instruments>
- <https://www.storzeye.eu/our-instruments/>
- <https://www.titanmedicalshop.com/products/>
- <https://www.accutome.com/>



### 3. Evaluation Criteria

Each contestant's model will be scored based on its localisation, classification, and counting accuracy.

#### a) Localisation

*The accuracy for identifying the position of each surgical instrument.*

Contestants are expected to annotate the position of each surgical instrument on the tray using bounding boxes. Intersection over Union (IoU) will be used to evaluate the localisation and contestants will be penalised for false-positive bounding boxes.



#### b) Classification

*The accuracy for identifying which surgical instruments are on the tray.*

Contestants are also expected to name all the surgical instruments on the tray. **Precision per class** will be used to evaluate classification performance. The classification result is considered correct when the precision is greater than 0.5.

$$\text{Precision} = \frac{TP}{TP + FP}$$

### c) Counting Accuracy

*The accuracy for counting how many of each surgical instrument is present.*

Contestants are expected to count how many of each surgical instrument is on the tray. The **correct rate** will be used to evaluate the counting accuracy and is considered most correct when the correct rate is 100%.

$$CR = \frac{C}{A}$$

CR – The correct rate;

C – The number of sample recognized correctly;

A – The number of all sample;

If a contestant has mistakenly identified an extra surgical instrument they will be penalised. The **object precision rate** will be used to measure the precision of detected objects on the prediction. A 100% rate means the object prediction highly matches the ground truth.

$$OPR = 1 - \frac{|L - A|}{A}$$

OPR - Objects precision rate

A - The number of all sample

L - The total number of prediction objects

### Winner Determination

There will be 1 winner from each evaluation criteria and 1 overall winner. To determine the overall winner, the score from each evaluation criteria will be normalised, weighted, and combined, and the team with the highest overall score will be chosen.

$$\bar{x} = \sum R_t \times W_t$$

$\bar{x}$  = Final score

$t$  = Tasks,  $t \in \{\text{classification, localization, counting}\}$

$R_t$  = Group ranking in the tasks

$W_t$  = Weight of the tasks,  $W \in \{\text{classification: 0.4, localization: 0.35, counting: 0.25}\}$

## 4. Submission

Each contestant's model will be tested by the Hospital Authority.

### Expected Output

Contestants will need to read the file paths specified within *input\_data.csv* to receive the questions.

For each question, contestants should output their answer to 2 files: *prediction\_result.csv* and *counting\_result.csv*.

The *prediction\_result.csv* file should contain:

Label file (class, prediction score, xmin, ymin, xmax, ymax);

The *counting\_result.csv* file should contain:

Label file (class, count);

The prediction program should have the following arguments (Python example):

```
python src/<path-to-prediction-program> <input-data-csv-filename> <path-for-output-prediction-csv> <path-for-output-counting-csv>
```

The .csv files should look like this:

*input\_data.csv* (provided question):

ImagePath
test/intraocular1.jpg
test/phaco1.jpg

*prediction\_result.csv* (contestant answer):

ImagePath	PredictionString (class prediction score xmin ymin xmax ymax;)
test/intraocular1.jpg	"Knife Scalpel Handles" 0.57 127 1668 1473 1755;"Hook Surgical" 0.45 202 1548 1662 1628;"Spoon S
test/phaco1.jpg	"Dressing Forceps" 0.68 1344 316 1453 832;"Tissue Forceps" 0.7 1478 301 1520 885;"Dressing Force

*counting\_result.csv* (contestant answer):

ImagePath	PredictionString (class prediction score xmin ymin xmax ymax;)
test/intraocular1.jpg	"Knife Scalpel Handles" 2;"Hook Surgical" 2;"Spoon Surgical" 1;"Spatula Surgical" 1;"Pusher" 1;"Can
test/phaco1.jpg	"Dressing Forceps" 2;"Tissue Forceps" 4;"Fixation Ring" 1;"Iris Scissors" 1;"Needle Holders" 1;"Hook :

The following is an example of a question and answer:



#### Prediction Result

"Knife Scalpel Handles" 0.57 127 1668 1473 1755;  
"Hook Surgical" 0.45 202 1548 1662 1628;  
"Spoon Surgical" 0.69 152 1316 1493 1395;  
"Spatula Surgical" 0.90 270 1195 1507 1256;  
"Knife Scalpel Handles" 0.87 256 1070 1379 1154  
"Pusher" 0.71 232 963 1519 1022;  
"Hook Surgical" 0.83 721 771 1027 876;  
"Cannula" 0.92 711 620 1032 698;  
"Speculum" 0.56 309 239 1090 559;  
"Micro Scissors" 0.59 1553 1510 2770 1832;  
"Micro Scissors" 0.64 1605 1145 2741 1426;  
"Micro Scissors" 0.66 1720 835 2608 1092;  
"Iris Scissors" 0.73 1551 129 2708 639;

#### Counting Result

"Knife Scalpel Handles" 2;  
"Hook Surgical" 2;  
"Spoon Surgical" 1;  
"Spatula Surgical" 1;  
"Pusher" 1;  
"Cannula" 1;  
"Speculum" 2;  
"Micro Scissors" 3;  
"Iris Scissors" 1;