

AVC Plan

Robot name: Apollo 100

Team members and roles (Note. we all plan to help on all things so roles are only a rough guideline):

-Thomas Edwards - Lead/Manager

-Julian Schurhammer - Software

-Nicky McCleery - Hardware

-Harry Just - Hardware

-Adam Jiang – Software

Our full plan and weekly up to date progress can be found on Git hub

Link to Team GitHub: <https://github.com/harryJst/AVCTeam3>

Week	Dates	Team Objectives	Due	Conflicts	Task outline
1	18April	Organise everything	22 April AVC PLAN	Phys 122 test	<ul style="list-style-type: none"> • Thomas- Organise things and set up Git Page • Julian - Write test code for moving robot • Nicky & Harry - Build first chassis • Adam - Gather info on networking gate • Everyone- Facebook and group chat
Holiday	25April	Finish off Week 1 tasks if not done			
2	2May	Have the robot moving through networking gate			<ul style="list-style-type: none"> • Thomas- Review and write up progress & help • Julian - Write test code for following white line • Nicky & Harry - Work on upgrading chassis • Adam - Write code for networking gate
3	9May	Have the robot chassis design finalised and have the robot following white line Quadrant 2 complete		Comp 102 test	<ul style="list-style-type: none"> • Thomas- Review and write up progress & help • Julian - Write test code for turning with white line • Nicky - Work on chassis or help with code • Harry - Work on chassis or help with code • Adam - Help with code for turning and overcoming intersections
4	16May	Quadrant 3 complete	Progress Report	ENGR 121 test	<ul style="list-style-type: none"> • Update results, work on quadrant 3
5	23May	Quadrant 4 complete			<ul style="list-style-type: none"> • Update results, work on quadrant 4
6	30May	Everything complete	ROBOT due	ENGR 101 test	<ul style="list-style-type: none"> • Update results, work on anything if behind
7	6June				
8	13June		Final Report due		

