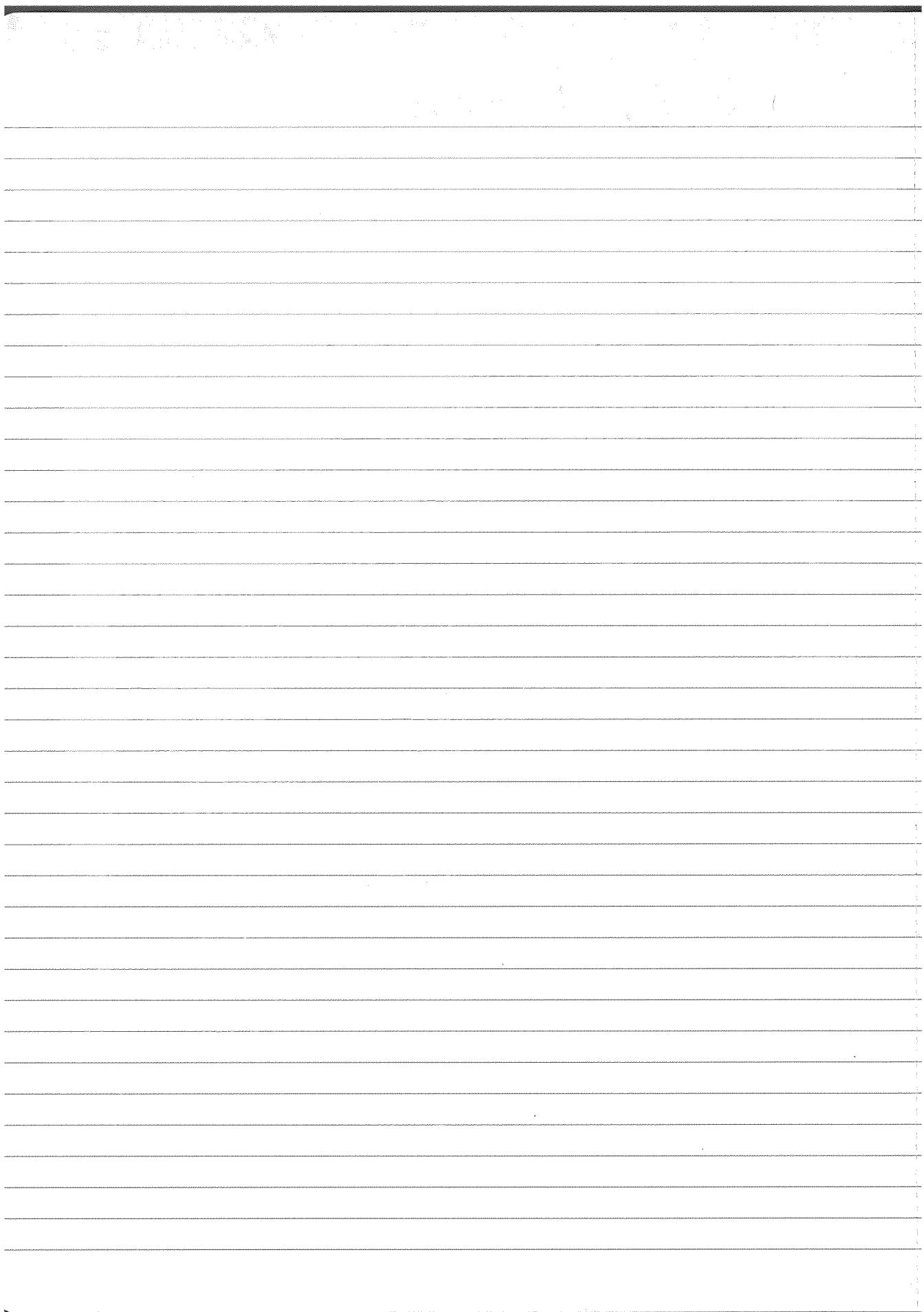


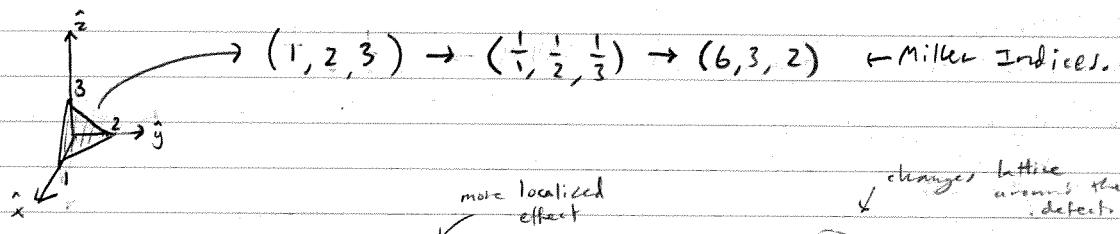
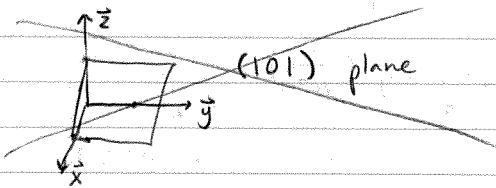
Alex Omid-Zohoor

Quals Notebook



- Crystal Structure:

- primitive cell is the smallest unit cell
- Miller Indices

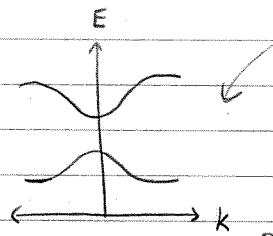


- imperfections

- imperfections can be fixed by annealing.

- Energy Band

E-k diagram



$$F = m_n^* \frac{dv}{dt} \quad m_n^* = \left(\frac{1}{\hbar^2} \frac{\partial^2 E}{\partial k^2} \right) (E)$$

↑ effective mass accounts for complex crystalline fields + quantum mechanics in crystal.

- Hole - $J = -e \sum_{\text{filled}} v_i = -e \left[\sum_{\text{total}} v_i - \sum_{\text{empty}} v_i \right] = +e \sum_{\text{empty}} v_i$

⇒ negative effective mass of electron in valence band. ← ??

$$\frac{1}{m_{xy}^*} = \frac{1}{\hbar^2} \frac{\partial^2 E}{\partial k_x \partial k_y}$$

$T \uparrow \Rightarrow E_g \downarrow$ Lattice expands ⇒ bonding is weakened ⇒ easier for e^- to escape

- Semiconductor in Equilibrium - No external force applied.

- Density of states: $g(E) \propto (m^*)^{3/2} \sqrt{E}$

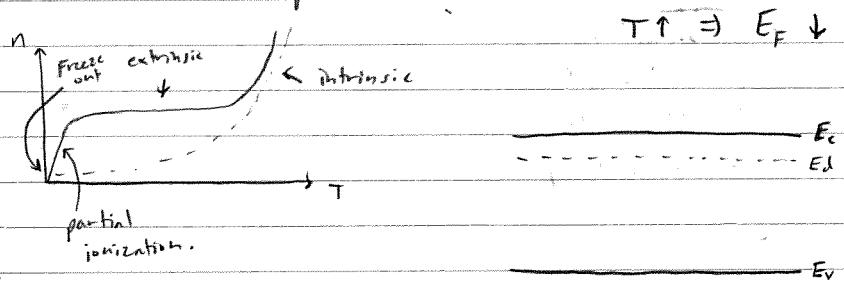
$$n(E) = g(E) \cdot f_F(E) \Rightarrow n = \int_{E_c}^{\infty} n(E) dE$$

- intrinsic carrier concentration: $n_i^2 = N_c p_o = N_c N_v \exp\left(\frac{-E_g}{kT}\right)$

E_g , N_c , and N_v are all also related to temperature. $N_c, N_v \propto (m^* T)^{3/2}$

$$T \uparrow \Rightarrow E_g \downarrow, N_c \uparrow, N_v \uparrow \Rightarrow n_i \uparrow$$

- Carrier Concentration vs. Temperature



Degenerate :- if doping concentration is higher than N_c or N_v

- if $E_F \geq E_c$ or $E_F \leq E_v$

- behaves like a conductor.

★

Pierrre, Ch 2 - Carrier Modeling

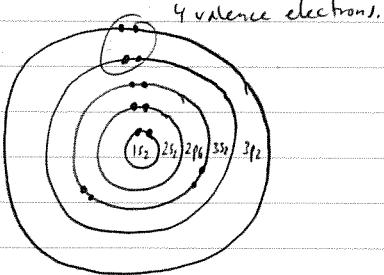
$$2.1 \text{ Quantization: } E_H = -\frac{m_0 g^4}{2(4\pi \epsilon_0 \hbar n)^2} = -\frac{13.6 \text{ eV}}{n^2} \quad n = 1, 2, 3, \dots$$

↑ electron binding energy. $\hbar = \frac{h}{2\pi}$, where h is Planck's const.

$$1 \text{ eV} = 1.6 \cdot 10^{-19} \text{ J} \quad h = 6.62607 \cdot 10^{-34} \text{ J} \cdot \text{s} \quad \epsilon_0 = 8.85 \cdot 10^{-12} \text{ F/cm}$$

2.2 Semiconductor Models:

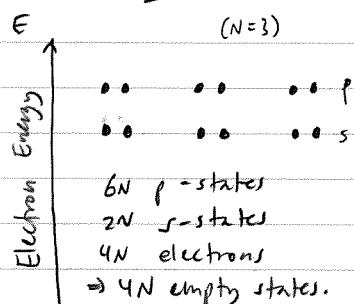
Si:



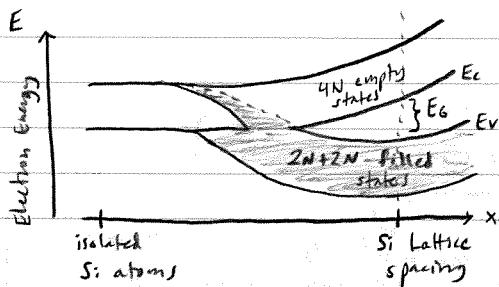
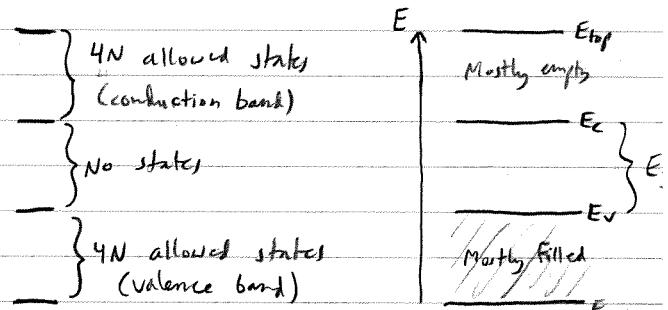
Bonding model \rightarrow spatial
Energy band model \rightarrow energy

figure 2.5:

N isolated atoms



Crystalline Si, N-atoms.



(at 300K)

Band Gap - Insulator $\sim 10\text{eV}$

$\text{SiO}_2 \approx 8\text{eV}$ Diamond $\approx 5\text{eV}$

Semiconductor $\sim 1\text{eV}$

$\text{GaAs} \approx 1.42\text{eV}$ $\text{Si} \approx 1.12\text{eV}$ $\text{Ge} \approx 0.66\text{eV}$

Metal $\sim 0\text{eV}$

2.3 Carrier Properties

$$\text{Charge : } q = 1.6 \cdot 10^{-19} \text{ C}$$

$$\text{Effective mass : } F = -qE = m_n^* \frac{dV}{dt}$$

Carrier Concentration:

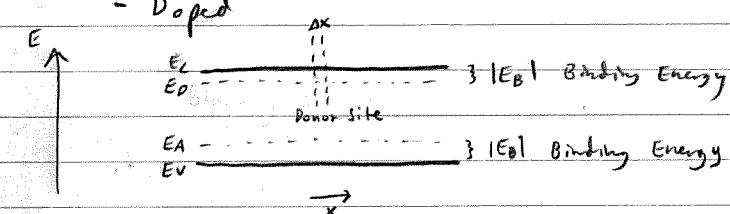
- Intrinsic $n = p = n_i$

at 300K: $\text{GaAs} \quad n_i = 2 \cdot 10^{16} / \text{cm}^3$

$\text{Si} \quad n_i = 1 \cdot 10^{10} / \text{cm}^3$

$\text{Ge} \quad n_i = 2 \cdot 10^{13} / \text{cm}^3$

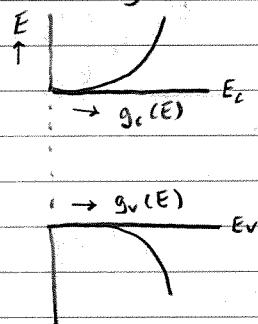
- Doped



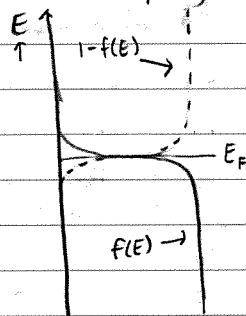
2.4 State and Carrier Distributions.

Figure 2.16

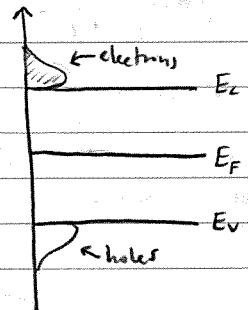
Density of States



Occupancy Factors



Carrier Distributions



$$g_c(E) = \frac{m_n^* \sqrt{2m_n^*(E-E_c)}}{\pi^2 \hbar^3} \quad E \geq E_c$$

$$f(E) = \frac{1}{1 + e^{(E-E_F)/kT}}$$

what would happen if $m_n^* >$
where must E_i lie?

$$g_v(E) = \frac{m_p^* \sqrt{2m_p^*(E_v-E)}}{\pi^2 \hbar^3} \quad E \leq E_v$$

probability that an available
energy state at E will be
occupied by an electron. ($1-f(E)$ for hole)

A: $n=p$, $g_c(E) > g_v(E)$
 $\Rightarrow E_i$ must lie below midgap

Effective Density of States:

$$N_c = 2 \left[\frac{m_n^* kT}{2\pi\hbar^2} \right]^{3/2}$$

$$N_v = 2 \left[\frac{m_p^* kT}{2\pi\hbar^2} \right]^{3/2}$$

$$n = N_c e^{(E_F - E_c)/kT}$$

$$p = N_v e^{(E_v - E_F)/kT}$$

$$n = n_i e^{(E_F - E_i)/kT}$$

$$p = n_i e^{(E_i - E_F)/kT}$$

$$n_i = \sqrt{N_c N_v} e^{-E_G/2kT}$$

$$np = n_i^2$$

} valid for nondegenerate, equilibrium.

Charge Neutrality:

Assuming Total Ionization

$$p - n + N_D^+ - N_A^- = 0 \Rightarrow$$

$$\boxed{p - n + N_D - N_A = 0}$$

$$n = \frac{N_D - N_A}{2} + \left[\left(\frac{N_D - N_A}{2} \right)^2 + n_i^2 \right]^{1/2}$$

$$p = \frac{n^2}{n} = \frac{N_A - N_D}{2} + \left[\left(\frac{N_A - N_D}{2} \right)^2 + n_i^2 \right]^{1/2}$$

} Assumes nondegenerate and total ionization.

4 cases:

1) intrinsic: $N_A = N_D = 0 \Rightarrow \boxed{n = p = n_i}$

2) Doped: $\Rightarrow N_D - N_A \approx N_D \gg n_i$ or $N_A - N_D \approx N_A \gg n_i$

$$\Rightarrow \boxed{n \approx N_D, p \approx \frac{n_i^2}{N_D}}$$

$$\text{or } \boxed{p \approx N_A, n \approx \frac{n_i^2}{N_A}}$$

most common

3) Doped, high T: $n_i \gg |N_D - N_A| \Rightarrow \boxed{n \approx p \approx n_i}$

4) Compensated semiconductor: $N_D \approx N_A \neq 0 \Rightarrow$ must use full equations.

Position of Fermi Level in intrinsic semiconductor:

$$E_F = \frac{E_c + E_v}{2} + \frac{3}{4} kT \ln \left(\frac{m_p^*}{m_n^*} \right)$$

$$E_F - E_i = kT \ln \left(\frac{N_D}{n_i} \right) , \quad N_D \gg N_A, n_i \quad n\text{-type}$$

$$E_i - E_F = kT \ln \left(\frac{N_A}{n_i} \right) , \quad N_A \gg N_D, n_i \quad p\text{-type.}$$

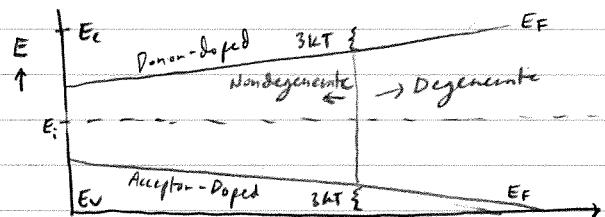


Figure 2.21

N_A or N_D

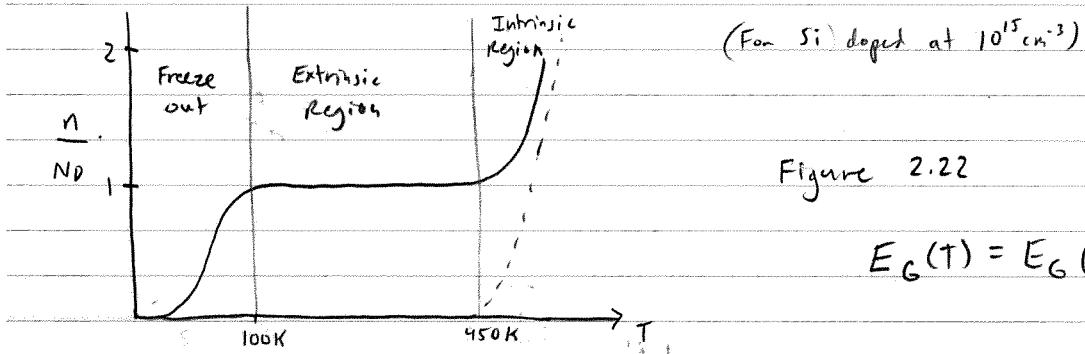
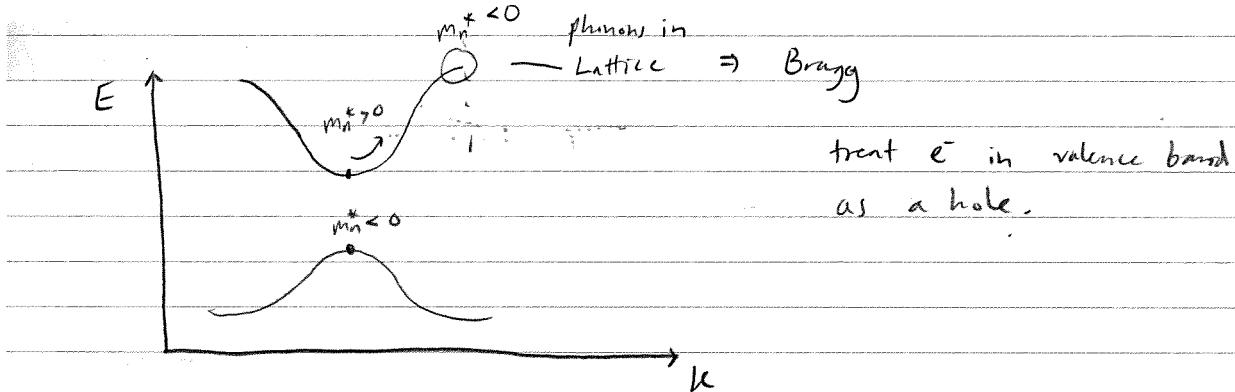


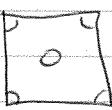
Figure 2.22

$$E_G(T) = E_G(0) - \frac{\alpha T^2}{(T+\beta)}$$

Effective Mass

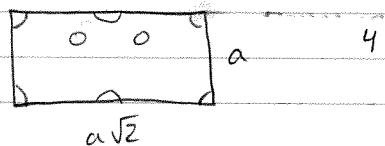
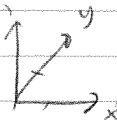


1.5. a)



b) 2

c)



$$\mu = \frac{g\tau}{m^*}$$

mean free time

$$f = m^* a = g E = m^* a \frac{d\nu}{dt}$$

$$\Rightarrow g E = m^* \frac{d\mu E}{dt} \Rightarrow g E = m^* \mu \frac{dE}{dt}$$

$$V = a \cdot \tau$$

$$f = m^* a = g E$$

$$\Rightarrow V = \frac{g E}{m^* \tau}$$

$$\mu = \frac{V}{E}$$

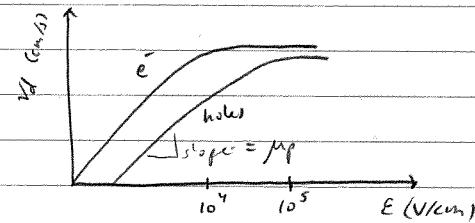
$$\mu = \frac{g\tau}{m^*}$$

Ch. 3 Carrier Action

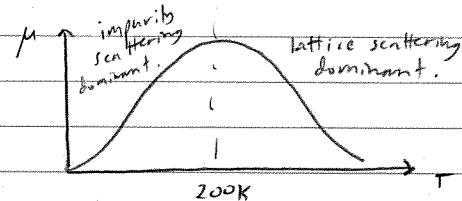
10/12/

Drift Current: $J_{driftn} = n \mu_n E_g$ $J_{driftp} = p \mu_p E_g$

$$V_{drift} = \mu E \quad \text{for } E < 10^5 \text{ V/cm}$$



$$\mu = \frac{e\tau}{m^*}$$



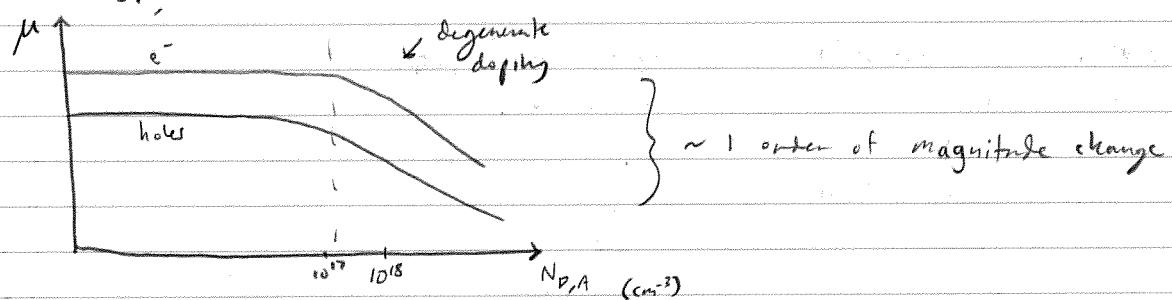
$$\text{Low } T: \mu_i \propto \frac{T^{3/2}}{N_i}$$

$$\text{High } T: \mu_i \propto T^{-3/2}$$

Shallow Impurities: require $\sim kT$ to ionize \Rightarrow most ionize

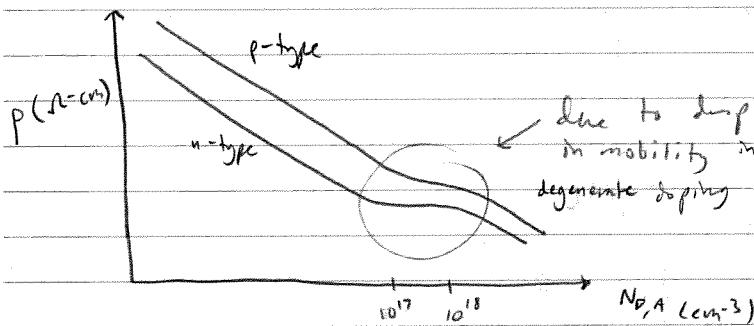
Deep Impurities: require energies larger than $\sim 5kT$ to ionize \Rightarrow only a fraction ionize.
These impurities can be effective recombination centers and are called traps.

$T = 300K$

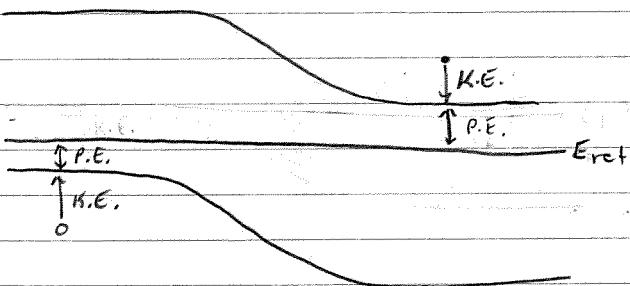


Resistivity:

$$\rho = \frac{1}{\mu_n n g + \mu_p p g}$$



Band Bending:



$$\frac{\partial \epsilon}{\partial x} = \frac{\rho}{\epsilon_0 \epsilon_r}$$

$$\epsilon = -\frac{\partial V}{\partial x} = \frac{1}{q} \frac{\partial E_c}{\partial x} = \frac{1}{q} \frac{\partial E_v}{\partial x} = \frac{1}{q}$$

$$V = -\frac{1}{q} (E_c - E_{ref})$$

Diffusion: $J_{\text{diff},n} = D_n g \frac{dn}{dx}$ $J_{\text{diff},p} = -D_p g \frac{dp}{dx}$

$$J_{\text{total}} = Eg(\mu_n n + \mu_p p) + g(D_n \frac{dn}{dx} - D_p \frac{dp}{dx})$$

drift diffusion.

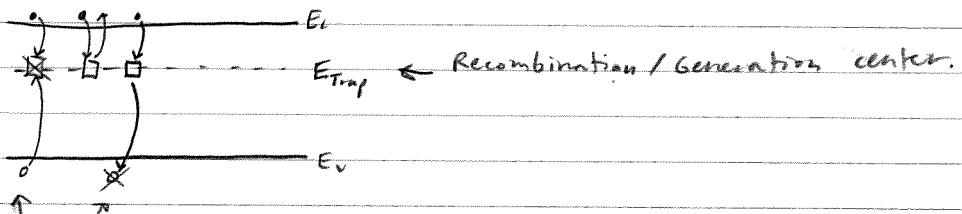
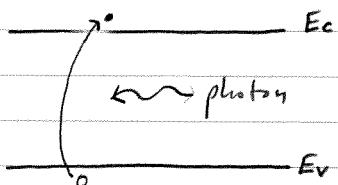
Einstein Relationship: $\frac{D_n}{\mu_n} = \frac{kT}{g}$ $\frac{D_p}{\mu_p} = \frac{kT}{g}$

$$D_p = \mu_p \frac{kT}{q} \quad \mu_p \propto \begin{cases} T^{3/2}, & T < 200K \\ T^{-1/2}, & T > 200K \end{cases}$$

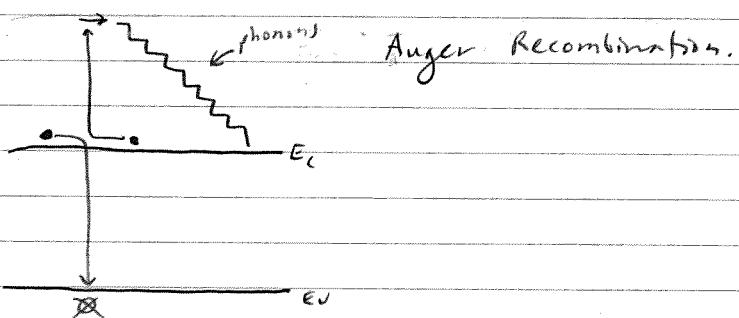
$$\Rightarrow D_p \propto \begin{cases} T^{3/2}, & T < 200K \\ T^{-1/2}, & T > 200K \end{cases}$$

\Rightarrow at room temp (200K), $D_p \propto T^{-1/2}$ \Rightarrow as you increase T, diffusion rate (D_p) goes down.

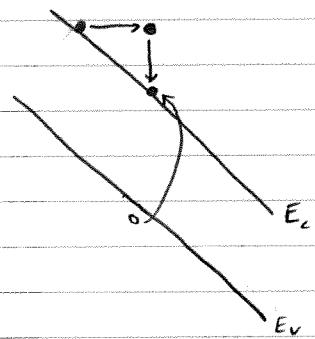
Recombination - Generation



these two are
the same thing.



Impact Ionization



start with one e^- in conduction band. End with 2 e^- in conduction band and one hole in valence band. Highly energetic e^- breaks a bond in one of the atoms.

Minority Carrier Diffusion Equations.

$$\frac{\partial \Delta n_p}{\partial t} = D_N \frac{\partial^2 \Delta n_p}{\partial x^2} - \frac{\Delta n_p}{\tau_n} + G_L + \underbrace{\mu \left(\frac{n \partial E}{\partial x} + E \frac{\partial n}{\partial x} \right)}_{\text{due to applied external field.}}$$

Quali - Fermi Level: When you are not in equilibrium (e.g. light shining, or voltage applied).

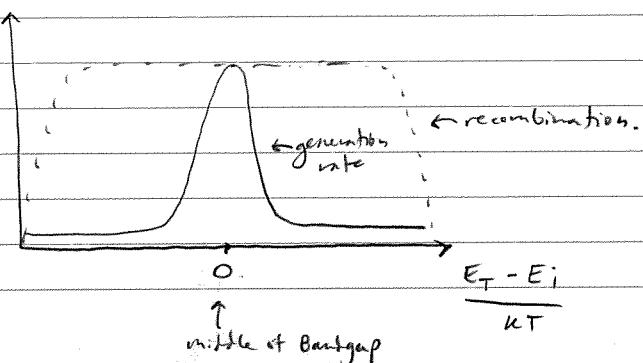
$$\Rightarrow n \neq p \Rightarrow F_p \neq F_N$$

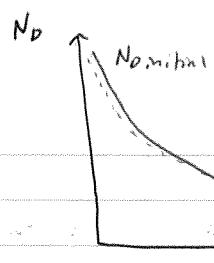
$$F_N = E_i + kT \ln \left(\frac{n}{n_i} \right) \quad J_N = \mu_n n \nabla F_N$$

$$F_p = E_i - kT \ln \left(\frac{p}{n_i} \right) \quad J_p = \mu_p p \nabla F_p$$

Shockley - Read - Hall Recombination Rate:

$$\text{Net recombination rate} \quad J = \frac{V_{th} \sigma N_T (pn - n_i^2)}{n + p + 2n_i \cosh[(E_T - E_i)/kT]}$$

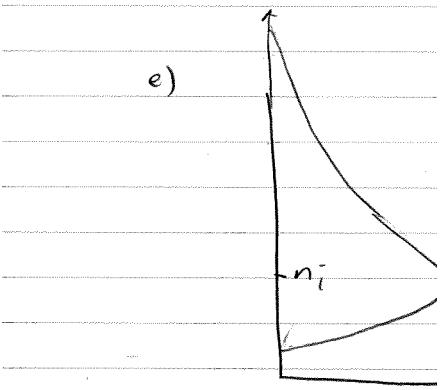
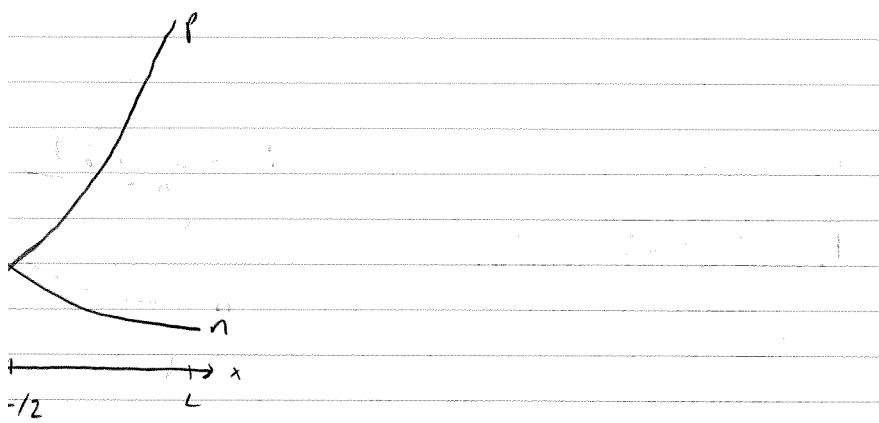
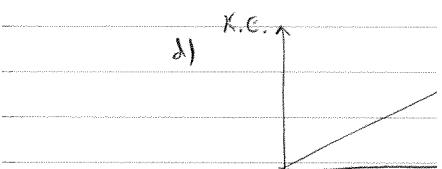
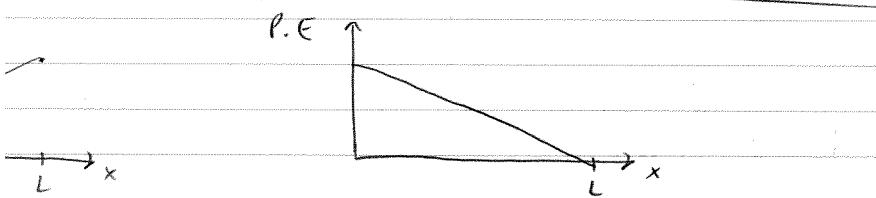
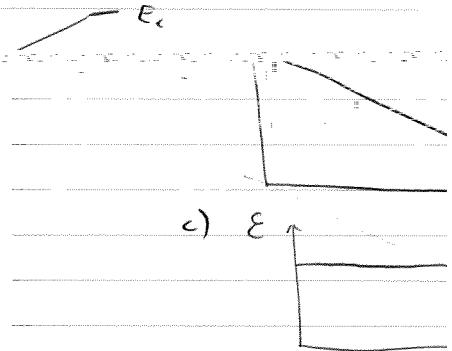
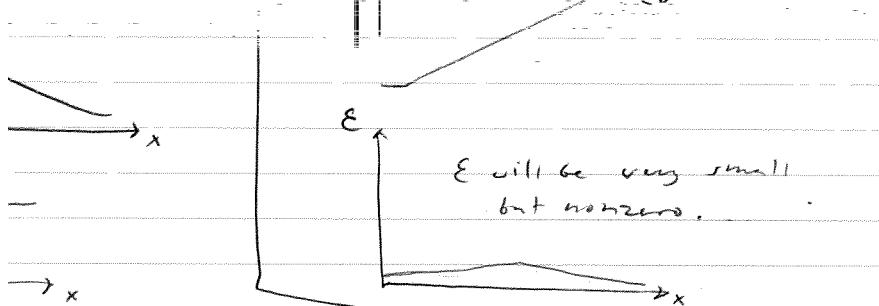




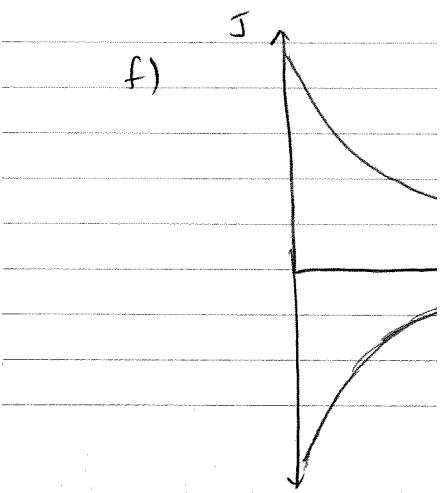
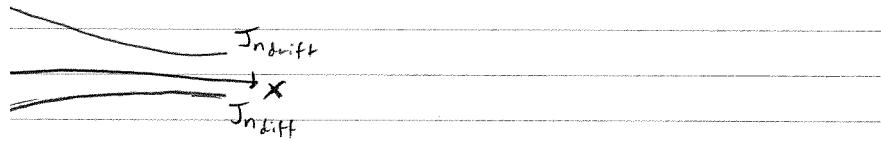
p will be small, but nonzero.

does $N_{\text{sat}} = N_n$? why?

3.12 a) yes EF is flat



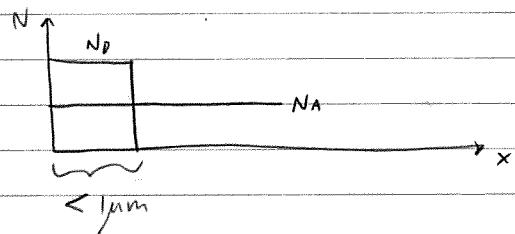
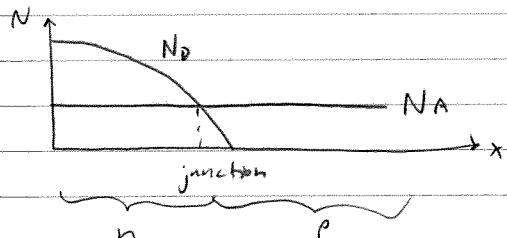
$$J_n = g \left(n \mu \bar{E} + D_n \frac{\partial n}{\partial x} \right) \xrightarrow{\text{equilibrium}} 0$$



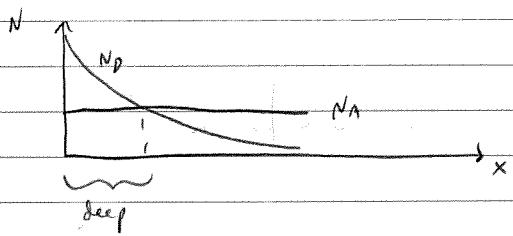
- Ask Harris: does $\rho = 0$ uniformly in 3.12 a? if so, how is there a nonzero E field?
 $E \rightarrow$
 $+ - + - + - ?$

101

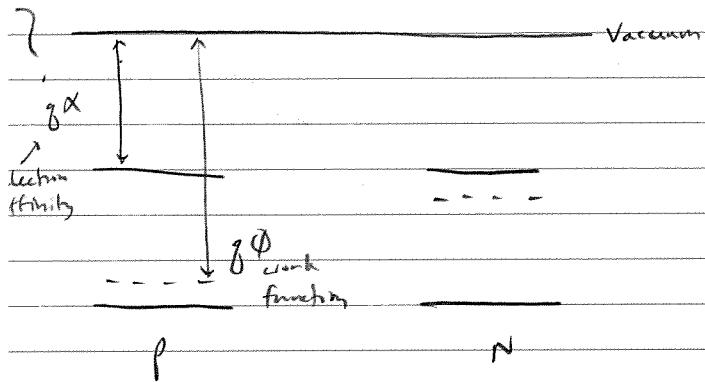
Ch. 5 - pn Junction Electrostatics



step junction - typically shallow doping

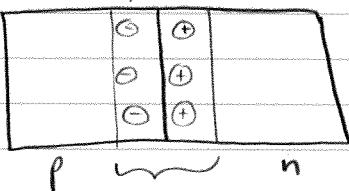


linearly graded junction - typically deep diffusion.



$\leftarrow E_{\text{built-in}}$ (causes band bending)

ionized dopants



$p \sim n$

space
charge
region

(i.e. depletion region)

$$\left. g \cdot V_{bi} \right\}$$

$$E_F$$

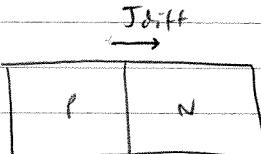
$$E_i$$

$$E_c$$

$$E_v$$

← equilibrium

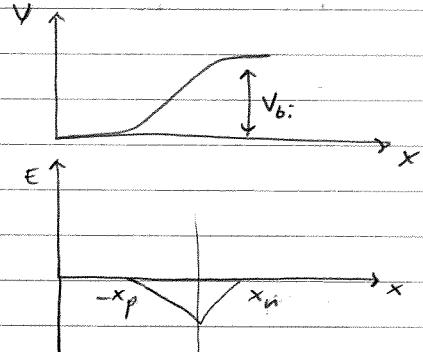
in equilibrium:



$$J_{\text{diff}} + J_{\text{drift}} = 0$$

$$\Rightarrow g \mu_n n E + g D_N \frac{dn}{dx} = 0$$

$$\Rightarrow E = - \frac{D_N}{\mu_n} \frac{\partial n / \partial x}{n} = - \frac{kT}{g} \frac{\partial n / \partial x}{n}$$



$$\Rightarrow V_{bi} = \int_{x_n}^{x_p} E(x) dx = \int_{x_n}^{x_p} - \frac{kT}{g} \frac{\partial n / \partial x}{n} = \frac{kT}{g} \ln \left(\frac{n(x_n)}{n(x_p)} \right)$$

$$\Rightarrow V_{bi} = \frac{kT}{g} \ln \left(\frac{N_A N_D}{n_i^2} \right)$$

← only works for nondegenerate case.

(when degenerate, dopants aren't totally ionized
 \Rightarrow can't use $n(-x_n) = N_D$, $n(-x_p) = \frac{n_i^2}{N_A}$)

another way to find V_{bi} :

$$E_F$$

$$E_F$$

$$\downarrow gV_{bi}$$

$$V_{bi} = \frac{1}{g} (E_{F_1} - E_{F_2})$$

how to find:

E

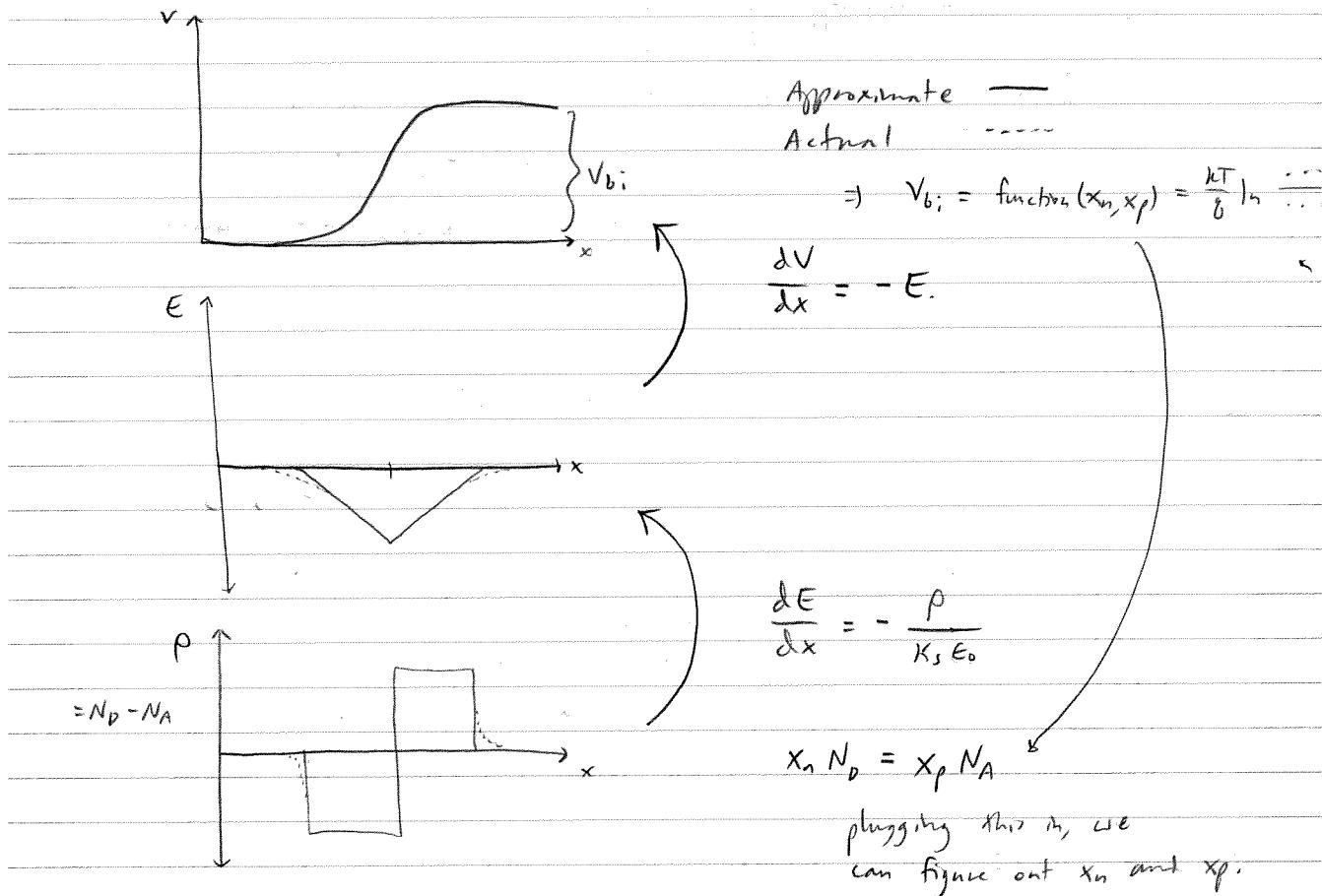
x_n, x_p

Assumptions:

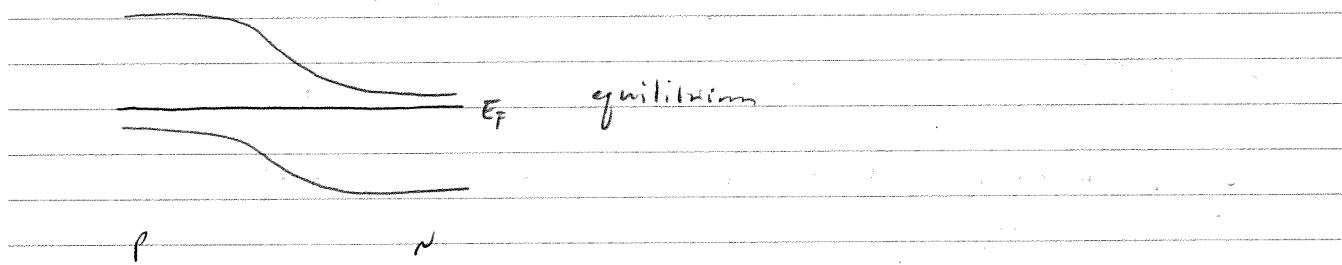
1. $p = 0$ in bulk

2. $n = p = 0$ in depletion region.

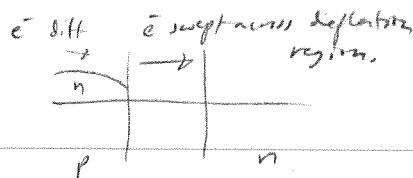
3. step junction.



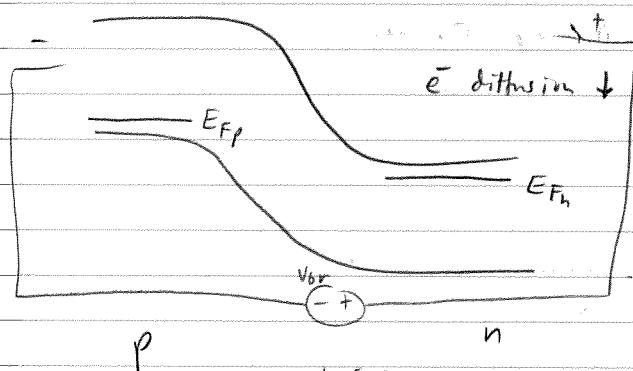
Ch. 6 pn Junction Diode: I-V characteristics



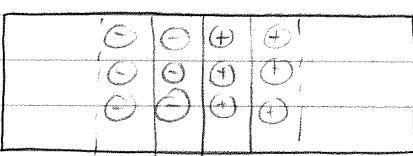
net e^- flow
net current



e^- drift \uparrow



Reverse bias



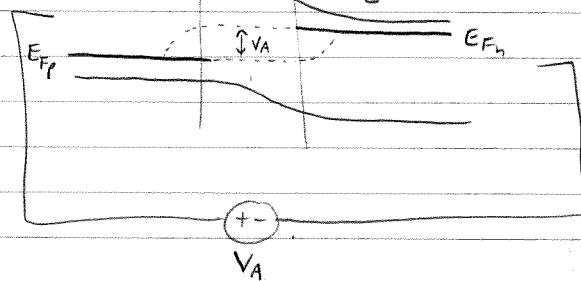
depletion region expands.

drop $V_{bi} + V_{br}$ across depletion region

e^- drift \uparrow

net e^- flow
net current

e^- diffusion \uparrow

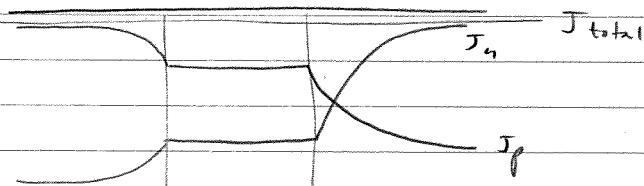


Forward bias

current determined mainly by diffusion of e^- from n to p and diffusion of holes from p to n but at the far left and far right, current is determined by drift of the majority carriers.

Assume that there is no recombination or generation in the depletion region $\Rightarrow J_n$ and J_p are flat in the depletion region.

J_{total}



$J = D \frac{dn}{dx}$ need to know $n(x)$
can find $n(x)$ from the continuity equation.

$$\Rightarrow 0 = D \frac{d^2n}{dx^2} - \frac{\partial P_n}{\partial p} \quad \Delta p = p - p_0$$

need boundary conditions: Law of the junction:

allows you to calculate the concentration of the carriers at the boundary

$$np = n_i^2 \exp \left(\frac{qV_A}{kT} \right)^n$$

can use this to solve $n(x)$, then can find J_n and J_p ($J_n + J_p = J_{total}$)

Reverse bias current:

$$J_{\text{total}} = q \left(\frac{D_p}{L_p} \cdot \frac{n_i^2}{N_D} + \frac{D_n}{L_p} \cdot \frac{n_i^2}{N_A} \right)$$

↑ ↑ ↑
 velocity p-on n-side p-side:
 ↓ ↓ ↓
 n-on p-side

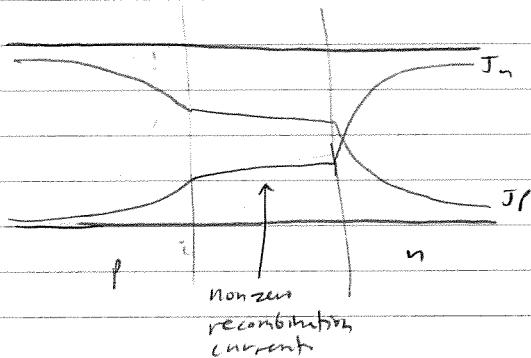
$$J = q \cdot v \cdot n$$

$$n = \frac{L}{\tau} = \frac{\sqrt{D\tau}}{\tau} = \frac{D}{L}$$

$$I_o = qA \left(\frac{D_p}{L_p} \cdot \frac{n_i^2}{N_D} + \frac{D_n}{L_p} \cdot \frac{n_i^2}{N_A} \right)$$

$$I = I_o \cdot \left(e^{\left(\frac{qV_A}{kT} \right)} - 1 \right)$$

Non-idealistic Phenomenon



Non-zero recombination-generation current in depletion region.

e.g. for reverse bias:

almost zero carrier concentration in depletion region.

\Rightarrow almost no recombination. $I_{\text{diff}} \propto n_i^2$

but there is generation

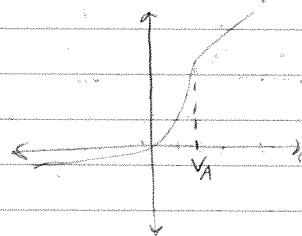
\Rightarrow in reverse bias, generation current is greater than diffusion current in Si

\Rightarrow causes generation currents but not in Ge.

for small forward bias, there are significant carriers in the depletion region \Rightarrow recombination occurs more than generation.
 \Rightarrow we get a nonzero recombination current.

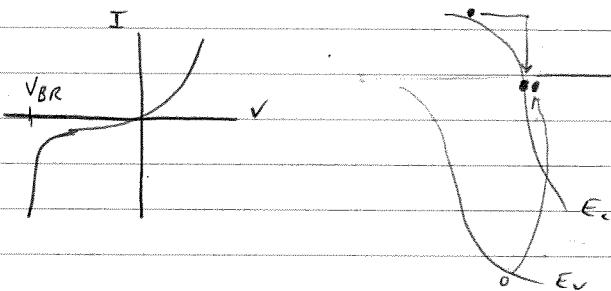
for very small forward bias, this recombination current dominates the diffusion current. But the opposite happens for large forward bias.

for $V_A > V_{bi}$ $I \propto e^{\frac{qV_A}{2kT}}$



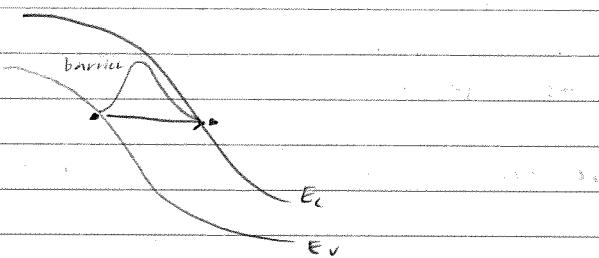
Avalanche Breakdown

(due to impact ionization)



Zener Breakdown

(tunneling)



low V_{BR} \Rightarrow usually zener

high V_{BR} \Rightarrow usually avalanche

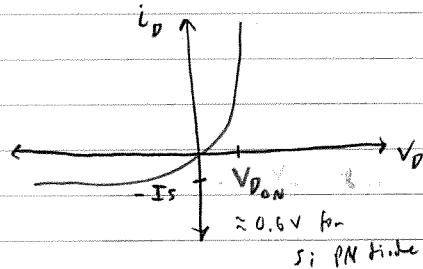
Quals - Circuits (Presenting on Diodes)

10/16/2011

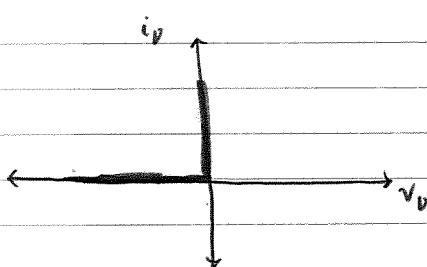


$$i_D = I_S \left(e^{\frac{V_D}{V_T}} - 1 \right)$$

$$I_S = 10^{-12} A, V_T = \frac{kT}{q} \approx 0.025 V \text{ at } 300K,$$

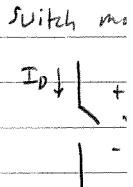


Actual (Nonlinear)

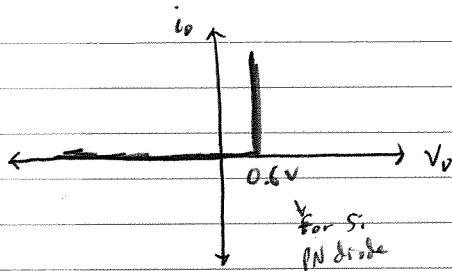


Ideal

used when $V_D \gg 0.6V$



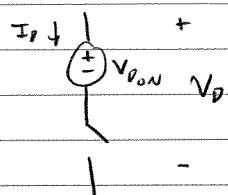
Piecewise Linear



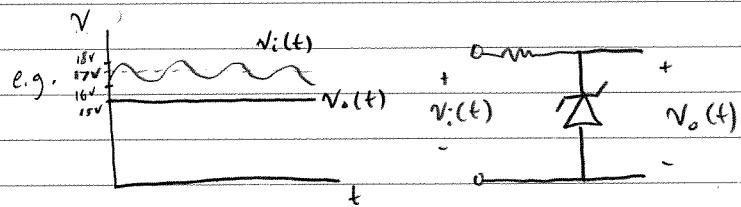
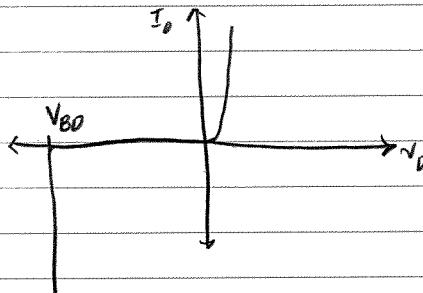
For Si
PN diode

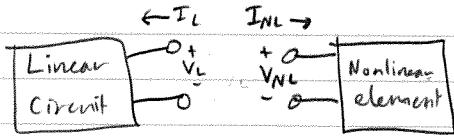


switch model



Zener Diode: Designed to operate in breakdown mode!





$$I_L = f_L(V_L)$$

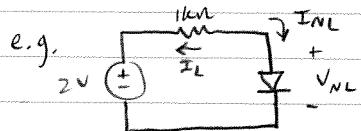
$$I_{NL} = g_{NL}(V_{NL})$$

$$I_{NL} = -I_L$$

$$V_{NL} = V_L$$

$\Rightarrow I_{NL} = -f_L(V_{NL}) \leftarrow$ linear "loadline"

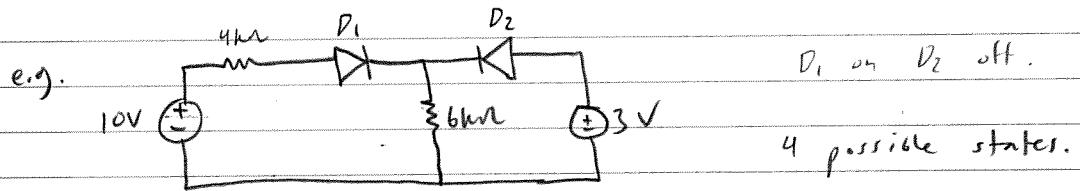
$I_{NL} = g_{NL}(V_{NL}) \Rightarrow$ solve for V_{NL} .



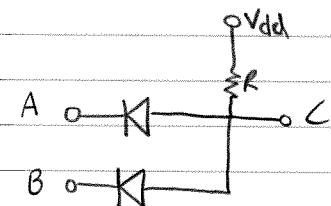
Given $I_L = 10^{-15} A$, find V_{NL}

Diode Circuit Analysis by Assumed Diode States:

- 1) Specify ideal diode model or Piecewise Linear model
- 2) Each diode can be ON or OFF
- 3) Circuit containing n diodes will have 2^n states
- 4) Combo consistent with KVL + KCL will be the solution.



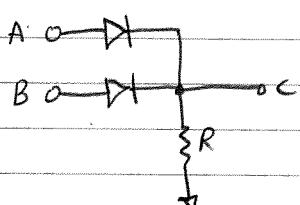
Diode Logic: AND Gate



$$C = A \wedge B \quad A \text{ and } B \text{ vary between } 0V \text{ and } V_{dd}$$

$\Rightarrow C$ varies between $0.6V$ and V_{dd} .

OR Gate:

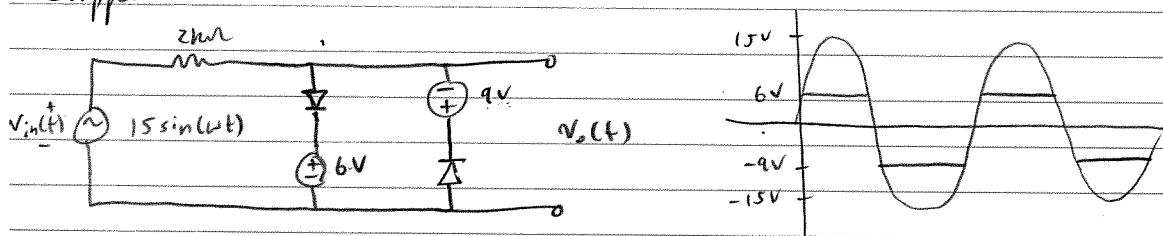


$$C = A \vee B$$

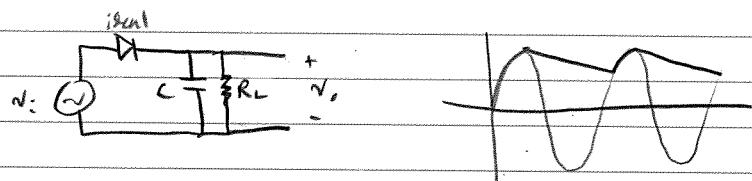
A and B vary between $0V$ and V_{dd}

$\Rightarrow C$ varies between $0V$ and $V_{dd} - 0.6V$

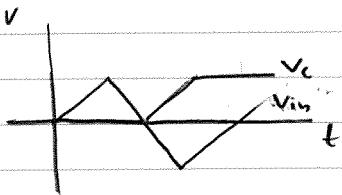
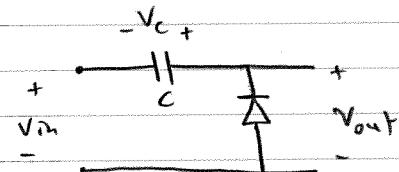
Clipper Circuit:



Peak Detector (Rectifier)

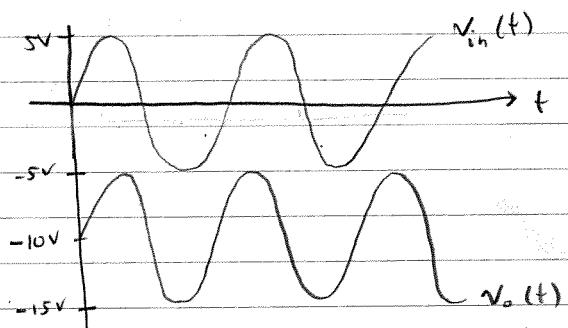
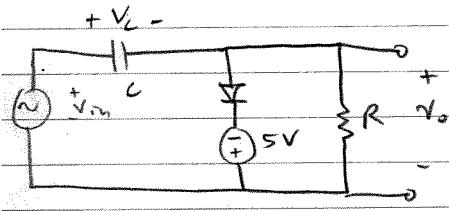


Level shifter

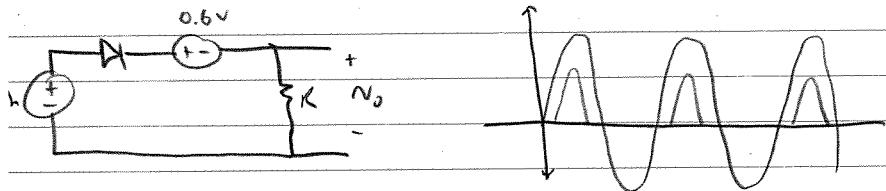


- 1) Diode = open, $V_c = 0$, $V_{out} = V_{in}$
- 2) Diode = short, $V_c = -V_{in}$, $V_{out} = 0$
- 3) Diode = open, $V_c = -V_{in}$ (min), $V_{out} = V_{in} + V_c$

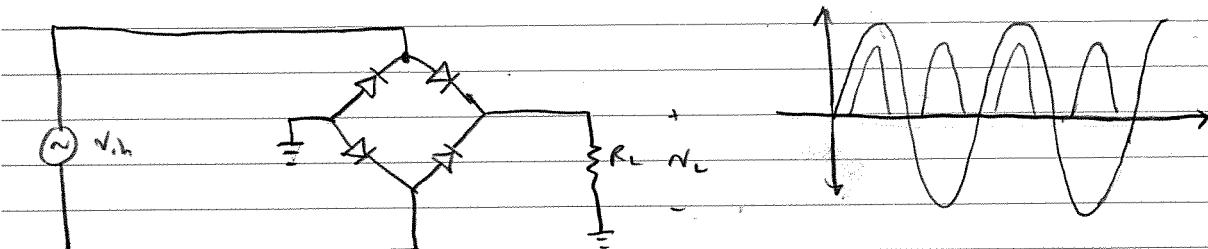
clamp circuit (level shifter)



Half Wave Rectifier



Full Wave Rectifier



Capacitors:

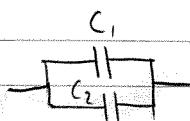
$$\text{Circuit diagram: } \begin{array}{c} \overrightarrow{i_c} \\ \text{---} \\ \text{---} \\ + v_c - \end{array} \quad q = v_c \quad i_c = C \frac{dv_c}{dt} = \frac{dq}{dt} \Rightarrow v_c(t) = v_c(0) + \frac{1}{C} \int i_c(t) dt$$

I-V characteristics.

$$W = \frac{1}{2} CV^2 = \frac{Q^2}{2C} = \frac{1}{2} QV$$

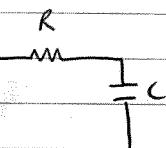
$$\begin{array}{c} + v_1 - + v_2 - \\ \text{---} \\ \text{---} \\ C_1 \quad C_2 \end{array} \dots \quad C_t = \left(\frac{1}{C_1} + \frac{1}{C_2} + \dots \right)^{-1}$$

$$v_1 = \frac{C_2}{C_1 + C_2} v_t$$



$$C_t = C_1 + C_2 + \dots$$

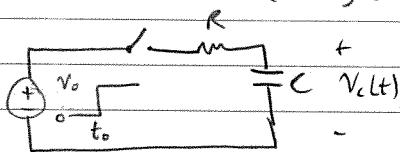
$$q_1 = \frac{C_1}{C_1 + C_2} Q_{\text{total}}$$



$$\tau = RC$$

(after $\sim 5\tau$, we assume cap is
totally charged)

$\text{---} \parallel$ DC - open circuit
high freq. AC - short circuit



$$1) \tau = RC$$

$$2) \text{ initial conditions at } t < 0 \\ v_c(t) = V(0) e^{-t/\tau}$$

$$3) t > 0$$

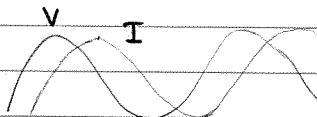
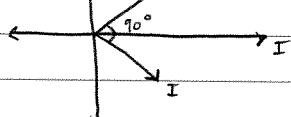
$$v_c(t) = V_c(\infty) (1 - e^{-t/\tau})$$

$$4) V_c(t) = [V_c(0) - V_c(\infty)] e^{-t/\tau} + V_c(\infty)$$

$$\text{Circuit diagram: } \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ C \end{array} \quad Z = \frac{1}{sC} = \frac{1}{j\omega C}$$

V

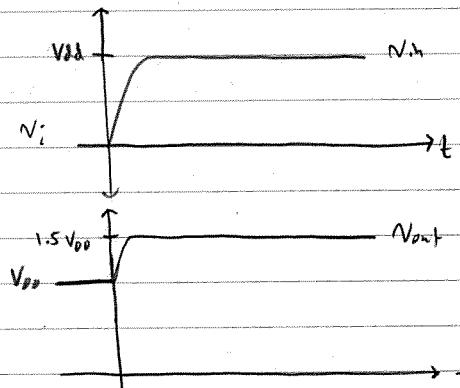
voltage leads current by 90°



Qnub Q

2010 Simon Wong

1)



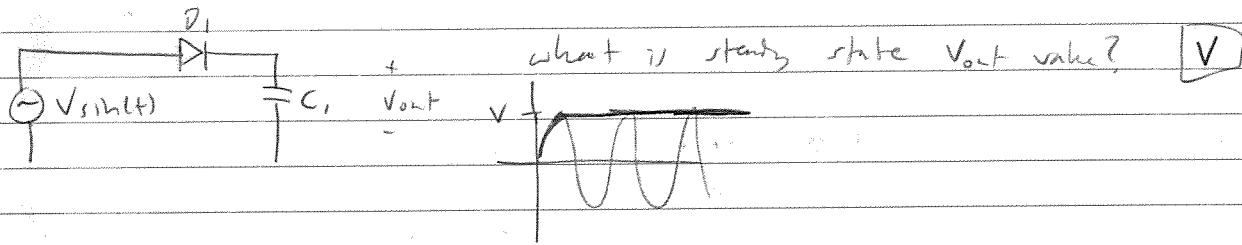
2) initial:

$$\left(\frac{1}{2} C V_{dd}^2\right) \cdot 2 = C V_{dd}^2 \quad \text{Final:} \quad \frac{1}{2} C (1.5 V_{dd})^2 = 1.25 C V_{dd}^2$$

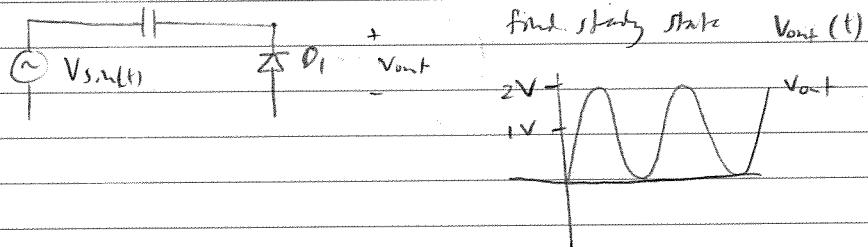
$$3.) V_{out} = \frac{C_{left}}{C_{left} + C_{right}} V_{dd} + V_{dd} \Rightarrow \text{if } C_{left} > C_{right} \quad V_{out_{max}} = 2V$$

4.) Modify the circuit to achieve final $v_{out} = 3V_{dd}$??

2005 Tom Lee

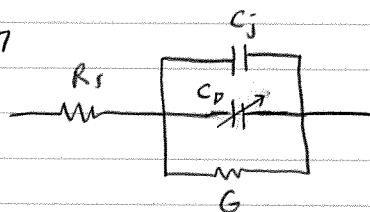


C_1



PN Diodes Small Signal Admittance and Transient Response

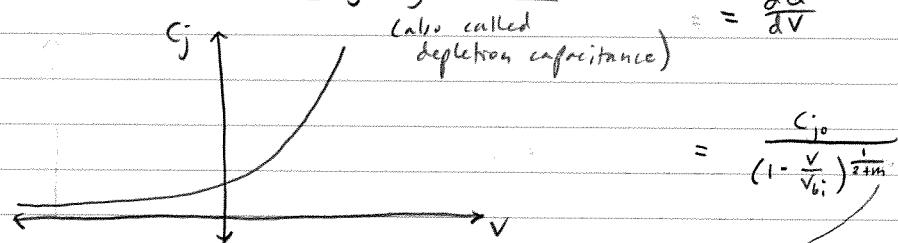
Ch. 7



Model of PN junction

Reverse: $G \approx 0 = \frac{dI}{dV}$ I is constant vs. V
in reverse bias.

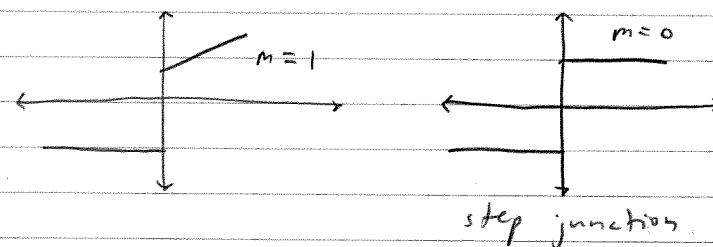
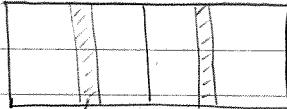
$$C \approx C_j = \frac{k_s e_0 A}{W} \quad \text{depletion width}$$

 C_j caused by movement of majority carriers

$$Q = x_n N_D \cdot A$$

\leftarrow function of applied
Voltage.

$$= \frac{C_{j0}}{\left(1 + \frac{V}{V_{bi}}\right)^{\frac{1}{2+m}}}$$

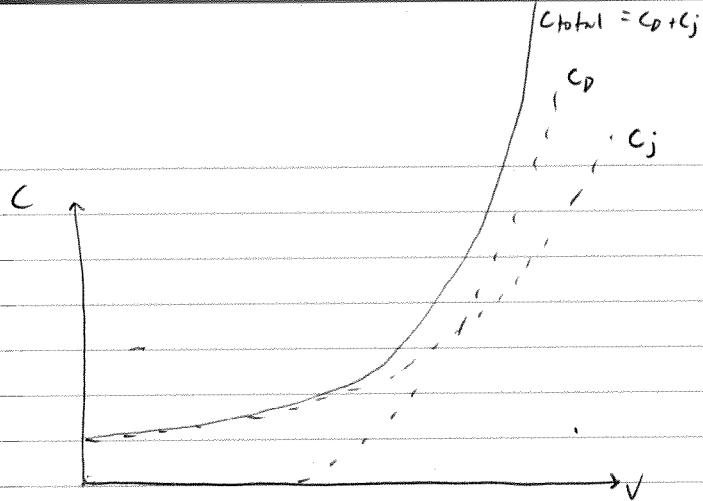
Linearly Graded Junction $\rightarrow N_B = N \cdot X^m$ Forward Bias:

$$C = C_p + C_j$$

7.3.2

diffusion region $\Rightarrow C_p$ diffusion capacitance.

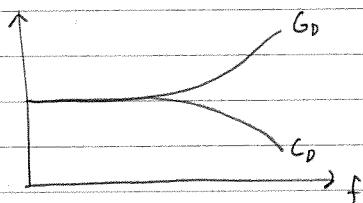
$$\frac{\partial p}{\partial t} = D \frac{\partial^2 p}{\partial x^2} - \frac{\Delta p}{\tau_p} \quad \dots \quad \text{...}$$



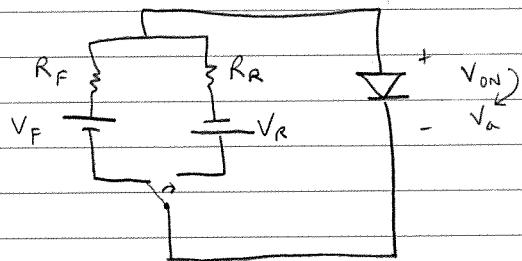
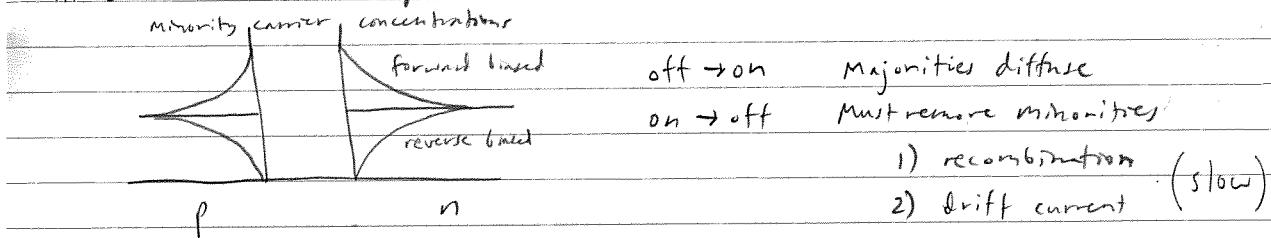
Reverse bias: C_J dominates

Forward bias: C_D dominates.

? pg. 320: Why does $G_D \uparrow$ as $f \uparrow$?

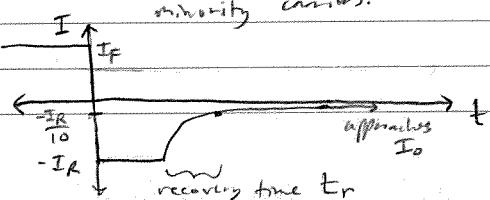
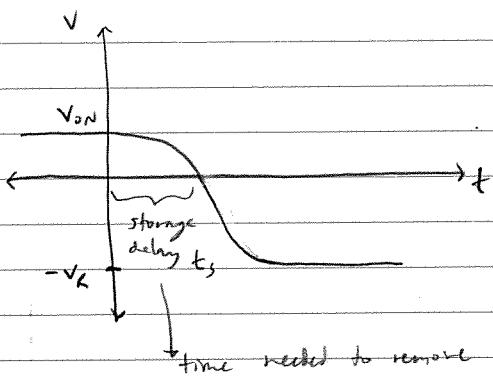


Ch. 8 Transient Response.



$$I_F = \frac{V_F - V_{DN}}{R_F} \approx \frac{V_F}{R_F}$$

$$I_R = \frac{V_R + V_A}{R_R} \approx \frac{V_R}{R_R}$$



represents
 recombination
 process

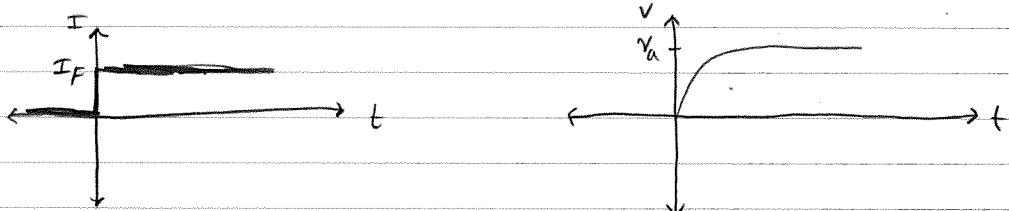
represents the
 number of minorities
 you have to remove.

$$t_s = \tau_p \ln \left(1 + \frac{I_F}{I_R} \right)$$

represents
 drift process

Increasing # of R-G centers $N_G \uparrow$ will decrease t_s ,
 but increase leakage current \Rightarrow there is a tradeoff.

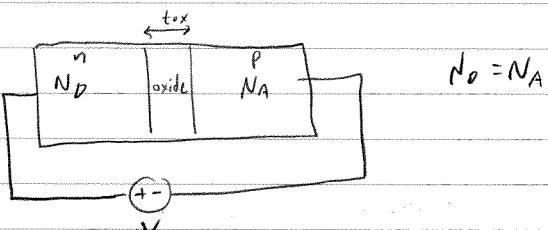
TURN ON: Due to movement of majority carriers (very quick process)



course

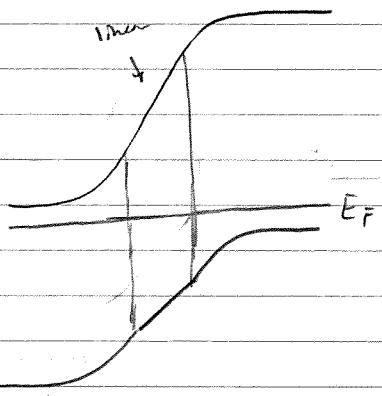
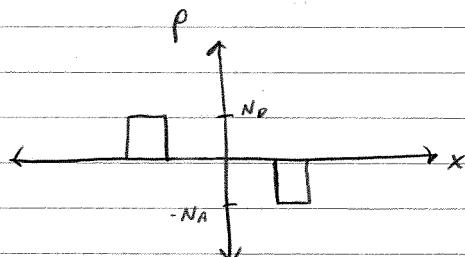
MIT OPEN COURSE QUIZ

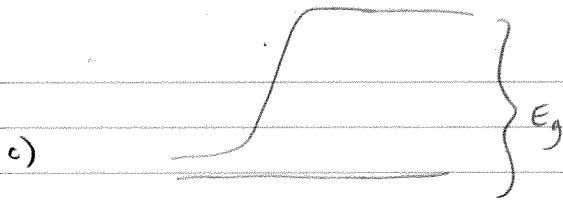
6.7205



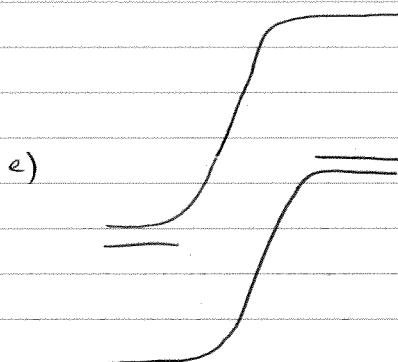
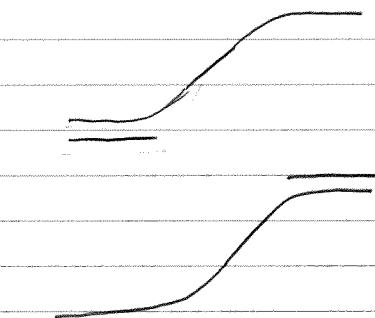
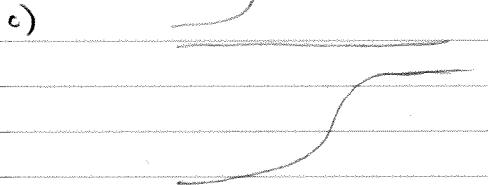
$$N_D = N_A$$

a) sketch $p(x)$ at $V=0$





$V_{bi} = \text{same as for a PN}$



inversion

Question from [REDACTED]

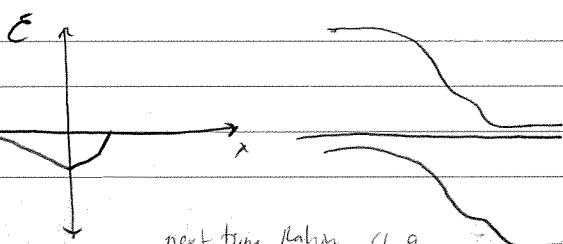
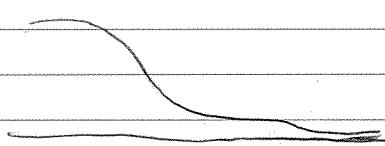
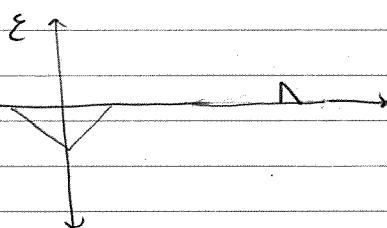
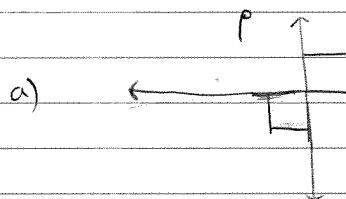
(old EE216 midterm question)

P	$N_A = 10^{15}$	n^-	$N_D = 10^{15}$	n^+	$N_D = 10^{17}$
---	-----------------	-------	-----------------	-------	-----------------

$$\xleftarrow{L}$$

a) draw p , E , V , band diagram.

b) if $L \ll x_n$, repeat part a)



next time plotting Ch. 9.

10/19/11

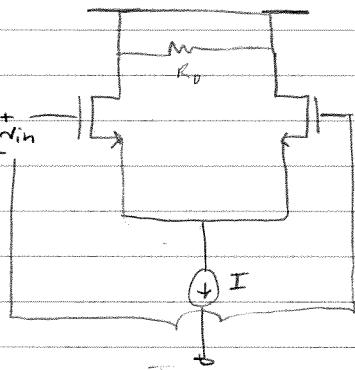


$$V_{gs1} = V_{gd2} \quad V_{gs1} > V_T \Rightarrow V_{gd2} > V_T \Rightarrow M2 \text{ is in Triode}$$

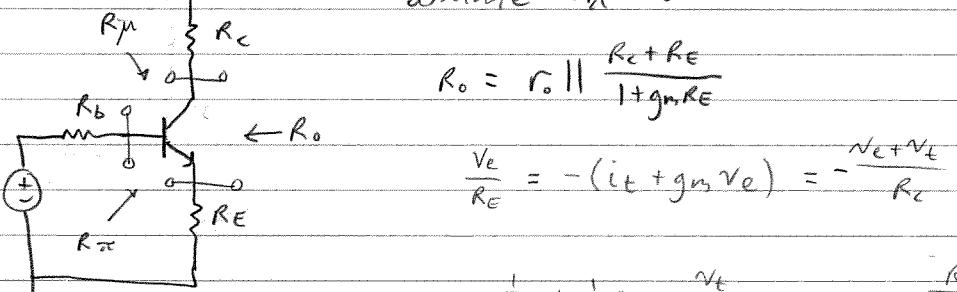
$$M_1: \frac{W}{L} \quad M_2: \frac{1}{K} \frac{W}{L} \quad \frac{1}{2} \mu C_{ox} \frac{W_1}{L} (V_{ov})^2 = V_{ds1tr}$$

$$V_{ds1tr} = (\sqrt{K+1} - 1) V_{ov} \quad V_b = \sqrt{K+1} V_{ov} + V_t$$

Diff pair



assume $r_\pi = \infty$



$$R_o = r_o \parallel \frac{R_c + R_E}{1 + g_m R_E}$$

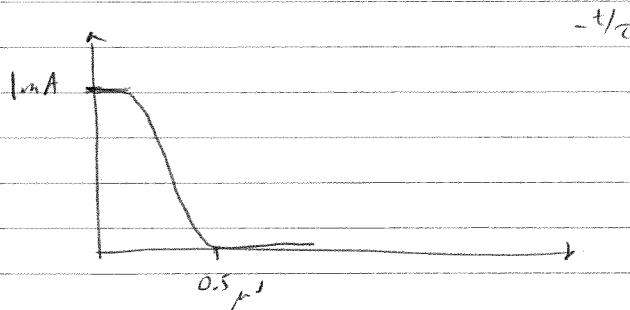
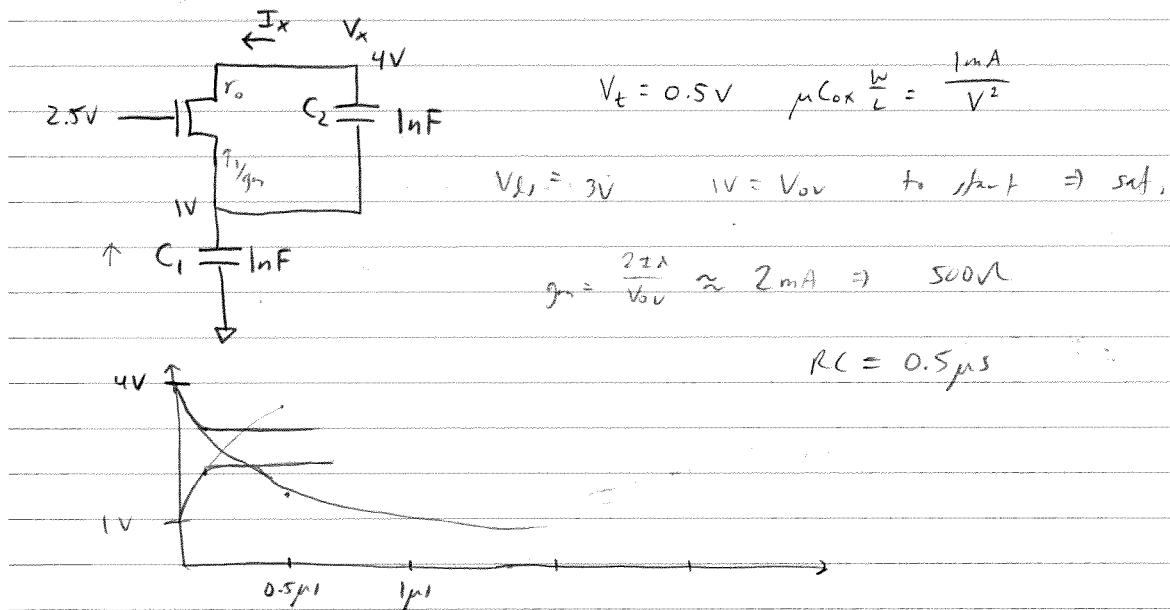
$$\frac{V_d}{R_E} = -(i_t + g_m V_e) = -\frac{V_t + V_e}{R_E}$$

$$V_e \left(\frac{1}{R_E} + \frac{1}{R_C} \right) = -\frac{V_t}{R_C} \Rightarrow V_e = -\frac{R_E}{R_C + R_E} V_t$$

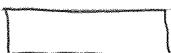
$$\Rightarrow -\frac{V_t}{R_E + R_C} = -i_t - g_m \left(\frac{R_E}{R_E + R_C} V_t \right) \Rightarrow V_t \left(\frac{1 + g_m R_E}{R_E + R_C} \right) = i_t$$

$$\Rightarrow \frac{V_t}{i_t} = \frac{R_C + R_E}{1 + g_m R_E} \Rightarrow R_o = r_o \parallel \frac{R_C + R_E}{1 + g_m R_E}$$

Murmann 2009

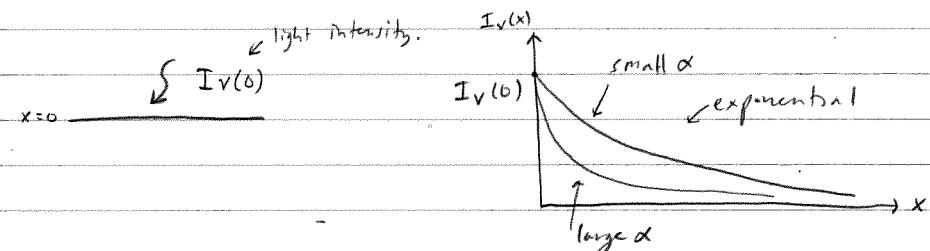


↓↓↓ E photon



if $E_{\text{photon}} > E_g$, photon absorbed.
otherwise, transparent \Rightarrow not absorbed.

$$E = \frac{hc}{\lambda} = \frac{1.24}{\lambda} \Rightarrow \lambda \leq \frac{1.24}{E_g} \text{ will be absorbed.}$$



Assuming a uniform absorption coefficient (α independent of x)

α is a function of λ .

$$I_v(x) = I_v(0) e^{-\alpha x}$$

$$g' = \frac{\alpha I_v(0)}{E_{\text{photon}}} = \frac{\alpha I_v(0)}{h\nu} \leftarrow \frac{\text{number}}{\text{cm}^3 \cdot \text{s}}$$

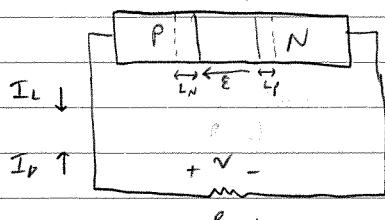
↑ generation rate.

reflection at surface

$$\text{in general: } G_v = \alpha(\lambda) I_v(\lambda) [1 - R(\lambda)] e^{-\alpha(\lambda)x} \leftarrow \begin{array}{l} \text{in general, these factors} \\ \text{are all functions of} \\ \text{wavelength.} \end{array}$$

Solar cell:

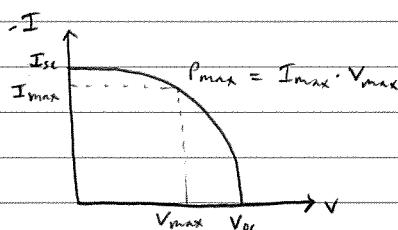
↓↓↓



$$I_{\text{net}} = I_L - I_p = I_L - I_s [e^{\frac{V}{(kT/q)}} - 1]$$

$$I_{sc} = I_L$$

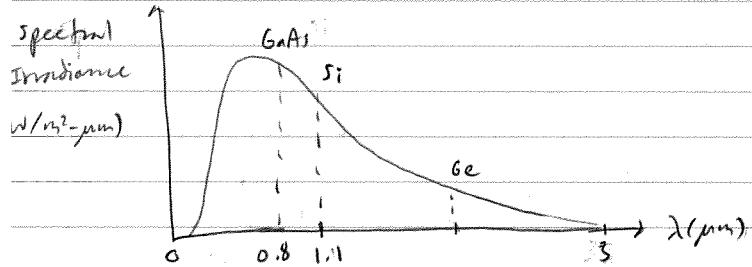
$$V_{oc} = \frac{kT}{q} \ln \left(1 + \frac{I_L}{I_s} \right)$$



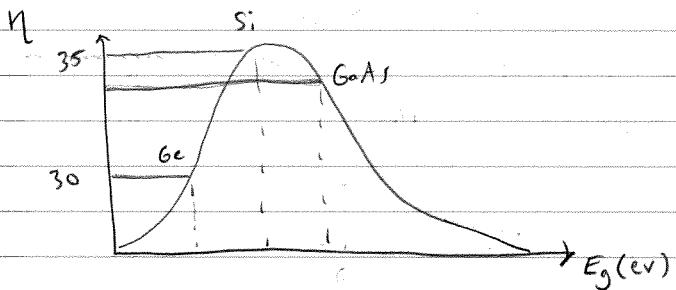
$$P = VI = V(I_L - I_s [e^{\frac{V}{(kT/\theta)}} - 1]) \quad \text{to find } P_{\max}, \text{ set } \frac{\partial P}{\partial V} = 0$$

$$\Rightarrow \left(1 + \frac{V_m}{(kT/\theta)}\right) e^{\frac{V_m}{(kT/\theta)}} = 1 + \frac{I_L}{I_s}$$

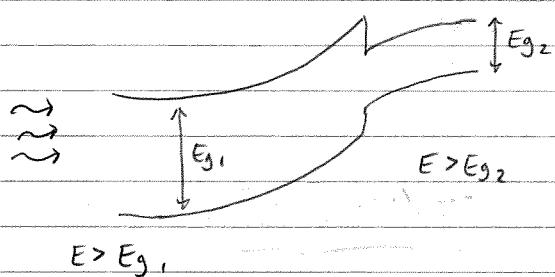
$$\text{Conversion efficiency: } \eta = \frac{P_{\max}}{P_{in}} \cdot 100$$



$$\text{fill factor: } ff = \frac{I_m V_m}{I_{sc} V_{oc}}$$

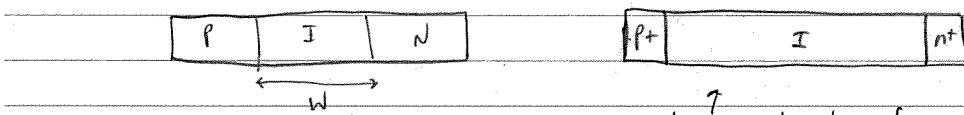


Heterojunction: can absorb a wider spectrum of light.



Amorphous Si: Δt + $\eta \downarrow$ but it's cheap.

PIN: Wider depletion region \Rightarrow more photocurrent:

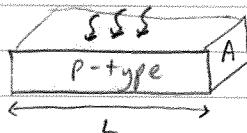


typical structure for
a solar cell.

$$\gamma_p = \frac{1}{c_p N_T} \quad \gamma_n = \frac{1}{c_n N_T} \quad \text{where } c_p \text{ and } c_n \text{ are capture coefficients.}$$

Photodetectors: Reverse Biased.

Photoconductors:



$$\sigma_0 = \mu_p g p_0 + \mu_n g n_0$$

$$\text{When you shine light} \Rightarrow \sigma_t = (\mu_p g(p_0 + \Delta p) + \mu_n g(n_0 + \Delta n)) \quad \Delta p = \Delta n$$

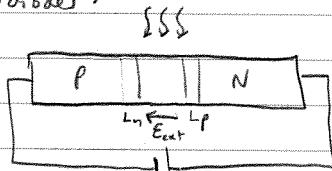
$$\Delta \sigma = g(\Delta n)(\mu_n + \mu_p) \quad J = \sigma_t E = (\sigma_0 + \Delta \sigma)E$$

$$I_L = J_L A = \Delta \sigma A \cdot E = g G_L \tau_p (\mu_p + \mu_n) A \cdot E \quad t_n = \frac{L}{\mu_n E}$$

$$I_L = g G_L \left(\frac{\tau_p}{t_n} \right) \left(1 + \frac{\mu_p}{\mu_n} \right) A L \quad \tau_p = \frac{I_L}{g G_L A \cdot L} \quad \begin{matrix} \text{electron transient time} \\ \text{time for electron to} \\ \text{flow across photoconductor.} \end{matrix}$$

↑
photoconductor gain

photodiodes:



$$I_L = g \int G_L dx = g G_L (L_p + L_n + W)$$

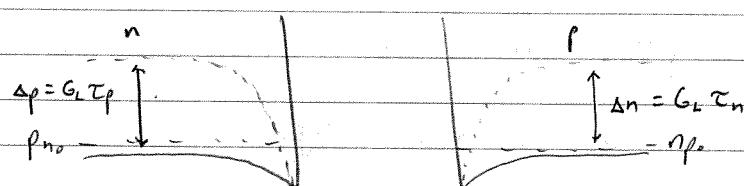
$$I_p = g \frac{D_p p_{no}}{L_p} + g G_L L_p$$

reverse biased

$$I_n = g \frac{D_n n_{po}}{L_n} + g G_L L_n$$

$$I_w = g G_L W$$

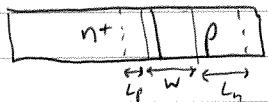
$$I_{\text{total}} = I_p + I_n + I_w = \underbrace{\left(g \frac{D_p p_{no}}{L_p} + g \frac{D_n n_{po}}{L_n} \right)}_{I_s} + \underbrace{g G_L (L_n + L_p + W)}_{I_L}$$



which is better?



$$L_n > L_p$$



$$L_n = D_n \tau_n$$

↓

$$\frac{kT}{q} / \mu_n \tau_n$$

$$\frac{kT}{q} \mu_p \tau_p$$

$$\mu_n > \mu_p$$

$$\mu_n > \mu_p \Rightarrow L_n > L_p$$

⇒ easier to collect
 e^- than holes.

+ bottom structure
will generate more
electrons that can
diffuse into the depletion currents

$$Y = G + j\omega C$$

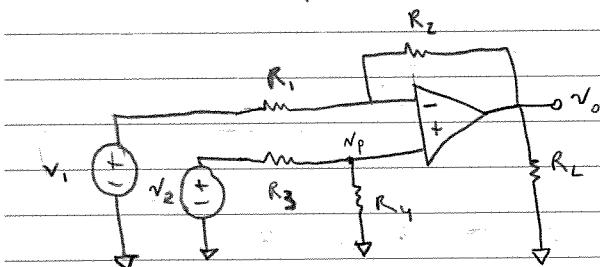
as $f \uparrow$ $C \downarrow$ because the minority
carriers cannot move fast enough to follow
the voltage.

Harris says G is independent of frequency, which does not
agree with Pierret.

Quants - Circuits Opamps

10/22/11

Difference Amplifier : express V_o in terms of V_1 and V_2



$$V_p = \frac{R_4}{R_3 + R_4} V_2$$

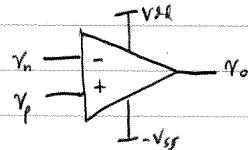
$$\frac{V_1 - V_p}{R_1} = \frac{V_p - V_o}{R_2} \Rightarrow \frac{V_o}{R_2} = \frac{V_1 - V_p}{R_1} - \frac{V_p}{R_2}$$

$$\Rightarrow V_o = V_p + \frac{R_2}{R_1} (V_p - V_1) = \left(\frac{R_1 + R_2}{R_1} \right) V_p - \frac{R_2}{R_1} V_1$$

$$= \left(\frac{R_1 + R_2}{R_1} \right) \left(\frac{R_4}{R_3 + R_4} \right) V_2 - \frac{R_2}{R_1} V_1 \quad \text{When } R_1 = R_3 \text{ and } R_2 = R_4,$$

$$\text{this simplifies to } V_{out} = \frac{R_2}{R_1} (V_2 - V_1)$$

OpAmp - Very high gain differential amp



$$\Rightarrow V_o = A \cdot (V_p - V_n)$$

$$V_{I_{CM}} = \frac{V_n + V_p}{2}$$

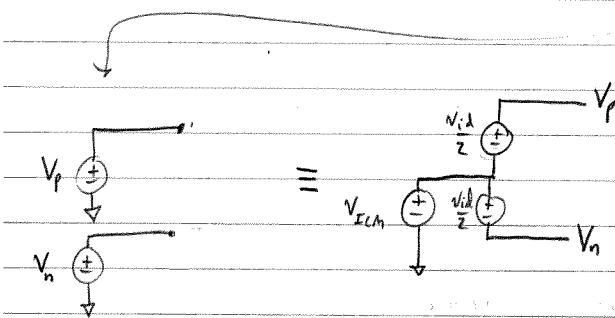
$$V_p = V_{I_{CM}} + \frac{V_{i,d}}{2}$$

$$V_{i,d} = V_p - V_n$$

$$V_n = V_{I_{CM}} - \frac{V_{i,d}}{2}$$

Ideal Opamp

- ① Infinite input impedance (zero input current)
- ② Zero output impedance
- ③ Infinite open loop gain ($A = \infty$) \leftarrow differential gain
- ④ Zero Common Mode gain
- ⑤ Infinite bandwidth

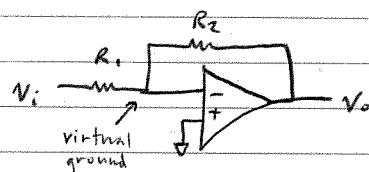


DC - direct coupled.

Opamps are DC amplifiers. They can amplify DC inputs.

Usually we use opamps in negative feedback configurations.

Inverting Amp:

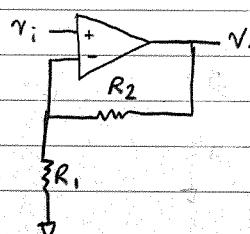


$$\frac{V_o}{V_i} = -\frac{R_2}{R_1}$$

$$\text{if } A < \infty, \frac{V_o}{V_i} = -\frac{R_2}{R_1} \left(\frac{1}{1 + (1 + \frac{R_2}{R_1})/A} \right)$$

~~Input Impedance = R_1~~ \Rightarrow need to make R_1 and R_2 high if you want high input impedance.

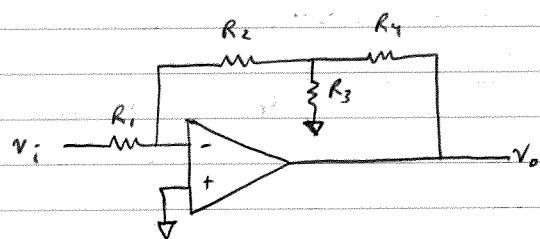
Non-inverting Amp:



$$\frac{V_o}{V_i} = \frac{R_1 + R_2}{R_1} = 1 + \frac{R_2}{R_1}$$

Very high input impedance.

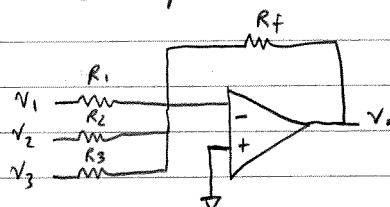
High Gain, High Input Impedance:



$$\frac{V_o}{V_i} = -\left(\frac{R_2}{R_1} + \frac{R_4}{R_1} + \frac{R_4 R_2}{R_1 R_3}\right)$$

Can increase $\frac{V_o}{V_i}$ by tuning
R₃ and R₄.

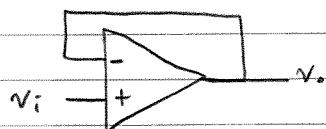
Summing Amp:



$$V_o = -\left(\frac{R_f}{R_1} V_1 + \frac{R_f}{R_2} V_2 + \frac{R_f}{R_3} V_3\right)$$

Can derive this from superposition.

Voltage Buffer/Follower:

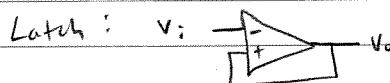


$$\frac{V_o}{V_i} = 1$$

Very high input impedance

Very low output impedance

Can sometimes have faster response.



Common Mode Rejection Ratio: CMRR

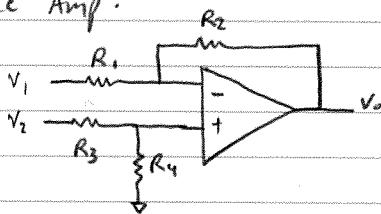
$$V_o = A_d V_{id} + A_{cm} V_{icm}$$

↓ ↓
A_d → ∞ A_{cm} → 0 for an opamp

$CMRR = 20 \log \frac{|A_d|}{|A_{cm}|}$

Want this to be as high as possible.

Difference Amp:



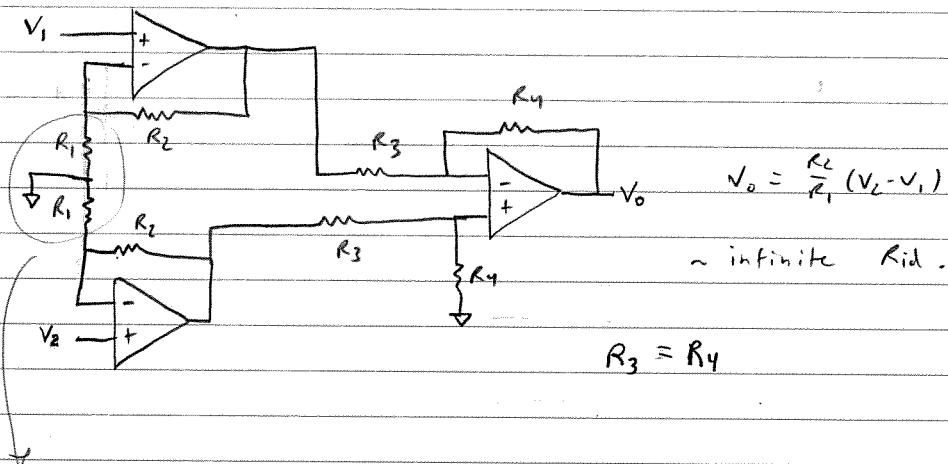
$$V_0 = \left(\frac{R_1 + R_2}{R_1} \right) \left(\frac{R_4}{R_3 + R_4} \right) V_2 - \frac{R_2}{R_1} V_1$$

$$\text{when } \frac{R_2}{R_1} = \frac{R_4}{R_3}, \quad V_0 = \frac{R_2}{R_1} (V_2 - V_1)$$

typically, $R_1 = R_3, R_2 = R_4$

$$R_{id} = R_1 + R_3$$

Same problem as inverting amp: if you want high input resistance + high gain,
must make R_2 and R_1 (and R_4 and R_3) very large.

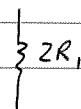


$$V_0 = \frac{R_2}{R_1} (V_2 - V_1)$$

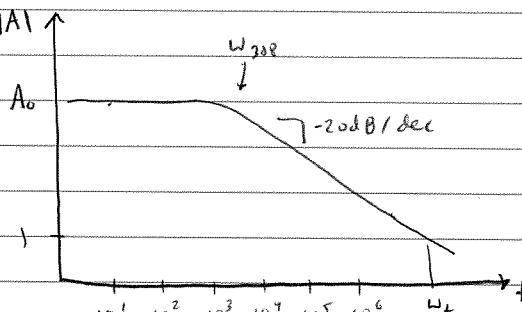
\sim infinite R_{id} .

$$R_3 \approx R_4$$

to increase CMRR (reduce A_{cm})
replace this with:



frequency response: $|A| \uparrow$



$$A(s) = \frac{A_0}{1 + \frac{s}{w_{3dB}}}$$

$$A(j\omega) = \frac{A_0}{1 + j \left(\frac{\omega}{w_{3dB}} \right)}$$

unity gain frequency

$$\text{At high frequency: } |A(j\omega)| \approx A_0 \left(\frac{\omega_b}{\omega}\right) = \frac{W_t}{\omega}$$

Gain Bandwidth Product: $W_t = A_0 W_{3dB}$

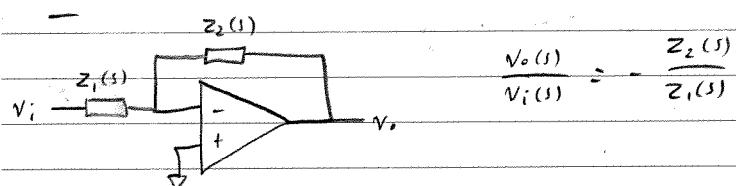
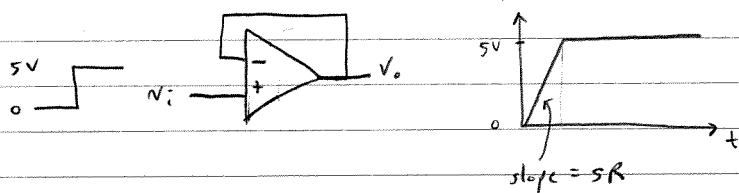
Nonidealities:

Output Voltage Saturation: Voltage limited by $\sim V_{dd} - 1V$, $\sim -V_{ss} + 1V$

Output Current Limit: e.g. $20mA$ = max current output the opamp can supply.

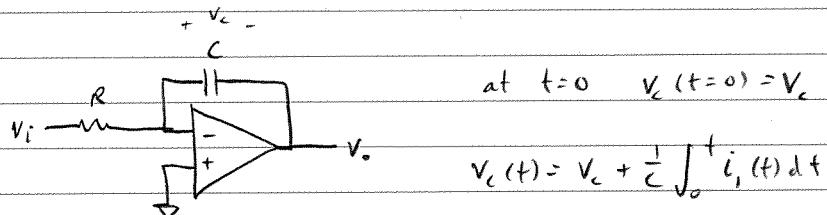
Stair Rate: How fast the output of the opamp can change.

$$SR = \left. \frac{dV_o}{dt} \right|_{max} \quad \text{units are typically } \text{V}/\mu\text{s in datasheets.}$$



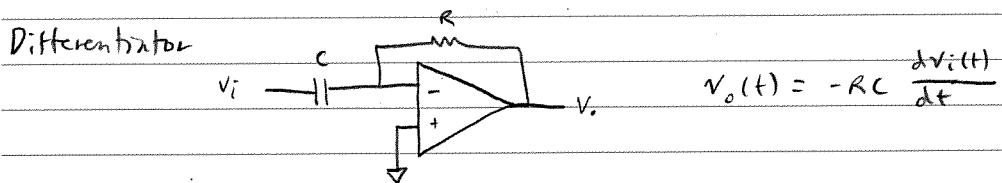
$$\frac{V_o(s)}{V_i(s)} = -\frac{Z_2(s)}{Z_1(s)}$$

Integrator: $V_o(t) = -\frac{1}{RC} \int_{t=0}^t i_i(t) dt + V_c$



$$V_c(t) = V_c + \frac{1}{C} \int_{t=0}^t i_i(t) dt$$

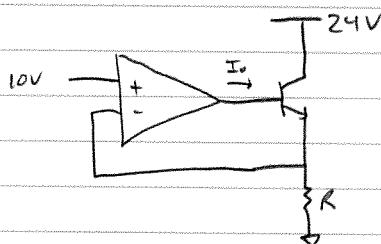
$$V_o = -V_c(t) \Rightarrow V_o(t) = \left(-\frac{1}{RC} \int_{t=0}^t i_i(t) dt \right) - V_c$$



$$V_o(t) = -RC \frac{dV_i(t)}{dt}$$

MIT question: 6.071, 2006 Final

1.



$$I_o = 5 \text{ mA} \quad \beta = 100 \quad \text{calculate } R$$

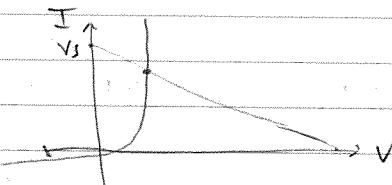
$$I_c = \beta \cdot I_o = 500 \text{ mA} \Rightarrow 500 \text{ mA} \cdot R = 10 \text{ V}$$

$$\Rightarrow R = 20 \Omega$$

2. A. 0.6 V

B. 0.6 V

$$C. i_L R_2 = 0.6 \Rightarrow i_L = \frac{0.6 \text{ V}}{R_2}$$



$$\Rightarrow V_L = i_L \cdot R_L \Rightarrow \frac{V_t}{R_2} \cdot R_L \Rightarrow V_L = \frac{R_L}{R_2} \cdot V_t$$

\Rightarrow the purpose of this circuit is to measure the IV characteristic of a diode

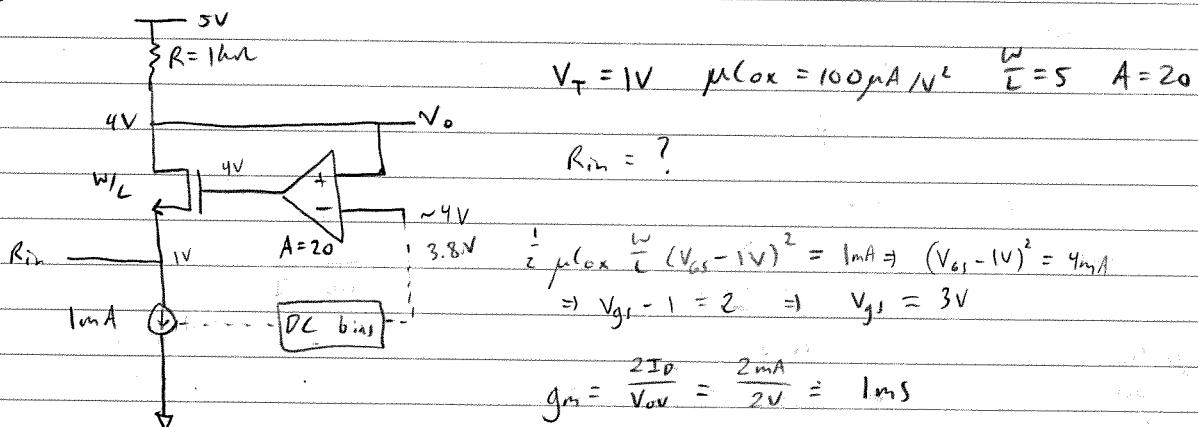
$$D. i_b = I_s (e^{\frac{V_b}{V_T}} - 1) \approx \frac{V_b - 0.6}{R_i}$$

\Rightarrow the purpose of this circuit is to be a constant current source.

$\Rightarrow V_b$ decreases by V_T

$$\Rightarrow V_L \text{ decreases by } \frac{R_L}{R_2} \cdot V_T \Rightarrow i_L \text{ decreases by } \frac{V_T}{R_2}$$

Woolley 2000 qual 1 Q



Using Blackman's Impedance formula:

$$\Rightarrow R_{in} = \frac{1}{gm} = 1 \text{ k}\Omega$$

$$Z_{(A=0)} = \frac{1}{gm} \quad R_{(\text{port shorted})} = -\left(\frac{gm R_V + A}{V_T}\right) = \frac{gm R_A}{V_T}$$

$$R_{(\text{port open})} = 0$$

$$\Rightarrow Z = R_{in} = \frac{1}{gm} \left(\frac{1 + gm R_A}{1 + 0} \right) = \frac{1}{gm} (1 + gm R_A) = \frac{1}{gm} + RA = 1 \text{ k}\Omega + 20 \text{ k}\Omega \Rightarrow R_{in} = 2 \text{ k}\Omega$$

Quals - Devices

- LEDs & Lasers

higher T \Rightarrow shorter mean free path.

\Rightarrow need higher E and higher V_{br}

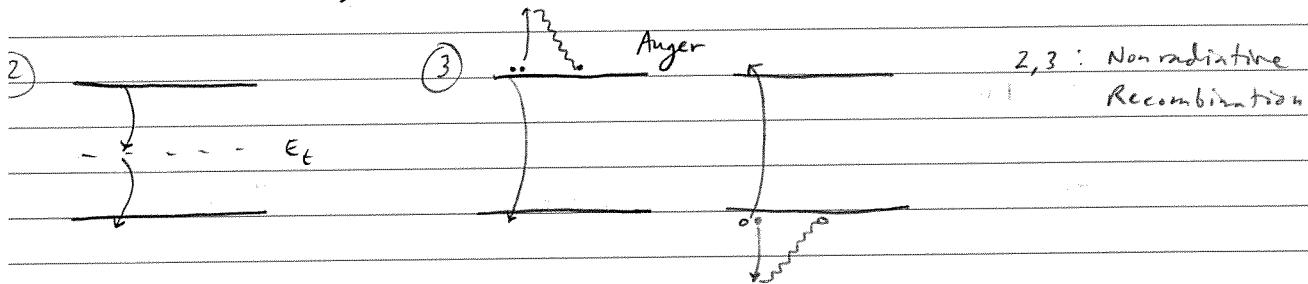
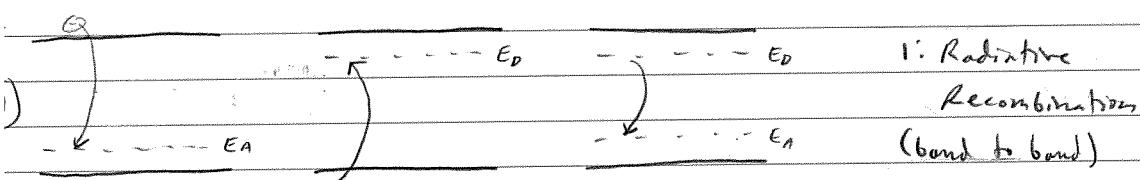
Avalanche breakdown: $T \uparrow V_{br} \uparrow$

Zener breakdown: $T \uparrow V_{br} \downarrow$ (V_{br} constant according to Harris)

- LEDs:

range of $E_{photon} \sim E_g$ to $E_g + kT$

$$\lambda = \frac{1.24}{E} \quad (E \text{ in eV}, \lambda \text{ in } \mu\text{m})$$



$$I(\nu) \propto \nu^2 (h\nu - E_g)^2 e^{-\frac{(h\nu - E_g)}{kT}} \quad \leftarrow \text{spontaneous emission rate.}$$

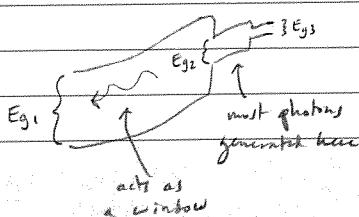
$$\text{Quantum Efficiency: } \eta = \frac{\text{radiative recombination rate}}{\text{total recombination rate (all processes)}} = \frac{R_r}{R_{nr} + R_r} = \frac{T_{nr}}{T_{nr} + T_r}$$

$$R_r \propto \frac{1}{T_r} \quad R_r \propto n_p \quad R_r = B n_p \quad \begin{matrix} \text{proportionality} \\ \text{constant} \end{matrix}$$

$$R_r^{\text{direct}} \sim 10^6 \cdot R_r^{\text{indirect}}$$

- Want photons to be generated close to the surface so that it is less likely to be re-absorbed.

- Or you can use a heterojunction:



Laser/

LED materials: $\text{Al}_x \text{Ga}_{1-x} \text{As}$

$0 < x < 0.45 \rightarrow$ direct bandgap

$x > 0.45 \rightarrow$ indirect bandgap

$30\mu\text{m} < \lambda < 40\mu\text{m}$ for typical LEDs.

injection efficiency

Internal Quantum Efficiency: $\eta_i = \varphi \cdot \eta \leftarrow$ radiative efficiency

$$\varphi = \frac{J_n}{J_n + J_p + J_R}$$

nonradiative recombination current

$$J_R = \frac{g n_i W}{2\pi} e^{\left(\frac{qV}{2kT} - 1\right)}$$

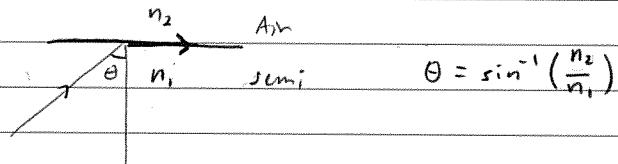
for n^+ , $J_n \gg J_p, J_R \Rightarrow$ assume $\varphi = 1$

1) Re-absorb, if $h\nu \geq E_g$

2) Reflection \rightarrow fresnel loss

$$\Gamma = \left(\frac{n_1 - n_2}{n_1 + n_2} \right)^2$$

3) Critical angle loss

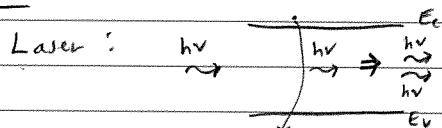


$$\theta = \sin^{-1}\left(\frac{n_2}{n_1}\right)$$

Visible range: $0.4\mu\text{m} < \lambda < 0.7\mu\text{m} \rightarrow 1.7\text{eV} < E_g < 3.1\text{eV}$

GaAs $\rightarrow \lambda = 0.871\mu\text{m}$ (not in visible range).

$\text{GaAs}_x \text{P}_x$ for $x = 0.4$ $E_g = 1.9\text{eV}$



Conditions:

$E_2 > E_1 \Rightarrow$ is thermal equilibrium, $N_2 < N_1$

$$\frac{dI(v)}{dz} \propto \frac{\# \text{ photon emitted}}{\text{cm}^3} - \frac{\# \text{ photon absorbed}}{\text{cm}^3}$$

$$\frac{dI(v)}{dz} = N_2 w_i h\nu - N_1 w_i h\nu \quad \text{where } w_i = \text{induced transition probability.}$$

$$\frac{dI(v)}{dz} = \gamma(v) I(v) \quad \text{where } \gamma(v) \propto N_2 - N_1$$

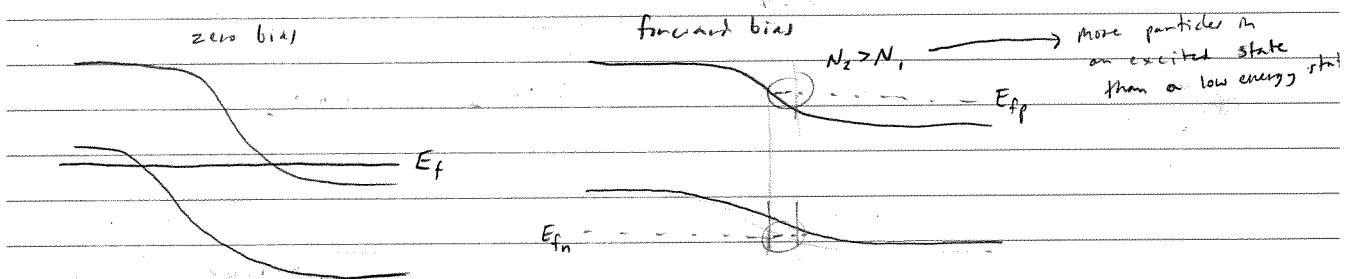
$$I(v) = I(0) e^{\gamma(v)z}$$

Conditions: need amplification and coherent emission.

amplification: $\gamma(v) > 0$ ($\gamma(v) < 0 \rightarrow \text{absorption}$)

$\gamma(v) \propto N_2 - N_1$ if $N_2 > N_1$, we call it population inversion.

this happens when both sides of a pn junction are degenerate.



optical cavity: $L = n \left(\frac{\lambda}{2}\right)$... where $n = 1, 2, 3, \dots$ and L is the length of the cavity dimensions.

Quants - Circuits Alex - Long Channel Model + CS

10/26/11

Subthreshold: $I_D = I_0 e^{(V_{GS}/S V_T)}$ where $V_T = \frac{kT}{q}$ (not threshold voltage) and $S > 1$.

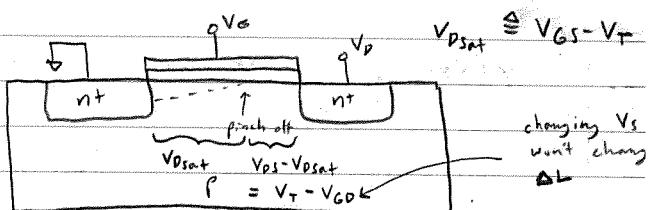
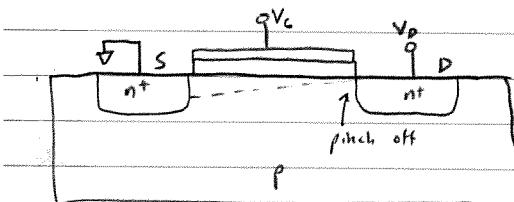
MOS - IV : Triode: $I_D = \mu C_{ox} \frac{W}{L} (V_{GS} - V_T - \frac{V_{DS}}{2}) V_{DS}$ $V_{GD} > V_T$

Saturation: $I_D = \frac{1}{2} \mu C_{ox} \frac{W}{L} (V_{GS} - V_T)^2 (1 + 2V_{DS})$ $V_{GD} < V_T$

CLM! Assume $\frac{\Delta L}{L} = \lambda V_{DS} \Rightarrow \lambda \propto \frac{1}{L}$, $\Delta L \propto V_{DS}$

MOS - resistor: $V_{DS} \ll 2(V_{GS} - V_T) \Rightarrow I_D \approx \mu C_{ox} \frac{W}{L} (V_{GS} - V_T) V_{DS}$

$$\Rightarrow R_{on} = \frac{\partial I_D}{\partial V_{DS}} \approx \frac{1}{\mu C_{ox} \frac{W}{L} (V_{GS} - V_{TH})} \quad R_{on} \text{ controlled by } V_{GS}$$



$$V_{GD} = V_T \Rightarrow$$

$$V_{GD} < V_T \Rightarrow \text{saturation.}$$

Saturation:

Transconductance:

$$g_m = \left. \frac{\partial I_D}{\partial V_{GS}} \right|_{V_{DS} = \text{constant}} = \mu C_{ox} \frac{W}{L} V_{ov} = \sqrt{2 \mu C_{ox} \frac{W}{L} I_D} = \frac{2 I_D}{V_{ov}}$$

$$\text{with CLM: } g_m = \mu C_{ox} \frac{W}{L} V_{ov} (1 + 2V_{DS}) = \sqrt{\frac{2 \mu C_{ox} \frac{W}{L} I_D}{1 + 2V_{DS}}} = \frac{2 I_D}{V_{ov}}$$

$$\text{Output Conductance: } g_{ds} = \left. \frac{\partial I_D}{\partial V_{DS}} \right|_{V_{GS} = \text{constant}} = \frac{\lambda I_D}{1 + 2V_{DS}} \approx \lambda I_D \quad \text{assuming } 2V_{DS} \ll 1$$

$$r_o = \frac{1}{g_{ds}} \approx \frac{1}{\lambda I_D}$$

Second Order Effects:

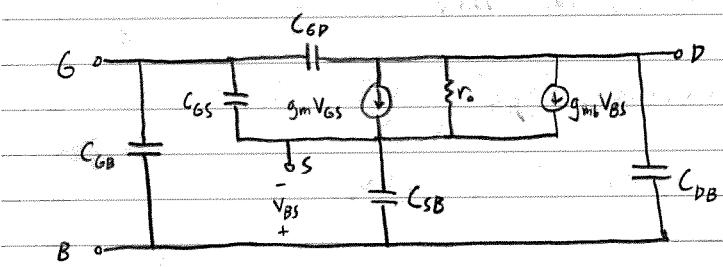
Work function difference between region & substrate.

$$\text{Body Effect: } V_{TH} = V_{TH0} + \gamma (\sqrt{2\Phi_F + V_{SB}} - \sqrt{2\Phi_F}) \quad V_{TH0} = \Phi_{MS} + 2\Phi_F + \frac{Q_e}{C_0}$$

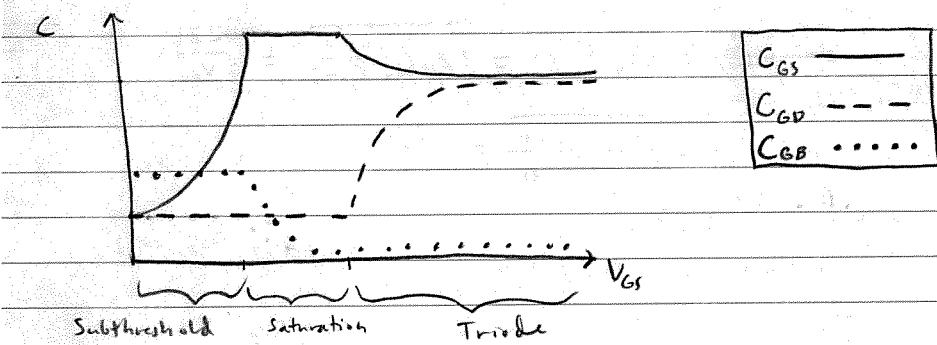
$$\Phi_F = \left(\frac{kT}{q} \right) \ln \left(\frac{N_{sub}}{n_i} \right) \quad \gamma = \sqrt{2qE_s N_{sub}} / C_{ox}$$

$$g_{mb} = \frac{\partial I_D}{\partial V_{BS}} = \mu C_{ox} \frac{W}{L} (V_{GS} - V_T) \left(-\frac{\partial V_r}{\partial V_{BS}} \right) = g_m \frac{\gamma}{2\sqrt{2\Phi_F + V_{SB}}} = \eta g_m.$$

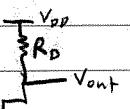
MOS small signal model:



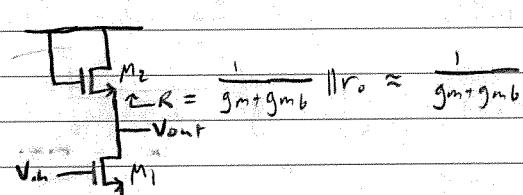
	Subthreshold	Triode	Saturation
C_{GS}	C_{ov}	$\frac{1}{2} WL C_{ox} + C_{ov}$	$\frac{2}{3} WL C_{ox} + C_{ov}$
C_{GD}	C_{ov}	$\frac{1}{2} WL C_{ox} + C_{ov}$	C_{ov}
C_{GB}	$(\frac{1}{C_{GP}} + \frac{1}{WL C_{ox}})^{-1}$	0	0



Common Source:

Resistive Load: 

$$A_v = -g_m (R_D \parallel r_o)$$

Diode connected Load: 

$$R = \frac{1}{g_m + g_m b} \parallel r_o \approx \frac{1}{g_m + g_m b}$$

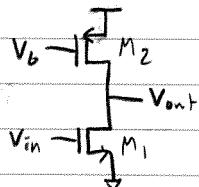
$$\Rightarrow A_v = -g_m \cdot \frac{1}{g_m + g_m b} = -\frac{g_m}{g_m b} \left(\frac{1}{1 + \eta} \right) = \sqrt{\frac{(W/L)_1}{(W/L)_2}} \left(\frac{1}{1 + \eta} \right)$$

$$\approx -\frac{g_m}{g_m b}$$

independent of bias currents + voltages \Rightarrow Linear

But, gain $\propto \sqrt{\frac{(W/L)_1}{(W/L)_2}}$ \Rightarrow gain \longleftrightarrow voltage swing

Current Source Load: High gain and Voltage swing:



$$A_v = -g_m (r_o || r_{o2})$$

How to increase gain? $\lambda \propto \frac{1}{L} \Rightarrow r_o \propto \frac{L}{I_D}$

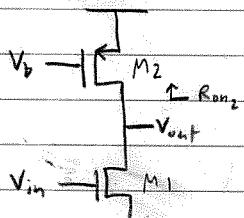
$$\text{Fix } W \text{ and } I_D, g_m, r_o = \sqrt{2(\frac{W}{L})_1 \mu C_{ox} I_D} \xrightarrow{r_o}$$

$\Rightarrow L \uparrow \Rightarrow \text{gain} \uparrow$ since $r_o \propto L$ and $g_m \propto \frac{1}{L}$

$L \uparrow \Rightarrow (\frac{W}{L}) \downarrow \Rightarrow V_{ov} \uparrow$ since $V_{ov} \propto \frac{1}{\frac{W}{L}}$ for a fixed $I_D \Rightarrow$ Voltage swing \downarrow

if $I_D \uparrow \Rightarrow \text{gain} \uparrow$

Triode Load:



$$A_v = -g_m (R_{on2} || r_{o1} || r_{o2}) \approx -g_m R_{on2}$$

$$R_{on2} = \frac{1}{\mu C_{ox} (\frac{W}{L})_2 (V_{DD} - V_b - IV_{THp})}$$

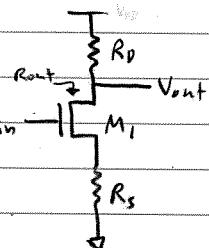
$V_{out, max} = V_{DD} \Rightarrow$ Larger Voltage swing

BUT Susceptible to process and temperature variations

(R_{on2} is a function of μ , C_{ox} , V_{THp})

CS with Source Degeneration:

This is a trick.
to simplify the
gain calculation



$$G_m = \frac{\partial I_D}{\partial V_{in}} = \frac{g_m}{1 + g_m R_S}$$

$R_{out} \approx (1 + g_m R_S) r_o$ Resistance seen at drain

$$A_v = -G_m R_D = -\frac{g_m R_D}{1 + g_m R_S} = -\frac{R_D}{\frac{1}{g_m} + R_S}$$

Resistance in source path.

$$= -\frac{R_D}{R_S} \text{ for } g_m R_D \gg g_m R_S$$

Now, considering Body Effect:

$$G_m = \frac{g_m r_o}{R_s + [1 + (g_m + g_{mb}) R_s] r_o}$$

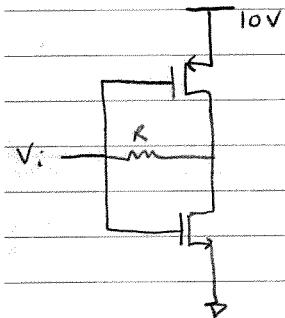
$$R_{out} = [1 + (g_m + g_{mb}) r_o] R_s + r_o \approx [1 + (g_m + g_{mb}) R_s] r_o$$

Lemma: $A_v = -G_m R_{out}$

where G_m = transconductance when output is grounded.

R_{out} = output resistance when input is grounded.

Questions from some Books.



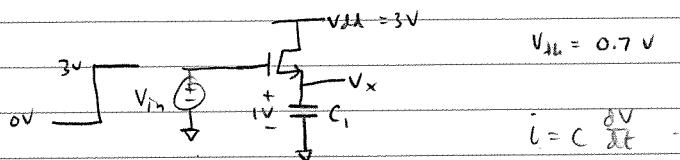
$$V_A = 60V \quad |V_f| = 2V \quad R \gg r_{ds} \quad \frac{V_o}{V_i} = ?$$

without R : $\frac{V_o}{V_i} = -g_m (r_{ds} \parallel r_{ds}) = -\frac{1}{2} g_m r_{ds}$

R acts as feedback. ?

by KCL : $A_v = \frac{V_o}{V_i} = -\frac{(g_{m1} + g_{m2})}{(r_{o1} \parallel r_{o2} \parallel R)}$

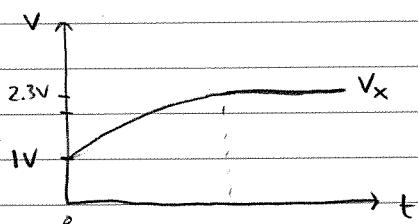
Razavi 2.11 a) sketch V_x as a function of time



$$\frac{dV_x}{dt} = \frac{i}{C}$$

$$dV_x = \frac{i}{C} dt$$

$$dV_x = \left(\frac{1}{C} \mu_{ox} \frac{V}{C} (3V - V_x - 0.7V)^2 \right) \frac{dt}{C}$$



$$\text{let } K = \frac{1}{2C} \mu C_{ox} \frac{W}{L} \Rightarrow \frac{dV_x}{(2.3 - V_x)^2} = K dt \Rightarrow \frac{1}{(2.3 - V_x)} = Kt + A =$$

Initial conditions at $t=0, V_x = 1 \Rightarrow A = \frac{1}{1.3} \approx 0.77$

$$\Rightarrow 2.3 - V_x = \frac{1}{Kt + 0.77} \Rightarrow V_x = \begin{cases} 2.3 - \frac{1}{Kt + 0.77}, & \text{for } 0 < t < \frac{0.77}{K} \\ 2.3 & t > \frac{0.77}{K} \end{cases}$$

$V_{dd} = 3V \Rightarrow$ MOSFET either in sat or cutoff.

$$i_c = C \cdot \frac{dV_x}{dt} = \frac{1}{2} \mu C_{ox} \frac{W}{L} (3 - V_x - 0.7)^2 = K (2.3 - V_x)^2$$

~~$$\Rightarrow \frac{dV_x}{dt} = \frac{K}{C} (5.29 - 4.6V_x + V_x^2)$$~~

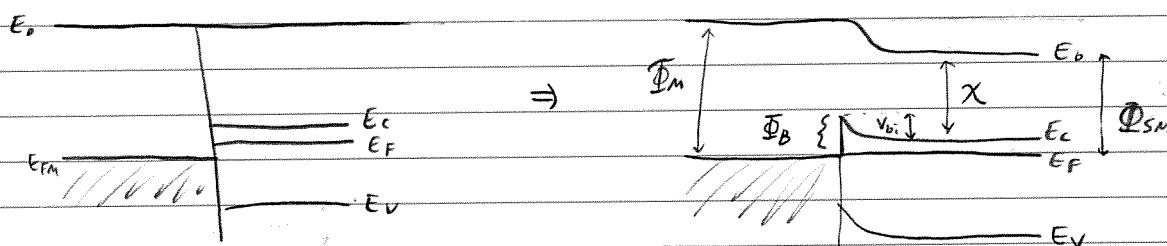
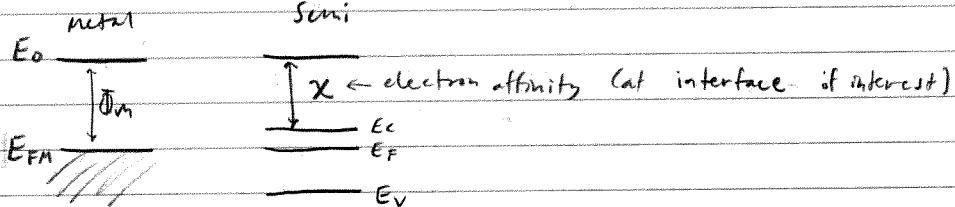
~~$$SV = \frac{K}{C}$$~~

$$\Rightarrow \int \frac{dV_x}{(2.3 - V_x)^2} = \int K dt \Rightarrow -2(2.3 - V_x)^{-1} + C_1 = Kt + C_2$$

$$\Rightarrow 2.3 - V_x = Kt + C_3 \Rightarrow V_x = 2.3 - \frac{1}{Kt + C}$$

$$V_x(0) = 1 = 2.3 - \frac{1}{Kt + C_3} \Rightarrow \frac{1}{C_3} = 1.3 \Rightarrow C_3 \approx 0.77$$

MS

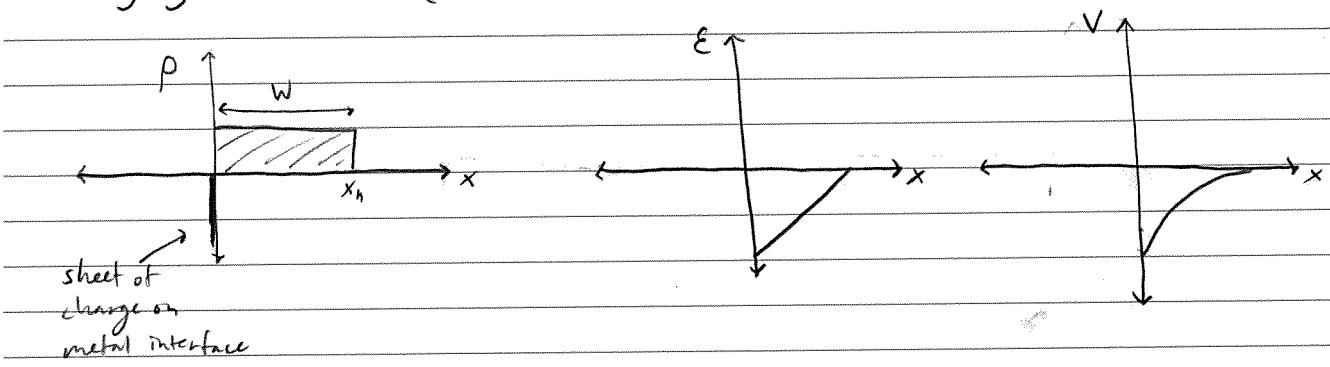


$$\Phi_B \propto V_{bi}; \quad V_{bi} = \frac{1}{\epsilon} [\Phi_B - (E_c - E_F)]_{FB} = \Phi_m - \Phi_{sm}$$

flat band

$\Phi_m = \Phi_B + X$	rectifying	ohmic
n-type	$\Phi_m > \Phi_s$	$\Phi_m < \Phi_s$
p-type	$\Phi_m < \Phi_s$	$\Phi_m > \Phi_s$

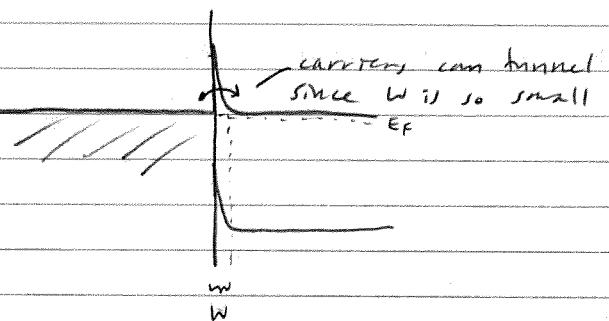
rectifying: $I = I_0 (e^{\frac{V}{V_T}} - 1)$



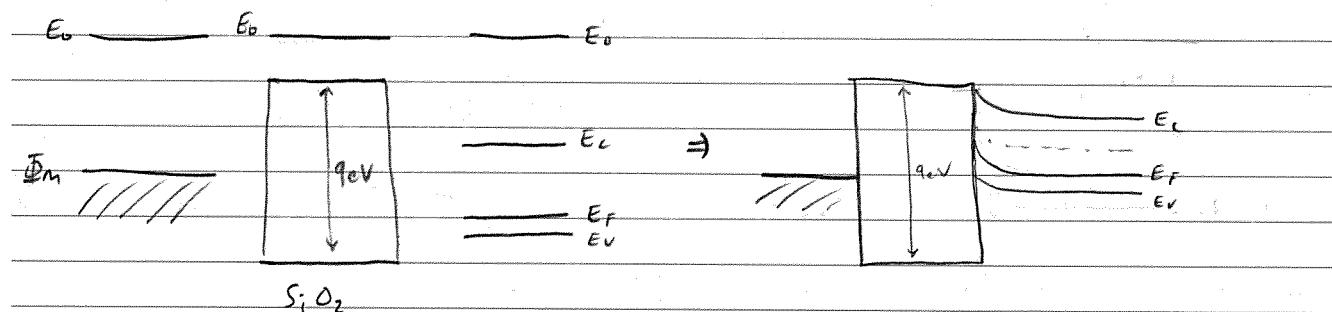
degenerate
↓

How to get an ohmic contact in reality? Heavily doped semiconductor.
 $(> 10^{18} \text{ cm}^{-3} \text{ for silicon})$

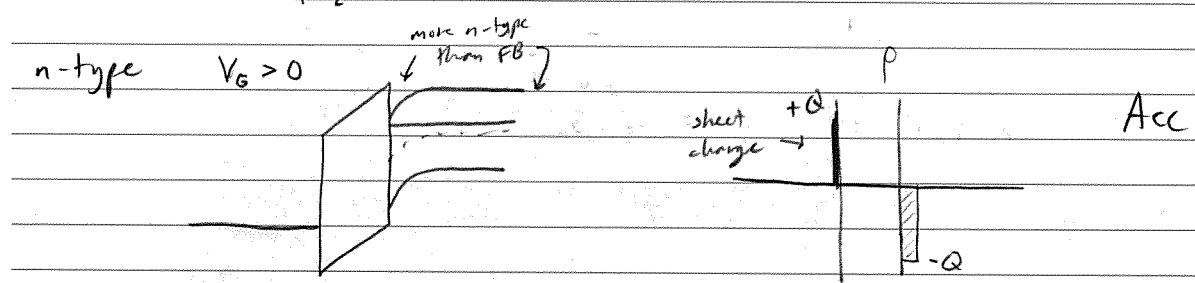
⇒



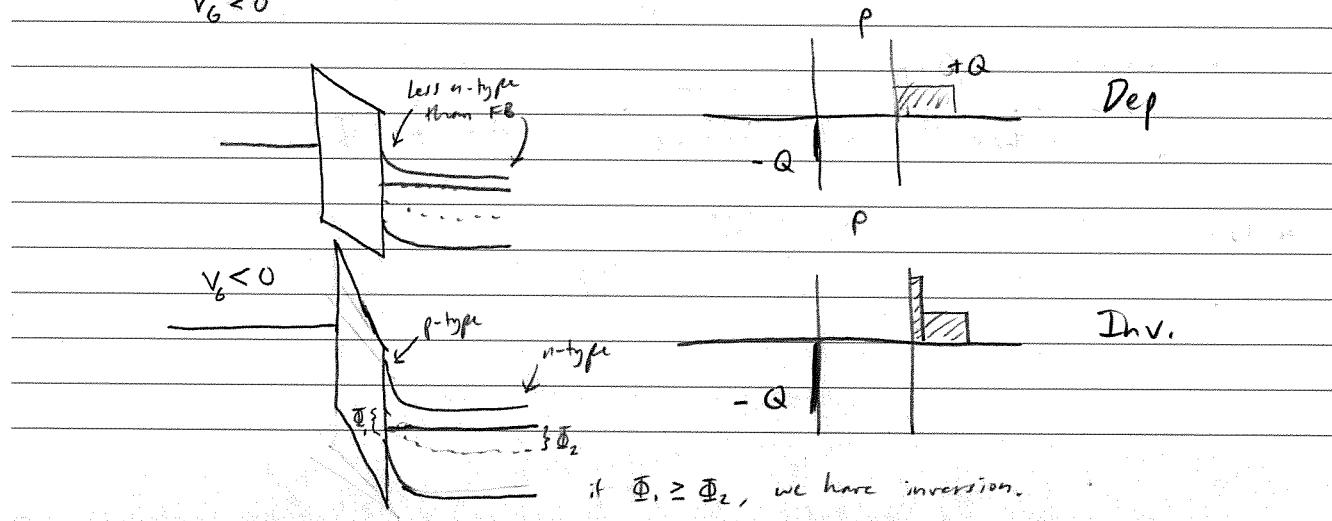
MOS



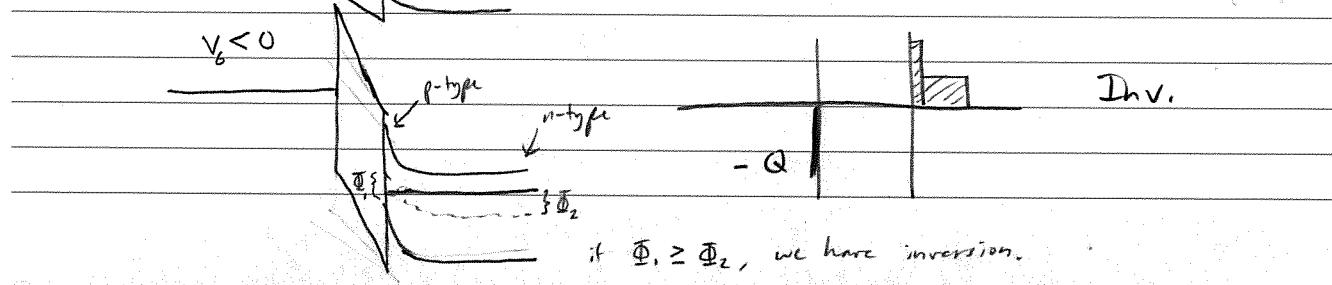
SiO_2



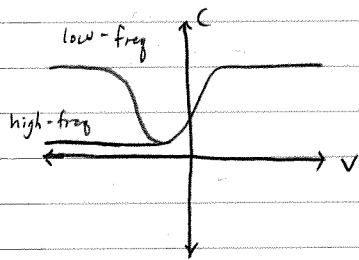
$V_G < 0$



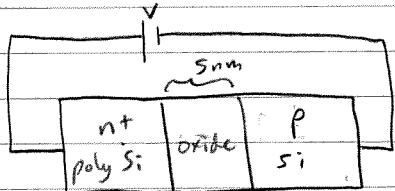
$V_G < 0$



C-V characteristics of MOS (n-type)



Question from MIT course.



$$\chi_{\text{gate}} = 4.04 \text{ eV}$$

$$C_{\text{ox}} = \frac{\epsilon_{\text{ox}}}{t_{\text{ox}}} = 7 \cdot 10^{-7} \frac{\text{F}}{\text{cm}^2}$$

a) if $Q_G = -2 \cdot 10^{-7} \frac{\text{C}}{\text{cm}^2} \Rightarrow \epsilon_{\text{ox}} = ?$

b) $Q_{\text{semi}} = -2 \cdot 10^{-7} \frac{\text{C}}{\text{cm}^2} \Rightarrow V = ?$

a) $Q = VC \Rightarrow V = \frac{Q}{C} = -\frac{2}{7} V \quad \epsilon_{\text{ox}} = \frac{-\frac{2}{7} V}{5 \cdot 10^{-7} \text{F}} = -\frac{2}{35} \cdot 10^7 \text{ V/cm}$

b) $W_{\text{max}} = \sqrt{\frac{2 \epsilon_r \epsilon_0}{q N_A} (2 \Phi_F)} \quad \Phi_F = \frac{kT}{e} \ln \left(\frac{N_A}{n_i} \right) \Rightarrow W_{\text{max}} = 2.6 \cdot 10^{-6} \text{ cm}$

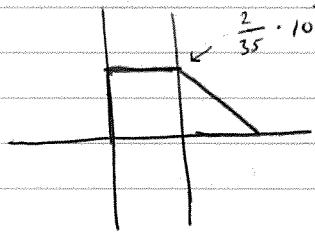
$\Rightarrow Q_{\text{bulk}} = q N_A W_{\text{max}} = 6 \cdot 10^{19} \text{ C} \cdot 6 \cdot 10^{17} \text{ cm}^{-3} \cdot 2.6 \cdot 10^{-6} \text{ cm} = 2.496 \cdot 10^{-7} \frac{\text{C}}{\text{cm}^2}$

\Rightarrow no inversion.

$$Q = q N_A \cdot W \Rightarrow W = \frac{Q}{q N_A} = \sqrt{\frac{2 K_s \epsilon_0}{q N_A} \Phi_s} \Rightarrow \text{solve for } \Phi_s \leftarrow V$$

$$\Rightarrow W = 2.1 \cdot 10^{-6} \text{ cm} \Rightarrow \Phi_s = \frac{W^2 g N_A}{2 K_s \epsilon_0} =$$

$$C = \frac{Q}{V}$$

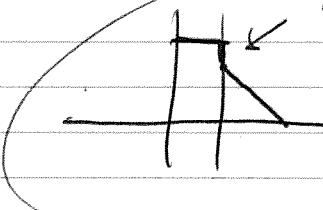
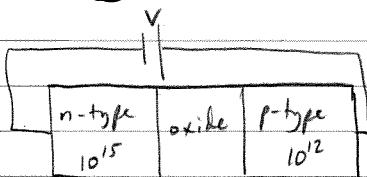


$$\Rightarrow V = \left(5 \text{ nm} + \frac{2.1 \cdot 10^6 \text{ nm}}{2} \right) \left(\frac{2}{35} \cdot 10^7 \text{ V/cm} \right) =$$

$$C = \frac{Q}{V}$$

$$E_F - E_C = \frac{Q}{K \epsilon_0}$$

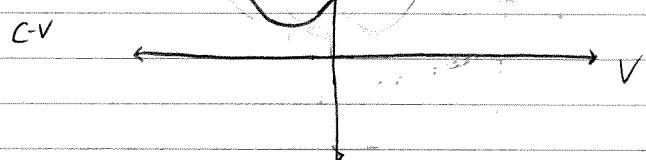
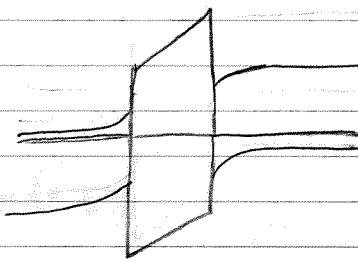
Question (from EE216)



if there was
an inversion
layer.

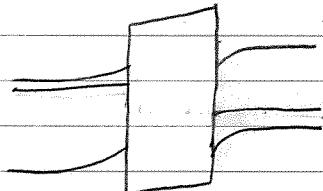
Draw band diagram for:

2) $V_G = 0$

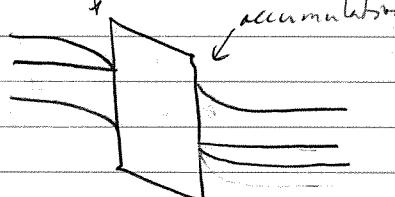


1) $V_G > 0$

$|V_G|$ small



OR

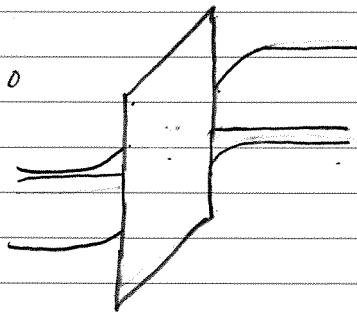


$|V_G|$ large

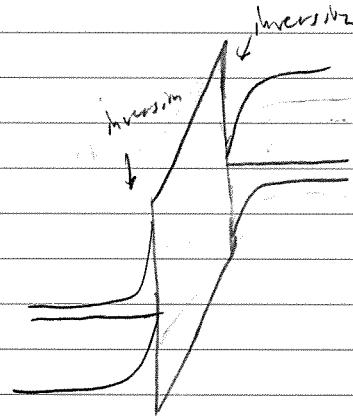
accumulation

accumulation

3) $V_G < 0$



OR



inversion

inversion

inversion

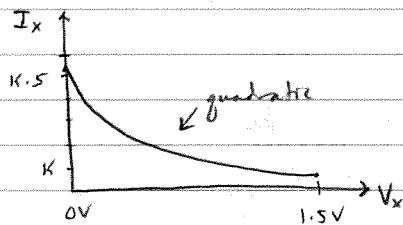
Circuits : Razavi

2.5 a) vary V_x from 0-1.5V, plot I_x and g_m

starts in sat, since $V_{gd} = 0 < V_t = 0.7V$ let $K = \frac{1}{2} \mu C_o \frac{W}{L}$

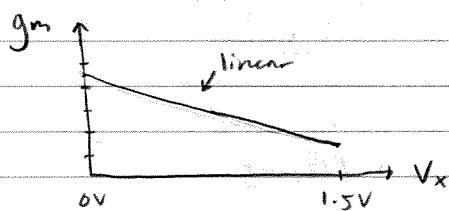
$$I_{x_{\max}} = \frac{1}{2} \mu C_o \frac{W}{L} (3 - 0.7)^2 = K \cdot 2.3^2 = K \cdot 5.29$$

$$I_{x_{\min}} = K (1.5 - 0.7)^2 = K \cdot 0.64$$



$$g_m = \mu C_o \frac{W}{L} V_{ov} \quad (\text{neglecting CLM})$$

$$\Rightarrow g_{m_{\max}} = 2K(2.3) \quad g_{m_{\min}} = 2K(0.8)$$

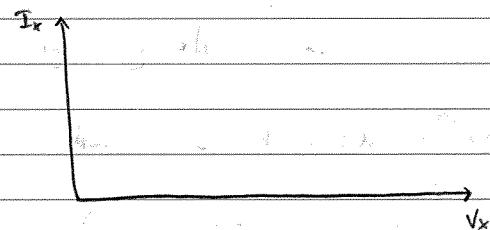
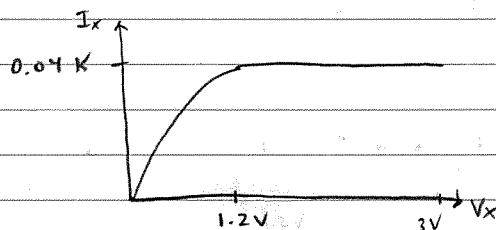


b) vary V_x from 0-3V, plot I_x and g_m $V_{ov} = 0.2V$

starts in triode, goes to saturation at $V_{gd} = V_t \Rightarrow V_x = 1.9V - 0.7V = 1.2V$

$$\text{in triode: } I_x = \mu C_o \frac{W}{L} (0.2V - \frac{V_x - 1.2}{2}) V_x$$

$$\text{in sat: } I_x = \frac{1}{2} \mu C_o \frac{W}{L} (0.2V)^2 = K(0.04) \quad (\text{ignoring CLM})$$



$$g_m = \frac{\partial I_d}{\partial V_{gs}}$$

what is g_m in triode ??

Circuits - [REDACTED] - EE114 L5 Gain & biasing + finite output R considerations.

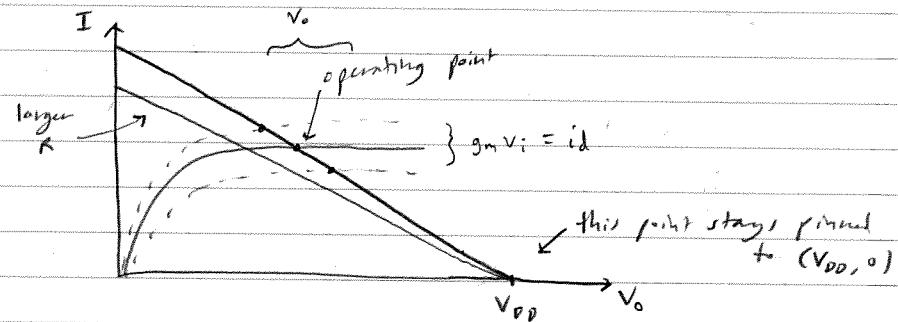
Upper bound of gain on CS with resistive load

$$A_v = -g_m R_L = -\frac{2I_d}{V_{DD}} R_L \quad I_d R_L < V_{DD}$$

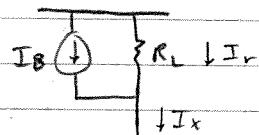
$$\Rightarrow |A_{v_{\max}}| < \frac{2V_{DD}}{V_{DD}}$$

Load Line:

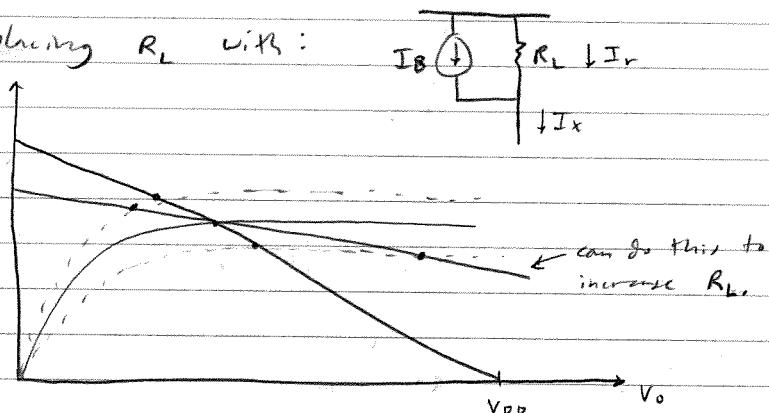
$$I_r = \frac{V_{DD} - V_o}{R_L} \quad I_d$$



We can fix this by replacing R_L with:



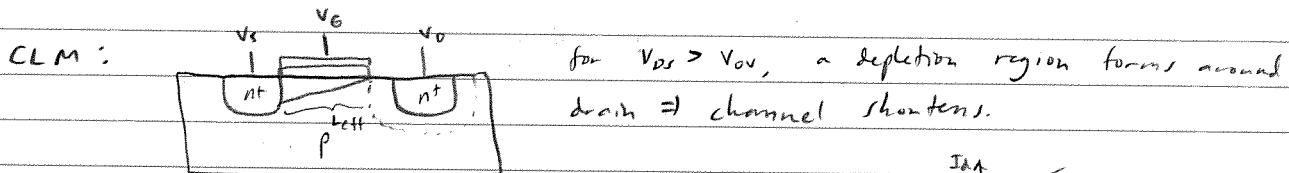
$$\Rightarrow I_x = \frac{V_{DD} - V_o}{R_L} + I_B$$



Why can't we get infinite gain?

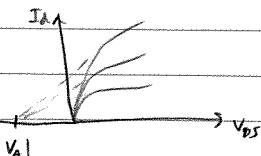
Mismatch between I_B and I_d and finite output resistance r_o .

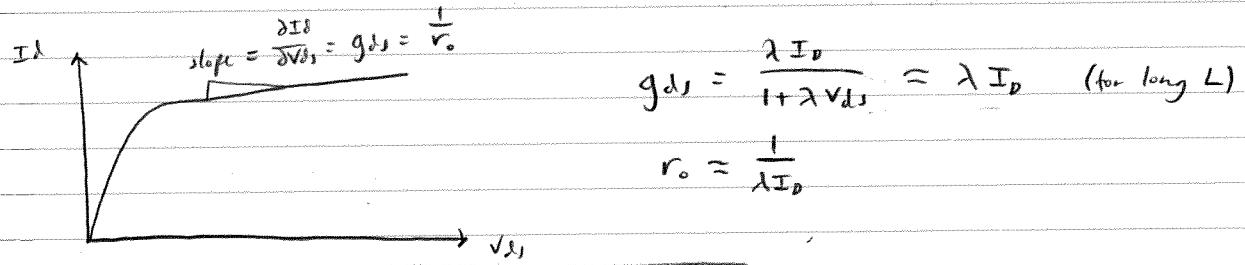
can use common mode feedback.



$$\lambda = \frac{\Delta L}{L} = \frac{1}{V_A} \quad I_d = \frac{1}{2} \mu (\alpha \frac{W}{L} (V_{GS} - V_t))^2 (1 + \lambda V_{DS})$$

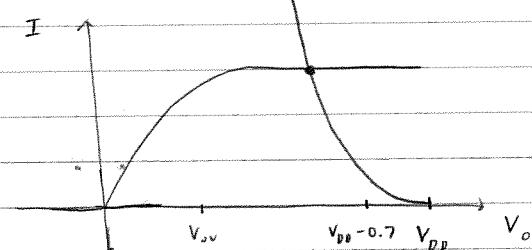
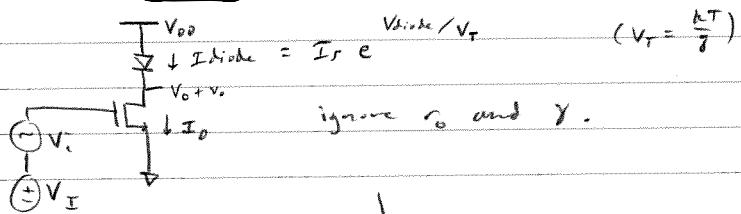
for EE114, $\lambda = 0.1 \text{ N}^{-1}$ for $L = 1 \mu\text{m}$ and $\lambda \propto \frac{1}{L}$





$$|A_v|_{R_L \rightarrow \infty} = g_m r_o = \frac{g_m}{g_{dss}} = \frac{g_m}{\lambda I_D} = \frac{2}{\lambda V_{ov}} \quad \leftarrow \text{intrinsic gain.}$$

Question:-

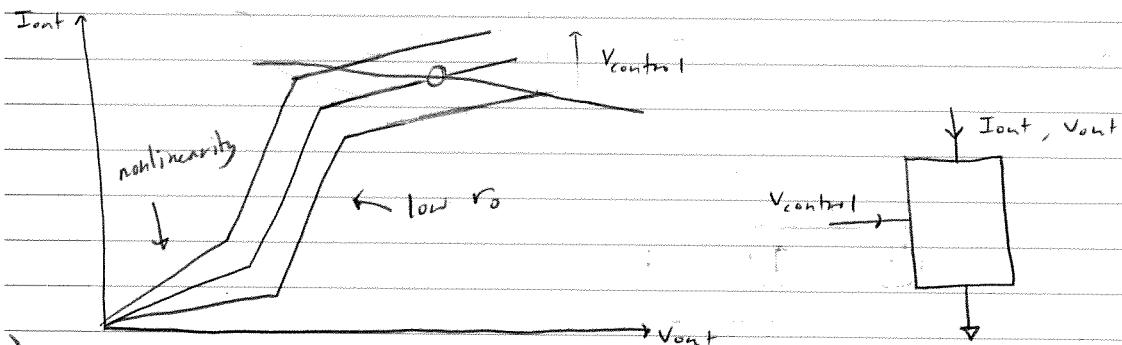


$$(2) \frac{\delta(-I_{\text{diode}})}{\delta V_o} = \frac{\partial}{\partial V_o} -I_s e^{(V_{dd} - V_o)/V_T} = \frac{I_s}{V_T} e^{(V_{dd} - V_o)/V_T} = \frac{I_{\text{diode}}}{V_T}$$

$$\begin{aligned}
 & \Rightarrow R_{\text{diode}} = \frac{V_T}{I_{\text{diode}}} \quad \Rightarrow A_v = -\frac{g_m V_T}{I_{\text{diode}}} \quad (V_T = \frac{kT}{q}) \\
 & \qquad \qquad \qquad g_m = \frac{2 I_d}{V_{ov}}, \quad I_d = I_{d,s} \\
 & \Rightarrow A_v = -\frac{2 V_T}{V_{ov}}
 \end{aligned}$$

$$(3) A_{v_{\max}} = -\frac{2 V_T}{V_{ov_{\min}}} \approx -\frac{2(0.026) V}{0.15 V} = -\frac{0.052}{0.15} = -0.35$$

Question - [REDACTED] from Qualls - Dutta (2008 or 2007)



1)

) Is this device useful for building an amplifier?

) Where and how would you bias it?

) What are the limitations?

c) Yes.

b) Bias it in far-right region, by placing a resistive load \parallel current source at the output and choosing $V_{control}$ such that the operating point is at point O

c) Limitations are finite output resistance ($\frac{dI_{out}}{dV_{out}} \neq 0$), limited output swing to keep the gain high (must stay in far-right region)
And high voltage operating point

) Do lower V_T devices have lower OFF currents for $V_{GS} = 0V$?

No, lower $V_T \Rightarrow$ higher off-current for same S (subthreshold slope)

) Series resistance (emitter) degrades bipolar transconductance more than source resistance for MOS? (T/F), explain

$$G_m = \frac{g_m}{1 + g_m R_s} \text{ for MOS}$$

~~$$G_m = \frac{g_m}{1 + g_m R_s + \frac{R_s}{R_n}}$$~~

$$G_m = \frac{g_m}{1 + (1 + \frac{1}{\beta}) g_m R_E} \Rightarrow \boxed{T}$$

i) Does decreasing C_{ox} improve gate delay independent of carrier mobility

No. $\boxed{T - \frac{1}{T}}$ gate delay depends on time it takes for minority carriers to form and channel \Rightarrow carrier mobility matters.

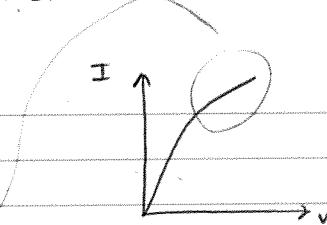
Devices -

Ideal MOSFET IV and Nonideal MOSFET

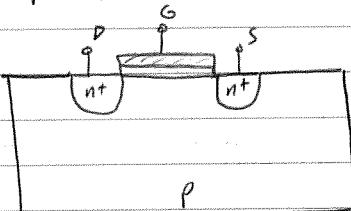
carrier concentration
at boundary.

low level injection: $p = \frac{n_i^2}{N_D} \cdot e^{\frac{qV_{DS}}{kT}}$

High level injection: $p = n \approx n_i e^{\frac{qV_{DS}}{kT}}$



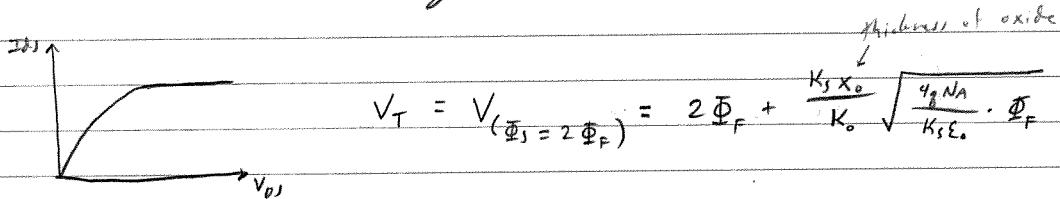
MOSFET:



Inversion is quicker than with MOS, since electrons can come from the source + drain (n^+) rather than bulk.

Source is the one that provides the carriers.

Current is dependent on how many carriers you have in the channel + the voltage across it (V_{DS})



$$V_T = V_{(\Phi_S = 2\Phi_F)} = 2\Phi_F + \frac{K_S X_0}{K_o} \sqrt{\frac{q_N N_A}{K_S E_o} \cdot \Phi_F}$$

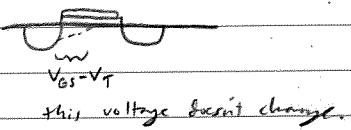
$\bar{\mu} < \mu_n$ effective mobility at the surface is $\sim 40\% - 60\%$ of the mobility in the bulk silicon, due to surface scattering.

$$I = q \bar{\mu} \frac{dV_y}{dy} t_i \times W = q (\underbrace{v_n \cdot t_i \cdot W}_{\text{charge density at a certain point}}) = v \cdot W \cdot Q_d \quad Q_d = C_{ox} (V_G - V_T - V_y)$$

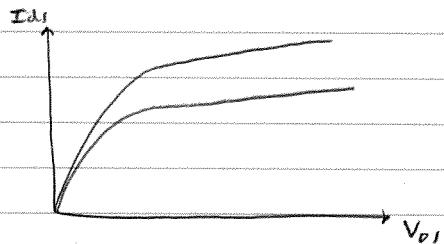
$$\Rightarrow I = \bar{\mu} \frac{dV_y}{dy} \cdot C_{ox} (V_G - V_T - V_y) W \quad \Rightarrow \int I dy = \int_0^{V_{DS}} dV_y C_{ox} (V_G - V_T - V_y) W Q_d$$

$$\Rightarrow I = \bar{\mu} C_{ox} \frac{W}{2} [(V_G - V_T) \cdot V_{DS} - \frac{1}{2} V_{DS}^2]$$

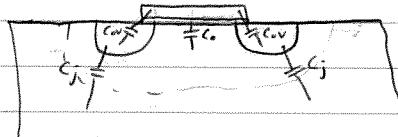
Why current doesn't depend on V_{DS} in Sat:



CLM:



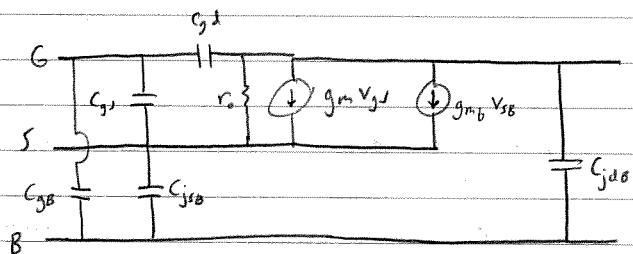
$$I = \bar{\mu} C_{ox} \frac{W}{L - \Delta L} [(V_G - V_T) \cdot V_{DS} - \frac{1}{2} V_{DS}^2]$$



Capacitor: Intrinsic $C_0 = C_{ox} \cdot L \cdot W$

Sat: $C_{gs} = \frac{2}{3} C_0$ $C_{gd} = 0$

Linear: $C_{gs} = C_{gd} \approx \frac{1}{2} C_0$



Transit Frequency: when $i_{in} = i_{out}$ $i_{in} = j\omega C_0 V_{gs}$ $i_{out} = g_m V_{gs}$

$$\Rightarrow f_T = \frac{g_m}{2\pi C_0}$$

$$g_m = \frac{\partial I_{DS}}{\partial V_{GS}} \Rightarrow \text{Linear: } g_m = \mu C_{ox} \frac{W}{L} V_{DS}$$

$$\text{Saturation: } g_m = \mu C_{ox} \frac{W}{L} (V_{GS} - V_T)$$

$$\Rightarrow \text{In Linear, } f_T = \frac{\mu V_{DS}}{2\pi L^2}. \quad \text{In Saturation } f_T = \frac{\mu (V_{GS} - V_T)}{2\pi L^2} = \frac{\mu V_{ov}}{2\pi L^2}$$

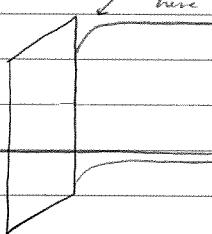
Nonidealities:

1) $\Phi_m \neq \Phi_s$, so even if $V_G = 0$,

\Rightarrow we need less V_G to get inversion.

$$\Rightarrow V'_T = V_T + \Delta V_T$$

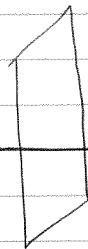
$$\Delta V_T = \Phi_m - \Phi_s$$



$$\text{charge density per area} = \sigma / m^2$$

② charge in oxide: $\Delta V_T = - \frac{1}{K_0 \epsilon_0} \int_0^{X_0} x \cdot p_{ox}(x) dx$

uses Poisson eq. & eq. for E field & potential.



$x p_{ox}(x) \rightarrow$ charge near semiconductor matters more.

if charge only exists at the boundary,

$$\Delta V_T = - \frac{Q_F}{C_0} \rightarrow C/m^2$$

different types of charge:

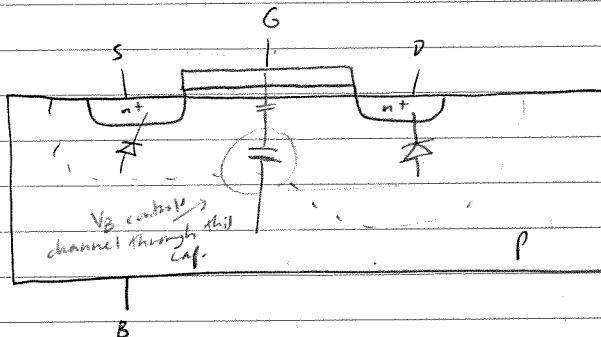
mobile Na^+, K^+ (comes from human body)

fixed: exists in oxide: can be reduced by annealing.

interface traps: (bias stress effect)

To change V_T , you can implant some charges to the surface of the silicon.

③ Backgate Effect:

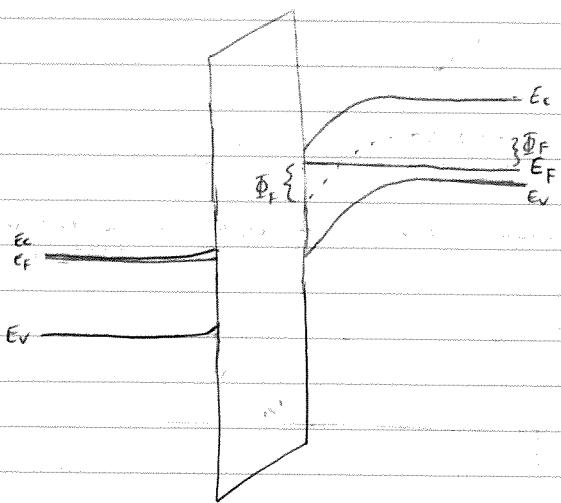


Normally want $V_B =$ Lowest voltage such that diodes remain reverse biased. raising V_B reduces V_T , since it acts as a second gate (similar to raising V_G)

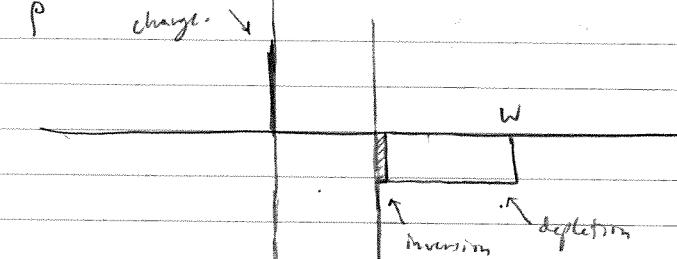
$$\Delta V_T = (V_T - 2\Phi_F) \left(\sqrt{1 - \frac{V_B}{2\Phi_F}} - 1 \right) = \gamma \left(\sqrt{|2\Phi_F + V_{SB}|} - \sqrt{2\Phi_F} \right)$$

Question from Berkeley, pg. 65

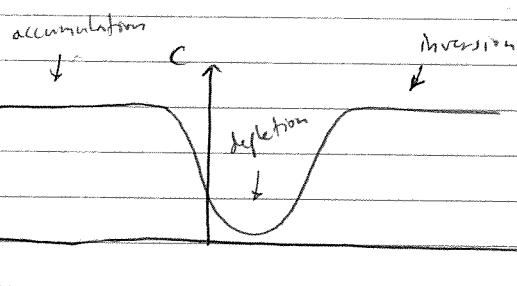
a) i)



ii) P charge sheet



iii)



iv)

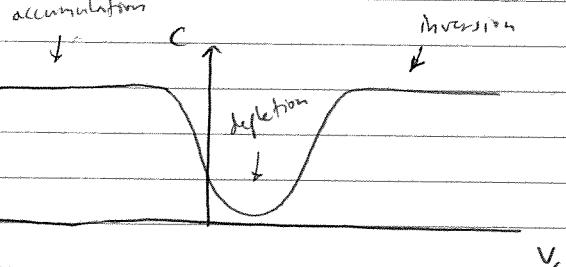


Fig. 74. d)

$$N_a = 10^{17} \text{ cm}^{-3} \quad \epsilon_{Si} = 10^{-12} \text{ F/cm} \quad \epsilon_{ox} = 3.45 \cdot 10^{-13} \text{ F/cm} \quad T_{ox} = 3.95 \text{ nm}$$

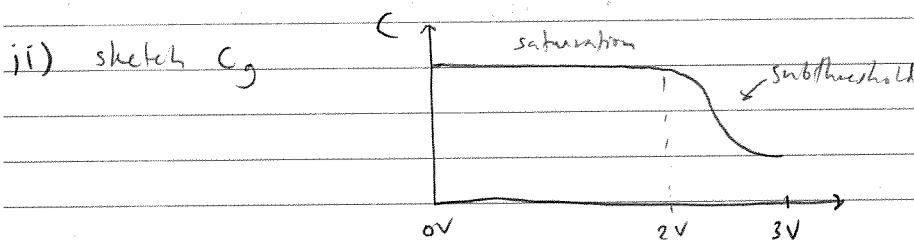
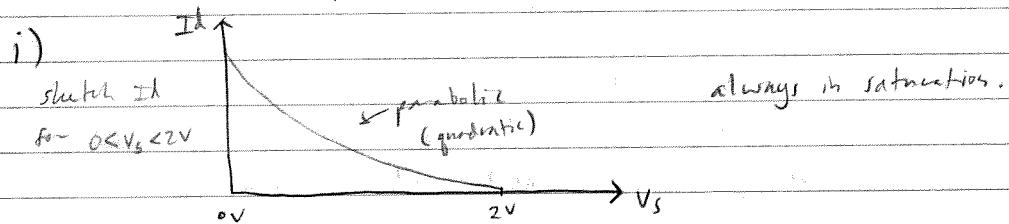
$$\Phi_F = E_i - E_F = kT \ln \left(\frac{N_a}{n_i} \right) = 0.026 \cdot 2.3 \cdot 7 = 0.42 \text{ V} \approx 0.4 \text{ V}$$

$$V_T = 2\Phi_F + \frac{\epsilon_{Si} T_{ox}}{\epsilon_{ox}} \sqrt{\frac{q_B N_A}{\epsilon_{Si} \epsilon_0} \cdot \Phi_F}$$

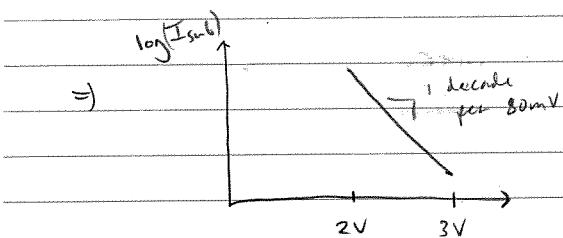
$$\sqrt{\frac{4 \cdot 1.6 \cdot 10^{17}}{10^{10}} \cdot 0.4} \quad \ln(10) = 2.3$$

$$V_T = 0.8 \text{ V} + 3.45 \cdot 10^{-6} \text{ cm} (1.6 \cdot 10^5) \approx 1.05 \text{ V}$$

$\mu = 1500 \text{ m Si for } e^- \quad \mu = 500 \text{ m Si for holes}$



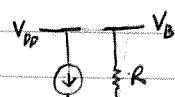
iii) $I_{sub} = I_0 e^{\frac{V_{GS}}{S V_T}} \quad S > 1$



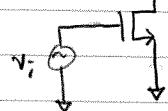
Circuits - Intrinsic + Extrinsic Capacitance.

Intrinsic:

spec. Time domain - response to pulse



Freq domain - frequency where gain goes to 1.

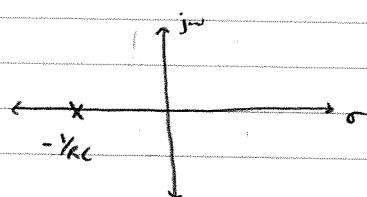


Intrinsic Lgs: Required for MOSFET operation



$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{\frac{1}{sC}}{R + \frac{1}{sC}} = \frac{1}{1 + sRC} = \frac{1}{1 - s/\rho}$$

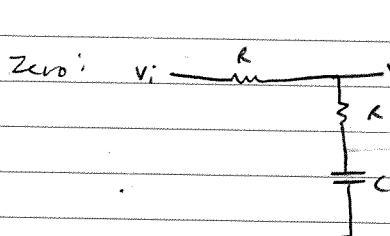
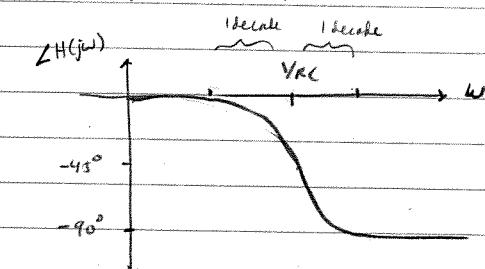
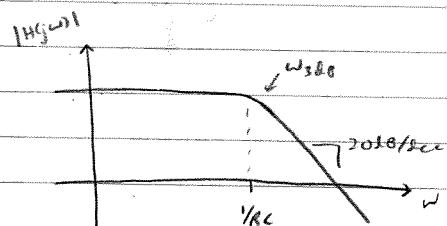
$$\rho = -\frac{1}{RC}$$



$$H(j\omega) = \frac{1}{1 + j\omega RC}$$

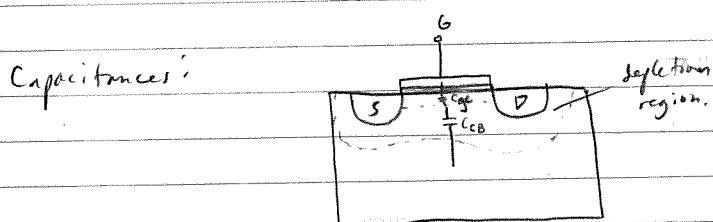
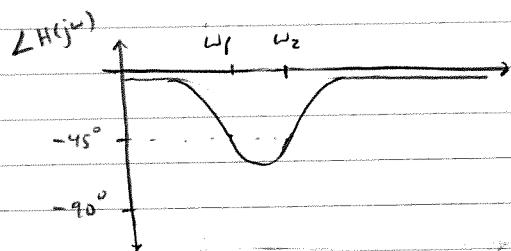
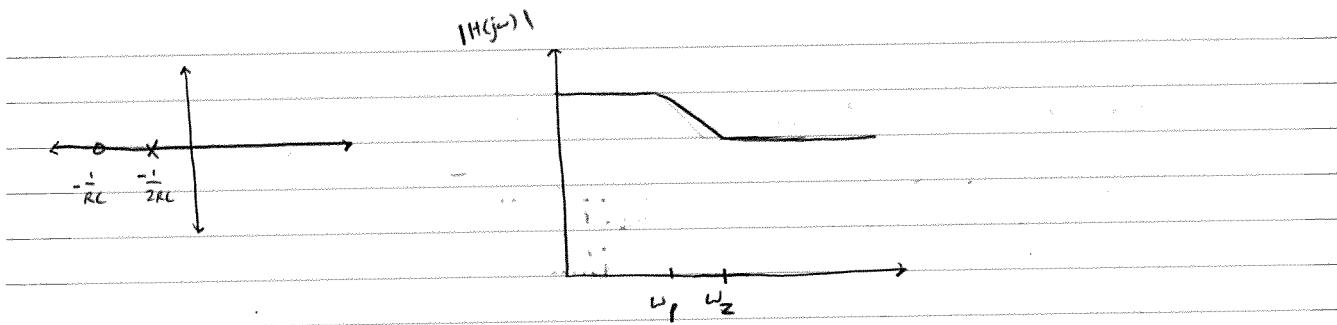
$$|H(j\omega)| = \frac{1}{\sqrt{1 + \omega^2 R^2 C^2}} \quad \angle H(j\omega) = \tan^{-1}(-\omega RC)$$

$$20 \log |H(j\omega_{3dB})| = 20 \log \left(\frac{1}{\sqrt{2}} \right) \approx -3$$

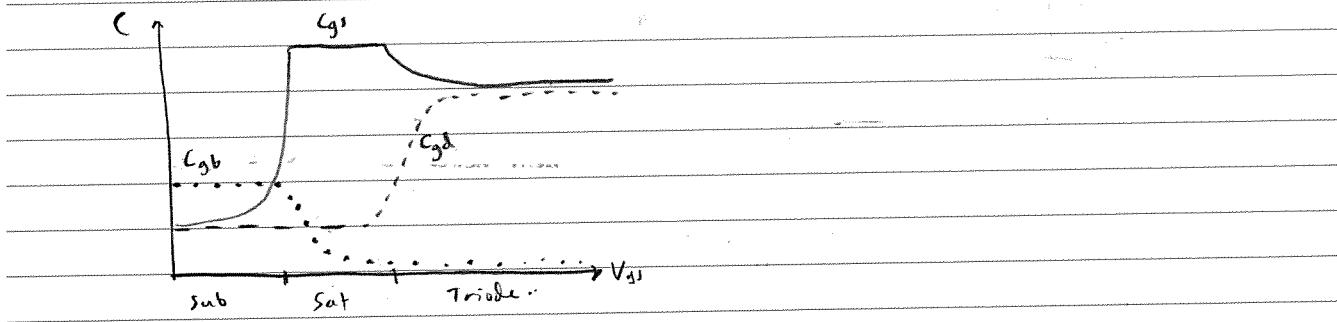
at ω_{3dB} , power is halved.

$$H(s) = \frac{\frac{1}{sC} + R}{\frac{1}{sC} + 2R} = \frac{1 + sRC}{1 + 2sRC} = \frac{1 - \frac{s}{2}}{1 - \frac{s}{\rho}}$$

$$Z = -\frac{1}{RC} \quad \rho = -\frac{1}{2RC}$$



	Subthreshold	Saturation	Triode
C_{sb}	C_{jst}	C_{jst}	C_{jst}
C_{db}	C_{jdb}	C_{jdb}	C_{jdb}
C_{gs}	C_{ov}	$\frac{2}{3} WL C_{ox} + C_{ov}$	$\frac{1}{2} WL C_{ox} + C_{ov}$
C_{gd}	C_{ov}	C_{ov}	$\frac{1}{2} WL C_{ox} + C_{ov}$
C_{gb}	$\left(\frac{1}{C_{cb}} + \frac{1}{C_{gc}}\right)^{-1}$ $= \left(\frac{1}{WL C_{ox}} + \frac{1}{\epsilon_s \cdot WL / x_d}\right)^{-1}$	0	0



Power - Bandwidth Tradeoff. (CS)

$$W_{3dB} = \frac{1}{R_i L_g} = \frac{1}{R_i \frac{2}{3} WLC_{ox}} = \frac{3 \mu}{4 L^2} \underbrace{\frac{R}{I_{av,1} R_i}}_{\text{technology}} \underbrace{V_{ov}}_{\text{design constraints}} \quad \leftarrow \text{design knob}$$

$$g_m = \frac{2 I_d}{V_{ov}} \quad |_{I_{av,1}} = g_m R \quad \Rightarrow \quad I_d = \frac{1}{2} \underbrace{\frac{|I_{av,1}|}{R}}_{\text{design constraints}} V_{ov} \quad \rightarrow \text{design knob.}$$

$\Rightarrow V_{ov} \uparrow \omega_{3dB} \uparrow$, but $I_d \uparrow \Rightarrow$ more bandwidth requires more power.

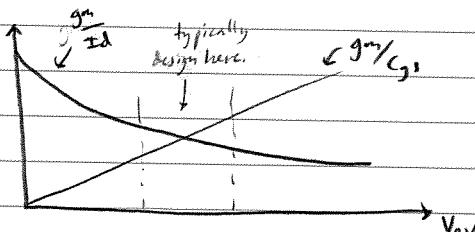
Want high $\frac{g_m}{I_d}$ and high $\frac{g_m}{C_{gs}}$



$$\frac{g_m}{I_d} = \frac{2}{V_{ov}}$$

$$\frac{g_m}{C_{gs}} = \frac{3}{2} \frac{\mu V_{ov}}{L^2}$$

	V _{ov} small	V _{ov} large	
g _m /I _d	Large \curvearrowleft	Small \curvearrowright	
g _m /C _{gs}	Small \curvearrowright	Large \curvearrowleft	



$$\frac{g_m}{I_d} \cdot \frac{g_m}{C_{gs}} = \frac{3 \mu}{L^2}$$

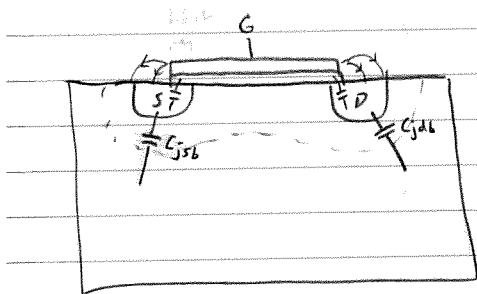
gets better with tech scaling.

$$\omega_t = \frac{g_m}{C_{gs}} = \text{transit frequency}; \quad i_i \rightarrow \boxed{i_o}$$

at which $\frac{i_o}{i_i} = 1$

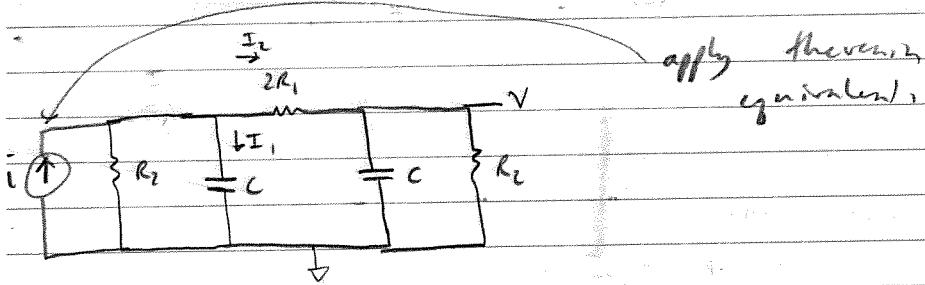
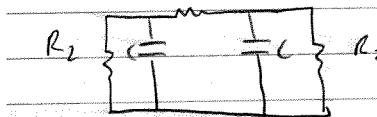
$$\omega_t = \frac{g_m}{C_{gs}}$$

Extrinsic Cap: $C_{ov} = C_{ov'} \cdot w$ depends on both direct cap and from fringing field.



Q: 1999 Tom Lee

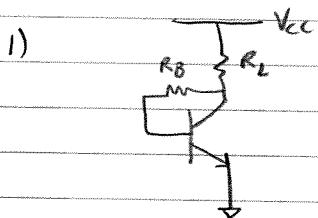
2) $2R_1 \quad R_2 \parallel (2R_1 + R_2) C$



$$\Rightarrow \left(2R_1 + \frac{R_2}{1+sR_2C} \right)$$

current divider $I_2 = \frac{\frac{1}{sC}}{\frac{1}{sC} + 2R_1 + \frac{R_2}{1+sR_2C}} I = \frac{I}{1+2sR_1C + \frac{sR_2C}{1+sR_2C}}$

$$\begin{aligned} \Rightarrow \frac{V}{I} &= \frac{2R_1 + \frac{R_2}{1+sR_2C}}{1+2sR_1C + \frac{sR_2C}{1+sR_2C}} = \frac{1}{2R_1 + \frac{R_2}{1+sR_2C}} + sC \\ &= \frac{2R_1 + \frac{R_2}{1+sR_2C}}{1+sC(2R_1 + \frac{R_2}{1+sR_2C})} \end{aligned}$$

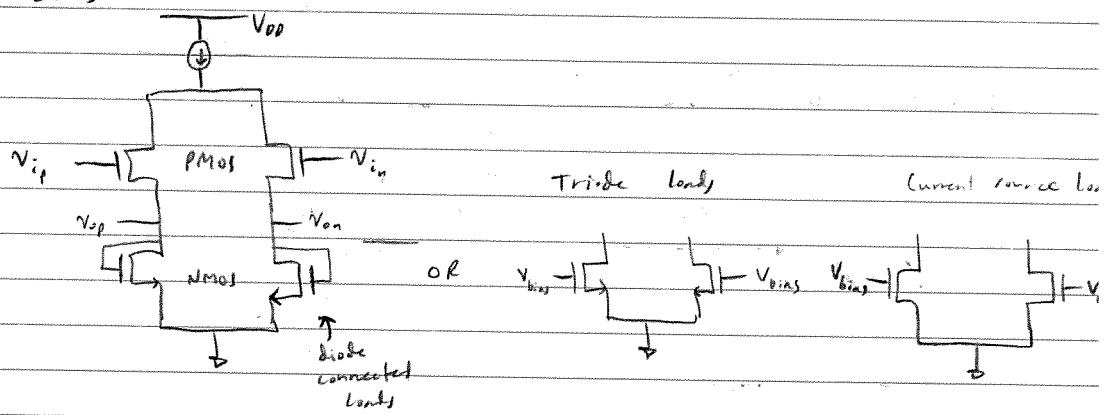


for saturation: $V_{BE} > V_t$ $\beta = \frac{I_c}{I_B}$
 $V_{BC} > V_t$

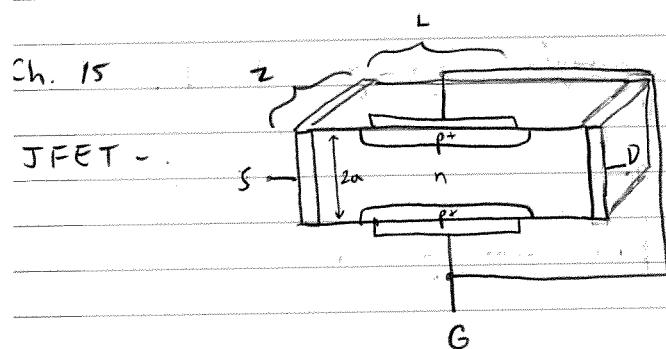
$$V_c = V_{cc} - I_c R_L \quad V_B = V_c - \frac{1}{\beta} I_c \cdot R_B \Rightarrow V_{BC} = - \frac{1}{\beta} I_c \cdot R_B < 0 \text{ if } I_c > 0$$

\Rightarrow contradiction. \Rightarrow Transistor will never be in saturation.

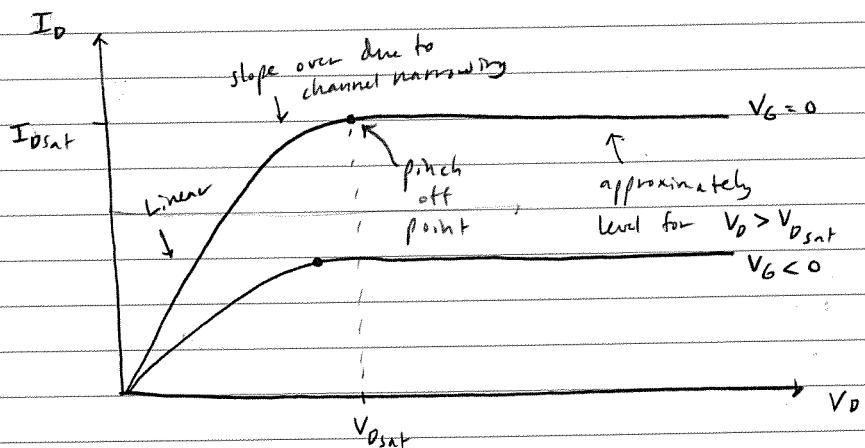
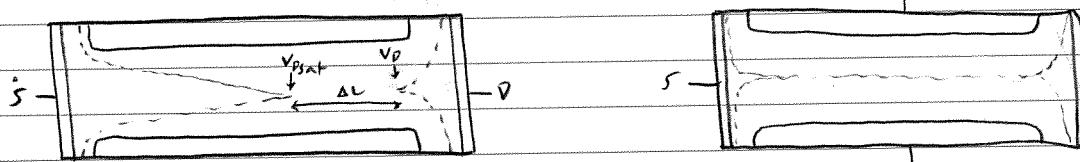
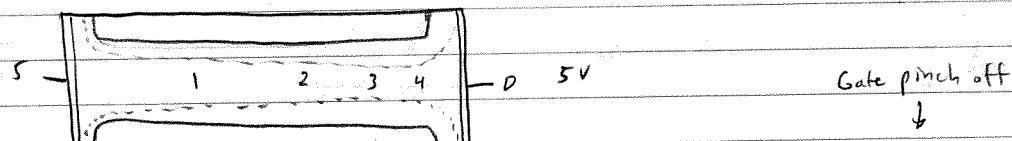
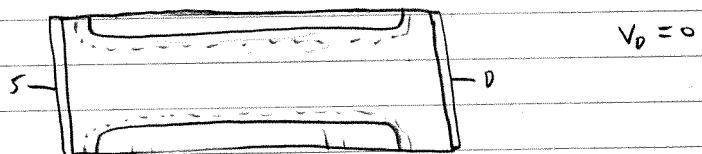
Simon Wong 2003



Devices - Alex Ch 15 + 19 (JFET, MESFET, and Modern FET structures)



if $V_G = 0V$, $V_S = 0V$, $V_D > 0V$



$$I_D = \frac{2gZ\mu_n N_D a}{L} \left\{ V_D - \frac{2}{3}(V_{bi} - V_p) \left[\left(\frac{V_D + V_{bi} - V_G}{V_{bi} - V_p} \right)^{3/2} - \left(\frac{V_{bi} - V_G}{V_{bi} - V_p} \right)^{3/2} \right] \right\}$$

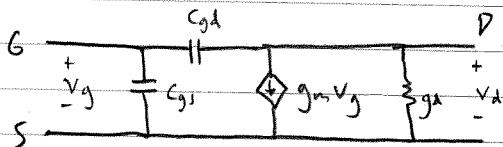
for $0 \leq V_D \leq V_{D,\text{sat}}$; $V_p \leq V_G \leq 0$

$$I_{D,\text{sat}} = \frac{2gZ\mu_n N_D a}{L} \left\{ V_G - V_p - \frac{2}{3}(V_{bi} - V_p) \left[1 - \left(\frac{V_{bi} - V_G}{V_{bi} - V_p} \right)^{3/2} \right] \right\}$$

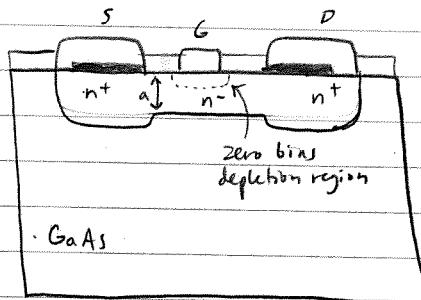
$$= I_{D_0} \left(1 - \frac{V_G}{V_p} \right)^2 \quad I_{D_0} = I_{D,\text{sat}}|_{V_G=0}$$

\uparrow
"Square Law"

Small Signal Model:



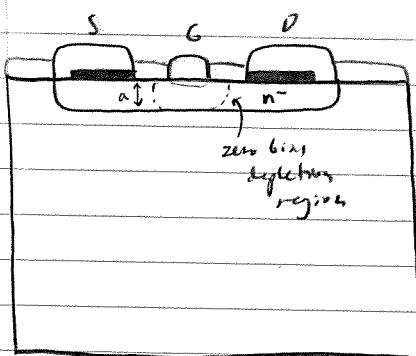
MESFET - GaAs MESFET - good for high freq. ICs (MMICs)



D-MESFET

(Digital logic circuits use both D + E)
Analog MMICs use D.

Depletion Mode - Normally ON



E-MESFET

Enhancement Mode - Normally OFF

Can use same equations as for JFET with the following mods:

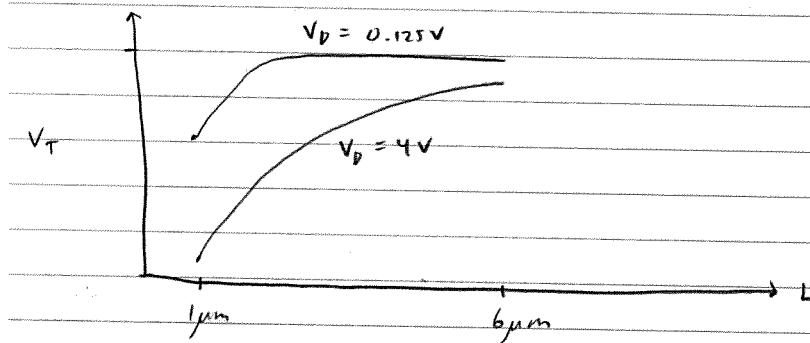
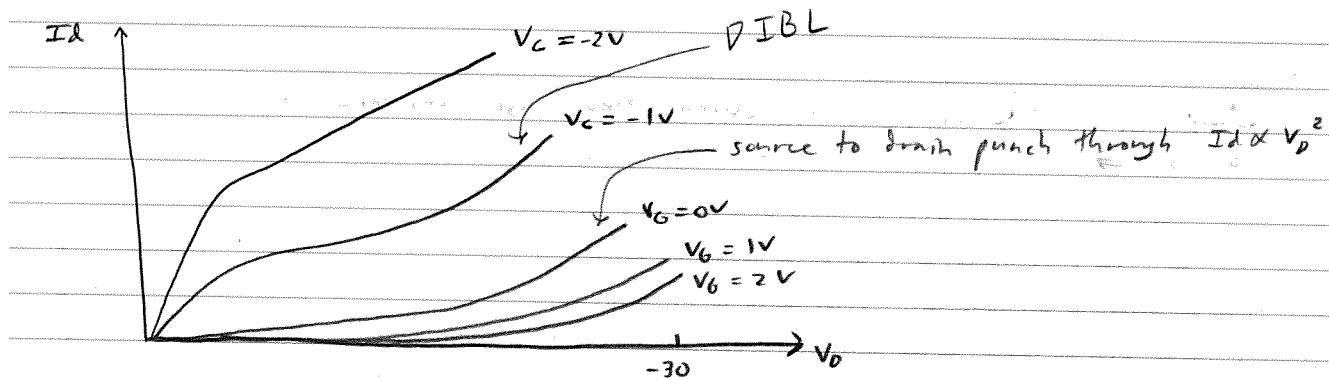
$$2a \rightarrow a$$

short channel \Rightarrow gradual channel approx doesn't hold \rightarrow variable mobility.

short channel \Rightarrow velocity saturation.

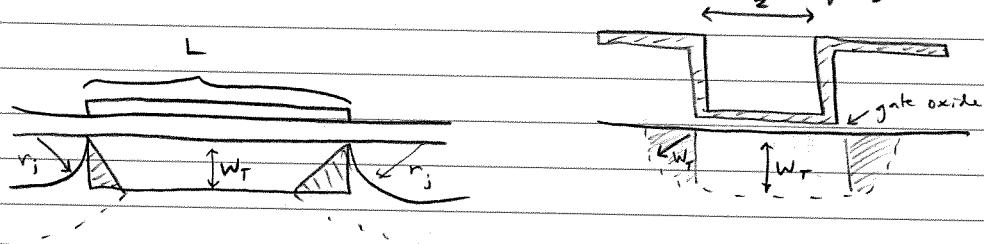
Ch. 19 Modern FET Structures

- Short channel effects:



$$L_{min} = 0.4 [r_j \times_0 (W_s + W_p)^2]^{1/3} \quad x_0 \text{ in } \text{\AA}$$

L_{min} can be made smaller by reducing depth of source drain islands, reducing oxide thickness, or increasing substrate doping.

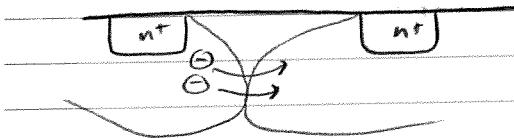


In short channel devices, the source and drain assist in depleting the region under the gate.

$$\Delta V_T (\text{short channel}) = -\frac{g_N A W_T}{C_0} \frac{r_j}{L} \left(\sqrt{1 + \frac{2W_T}{r_j}} - 1 \right)$$

$$\Delta V_T (\text{narrow width}) = \frac{g_N A W_T}{C_0} \frac{\pi W_T}{2z}$$

Parasitic BTI Action : 1) source to drain punch-through

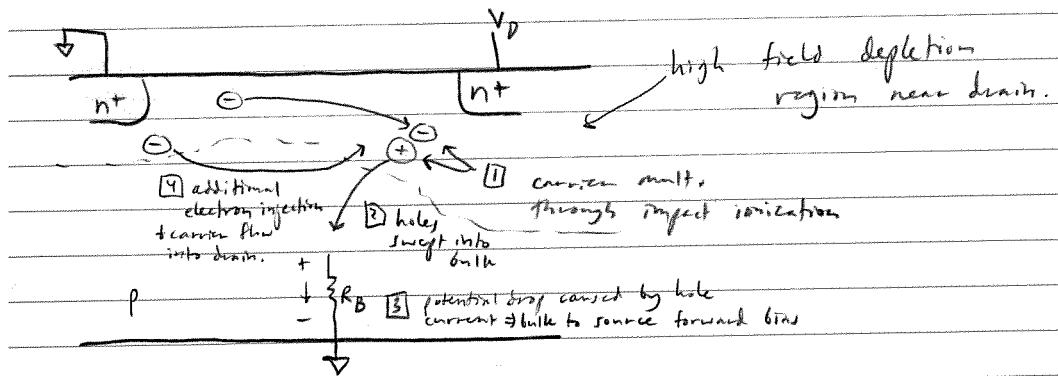


current no longer constrained to surface channel.

$$I_D \propto V_D^2$$

- Can fix by increasing doping of subgate region,
- but increasing substrate doping increases parasitic caps.
- \Rightarrow selectively increase subgate doping through deep-ion implantation.

2) carrier multiplication + regenerative feedback



Hot Carrier Effects :

1) Oxide charging (BIAS STRESS)

- channel carriers + carriers entering drain depletion region gain sufficient energy to surmount Si-SiO₂ surface barrier.

\rightarrow enter oxide \rightarrow neutral centers in oxide trap carriers \rightarrow charge build up \rightarrow changed V_T and gm over time.

- solution : LDD (lightly doped drain)

2) Velocity Saturation

- high E field ($> 3 \cdot 10^4$ V/cm for e^- , $> 10^5$ V/cm for holes)
- I_{sat} reduced : $I_{D_{\text{sat}}} \approx Z C_0 (V_G - V_T) v_{\text{sat}}$
- I_{sat} linearly dependent on $(V_G - V_T)$ rather than square law.

3) Velocity overshoot / Ballistic Transport

- if $L \leq l \Rightarrow$ ballistic transport (l is avg. distance between scattering event (mean free path))
- could lead to faster devices
- Average velocity can exceed v_{sat} . this is called velocity overshoot.
- $L \leq 0.3\mu\text{m}$ for GaAs

Circuits - Alex L8, L9, L10 Miller Approximation and ZVTC, + Backgate Effect.

Razavi: $V_t = 0.7 \text{ V}$ $V_{DD} = 3 \text{ V}$

3.10

a) $\left(\frac{w}{L}\right)_1 = 100 \quad \left(\frac{w}{L}\right)_2 = 20 \quad V_{DS} = V_{GS} - V_t$

$$I_{D2} = I_{D1} \Rightarrow 20(V_{GS2} - V_t)^2 = 100(V_{GS1} - V_t)^2$$

$$\Rightarrow (2.3 - V_o)^2 = 5(V_i - 0.7)^2 \quad \text{Edge of Triode} \Rightarrow V_{D1} = V_{GS1} - V_t \\ \Rightarrow V_o = V_i - V_t$$

$$\Rightarrow 5.29 - 4.6V_o + V_o^2 = 5V_o^2 \Rightarrow 5.29 - 4.6V_o - 4V_o^2 = 0$$

$$\Rightarrow V_o = 0.71 \text{ V} \Rightarrow V_i = 1.41 \text{ V}$$

$$g_{m1} = \frac{2I_1}{V_{GS1}} \quad g_{m2} = \frac{2I_2}{V_{GS2}} \quad a_{v1} = -\frac{g_{m1}}{g_{m2}} = -\frac{V_{oV2}}{V_{oV1}} = -\frac{3 - 0.71 - 0.7}{1.41 - 0.7} = \frac{1.59}{0.71} =$$

$$\Rightarrow a_{v2} = -2.23$$

b) $V_o = V_i - V_t - 0.05 \text{ V}$

$$\Rightarrow (2.3 - V_o)^2 = 10(V_i - V_t - \frac{V_o}{2})V_o$$

$$\Rightarrow (2.3 - V_o)^2 = 10(V_o + V_t + 0.05V - V_t - \frac{V_o}{2})V_o = 10(0.05V_o + \frac{V_o^2}{2})$$

$$\Rightarrow 5.29 - 4.6V_o + V_o^2 - 0.5V_o - 5V_o^2 = 0 \Rightarrow 5.29 - 5.1V_o - 4V_o^2 = 0$$

$$\Rightarrow V_o = 0.6774 \text{ V} \Rightarrow V_i = 1.4274$$

$$\Rightarrow g_{m1} = \frac{\partial}{\partial V_{GS1}} (\mu_{ox} \frac{w}{L} (V_{GS1} - V_t + \frac{V_{DS}}{2}) V_{DS}) = \mu_{ox} \frac{w}{L} V_{DS} = \frac{I_D}{(V_{oV1} + \frac{V_{DS}}{2})}$$

$$g_{m2} = \frac{\partial}{\partial V_{GS2}} (\mu_{ox} \frac{w}{L} (V_{GS2} - V_t + \frac{V_{DS}}{2}) V_{DS}) = \mu_{ox} \frac{w}{L} [(V_{GS2} - V_t) + V_{DS}]$$

$$\Rightarrow \text{gain} = -\frac{g_{m1}}{g_{m2} + g_{av}} = -\frac{\mu_{ox} \left(\frac{w}{L}\right)_1 V_o}{\mu_{ox} \left(\frac{w}{L}\right)_2 V_{oV2} + (V_{oV1} + V_o) \left(\frac{w}{L}\right)_1}$$

$$= -\frac{100 V_o}{20(3 - V_o) + 100(V_i - 0.7 + V_o)} = -\frac{100(0.6774)}{20(3 - 0.6774 - 0.7) + 100(1.4274 - 0.7 + 0.6774)} \\ = -0.3917$$

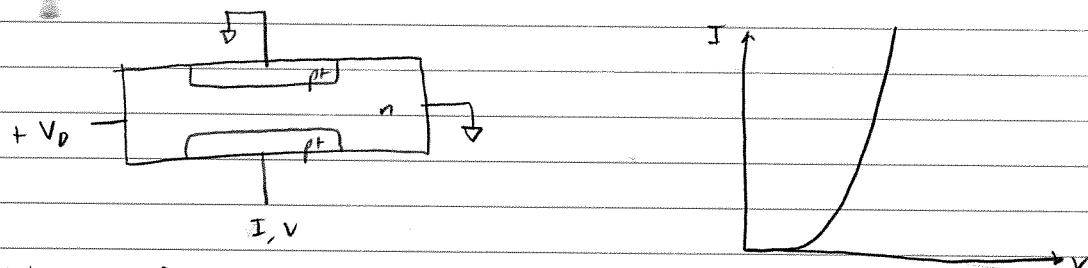
$$\Rightarrow a_{v_0} = -0.3917$$

neglecting gds; $a_{v_0} = -2.0874$

3.11

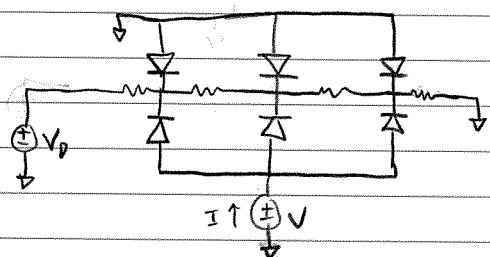
Quals-Dutton 2009

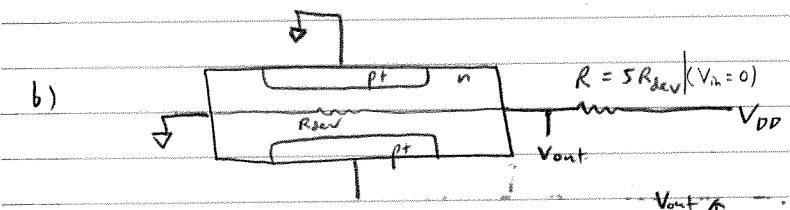
1. a)



sketch I, V for $V_D > 0$.

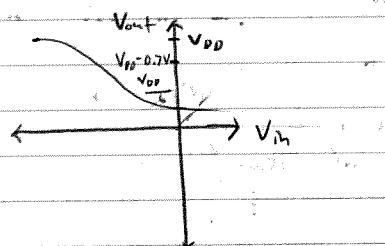
diode forward biased





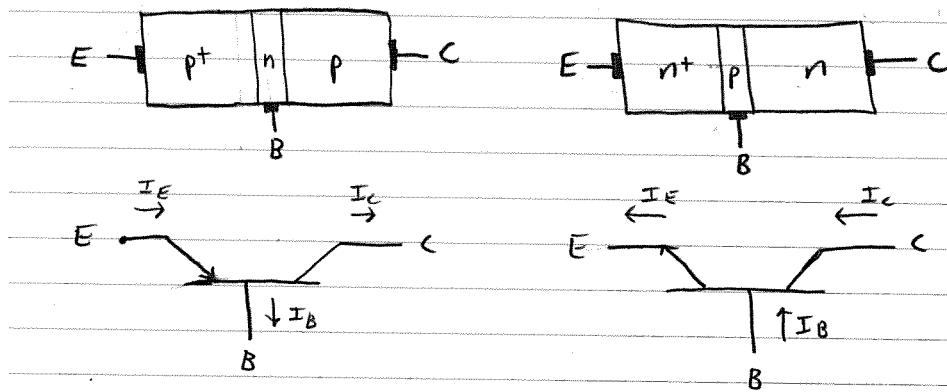
sketch V_{out} vs V_{in}

for $V_{in} < 0$



Devices - Alex CH 10-11.1 BJT Fundamentals and Static Characteristics.

10 - BJT Fundamentals

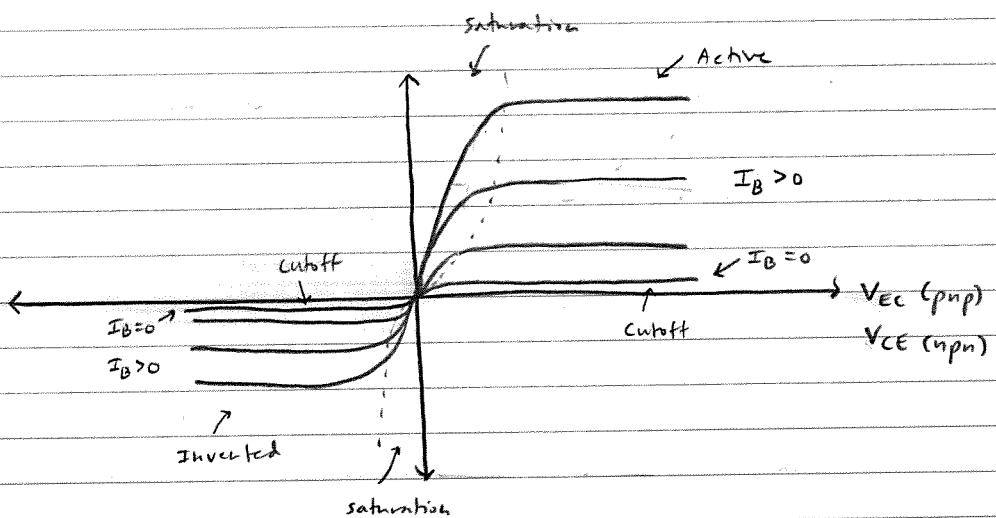


$$I_E = I_B + I_C \quad V_{EB} + V_{BC} + V_{CE} = 0$$

In the limit of $\frac{W}{L_B} \rightarrow 0$ (narrow base)

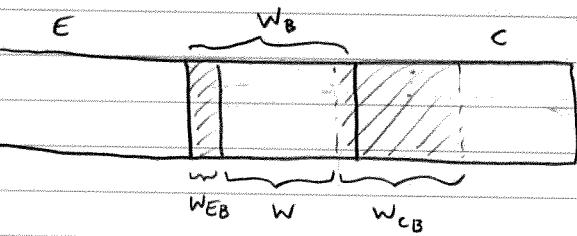
$$I_C = I_s (e^{\gamma})$$

<u>Biasing Mode</u>	E-B Bias	C-B Bias
Saturation	Forward	Forward
Active	Forward	Reverse
Inverted	Reverse	Forward
Cutoff	Reverse	Reverse



BJT in Equilibrium Conditions

B



Depletion regions

E_c

Band diagram

E_i

E_F

E_V

V

Potential

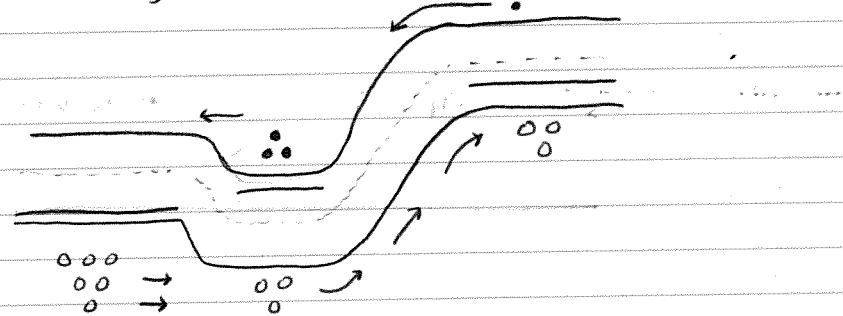
E

Electric Field

P

Charge Density

Carrier Activity under Active mode biasing



W is narrow compared to minority carrier diffusing length.

⇒ most holes diffuse completely through quasineutral base region.

Performance Parameters

Emitter Efficiency :

$$\gamma = \frac{I_{E1}}{I_E} = \frac{I_{E1}}{I_{Ep} + I_{En}}$$

for pnp

← ideally unity

Base Transport Factor :

$$\alpha_T = \frac{I_{Cp}}{I_{Ep}}$$

← ideally unity

Common Base DC current gain:

$$\alpha_{dc} = \gamma \alpha_T = \frac{I_{Cp}}{I_E} \quad \text{ideally unity}$$

Common Emitter DC current gain:

$$\beta_{dc} = \frac{I_C}{I_B} = \frac{\alpha_{dc}}{1 - \alpha_{dc}}$$

ideally infinite

CH 11: BJT Static Characteristics.

Solve using diffusion equations and boundary equations.

get complicated eqs for I_{en} , I_{en} , I_{Ep} , I_{Cp} , Δp_{ex}

Can make some simplifications if $W \ll L_B$

for $W \ll L_B$:

$$\Delta p_B(x) = \Delta p_B(0) + [\Delta p_B(W) - \Delta p_B(0)] \frac{x}{W} \quad \leftarrow \text{Linear}$$

perturbed carrier concentration is

Performance parameters:

$$\gamma = \frac{1}{1 + \frac{D_E}{D_B} \frac{N_B}{N_E} \frac{W}{L_E}} \quad \leftarrow N_E \gg N_B \Rightarrow \text{better emitter efficiency (near unity)}$$

$$\alpha_T = \frac{1}{1 + \frac{1}{2} \left(\frac{W}{L_B} \right)^2} \quad \leftarrow W \ll L_B \Rightarrow \text{better base transport factor (near unity)}$$

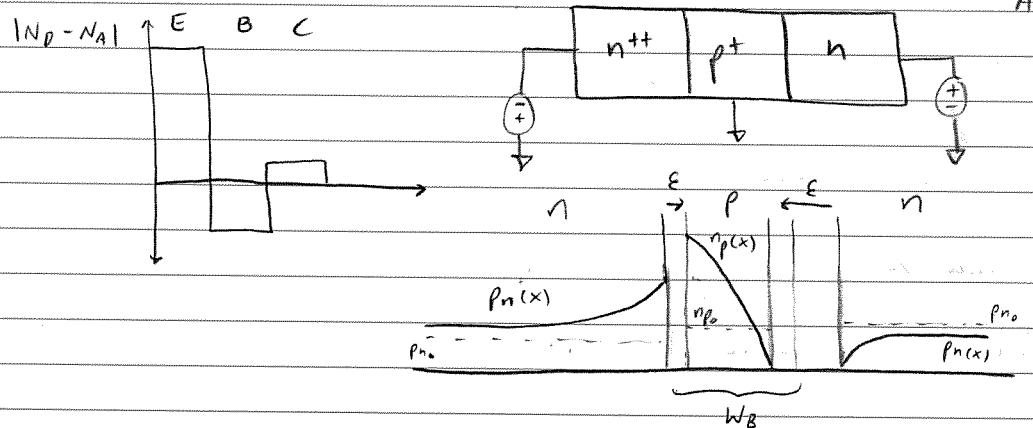
$$\alpha_{dc} = \frac{1}{1 + \frac{D_E}{D_B} \frac{N_B}{N_E} \frac{W}{L_E} + \frac{1}{2} \left(\frac{W}{L_B} \right)^2}$$

$$\beta_{dc} = \frac{1}{\frac{D_E}{D_B} \frac{N_B}{N_E} \frac{W}{L_E} + \frac{1}{2} \left(\frac{W}{L_B} \right)^2}$$

- BJT (Nemam)

Biasing

Active Mode.



choose $W_B \ll L_p, L_n$

$$i_c = I_s \exp\left(\frac{V_{BE}}{V_T}\right)$$

in base

$$I_s = g D_n A \frac{dN_b(x)}{dx} = \frac{-g D_n A_{BE}}{W}$$

cross-sectional Area between
base and emitter
junction.

width of germinational
base region

$$i_E \Rightarrow i_{E_1} = i_c$$

$$i_{E_2}$$

↑ due to diffusion of holes from B to E.

$$I_E = I_{SE} \exp\left(\frac{V_{BE}}{kT}\right) = i_{E_1} + i_{E_2}$$

$$i_B \Rightarrow i_{B_1} = i_{E_2} \leftarrow \text{diffusion of holes from B to E.}$$

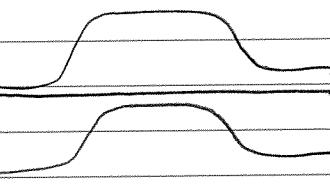
i_{B_2} ← recombination current. some electrons entering the base actually recombine with holes. Thus, we need a hole current to replace these holes.

$$\text{We want } i_c = i_E \Rightarrow \alpha_{dc} \approx \frac{i_c}{i_E} \approx 1$$

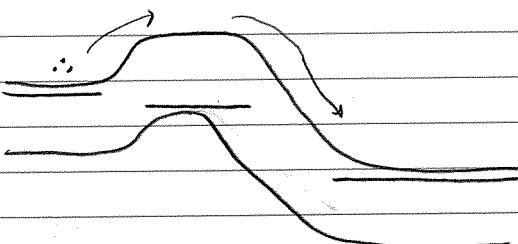
↑ common base current gain.

$$\beta = \frac{i_c}{i_B} = \frac{\alpha_{dc}}{1 - \alpha_{dc}} \leftarrow \text{common base current gain.}$$

Band Diagram: eq.



Active



Berkeley Qualls

Fall 2004 Bokor

BJT:

$$3. \text{ a) } \beta = \frac{I_c}{I_B} = \frac{2mA}{10\mu A} = 0.2 \cdot 1000 = 200$$

$$I_c = I_s \exp\left(\frac{V_{BE}}{V_T}\right) \Rightarrow g_m = \frac{\partial I_c}{\partial V_{BE}} = \frac{I_c}{V_T}$$

$$\text{MOSFET: } g_m = \frac{2I_d}{V_{ov}} = \frac{16mA}{(5-0.7)V} = \frac{16mA}{4.3V} \approx 4mS$$

$$\text{BJT: } g_m = \frac{8mA}{0.026V} \approx 300mS$$

b) Discuss the comparison of the two g_m values. If one is much larger than the other, give some physical explanation.

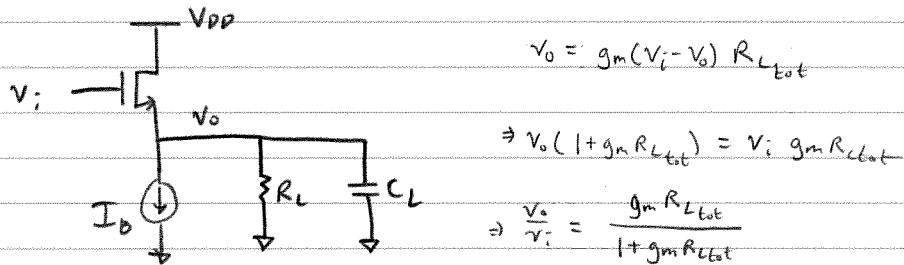
$g_m_{\text{BJT}} \gg g_m_{\text{MOS}}$. For BJT, the concentration of carriers is exponentially dependent on V_{BE} , but for MOS, the carriers in the inversion layer are linearly dependent on V_{GS} (like a capacitor).

As far as the input-output characteristics are concerned, in what way does the transistor with lower g_m outperform the transistor with higher g_m ?

MOS: higher input impedance ($\propto r_\pi$), lower power,
better scaling, compatible with digital process.

Circuits - L11-13, CD, PVT, Current Mirrors

L11 - Common Drain

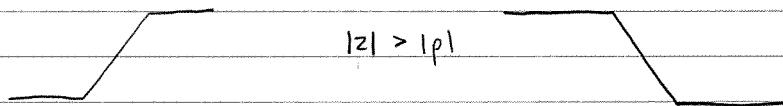


$$C_{L_{tot}} = C_L + C_{sb} \quad R_{L_{tot}} = R_L \parallel r_o \parallel \frac{1}{g_{mb}}$$

$$\Rightarrow A_v = \frac{V_o}{V_i} = \underbrace{\frac{g_m}{g_m + \frac{1}{R_{L_{tot}}}}}_{\alpha_{v_o}} \left(\frac{1 + \frac{sC_{gs}}{g_m}}{1 + \frac{s(C_{gs} + C_{L_{tot}})}{g_m + \frac{1}{R_{L_{tot}}}}} \right) \quad \leftarrow 1 \text{ zero, 1 pole}$$

if $R_L \rightarrow \infty, r_o \rightarrow \infty, g_{mb} = 0 \Rightarrow \alpha_{v_o} = 1$

if $|z| < |p|$



if $|z| = |p|$ infinite bandwidth?

CD Input Impedance: NMOS

$$Y_{in} = s(C_{gd} + C_{gb}) + sC_{gs}(1 - \alpha_v(s))$$

for PMOS with Body-Source Tie,

$$Y_{in} = s(C_{gd} + s(C_{gs} + C_{gb})(1 - \alpha_v(s))) \approx s(C_{gd} + C_{gb})$$

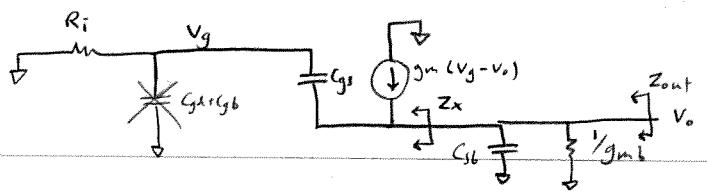
\Rightarrow very small input capacitance.

\Rightarrow capacitive impedance up to moderate frequencies

$\sim C_{gd} + C_{gb}$ plus a fraction of C_{gs} .

$$Z_{out} = \frac{1}{g_m + g_{mb}} \parallel \frac{1}{s(C_{gs} + C_{sb})} \quad \text{low output impedance up to high freq.}$$

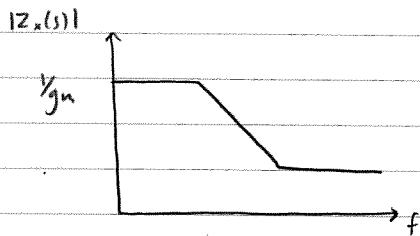
↑
ignoring R_i .



if we consider R_i :

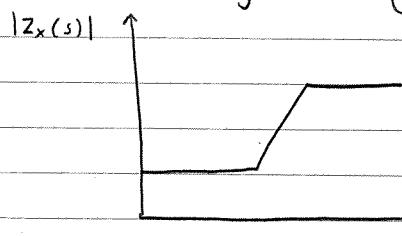
$$Z_x = \frac{1}{g_m} \frac{1 + sR_i g_s}{(1 + \frac{sC_{gs}}{g_m})}$$

Two cases: $R_i < \frac{1}{g_m}$

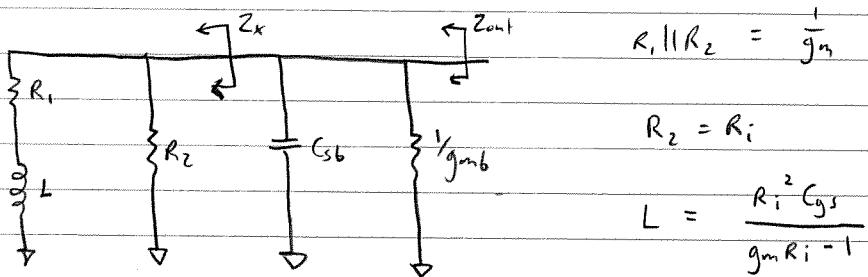


$$R_i > \frac{1}{g_m}$$

Inductive load

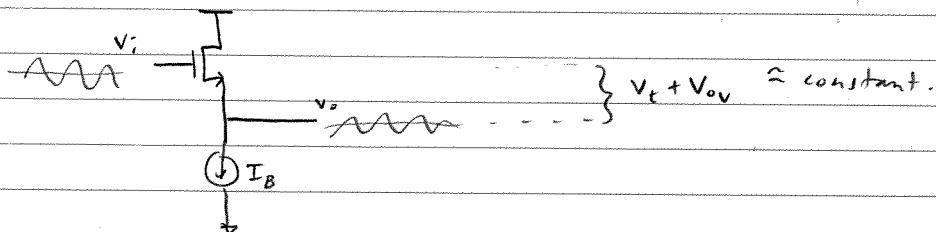


Equivalent circuit for $R_i > \frac{1}{g_m}$

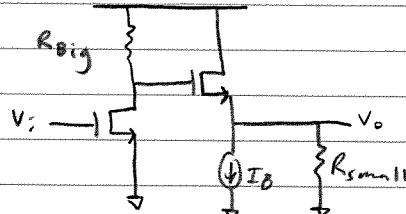


This circuit is prone to ringing! Forms an LC tank with any capacitance at the output.

Application 1: Level Shifter:



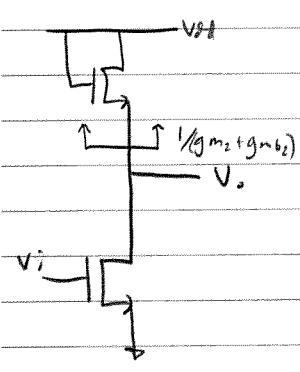
Application 2: Voltage Buffer



Issues: Nonlinearity - V_t , function of V_o (Body Effect)
 I_D and thus V_{ov} changes with V_o , (gets worse for small R_L)

Reduced input & output swing.

Application 3: Load Device:



Advantages:

- Ratiometric (reduced PVT)
- First order cancellations of nonlinearities.

Disadvantage:

- Reduced swing.

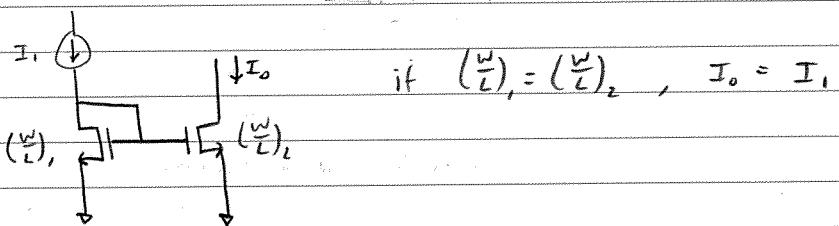
L12 - PVT

if Temperature ↑, R_{nwell} ↑, R_{poly} ↑, $\mu_{Cox} \downarrow$, $C_{poly} \downarrow$, $V_t \downarrow$

Pelgrans Rule:

$$\sigma_{\Delta x} = \frac{A_x}{\sqrt{WL}}$$

L13 - Current Mirrors



Want to:

- Minimize error between I_o and I_i

- Maximize R_{out}

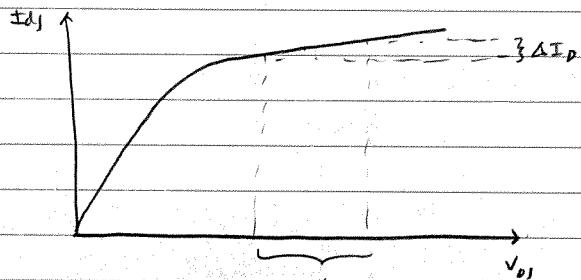
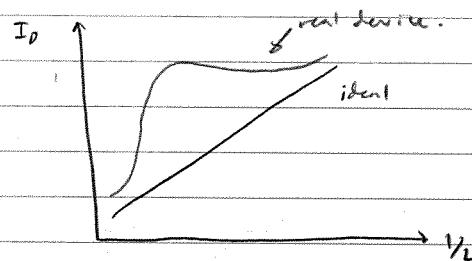
- Minimize V_{DDQ} , V_i

- Minimize C_o

Can scale by changing ratio of $(\frac{W}{L})_2$ and $(\frac{W}{L})_1$ \Rightarrow if $I_o = k I_i$,

$$k = \frac{(\frac{W}{L})_2}{(\frac{W}{L})_1}$$

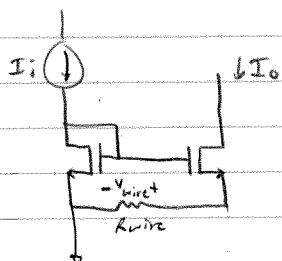
usually, we scale W , not L . Since $L_{eff} \neq L$ and it is more variable.



$$\epsilon = \frac{I_o - I_i}{I_i} = \frac{\Delta V_{DS} \cdot g_{ds}}{I_i} \approx \lambda V_{DS}$$

$$\Rightarrow \boxed{\epsilon = \lambda V_{DS}}$$

$$\lambda \propto \frac{1}{L} \Rightarrow \boxed{\begin{array}{l} \text{to reduce } \epsilon \\ \text{use large } L \end{array}}$$



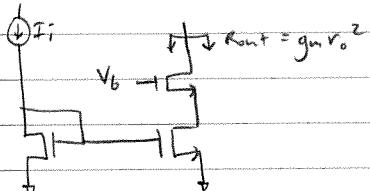
$$\epsilon = \frac{\Delta I}{I_i} \approx \frac{g_m V_{wire}}{I_i} \approx$$

$$\frac{2 V_{wire}}{V_{ov}} = \epsilon$$

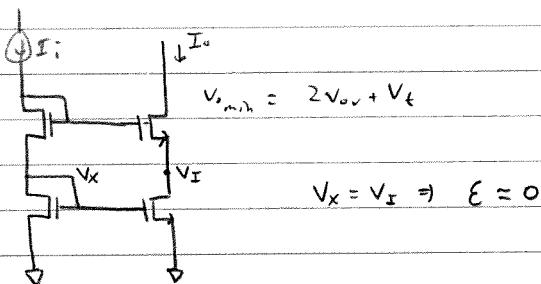
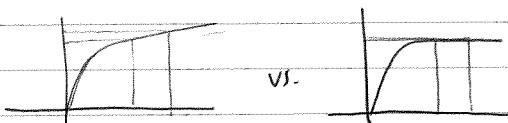
to reduce ϵ
increase V_{ov}

, but this reduces
output swing
(Increase $V_{o_{min}}$).

Can use Cascode to increase R_o :



want high R_o to minimize
 ϵ due to ΔV_{ds}

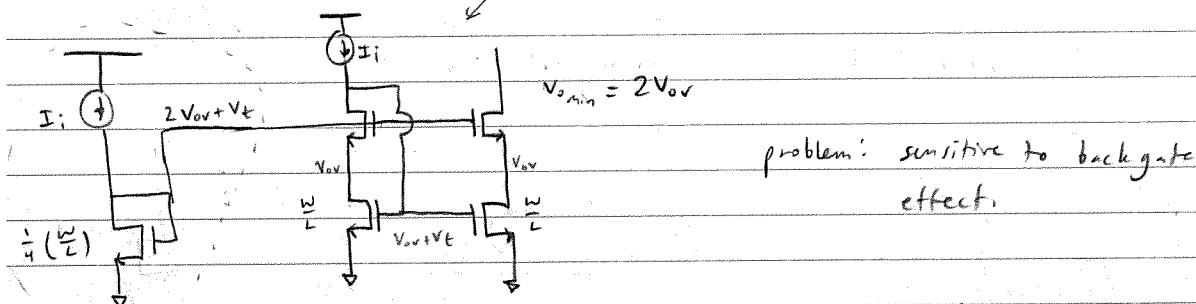


$$V_{o_{min}} = 2 V_{ov} + V_t$$

$$V_x = V_x \Rightarrow \epsilon \approx 0$$

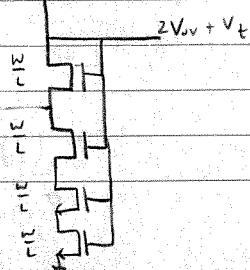
To reduce $V_{o_{min}}$:

requires that $V_t > V_{ov}$ (which is usually true)

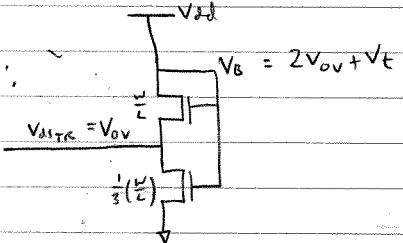


To reduce back-gate effect replace this with:

but requires a lot of headroom (high V_{in})



Typically, people will use this instead:

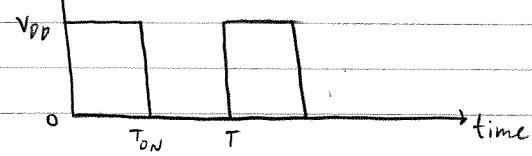


sensitive to backgate effect, but requires less headroom at input.
(lower V_{in}).

$$V_{ds,TR} = (\sqrt{k+1} - 1) V_{ov} \quad V_B = \sqrt{k+1} V_{ov} + V_T = V_{ds,TR} + V_{ov} + V_T$$

Quans Wong 2009

$$V_{in} \uparrow \quad \text{duty cycle} = \frac{T_{on}}{T}$$



$$\text{F.S. } C_n = \frac{1}{T} \int_0^T f(t) e^{-2\pi i n t / T} dt$$

$$= \frac{V_{dd}}{T} \int_0^{DT} e^{-2\pi i n t / T} dt = \frac{V_{dd}}{T} \left(-\frac{T}{2\pi i n} e^{-2\pi i n t / T} \right]_0^{DT}$$

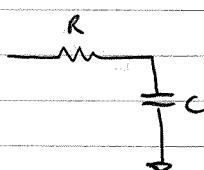
$$= V_{dd} \left(-\frac{1}{2\pi i n} (e^{-2\pi i n D} - 1) \right)$$



$$= \frac{V_{dd}}{2\pi i n} (1 - e^{-2\pi i n D}) \quad \text{for } n \neq 0$$

$$\text{for } n=0, \quad C_0 = \frac{1}{T} \int_0^T f(t) dt = V_{dd} \cdot D \quad \leftarrow \text{DC component} \\ (\text{This is what we want})$$

Design a circuit such that the periodic input waveform shown, the output is approximately a DC voltage of $V_{dd} \cdot \text{Duty cycle}$.

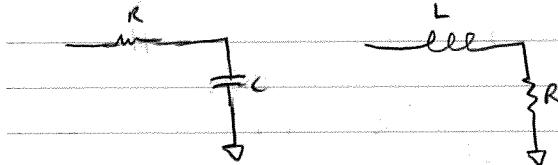


$$\frac{1}{2\pi R C} \ll \frac{1}{T} \Rightarrow R C \gg \frac{T}{2\pi}$$

If the output has to drive a heavy load, ($I=1A$), how would you modify your circuit?

for RC

need R_{out} small \Rightarrow need huge C.



$$\frac{R}{R + j\omega L} = \frac{1}{1 + j\omega \frac{L}{R}}$$

$$\Rightarrow \omega_{3dB} = \frac{R}{2\pi L}$$

for LR, need $\frac{R}{2\pi L} \ll \frac{1}{T} \Rightarrow$ need $\frac{L}{R} \gg \frac{T}{2\pi}$

\Rightarrow can use small R. \Rightarrow lower R_{out} \Rightarrow can drive heavy load.

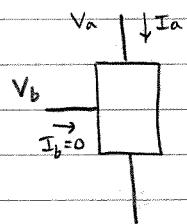
Answer:

Could also use LC filter (adding R_{load} will reduce peaking)

$$\frac{1}{sC} = \frac{1}{1 + s^2 LC} \quad 2 \text{ poles at } \frac{1}{2\pi\sqrt{LC}} \ll \frac{1}{T}$$
$$\Rightarrow LC \gg \left(\frac{T}{2\pi}\right)^2$$

or could add a unity gain voltage buffer.

Quals - Dutton 2007



$$I_a = \left(V_b + \frac{V_a}{10}\right)^2 = V_b^2 + \frac{V_a V_b}{5} + \frac{V_a^2}{100}$$

$$g_m = \frac{\partial I}{\partial V_b} = 2V_b + \frac{V_a}{5}$$

$$g_{ds} = \frac{\partial I}{\partial V_a} = \frac{V_b}{5} + \frac{V_a}{50} = \frac{10V_b + V_a}{50} \Rightarrow V_o = \frac{50}{10V_b + V_a} = \frac{50}{5g_m} = \frac{10}{g_m}$$

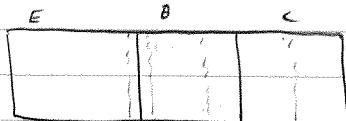
$$\Rightarrow \text{intrinsic gain} = g_m V_o = g_m \frac{10}{g_m} = 10$$

Device -

Ch 11 + Ch 12 BJT Nonidealities

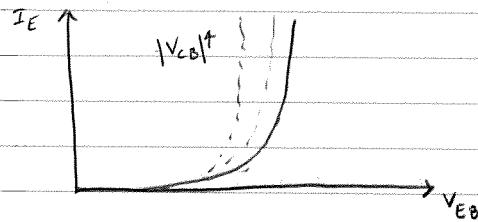
Ch. 11 - BJT Nonidealities.

1) Base Width Modulation ("Early Effect")

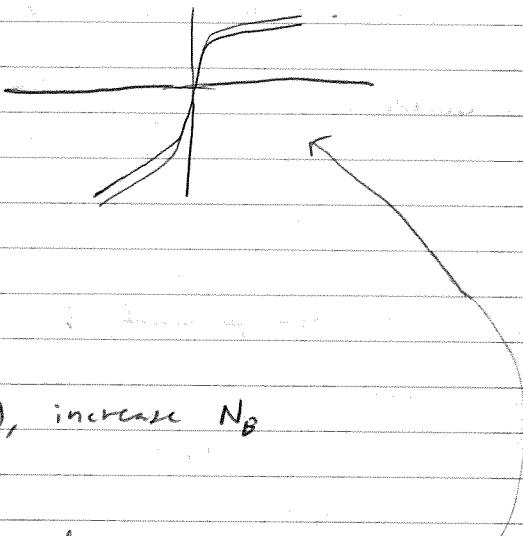
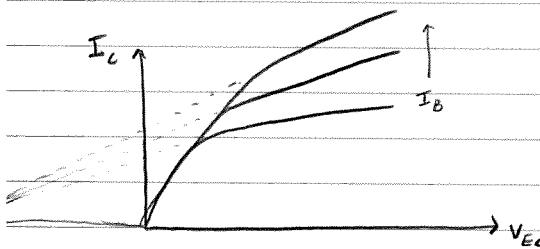


if we change V_{CB} so as to increase the reverse bias, w will change.

w goes to neutral region.



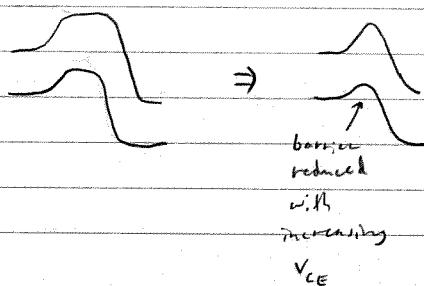
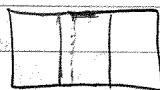
input characteristic of CB.



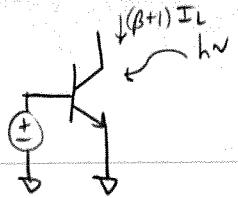
To reduce early effect (Base width modulation), increase N_B (Doping of Base).

This effect is also much worse in Inverted mode, since B-E becomes reverse biased. + $N_E \gg N_B \Rightarrow$ depletion region is larger.

2) Punch Through - when depletion regions touch each other ($w \rightarrow 0$) we observe punch through.

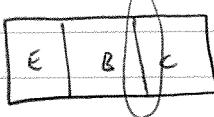


I can cause breakdown if some other breakdown mechanism doesn't occur first.



3) Breakdown

- Common Base



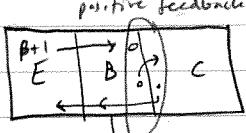
↓ this junction

V_{CB0}

typically breaks down (avalanche or punch through)
since it is the junction that

is reverse biased in active mode.

- Common Emitter



breakdown voltage

Thru., V_{CEO} smaller than
for common base. (V_{CB0})

(carrier multiplication + internal
feedback mechanism, or punch through)

in active mode,

B-E is forward biased

Base current
is constant.

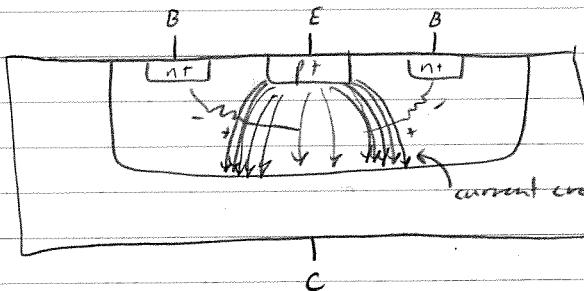
$\Rightarrow V_{BE}$ is small

for CE configuration.

$\Rightarrow V_{CE} = V_{CB} + V_{BE} \approx V_{CB}$

Can be used as a photodetector if you shine light on
the depletion region of B-C. Should multiply photocurrent by $\beta+1$.

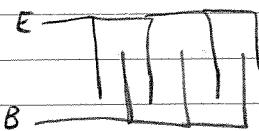
4) Geometrical Effects



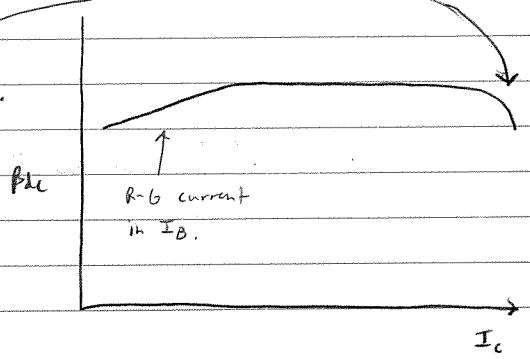
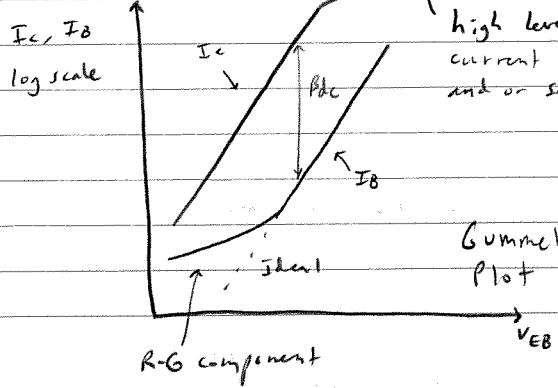
reduces current and
current crowding - can cause local heating

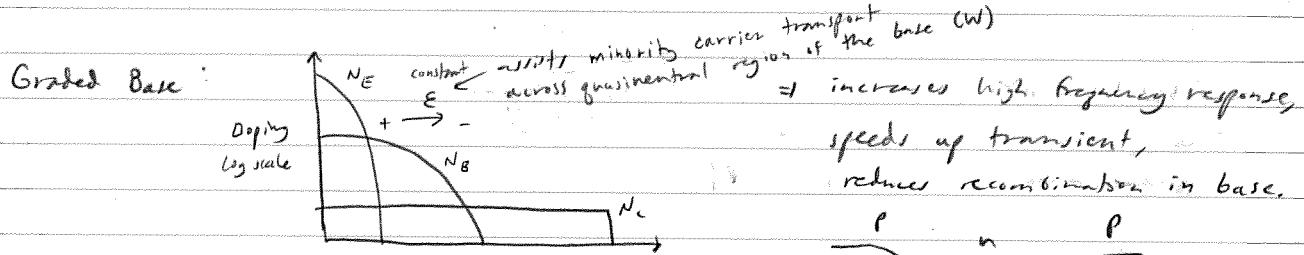
solutions: - increase N_B ↑ to reduce parasitic resistance r_b .

- interdigitate E and B.

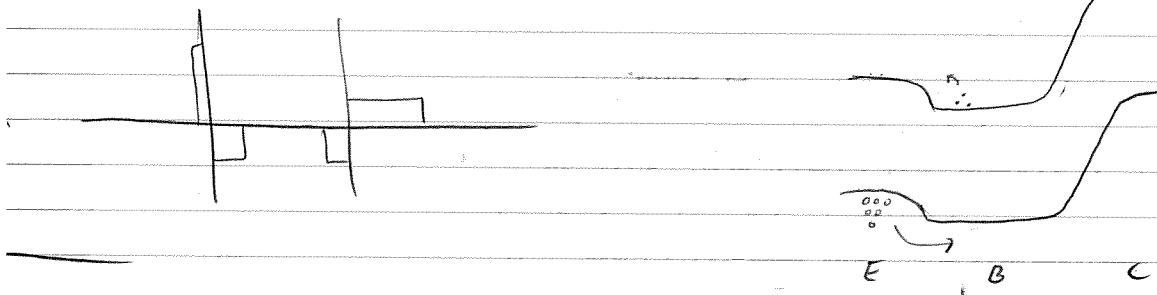


ideal



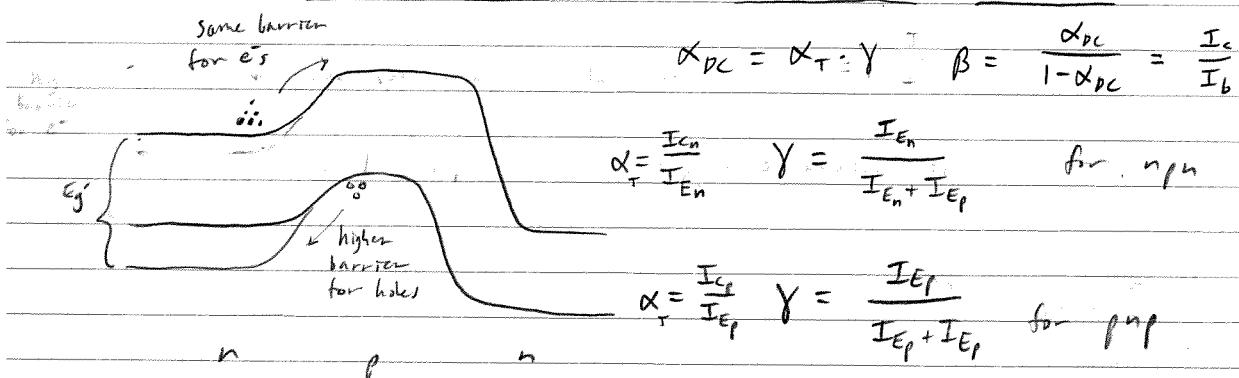


Kirk Effect (Base Expansion) : ???



if Emitter is degenerately doped, $\gamma = \frac{I_e}{I_h} +$ (emitter efficiency is reduced).
 \uparrow
 \Rightarrow bandgap is reduced, \Rightarrow c^- current is reduced.

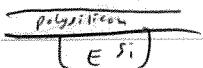
$$\left\{ \begin{array}{l} \text{degenerate emitter} \\ E_g = \dots \end{array} \right. \Rightarrow E_g$$



Heterojunction Bipolar Transistors (HBT)

- using a base material with smaller E_g than the emitter increases emitter efficiency and allows higher doping of the base.
- Has best high frequency performance
- semiconductor materials must be lattice-matched to minimize defects at the interface (e.g. AlGaAs/GaAs) \uparrow reduces parasitic resistance and early effect.

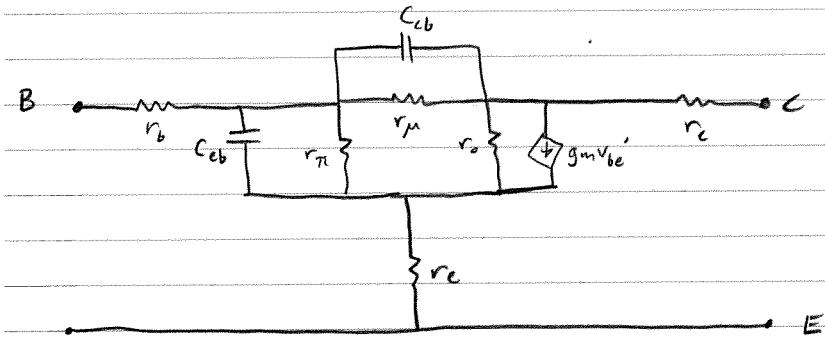
- Polysilicon emitter BJT.



increases emitter efficiency $\gamma \uparrow$

Ch. 12 - BJT Dynamic Response Modeling.

small signal model (Hybrid Pi)

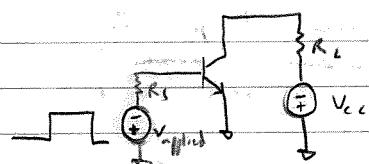


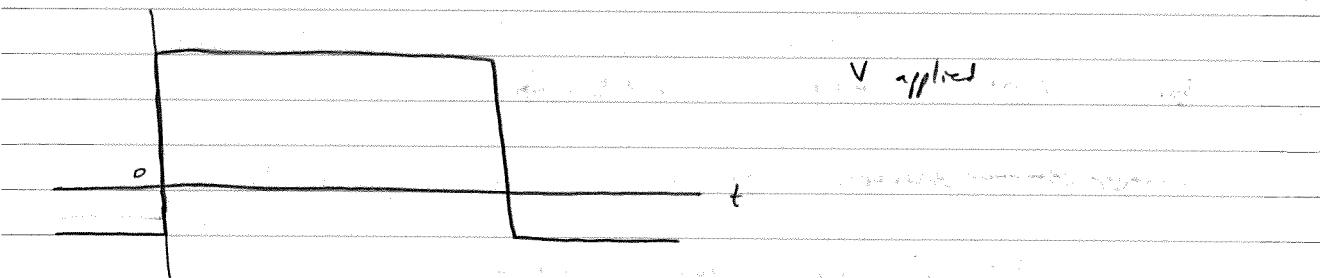
$$g_m = \frac{I_c}{V_T} \quad (V_T = \frac{kT}{q})$$

$$r_\pi = \left(\frac{I_B}{V_T} \right)^{-1} = \frac{\beta R_c}{g_m}$$

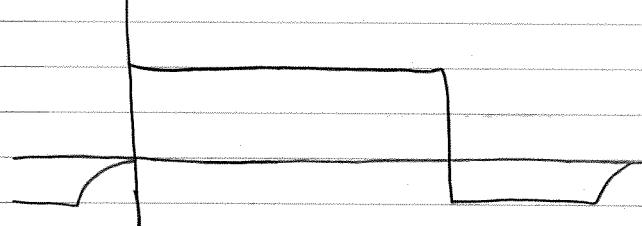
How to increase speed: $W \uparrow$, $N_B \uparrow$ ($\Rightarrow r_b \downarrow$),
reduce size of PN junctions $\Rightarrow C \downarrow$

Transient (switching) Response (Between Sat and Cut-off)

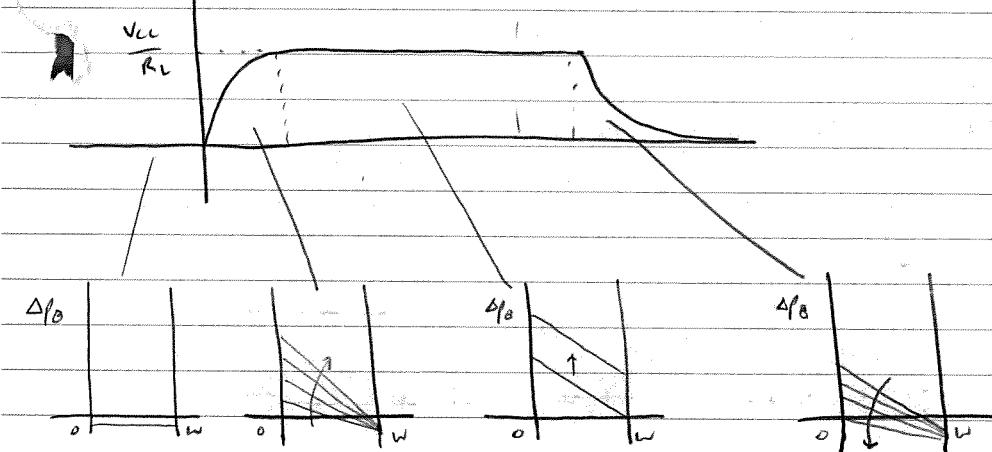




i_B



i_C



To Speed up transient Turn ON: Place cap in parallel with R_S . The discharge of this cap

To Speed up transient Turn OFF: provides a pulse of current that accelerates the build up of stored charge and reduces the time to saturation.

- 1) introduce trap states (Au, for example) to increase recombination rate of minority carriers.



- 2) use schottky diode clamped n-p-n transistor

clamps C-E junction to a low positive voltage.

⇒ limits number of minority carriers in base during on state. Also, schottky diode itself has very little minority carrier charge storage.

11.3.1 MOS vs. BJT for switching.

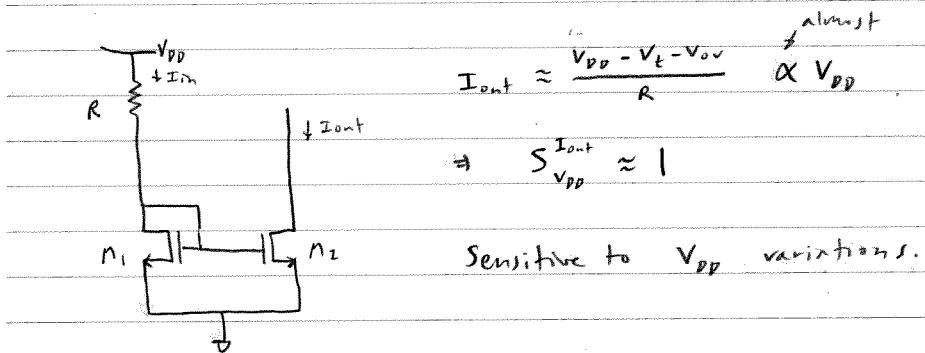
Cmos - Low power dissipation, high packing density

But BJT - can supply several times the drive current of an equal size MOS transistor

⇒ faster switching of large capacitive loads.

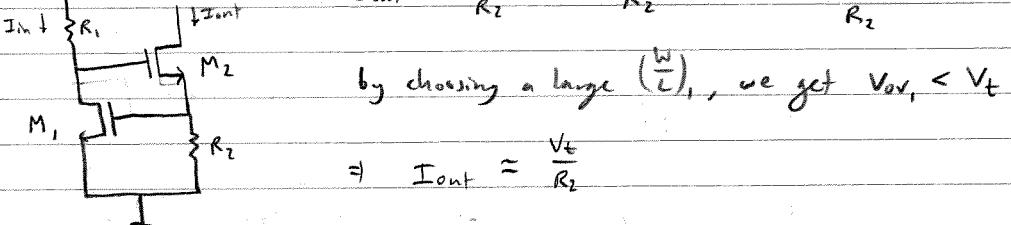
Bicmos - used when you need BJTs for high-load, high-speed portions of predominantly CMOS circuitry.

Circuits - Alex L14-L15 Supply insensitive bias current generation
Voltage biasing considerations.



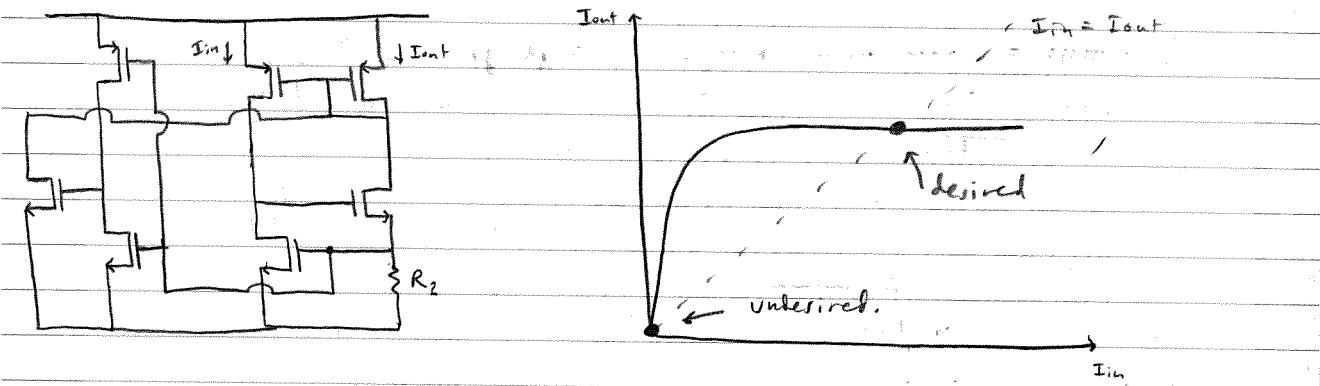
V_t - referenced bias:

$$I_{out} = \frac{V_{GS1}}{R_2} = \frac{V_t + V_{ov}}{R_2} = \frac{V_t + \sqrt{\mu C_o (\frac{W}{L})}}{R_2}$$



$$S_{V_{DD}}^{I_{out}} = S_{V_{DD}}^{I_{in}} \cdot S_{I_{in}}^{I_{out}} \approx 1 \cdot \frac{I_{in}}{I_{out}} \cdot \frac{\delta I_{out}}{\delta I_{in}} = \frac{1}{2} \frac{V_{ov}}{V_t + V_{ov}} \approx 11.5\% \text{ for } V_{ov} = 0.15V, V_t = 0.5V$$

Self Biasing / Start-up Circuits: 2 stable operating points.



ΔV_{GS} Reference (Constant g_m reference)

The diagram shows a circuit with two NMOS transistors, M₁ and M₂, connected in series with a resistor R₂. The drain of M₁ is connected to the gate of M₂. The source of M₂ is connected to ground. The drain of M₂ is the output current I_{out}. The input current I_{ref} is applied to the gate of M₁. A 'Start up circuit' is shown at the bottom. The voltage across R₂ is labeled ΔV. The equations derived are:

$$\begin{aligned} \Delta V &= I_{ref} \cdot R_2 = V_{GS1} - V_{GS2} = V_{OV1} - V_{OV2} \\ &= V_{OV1} \left(1 - \frac{1}{m}\right) \\ \Rightarrow I_{ref} &\approx \frac{V_{OV1} \left(1 - \frac{1}{m}\right)}{R_2} \end{aligned}$$

Why is this useful? $g_{m1} = \frac{2I_{ref}}{V_{OV1}} \Rightarrow g_{m1} = \frac{2\left(1 - \frac{1}{m}\right)}{R_2}$

$\Rightarrow g_m$ independent of T and V_{dd} variations.

- use large V_{ov} to reduce Mismatch errors.

- minimize I_{ref} · R₂ to reduce sensitivity to backgate effect.

V_{BE} Reference

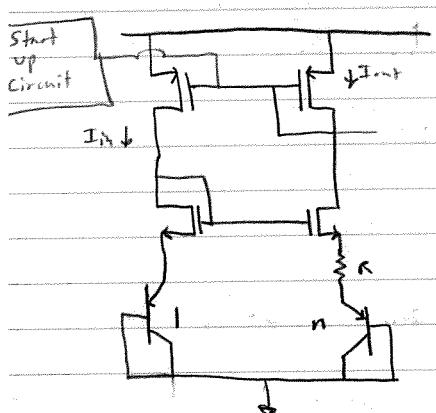
The diagram shows a circuit with two NMOS transistors, M₁ and M₂, connected in series with a resistor R. The drain of M₁ is connected to the gate of M₂. The source of M₂ is connected to ground. The drain of M₂ is the output current I_{out}. The input current I_{ref} is applied to the gate of M₁. The voltage across R is labeled V_{BE}. The equations derived are:

$$\begin{aligned} I_{out} &= \frac{|V_{BE}|}{R} \\ TC_F &= \frac{\left(\frac{\partial I_{out}}{\partial T}\right)}{I_{out}} \frac{1}{K} \quad \frac{\partial V_{BE}}{\partial T} \approx -2mV/K \\ &\approx -0.53\% / K \end{aligned}$$

↑
not very good ($\sim 53\%$ at $\Delta T = 100K$)

\uparrow same as $^{\circ}C$

ΔV_{BE} Reference

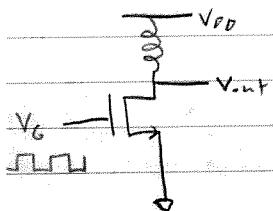


$$I_{out} = \frac{1}{K} \frac{kT}{q} \ln(n)$$

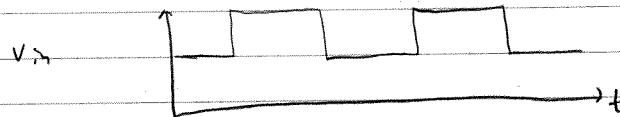
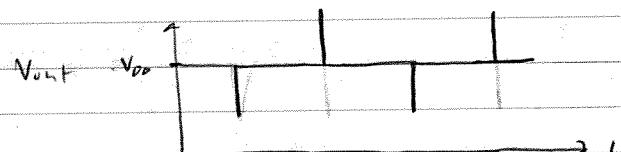
$$TC_F = 0.13\% / K \quad \leftarrow \text{a little better.}$$

TC of resistor and $\frac{kT}{q}$ partially cancel.

Questions - Quals Kovacs 2006

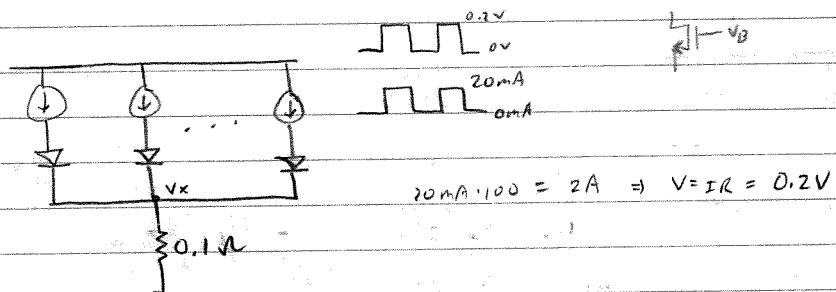


$$V = L \frac{dI}{dt}$$

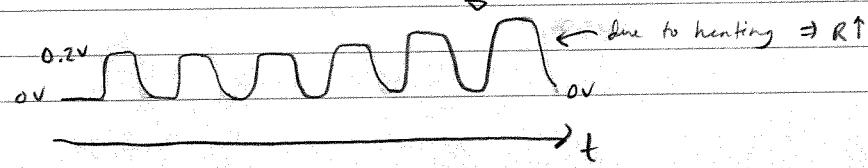


$$\frac{V_{out}}{V_{in}} = -g_m s L \Rightarrow \text{differentiator.}$$

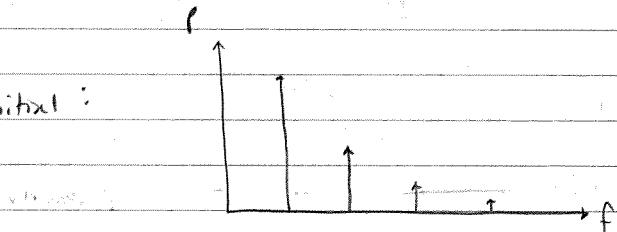
Kovacs - 2005



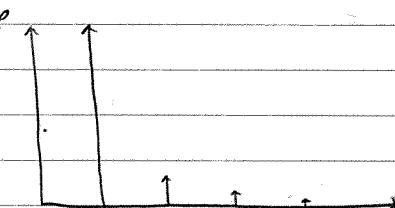
$$20\text{mA} \cdot 100 = 2\text{A} \Rightarrow V = IR = 0.2\text{V}$$



power spectrum: initial:



after 1 minute:



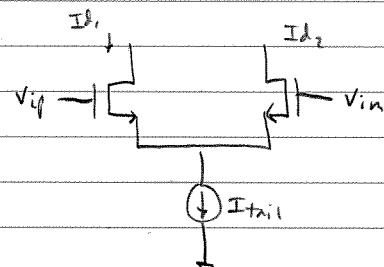
more total power.

but perhaps slightly less square, due to increased RC time constant
= more lowpass filtering.

Circuits:

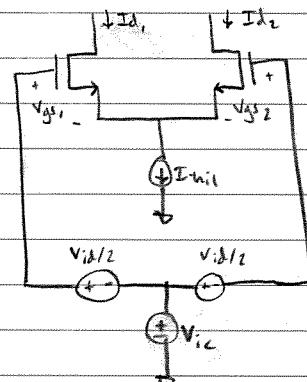
L16 - L18 differential pair + multi-stage amps.

L16 - Differential pair



$$V_{id} = V_{ip} - V_{im}$$

$$V_{ic} = \frac{V_{ip} + V_{im}}{2}$$



$$V_{ip} - V_{gs1} = V_{im} - V_{gs2}$$

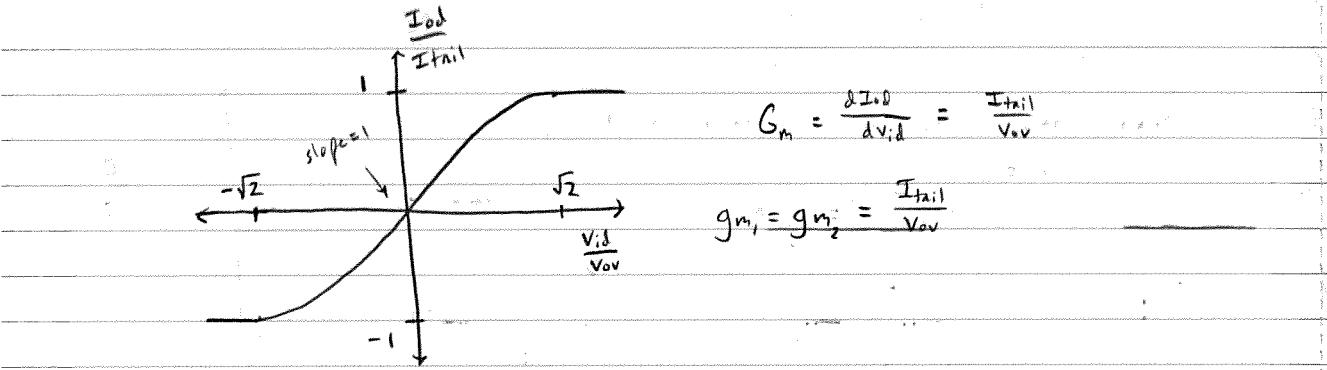
$$I_{d1} + I_{d2} = I_{tail}$$

$$V_{gs1} = V_t + \sqrt{\frac{2I_{d1}}{\mu C_{ox} \frac{W}{L}}} \quad V_{gs2} = V_t + \sqrt{\frac{2I_{d2}}{\mu C_{ox} \frac{W}{L}}}$$

$$I_{od} = I_{d1} - I_{d2} = \frac{1}{2} \mu C_{ox} \frac{W}{L} V_{id} \sqrt{\frac{4I_{tail}}{\mu C_{ox} \frac{W}{L}}} - V_{id}^2$$

$$\text{for } V_{id} = 0, \frac{I_{tail}}{2} = \frac{1}{2} \mu C_{ox} \frac{W}{L} V_{ov}^2$$

$$\Rightarrow \frac{I_{od}}{I_{tail}} = \frac{V_{id}}{V_{ov}} \sqrt{1 - \left(\frac{V_{id}}{2V_{ov}}\right)^2}$$

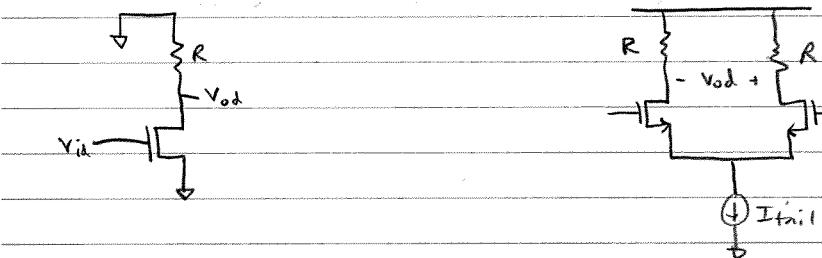


$$G_m = \frac{dI_{dS}}{dV_{dS}} = \frac{I_{tail}}{V_{ov}}$$

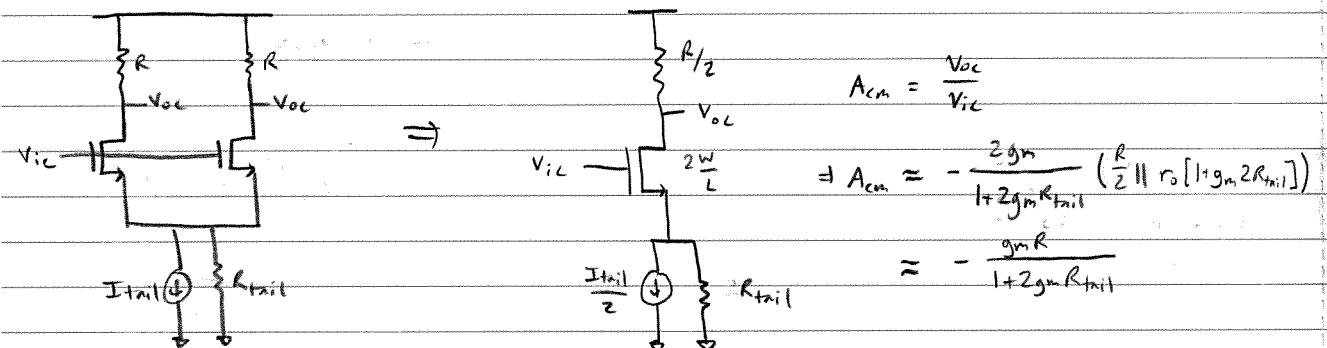
$$g_{m1} = g_{m2} = \frac{I_{tail}}{V_{ov}}$$

$$V_x = V_{ds} - V_t - V_{ov} \sqrt{1 - \frac{1}{4} \left(\frac{V_{ds}}{V_{ov}} \right)^2} \Rightarrow V_x \text{ is an AC ground}$$

Small Signal Half Circuit:



Common Mode Gain



$$CMRR = \left| \frac{A_{dm}}{A_{cm}} \right| \text{ ideally } \infty \approx 1 + 2g_m R_{tail} \text{ for this circuit.}$$

(Alternate definition include CMRR = $\left| \frac{A_{dm}}{A_{cm-DM}} \right| = \frac{g_m}{\Delta g_m} (1 + 2g_m R_{tail})$ for a circuit with Δg_m
Power Supply Rejection Ratio: $A_+ = \frac{V_{od}}{V_{ss}}$ $A_- = \frac{V_{od}}{V_{ss}}$ mismatch between M1 + M2

$$PSRR_+ = \left| \frac{A_{dm}}{A_+} \right| \quad PSRR_- = \left| \frac{A_{dm}}{A_-} \right|$$

$$\frac{\mu C_{ox} \frac{W}{L}}{2} = 4mA/V^2 \quad V_t = 1V$$

$$\frac{1}{2} \mu C_{ox} \frac{W}{L} (V_{gs} - V_t)^2 = 0.5mA$$

$$V_{gs} =$$

$$2 - 1.5 = 0.5$$

5V

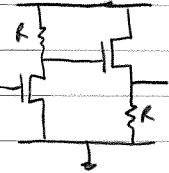
$$T = \sqrt{0.5} = \frac{\sqrt{2}}{2}$$

$$2 - 1.707$$

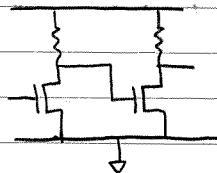
$$1.707$$

$$0.3$$

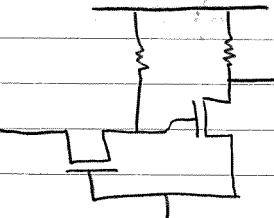
L17 - Multi-Stage Amplifiers (single Ended)



CS-CD



CS-CS



CG-CS

High Rin
Low Rout
Medium Av

High Rin
High Rout
High Av
(Limits for
(cascading))

Low Rin
High Rout
I to V gain (transresistance)
Capacitance at source.

$$(G \text{ Transfer Function: } \frac{i_o}{i_i} \approx \frac{1}{1 + s \frac{C_S}{g_m'}} \text{ for } g_m' R_s \gg 1)$$

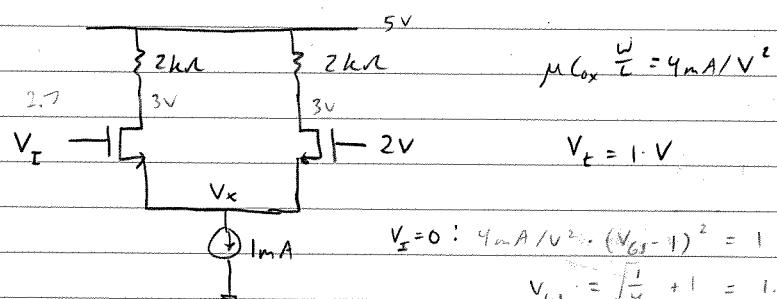
$$\frac{V_o}{V_i} \approx g_m' R_o \quad R_i = \frac{R_o}{g_m' r_o} + \frac{1}{g_m'} \quad (R_o = R_D \parallel (1 + g_m' R_s) r_o)$$

L18 Multi-Stage Amplifiers (Differential)

$$BW_{\text{cascade}} = BW_{\text{stage}} \sqrt{2^{N-1}} \quad \leftarrow \text{Bandwidth shrinkage}$$

Quals Questions

Murmann 2010

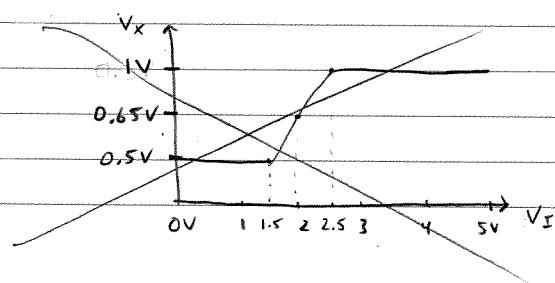


sketch V_x vs. V_i

as V_i ranges from 0-5V

$$V_i=0: 4mA/V^2 \cdot (V_{GS}-1)^2 = 1$$

$$V_{GS} = \sqrt{\frac{1}{4}} + 1 = 1.5V$$



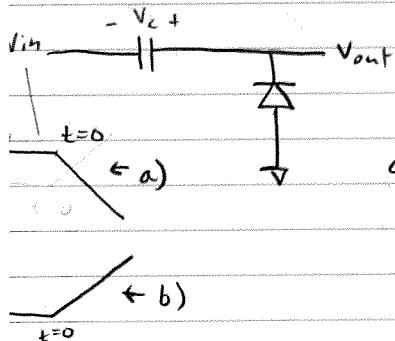
$$V_i=2: V_{GS} = \sqrt{\frac{0.5}{4}} + 1 \approx 1.35V$$

$$V_{ov} = \frac{1}{2\sqrt{2}} \\ \Rightarrow \sqrt{2} V_{ov} = \frac{1}{2}$$

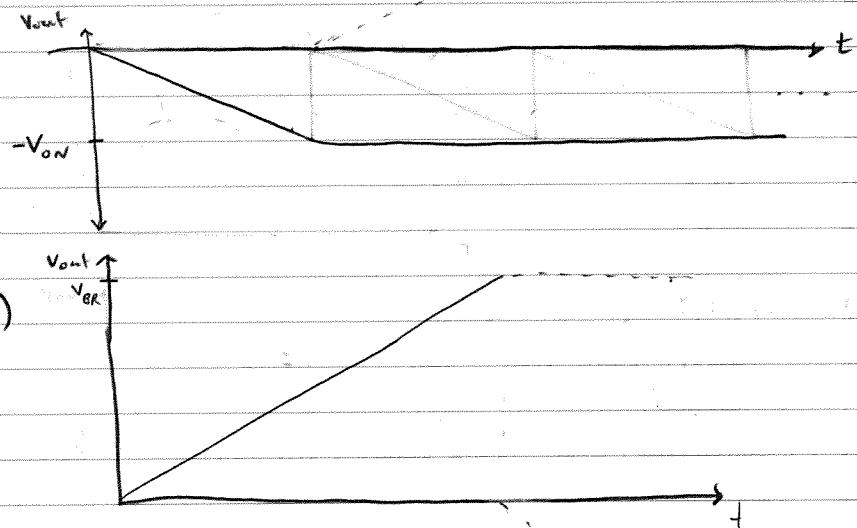
$$V_i = 2.5: V_{GS} = \sqrt{\frac{1}{4} + 1} = 1.5V$$

$$\Rightarrow V_x = 2.5 - 1.5 = 1V$$

$$V_{out} = V_{in} + V_C$$

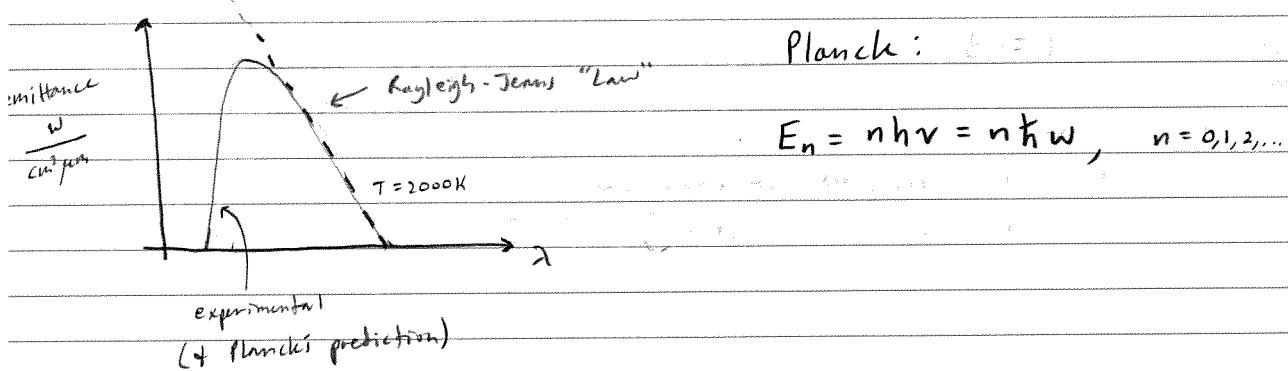


Sketch $V_{out}(t)$ assuming $V_{out}(0) = 0V$



Devices - [REDACTED] - Quantum Mechanics (Ch. 2 Pierret Advanced.)

1. Black body radiation



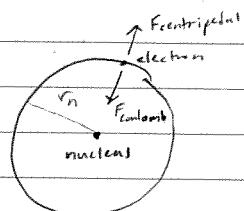
Motivated by discrete spectral emission lines of heated gases. (H, He, etc).

2. Bohr Atom

$$L_n = m_e v r_n = n \hbar$$

↑ ↑
angular momentum electron velocity

$$n = 1, 2, 3, \dots$$



$$F_{\text{centrifugal}} = F_{\text{Coulomb}}$$

$$\frac{m_e v^2}{r_n} = \frac{e^2}{4\pi\epsilon_0 r_n^2} \Rightarrow r_n = \frac{4\pi\epsilon_0 (n\hbar)^2}{m_e e^2}$$

$$E_n = PE + KE = -\frac{e^2}{4\pi\epsilon_0 r_n} + \frac{1}{2} \frac{e^2}{4\pi\epsilon_0 r_n} = -\frac{1}{2} \frac{e^2}{4\pi\epsilon_0 r_n}$$

$$\Rightarrow E_n = -\frac{m_e e^4}{2(4\pi\epsilon_0 \hbar)^2} = -\frac{13.6}{n^2} \text{ eV}$$

← applies for Hydrogen atom.

3. Wave-Particle Duality

$$\text{deBroglie : } p = mc = \frac{E}{c^2} \cdot c = \frac{E}{c} = \frac{h\nu}{c} = \frac{h\nu}{\lambda\nu} = \frac{h}{\lambda}$$

$$\Rightarrow p = \frac{h}{\lambda}$$

4. a) Wave mechanics \rightarrow schroedinger
 b) Matrix mechanics \rightarrow heisenberg } quantum mechanics.

5. 5 postulates of quantum Mechanics i. (time dependent)

① $\Psi = \Psi(x, y, z, t)$

② $-\frac{\hbar^2}{2m} \nabla^2 \Psi + U\Psi = -\frac{\hbar}{i} \frac{\partial \Psi}{\partial t}$

time dependent schrodinger equation

③ $\Psi, \nabla \Psi$ must be finite (bounded), continuous, and single valued for all x, y, z, t .

④ $\Psi^* \Psi dV$ is probability a particle will be found in dV .

$$\Rightarrow \iiint_V \Psi^* \Psi dV = 1$$

⑤ $\langle a \rangle = \int_V \Psi^* a_{op} \Psi dV$ must use the lookup table to find the operator for a given a .

e.g. $\begin{array}{ccc} a & & a_{op} \\ x, y, z & \rightarrow & x, y, z \\ f(x, y, z) & \rightarrow & f(x, y, z) \\ p_x & \rightarrow & \frac{\hbar}{i} \frac{\partial}{\partial x} \end{array}$

$E \rightarrow \frac{\hbar}{i} \frac{\partial}{\partial t}$

Time Independent: particle has constant energy.

$$\boxed{\Psi(x, y, z, t) = \Psi(x, y, z) e^{-iEt/\hbar}}$$

$$\boxed{\nabla^2 \Psi + \frac{2m}{\hbar^2} [E - U] \Psi = 0}$$

1) Free Particle .

$$F = 0, \quad U = \text{constant}, \quad (F = \nabla U) \quad \downarrow \quad \text{set } U = 0$$

1 dimension.

$$\frac{d^2\psi}{dx^2} + \frac{2mE}{\hbar^2} \psi = 0$$

continuous \Rightarrow all wavelengths can exist. E-k plot is continuous.

$$\Rightarrow \psi = A_+ e^{ikx} + A_- e^{-ikx}$$

$$k = \sqrt{\frac{2mE}{\hbar^2}} = \frac{2\pi}{\lambda}$$

$$\Rightarrow \psi(x, y, z, t) = (A_+ e^{ikx} + A_- e^{-ikx}) e^{-iEt/\hbar}$$

$$\boxed{\psi(x, y, z, t) = A_+ e^{i(kx-Et/\hbar)} + A_- e^{-i(kx-Et/\hbar)}}$$

$\xrightarrow{\text{wave } +x}$ $\xleftarrow{-x \text{ wave}}$

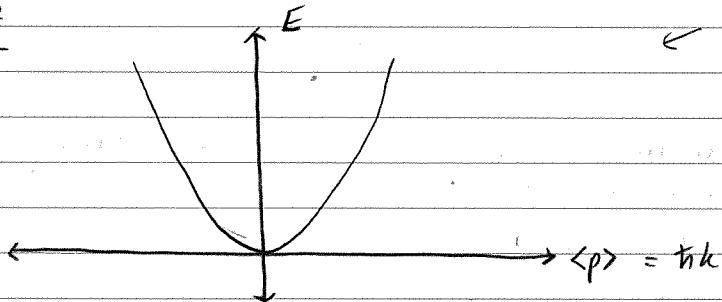
$$\langle p \rangle = \langle p_x \rangle = \int_{-\infty}^{\infty} \psi^* \frac{\hbar}{i} \frac{d\psi}{dx} dx = \int_{-\infty}^{\infty} \psi^* \frac{\hbar}{i} \partial_x \psi$$

$$= \hbar k \int_{-\infty}^{\infty} \psi^* \psi dx = \hbar k \quad \Rightarrow \quad \langle p \rangle = \hbar k$$

$$E = \frac{\hbar^2 k^2}{2m} = \frac{\langle p \rangle^2}{2m}$$

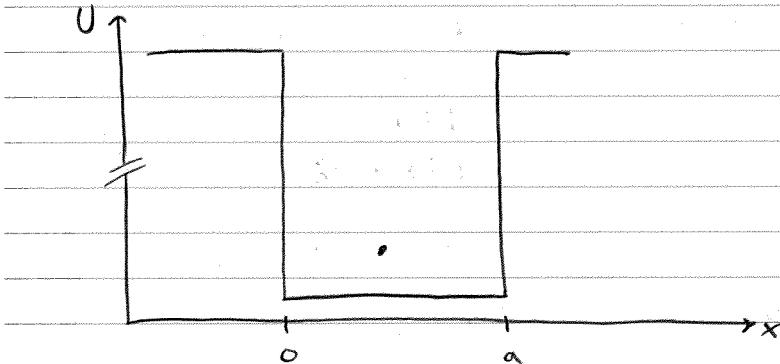
quantizat.

E-k diagram.



\Rightarrow Energy is continuous (not quantized) for an isolated free particle.

2) Particle in an infinite potential well.



m
 E

$$0 < x < a$$

$$U(x) = \text{constant} = 0$$

only discrete wavelengths
that depend on the
dimensions of the well
can exist

$$\psi = A \sin(kx) + B \cos(kx)$$

$$\psi(0) = \psi(a) = 0 \quad (\text{boundary conditions})$$

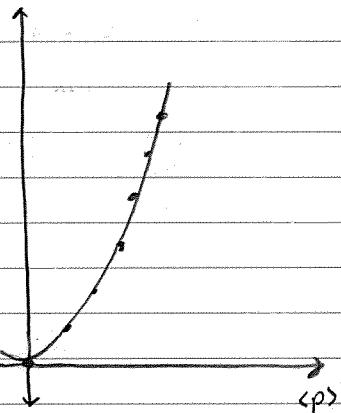
$$\Rightarrow B = 0 \quad \text{due to}$$

$$\psi = A \sin(ka) = 0 \Rightarrow k = \frac{n\pi}{a} \quad n = \pm 1, \pm 2, \pm 3, \dots$$

$$\Rightarrow \psi_n(x) = A_n \sin\left(\frac{n\pi x}{a}\right)$$

$$E = \frac{\hbar^2 k^2}{2m} \Rightarrow E_n = \frac{n^2 \pi^2 \hbar^2}{2ma^2}$$

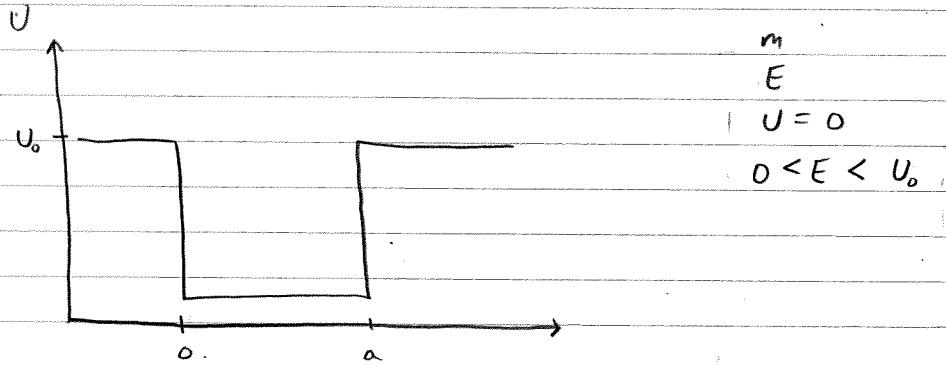
E



E is quantized for
a particle in a box.

(but follows the same exact
parabolic shape as
for a free particle)

3) particle in a finite potential well



$$0 < x < a : \frac{d^2\psi}{dx^2} + k^2\psi_0 = 0 \rightarrow \psi = A_0 \sin(kx) + B_0 \cos(kx)$$

$$k = \sqrt{\frac{2mE}{\hbar^2}}$$

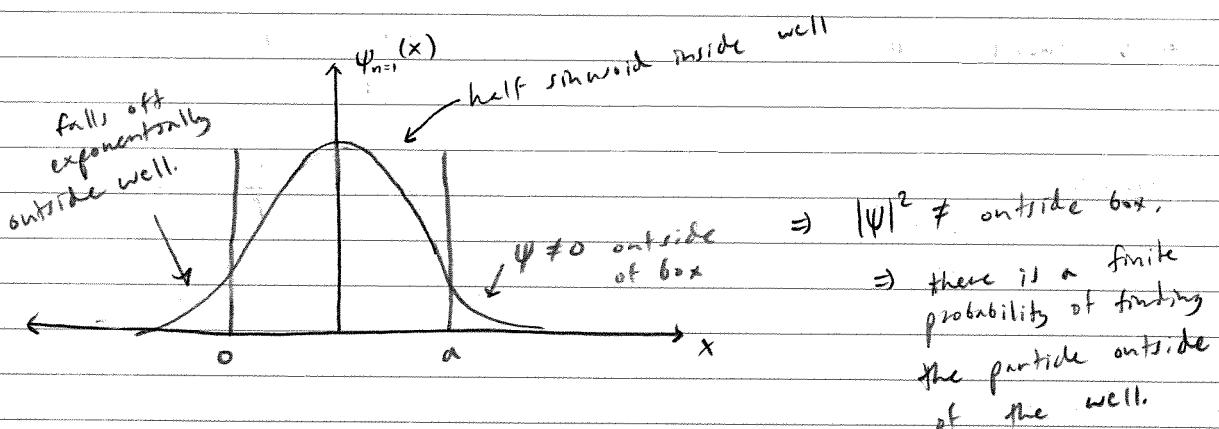
$$x < 0, x > a : \frac{d^2\psi}{dx^2} - \alpha^2\psi = 0 \rightarrow \psi = A_- e^{\alpha x} + B_- e^{-\alpha x}$$

$$\alpha = \sqrt{\frac{2m(U_0 - E)}{\hbar^2}}$$

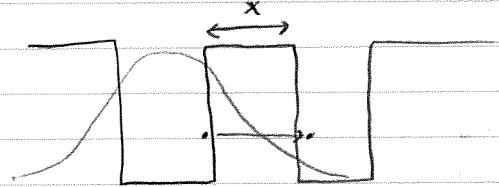
$$\psi_-(-\infty) = 0 ; \quad \psi_+(+\infty) = 0$$

$$\psi_-(0) = \psi(0) ; \quad \psi_+(a) = \psi_+(a)$$

$$\left. \frac{d\psi_-}{dx} \right|_0 = \left. \frac{d\psi}{dx} \right|_0 \quad \left. \frac{d\psi}{dx} \right|_a = \left. \frac{d\psi_+}{dx} \right|_a \quad \text{solve.}$$



This explains tunneling:



if x is small, there is significant probability of tunneling.

Circuits - L19-21 Feedback

$$v_i \rightarrow \sum \rightarrow a \rightarrow v_o$$

$$v_o = a(v_i - fv_o)$$

$$\Rightarrow \frac{v_o}{v_i} = \frac{a}{1+af} = A$$

$a \leftarrow$ Open Loop Gain
 $af \leftarrow$ Loop Gain (T)
 $\frac{a}{1+af} \leftarrow$ Closed Loop Gain

Gain Sensitivity

$$\frac{\Delta A}{A} = \frac{\frac{\Delta a}{a}}{1+af} = \frac{\Delta a}{a(1+T)} \Rightarrow \text{gain sensitivity reduced by } 1+T$$

Linearity:

$$v_i \rightarrow \sum \rightarrow [a_1x + a_3x^3] \rightarrow v_o$$

$$\Rightarrow v_{in} \rightarrow [b_1x + b_3x^3] \rightarrow v_o$$

$$\Rightarrow b_1 = \frac{a_1}{1+af} \quad b_3 = \frac{a_3}{(1+af)^4} \quad \leftarrow \text{cubic nonlinearity reduced by } (1+T)^4 !$$

Bandwidth:

$$v_i \rightarrow \sum \rightarrow a(s) \rightarrow v_o$$

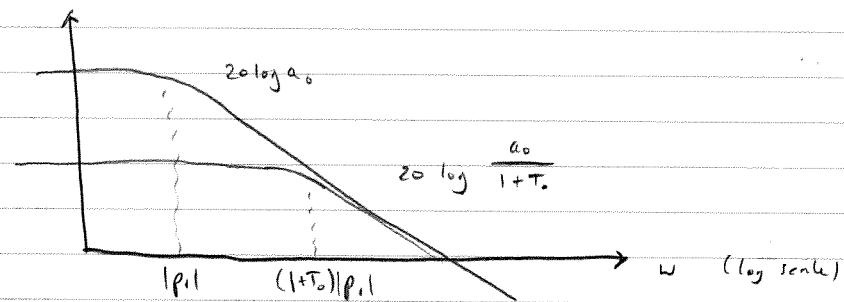
$$a(s) = \frac{a_0}{1 - \frac{s}{p_1}}$$

$$A(s) = \frac{a_0}{1+a_0f} \cdot \frac{1}{1 - \frac{s}{p_1} \left(\frac{1}{1+a_0f} \right)}$$

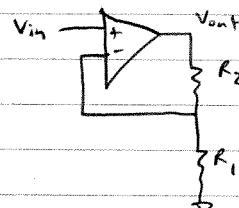
\Rightarrow Bandwidth increases by $(1+T)$

Gain decreases by $(1+T)$... GBW Product is constant,

Gain (dB)



Ex: Non-Inverting Opamp.

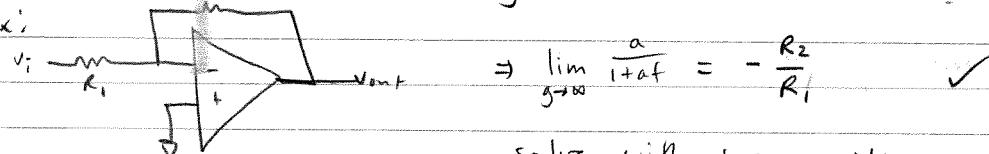


$$f = \frac{R_1}{R_1 + R_2} \quad a = g$$

$$\frac{V_{out}}{V_{in}} = \frac{a}{1+af} = \frac{g}{1+g\frac{R_1}{R_1+R_2}} = \frac{R_1+R_2}{R_1} = 1 + \frac{R_2}{R_1}$$

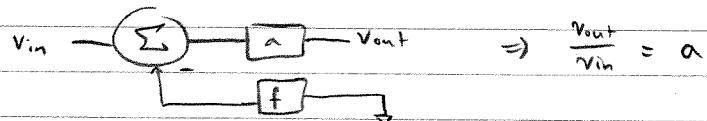
$$a = -\frac{R_2}{R_1+R_2} g \quad af = g \frac{R_1}{R_1+R_2} \quad \frac{a}{1+af} = -\frac{\left(\frac{R_2}{R_1+R_2}\right)g}{1 + \frac{R_1}{R_1+R_2}g}$$

ex:

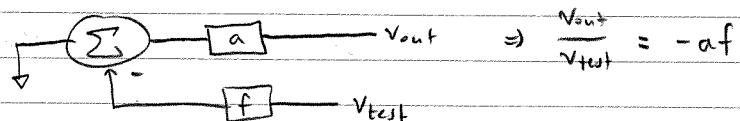


solve with superposition.

Find open loop gain



Find loop gain



Stability: All poles must be in left half plane.

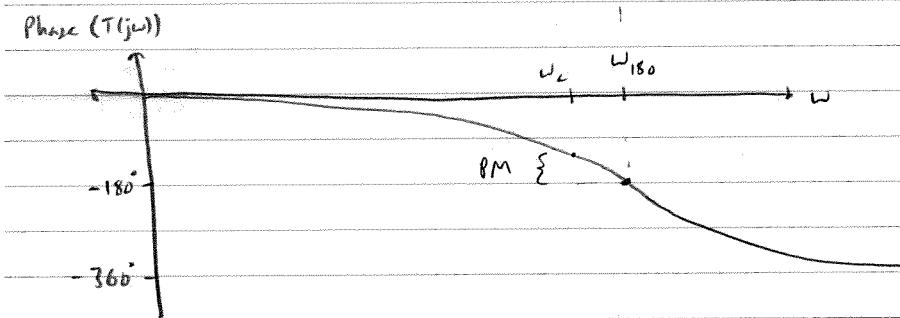
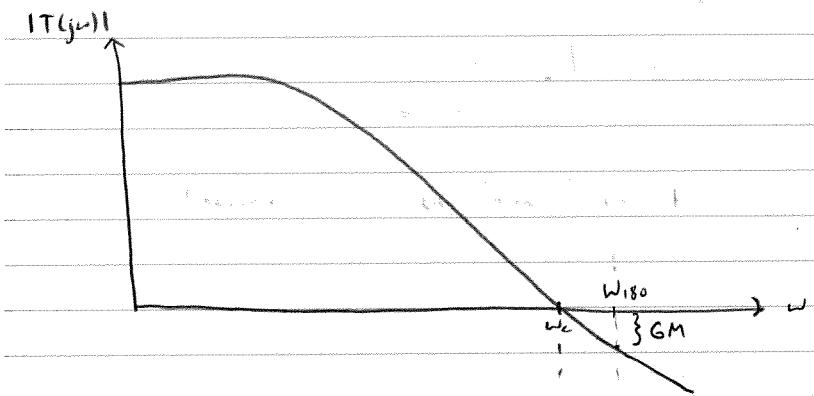
$$GM = \frac{1}{|T(j\omega)|} \Big|_{\omega=\omega_{180}}$$

$$PM = 180^\circ + \text{phase}[T(j\omega)] \Big|_{\omega=\omega_c}$$

Typically want $GM \geq 3 \dots 5$

Typically want $PM \geq 60 \dots 70^\circ$

Bode Criterion : if $|T(j\omega)| > 1$ at ω where $|\text{Phase}(T(j\omega))| = -180^\circ$
system is unstable.



Return Ratio Analysis :

1. Set all independent sources to zero.
2. Disconnect the dependent source from the rest of the circuit which introduces a break in the feedback loop.
3. On the side of the break that is not connected to the dependent source, connect an independent test source s_t of the same sign and type as the dependent source.
4. Find the return signal s_r generated by the dependent source.
5. Return ratio $R = -\frac{s_r}{s_t}$.

A_∞ is transfer function when gain element becomes infinite..

d is transfer function when gain element becomes zero.

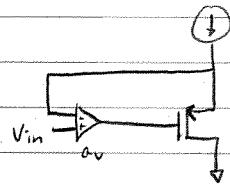
$$A = A_\infty \frac{R}{1+R} + \frac{d}{1+R}$$

Blackman's Impedance Formula

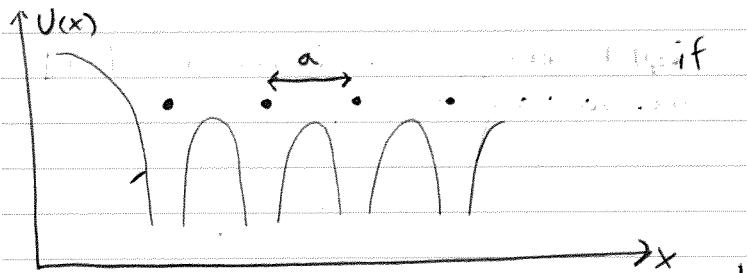
$$Z_{\text{port}} = Z_{\text{port}}(k=0) \frac{1 + R(\text{port shorted})}{1 + R(\text{port open})}$$

- ① Find port impedance with feedback loop broken.
-e.g. set $g_m = 0$ ($k=0$ in model; can also be a_v , etc.).
- ② Calculate loop gain in circuit with port under consideration shorted.
- ③ Calculate loop gain in circuit with port under consideration open.

ex: Bootstrapped Source Follower



Device - [REDACTED] Quantum (Pierret Advanced Ch. 3)



if potential is periodic
function of x is infinite
crystal lattice

Block Theorem: $\psi(x+a) = \psi(x)$ ← unit cell wavefunction with same periodicity as the potential.

$$\psi(x+a) = e^{ika} \psi(x) \quad a \text{ is internatomic distance.}$$

$$\psi(x) = e^{-ika} \psi(r) \quad \begin{cases} \psi(r+a) = e^{ika} \psi(r) & U(r+a) = U(r) \\ \psi(r) = e^{ika} \psi(r) & \text{For 3-D} \\ \psi(r+a) = \psi(r) & \end{cases}$$

In 1-D system, 2 (and only 2) values of k exist for each value of E .

for a given E , values of k differing by a multiple of $\frac{2\pi}{a}$
give rise to the same wave function solution

If the periodic potential or crystal is assumed to be infinite in extent
then k must be real, and can assume a continuum of values.

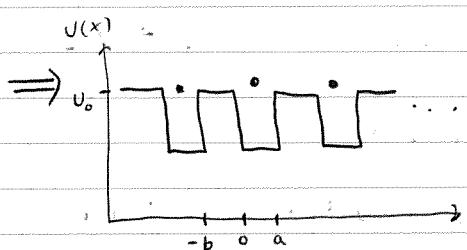
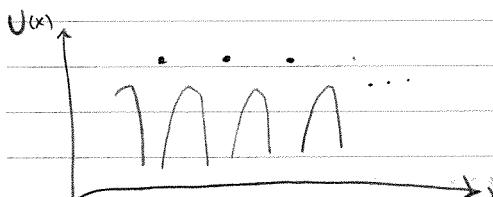
$$\psi(x) = \psi(x+Na) = e^{ikNa} \psi(x)$$



$$\Rightarrow e^{ikNa} = 1 \Rightarrow k = \frac{2\pi n}{Na} \quad n = 0, \pm 1, \pm 2, \dots, \pm \frac{N}{2} \quad -\frac{\pi}{a} \leq k \leq \frac{\pi}{a}$$

Kronig-Penney Model:

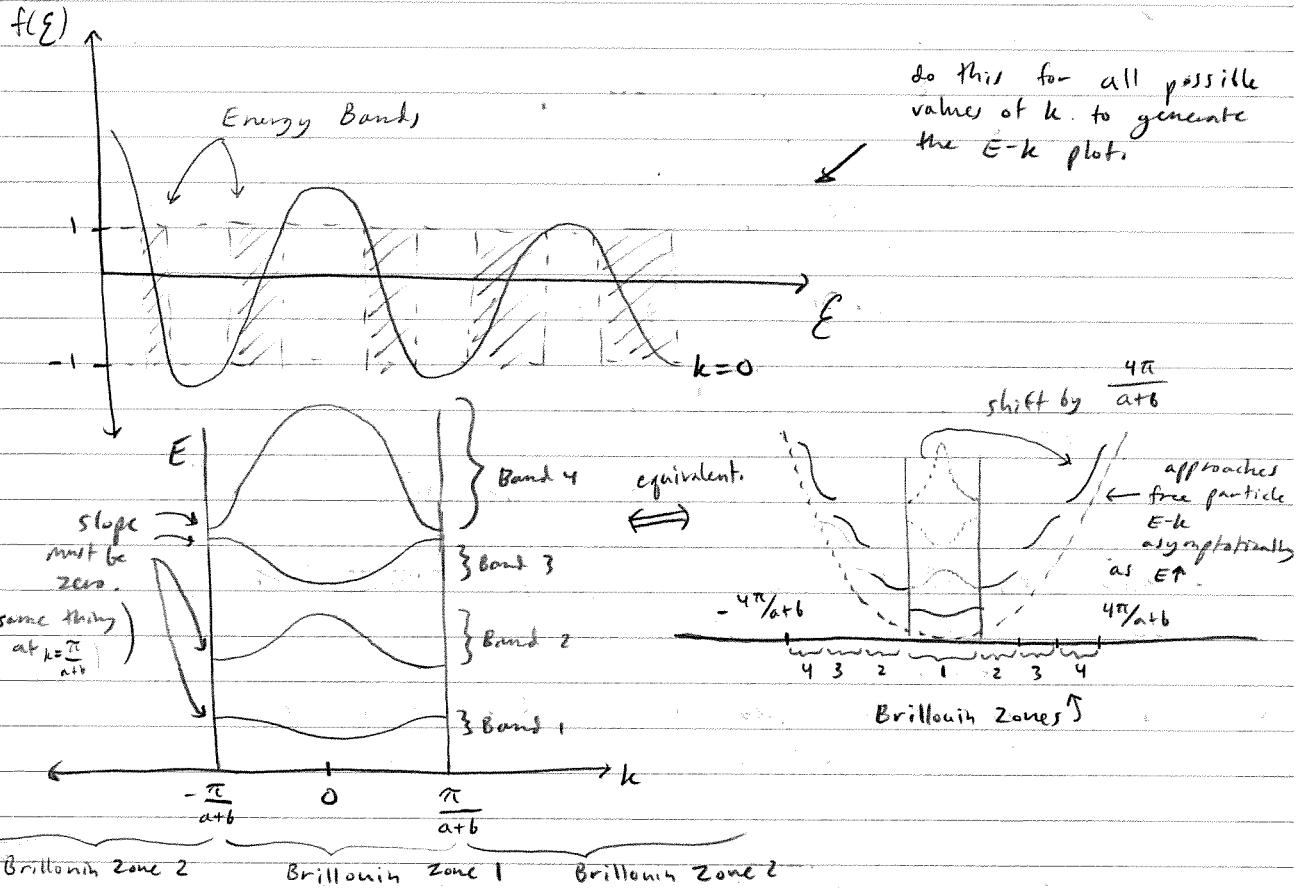
$$U(x)$$



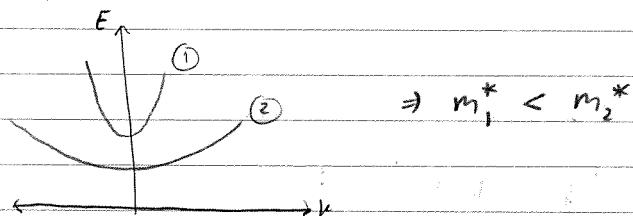
As $N \rightarrow \infty$, $E-k$ becomes approximately continuous.

$$E = \frac{E}{U_0}$$

$f(E) = \cos(k(a+b)) \Rightarrow$ acceptable energy levels E correspond to $|f(E)| \leq 1$

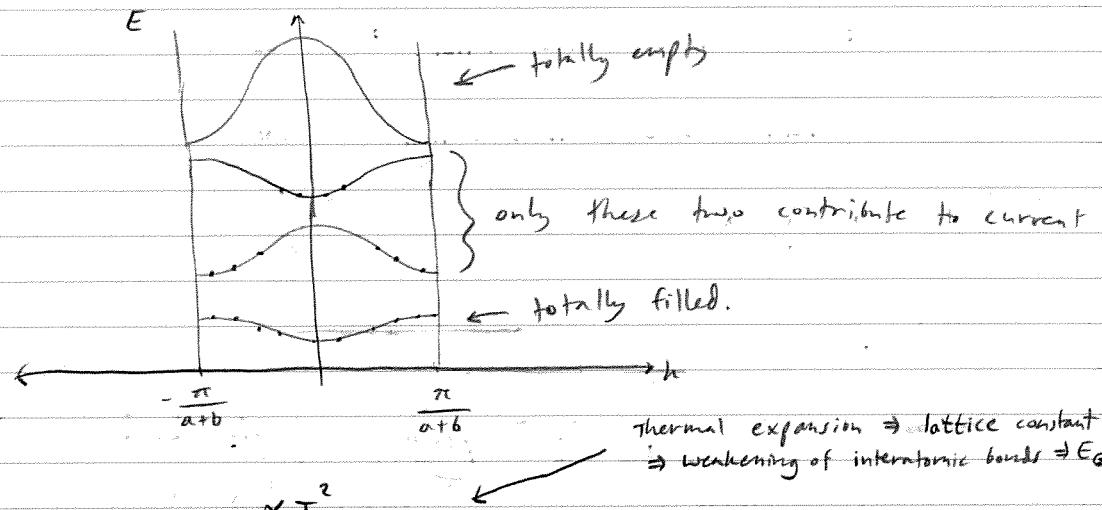


$$v_g = \frac{1}{\hbar} \frac{dE}{dk} \quad \leftarrow \text{group velocity} \quad m^* = \frac{1}{\hbar^2} \frac{d^2E}{dk^2} \quad \leftarrow \text{effective mass.}$$



effective mass is positive near bottom of band and negative near top of band.

Charge Transport: Totally filled or empty bands do not contribute to currents



$$E_G(T) = E_G(0) - \frac{\alpha T^2}{(T+\beta)}$$

thermal expansion \Rightarrow lattice constant \uparrow
 \Rightarrow weakening of interatomic bonds $\Rightarrow E_G \uparrow$

Circuits - Alex 2-Port Feedback Ch. 8 Gray + Meyer

11/23/11

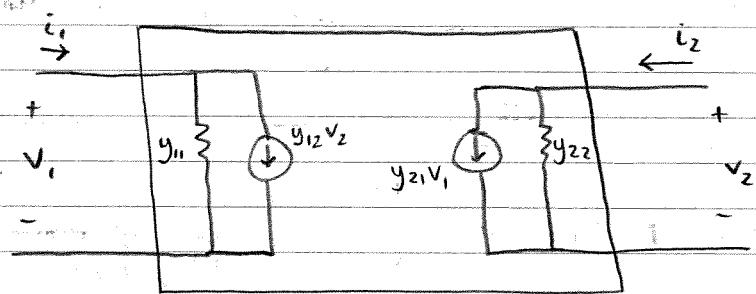
	Shunt	Series
Input	I	V
Output	V	I

Name	Amplifier Type	Z_i'	Z_o'	Feedback Parameter
Series-Shunt	Voltage	$Z_i(1+T)$	$\frac{Z_o}{(1+T)}$	h
Shunt-Series	Current	$\frac{Z_i}{(1+T)}$	$Z_o(1+T)$	g
Shunt-Shunt	Transimpedance	$\frac{Z_i}{(1+T)}$	$\frac{Z_o}{(1+T)}$	y
Series-Series	Transconductance	$Z_i(1+T)$	$Z_o(1+T)$	z

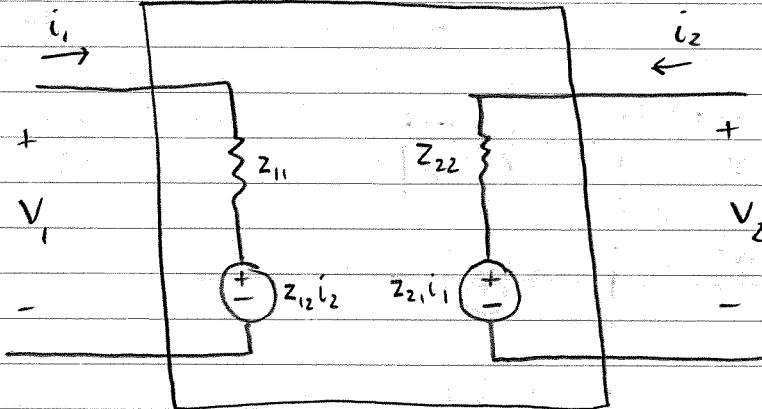
Assumptions for 2-port Model:

- neglect feed forward (i.e. $|y_{21_f}| \ll |y_{21_a}|$)
- neglect feedback through a . (i.e. $|y_{12_f}| \gg |y_{12_a}|$)
- add $(y, z, h, g)_{11}$ and $(y, z, h, g)_{22}$ to input and output (loading effects)

Shunt-Shunt:

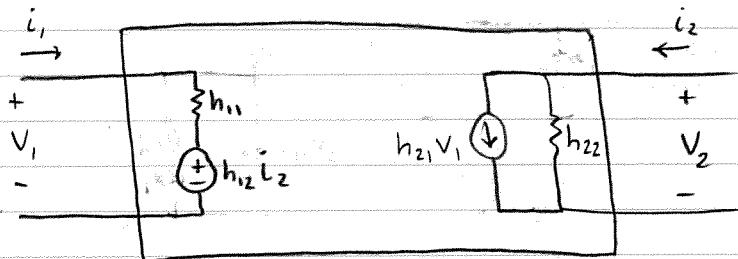


Series-Series:

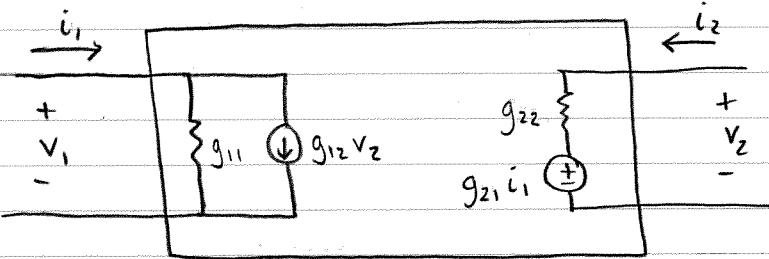


See next page ↗

Series - Shunt:



Shunt - Series:



Circuits: MIT 6.002 L1-L3

12/3/11

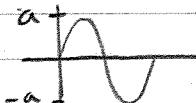
RMS of a periodic function: $f_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T (f(t))^2 dt}$

e.g. sine wave: $f(t) = a \sin(t)$

$$\begin{aligned} f_{\text{rms}} &= \sqrt{\frac{1}{2\pi} \int_0^{2\pi} a^2 \sin^2(t) dt} = \sqrt{\frac{a^2}{2\pi} \int_0^{2\pi} \frac{1}{2}(1 - \cos(2t)) dt} = \sqrt{\frac{a^2}{4\pi} \int_0^{2\pi} 1 - \cos(2t) dt} \\ &= \sqrt{\frac{a^2}{4\pi} \left(t - \frac{1}{2} \sin(2t) \right)_0^{2\pi}} = \sqrt{\frac{a^2}{4\pi} [(2\pi - 0) - (0 - 0)]} = \sqrt{\frac{a^2}{2}} = \frac{a}{\sqrt{2}} \end{aligned}$$

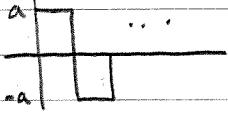
Periodic function

$a \sin(t)$



$$\frac{a}{\sqrt{2}}$$

Square wave



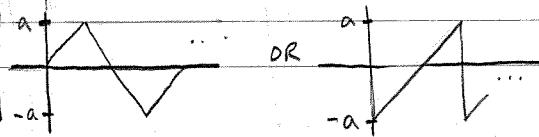
$$a$$

pulse train



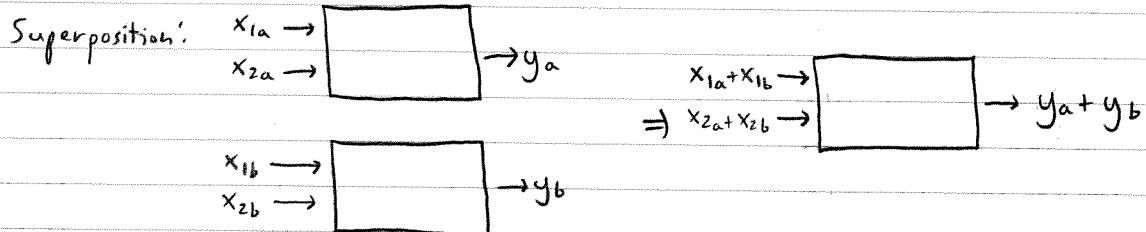
$$a\sqrt{D}$$

triangle or saw

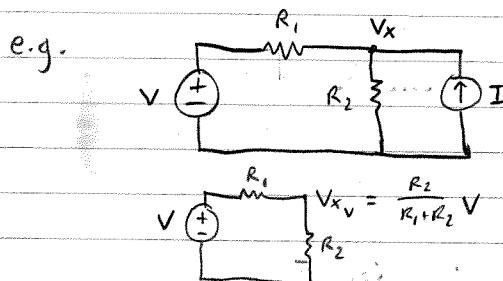


$$\frac{a}{\sqrt{3}}$$

Linearity \Rightarrow Homogeneity
Superposition

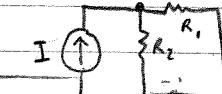


Superposition for circuit analysis: The output of a circuit is determined by summing the responses to each independent source acting alone



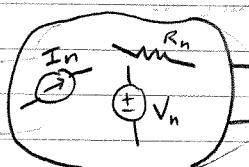
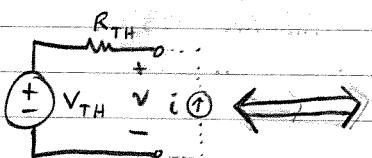
$$V_{x_I} = I \frac{R_1 R_2}{R_1 + R_2}$$

$$V_{x_V} = \frac{R_2}{R_1 + R_2} V$$



$$\Rightarrow V_x = V_{x_V} + V_{x_I} \Rightarrow V_x = \frac{R_2}{R_1 + R_2} V + \frac{R_1 R_2}{R_1 + R_2} I$$

Thevenin and Norton Equivalent:



can replace arbitrary (linear) networks of R, I, V with a Thevenin equivalent:

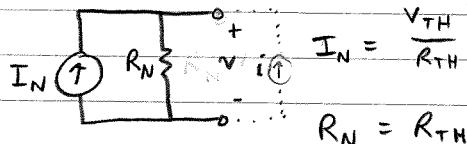
$$v = V_{TH} + i R_{TH}$$

V_{TH} = open circuit voltage.

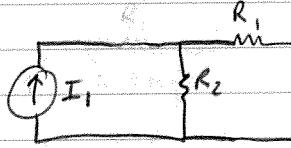
R_{TH} = resistance of network seen from port

(Independent sources set to 0)

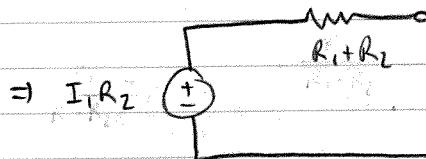
Norton:



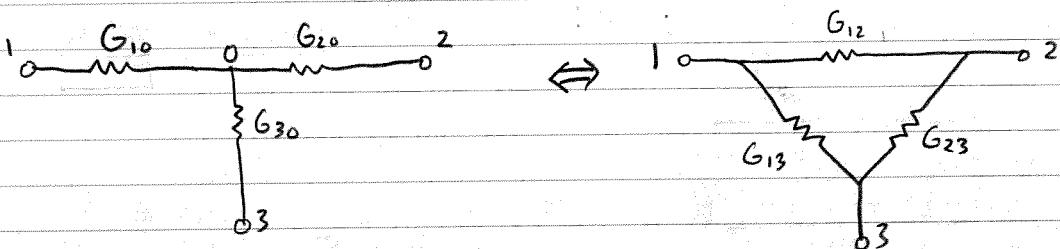
e.g. find Thevenin equivalent of:



$$V_{TH} = V_{oc} = I_1 R_2 \quad R_{TH} = R_1 || R_2$$



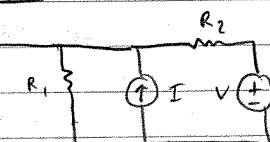
Star to Delta Conversion:



$$G_{12} = \frac{G_{10} G_{20}}{G_{10} + G_{20} + G_{30}} \quad G_{23} = \frac{G_{20} + G_{30}}{G_{10} + G_{20} + G_{30}} \quad G_{13} = \frac{G_{10} G_{30}}{G_{10} + G_{20} + G_{30}}$$

Delta to Star Conversion:

$$R_{10} = \frac{R_{12} R_{13}}{R_{12} + R_{13} + R_{23}} \quad R_{20} = \frac{R_{12} R_{23}}{R_{12} + R_{13} + R_{23}} \quad R_{30} = \frac{R_{13} + R_{23}}{R_{12} + R_{13} + R_{23}}$$



Find Thevenin & Norton Eq.

by superposition, $V_1 = I (R_1 || R_2)$ $V_2 = \frac{R_1}{R_1 + R_2} V$

$$\Rightarrow V_{TH} = V_1 + V_2 = \frac{R_1}{R_1 + R_2} (V + I R_2) \quad R_{TH} = R_1 || R_2$$

$$\Rightarrow I_N = \frac{V_{TH}}{R_{TH}} = I + \frac{V}{R_2}$$

BJT Current Equations: Pierret 11.1.2 - 11.1.4

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$$I_E = gA \left[\left(\frac{D_E}{L_E} n_{E0} + \frac{D_B}{L_B} p_{B0} \frac{\cosh(W/L_B)}{\sinh(W/L_B)} \right) (e^{V_{EB}/V_T} - 1) \right.$$

$$\left. - \left(\frac{D_B}{L_B} p_{B0} \frac{1}{\sinh(W/L_B)} \right) (e^{V_{CB}/V_T} - 1) \right]$$

$$I_C = gA \left[\left(\frac{D_B}{L_B} p_{B0} \frac{1}{\sinh(W/L_B)} \right) (e^{V_{EB}/V_T} - 1) \right.$$

$$\left. - \left(\frac{D_C}{L_C} n_{C0} + \frac{D_B}{L_B} p_{B0} \frac{\cosh(W/L_B)}{\sinh(W/L_B)} \right) (e^{V_{CB}/V_T} - 1) \right]$$

$$I_B = I_E - I_C$$

Ebers-Moll Equations + Model:

$$I_{FO} = gA \left(\frac{D_E}{L_E} n_{E0} + \frac{D_B}{L_B} p_{B0} \frac{\cosh(W/L_B)}{\sinh(W/L_B)} \right)$$

$$I_{RO} = gA \left(\frac{D_C}{L_C} n_{C0} + \frac{D_B}{L_B} p_{B0} \frac{\cosh(W/L_B)}{\sinh(W/L_B)} \right)$$

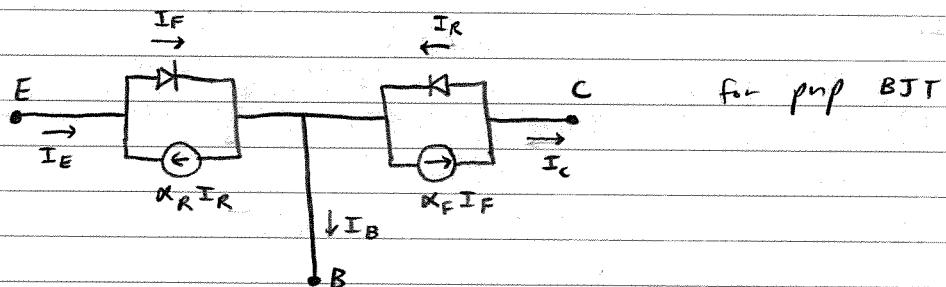
$$\alpha_F I_{FO} = \alpha_R I_{RO} = gA \frac{D_B}{L_B} \frac{p_{B0}}{\sinh(W/L_B)}$$

note: ($\alpha_F = \alpha_{dc}$)

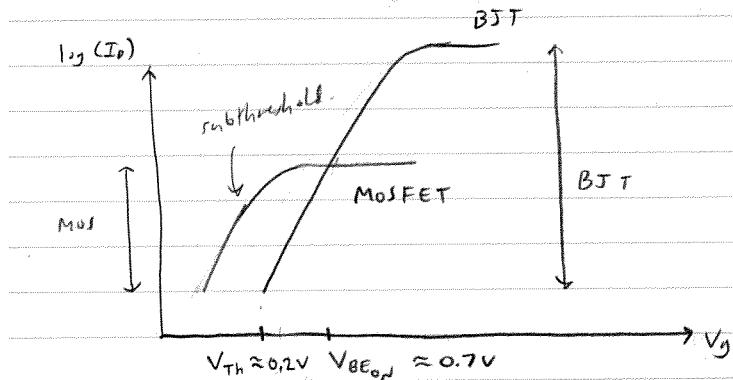
$$\Rightarrow I_E = \overbrace{I_{FO} (e^{V_{EB}/V_T} - 1)}^{\text{IF}} - \alpha_R I_{RO} (e^{V_{CB}/V_T} - 1)$$

$$I_C = \alpha_F I_{FO} (e^{V_{EB}/V_T} - 1) - \overbrace{I_{RO} (e^{V_{CB}/V_T} - 1)}^{\text{IR}}$$

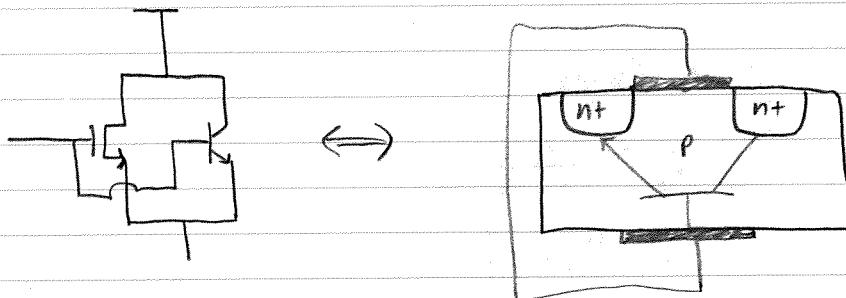
Model:



Dutton Quals Question.



range is higher for BJT. why might this be helpful or important?



Last 2 lectures of EE214A.

Return Ratio Example : Blackman's for Super Source Follower

I_2

$V_{in} \rightarrow M_1 \quad M_2 \quad I_1$

$R_{out} = R_{out} \frac{1 + R_{(short)}}{1 + R_{(open)}}$

$R_{out} = R_{out} = r_{o2}$

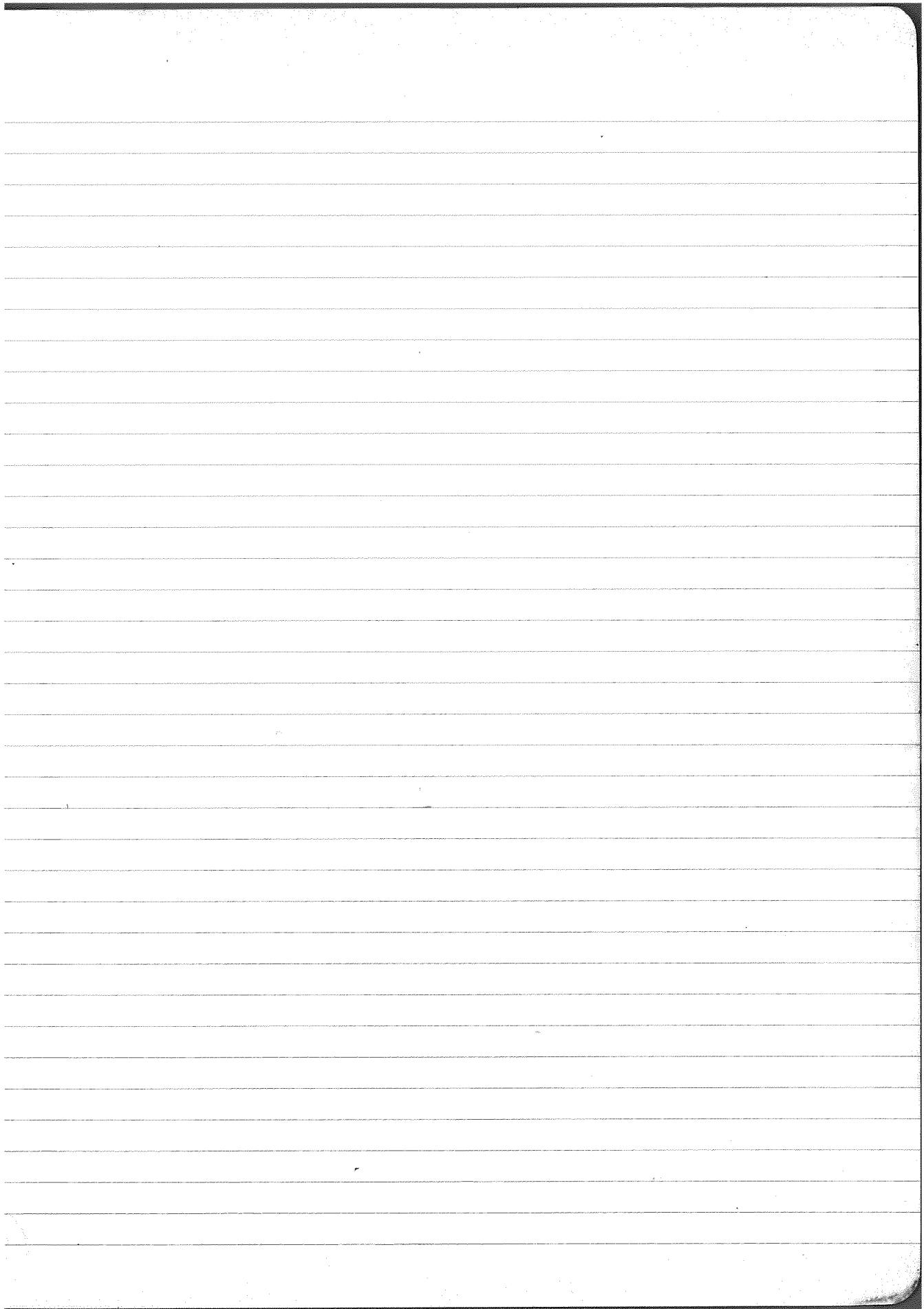
$R_{(short)} = 0 \quad R_{(open)} = -\frac{V_t}{g_m} = g_m r_{o1} (1 + g_m r_{o2})$

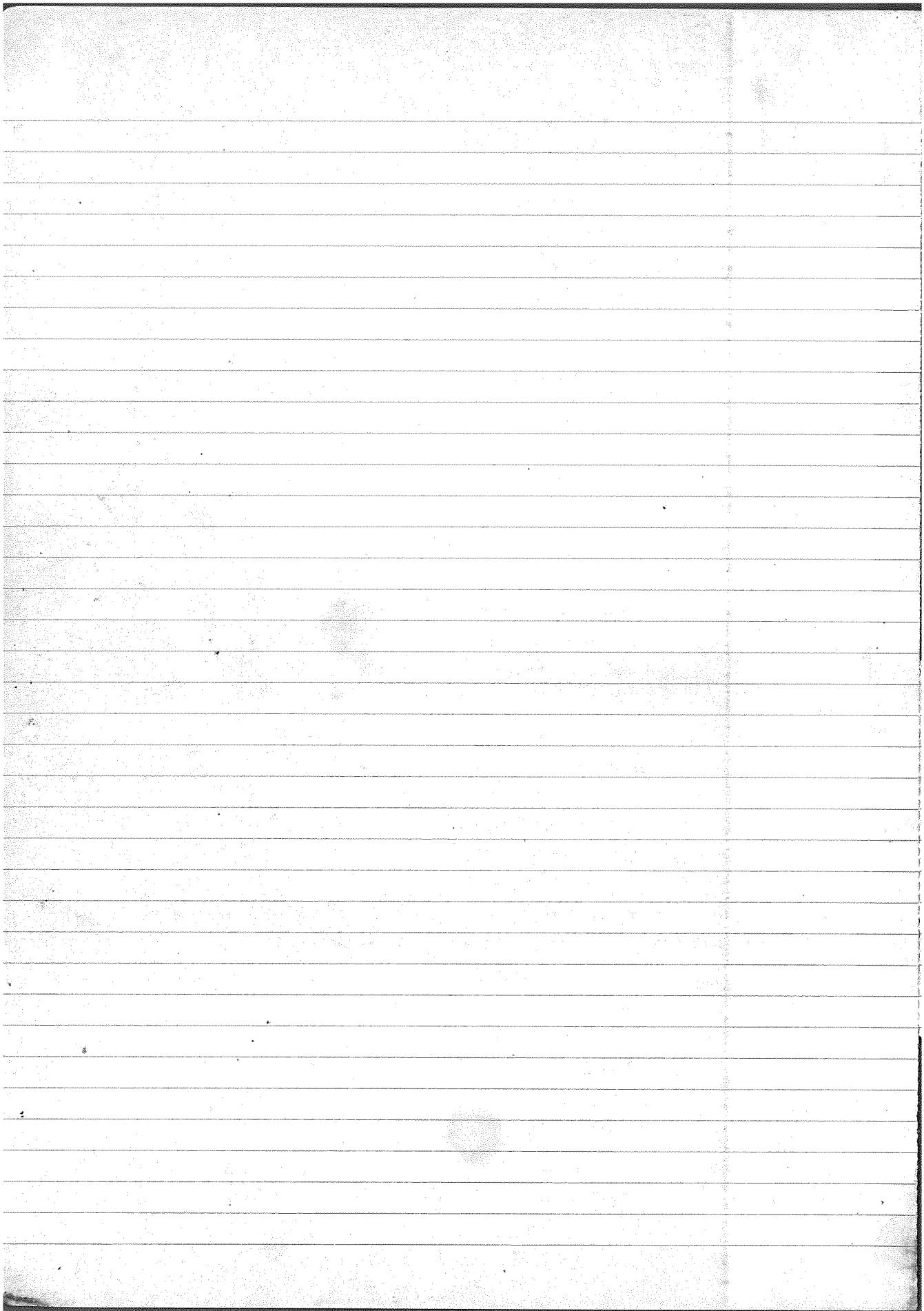
$\Rightarrow R_{out} = r_{o2} \left(\frac{1 + 0}{1 + g_m r_{o1} (1 + g_m r_{o2})} \right) \approx \frac{1}{g_m r_{o1}}$

$\frac{g_m V_1}{V_{in}} + V_1 = r_{o1} \quad r_{o2} \quad \text{Can also use } \frac{1}{\beta g_m}$

$\frac{+ V_2}{- V_2} = g_m V_2 \quad r_{o2}$

$\Rightarrow R_{out} = \frac{1}{g_m r_{o1}}$





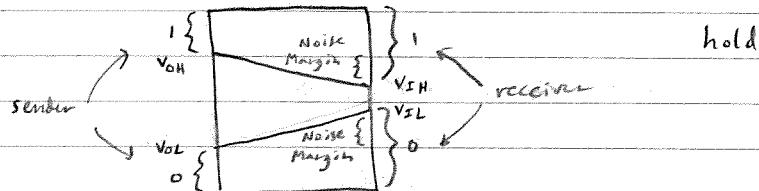
Circuits

MIT - 6.002 L4 -

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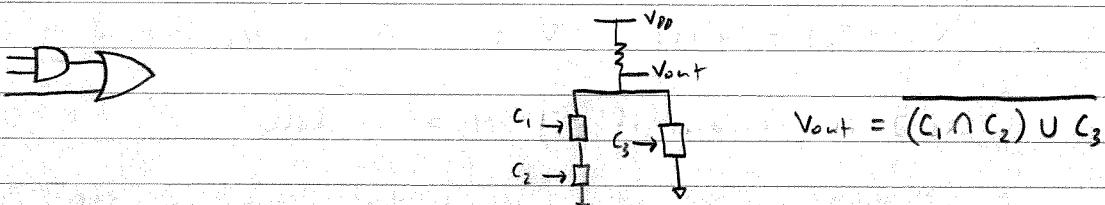
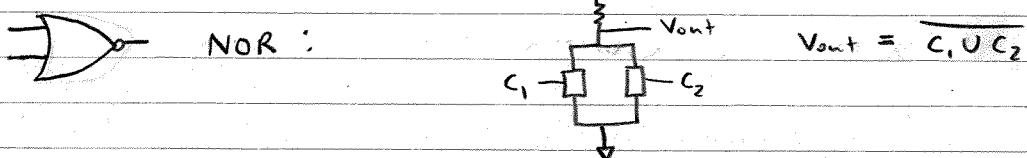
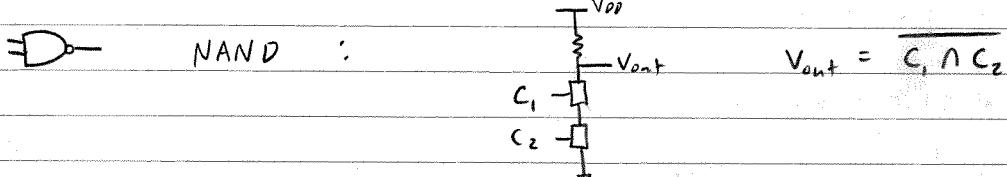
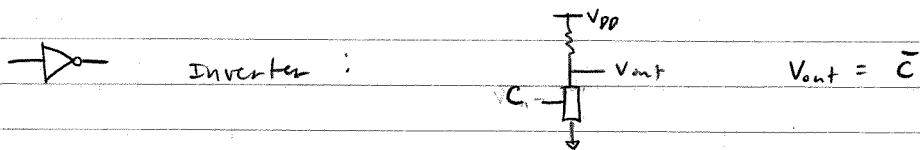
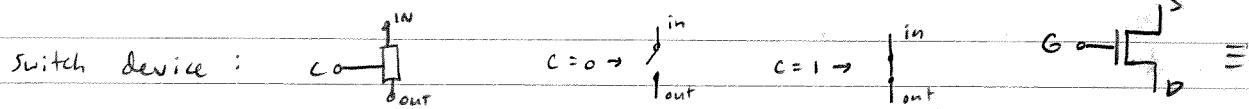
4. The Digital Abstraction

Digital: better noise immunity (lots of noise margin)



Static Discipline: If inputs to the digital system meet valid input thresholds, then the system guarantees its outputs will meet valid output thresholds.

5. Inside The Digital Gate



Systems: Take a signal and convert it to another signal.

L2 Time scaling: $x(bt)$: scales $x(t)$ $0 < b < 1$ expands
 $b > 1$ compresses

$x[nk]$ compresses, downsamples, or decimates $x[n]$

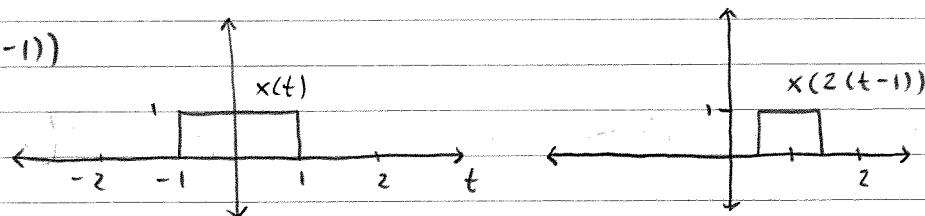
$x[n/m]$ expands, upsamples, or interpolates $x[n]$

This specifies every m th sample. Intermediate samples must be synthesized (set to zero or interpolated).

Time Reversal: $x(-t)$ $x[-n]$

Time Shift: $x(t-t_0)$ delayed, $x(t+t_0)$ advanced
 $x[n-n_0]$ delayed, $x[n+n_0]$ advanced

E.g. $x(2(t-1))$



Even: $x(t) = x(-t)$

Odd: $x(t) = -x(-t) \Rightarrow x(0) = 0$

Decomposition: $x_e(t) = \frac{1}{2} (x(t) + x(-t))$

$$x_o(t) = \frac{1}{2} (x(t) - x(-t))$$

Periodic: $x(t)$ is periodic if $\exists T_0 > 0$ s.t.

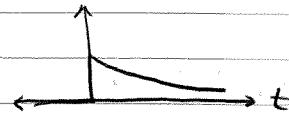
$$x(t+T_0) = x(t) \quad \forall t, \quad T_0 \text{ is the period of } x(t)$$

$x[n]$ is periodic if $\exists N_0 > 0$ s.t.

$$x[n+N_0] = x[n] \quad \forall n \quad N_0 \text{ is the period of } x[n]$$

* The smallest T_0 or N_0 is the fundamental period of the periodic signal.

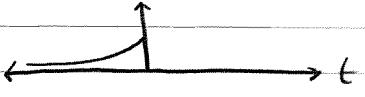
Causal: non-zero only for $t \geq 0$



Noncausal: non-zero for some $t < 0$



Anticausal: non-zero only for $t \leq 0$



Complex Signals: $z(t) = x(t) + jy(t)$ $x, y \in \mathbb{R}$ $j = \sqrt{-1}$

Complex Numbers: $z = x + jy$

$x = \operatorname{Re}(z)$ in-phase component (in phase with a cosine)

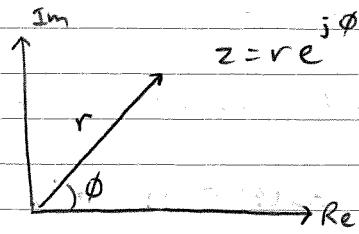
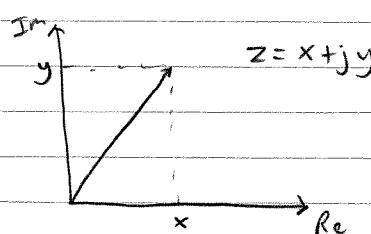
$y = \operatorname{Im}(z)$ quadrature component (delayed 90° from cosine)

Polar Form: $z = r e^{j\phi}$ (sine lags cosine by 90°)

r : modulus or magnitude of z $r = |z| = \sqrt{(\operatorname{Im}(z))^2 + (\operatorname{Re}(z))^2}$

ϕ : angle or phase of z $\phi = \tan^{-1}\left(\frac{\operatorname{Im}(z)}{\operatorname{Re}(z)}\right)$

$$e^{j\phi} = \cos \phi + j \sin \phi$$



Complex Exponential: $z = x + jy$

$$e^z = e^{x+jy} = e^x e^{jy} = e^x (\cos y + j \sin y)$$

Energy: Signal energy for a (possibly complex) $x(t)$ is:

$$E_x = \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt$$

Energy signal: $0 < E_x < \infty$
 $P_x = 0$

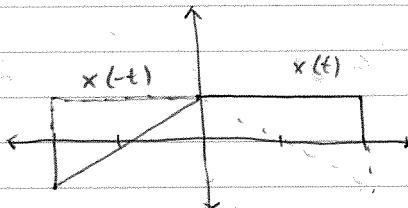
Power: The average of signal energy over time is the signal power:

$$P_x = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

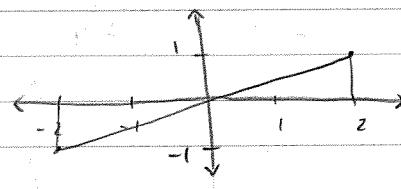
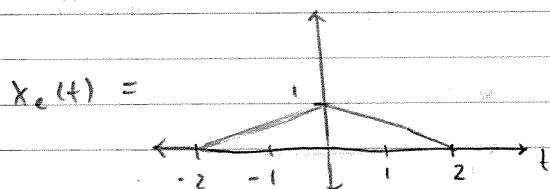
Power Signal: $0 < P_x < \infty$
 $E_x = \infty$

EE102A PSET 1

$$x_e(t) = \frac{1}{2}(x(t) + x(-t))$$



$$x_o(t) = \frac{1}{2}(x(t) - x(-t))$$



Trick: Since the graph consists of straight lines, we can compute the values at $-2, 0$, and 2 and connect them.

3. $y(t) = x_1(t) + x_2(t) = y(t+T_0)$ must $x_1(t) + x_2(t)$ be periodic?

No. e.g. if $a(t)$ is not periodic and $b(t)$ is periodic,

$$\text{let } x_1(t) = b(t) + a(t) \quad x_2(t) = b(t) - a(t)$$

\Rightarrow neither $x_1(t)$ or $x_2(t)$ are periodic, but:

$$y(t) = x_1(t) + x_2(t) = 2b(t) \text{ is periodic.}$$

4. $x(t)$ periodic and $x(t)$ is odd. What is $x(T_0)$?

$$x(t) = -x(-t) \Rightarrow x(0) = 0 \quad x(0+T_0) = x(0)$$

$$\Rightarrow x(T_0) = 0$$

5. $x_1(t)$ and $x_2(t)$ are periodic with periods T_1 and T_2

Find values of T_1 and T_2 such that $x_1(t) + x_2(t)$ is aperiodic.

$$y(t) = x_1(t) + x_2(t)$$

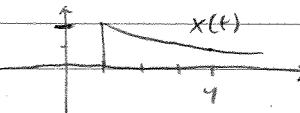
$$\Rightarrow y(t+T) = x_1(t+T) + x_2(t+T) = y(t) \text{ if } T = nT_1 = mT_2$$

$$\text{where } n, m \in \mathbb{Z} \Rightarrow \frac{T_1}{T_2} = \frac{m}{n}$$

$\Rightarrow x_1(t) + x_2(t)$ is aperiodic if $\frac{T_1}{T_2}$ is an irrational number

$$\text{e.g. let } T_1 = \pi, T_2 = 1$$

$$6. x(t) = \frac{1}{\sqrt{t}} u(t-1)$$



$$E_x = \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt = \int_1^\infty \frac{1}{t} dt = [\ln(t)]_1^\infty = \infty - 0 = \infty$$

$$P_x = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_1^T \frac{1}{t} dt = \lim_{T \rightarrow \infty} \left(\frac{\ln(T)}{2T} - \frac{\ln(1)}{2T} \right) = 0$$

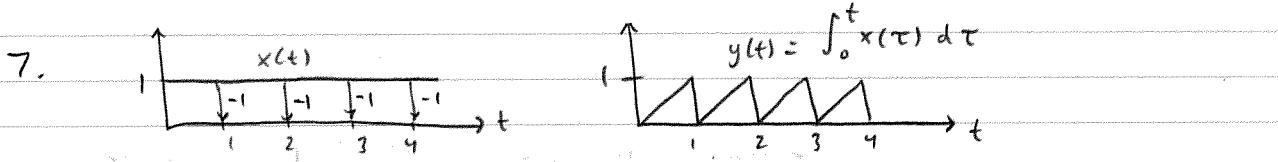
$$= \lim_{T \rightarrow \infty} \frac{\ln(T)}{2T} = \lim_{T \rightarrow \infty} \frac{(1/T)}{2} = 0$$

L'Hopital's rule: $\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}$

$$E_x = \infty \quad P_x = 0 \quad \text{Energy: } 0 \leq E_x < \infty, \quad P_x = 0$$

$$\text{Power: } 0 < P_x < \infty, \quad E_x = 0$$

$\Rightarrow x(t)$ is neither an Energy or a Power signal.



8. a) $\int_{-\infty}^{\infty} f(t+1) \delta(t+1) dt = f(t+1)|_{t=-1} = [f(0)]$

b) $\int_{-\infty}^{\infty} e^{j\omega t} \delta(t) dt = e^{j\omega t}|_{t=0} = e^{j\omega t}$

c) $\int_{-\infty}^{\infty} f(t)(\delta(t-1) + \delta(t+1)) dt = f(t)|_{t=1} = [f(1)]$

d) $\int_{-\infty}^{\infty} f(\tau) \delta(t-\tau) \delta(t-2) d\tau = \delta(t-2) \int_{-\infty}^{\infty} f(\tau) \delta(t-\tau) d\tau$
 $= \delta(t-2) f(t)|_{t=t} = \delta(t-2) f(t) = [\delta(t-2) f(2)].$

Devices - EE311 L1

Moore's Law - # of transistors that can be placed inexpensively on an IC doubles every 2 years. (exponential growth)

Scaling: Constant E field \Rightarrow all device parameters are scaled by same factor α : $t_{ox} \downarrow, L \downarrow, x_j \downarrow, V_{DD} \downarrow$, Channel Doping \uparrow

- Why Scale?
1. increase packing density $\sim \alpha^2$
 2. improve frequency response (speed) $\sim \alpha$ (digital) $\sim \alpha^2$ (analog)
 3. power/ckt: $\sim \frac{1}{\alpha^2}$
 4. improve current drive (transconductance g_m)

$$g_{m,\text{sat}} = \mu C_{ox} \frac{W}{L} (V_{gs} - V_t) \quad g_{m,\text{triode}} = \mu C_{ox} \frac{W}{L} V_{ds}$$

Want to maximize I_{ON} and minimize I_{OFF}

$$I_D \propto g_m \propto \frac{K}{t_{ox}}$$

historically C_{ox} has been increased by $t_{ox} \downarrow$. Can also increase C_{ox} by $K \uparrow$. \Rightarrow can use $t_{ox} \uparrow \Rightarrow$ reduced gate leakage.

Ge Nanowire and Carbon Nanotube FETs.

- Key Challenge: Controlled Growth.

Interconnect Scaling:

- Bigger Chip \Rightarrow Longer Interconnects

- scaling to smaller dimensions \Rightarrow reduced cross-section

- \Rightarrow Larger R, L, C

- Need Better materials

- lower resistivity metals (Current metals are Al and Cu)

- lower K dielectrics

- other solutions (3D or optical interconnects)

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Systems

EE102A

L3

Signal Models.

$$\text{Sinusoidal: } x(t) = A \cos(\omega t + \theta) = A \cos(2\pi f t + \theta) \quad T = \frac{1}{f} = \frac{2\pi}{\omega}$$

$$\text{Euler: } e^{j\phi} = \cos\phi + j\sin\phi \quad \Rightarrow \cos\phi = \frac{1}{2}(e^{j\phi} + e^{-j\phi}) \quad \sin\phi = \frac{1}{2j}(e^{j\phi} - e^{-j\phi})$$

$$A e^{j(\omega t + \theta)} = A \cos(\omega t + \theta) + j A \sin(\omega t + \theta)$$

$$\text{Exponential: } x(t) = e^{\sigma t} \quad \sigma < 0 \Rightarrow \text{decay} \quad \sigma > 0 \Rightarrow \text{growth.}$$

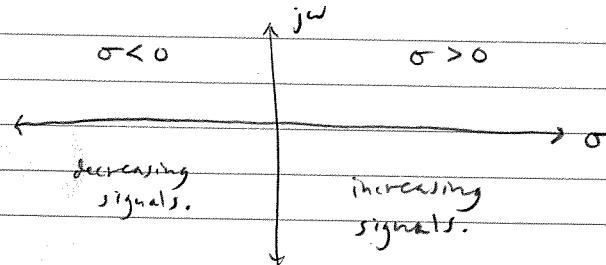
$$\text{damped or growing sinusoids: } x(t) = e^{\sigma t} \cos(\omega t + \theta)$$

$$\text{Complex exponential signal: } e^{(\sigma+j\omega)t + j\theta} = e^{\sigma t} (\cos(\omega t + \theta) + j \sin(\omega t + \theta))$$

$$s = \sigma + j\omega$$

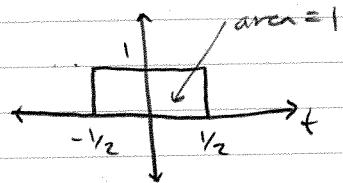
$$\sigma < 0$$

$$\sigma > 0$$



unit step: $u(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$

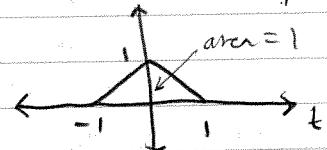
rect: $\text{rect}(t) = \begin{cases} 1 & |t| \leq \frac{1}{2} \\ 0 & \text{otherwise} \end{cases}$



unit ramp: $r(t) = \begin{cases} t & t \geq 0 \\ 0 & t < 0 \end{cases}$

$$r(t) = \int_{-\infty}^t u(\tau) d\tau$$

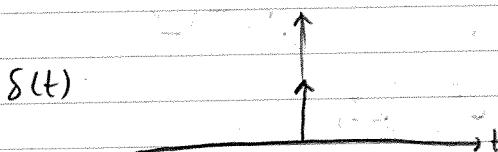
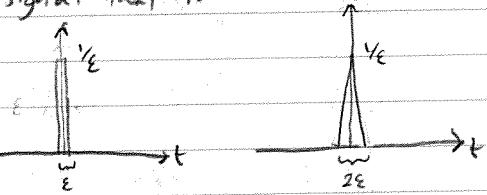
unit triangle: $\Delta(t) = \begin{cases} -1-|t| & , |t| < 1 \\ 0 & \text{otherwise} \end{cases}$



delta function (impulse): idealization of a signal that is

- very large near $t=0$
- very small away from $t=0$
- has integral 1

e.g.



Properties of δ :

$$\int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0)$$

$$\int_{-\infty}^{\infty} \alpha \delta(t) f(t) dt = \alpha f(0)$$

$$f(t) \delta(t) = f(0) \delta(t)$$

sifting: $\int_{-\infty}^{\infty} f(t) \delta(t-T) dt = f(T)$

$$u'(t) = \delta(t)$$

Derivatives of δ : $\int_{-\infty}^{\infty} \delta'(t) f(t) dt = \delta(t) f(t) \Big|_{-\infty}^{\infty} - \int_{-\infty}^{\infty} \delta(t) f'(t) dt$

$$= 0 - f'(0) = f'(0)$$

in general: $\int_{-\infty}^{\infty} \delta^{(k)}(t) f(t) dt = (-1)^k f^{(k)}(0)$ if $f^{(k)}(0)$ is continuous at

$\delta(t)$ is not a signal in the ordinary sense.

It only makes mathematical sense when inside an integral sign.

Some innocent looking expressions such as $\delta(t)^2$ or $\delta(t^2)$ don't make any sense at all.

L4 Systems characteristics and Models

A system is a function mapping input signals into output signals.
this does not necessarily mean multiplication.

$y = Sx$ or $y = S(x)$ meaning the system S acts on x



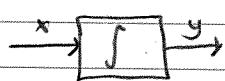
scaling system: $y(t) = \alpha x(t)$ $\alpha \in \mathbb{R}$



differentiator: $y(t) = x'(t)$



integrator: $y(t) = \int_a^t x(\tau) d\tau$
often $a = -\infty$ or 0



time shift system: $y(t) = x(t-T)$, called delay system if $T > 0$
called predictor system if $T < 0$

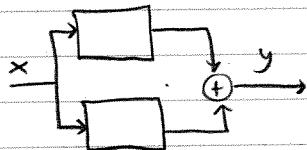
convolution system: $y(t) = \int x(t-\tau) h(\tau) d\tau$

Interconnection of Systems:

Cascade (series) : $y = G(F(x)) = GFx$

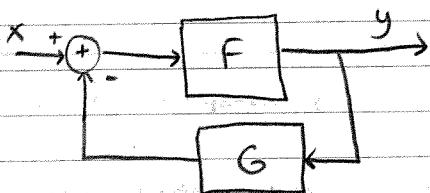


Sum (parallel) :



$$y = F(x) + G(x) = Fx + Gx$$

Feedback : $y = F(x - Gy)$



e.g.

```

graph LR
    x((x)) --> sum((+))
    sum --> int[Integrator]
    int --> y((y))
    y --> feedback(( ))
    feedback --> sum
  
```

$$y(t) = \int_a^t (x(\tau) - \alpha y(\tau)) d\tau$$

OR

$$y'(t) = x(t) - \alpha y(t)$$

Linearity : A system F is linear if the following 2 properties hold:

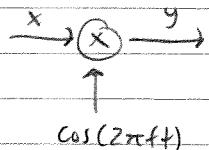
1) Homogeneity: $F(ax) = aF(x) \quad a \in \mathbb{R}$

2) Superposition: $F(x+y) = F(x) + F(y)$

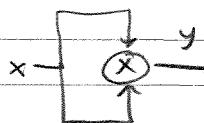
\Rightarrow Scaling before or after the system is the same
summing before or after the system is the same

Linear Systems: Scaling, differentiator, integrator, running average, time shift, convolution, summer, difference.

Nonlinear Systems: sign detector, multiplier (sometimes), comparator



Multiplication as modulator is linear



Multiplication as squaring system is nonlinear.

System Memory

A system is memoryless if output depends only on present input

A system with memory has an output signal that depends on inputs in the past or future.

A causal system has an output that depends only on past or present inputs.

Time Invariance:

A system is time invariant if a time shift in the input only produces the same time shift in the output.

$$y(t) = Fx(t) \Rightarrow y(t-\tau) = Fx(t-\tau) \text{ if } F \text{ is time invariant}$$

System Stability: Bounded Input Bounded Output (BIBO) Stable if:

Any bounded input $|x(t)| \leq M_x < \infty$ always results in a bounded output: $|y(t)| \leq M_y < \infty$ $\int_{-\infty}^{\infty} |h(t)| dt < \infty \Rightarrow \text{BIBO stable}$

EE102A PSET 2

1. State whether systems are linear or time invariant:

a) $y(t) = x(t) \sin(\omega t + \phi)$ Yes, No.

b) $y(t) = t x'(t)$ Yes, No.

c) $y(t) = 1 + x(t) \cos(\omega t)$ No, No.

d) $y(t) = \cos(\omega t + x(t))$ No, No.

e) $y(t) = \int_{-t}^t x(\tau) d\tau$ Yes, No.

f) $y(t) = \int_{-\infty}^{t/2} x(\tau) d\tau$ Yes, No.

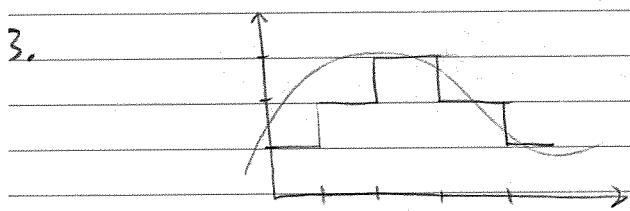
2. $y(t) = \frac{x^2(t)}{\int_{-\infty}^t x(\tau) d\tau}$

a) Does the system obey homogeneity? Yes.

$$\frac{a^2 x^2(t)}{a \int_{-\infty}^t x(\tau) d\tau} = a y(t)$$

b) Does the system obey superposition? No.

c) Is the system linear? No.



Is it linear? No. due to quantization error.
(Solutions given say it is linear...)

4. $x_e(t) = \frac{1}{2} (x(t) + x(-t)) \Rightarrow$ homogeneity ✓

superposition ✓ \Rightarrow [Linear]

$$\frac{1}{2} (x(t-\tau) + x(-(t-\tau))) \neq \frac{1}{2} (x(t-\tau) + x(-t-\tau))$$

\Rightarrow time variant.

$$5. \quad a) \quad x(t) = 4\Delta\left(\frac{t}{2}\right) - 6\Delta(t) + 4\Delta(2t)$$

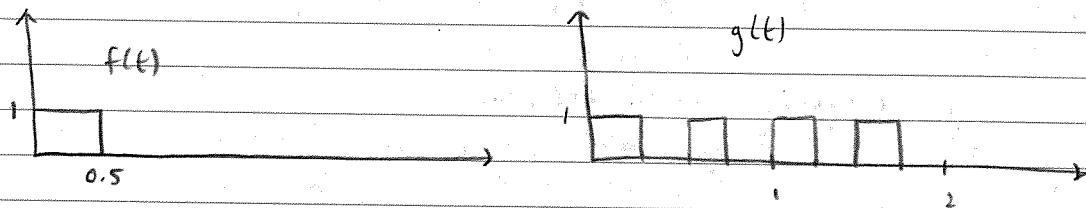
$$= 4\Delta\left(\frac{t}{2}\right) - 2\Delta(t) - 2\Delta((t-1/2)/2) - 2\Delta((t+1/2)/2)$$

$$b) \quad x(t) = 2\Delta\left(\frac{t}{2}\right) - 2\Delta(t) + \text{rect}\left(\frac{t}{2}\right)$$

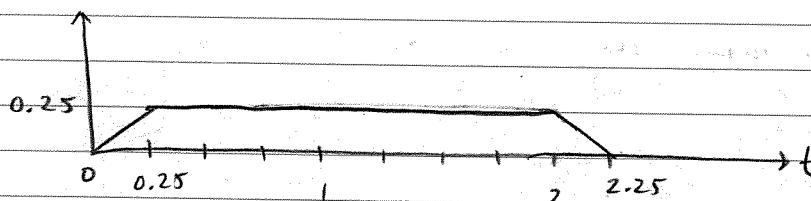
$$6. \quad y' = z - ay \Rightarrow z = y' + ay \Rightarrow z' = y'' + ay'$$

$$z' = x - by \Rightarrow y'' + ay' = x - by \Rightarrow y'' + ay' + by = x$$

7.



graphically compute $h(t) = (f * g)(t)$



Scaling:

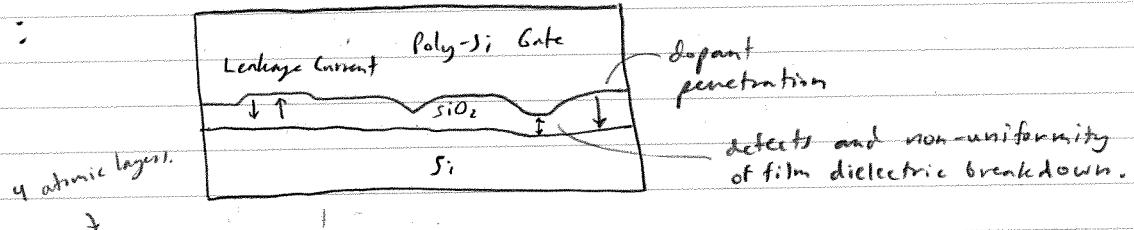
$$I_D \propto \text{Charge} \times \text{velocity}$$

$$\propto C_{ox} (V_{GS} - V_T) \times \text{velocity}$$

$$\propto \frac{k}{t_{ox}} (V_{GS} - V_T) \times \text{velocity}$$

\Rightarrow scale down t_{ox} to increase I_D .

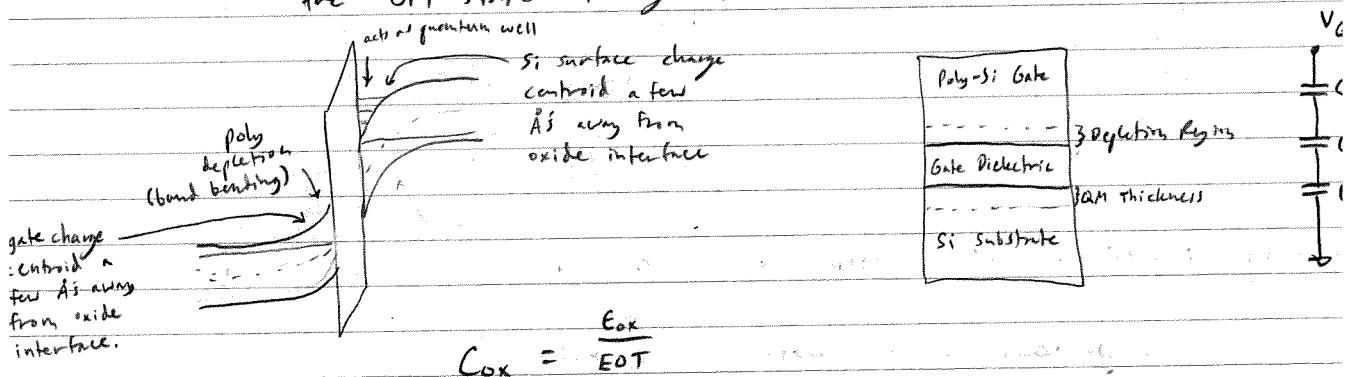
Problems:



Below 20 Å (2nm), problems with SiO₂:

- Gate leakage \Rightarrow circuit instability, power dissipation.
- Performance degradation due to t_{ox} (electrical) $>$ t_{ox} (physical)
 - Carrier quantization in channel and depletion in poly-Si gate.
- Degradation and breakdown.
- Dopant penetration through gate oxide
- Defects.

As $t_{ox} \downarrow$, I_G (gate leakage due to direct tunneling) dominates the OFF-state leakage currents.



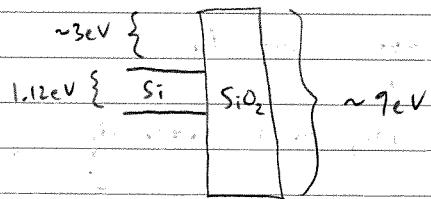
Equivalent Oxide Thickness $\rightarrow EOT = EOT_{DR} + EOT_{GD} + EOT_{QM}$

Thus, increased t_{ox} reduces C_{ox} which reduces g_m and $I_d(\text{on})$

Technology: Atomic Layer CVD (chemical vapor deposition).

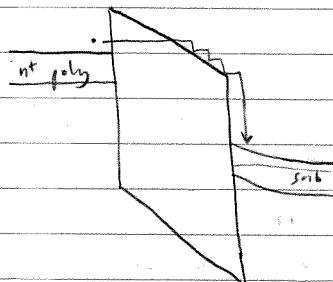
- Deposition is done one monolayer at a time: excellent control
- Being investigated for high k dielectrics like ZrO₂ and HfO₂

Reliability of SiO_2 :



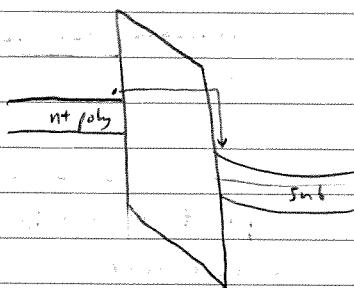
Conduction in Dielectrics: Tunneling

$t_{ox} > 5\text{nm}$



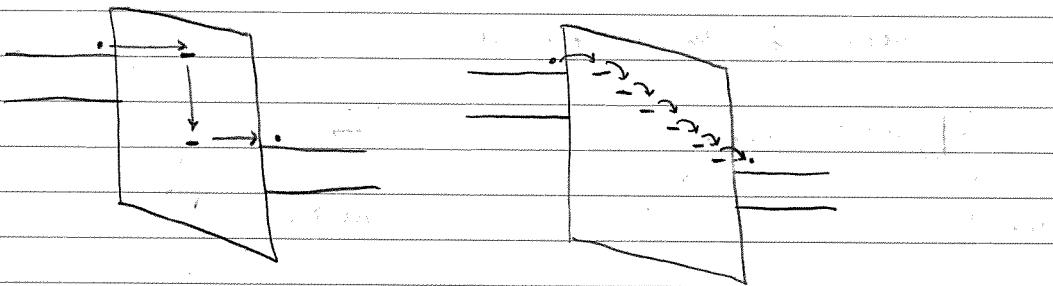
Fowler-Nordheim (FN) Tunneling

$t_{ox} < 3\text{nm}$



Direct Tunneling

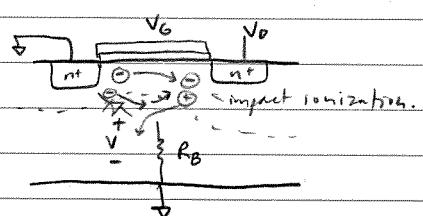
Conduction in Dielectrics: Leakage (Trap assisted tunneling)



- Trap assisted tunneling resulting in leakage at low gate voltage.
- Increase in traps will cause more leakage.
- Traps are present in as-grown dielectric
- Traps can be generated by electrical stress.

Hot Carrier Effects:

- change in V_t , g_m
- leakage
- junction breakdown



Time Domain Analysis of Continuous Time Systems.

zero input response: system response to zero input. This is due only to initial conditions. (This is zero for a linear system)

zero state response: system response to zero initial conditions. This is due only to input.

$$\text{output} = \text{zero state response} + \text{zero input response}$$

Impulse response: $h(t, \tau) = H(\delta(t-\tau))$ & for time variant system,

$$h(t) = H(\delta(t)) \quad \text{for LTI system}$$

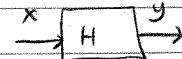
Extended Linearity: if $y_n = Sx_n$ $\sum_n a_n y_n = S(\sum_n a_n x_n)$

\Rightarrow summation and system operator commute

$$\text{if } y_n = Sx_n, \int_{-\infty}^{\infty} a(\tau) y(t-\tau) d\tau = S \left(\int_{-\infty}^{\infty} a(\tau) x(t-\tau) d\tau \right)$$

\Rightarrow integration and system operator commute.

$$\text{Can write } x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau$$



$$\Rightarrow y(t) = H(x(t)) = H \left(\int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau \right) = \int_{-\infty}^{\infty} x(\tau) H(\delta(t-\tau)) d\tau$$

$$= \int_{-\infty}^{\infty} x(\tau) h(t, \tau) d\tau \quad \text{if } H \text{ is LTI, } y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau = x(t) * h(t)$$

\Rightarrow The response of an LTI system is completely characterized by its impulse response $h(t)$.

$$y(t) = (x * h)(t) \quad \text{for an LTI system}$$

Properties of Convolution:

Commutative: $f * g = g * f$

Associative: $f * (g * h) = (f * g) * h$

Distributive: $f * (g + h) = f * g + f * h$

Properties of Convolution Systems

-The properties of the convolution integral have important consequences for systems described by convolution:

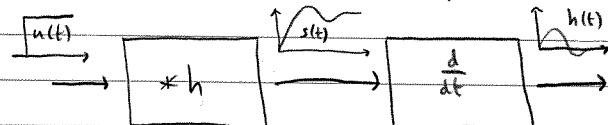
Convolution systems are linear: $h * (\alpha x_1 + \beta x_2) = \alpha(h * x_1) + \beta(h * x_2)$

Convolution systems are time invariant: if $x_i(t) = x(t-T)$, $y_i(t) = y(t-T)$

i.e. convolution systems commute with delay.

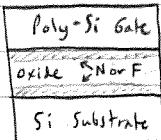
Measuring the impulse response of an LTI system:

Since it can be practically difficult to measure the impulse response of an LTI system directly (input amplitude is often limited, so a very short pulse then has very little energy), A common alternative is to measure the step response $s(t)$, the response to a unit step input $u(t)$.



Nitrided SiO_2 :

- Incorporating N or F instead of Hydrogen strengthens the Si/ SiO_2 interface and increases the gate dielectric lifetime because Si-F and Si-N bonds are stronger than Si-H bonds.



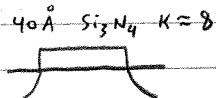
- Nitroxides:
- improves reliability
 - barrier to dopant penetration from poly-Si gate into Si substrate (esp. if gate is doped with Boron).
 - marginal increase in K .
 - used extensively.

High K Dielectrics:

$$I_D \propto C_{ox} \propto \frac{K}{t_{ox}}$$

Historically, C_{ox} has been increased by decreasing t_{ox} , but it can also be increased by using a higher K dielectric. For higher K , we can use larger t_{ox} .

\Rightarrow Higher thickness \Rightarrow reduced gate leakage $I_{DT} \propto e^{-t_{ox}}$



$$C_{ox} = \frac{KEA}{t_{ox}} \Rightarrow t_{high-K} = \left(\frac{K_{high-K}}{K_{SiO_2}} \right) t_{SiO_2}$$

	K	Conduction Band - Barrier Height
SiO_2	4	3.2 eV
Si_3N_4	8	2.2 eV

↑ ↑
good bad (reduction in bandgap \Rightarrow increased gate leakage)

Requirements for MOS Gate Dielectrics

- high $K \Rightarrow$ higher charge induced in channel
- wide bandgap \Rightarrow higher barriers \Rightarrow lower leakage
- ability to grow high purity films on Si with clean interface
- high resistivity and breakdown voltage
- low bulk and interfacial trap densities.
- Compatibility with substrate + top electrode (minimal interdiffusion + reaction)
- Thermal stresses - most oxides have larger thermal expansion coefficients than Si.
- Good Si fabrication processing compatibility
- stability at high T , ability to be cleaned, etched, etc.

	K	Eg	$\Delta E_{\text{G}} \text{ to Si}$
Candidates for high K:			
SiO_2	4	9	3.5
Si_3N_4	7	5.3	2.4
HfO_2	25	6	1.5
ZrO_2	25	5.8	1.4

Higher K materials have lower bandgap.

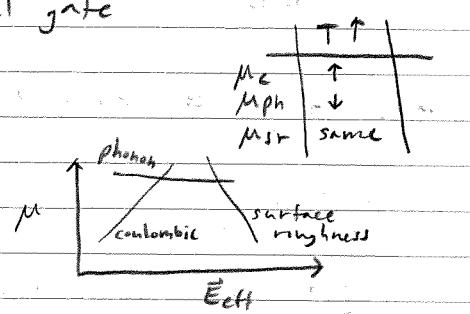
Atomic Layer Deposition \rightarrow then annealing.

Issues with High K Dielectrics:

- How good is interface with Si? \rightarrow mobility
- Compatibility with gate electrode \Rightarrow metal gate
- Device reliability + lifetime.
- Minimum EOT achievable.

Reduced Mobility in high K Gate stacks

$$\frac{1}{\mu_{\text{eff}}} = \frac{1}{\mu_c} + \frac{1}{\mu_{ph}} + \frac{1}{\mu_{sr}}$$



interface traps cause coulombic scattering \Rightarrow reduces mobility.

High-K / Poly-Si gate transistors: high V_T , degraded channel mobility (phonon scatter)
Metal gate screens surface phonon scattering + improves channel mobility.

Frequency domain representation of continuous time signals in general means a Fourier Series or Fourier Transform.

Fourier Series: Time limited signals and periodic signals.

Fourier Transforms: Any energy signal, many power signals.

Fourier Series: If $f(t)$ is a well behaved periodic signal, or it is defined for only a finite interval, then $f(t)$ can be written as a Fourier series:

$$f(t) = \sum_{n=-\infty}^{\infty} D_n e^{jn\omega_0 t} \quad \text{where } \omega_0 = \frac{2\pi}{T_0}$$

$$D_n = \frac{1}{T_0} \int_{-\tau}^{\tau+T_0} f(t) e^{-jn\omega_0 t} dt \quad \text{for } \forall n \in \mathbb{Z}$$

The sequence $\{D_n\}$ is called the Fourier coefficients of $f(t)$.

Fourier Transform: If $f(t)$ is a well-behaved aperiodic signal, then $f(t)$ can be written as:

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega \quad \leftarrow \text{inverse transform}$$

$$\text{where } F(j\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt \quad \leftarrow F(j\omega) \text{ is the Fourier Transform of } f(t).$$

In either case $f(t)$ is represented as a weighted average or linear combination of complex exponentials.

* Very important for LTI systems, since complex exponentials are eigenfunctions:
If $x(t)$ is an eigenfunction of a system, then $y(t) = a x(t)$ and a is a complex constant (eigenvalue)

$$\text{Fourier Series of Cosine: } f(t) = A \cos(\omega_0 t + \theta) = A \left(\frac{e^{j(\omega_0 t + \theta)} + e^{-j(\omega_0 t + \theta)}}{2} \right)$$

$$= \frac{A}{2} e^{j\theta} e^{j\omega_0 t} + \frac{A}{2} e^{-j\theta} e^{-j\omega_0 t}$$

$$\Rightarrow D_1 = \frac{A}{2} e^{j\theta} \quad D_{-1} = \frac{A}{2} e^{-j\theta} \quad D_n = 0 \text{ for } \forall n \neq 1, -1$$

LTI system:

$$\begin{array}{c} e^{j\omega t} \xrightarrow{* h(t)} y(t) \\ y(t) = \int_{-\infty}^{\infty} h(\tau) e^{j\omega(t-\tau)} d\tau = e^{j\omega t} * h(t) \\ = e^{j\omega t} \int_{-\infty}^{\infty} h(\tau) e^{-j\omega\tau} d\tau = H(j\omega) e^{j\omega t} \end{array}$$

⇒ Complex exponential is an eigenfunction of LTI system with eigenvalue $H(j\omega)$

Parseval's Theorem: $\lim_{N \rightarrow \infty} \sum_{n=-N}^N |D_n|^2 = \frac{1}{T_0} \int_{t_0}^{t_0+T_0} |f(t)|^2 dt$

i.e. the power of the signal in the time domain equals the sum of the powers of the frequency components.

$$D_0 = \frac{1}{T_0} \int_{t_0}^{t_0+T_0} f(t) dt \quad \leftarrow \text{DC coefficient or time-average mean of the signal.}$$

Symmetry: Fourier coefficients for a real waveform have the following symmetry properties:

$$R(D_{-n}) = R(D_n) \quad \text{even}$$

$$I_m(D_{-n}) = -I_m(D_n) \quad \text{odd}$$

$$D_{-n} = D_n^*$$

$$|D_{-n}| = |D_n|$$

$$\angle D_{-n} = -\angle D_n \quad \text{odd}$$

$$\text{sinc}(t) = \frac{\sin(\pi t)}{\pi t}$$

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a) $y(t) = \int_{-\infty}^t x(\tau) d\tau = \int_{-\infty}^{\infty} h(\tau) x(t-\tau) d\tau = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$

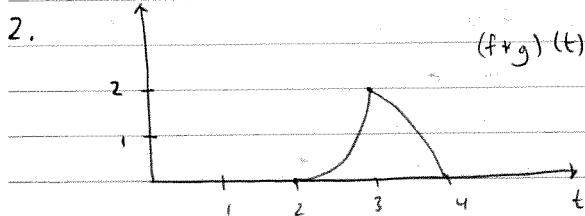
$$\Rightarrow [h(t) = u(t)]$$

b) $y(t) = \int_{t-T}^t x(\tau) d\tau = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$

$$\Rightarrow [h(t) = u(t) - u(t-T)]$$

c) $y(t) = x(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \Rightarrow [h(t) = \delta(t)]$

d) $y(t) = x(t-1) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \Rightarrow [h(t) = \delta(t-1)]$



3. $\int_{-\infty}^{\infty} u(\tau) \text{rect}(t-1-\tau) d\tau = \int_0^{\infty} \text{rect}(t-1-\tau) d\tau$

$$\int_{-\infty}^{\infty} \text{rect}(\tau-1) u(t-\tau) d\tau = \int_{-\infty}^t \text{rect}(\tau-1) d\tau = \begin{cases} 0, & t < \frac{1}{2} \\ t - \frac{1}{2}, & \frac{1}{2} < t < \frac{3}{2} \\ 1, & t > \frac{3}{2} \end{cases}$$

$\leftarrow \int_{1/2}^t 1 d\tau$

4. $(\delta * \delta)(t) = \delta(t)$

5. $x'(t) = (x * \delta')(t)$ if $f * g = y$ show that $f' * g' = y''$

$$y' = y * \delta' = (f * g) * \delta' = f * (g * \delta') = f * g'$$

$$y'' = y' * \delta' = f * g' * \delta' = f * \delta' * g' = f' * g' \quad \checkmark$$

6. $x * y = z \Rightarrow \int_{-\infty}^{\infty} x(\tau) y(t+\tau) d\tau = z(t)$

$$y * x = \int_{-\infty}^{\infty} y(\tau) x(t+\tau) d\tau \quad \text{Let } \tau' = t+\tau \Rightarrow \int_{-\infty}^{\infty} y(\tau'-t) x(\tau') d\tau'$$

$$= \int_{-\infty}^{\infty} x(\tau') y(-t+\tau') d\tau' = z(-t)$$

$$7. \quad a) \quad f(t) = \cos(3\pi t) + \frac{1}{2} \sin(4\pi t)$$

$$\begin{array}{c} \uparrow \\ T_1 = \frac{2}{3} \end{array} \quad \begin{array}{c} \uparrow \\ T_2 = \frac{1}{2} \end{array}$$

$$\Rightarrow T_0 = \text{LCM}(\frac{2}{3}, \frac{1}{2}) = [2] \quad \Rightarrow \omega_0 = \frac{2\pi}{T_0} = \pi$$

$$b) \quad f(t) = \cos(3\pi t) + \frac{1}{2} \sin(4\pi t)$$

$$= \frac{1}{2} (e^{j3\pi t} + e^{-j3\pi t}) + \frac{1}{4j} (e^{j4\pi t} - e^{-j4\pi t})$$

$$\Rightarrow D_3 = \frac{1}{2} \quad D_{-3} = \frac{1}{2} \quad D_4 = -\frac{1}{4}j \quad D_{-4} = \frac{1}{4}j$$

$$8. \quad f(at) \Rightarrow \text{period is } \frac{T_0}{a} \Rightarrow \omega_0 = \frac{2\pi}{T_0/a} = a \frac{2\pi}{T_0}$$

$$\Rightarrow f(at) = \sum_{n=-\infty}^{\infty} D_{n,a} e^{jn\omega_0 t} \quad D_{n,a} = \frac{1}{T_0/a} \int_{t_0}^{t_0+T_0/a} f(at) e^{-jn\omega_0 t} dt$$

$$\text{let } \tau = at \Rightarrow D_{n,a} = \frac{1}{T_0/a} \int_{t_0}^{t_0+T_0} f(\tau) e^{-jn\omega_0 \tau} \frac{d\tau}{a}$$

$$= \frac{1}{T_0} \int_{t_0}^{t_0+T_0} f(\tau) e^{-jn\omega_0 \tau} d\tau = D_n$$

\Rightarrow The Fourier series coefficients are the same as in the unscaled case.

$$\Rightarrow f(at) = \sum_{n=-\infty}^{\infty} D_n e^{jn\omega_0(at)} \quad \text{which is the original Fourier series evaluated at at.}$$

$$9. \quad f(t) = \sum_{n=-\infty}^{\infty} D_n e^{jn\omega_0 t} \quad D_n = \frac{1}{T_0} \int_{t_0}^{t_0+T_0} f(t) e^{-jn\omega_0 t} dt$$

$$\hat{D}_n = \frac{1}{T_0} \int_{t_0}^{t_0+T_0} f(t-\tau) e^{-jn\omega_0(t-\tau)} dt = \frac{1}{T_0} \int_{t_0}^{t_0+T_0} f(\tau') e^{-jn\omega_0(\tau'+\tau)} d\tau'$$

$$= e^{-jn\omega_0 \tau} D_n \Rightarrow \boxed{f(t-\tau) = \sum_{n=-\infty}^{\infty} D_n e^{-jn\omega_0(t-\tau)} e^{jn\omega_0 \tau}}$$

$$F(j\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega$$

$$\text{rect}(t) \Leftrightarrow \text{sinc}\left(\frac{\omega}{2\pi}\right)$$

$$\text{rect}\left(\frac{t}{T}\right) \Leftrightarrow T \text{sinc}\left(\frac{\omega T}{2\pi}\right)$$

$$e^{-at} u(t) \Leftrightarrow \frac{1}{a+j\omega}$$

Properties of odd and even functions:

let $e_1(t)$ and $e_2(t)$ be even functions and $o_1(t)$ and $o_2(t)$ be odd functions

$$e_1(t) \pm e_2(t) = \text{even}$$

$$e_1(t) e_2(t) = \text{even}$$

$$o_1(t) \pm o_2(t) = \text{odd}$$

$$o_1(t) o_2(t) = \text{even}$$

$$e_1(t) o_2(t) = \text{odd}$$

Symmetry Properties

For any real, imaginary, or complex signal:

- an even signal has an even transform $f(t) = f(-t) \Rightarrow F(j\omega) = F(-j\omega)$

- an odd signal has an odd transform $f(t) = -f(-t) \Rightarrow F(j\omega) = -F(-j\omega)$

A real signal has Hermitian symmetry: $F(-j\omega) = F^*(j\omega)$

An imaginary signal has anti-Hermitian symmetry: $F(-j\omega) = -F^*(j\omega)$

<u>$f(t)$</u>	<u>$F(j\omega)$</u>
real + even	real + even
real + odd	imag + odd
imag + even	imag + even
imag + odd	real + odd

Systems

EE102A

L9

Fourier Transform-Theorems

Linearity: $a f_1(t) + b f_2(t) \Leftrightarrow a F_1(j\omega) + b F_2(j\omega)$

Scaling: $f(at) \Leftrightarrow \frac{1}{|a|} F\left(\frac{j\omega}{a}\right)$

Complex Conjugation: $f^*(t) \Leftrightarrow F^*(-j\omega)$

Duality: $F(j\omega) \Big|_{\omega \rightarrow t} \Leftrightarrow 2\pi f(-t) \Big|_{t \rightarrow \omega}$

Shift: $f(t-\tau) \Leftrightarrow e^{-j\omega\tau} F(j\omega)$

Modulation: $f(t) e^{j\omega_0 t} \Leftrightarrow F(j(\omega - \omega_0))$

$$f(t) \cos(\omega_0 t) \Leftrightarrow \frac{1}{2} (F(j(\omega - \omega_0)) + F(j(\omega + \omega_0)))$$

$$f(t) \sin(\omega_0 t) \Leftrightarrow \frac{1}{2} (F(j(\omega - \omega_0)) - F(j(\omega + \omega_0)))$$

Derivative: $f'(t) \Leftrightarrow j\omega F(j\omega)$

$$f^n(t) \Leftrightarrow (j\omega)^n F(j\omega)$$

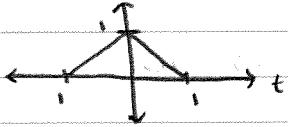
$$(-jt) f(t) \Leftrightarrow F'(j\omega) \quad \text{by duality}$$

Parsevals Theorem: $\mathcal{E}_f = \int_{-\infty}^{\infty} |f(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega$

Convolution: $(f_1 * f_2)(t) \Leftrightarrow F_1(j\omega) F_2(j\omega)$

↓

example: $\Delta(t) = \begin{cases} 1 - |t|, & |t| < 1 \\ 0, & \text{otherwise} \end{cases}$



$$= \text{rect}(t) * \text{rect}(t)$$

since $\text{rect}(t) \Leftrightarrow \text{sinc}\left(\frac{\omega}{2\pi}\right)$

$$\Delta(t) \Leftrightarrow \text{sinc}^2\left(\frac{\omega}{2\pi}\right)$$

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1. $D_n = \frac{1}{2} \int_{-1}^1 |t| e^{-jn\omega_0 t} dt \quad \omega_0 = \frac{2\pi}{T} = \pi$

$$\Rightarrow D_n = \frac{1}{2} \int_{-1}^0 -te^{-jn\pi t} dt + \frac{1}{2} \int_0^1 te^{-jn\pi t} dt = \frac{1}{2} \int_0^1 (te^{jn\pi t} + te^{-jn\pi t}) dt$$

$$= \frac{1}{2} \left(\frac{je^{-jn\pi}}{n\pi} + \frac{e^{-jn\pi} - 1}{(n\pi)^2} - \frac{je^{jn\pi}}{n\pi} + \frac{e^{jn\pi} - 1}{(n\pi)^2} \right)$$

$$= \frac{1}{2} \left(\frac{j(-1)^n}{n\pi} + \frac{(-1)^n - 1}{n\pi^2} - \frac{j(-1)^n}{n\pi} + \frac{(-1)^n - 1}{(n\pi)^2} \right) = \frac{(-1)^n - 1}{(n\pi)^2}$$

since $e^{j\pi} = e^{-j\pi} = -1$

$$\Rightarrow D_n = \begin{cases} \frac{1}{2}, & n = 0 \\ -\frac{2}{(n\pi)^2}, & n \text{ odd} \\ 0, & n \text{ even} \end{cases}$$

2. a) even

b) odd

c) real

d) real and even

e) imag and odd

f) imag and even

$$3. a) D_0 = \frac{1}{T} \int_0^T f(t) dt = \frac{\alpha T A}{T} = \alpha A$$

$$\alpha = \alpha A \Rightarrow \alpha = \frac{\alpha}{A}$$

$$\begin{aligned} b) D_1 &= \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-j2\pi t/T} dt = \frac{A}{T} \int_{-\pi T/2}^{\pi T/2} e^{-j2\pi t/T} dt = \frac{A}{T} \left(\frac{T}{-j2\pi} e^{-j2\pi t/T} \right) \Big|_{-\pi T/2}^{\pi T/2} \\ &= \frac{A}{\pi} \left(\frac{1}{-j2\pi} (e^{-j\pi\alpha} - e^{j\pi\alpha}) \right) = \frac{A}{\pi} \left(\frac{1}{2j} (e^{j\pi\alpha} - e^{-j\pi\alpha}) \right) \\ &= \frac{A}{\pi} \sin(\pi\alpha) = A\alpha \operatorname{sinc}(\pi\alpha) \end{aligned}$$

$$c) \alpha = \frac{1}{2}$$

$$1. a) f(t) = \Delta(t+1) + \Delta(t) + \Delta(t-1)$$

$$F(j\omega) = (e^{-j\omega} + 1 + e^{j\omega}) \operatorname{sinc}^2\left(\frac{\omega}{2\pi}\right) = (1 + 2\cos(\omega)) \operatorname{sinc}^2\left(\frac{\omega}{2\pi}\right)$$

$$b) f(t) = 2\Delta(t/2) - \Delta(t)$$

$$F(j\omega) = 4 \operatorname{sinc}^2\left(\frac{\omega}{\pi}\right) - \operatorname{sinc}^2\left(\frac{\omega}{2\pi}\right)$$

$$c) f(t) = \operatorname{rect}(t) * \operatorname{rect}(t/3)$$

$$F(j\omega) = 3 \operatorname{sinc}\left(\frac{\omega}{2\pi}\right) \operatorname{sinc}\left(\frac{3\omega}{2\pi}\right)$$

real + even \Leftrightarrow real + even

real + odd \Leftrightarrow imag + odd

$$f * g = F(j\omega) G(j\omega)$$

$$\text{even} \times \text{odd} = \text{odd} \quad \text{odd} \Leftrightarrow \text{odd} \quad \Rightarrow \boxed{\text{true}}$$

$$\text{imag} \times \text{real} = \text{imag} \quad \text{real} + \text{odd} \Leftrightarrow \text{imag} + \text{odd} \Rightarrow h(t) \text{ is real and odd}$$

b) odd * odd \Leftrightarrow odd * odd = even \Rightarrow false

c) $f(t) * f(-t) \Leftrightarrow F(j\omega) F(-j\omega)$ even \Rightarrow true

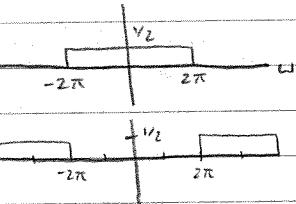
6. a) $f_1(t) = \text{sinc}(2t)$ $f_2(t) = \text{sinc}(t) \cos(3\pi t)$ $f(t) = (f_1 * f_2)(t)$

$$\text{rect}(t) \Leftrightarrow \text{sinc}\left(\frac{\omega}{2\pi}\right) \Rightarrow \text{sinc}\left(\frac{t}{2\pi}\right) \Leftrightarrow 2\pi \cdot \text{rect}(-\omega) = 2\pi \cdot \text{rect}(\omega)$$

$$\Rightarrow \text{sinc}(t) = \text{rect}\left(\frac{\omega}{2\pi}\right)$$

$$\Rightarrow F_1(j\omega) = \frac{1}{2} \text{rect}\left(\frac{\omega}{4\pi}\right)$$

$$F_2(j\omega) = \frac{1}{2} \left(\text{rect}\left(\frac{\omega+3\pi}{2\pi}\right) + \text{rect}\left(\frac{\omega-3\pi}{2\pi}\right) \right)$$



$$F(j\omega) = F_1(j\omega) F_2(j\omega) = 0 \Rightarrow F(j\omega) = 0$$

b) $f(t) = 0$ since $0 \Leftrightarrow 0$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} d\omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} 0 \cdot e^{j\omega t} d\omega = 0$$

7. $\int_{-\infty}^{\infty} \text{sinc}^2(t) \cos(2\pi t) dt$ $\cos(2\theta) = 2\cos^2(\theta) - 1$

$$\downarrow \int_{-\infty}^{\infty} \text{sinc}^2(t) (2\cos^2(\pi t) - 1) dt = 2 \int_{-\infty}^{\infty} (\text{sinc}(t) \cos(\pi t))^2 dt - \int_{-\infty}^{\infty} \text{sinc}^2(t) dt$$

$$\text{sinc}(t) \cos(\pi t) \Leftrightarrow \frac{1}{2} \left(\text{rect}\left(\frac{(t-\pi)}{2\pi}\right) + \text{rect}\left(\frac{(t+\pi)}{2\pi}\right) \right)$$

$$\text{sinc}(t) \Leftrightarrow \text{rect}\left(\frac{t}{2\pi}\right)$$

$$\Rightarrow \frac{2}{2\pi} \int_{-2\pi}^{2\pi} \left(\frac{1}{2}\right)^2 dt = \frac{1}{2\pi} \int_{-\pi}^{\pi} 1^2 dt = \frac{8\pi}{8\pi} - \frac{2\pi}{2\pi} = 1 - 1 = 0$$

Systems [EE102A] [L 10] Fourier Theorems + Generalized Fourier Transforms

$$\mathcal{F}[f(t)] = F(j\omega) \quad \mathcal{F}^{-1}[F(j\omega)] = f(t)$$

Frequency Domain Convolution Theorem:

$$\mathcal{F}[f_1(t)f_2(t)] = \frac{1}{2\pi} (F_1 * F_2)(j\omega)$$

$$\downarrow \text{e.g. } \mathcal{F}[\text{sinc}^2(t)] = \frac{1}{2\pi} (\text{rect}(\frac{\omega}{2\pi}) * \text{rect}(\frac{\omega}{2\pi})) = \Delta(\frac{\omega}{2\pi})$$

Generalized Fourier Transforms:

$$\delta(t) \Leftrightarrow 1$$

$$\delta(t-\tau) \Leftrightarrow e^{-j\omega\tau}$$

$$1 \Leftrightarrow 2\pi \delta(\omega)$$

$$e^{j\omega_0 t} \Leftrightarrow 2\pi \delta(\omega - \omega_0)$$

$$\cos(\omega_0 t) \Leftrightarrow \pi (\delta(\omega - \omega_0) + \delta(\omega + \omega_0))$$

$$\sin(\omega_0 t) \Leftrightarrow j\pi (\delta(\omega - \omega_0) - \delta(\omega + \omega_0))$$

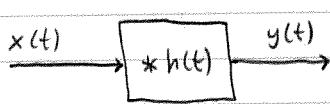
$$\text{sgn}(t) \Leftrightarrow \begin{cases} \frac{2}{j\omega}, & \omega \neq 0 \\ 0, & \omega = 0 \end{cases} \quad \text{where } \text{sgn}(t) = \begin{cases} -1, & t < 0 \\ 0, & t = 0 \\ 1, & t > 0 \end{cases}$$

$$u(t) \Leftrightarrow \pi \delta(\omega) + \frac{1}{j\omega}$$

Integral Theorem:

$$\int_{-\infty}^t f(\tau) d\tau \Leftrightarrow \pi F(0) \delta(\omega) + \frac{F(j\omega)}{j\omega}$$

For an LTI system:



$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$Y(j\omega) = H(j\omega) X(j\omega)$$

Scaled by system amplitude response $|H(j\omega)|$: $|Y(j\omega)| = |H(j\omega)| |X(j\omega)|$ Phase shifted by system phase response $\angle H(j\omega)$: $\angle Y(j\omega) = \angle H(j\omega) + \angle X(j\omega)$ If input is complex exponential: $x(t) = e^{j\omega_0 t}$, $X(j\omega) = 2\pi \delta(\omega - \omega_0)$

$$Y(j\omega) = H(j\omega) 2\pi \delta(\omega - \omega_0) = H(j\omega_0) 2\pi \delta(\omega - \omega_0)$$

$$\Rightarrow y(t) = H(j\omega_0) e^{j\omega_0 t} = |H(j\omega_0)| e^{j(\omega_0 t + \angle H(j\omega_0))}$$

Thus a sinusoidal input $e^{j\omega_0 t}$ to an LTI system produces a sinusoidal output at the:

- Same frequency
- Scaled in amplitude
- Phase shifted
- This corresponds to multiplication by a complex number $H(j\omega_0)$

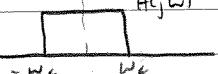
Note that magnitudes multiply and phases add.

Ideal Filters:



in general $h(t)$ will decay as $\frac{1}{t^n}$
where n is the number of times you
can differentiate $H(j\omega)$ before you
get impulses.

Lowpass:



$$H(j\omega) = \text{rect}\left(\frac{\omega}{2\omega_c}\right)$$

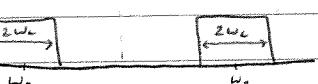
$$= \text{rect}\left(\frac{\pi}{\omega_c} \frac{\omega}{2\pi}\right) = \left(\frac{\pi}{\omega_c}\right)\left(\frac{\omega}{\pi}\right) \text{rect}\left(\frac{\pi}{\omega_c} \frac{\omega}{2\pi}\right) \Rightarrow h(t) = \frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c}{\pi} t\right)$$

Highpass:



$$H(j\omega) = 1 - \text{rect}\left(\frac{\omega}{2\omega_c}\right) \Rightarrow h(t) = \delta(t) - \frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c}{\pi} t\right)$$

Ideal Bandpass:



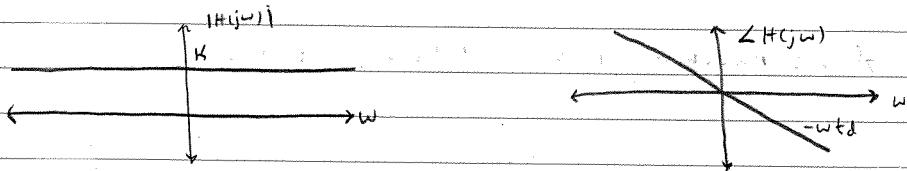
$$H(j\omega) = \text{rect}\left(\frac{\omega - \omega_0}{2\omega_c}\right) + \text{rect}\left(\frac{\omega + \omega_0}{2\omega_c}\right)$$

$$\Rightarrow h(t) = 2\cos(\omega_0 t) \frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c}{\pi} t\right)$$

Distortionless LTI Systems:

ideally we want: $y(t) = K \times (t - t_d)$ $\Rightarrow H(j\omega) = K e^{-j\omega t_d}$

such that $|H(j\omega)| = K$ $\angle H(j\omega) = -\omega t_d$ \leftarrow negative linear phase as a function of frequency \Rightarrow distortionless



Phase distortion and group delay:

Group delay is the frequency dependent negative slope of $\angle H(j\omega)$:

$$t_d(\omega) = -\frac{d}{d\omega} \angle H(j\omega)$$

Importance of Amplitude and Phase Distortion depends on Application:

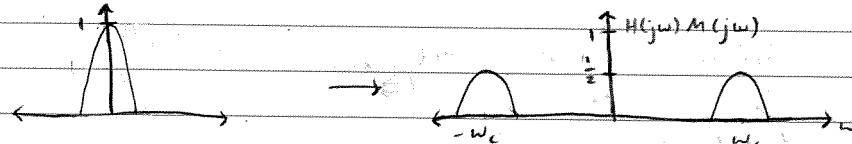
- Audio or Speech:
 - Amplitude distortion is very important
 - Humans are relatively insensitive to phase distortion

- Images or Video:
 - Phase distortion is very important.
Nonlinear phase \Rightarrow blurry images.
 - Amplitude distortion is relatively unimportant
as long as it is slowly varying.

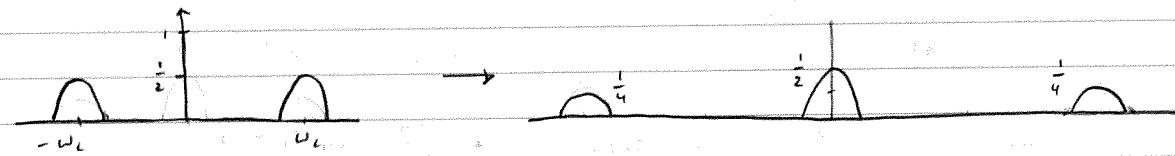
Systems **EE102A** **L12** Modulation and Demodulation

Double-Sideband, Suppressed Carrier (Multiply by a cosine)

$$m(t) \cos(\omega_c t) \Leftrightarrow \frac{1}{2} [M(j(\omega + \omega_c)) + M(j(\omega - \omega_c))]$$

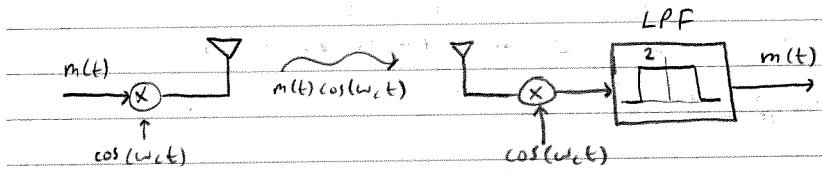


To demodulate, we multiply again by $\cos(\omega_c t)$



$$\begin{aligned} F(m(t) \cos^2(\omega_c t)) &= \frac{1}{2\pi} \left[\frac{1}{2} M(j(\omega + \omega_c)) + \frac{1}{2} M(j(\omega - \omega_c)) \right] \\ &\quad * [\pi \delta(\omega + \omega_c) + \pi \delta(\omega - \omega_c)] \\ &= \frac{1}{4} M(j(\omega + 2\omega_c)) + \frac{1}{2} M(j\omega) + \frac{1}{4} M(j(\omega - 2\omega_c)) \end{aligned}$$

Lowpass filtering extracts $M(j\omega)$



This is a synchronous receiver meaning that the transmitter and receiver must be in phase. Synchronizing the receiver requires a more complex system (PLL).

One solution is to demodulate with a complex exponential.

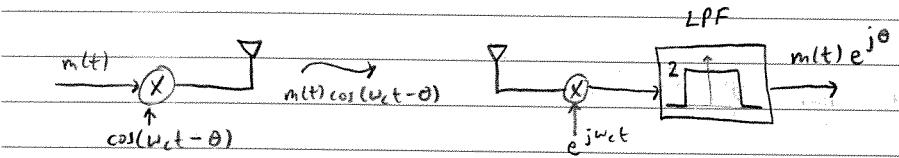
$$e^{j\omega_c t} \Leftrightarrow 2\pi \delta(\omega - \omega_c)$$

Then for an arbitrary phase shift θ between in the modulated signal:

$$\begin{aligned} F(\cos(\omega_c t - \theta)) &= F[\cos(\theta) \cos(\omega_c t) + \sin(\theta) \sin(\omega_c t)] \\ &\stackrel{\text{carrier}}{=} \cos\theta (\pi \delta(\omega + \omega_c) + \pi \delta(\omega - \omega_c)) + \sin\theta (\pi j \delta(\omega + \omega_c) - \pi j \delta(\omega - \omega_c)) \\ &= \pi (\cos\theta + j\sin\theta)(\delta(\omega + \omega_c)) + \pi (\cos\theta - j\sin\theta)(\delta(\omega - \omega_c)) \\ &\stackrel{\text{modulated}}{=} \pi e^{j\theta} \delta(\omega + \omega_c) + \pi e^{-j\theta} \delta(\omega - \omega_c) \end{aligned}$$

$$\Rightarrow F(m(t) \cos(\omega_c t - \theta)) = \frac{1}{2} e^{j\theta} M(j(\omega + \omega_c)) + \frac{1}{2} e^{-j\theta} M(j(\omega - \omega_c))$$

$$\Rightarrow F(m(t) \cos(\omega_c t - \theta) e^{j\omega_c t}) = \underbrace{\frac{1}{2} e^{j\theta} M(j\omega)}_{\text{demodulated}} + \underbrace{\frac{1}{2} e^{-j\theta} M(j(\omega - 2\omega_c))}_{\text{recovered signal.}}$$



This is a quadrature receiver.

Cost is that the receiver has to be implemented for complex signals. This is done by keeping track of two real signals, the real part and the imaginary part (the I and Q channels).

A cheap alternative that avoids the need for synchronization is AM modulation. We add a constant before multiplying:

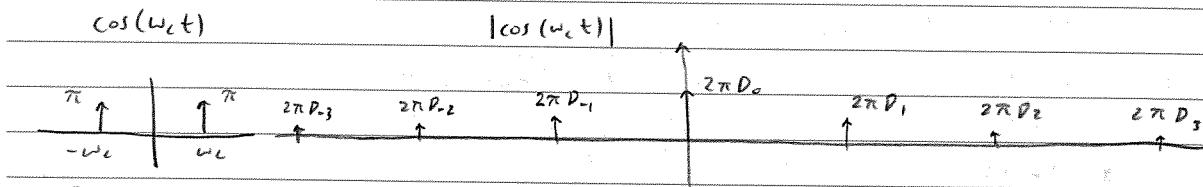
$$x_{AM}(t) = [A + m(t)] \cos(w_c t) \quad \text{such that } A + m(t) > 0$$

Simple receivers for these signals are envelope detectors: (rectifier \rightarrow LPF)

choose LPF such that $w_{LPF} < w_{3dB_m} < w_{3dB_{LPF}} < w_c$

$$F[|\cos(w_c t)|] = F\left[\sum_{n=-\infty}^{\infty} D_n e^{j 2n w_c t}\right] = \sum_{n=-\infty}^{\infty} D_n 2\pi \delta(\omega - 2n w_c)$$

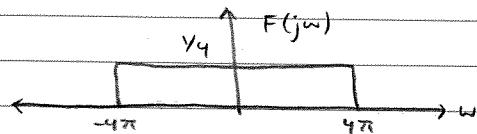
These are an array of δ 's separated by $2w_c$



EE102A PSET 5

$$1, a) f(t) = \operatorname{sinc}(2t) \cos(2\pi t) \Leftrightarrow \frac{1}{2\pi} \left(\frac{1}{2} \operatorname{rect}\left(\frac{\omega}{4\pi}\right) * (\pi \delta(\omega+2\pi) + \pi \delta(\omega-2\pi)) \right)$$

$$= \frac{1}{4} \operatorname{rect}\left(\frac{\omega+2\pi}{4\pi}\right) + \frac{1}{4} \operatorname{rect}\left(\frac{\omega-2\pi}{4\pi}\right) = \frac{1}{4} \operatorname{rect}\left(\frac{\omega}{8\pi}\right)$$



$$b) F(j\omega) = \frac{1}{4} \operatorname{rect}\left(\frac{\omega}{8\pi}\right) \Rightarrow f(t) = \operatorname{sinc}(4t)$$

$$\begin{aligned}
 2. a) \int_{-\infty}^{\infty} f_1(t) f_2^*(t) dt &= \int_{-\infty}^{\infty} f_1(t) \left(\frac{1}{2\pi} \int_{-\infty}^{\infty} F_2(j\omega) e^{j\omega t} d\omega \right)^* dt \quad (e^{j\omega t}^* = e^{-j\omega t}) \\
 &= \frac{1}{2\pi} \int_{-\infty}^{\infty} f_1(t) \int_{-\infty}^{\infty} F_2^*(j\omega) e^{-j\omega t} d\omega dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} F_2^*(j\omega) \int_{-\infty}^{\infty} f_1(t) e^{-j\omega t} dt d\omega \\
 &= \frac{1}{2\pi} \int_{-\infty}^{\infty} F_2^*(j\omega) F_1(j\omega) d\omega \quad \checkmark
 \end{aligned}$$

b) real signals have Hermitian symmetry: $F(-j\omega) = F^*(j\omega)$

$$\Rightarrow \int_{-\infty}^{\infty} f_1(t) f_2^*(t) dt = \int_{-\infty}^{\infty} f_1(t) f_2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} F_1(j\omega) F_2^*(j\omega) = \int_{-\infty}^{\infty} F_1(j\omega) F_2(-j\omega) \quad \checkmark$$

$$c) \text{sinc}(t-n) \Leftrightarrow e^{j\omega n} \text{rect}\left(\frac{\omega}{2\pi}\right)$$

$$\text{sinc}(t-m) \Leftrightarrow e^{j\omega m} \text{rect}\left(\frac{\omega}{2\pi}\right)$$

$$\Rightarrow \int_{-\infty}^{\infty} \text{sinc}(t-n) \text{sinc}(t-m) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega(m-n)} \text{rect}\left(\frac{\omega}{2\pi}\right) d\omega$$

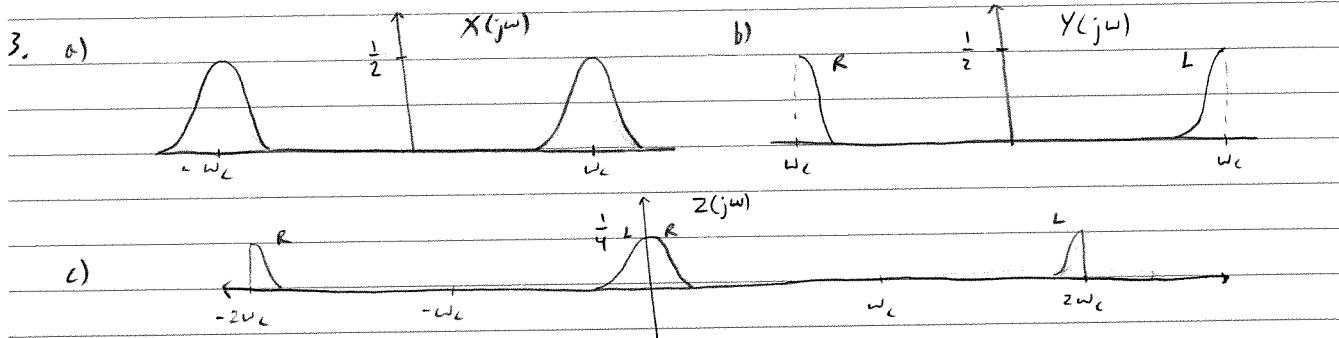
$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j\omega(m-n)} dw \quad \text{period of } e^{j\omega(m-n)} \text{ is } T_0 = \frac{2\pi}{(m-n)}$$

$\Rightarrow 2\pi = T_0(m-n)$ integral of a complex exponential over an integer number of periods is zero.

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j\omega 0} dw = \frac{1}{2\pi} \int_{-\pi}^{\pi} 1 dw = \frac{2\pi}{2\pi} = 1$$

$$\Rightarrow \int_{-\infty}^{\infty} \text{sinc}(t-n) \text{sinc}(t-m) dt = \begin{cases} 1, & n=m \\ 0, & n \neq m \end{cases} \quad \checkmark$$

\Rightarrow the set of sincs shifted by integer delays are an orthogonal set of signals.

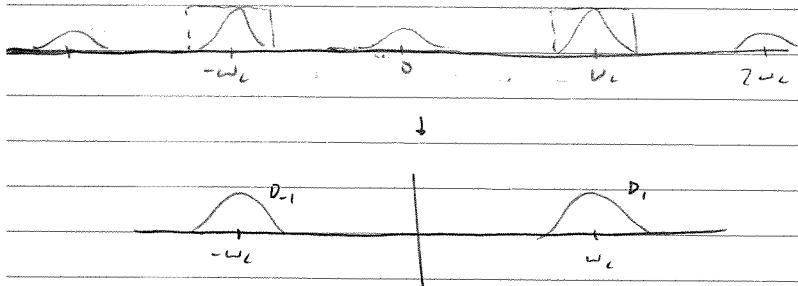


Yes, the system recovers $m(t)$.

$$\text{assume } T_0 = \frac{2\pi}{\omega_c}$$

4. F.S. of $f(t)$: $f(t) = \sum_{n=-\infty}^{\infty} D_n e^{jn\omega_c t}$ $\omega_c = \frac{2\pi}{T_0}$ $D_n = \frac{1}{T_0} \int_{-\frac{T_0}{2}}^{\frac{T_0}{2}} f(t) e^{-jn\omega_c t} dt$

$$\Rightarrow f(t) = \sum_{n=-\infty}^{\infty} D_n e^{jn\omega_c t} \quad D_0 = \int_0^T f(t) dt \neq 0 \quad D_1, D_{-1} \neq 0$$



b) $T = \frac{2\pi}{\omega_c}$ bandwidth is $2\pi B$ need $\omega_c = \frac{2\pi}{T} \geq 2\pi B$

$$\Rightarrow T \leq \frac{1}{B} \quad \text{Longest possible period is } \frac{1}{B}$$

Impulse Trains - Sampling Functions

$$\delta_T(t) = \sum_{n=-\infty}^{\infty} \delta(t-nT)$$

$$\delta_T(t) \Leftrightarrow \omega_0 \delta_{\omega_0}(\omega) \quad \omega_0 = \frac{2\pi}{T}$$

Ideal Sampling:

$$f(t) \delta_T(t) = \sum_{n=-\infty}^{\infty} f(nT) \delta(t-nT)$$

Fourier Transform of Periodic Signals:

if $f_1(t)$ is one cycle of a periodic function with period T ,

$$f(t) = f_1(t) * \delta_T(t) \Rightarrow F(j\omega) = \omega_0 F_1(j\omega) \delta_{\omega_0}(\omega) \quad \omega_0 = \frac{2\pi}{T}$$

\Rightarrow The Fourier transform of a periodic signal is the sampled Fourier transform of one period.

Sampling Theorem: F.T. of time-sampled signal:

$$\tilde{f}(t) = f(t) \delta_T(t) \quad \tilde{F}(j\omega) = \frac{1}{T} F(j\omega) * \delta_{\omega_0}(\omega) = \frac{1}{T} \sum_{n=-\infty}^{\infty} F(j(\omega-n\omega_0))$$

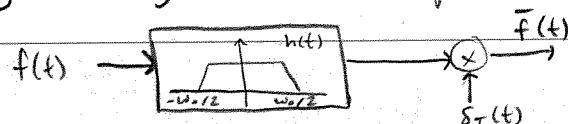
sampled signal

\Rightarrow The spectrum of the sampled signal consists of shifted replicas of the original spectrum scaled by $\frac{1}{T}$.

 Nyquist Rate: $\frac{1}{T} > 2B \leftarrow$ Nyquist rate.

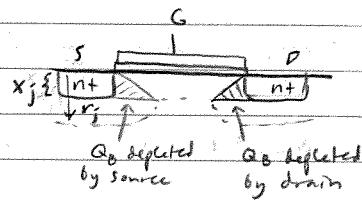
The signal can be recovered exactly (no aliasing) if sampling rate $\frac{1}{T}$ Hz is greater than the Nyquist rate ($2B$).

Minimizing Aliasing: First lowpass filter the signal, then sample:

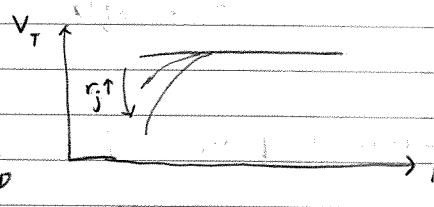
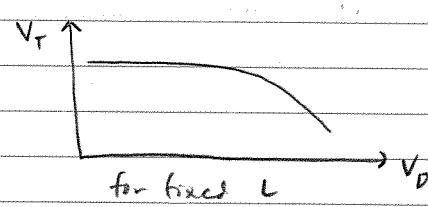
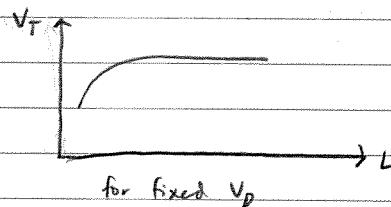


Short Channel Effects of Shallow Junctions:

$$V_T = V_{FB} - 2\phi_F = \frac{Q_0}{C_{ox}} \left[1 - \left(\sqrt{1 + \frac{2W_s}{r_j}} - 1 \right) \cdot \frac{r_j}{L} \right]$$



$\Rightarrow V_T$ is a function of junction depth, depletion width, & channel length



Roll-off in V_T as $L \downarrow$ and $V_D \uparrow$

To minimize V_T roll-off: $r_j \uparrow$, $C_{ox} \uparrow$ (to increase gate control)

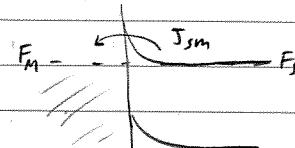
Sheet resistance increases as junction depth is reduced: (2009: $x_j \approx 15\text{nm}$)

\uparrow
 $R_{sh} \propto \frac{1}{N_{sd} x_j}$ N_{sd} limited by solid solubility \Rightarrow does not scale.

- Contact resistance is one of the dominant components for future technology. ($L < 1$)

- Silicidation of junctions reduces parasitic resistance.

Tunneling - Ohmic Contacts



$$x_d = \sqrt{\frac{2k\epsilon_0 \Phi_B}{3N_d}}$$

when $x_d \leq 2.5-5\text{nm}$, electrons can tunnel directly through the barrier.

Required doping is: $N_{dmin} = 6 \cdot 10^{19} \text{ cm}^{-3}$ for $x_d = 2.5\text{nm}$

$P(E)$ is tunneling probability: $P(E) \propto \exp\left(-\frac{2\Phi_B}{\hbar} \sqrt{\frac{\epsilon_s m^*}{N}}\right)$

$\Rightarrow J_{sm} \propto \exp\left(-2x_d \sqrt{2m^*(g\Phi_B - gV)/\hbar^2}\right)$ doping density

Specific contact resistivity $\rho_c = \rho_{co} \exp\left(\frac{2\Phi_B}{\hbar} \sqrt{\frac{\epsilon_s m^*}{N}}\right) \text{ } \Omega \cdot \text{cm}^2$

$\Rightarrow \rho_c \downarrow$ as doping density N \uparrow , barrier height $\Phi_B \downarrow$, effective mass $m^* \downarrow$

For a given doping density, contact resistance is higher for n-type than p-type Si since $\Phi_{Bn} > \Phi_{Bp}$

Fourier Transform:

- must exist or be defined in a generalized sense.
- usually exists for communications, optics, image processing.

BUT - For many signals + systems Fourier Transform doesn't exist

- signals that grow with time (e.g. bank account)
- unstable systems (many mechanical or electrical systems)
- For these cases, we must use the Laplace Transform.

Bilateral Laplace Transform:

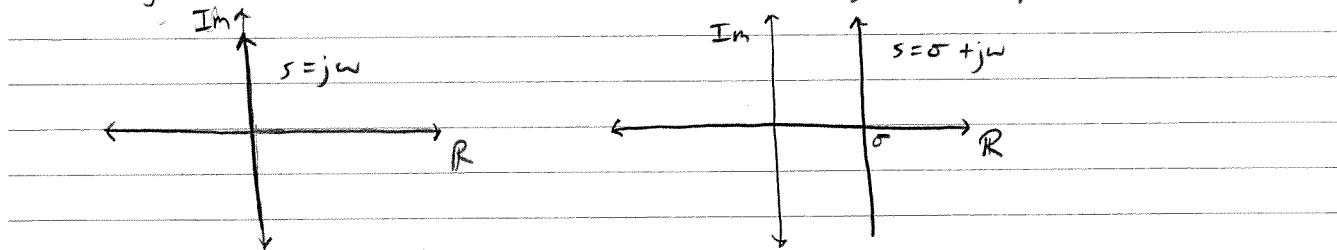
$$F(s) = \int_{-\infty}^{\infty} f(t) e^{-st} dt \quad \text{where } s = \sigma + j\omega$$

$$f(t) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} F(s) e^{st} ds \quad \text{where } c > \sigma_0 \quad (\text{but we will never use this})$$

Notation: $\mathcal{L}[f(t)] = F(s) \quad f(t) = \mathcal{L}^{-1}[F(s)] \quad f(t) \Leftrightarrow F(s)$

Fourier Transform is a special case of the Laplace Transform: $F(j\omega) = F(s)$, provided that the $j\omega$ axis is in the region of convergence.

\Rightarrow The Fourier transform is the Laplace transform evaluated along the $j\omega$ axis. It is also called the frequency response.

Main motivation for Laplace Transform:

- It converts integral + differential equations into algebraic equations.
- Handles growing exponentials + unstable systems
- Easily includes non-steady-state conditions.

Unilateral Laplace Transform: The Bilateral Laplace Transform for causal signals

$$F(s) = \int_0^{\infty} f(t) e^{-st} dt$$

Table of Laplace Transforms

<u>function</u>	<u>Laplace Transform</u>	<u>Property</u>
General:		
$f(t)$	$F(s) = \int_0^\infty f(t) e^{-st} dt$	definition
$f(t) + g(t)$	$F(s) + G(s)$	superposition } Linear
$\alpha f(t)$	$\alpha F(s)$	homogeneity }
f'	$sF(s) - f(0^-)$	differentiation
f''	$s^2 F(s) - sf(0^-) - f'(0^-)$	2nd derivative
$g(t) = \int_0^t f(\tau) d\tau$	$G(s) = \frac{1}{s} F(s)$	running integral
$f(\alpha t), \alpha > 0$	$\frac{1}{\alpha} F\left(\frac{s}{\alpha}\right)$	time scaling
$e^{at} f(t)$	$F(s-a)$	frequency shifting
$t f(t)$	$-\frac{dF(s)}{ds}$	multiplication by t
$t^k f(t)$	$(-1)^k \frac{d^k F(s)}{ds^k}$	"
$\frac{f(t)}{t}$	$\int_s^\infty F(s) ds$	division by t
$g(t) = \begin{cases} 0 & 0 < t < T \\ f(t-T) & t \geq T \end{cases}$	$G(s) = e^{-sT} F(s)$	time shift (delay)

<u>function</u>	<u>Laplace Transform</u>	<u>comment</u>
specific:		
$u(t)$ or 1	$\frac{1}{s}$	
δ	1	
δ^k	s^k	kth derivative of δ
t	$\frac{1}{s^2}$	ramp = $u(t) * u(t)$
t^k , $k \geq 0$	$\frac{k!}{s^{k+1}}$	powers of t
e^{at}	$\frac{1}{s-a}$	
$\cos(\omega t)$	$\frac{s}{s^2 + \omega^2}$	$= \frac{(1/2)}{s - j\omega} + \frac{(1/2)}{s + j\omega}$
$\sin(\omega t)$	$\frac{\omega}{s^2 + \omega^2}$	$= \frac{(1/2j)}{s - j\omega} - \frac{(1/2j)}{s + j\omega}$
$e^{-at} \cos(\omega t)$	$\frac{s+a}{(s+a)^2 + \omega^2}$	frequency shifting
$e^{-at} \sin(\omega t)$	$\frac{\omega}{(s+a)^2 + \omega^2}$	" "

Systems EE102A L15 Inversion of the Laplace Transform

$$f(t) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} F(s) e^{st} dt \quad \leftarrow \text{complicated}$$

Simpler approach: rewrite rational Laplace transform in simple terms we recognize & can invert by inspection (partial fraction)

Partial Fraction Expansion:

$$F(s) = \frac{b(s)}{a(s)} = \frac{r_1}{s-\lambda_1} + \dots + \frac{r_n}{s-\lambda_n}$$

residues.

roots of $a(s)$, poles of F

Heaviside "Cover-up" procedure: $r_k = (s-\lambda_k) F(s) \Big|_{s=\lambda_k}$

$$\text{e.g. } \frac{s^2-2}{s(s+1)(s+2)} = \frac{r_1}{s} + \frac{r_2}{s+1} + \frac{r_3}{s+2}$$

$$\Rightarrow r_1 = \frac{0-2}{(1)(2)} = -1 \quad r_2 = \frac{1-2}{-1(1)} = 1 \quad r_3 = \frac{4-2}{-2(-1)} = 1 \quad \checkmark$$

Another Method: $r_k = \frac{b(\lambda_k)}{a'(\lambda_k)}$

$$\text{e.g. } \frac{s^2-2}{s(s+1)(s+2)} = \frac{s^2-2}{s^3+3s^2+2s} \Rightarrow a'(s) = 3s^2+6s+2$$

$$\Rightarrow r_1 = \frac{0-2}{2} = -1 \quad r_2 = \frac{1-2}{3-6+2} = 1 \quad r_3 = \frac{4-2}{12-12+2} = 1 \quad \checkmark$$

Last resort: Clear Fractions, solve linear equations:

$$\frac{s^2-2}{s(s+1)(s+2)} = \frac{r_1}{s} + \frac{r_2}{s+1} + \frac{r_3}{s+2}$$

$$\Rightarrow s^2-2 = r_1(s+1)(s+2) + r_2(s)(s+2) + r_3(s)(s+1)$$

equate coefficients of s^2, s, s^0 . solve for r_1, r_2, r_3 .

Nonproper Rational Functions: if order of $a(s) \leq$ order of $b(s)$

\Rightarrow divide a into b using long division.

Systems EE102A PSET 5

(woops. I've already
done this PSET)

a) $f(t) = \text{sinc}(2t) \cos(2\pi t)$

$$\text{rect}(t) \Leftrightarrow \text{sinc}\left(\frac{\omega}{2\pi}\right) \Rightarrow \text{by duality} \quad \text{sinc}\left(\frac{t}{2\pi}\right) \Leftrightarrow 2\pi \text{rect}(\omega)$$

$$\Rightarrow \text{sinc}(t) \Leftrightarrow \text{rect}\left(\frac{\omega}{2\pi}\right) \Rightarrow \text{sinc}(2t) \Leftrightarrow \frac{1}{2} \text{rect}\left(\frac{\omega}{4\pi}\right)$$

$$\cos(2\pi t) \Leftrightarrow \pi (\delta(\omega - 2\pi) + \delta(\omega + 2\pi))$$

$$\Rightarrow F(j\omega) = \frac{1}{2\pi} \left(\frac{1}{2} \text{rect}\left(\frac{\omega}{4\pi}\right) * (\pi (\delta(\omega - 2\pi) + \delta(\omega + 2\pi))) \right) = \frac{1}{4} \text{rect}\left(\frac{\omega}{8\pi}\right)$$

b) $f(t) = F^{-1}\left(\frac{1}{4} \text{rect}\left(\frac{\omega}{8\pi}\right)\right) = \text{sinc}(4t)$

Systems EE102A PSET 6

1. $f(t) = \text{sinc}^2\left(\frac{t}{3}\right) (\Delta(3t) * \delta_1(t))$

$$\text{sinc}(t) \Leftrightarrow \text{rect}\left(\frac{\omega}{2\pi}\right) \Rightarrow \text{sinc}^2(t) \Leftrightarrow \Delta\left(\frac{\omega}{2\pi}\right) \Rightarrow \text{sinc}^2\left(\frac{t}{3}\right) \Leftrightarrow 3\Delta\left(\frac{3\omega}{2\pi}\right)$$

$$\text{rect}(t) \Leftrightarrow \text{sinc}\left(\frac{\omega}{2\pi}\right) \Rightarrow \Delta(t) \Leftrightarrow \text{sinc}^2\left(\frac{\omega}{2\pi}\right) \Rightarrow \Delta(3t) \Leftrightarrow \frac{1}{3} \text{sinc}^2\left(\frac{\omega}{6\pi}\right)$$

$$\delta_1(t) \Leftrightarrow \omega_0, \delta_{\omega_0}(\omega) \Rightarrow \delta_1(t) \Leftrightarrow 2\pi \delta_{2\pi}(\omega)$$

$$\Delta(3t) * \delta_1(t) \Leftrightarrow \frac{1}{3} \text{sinc}^2\left(\frac{\omega}{6\pi}\right) * 2\pi \delta_{2\pi}(\omega)$$

$$\text{sinc}^2\left(\frac{t}{3}\right) (\Delta(3t) * \delta_1(t)) \Leftrightarrow 3\Delta\left(\frac{3\omega}{2\pi}\right) * (\text{sinc}^2\left(\frac{\omega}{6\pi}\right) \delta_{2\pi}(\omega))$$

$$= \sum_{n=-\infty}^{\infty} \text{sinc}^2\left(\frac{n}{3}\right) \Delta\left(\frac{3(\omega - 12\pi n)}{2\pi}\right)$$

2. a) $r(t) = f(t) \cos(\omega_c t) \delta_{\frac{2\pi}{\omega_c}}(t)$

$$\Rightarrow R(j\omega) = \frac{1}{2\pi} F(f(t) \cos(\omega_c t)) * \omega_c \delta_{\omega_c}(\omega) = \frac{\omega_c}{4\pi} (F(j(\omega + \omega_c)) + F(j(\omega - \omega_c))) * \delta_\omega$$

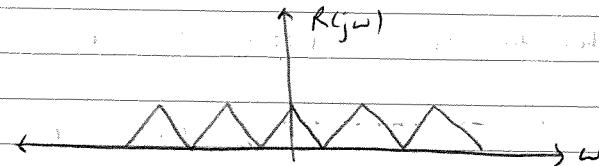
$$\uparrow \frac{1}{T} F(j\omega)$$



with the largest $n \in \mathbb{Z}$

Nyquist

b) $\omega_{\min} = \frac{\omega_c}{n} \wedge$ such that $\frac{\omega_c}{n} \geq 2(2\pi B) = 4\pi B$



3. a) $\tilde{f}(t) = \bar{f}(t) * p(t) = \bar{f}(t) * \text{rect}\left(\frac{4t}{T}\right)$ $\text{rect}(t) \Leftrightarrow \frac{T}{4} \text{sinc}\left(\frac{\omega T}{2\pi}\right)$

b) $\tilde{F}(j\omega) = \frac{T}{4} \text{sinc}\left(\frac{\omega T}{8\pi}\right) \bar{F}(j\omega)$

c) No. The filter will extract $F(j\omega) \left(\frac{T}{4} \text{sinc}\left(\frac{\omega T}{8\pi}\right) \right)$

d) $H_r(j\omega) = \frac{\text{rect}\left(\frac{\omega T}{2\pi}\right)}{\left(\frac{T}{4} \text{sinc}\left(\frac{\omega T}{8\pi}\right)\right)}$

4. a) $f(t) = \delta_2(t) + \delta_2(t-1-\tau)$

b) $F(j\omega) = \pi \delta_\pi(\omega) + e^{-j\omega(1+\tau)} \pi \delta_\pi(\omega) = \pi (1 + e^{-j\omega(1+\tau)}) \delta_\pi(\omega)$

$$= \sum_{n=-\infty}^{\infty} \pi (1 + e^{-j\omega(1+\tau)}) \delta(\omega - n\pi) = \pi \sum_{n=-\infty}^{\infty} (1 + e^{jn\pi(1+\tau)}) \delta(\omega - n\pi)$$

$$= \pi \sum_{n=-\infty}^{\infty} \delta(\omega - n\pi) (1 + e^{jn\pi} e^{-jn\pi\tau}) = \pi \sum_{n=-\infty}^{\infty} \delta(\omega - n\pi) (1 + (-1)^n e^{-jn\pi\tau})$$

c) $F(j\omega) \Big|_{\tau=0} = \pi \sum_{n=-\infty}^{\infty} \delta(\omega - n\pi) (1 + (-1)^n) = 2\pi \sum_{n=-\infty}^{\infty} \delta(\omega - 2\pi n) = 2\pi \delta_{2\pi}(\omega)$

d)

e) $g(t)$ is real + even real \Rightarrow hermitian $G(-j\omega) = G^*(j\omega)$
 even \Rightarrow even. $G(-j\omega) = G(j\omega)$
 $\Rightarrow G(j\omega)$ is real + even.

Yes. We can reconstruct $G(j\omega)$. We just need to LPF $\bar{G}(j\omega)$ and take the real part.

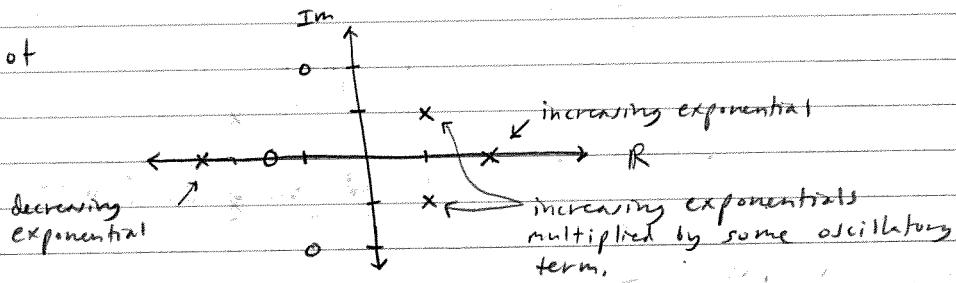
Laplace Transforms allow us to solve LCCODE's.

LCCODE's have rational transfer functions $H(s) = \frac{b(s)}{a(s)}$ of the form:

$$H(s) = \frac{b_0 + b_1 s + \dots + b_m s^m}{a_0 + a_1 s + \dots + a_n s^n} = k \frac{(s-z_1) \dots (s-z_m)}{(s-p_1) \dots (s-p_n)} \quad \begin{matrix} \leftarrow \text{zeros} \\ \leftarrow \text{poles} \end{matrix} \quad k = \frac{b_m}{a_n}$$

When coefficients of $a(s)$ & $b(s)$ are all real, the poles and zeros of $H(s)$ (roots of $b(s)$ and $a(s)$) are real or come in complex pairs.

Pole-Zero Plot



If the poles of $H(s)$ are p_1, \dots, p_n the asymptotic growth (or decay) rate of $h(t)$ is determined by the maximum real parts

$\alpha = \max \{ R(p_1), \dots, R(p_n) \}$ poles which achieve this max real part are called dominant.

$$\text{e.g. } H(s) = \frac{100}{s+2} + \frac{1}{s+1} \Rightarrow h(t) = 100 e^{-2t} + e^{-t}$$

System is stable only when all poles of $H(s)$ have negative real part (roots of $a(s)$ in left half plane).

Characteristic Equation: The poles of a system depend only on the coefficients of:

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_0 y = 0$$

With zero initial conditions, the Laplace transform of this equation is:

$$Y(s) [a_n s^n + a_{n-1} s^{n-1} + \dots + a_0] = 0$$

The polynomial is the characteristic polynomial for the system:

$$X(s) = a_n s^n + a_{n-1} s^{n-1} + \dots + a_0$$

First Order System: $X(s) = a_1 s + a_0$

has single pole at $\lambda = -a_0/a_1$ and corresponds to a simple exponent

stable if pole is in left half plane $\Rightarrow -\frac{a_0}{a_1} < 0$

Stable iff both $a_1 > 0$ and $a_0 > 0$ (coefficients all positive)

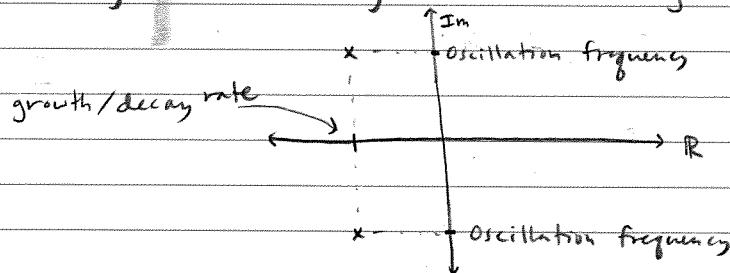
Second Order System: $X(s) = a_2 s^2 + a_1 s + a_0 = s^2 + bs + c$

has 2 poles: $\lambda_{1,2} = -\left(\frac{b}{2}\right) \pm \sqrt{\left(\frac{b}{2}\right)^2 - c}$

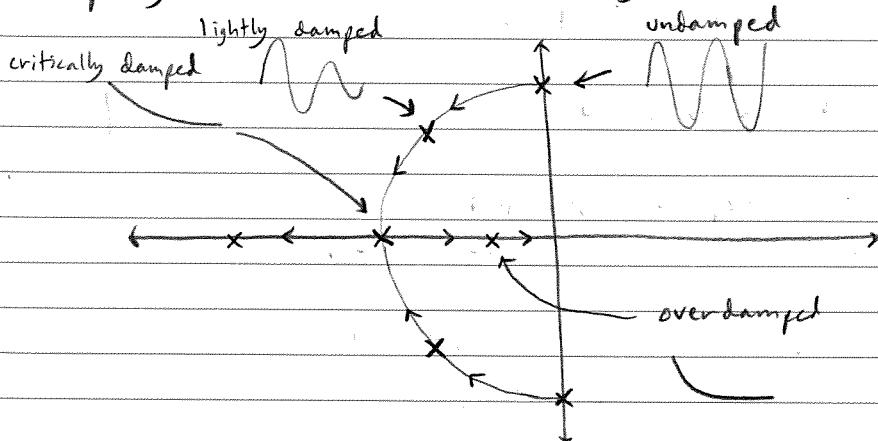
Stable iff $a_2 > 0$, $a_1 > 0$, and $a_0 > 0$ (coefficients all posit)

Properties of Complex Pole Pair

$\lambda = \sigma + j\omega$ $\lambda^* = \sigma - j\omega \Rightarrow \lambda + \lambda^*$ give the time-domain term $a e^{\sigma t} \cos \omega t$



Damping of Second Order Systems



Critically damped case has fastest decay rate. This is often a good design choice.

For a complex system, typically either a single pole or complex pair will be dominant.

You can tell a lot about the system by the characteristics of this dominant pole: (without having to explicitly solve for the time response

- Stability, Type of solution, Rate of Decay.

Systems [EE102A] [L17] Frequency Response, Bode Plots, and Filters

The Laplace transform $H(s)$ exists for any $s = \sigma + j\omega$ in the region of convergence.

One special case is when $\sigma = 0$ and $s = j\omega$. This corresponds to the Fourier transform, and $H(j\omega)$ is called the Frequency Response of the system.

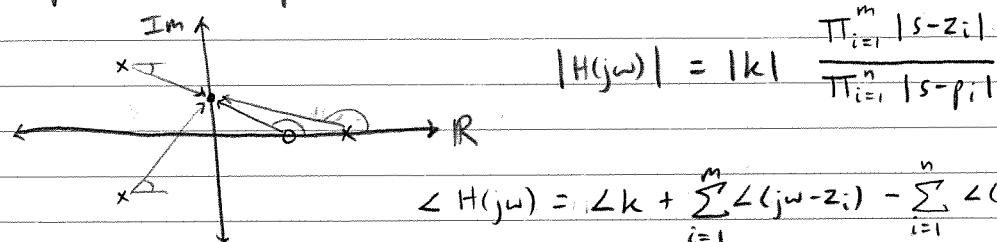
The frequency response characterizes the system in steady state (after the transients have died out).

2 applications of frequency response: Filter Design + Feedback Control.

$$\text{Bode Plots: } 20 \log_{10} |H(j\omega)| = 20 \log_{10} |k| + \sum_{i=1}^m 20 \log_{10} |j\omega - z_i| - \sum_{i=1}^n 20 \log_{10} |j\omega - p_i|$$

$$\angle H(j\omega) = \angle k + \sum_{i=1}^m \angle (j\omega - z_i) - \sum_{i=1}^n \angle (j\omega - p_i)$$

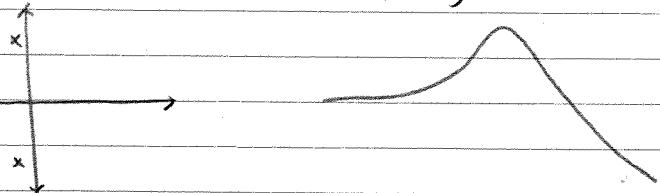
Graphical Interpretation: $|H(j\omega)|$, $\angle H(j\omega)$



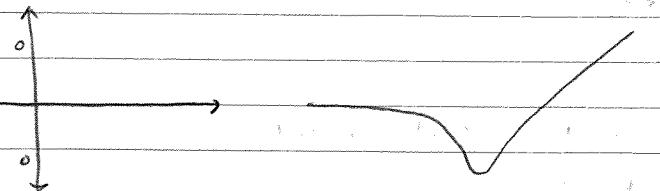
$\Rightarrow |H(j\omega)|$ gets big when $j\omega$ is near a pole
 $|H(j\omega)|$ gets small when $j\omega$ is near a zero

$\angle H(j\omega)$ changes rapidly when $j\omega$ is near a pole or zero.

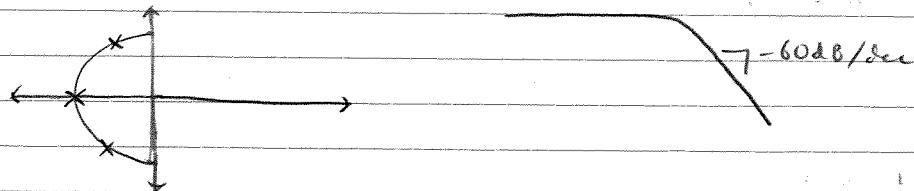
Gain Enhancement by Poles



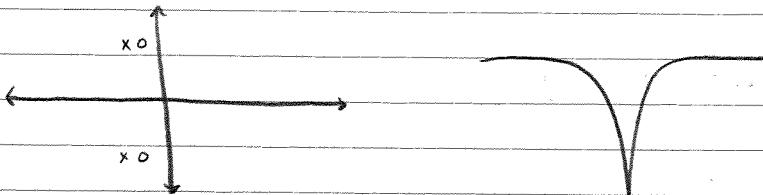
Gain Suppression by Zeros



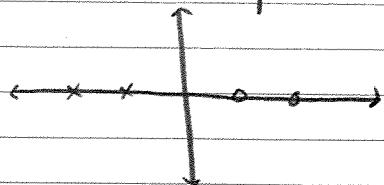
Butterworth Filter



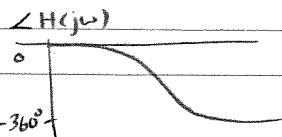
Notch Filter



Allpass Filter

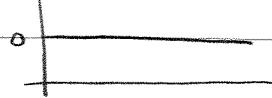


$$H(s) = \frac{(s-1)(s-3)}{(s+1)(s+3)}$$

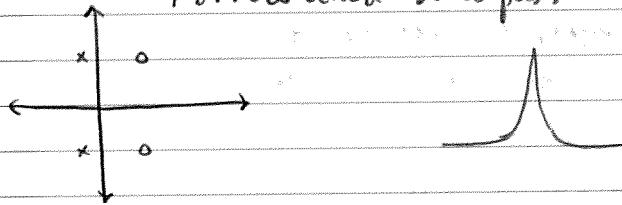


$$|H(j\omega)| = 1, \forall \omega$$

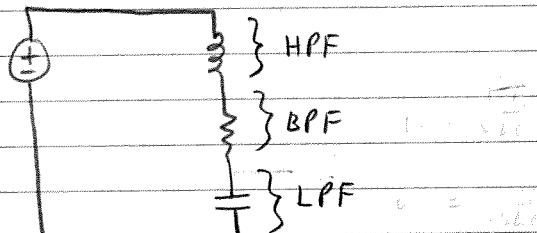
$$20 \log_{10} |H(j\omega)|$$



Narrow band band pass.



RLC Circuit Examples.



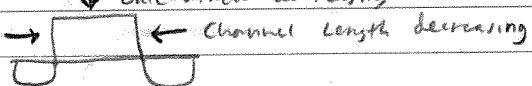
Devices

EE311 L4

Silicided & Metal Gates

1/17/2012

MOS Gate Electrode



As channel length is scaled, gate resistance increases.

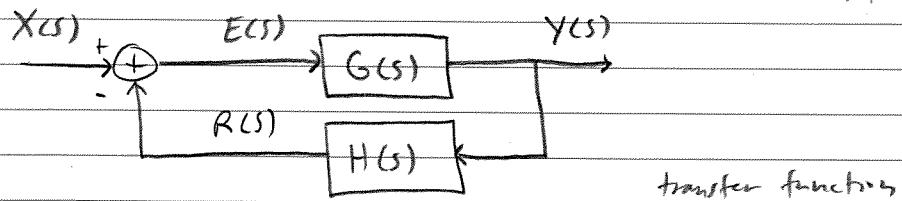
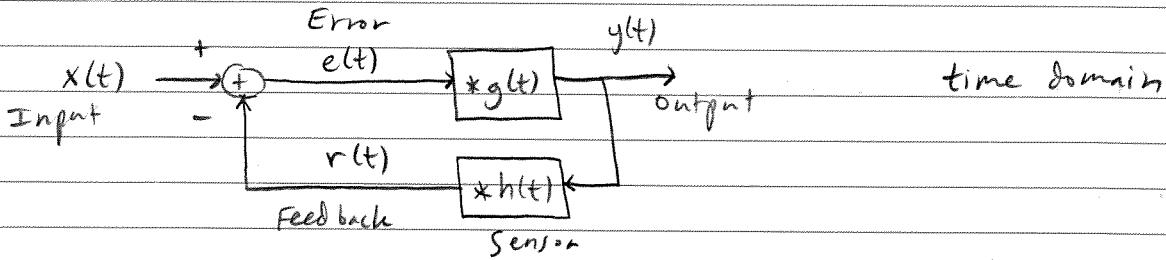
- Gate electrode is also used as an interconnect layer in many applications.

Silicidation of junctions is necessary to minimize the impact of junction parasitic resistance

Why we use silicides:

- Silicides are Si - metal compounds,
- Low resistance
- Good process compatibility with Si,
- Little or no electromigration.
- Easy to dry etch,
- Good contacts to other materials,

- Feedback:
- reduces sensitivity to parameter variation
 - reduces sensitivity to external interference,
 - reduces nonlinearity



$$Y(s) = (X(s) - H(s)Y(s))G(s) \Rightarrow T(s) = \frac{G(s)}{1 + G(s)H(s)}$$

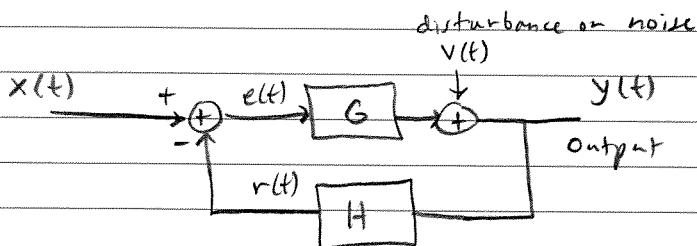
$G(s)H(s)$ is Loop Gain

Can trade gain for sensitivity.

$$S = \frac{\Delta T/T}{\Delta G/G} = \frac{1}{1+GH} \quad \text{reduced by } 1+GH$$

loop gain.

Reducing Effects of Disturbances with Feedback:



$$y(t) \Big|_{v(t)=0} = \frac{G}{1+GH} x(t) \quad y(t) \Big|_{x(t)=0} = \frac{1}{1+GH} v(t)$$

$$\Rightarrow y(t) = \frac{G}{1+GH} x(t) + \frac{1}{1+GH} v(t)$$

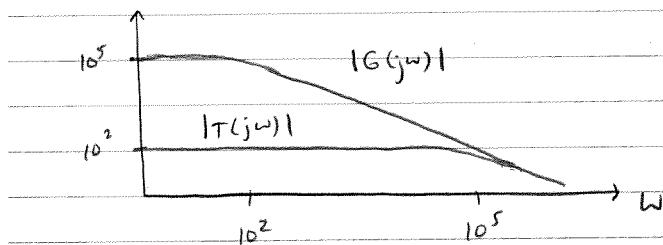
$$\text{if } GH \gg 1, \quad y(t) \approx \frac{1}{H} x(t) + \frac{1}{GH} v(t)$$

\Rightarrow interference is suppressed by the reciprocal of the loop gain, while the closed loop transfer function has a gain of the reciprocal of the feedback gain.

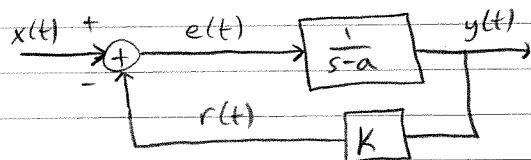
Can also trade gain for improved linearity.

For dynamic systems:

Can trade gain for bandwidth.



Stabilization of Unstable Systems:

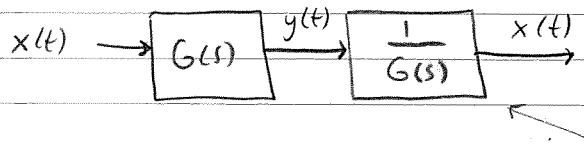


The plant has a transfer function that is an increasing exponential ($a > 0$). It is unstable.

$$T(s) = \frac{G(s)}{1+G(s)H(s)} = \frac{\frac{1}{s-a}}{1+\frac{K}{s-a}} = \frac{1}{s-a+K}$$

this is stable for $K > a$. \Rightarrow we can get any decay rate with enough feedback gain.

Inverse Systems



One way to implement this inverse system is with feedback:

$$x(t) \xrightarrow{+} K \xrightarrow{-} G(s) \xrightarrow{y(t)} T(s) = \frac{K}{1 + KG(s)}$$

for frequencies where $KG(s) \gg 1$

$$T(s) \approx \frac{1}{G(s)}$$

Feedback Summary:

Can be used to

- Reduce sensitivity to system variations
- Suppress the effect of disturbances or noise
- Improve the linearity of a non-linear system

The costs of feedback are

- Increased complexity
- Reduced gain
- Potential instability.

← Systems EE102A L19 Overview and Conclusions

Key ideas:

- Linearity & Time Invariance
- Convolution systems
- Complex exponentials, and transfer functions
- Representation of signals by linear combos of complex exponentials
 - Fourier Series
 - Fourier Transform
- Convolution becomes multiplication (and vice versa)
- Communications and modulation

- Sampling and reconstruction
- Even unstable signals can have transforms
 - Laplace Transform
- Solving for the evolution of dynamic systems
- Steady state frequency response
- Feedback and automatic control.

Complex exponential $e^{j\omega t}$ is an eigenfunction of LTI system with eigenvalue $H(j\omega)$

Since complex exponentials are so easy to analyze for LTI systems, we'd like to represent arbitrary signals as linear combinations of complex exponentials.

- If $f(t)$ is periodic or of finite duration: Fourier Series

$$f(t) = \sum_{n=-\infty}^{\infty} D_n e^{jn\omega_0 t} \quad D_n = \frac{1}{T_0} \int_{-\infty}^{T_0} f(t) e^{-jn\omega_0 t} dt$$

where T_0 is the fundamental period and $\omega_0 = \frac{2\pi}{T_0}$

- If $f(t)$ is aperiodic, but is an energy or power signal: Fourier Transform

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(j\omega) e^{j\omega t} dt \quad F(j\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$

- If $f(t)$ is not a power signal, we use the Laplace Transform

$$f(t) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} F(s) e^{st} dt \quad F(s) = \int_{-\infty}^{\infty} f(t) e^{-st} dt$$

Although the specifics differ, all of these have similar characteristics:

- Expanding a signal in time compresses it in frequency.
- Time shift \rightarrow multiplication by complex exponential in frequency.
- Multiplication by a complex exponential in time \rightarrow frequency shift.
- Convolution in time domain \rightarrow multiplication in frequency
- Multiplication in time domain \rightarrow convolution in frequency domain

Convergence:

Frequency domain representations:

- Converge to the midpoint of a discontinuity
- Oscillate at either side of discontinuity (Gibbs Effect)

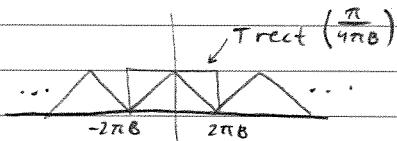
Impulse Trains: $\delta_T(t) \Leftrightarrow \omega_0 \delta_{\omega_0}(\omega)$ relates F.S. to F.T.

If $f_i(t)$ is one cycle of a periodic function $f(t)$ with period T :

$$f(t) = f_i(t) * \delta_T(t) \Rightarrow F(j\omega) = \omega_0 F_i(j\omega) \delta_{\omega_0}(\omega)$$

\Rightarrow F.T. of periodic signal is sampled F.T. of one period.

Sampling:



\Rightarrow LPF with $H(j\omega) = T \text{rect}\left(\frac{\pi}{4\pi B}\right)$ $h(t) = \text{sinc}(2Bt)$
to recover $f(t)$ from $\bar{f}(t)$

Reconstructed signal is:

$$\bar{f}(t) * h(t) = \left(\sum_{n=-\infty}^{\infty} f(nT) \delta(t-nT) \right) * h(t) = \sum_{n=-\infty}^{\infty} f(nT) \text{sinc}(2Bt-n)$$

This is the Shannon sampling theorem

Periodic signals have sampled spectra.

Sampled signals have periodic spectra.

Dynamic Systems: Laplace Transform

Differentiation: multiply by s : $f'(t) \rightarrow sF(s) - f(0)$

Integration: multiply by $1/s$: $\int_0^t f(\tau) d\tau \rightarrow \frac{1}{s} F(s)$

EE102A PSET 7

$$1. \text{ a) } f(t) = (1-t^2)e^{-2t} = e^{-2t} - t^2e^{-2t}$$

$$t^k f(t) \Leftrightarrow (-1)^k \frac{d^k F(s)}{ds^k}$$

$$\Rightarrow t^2 e^{-2t} \Leftrightarrow (-1)^2 \frac{d^2}{ds^2} \left(\frac{1}{s+2} \right) = \frac{d}{ds} \left(\frac{-1}{(s+2)^2} \right) = \frac{2(s+2)}{(s+2)^4} = \frac{2}{(s+2)^3}$$

$$\Rightarrow F(s) = \frac{1}{s+2} - \frac{2}{(s+2)^3} = \frac{s^2 + 4s + 2}{(s+2)^4}$$

$$\text{b) } f(t) = \begin{cases} 0 & 0 \leq t < 1 \\ 1 & 1 \leq t < 2 \\ e^{-2(t-2)} & 2 \leq t \end{cases}$$

$$= u(t-1) - u(t-2) + e^{-2(t-2)}$$

$$\Rightarrow F(s) = e^{-s} \frac{1}{s} - e^{-2s} \frac{1}{s} + e^{-2s} \left(\frac{1}{s+2} \right)$$

$$= \frac{e^{-s}}{s} + e^{-2s} \left(\frac{-2}{s+s(s+2)} \right)$$

$$= \frac{(s+2)e^{-s} - 2e^{-2s}}{s(s+2)} = \frac{se^{-s} + 2(e^{-s} - e^{-2s})}{s(s+2)}$$

$$2. \quad f(t) = \begin{cases} \sin(2\pi t) & 0 \leq t < 1 \\ 0 & 1 \leq t \end{cases}$$

$$f(t) = \sin(2\pi t) - \sin(2\pi(t-1))$$

$$= \frac{2\pi}{s^2 + 4\pi^2} - \frac{2\pi}{s^2 + 4\pi^2} e^{-s} = \frac{2\pi}{s^2 + 4\pi^2} (1 - e^{-s})$$

$$3. \quad f(t) = \left(\frac{1}{2} + \frac{1}{2} \cos(4\pi t) \right) e^{-t} \Leftrightarrow \frac{1}{2} \left(\frac{s+1}{(s+1)^2 + 16\pi^2} + \frac{1}{(s+1)} \right)$$

$$4. \text{ a) } \frac{s^2}{(s+1)^2} \quad \frac{1}{s^2 + 2s + 1} = \frac{1}{s^2} \quad \Rightarrow \quad 1 - \frac{2s+1}{(s+1)^2}$$

$$\frac{2s+1}{(s+1)^2} = \frac{r_1}{(s+1)^2} + \frac{r_2}{s+1} \Rightarrow r_1 = -1 \quad r_2 = 2$$

$$\Rightarrow 1 + \frac{1}{(s+1)^2} - \frac{2}{s+1} \Rightarrow f(t) = (\delta(t) + te^{-t} - 2e^{-t})u(t)$$

$$\Rightarrow f(t) = (\delta(t) + (t-2)e^{-t})u(t)$$

$$b) \frac{4}{s^3+4s} = \frac{4}{s(s^2+4)} = \frac{r_1}{s} + \frac{r_2 s + r_3}{s^2+4} \Rightarrow r_1 = 1$$

$$; r_2 = \lim_{s \rightarrow \infty} \left(\frac{4}{(s^2+4)} - r_1 \right) = -r_1 = -1 \Rightarrow r_2 + r_3 = -1 \Rightarrow r_3 = 0$$

$$\Rightarrow \frac{1}{s} - \frac{s}{s^2+4} \Rightarrow f(t) = (1 - \cos(2t))u(t)$$

$$c) \frac{s+3}{(s+1)^2(s+2)} = \frac{r_1}{s+2} + \frac{r_2 s + r_3}{(s+1)^2}$$

$$r_1 = 1, r_2 = -r_1 = -1$$

$$r_2 + r_3 = 2 \Rightarrow r_3 = 3 \Rightarrow \frac{1}{s+2} + \frac{-s+3}{(s+1)^2}$$

$$\frac{s+3}{(s+1)^2(s+2)} = \frac{r_1}{s+2} + \frac{r_2}{s+1} + \frac{r_3}{(s+1)^2} \quad r_1 = 1, r_3 = 2, r_2 = -1$$

$$\Rightarrow \frac{1}{s+2} - \frac{1}{s+1} + \frac{2}{(s+1)^2} \Rightarrow f(t) = e^{-2t} - e^{-t} + 2te^{-t}$$

$$\Rightarrow f(t) = e^{-2t} + (2t-1)e^{-t}$$

$$d) \frac{10}{(s+1)(s^2+4s+13)} = \frac{10}{(s+1)((s+2)^2+9)} = \frac{r_1}{s+1} + \frac{r_2 s + r_3}{((s+2)^2+9)}$$

$$r_1 = 1 \quad r_2 = -r_1 = -1 \quad r_3 = -3$$

$$\Rightarrow \frac{1}{s+1} - \frac{s+3}{(s+2)^2+9} = \frac{1}{s+1} - \frac{s+2}{(s+2)^2+9} - \frac{1}{3} \frac{3}{(s+2)^2+9}$$

$$\Rightarrow f(t) = e^{-t} - e^{-2t} \cos(3t) - \frac{1}{3} e^{-2t} \sin(3t)$$

$$\Rightarrow f(t) = e^{-t} - e^{-2t} (\cos(3t) + \frac{1}{3} \sin(3t))$$

5. a) i) $L\theta''(t) = g\theta(t) - k_o\theta(t)$

$$ii) s^2 P(s) = 10P(s) - 9P(s) = P(s) \Rightarrow s^2 =$$

$$\theta''(t) + (k_o - g)\theta(t) = 0 \quad \text{no damping} \Rightarrow \text{unstable},$$

$$s^2 P(s) - s\theta(0) - \theta'(0) - P(s) = 0$$

$$\Rightarrow s^2 P(s) - P(s) - 1 = 0 \Rightarrow P(s) = \frac{1}{s^2-1} = \frac{1}{(s+1)(s-1)}$$

$$= \frac{r_1}{s+1} + \frac{r_2}{s-1}, \quad r_1 + r_2 = 0 \Rightarrow r_2 = \frac{1}{2}, \quad r_1 = -\frac{1}{2}$$

$$\Rightarrow \theta(t) = -\frac{1}{2}(e^t - e^{-t}) \quad \text{which does not converge to } 0 \Rightarrow \text{unstable.}$$

$$\text{iii) } s^2 P(s) - s\theta(0) - \theta'(0) + P(s) = 0$$

$$s^2 P(s) - 1 + P(s) = 0 \Rightarrow P(s) = \frac{1}{s^2 + 1}$$

$$\Rightarrow \theta(t) = \sin(t) \Rightarrow \text{unstable.}$$

$$\text{b) i) } a(t) = k_1 \theta'(t) + k_0 \theta(t)$$

$$\theta''(t) + k_1 \theta'(t) + (k_0 - 10) \theta(t) = 0 \quad \text{will be stable if } k_1 > 0 \text{ and } k_0 > 10$$

ii) We want a critically damped solution with roots at $s = -1$.

$$\Rightarrow X(s) = (s+1)^2 = s^2 + 2s + 1$$

$\nwarrow \frac{1}{\text{time constant}}$

$$\text{for } \theta(t), \quad X(s) = s^2 + k_1 s + (k_0 - 10) \Rightarrow k_1 = 2 \quad k_0 = 11$$

$$\text{iii) } s^2 P(s) - s\theta(0) - \theta'(0) + 2(sP(s) - \theta(0)) + P(s) = 0$$

$$s^2 P(s) + 2sP(s) + P(s) = 1 \Rightarrow P(s) = \frac{1}{s^2 + 2s + 1} = \frac{1}{(s+1)^2}$$

$$\Rightarrow \theta(t) = te^{-t} \quad \text{which is stable}$$

$$6. \quad \text{a) } Y(s) = \frac{1}{s} \left(\frac{1}{s+1} \right) = \frac{1}{s} - \frac{1}{s+1} \Rightarrow y(t) = (1 - e^{-t})u(t)$$

$$\text{b) } a(X(s) - Y(s)) \left(\frac{1}{s+1} \right) = Y(s) \Rightarrow \frac{a}{s+1} X(s) = \left(1 + \frac{a}{s+1} \right) Y(s)$$

$$\Rightarrow \frac{Y(s)}{X(s)} = \frac{\frac{a}{s+1}}{1 + \frac{a}{s+1}} = \frac{a}{s+1+a}$$

$$\text{c) } 1+a = \frac{1}{2} = \frac{1}{100m} = \frac{1}{0.1} = 10 \Rightarrow \boxed{a=9}$$

$$\Rightarrow \frac{1}{s} \frac{9}{s+10} = \frac{r_1}{s} + \frac{r_2}{s+10} \Rightarrow r_1 = \frac{9}{10} \quad r_2 = -\frac{9}{10}$$

$$\Rightarrow \frac{9}{10} \left(\frac{1}{s} - \frac{1}{s+10} \right) \Rightarrow y(t) = \frac{9}{10} (1 - e^{-10t})$$

$$\text{d) } H(s) = \frac{a}{1+a} = \frac{9}{10} \Rightarrow \text{steady state error is } 10\%.$$

7. a) $h(t) \Leftrightarrow H(s)$ $\frac{d}{dt} h(t) \Leftrightarrow sH(s) - h(0)$ True

\downarrow adds zero.
doesn't affect stability

b) $h(t) \Leftrightarrow H(s)$ $\int_{-\infty}^t h(\tau) d\tau \Leftrightarrow \frac{1}{s} H(s)$ \Rightarrow adds a pole at zero

which would seem to result in an unstable system by the definition given above (no poles on jw axis or in right half plane), but $H(s)$ may have a zero at 0 in which case the two cancel and the system remains stable.

\Rightarrow False

c) False $H_{inv} = \frac{1}{H(s)} \Rightarrow$ zeros of $H(s)$ become poles of $H_{inv}(s)$

1/9/2012

Systems EE261 HW 1

1. a) \checkmark
 b) $\sum_{k=0}^{n-1} e^{2\pi i k/n}$ $\sum_{k=0}^{n-1} r^k = \frac{1-r^n}{1-r}$ $r = e^{2\pi i/n}$

$$\Rightarrow \sum_{k=0}^{n-1} e^{2\pi i k/n} = \frac{1-e^{2\pi i}}{1-e^{2\pi i/n}} = \frac{1-1}{1-e^{2\pi i/n}} = 0$$

c) $\sum_{k=-N}^N e^{2\pi i k t} = \frac{\sin(2\pi t(N+1/2))}{\sin(\pi t)}$

2. a) $f(x) = \sin(2\pi m x) + \sin(2\pi n x)$
 $f(x+T) = \sin(2\pi m(x+T)) + \sin(2\pi n(x+T)) = f(x)$

\Rightarrow T is the smallest T such that $mT \in \mathbb{Z}$ and $nT \in \mathbb{Z}$

\Rightarrow Let $T = \frac{1}{2}$, we need the largest T such that $\frac{m}{2} \in \mathbb{Z}$ and $\frac{n}{2} \in \mathbb{Z}$

$$\Rightarrow T = \frac{1}{\text{GCD}(m,n)}$$

b) $g(x) = \sin(2\pi px) + \sin(2\pi qx)$ $p = \frac{m}{r}$ $q = \frac{n}{s} \Rightarrow T$ is smallest T

s.t. $\frac{m}{r}T \in \mathbb{Z}$ and $\frac{n}{s}T \in \mathbb{Z} \Rightarrow T = \frac{a}{b} \Rightarrow \frac{m}{r} \frac{a}{b} \in \mathbb{Z}$ and $\frac{n}{s} \frac{a}{b} \in \mathbb{Z}$

$$\Rightarrow \text{let } a = \text{LCM}(r,s) \quad b = \text{GCD}(m,n) \Rightarrow T = \frac{\text{LCM}(r,s)}{\text{GCD}(m,n)}$$

c) $f(t) = \cos(t) + \cos(\sqrt{2}t)$

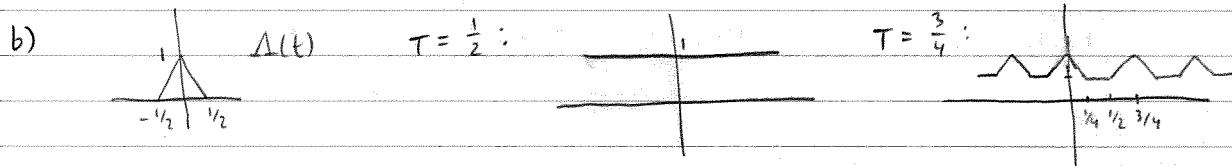
Assume $f(t) = f(t+T) \Rightarrow \cos(t+T) + \cos(\sqrt{2}t + \sqrt{2}T) = \cos(t) + \cos(\sqrt{2}t)$

$$\Rightarrow \frac{T}{2\pi} \in \mathbb{Z} \text{ and } \frac{\sqrt{2}T}{2\pi} \in \mathbb{Z}$$

let $T = k \cdot 2\pi, k \in \mathbb{Z} \Rightarrow \frac{\sqrt{2}T}{2\pi} = \frac{k \cdot 2\pi}{\sqrt{2}\pi} = \frac{k}{\sqrt{2}} \notin \mathbb{Z}$

d) ✓

3. a) $g(t+T) = \sum_{n=-\infty}^{\infty} f(t+T-nT) = \sum_{n=-\infty}^{\infty} f(t-(n-1)T) = \sum_{m=-\infty}^{\infty} f(t-mT) = g(t)$



c) No. Especially if $T = \text{period of } f(t)$.

Then $g(t) = \sum_{n=-\infty}^{\infty} f(t-nT) = \sum_{n=-\infty}^{\infty} f(t) \leftarrow \text{doesn't converge unless } f(t)=$

4. Parsevals: $\int_0^T |f(t)|^2 dt = \sum_{n=-\infty}^{\infty} |\hat{f}(n)|^2$

$$f(t) = \sum_{n=-\infty}^{\infty} D_n e^{j\omega_0 n t} \quad D_n = \frac{1}{T} \int_0^T f(t) e^{-j\omega_0 n t} dt$$

$$g(t) = f(t-T) \text{ which is period } T.$$

$$\Rightarrow \hat{g}(t) = \int_0^T g(t) e^{-j2\pi n t} dt = \int_0^T f(t-T) e^{-j2\pi n t} dt \quad \text{let } \tau = t-T \quad d\tau = T dt$$

$$\Rightarrow \hat{g}(t) = \frac{1}{T} \int_0^T f(\tau) e^{-j2\pi n \tau/T} d\tau = D_n$$

$$\int_0^T |g(t)|^2 dt = \int_0^T |f(t-T)|^2 dt = \frac{1}{T} \int_0^T |f(\tau)|^2 d\tau$$

$$\Rightarrow \sum_{n=-\infty}^{\infty} |D_n|^2 = \frac{1}{T} \int_0^T |f(t)|^2 dt$$

5. ✓

Jong OH - Th - 3-4 CISX - 312

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- FinFET *
- strained silicon
- ultra-thin body SOI * used in research, not yet commercialized.

Key Points

- Scaling - how it affects circuit/system performance.
- Today we are 22nm
- Develop an intuitive feel in addition to solving equations

Textbook: Taur & Ning "Fundamentals of Modern VLSI Devices" 2nd. Ed.
(not required)

Cmos performance - consider how it affects digital performance,
not analog performance.

- BJTs are coming back possibly. Complementary Lateral BJTs, from IBM. (They used to be vertical).
- Now lithography is good enough that you can pattern a short base to make a lateral BJT.

2011 - \$300 Billion revenue, US GDP is \$15 Trillion
(worldwide).
2% of US GDP

- Computer - Billions of transistors, GB of storage must have at least 1B transistors if its DRAM or SRAM (doesn't count for hard disk)
- Data center consumes ~1% of energy in U.S.
- CPU consumes
 - ~50% of server power (other 50% goes to cooling, etc.)
 - ~50% of CPU power consumed in active devices. (other 50% in wires)

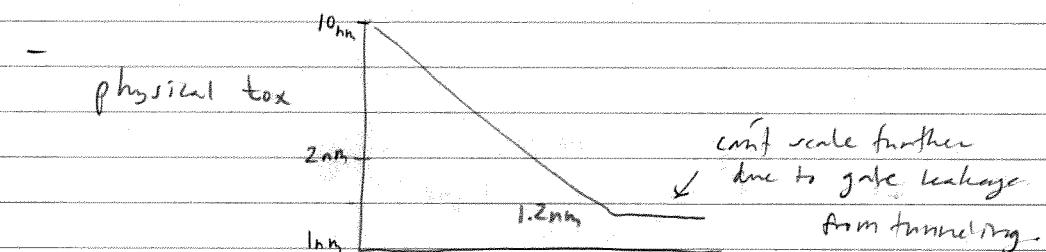
- Two classes of applications:

- High performance applications - Data Centers (don't care as much about power)

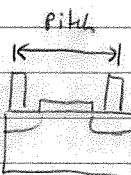
- Power constrained applications - mobile devices (should be low power).

- ~1 Billion transistors per chip. (per die)

- Transistor count doubles about every 2 years (Moores Law)



- gate pitch

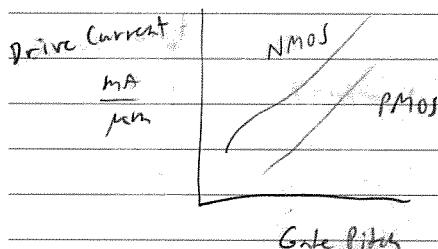


smaller pitch \rightarrow better packing density

\rightarrow more chips/wafer

scales by 0.7 for every generation.

\rightarrow more profit since the cost of a wafer is relatively constant.



- 90nm technology \rightarrow 50nm L 1.2 nm tox

- 65nm technology \rightarrow 35nm L 1.2 nm tox

- 45nm technology \rightarrow 34nm L 1.2 nm tox

(can't decrease

much more, because tox is not scaled down)

45nm High K with Metal Gate, 2007

32 nm technology - 28 nm L 2008

- SRAM occupies about half of the chip area for a CPU.

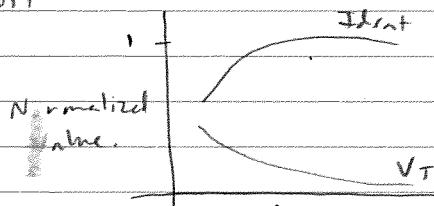
⇒ being able to make a small SRAM cell is important.

32 nm technology, high K metal gate. 2009. (Intel)

Intrinsic variation - due to underlying physics.

extrinsic variations - due to imperfections in manufacturing.

Tradeoff



Future:

- EE316
- Transport enhanced FET
 - Multigate / FinFET
 - Nano electro-mechanical relays (high subthreshold slope)
- EE320
- Nanotubes, Nanowires
 - Molecular devices, spintronics, quantum cascade.
- time ↓

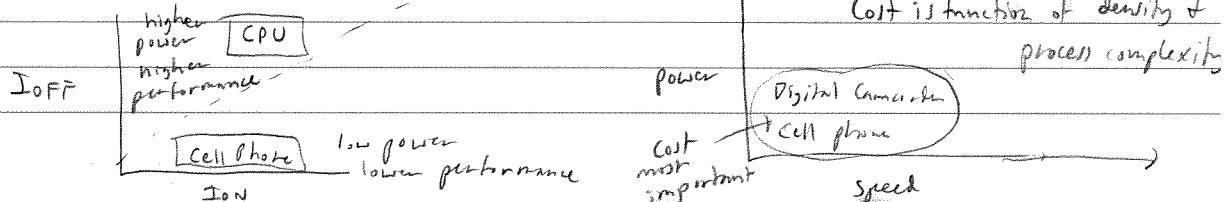
- high k metal gate
- ultrathin body SOI
- strained silicon.

- FinFET
- Device design is application dependent.

performance
most important. Then cost



Cost is function of density & process complexity



In Strong Inversion,

Large change in carrier concentration with small changes in surface potential (ψ_s) \rightarrow "pinning" of surface potential at $2\psi_B$.

Inversion Layer Thickness Estimate: $\frac{Q_i}{\epsilon_{n(i)}/2} = 2\epsilon_{Si} kT/(qQ_i)$

Gate Voltage Equation:

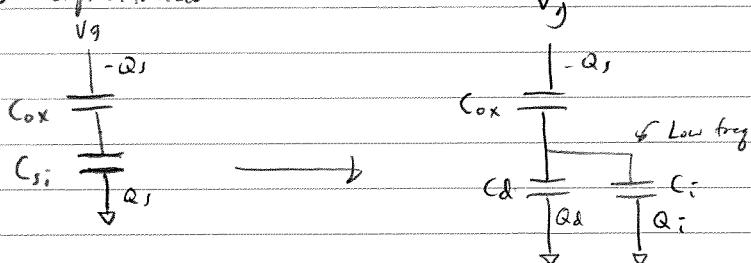
$$V_g = V_{ox} + \psi_s = -\frac{Q_s}{C_{ox}} + \psi_s$$

\uparrow
 $\sim \text{few \AA}$ (0.4 nm)

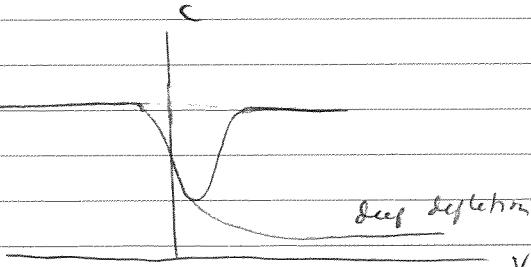
$$C_{ox} = \epsilon_{ox}/t_{ox} \quad \text{and} \quad \epsilon_{ox} E_{ox} = \epsilon_{Si} E_S \quad \text{and} \quad Q_s = -\epsilon_{Si} E_S$$

$$\text{and } E_{ox} = \frac{V_{ox}}{t_{ox}}$$

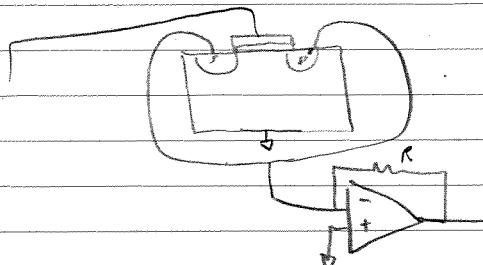
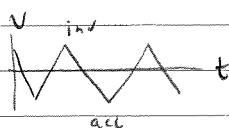
MOS Capacitance:



C-V



- Split C-V measurement



- start from inversion then go to acc.
this is faster.

should shift the C-V curve
left or right.

$$\text{Flatband Voltage: } V_g = V_{FB} + \psi_s + V_{ox} = V_{FB} + \psi_s - \frac{Q_s}{C_{ox}}$$

$$\phi_m = \chi \xrightarrow{\sim 4\text{ eV}} (\text{n}^+ \text{poly}) - \text{used for pmos}$$

$\phi_{\text{Aluminum}} \approx 4\text{ eV}$

(n-type sub)

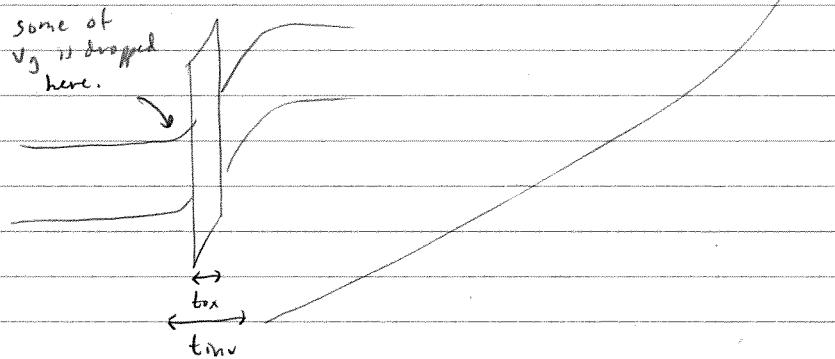
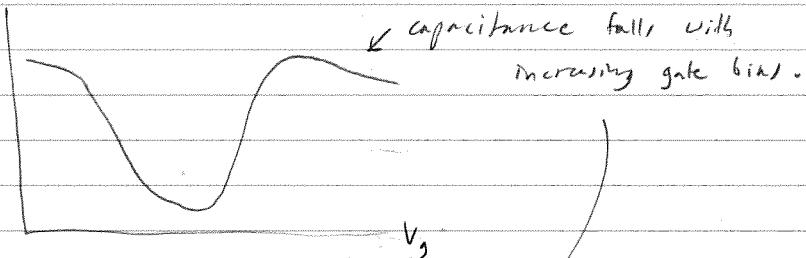
$$\phi_m = \chi + \frac{E_F}{2g} \text{ (midgap)}$$

$$\phi_m = \chi + \frac{E_F}{g} \text{ (p}^+\text{poly) - used for nmos}$$

(p-type sub)

for p-type need a workfunction close to that of p⁺ poly.

- Polysilicon Gate Depletion Effect.



You can have a fermi level higher than the conduction band. (called degenerate)

for 10^{20} doped Si, E_F sits ~10mV above E_c .

$$\int t e^{at} = \left(\frac{t}{a} - \frac{1}{a^2} \right) e^{at}$$

Systems EE261 HW 2

$$1 - \cos(2A) = 2 \sin^2(A)$$

1/12/12

$$\begin{aligned}
 1. \text{ a)} \hat{f}(n) &= \frac{1}{j} \int_{-1/2}^{1/2} f(t) e^{-2\pi j n t} dt \\
 &= \int_{-1/2}^0 (2t+1) e^{-2\pi j nt} dt = 2 \int_{-1/2}^0 t e^{-2\pi j nt} dt + \int_{-1/2}^0 e^{-2\pi j nt} dt \\
 &= 2 \left(\frac{t}{-2\pi j n} + \frac{1}{4\pi^2 n^2} \right) e^{-2\pi j nt} \Big|_{-1/2}^0 + \left(\frac{1}{-2\pi j n} e^{-2\pi j nt} \Big|_{-1/2}^0 \right) \\
 &= \frac{1}{2\pi^2 n^2} - \left(\left(\frac{1}{2\pi^2 n^2} + \frac{1}{2\pi j n} \right) e^{j\pi n} + \left(\frac{1}{-2\pi j n} + \frac{1}{2\pi j n} \right) e^{-j\pi n} \right) \\
 &= \frac{1}{2\pi^2 n^2} (1 - (-1)^n) - \frac{1}{j 2\pi n} (-1)^n + \frac{1}{j 2\pi n} ((-1)^n - 1) \\
 \boxed{\hat{f}(n) = \frac{1}{2\pi^2 n^2} (1 - e^{j\pi n}) - \frac{1}{j 2\pi n}}
 \end{aligned}$$

$$\text{b)} g(t) = f(-t) \Rightarrow \hat{g}(n) = \hat{f}(-n) \quad \widetilde{Ff}^- = (\mathcal{F}f)^-$$

$$\Rightarrow \hat{g}(n) = \frac{1}{2\pi^2 n^2} (1 - e^{-j\pi n}) + \frac{1}{j 2\pi n}$$

$$\text{c)} h(t) = f(t) + g(t) \Rightarrow \hat{h}(n) = \hat{f}(n) + \hat{g}(n)$$

$$\Rightarrow \hat{h}(n) = \frac{1}{\pi^2 n^2} \left(1 - \frac{1}{2} (e^{j\pi n} + e^{-j\pi n}) \right) = \frac{1}{\pi^2 n^2} (1 - \cos(\pi n))$$

$$= \frac{2}{\pi^2 n^2} \sin^2 \left(\frac{\pi n}{2} \right) = \frac{1}{2} \operatorname{sinc}^2 \left(\frac{n}{2} \right)$$

$$\Rightarrow h(t) = \sum_{n=-\infty}^{\infty} \hat{h}(n) e^{j 2\pi n t} = \boxed{\sum_{n=-\infty}^{\infty} \frac{1}{2} \operatorname{sinc}^2 \left(\frac{n}{2} \right) e^{j 2\pi n t} = h(t)}$$

$$2. \text{ a)} \|f+g\|^2 + \|f-g\|^2 \quad \text{Note: } \|f\|^2 = (f, f) \quad (f, g) = \overline{(g, f)}$$

$$(f+g, f+g) + (f-g, f-g) = (f+g, f) + (f+g, g)$$

$$+ (f-g, f) - (f-g, g) = (f, f) + (g, f) + (f, g) + (g, g)$$

$$+ (f, f) - (g, f) - (f, g) + (g, g) = 2(f, f) + 2(g, g)$$

$$= 2\|f\|^2 + 2\|g\|^2$$

b)

c)

$\text{sinc}(x) \Leftrightarrow \text{rect}(s)$

3. a) $f(x) = a \text{sinc}(b(x-c))$

$$\mathcal{F}f(s) = \frac{a}{|b|} \text{rect}\left(\frac{s}{b}\right) e^{-2\pi j s c}$$

b) $g(x) = 3 \Delta\left(\frac{x+2}{3}\right) + 3 \Delta\left(\frac{x-2}{3}\right)$

$$\mathcal{F}g(s) = 3 (3 \text{sinc}^2(3s) e^{-4\pi js} + 3 \text{sinc}^2(3s) e^{4\pi js})$$

$$= 18 \text{sinc}^2(3s) \left(\frac{1}{2} (e^{-4\pi js} + e^{4\pi js})\right)$$

$$= 18 \text{sinc}^2(3s) \cos(4\pi s)$$

4. $f(t) = \Pi(t) - \frac{1}{2} \Delta(2t)$

$$\mathcal{F}f(s) = \text{sinc}(s) - \frac{1}{4} \text{sinc}^2\left(\frac{s}{2}\right)$$

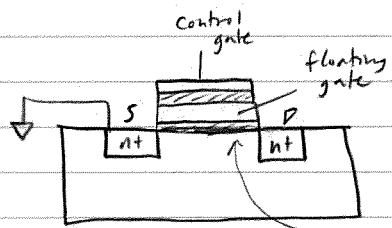
EE 261

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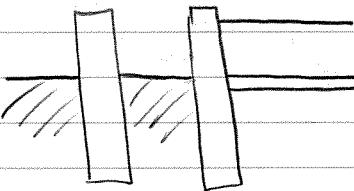
Devices, Different Structures + Devices

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Flash Memory:

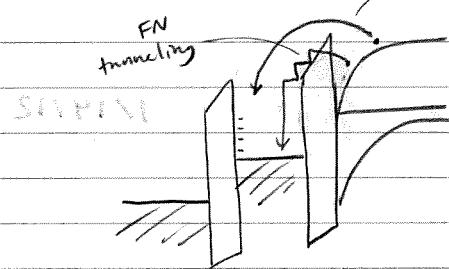


too thin but not
too thin (don't want direct tunnelling)



Write: $V_{control\ gate} \gg V_{th}$

hot carrier injection



- bands bend

- e⁻s tunnel or are injected (hot carriers) into floating gate

- as e⁻s build up, band bending decreases, e⁻s stop entering floating gate.

Read: $V_{to} < V_{control} < V_{t1}$

① shielding \Rightarrow R_{channel} is big

$|V_{t1}| > V_{th_{original}}$ (V_{th} increases)

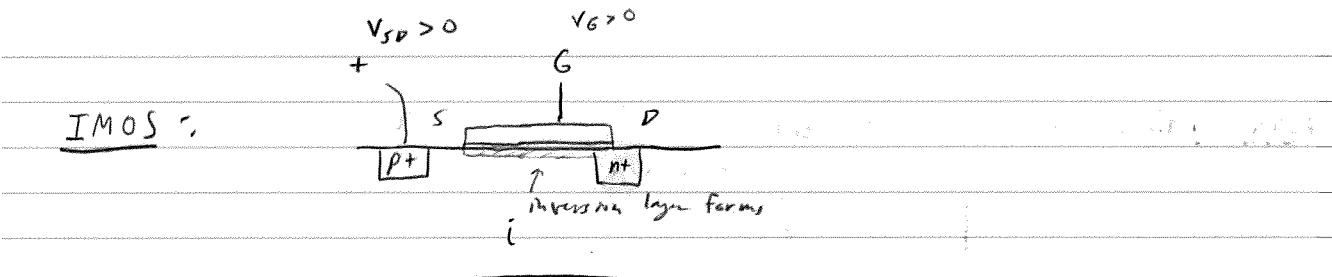
② no shielding \Rightarrow R_{channel} is smaller.

$|V_{t0}| = V_{th_{original}}$

$$I_{channel} \approx \frac{V_{DS}}{R_{channel}}$$

Erase: $V_{control\ gate} \ll 0$ (or apply $V_S > 0$)

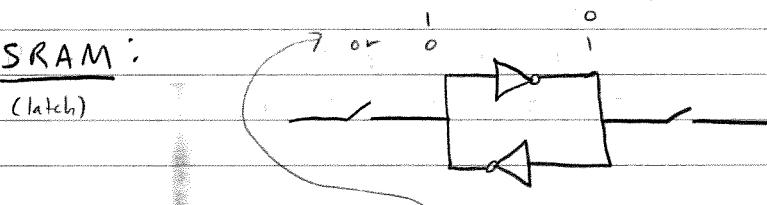
\Rightarrow bands bend the other way, e⁻s tunnel into the source.



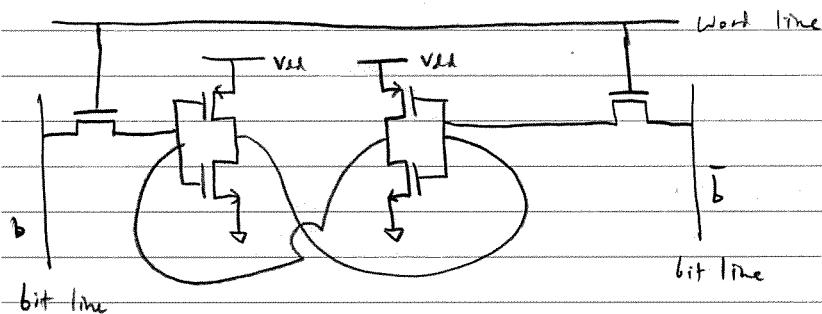
Trigate / FinFET :

- I_{ON} increased (3 channels)
- I_{OFF} decreased (better control of channel.)
- SCE suppressed
- Subthreshold slope increased $\Rightarrow I_{sub} \downarrow$
- Can use thicker oxide while still achieving same performance $\Rightarrow I_{gate} \uparrow$
- For scaled MOSFETs, 70% of I_{OFF} comes from gate leakage.

SRAM :



Bistable system (two stable states)



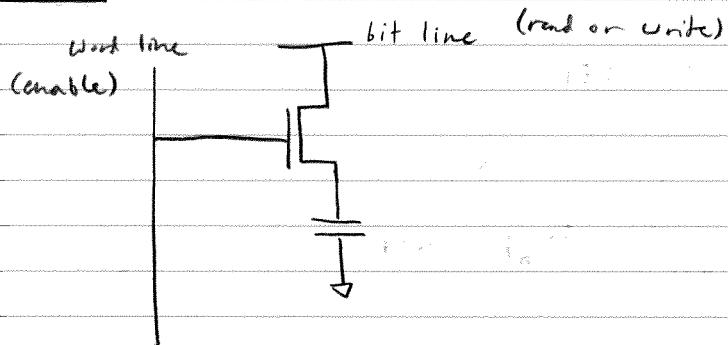
To Write:

- make word line high to turn on switches.
- make $b = 1$, $b' = 0$

To Read:

- make word line high
- read from one of the bit lines.

DRAM :



bit line \rightarrow where you read out or write the data.

Word line \rightarrow control

	word	bit
Read	1	read out.
Write	1	1 or 0 (depending on what you want to write)

Since the cap is leaky, you need to rewrite every few cycles.

\downarrow if 1 ; write 1

read \downarrow if 0 , do nothing.

$$\int_{-\infty}^{\infty} |f(t)|^2 dt = \int_{-\infty}^{\infty} |F(s)|^2 ds$$

$$\int_{-\infty}^{\infty} f(t) g(t) dt = \int_{-\infty}^{\infty} F(s) G(s) ds$$

1. a) $\int_{-\infty}^{\infty} \text{sinc}^4(t) dt = \int_{-\infty}^{\infty} |\mathcal{F}[\text{sinc}^2]|^2 ds = \int_{-1}^1 |\mathcal{F}(s)|^2 ds$

$$= 2 \cdot \int_0^1 s^2 ds = 2 \left(\frac{1}{3} s^3 \right]_0^1 = \boxed{\frac{2}{3}}$$

b) $\int_{-\infty}^{\infty} \frac{2}{1+(2\pi t)^2} \text{sinc}(2t) dt \quad e^{-at|t|} \Leftrightarrow \frac{2a}{a^2 + 4\pi^2 s^2}$

$$\Rightarrow \frac{2a}{a^2 + 4\pi^2 s^2} \Leftrightarrow e^{-a|s|} = e^{-a|s|}$$

$$\text{sinc}(2t) \Leftrightarrow \frac{1}{2} \pi \left(\frac{s}{2} \right)$$

$$\Rightarrow \int_{-\infty}^{\infty} e^{-|s|} \frac{1}{2} \pi \left(\frac{s}{2} \right) ds = \frac{1}{2} \int_{-1}^1 e^{-|s|} ds = \int_0^1 e^{-s} = -e^{-s}]_0^1 = -e^{-1} + 1$$

$$= \boxed{1 - \frac{1}{e}}$$

2. a) $G(s) = \int_{-\infty}^{\infty} f(t) \cos(2\pi s_0 t) e^{-2\pi j st} dt \quad \cos(2\pi s_0 t) = \frac{1}{2} (e^{j 2\pi s_0 t} + e^{-j 2\pi s_0 t})$

$$\Rightarrow G(s) = \frac{1}{2} \int_{-\infty}^{\infty} f(t) (e^{-2\pi j (s-s_0)t} + e^{-2\pi j (s+s_0)t}) dt$$

$$= \frac{1}{2} \int_{-\infty}^{\infty} f(t) e^{-2\pi j (s-s_0)t} dt + \frac{1}{2} \int_{-\infty}^{\infty} f(t) e^{-2\pi j (s+s_0)t} dt$$

$$= \frac{1}{2} F(s-s_0) + \frac{1}{2} F(s+s_0)$$

b) $f(t) = 4 \text{sinc}^2(2t) \cos(2\pi \cdot 4t) = \boxed{4 \text{sinc}^2(2t) \cos(8\pi t)}$

3. a) $\int_{-\infty}^{\infty} t^2 e^{-\pi t^2} dt = \left(\frac{j}{2\pi}\right)^2 F(e^{-\pi t^2})(0)$

$$F(e^{-\pi t^2}) = e^{-\pi s^2} \Rightarrow \frac{d}{ds} e^{-\pi s^2} = -2\pi s e^{-\pi s^2}$$

$$\frac{d^2}{ds^2} e^{-\pi s^2} = (-2\pi s)(-2\pi s) e^{-\pi s^2} - 2\pi (e^{-\pi s^2}) = 4\pi^2 s^2 e^{-\pi s^2} - 2\pi e^{-\pi s^2}$$

$$\Rightarrow \int_{-\infty}^{\infty} t^2 e^{-\pi t^2} dt = \left(\frac{j}{2\pi}\right)^2 (0 - 2\pi) = -\frac{1}{(2\pi)^2} (-2\pi) = \boxed{\frac{1}{2\pi}}$$

OR integrate by parts: let $u=t \quad dv = t e^{-\pi t^2} \quad du=dt \quad v = -\frac{1}{2\pi} e^{-\pi t^2}$

$$\Rightarrow uv - \int v du = -\frac{t}{2\pi} e^{-\pi t^2} \Big|_{-\infty}^{\infty} + \frac{1}{2\pi} \int e^{-\pi t^2} dt = (0-0) + \frac{1}{2\pi} (1) = \boxed{\frac{1}{2\pi}}$$

$$b) \int_{-\infty}^{\infty} t^4 e^{-\pi t^2} dt = \text{let } u = t^3, dv = t e^{-\pi t^2} du = 3t^2 dt, v = -\frac{1}{2\pi} e^{-\pi t^2}$$

$$uv - \int v du = -t^3 \frac{1}{2\pi} e^{-\pi t^2} \Big|_{-\infty}^{\infty} - \frac{3}{2\pi} \int t^2 e^{-\pi t^2} dt = (0-0) - \frac{3}{2\pi} \left(\frac{1}{2\pi} \right) = \boxed{\frac{3}{(2\pi)^2}}$$

c)

$$4. f(t) = f_0 + f_1 t + f_2 t^2 + \dots + f_n t^n = f_0 - f_1 t + f_2 t^2 + \dots + f_n (-t)^n$$

$$\Rightarrow f_1 t + f_3 t^3 + \dots + f_{2n+1} t^{2n+1} = -(f_1 t + f_3 t^3 + \dots + f_{2n+1} t^{2n+1})$$

Assume f is even. Let f_e denote the sum of even power terms in f . Let f_o denote the sum of odd power terms in f .

$f - f_e = f_o$ since even + even = even, this contradicts the hypothesis that f is even. Hence, f is an even function iff $f_k = 0$ for all odd values of k .

$$5. a) f(t) = 2\Delta\left(\frac{t-2}{2}\right) + 2.5\Delta\left(\frac{t-4}{2}\right)$$

$$F(s) = 4 \operatorname{sinc}^2(2s) e^{-j4\pi s} + 5 \operatorname{sinc}^2(2s) e^{-j8\pi s}$$

$$b) Ff(s) = \sum_{k=1}^{n-1} F(f(kT)) \Delta\left(\frac{t-nT}{T}\right)$$

$$= \sum_{k=1}^{n-1} f(kT) T \operatorname{sinc}^2(st) e^{-j2\pi kT s}$$

$$= \boxed{T \operatorname{sinc}^2(st) \sum_{k=1}^{n-1} f(kT) e^{-j2\pi kT s}}$$

1. mean = expected value = center of mass

$$E(X) = \int_{-\infty}^{\infty} x f(x) dx = \frac{i}{2\pi} (Ff)'(0)$$

$$f' \Leftrightarrow 2\pi i s Ff \quad -2\pi i t f(t) \Leftrightarrow Ff'$$

$$\Rightarrow t f(t) \Leftrightarrow \frac{i}{2\pi} Ff'$$

$$\Rightarrow \int_{-\infty}^{\infty} t f(t) e^{-j2\pi s t} dt = \frac{i}{2\pi} Ff'(s)$$

$$\Rightarrow \boxed{\int_{-\infty}^{\infty} t f(t) dt = \frac{i}{2\pi} Ff'(0)}$$

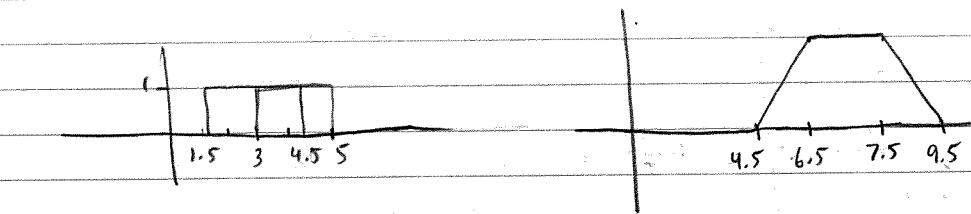
$$\text{now let } g(t) = t f(t) \Rightarrow -2\pi i t g(t) \Leftrightarrow Fg' = \frac{i}{2\pi} Ff''$$

$$\Rightarrow t^2 f(t) \Leftrightarrow \left(\frac{i}{2\pi}\right)^2 Ff''$$

$$\Rightarrow \int_{-\infty}^{\infty} t^2 f(t) = \left(\frac{i}{2\pi}\right)^2 Ff''(0)$$

2.

3. a)



$$b) f(x) = \Lambda\left(\frac{1}{5}(x-7)\right) - \Lambda\left(2(x-7)\right)$$

directly,

$$\Rightarrow Ff = e^{-j14\pi s} 5 \operatorname{sinc}^2(5s) - e^{-j14\pi s} \frac{1}{2} \operatorname{sinc}^2\left(\frac{s}{2}\right)$$

$$= e^{-j14\pi s} \left(5 \operatorname{sinc}^2(5s) - \frac{1}{2} \operatorname{sinc}^2\left(\frac{s}{2}\right) \right)$$

or by convolution theorem: $\Pi\left(\frac{1}{3}(x-3)\right) \Leftrightarrow e^{-j6\pi s} 3 \operatorname{sinc}(3s)$

$$\Pi\left(\frac{1}{2}(x-4)\right) \Leftrightarrow e^{-j8\pi s} \cdot 2 \operatorname{sinc}(2s) \Rightarrow Ff = e^{-j14\pi s} 3 \operatorname{sinc}(3s) - 2 \operatorname{sinc}(2s)$$

$$\Rightarrow Ff = e^{-j14\pi s} 6 \frac{\sin(3\pi s) \sin(2\pi s)}{6\pi^2 s^2} \Rightarrow Ff = e^{-j14\pi s} \frac{\sin(3\pi s) \sin(2\pi s)}{\pi^2 s^2}$$

sinc falls off as $\frac{1}{s^2}$ because $f(x)$ is continuous, but does not have continuous derivative.

$$4. \quad g(t) = (f * h)(t) \Rightarrow G(s) = F(s) H(s)$$

$$g(t) = h(t) = \sin(t) \Rightarrow G(s) = H(s) = \text{PI}(s)$$

$$\Rightarrow F(s) = 1 \text{ for } -\frac{1}{2} \leq s \leq \frac{1}{2}.$$

5.

$$6. \quad a) \quad W_H(t) = \text{PI}(t) \cos^2(\pi t)$$

$$\Rightarrow W(s) = \text{sinc}(s) * \frac{1}{2} (\delta(s-\frac{1}{2}) + \delta(s+\frac{1}{2})) * \frac{1}{2} (\delta(s-\frac{1}{2}) + \delta(s+\frac{1}{2}))$$

$$\Rightarrow W(s) = \text{sinc}(s) * \left(\frac{1}{4} \delta(s-1) + \frac{1}{2} \delta(s) + \frac{1}{4} \delta(s+1) \right)$$

$$\Rightarrow W(s) = \frac{1}{4} (\text{sinc}(s-1) + 2\text{sinc}(s) + \text{sinc}(s+1))$$

b) $W(s)$ has a slightly wider peak than $\text{sinc}(s)$, so it will have smoothing effects on $F(s)$ but it dies off faster than sinc , so we should expect less weird artifacts such as ringing.

$$7. \quad \text{Autocorrelation} \quad f * f = f(t) * \overline{f(-t)} = \int_{-\infty}^{\infty} f(\tau) f(\tau-t) d\tau$$

$$\text{for real } f, \quad f * f = \int_{-\infty}^{\infty} f(\tau) f(\tau-t) d\tau$$

$$a) \quad (f * f)(0) = \int_{-\infty}^{\infty} f(\tau) f(\tau) d\tau = \int_{-\infty}^{\infty} f(\tau)^2 d\tau \quad ?$$

$$\boxed{|(f * f)(x)| \leq (f * f)(0)} \quad \text{by Cauchy-Schwarz inequality.}$$

$$b) \quad W_{FF} = \frac{1}{\|Ff(0)\|} \int_{-\infty}^{\infty} \overline{Ff(s)} ds \Rightarrow W_F W_{\overline{Ff}} = \left(\frac{1}{\|Ff(0)\|} \int_{-\infty}^{\infty} f(t) dt \right) \left(\frac{1}{\|Ff(0)\|} \int_{-\infty}^{\infty} \overline{Ff(s)} ds \right)$$

$$= \left(\frac{\|Ff(0)\|}{\|Ff(0)\|} \right) \left(\frac{\|Ff(0)\|}{\|Ff(0)\|} \right) = 1$$

$$c) \quad f * f = f(t) * f(-t) \Leftrightarrow \overline{Ff} \cdot \overline{Ff} = Ff \cdot \overline{Ff} \quad \text{since } \overline{Ff} = \overline{Ff} \quad \begin{cases} f \text{ is real} \\ \Rightarrow Ff \text{ is Hermitian symmetric} \end{cases}$$

$$\text{assuming } f = \|Ff\|^2 \Rightarrow W_{f * f} W_{\overline{Ff}^2} = 1$$

Nobel Prize in Physics

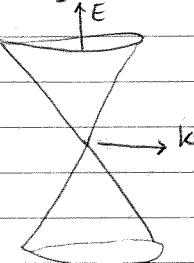
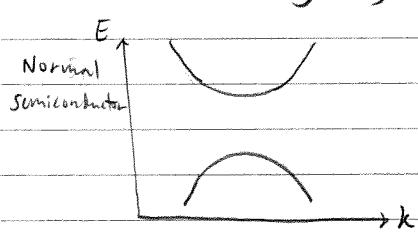
- 2009 - CCD
- 2010 - Graphene, (Geim & Novoselov)

Important Properties of Graphene:

High Mobility:	Material	Graphene	CNT	GaAs	Si	Organics
e ⁻ Mobility (cm ² /Vs)	200,000	100,000	8,500	1,400	~1	

What is Graphene:

- Graphene is a 2-D crystalline form of carbon: a single layer of carbon atoms arranged in hexagons. (Can be used to make bucky balls (0-D), CNTs (1-D) and graphite (3-D pencil lead)).
- Graphite consists of layers of carbon atoms (graphene sheets) tightly bonded in plane, but only loosely bonded between planes.
- As a crystal, 2-D graphene is quite different from 3-D materials like Si. In Si, charge carriers (e⁻s and h⁺s) interact with the periodic field of the atomic lattice to form quasiparticles (excitations that act like classical particles with mass m*). But quasiparticles in graphene don't look anything like an ordinary semiconductor's.



Graphene. $m^* = 0$ for both \pm
 \Rightarrow quasiparticles behave as if they were massless electrons (Dirac Fermions), which travel at a constant speed (some fraction of $c = 3 \cdot 10^8 \text{ m/s}$)

Graphene's unusual electronic properties arise from the fact that the Carbon atom has 4 e⁻s, 3 of which are tied up in bonding with its neighbors. But the unbound 4th e⁻s are in orbitals extending vertically above and below the plane, and the hybridization of these spreads across the whole graphene sheet. Thus, electrons are sort of free and can move ballistically - without collisions - over great distances, even at T=300K. $\Rightarrow \sigma$ of graphene is 10-100x higher than! By applying a gate voltage, one can continually control the carrier density by varying the voltage and thus the conductivity.

Why is Graphene useful:

- Super small transistors - 2008 - 1nm graphene transistor.
1 atom thick, 10 atoms long.
- Energy storage - can be used to create ultra capacitors.
- Optical Devices - Solar cells & Flexible touch screens.
(ITO also 97% transparent)
- High Energy Particle Physics: $m^* = 0 \Rightarrow$ electrons can move very fast through the lattice. In fact they behave as Heisenberg's relative particles.

Systems EE261 HW 5

1/15/2012

$$1. \text{ a) } \langle g\delta', \varphi \rangle = \langle \delta', g\varphi \rangle = -\langle \delta, (g\varphi)' \rangle$$

$$= -\langle \delta, g\varphi' + \varphi g' \rangle = -\langle \delta, g\varphi' \rangle - \langle \delta, \varphi g' \rangle$$

$$= -g(0)\varphi'(0) - \varphi(0)g'(0) = -g(0)\langle \delta, \varphi' \rangle - g'(0)\langle \delta, \varphi \rangle$$

$$= g(0)\langle \delta', \varphi \rangle - g'(0)\langle \delta, \varphi \rangle = \langle g(0)\delta' - g'(0)\delta, \varphi \rangle$$

$$\text{b) } f'*g = f*g'$$

$$2. \quad f(t) = u(t-1) - u(-(t+1)) \quad u(t) \Leftrightarrow \frac{1}{2}(\delta(s) + \frac{1}{\pi is})$$
$$\text{sgn}(t) \Leftrightarrow \frac{1}{\pi is}$$

$$\Rightarrow Ff = e^{-2\pi is} \left(\frac{1}{2}\delta(s) + \frac{1}{2\pi is} \right) - e^{2\pi is} \left(\frac{1}{2}\delta(-s) - \frac{1}{2\pi is} \right)$$

$$= e^{-2\pi is} \left(\frac{1}{2}\delta(s) + \frac{1}{2\pi is} \right) - e^{2\pi is} \left(\frac{1}{2}\delta(s) - \frac{1}{2\pi is} \right)$$

$$= \delta(s) \frac{1}{2} (e^{-2\pi is} - e^{2\pi is}) + \frac{1}{2\pi is} (e^{-2\pi is} + e^{2\pi is})$$

$$= -i[\delta(s) \sin(2\pi s) + \frac{1}{\pi s} \cos(2\pi s)] = \boxed{\frac{1}{\pi s} \cos(2\pi s)}$$

$$\text{real} + \text{odd} \Leftrightarrow \text{im}y + \text{odd} \quad \checkmark \quad \begin{matrix} \nearrow \\ \text{odd} \end{matrix} \quad \begin{matrix} \nwarrow \\ \text{even} \end{matrix} \quad \text{odd} \times \text{even} = \text{odd}$$

$$3. a) \quad g(t) = f(t) \sum_{k=-\infty}^{\infty} T p(t - kT) = f(t) \cdot p(t) * T \text{III}_{\frac{T}{T}}$$

$$\Rightarrow G(s) = F(s) * (T P(s) \text{III}_{\frac{1}{T}})$$

\exists Let bandwidth of $p(t)$ be B_p

$$\Rightarrow \text{if } 2(B + B_p) < \frac{1}{T} \text{ then } \text{III}_{\frac{1}{T}} G(s) = F(s) * P(s)$$

$$\Rightarrow \text{if } \frac{1}{T} > 2B, \quad \text{III}_{\frac{1}{T}} G(s) = P(0) F(s)$$

$$\Rightarrow f(t) = \frac{1}{P(0)} F^{-1}(\text{III}_{\frac{1}{T}} G)(t)$$

$$g(t) = f(t) \left(\sum_{k=-\infty}^{\infty} T p(t - kT) \right)$$

$$= f(t) \cdot T p(t) * \text{III}_{\frac{T}{T}}$$

$$\Rightarrow G(s) = T F(s) * (P(s) \text{III}_{\frac{1}{T}}) = F(s) * \left(P(s) \sum_{k=-\infty}^{\infty} \delta(s - \frac{k}{T}) \right)$$

$$= F(s) * \sum_{k=-\infty}^{\infty} P\left(\frac{k}{T}\right) \delta(s - \frac{k}{T}) = \sum_{k=-\infty}^{\infty} P\left(\frac{k}{T}\right) F(s - \frac{k}{T})$$

\Rightarrow just like with ideal sampling, the fourier transform of the sampled signal is an infinite sum of shifted copies of the original signals fourier transform. The only difference is in the case when realistic pulses are used, each of these copies is scaled by the value of the pulses fourier transform at the center frequency of that copy. But a scaling factor can easily be taken out by adjusting the gain of the lowpass filter we use to reconstruct $f(t)$ from its samples. The answer is yes, under certain conditions it's possible to recover $f(t)$ from $g(t)$

b) $\frac{1}{T} > 2B$.

$$4. f(t) = \cos(2\pi t) \quad \frac{1}{T} = \frac{2}{3} \Rightarrow T = \frac{3}{2}$$

$$\Rightarrow \hat{f}(t) = \cos(2\pi t) \text{III}_{3/2} \quad \cos(2\pi t) \Leftrightarrow \frac{1}{2} (\delta(s-1) + \delta(s+1))$$

$$\Rightarrow \hat{F}(s) = \frac{1}{2} (\delta(s-1) + \delta(s+1)) * \text{III}_{3/2}$$

$$= \sum_{k=-\infty}^{\infty} \delta(s - (\frac{1}{3} + \frac{2}{3}k))$$

$$\Rightarrow \text{III}_{4/3} \hat{F}(s) = (\delta(s - \frac{1}{3}) + \delta(s + \frac{1}{3})) = G(s)$$

$$\Rightarrow g(t) = 2 \cos(\frac{2}{3}\pi t)$$

$$5. \text{ a) } f_0(t) = f(t) \text{III}_{2T}(t) \Rightarrow F_0(s) = F(s) * \frac{1}{2T} \text{III}_{\frac{1}{2T}}(s)$$

$$\Rightarrow F_0(s) = F(s) * \frac{1}{2T} \sum_{k=-\infty}^{\infty} \delta(s - \frac{k}{2T}) = \frac{1}{2T} \sum_{k=-\infty}^{\infty} F(s) * \delta(s - \frac{k}{2T})$$

$$= \boxed{\frac{1}{2T} \sum_{k=-\infty}^{\infty} F(s - \frac{k}{2T})}$$

$$\text{b) } f_1(t) = f(t) \text{III}_{2T}(t - (T+\alpha))$$

$$\Rightarrow F_1(s) = F(s) * \left(e^{-2\pi i(T+\alpha)s} \frac{1}{2T} \text{III}_{\frac{1}{2T}} \right)$$

$$= F(s) * \left(\frac{1}{2T} \sum_{k=-\infty}^{\infty} e^{-2\pi i(T+\alpha)s} \delta(s - \frac{k}{2T}) \right)$$

$$= F(s) * \left(\frac{1}{2T} \sum_{k=-\infty}^{\infty} e^{-2\pi ik(\frac{T+\alpha}{2T})} \delta(s - \frac{k}{2T}) \right)$$

$$= \frac{1}{2T} \sum_{k=-\infty}^{\infty} e^{-\pi ik(1 + \frac{\alpha}{T})} F(s - \frac{k}{2T})$$

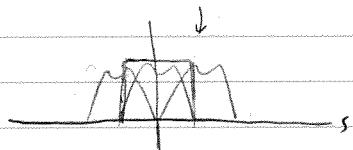
c) Yes, if $0 \leq \alpha < T$. To see how, let's look at the band from 0 to $\frac{1}{T}$ Hz. Let $G_0(s)$ be the portion of $F_0(s)$ in $s = [0, \frac{1}{T}]$ and let $G_1(s)$ be the portion of $F_1(s)$ in $s = [0, \frac{1}{T}]$

$$G_0(s) = \frac{1}{2T} F(s) + \frac{1}{2T} F(s - \frac{1}{2T})$$

$$G_1(s) = \frac{1}{2T} F(s) + \frac{1}{2T} e^{-\pi i(1+\alpha/T)} F(s - \frac{1}{2T})$$

if $\alpha = 0$, $F(s) = G_0(s) + G_1(s)$

if $\alpha = 1$, $G_0(s) = G_1(s) \Rightarrow$ we have aliasing and can't recover $F(s)$



if $0 < \alpha < 1$, we have 2 equations and 2 unknowns
($F(s)$ and $F(s - \frac{1}{2T})$) and can recover $F(s)$.

6. Orthogonality: $f \perp g$ iff $(f, g) = \int_{-\infty}^{\infty} f \cdot \overline{g} dt = 0$

$$\begin{aligned} \int_{-\infty}^{\infty} \text{sinc}(t-a) \overline{\text{sinc}(t-b)} dt &= \int_{-\infty}^{\infty} e^{-2\pi i sa} \pi \cdot \overline{e^{-2\pi i sb} \pi} ds \\ &= \int_{-1/2}^{1/2} e^{-2\pi i sa} e^{2\pi i sb} ds = \int_{-1/2}^{1/2} e^{-2\pi i s(a-b)} ds = -\frac{1}{2\pi i(a-b)} [e^{-2\pi i s(a-b)}]_{-1/2}^{1/2} \\ &= -\frac{1}{2\pi i(a-b)} (e^{-\pi i(a-b)} - e^{\pi i(a-b)}) = -\frac{e^{\pi i(a-b)}}{2\pi i(a-b)} (1 - e^{-2\pi i(a-b)}) \end{aligned}$$

= 0 for $a-b \in \mathbb{Z}$ and $a-b \neq 0 \Rightarrow \text{sinc}(t-a)$ and $\text{sinc}(t-b)$ are orthogonal

$$\begin{aligned} \text{if } a-b=0, \quad \int_{-\infty}^{\infty} \text{sinc}(t-a) \overline{\text{sinc}(t-b)} dt &= \int_{-\infty}^{\infty} |\text{sinc}(t-a)|^2 = \int_{-\infty}^{\infty} |e^{-2\pi i sa} \pi|^2 ds \\ &= \int_{-\infty}^{\infty} (|e^{-2\pi i sa}| |\pi|^2) ds = \int_{-\infty}^{\infty} (1 \cdot |\pi|^2)^2 ds = \int_{-1/2}^{1/2} 1 ds = 1 \end{aligned}$$

$\Rightarrow \text{sinc}(t-a)$ and $\text{sinc}(t-b)$ are not orthogonal for $a-b=0$.

$$W = e^{2\pi i/N}$$

Systems EE261 HW 6

1/16/2012

$$\begin{aligned} 1. \quad F[m] &= \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / N} \quad G[m] = \sum_{k=0}^{2N-1} g[k] e^{-2\pi i k m / (2N)} \\ &= \sum_{k=0}^{N-1} g[k] w^{-km} + \sum_{k=N}^{2N-1} g[k] w^{-km} = \sum_{k=0}^{N-1} f[k] w^{-km} + \sum_{k=0}^{N-1} f[k+N] w^{-(k+N)m} \\ &= \sum_{k=0}^{N-1} f[k] w^{-km} + \sum_{k=0}^{N-1} f[k] w^{-km} = 2 F[m] \end{aligned}$$

$$\begin{aligned} &= \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / (2N)} + \sum_{k=N}^{2N-1} f[k] e^{-2\pi i k m / (2N)} \\ &= \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / (2N)} + \sum_{k=0}^{N-1} f[k+N] e^{-2\pi i m (k+N) / (2N)} \\ &= \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / (2N)} + e^{-\pi i m} \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / (2N)} \\ &= \begin{cases} 2 F[m/2], & m \text{ even} \\ 0, & m \text{ odd} \end{cases} \end{aligned}$$

$$\begin{aligned} 2. \quad F[m] &= \sum_{k=0}^{N-1} f[k] w^{-km} = \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / N} \\ G[m] &= \sum_{k=0}^{N/2-1} g[n] w^{-km} = \sum_{k=0}^{N/2-1} g[n] e^{-2\pi i k m / (N/2)} \\ &= \frac{1}{2} \sum_{k=0}^{N/2-1} f[2k] e^{-2\pi i 2k m / N} \quad \text{let } n = 2k \\ &= \frac{1}{4} \left(\sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / N} + e^{-i\pi m} \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / N} \right) \\ &= \frac{1}{4} (F[m] + (-1)^m F[m]) = \frac{1}{4} F[m] (1 + (-1)^m) \end{aligned}$$

First let's derive the formula for downsampling:

$$g[n] = f[2n] \quad n = 0, \dots, \frac{N}{2} - 1$$

$$\begin{aligned} F[m] &= \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / N} \\ G[m] &= \sum_{k=0}^{\frac{N}{2}-1} g[k] e^{-2\pi i k m / (N/2)} = \sum_{k=0}^{\frac{N}{2}-1} f[2k] e^{-2\pi i (2k)m / N} \\ &= \frac{1}{2} \left(\sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / N} + \sum_{k=0}^{N-1} f[k] e^{-\pi i k} e^{-2\pi i k m / N} \right) \end{aligned}$$

$$= \frac{1}{2} \left(\sum_{k=0}^{N-1} f[k] e^{-2\pi i k m/N} + \sum_{k=0}^{N-1} f[k] e^{-2\pi i k (m+\frac{N}{2})/N} \right)$$

$$= \boxed{\frac{1}{2} (F[m] + F[m + \frac{N}{2}])} \quad \text{for even downsampling.}$$

Now let $g[n] = f[2n+1]$ $n = 0, \dots, \frac{N}{2}-1$

$$F[n] = \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m/N}$$

$$G[n] = \sum_{k=0}^{\frac{N}{2}-1} g[k] e^{-2\pi i k m/(N/2)} = \sum_{k=0}^{\frac{N}{2}-1} f[2k+1] e^{-2\pi i (2k)m/N} = e^{2\pi i m/N} \sum_{k=0}^{\frac{N}{2}-1} f[2k+1] e^{-2\pi i (2k)m/N}$$

$$= \frac{1}{2} e^{2\pi i m/N} \left(\sum_{k=0}^{N-1} f[k] e^{-2\pi i k m/N} - \sum_{k=0}^{N-1} f[k] e^{-\pi i k} e^{-2\pi i k m/N} \right)$$

$$= \frac{1}{2} e^{2\pi i m/N} \left(\sum_{k=0}^{N-1} f[k] e^{-2\pi i k m/N} - \sum_{k=0}^{N-1} f[k] e^{-2\pi i k (m+\frac{N}{2})/N} \right)$$

$$= \boxed{\frac{1}{2} e^{2\pi i m/N} (F[m] - F[m + \frac{N}{2}])} \quad \text{for odd downsampling.}$$

2. By linearity, $G[m] = \frac{1}{2} \left(\frac{1}{2} (F[m] + F[m + \frac{N}{2}]) + \frac{1}{2} e^{2\pi i m/N} (F[m] - F[m + \frac{N}{2}]) \right)$

$$= \boxed{\frac{1}{4} \left((1 + e^{2\pi i m/N}) F[m] + (1 - e^{2\pi i m/N}) F[m + \frac{N}{2}] \right)}$$

Another method: First, let $h[n] = (\frac{1}{2}, 0, 0 \dots, 0, 0, \frac{1}{2})$ (length N)

$$\Rightarrow h[n] = \frac{1}{2} (\delta[n] + \delta_{N-1}[n])$$

$$X[n] = f[n] * h[n] = \frac{1}{2} (f[n] + f[n+1]), \quad n = 0, \dots, N-1$$

$$FS_k = \omega^{-k} \Rightarrow X[m] = F[m] * H[m] = F[m] \cdot \frac{1}{2} (1 + e^{-2\pi i m(N-1)/N})$$

$$= F[m] \cdot \frac{1}{2} (1 + e^{-2\pi i m} e^{-2\pi i m/N}) = \frac{1}{2} F[m] (1 + e^{2\pi i m/N})$$

Now perform even downsampling to get $G[m]$

$$G[m] = \frac{1}{2} (X[m] + X[m + \frac{N}{2}]) = \frac{1}{4} F[m] (1 + e^{2\pi i m/N})$$

$$+ \frac{1}{4} F[m + \frac{N}{2}] (1 + e^{2\pi i [m + N/2]/N}) =$$

$$= \boxed{\frac{1}{4} F[m] (1 + e^{2\pi i m/N}) + \frac{1}{4} F[m + \frac{N}{2}] (1 - e^{2\pi i m/N})} \quad \checkmark$$

$$3. a) F[m] = \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / N}$$

$$G[m] = \sum_{k=0}^{2N-1} g[k] e^{-2\pi i k m / (2N)} = \sum_{k=0}^{N-1} f[k] e^{-2\pi i k (m/2) / N}$$

$$\Rightarrow G[2m] = \sum_{k=0}^{N-1} f[k] e^{-2\pi i k m / N} = F[m]$$

$$b) G[m] = \sum_{k=0}^{N-1} f[k] e^{-2\pi i k (m/2) / N}$$

$$\sum_{k=-\infty}^{\infty} F\left[\frac{1}{2}(m-1)-k\right] \text{sinc}\left(k+\frac{1}{2}\right)$$

$$= \sum_{k=-\infty}^{\infty} \left(\sum_{n=0}^{N-1} f[n] e^{-2\pi i n \left(\frac{1}{2}(m-1)-k\right) / N} \right) \text{sinc}\left(k+\frac{1}{2}\right)$$

$$= \sum_{k=-\infty}^{\infty} \left(\sum_{n=0}^{N-1} f[n] e^{-\pi i n m / N} e^{\pi i n / N} e^{2\pi i n k / N} \right) \text{sinc}\left(k+\frac{1}{2}\right)$$

? Look up linear interpolation in book.

4. a) Linear, Time variant.

b) Nonlinear, Time invariant

c) $\omega(t) = \int_{-\infty}^{\infty} v(\tau) e^{-2\pi i t \tau} d\tau = Fv$

$$\int_{-\infty}^{\infty} (\alpha v_1(\tau) + \beta v_2(\tau)) e^{-2\pi i t \tau} d\tau = \alpha \omega_1(t) + \beta \omega_2(t) \Rightarrow \text{Linear}$$

$$\int_{-\infty}^{\infty} v(\tau - \tau_0) e^{-2\pi i t \tau} d\tau = \int_{-\infty}^{\infty} v(\tau) e^{-2\pi i t (\tau + \tau_0)} d\tau$$

$$= \int_{-\infty}^{\infty} v(\tau) e^{-2\pi i t \tau} e^{-2\pi i t \tau_0} e^{2\pi i t \tau_0} d\tau \neq \omega(t - \tau_0) = \int_{-\infty}^{\infty} v(\tau) e^{2\pi i t \tau_0} e^{-2\pi i t \tau} d\tau \Rightarrow \text{Time Variant}$$

d) $\frac{d}{dt}(\alpha v_1(t) + \beta v_2(t)) = \alpha \frac{d}{dt} v_1(t) + \beta \frac{d}{dt} v_2(t) = \alpha \omega_1(t) + \beta \omega_2(t) \Rightarrow \text{Linear}$

$$\frac{d}{dt} v(t - \tau) = \omega(t - \tau) \Rightarrow \text{Time invariant}$$

e) Nonlinear, Time variant

5. a) $\delta(t) e^{int^2} = \delta(t) \quad \delta(t) * e^{int^2} = e^{int^2} \quad e^{int^2} e^{-int^2} = e^0 = 1 = \omega(t)$

$$\delta(t) f(t) = f(0) \delta(t) \quad \delta(t) * f(t) = f(t)$$

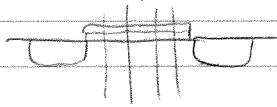
b) $\delta(t - \tau) e^{-int^2} = \delta(t - \tau) e^{-in\tau^2} \quad e^{int^2} * \delta(t - \tau) e^{-in\tau^2} = e^{int^2} e^{in(t - \tau)^2}$

$$e^{in\tau^2} e^{in(t - \tau)^2} e^{-int^2} = e^{in(t^2 - 2t\tau + \tau^2 - \tau^2 - t^2)} = e^{-2int\tau} = \omega(t)$$

c) $\boxed{\omega(t) = \int_{-\infty}^{\infty} h(t, \tau) v(\tau) d\tau = \int_{-\infty}^{\infty} e^{-2\pi i t \tau} v(\tau) d\tau}$ This is the Fourier Transform.

Devices EE316 L3 - Long Channel MOSFET

- Long Channel Behavior :

- The electric field in channel is essentially 1-D. (Normal to the semiconductor surface)
- $E_x \gg E_y$ 
- \Rightarrow we can solve Poisson's eq. in slices.

- Drain Current Model:

$$- n(x) = \frac{n_i^2}{N_a} e^{q(\psi - V)/kT} \quad \leftarrow \text{Boltzmann approx.}$$

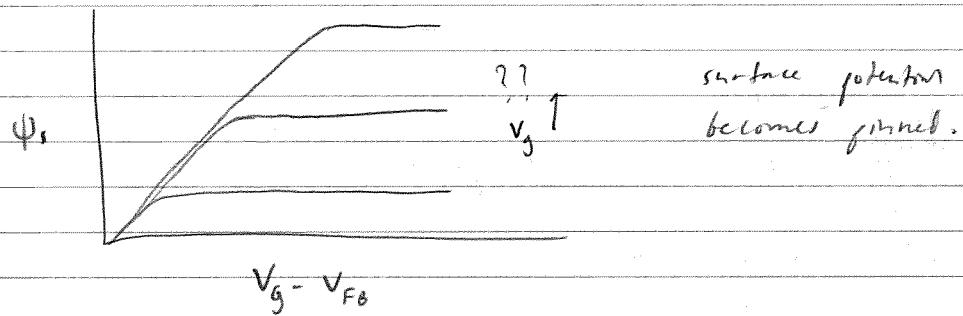
$$- \psi(0, y) = V(y) + 2\psi_B$$

$$- W_{dn}(y) = \sqrt{\frac{2\epsilon_s(v(y) + 2\psi_B)}{qN_a}} \quad \leftarrow \begin{array}{l} \text{depletion region} \\ \text{width at drain.} \end{array}$$

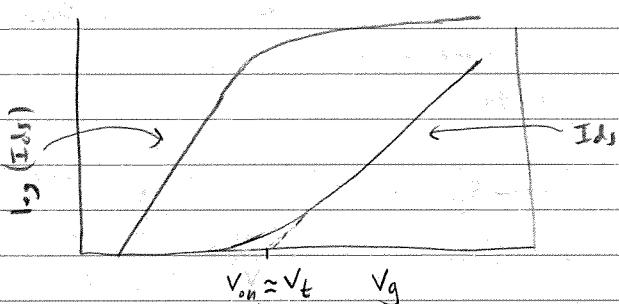
$$\Rightarrow J_n(x, y) = -q\mu_n n(x, y) \frac{\partial V(y)}{\partial y} \quad \leftarrow \begin{array}{l} \text{gradient of} \\ \text{quasi Fermi level} \\ \text{along } y\text{-direction.} \end{array}$$

↓

Gradual Channel Approx.



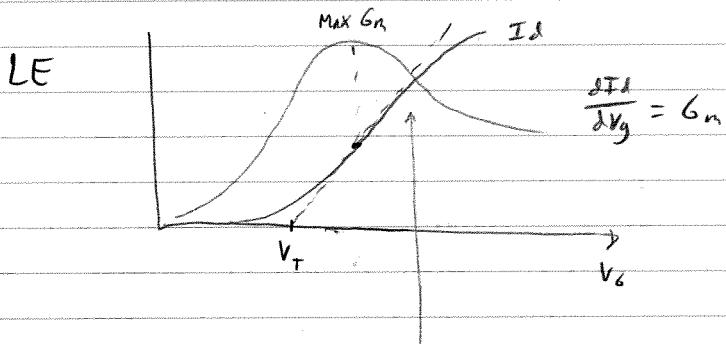
$$V_t = V_{FB} + 2\psi_B + \frac{\sqrt{4\epsilon_s q N_a \psi_B}}{C_{ox}}$$



Experimental Determination of the Threshold Voltage

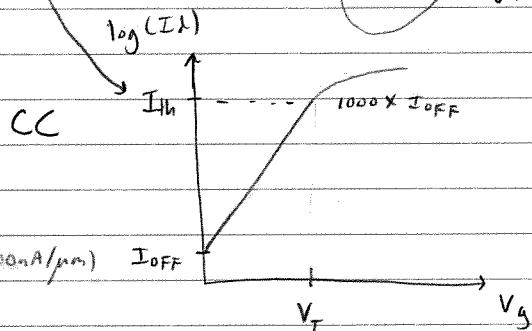
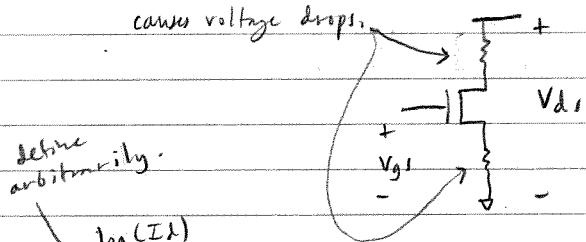
- LE - Linear Extrapolation at maximum G_m point. ← used for modeling device
- CC - Constant Current Method ← used in industry
- TC - Transconductance Change

- All devices are now non-uniformly doped along x-direction,
so 2 Φ_0 point doesn't make sense (it depends on x)



bands over because at high V_g , V_g increases, $\Rightarrow \mu_{eff} \downarrow$
also, bands over due to drain, source, and contact resistances.

causes voltage drops,

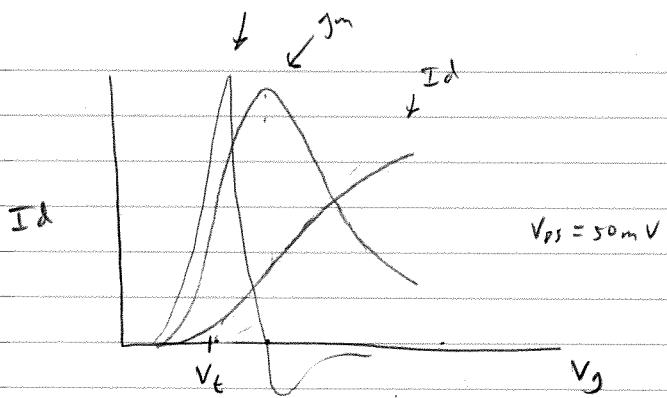


review this.

Used in industry because it's very fast. Don't need to sweep, just measure a point, so you can do it in a tester.

TC - used for things like thin SOI, FinFET, which have no doping ($\Phi_0 = 0$)

$$\frac{\delta g_m}{\delta V_g} = \frac{\partial^2 I_d}{\partial V_g}$$

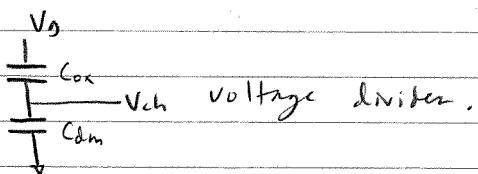


- For organic TFTs, Poisson eq. doesn't apply, so we can't use the same approximations. But we generally use the same methods to extract " V_{th} "

$$m = 1 + \frac{C_{dm}}{C_{ox}} = 1 + \frac{3t_{ox}}{W_{dm}} \quad C_{dm} = \frac{\epsilon_s}{W_{dm}} \quad \text{typically, } m \approx 1.2$$

\wedge body-effect coefficient.

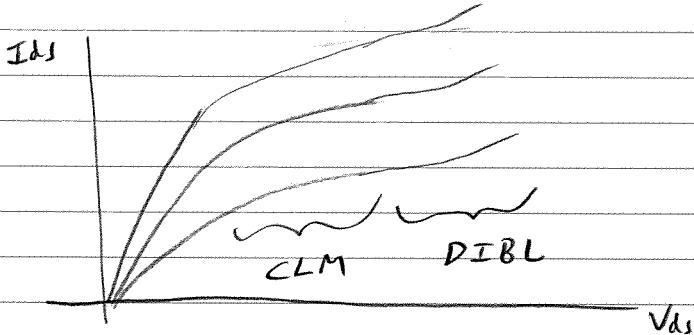
$$I_{ds} = I_{dsat} = \frac{1}{2} M_{eff} C_{ox} \frac{W}{L} \frac{(V_g - V_t)^2}{m}$$

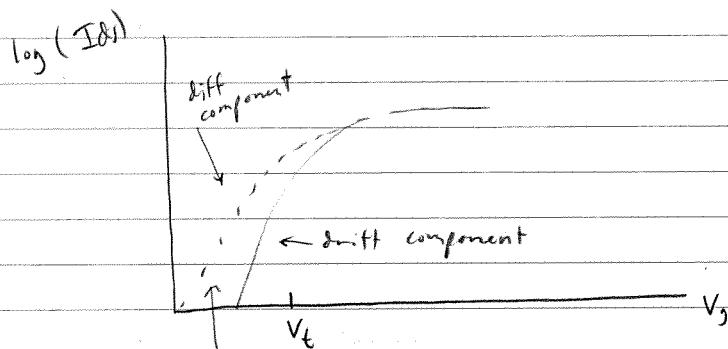
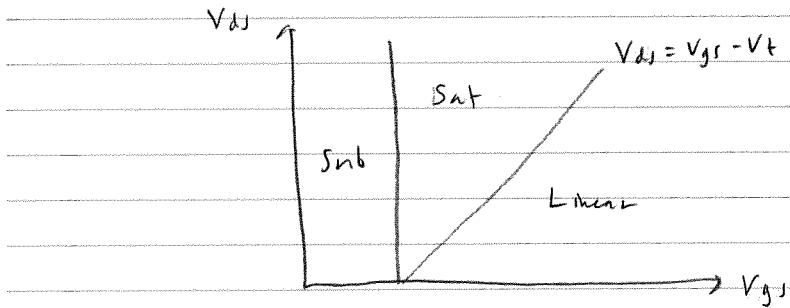


$$V_{ch} = \frac{C_{ox}}{C_{ox} + C_{dm}} V_g = \frac{V_g}{m}$$

$$\text{Pinch OFF: } V_{ds} = V_{dsat} = \frac{V_g - V_t}{m}$$

Beyond Pinch OFF: Channel Length Modulation.





In subthreshold, $|I_{ds}|$ is dominated by diffusion current.

Subthreshold:

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} (m-1) \left(\frac{kT}{q}\right)^2 e^{q(V_g - V_t)/mkT} (1 - e^{-qV_{ds}/kT})$$

Inverse subthreshold slope:

$$S = \left(\frac{\partial \log(I_{ds})}{\partial V_g} \right)^{-1} = m \frac{kT}{q} \ln(10) = \frac{\partial V_g}{\partial \psi_s} \frac{\partial \psi_s}{\partial \log I_{ds}}$$

$$= 2.3 \frac{m kT}{q} \quad (60 \text{ mV/dec, for } m=1, T=300 \text{ K})$$

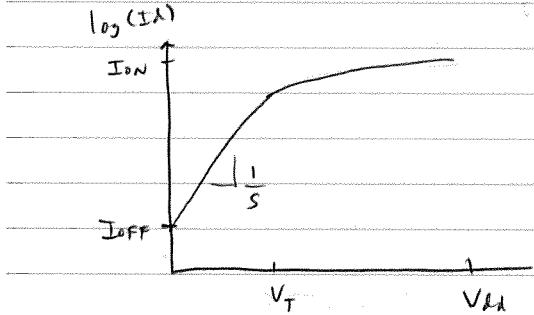
$\int \Phi_1$ not all of applied V_{gs} goes to band bending Φ_s .
some goes to bonding in the oxide.



for low m , we want $C_{ox} \gg C_{ds}$

\Rightarrow we want to minimize t_{ox} .

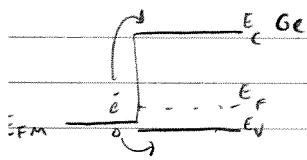
We want S small (slope steep) so we can get a maximum $\left(\frac{I_{ON}}{I_{OFF}}\right)$



Can get S lower than 60 mV/dec , if you have gain (rather than capacitive division) between gate and channel.
Or, if you have some different mechanism of current. (e.g. IMOS)

Meeting With Professor Saraswat

- 1998 - Q2
- 2003 - Leaky Cap - gate leakage does not change Cap value.
- 2004 - Ultimate Limit to Scaling - $\sim 0.5 \text{ nm}$, beyond that, e keeps moving back & forth.
- 2007 - Current Source into gate of MOSFET
- SOI



↑ Fermi level pinning, doesn't matter what type of metal you use.

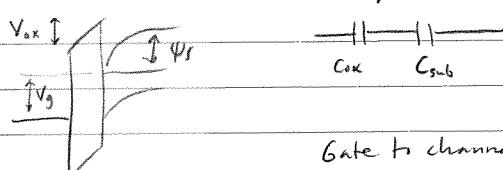
If this is close to midgap, you can have an ambipolar I_D-V_g characteristic,

Device EE316 L4 Device Scaling + Short Channel Effects

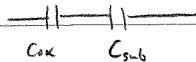
$$S = \left(\frac{\partial \log I_D}{\partial V_g} \right) = \frac{\partial V_g}{\partial \psi_s} \quad \frac{\partial \psi_s}{\partial \log I_D}$$

capacitive driven

in MOSFETs.



60 mV per decade due to Fermi



Dirac distribution, no e^{q\psi/kT}

Gate to channel potential

coupling: > 1 in MOSFETs.

$$S \downarrow \Rightarrow \frac{I_{on}}{I_{off}} \uparrow \Rightarrow \text{we want steeper subthreshold slope.}$$

Body Effect: Dependence of V_{th} on V_{bs}

$$V_{th} = V_{fb} + 2\psi_0 + \frac{\sqrt{2\epsilon_s q N_A (2\psi_0 + V_{bs})}}{C_{ox}}$$

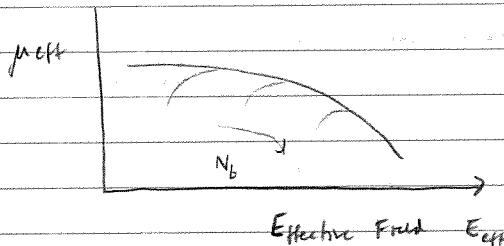
$$V_{bs} > 0 \quad V_{th} \uparrow \quad V_{bs} < 0 \quad V_{th} \downarrow$$

$$\boxed{\frac{dV_{th}}{dT} \text{ is typically } -1mV/K} \quad \text{for } N_A = 10^{16} \text{ cm}^{-3} \quad \begin{aligned} & \text{(for diode,} \\ & V_{be} \sim -2mV/K \end{aligned})$$

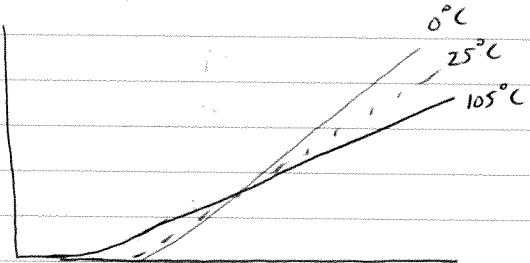
Temperature dependence.

In consumer electronics, devices run at 85°C.

Electron Mobility:



Temperature Dependence of I_{ds}



$$I \propto \frac{1}{T} \quad \text{since} \quad \mu \propto T^{-3/2} \quad I \propto \mu$$

$$\text{But } T \downarrow \Rightarrow V_{th} \uparrow$$

Intrinsic MOSFET Capacitance:

$$\text{Sub: } C_g = WL C_{ox} = \boxed{WL \left(\frac{1}{C_{ox}} + \frac{1}{C_L} \right)^{-1}}$$

$$\frac{1}{\frac{1}{C_{ox}} + \frac{1}{C_L}}$$

Linear: $\boxed{C_g = WL C_{ox}}$ (depl. cap is shorted)

Sat: $Q_i(y) = -C_{ox} (V_g - V_t) \sqrt{1 - \frac{y}{L}}$

$$\boxed{C_g = \frac{2}{3} WL C_{ox}}$$

MOSFET Scaling

Goals: achieve density and performance gains, and power reductions in VLSI.

Issues: short channel effect, power density, switching delay, reliability.

Constant-Field scaling: Scale the device voltages + device dimensions (both horizontal + vertical) by the same factor ($k > 1$) such that the electric field remains unchanged.
(also increase substrate biasing by K).

$$\frac{V}{K}, \frac{L}{K}, \frac{W}{K}, \frac{t_{ox}}{K}, K N_a, \frac{x_j}{K}$$

Derived Scaling	E	1
Behavior of device parameters.	V_d	1
	W_d	$1/K$
	C	$1/K$
	Q_i	1
	I_{ds}	$1/K$
	R_{ch}	1

Derived Scaling behavior of circuit parameters.	Circuit delay ($\tau = \frac{CV}{I}$)	$1/K$
	(ON) Power Dissipation ($P \sim VI$)	$1/K^2$
	(ON) Power Delay Product ($P \cdot \tau$)	$1/K^3$
	Circuit Density ($\alpha^{1/A}$)	K^2
	(ON) Power Density (P/A)	1

ION implantation - makes shallower but sharper junction compared to (gas) diffusion based doping.

Generalized scaling:

allow \bar{E} to scale up by α ($\bar{E} \rightarrow \alpha \bar{E}$) $\alpha > 1$

while device dimension scale down by K . $K > 1$

i.e. voltage scales by $V \rightarrow (\alpha/K) V$

$N_A, N_D \rightarrow (\alpha K) N_A, (\alpha K) N_D$

More flexibility than constant field scaling, but has reliability + power concerns.



Generalized scaling circuit parameters.	Long Ch. Vol. Sat
Circuit delay time ($\tau = CV/I$)	$1/(\alpha K)$ $1/K$
Power dissipation (IV)	α^3/K^2 α^2/K^2
Power delay product	α^2/K^3
Circuit density	K^2
Power density	α^3 α^2

Scaling of Depletion Width : (constant Field Scaling)

$$W_{dm} = \sqrt{\frac{4\epsilon_s kT \ln(N_a/n_i)}{q^2 N_a}}$$

\Rightarrow maximum gate depletion width scales even less than $\frac{1}{\sqrt{K}}$.

determines minimum channel length.
you can get without suffering short channel effects.

Constant Voltage Scaling ($\alpha = K$)

$$N_a \rightarrow K^2 N_a \Rightarrow W_{dm} \rightarrow \frac{1}{K} W_{dm}$$

But $\vec{E} \rightarrow kE$ (reliability issue due to high \vec{E} field)

$$P/A \rightarrow K^3 P/A$$

Scaling in practice. (rising oxide field)

Feature Size	Power Supply	Gate Oxide	Oxide Field
2 μm	5 V	35 nm	1.4 MV/cm
0.7 (65 nm)	1.2 V	1.2 nm	10 MV/cm
0.7 (45 nm)	1 V	1 nm	10 MV/cm
0.7 (32 nm)	0.9 V	0.95 nm	9.5 MV/cm

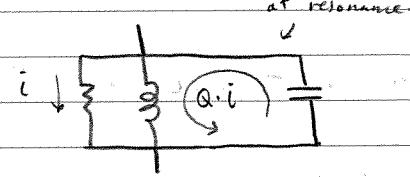
$$\begin{matrix} 0.7 \\ \downarrow \\ 0.7 \end{matrix} \rightarrow \begin{matrix} 0.7 \\ \downarrow \\ \sim 0.5 \end{matrix} \quad 0.7 \sim \sqrt{2}$$

Scaling in practice : Field + Power density have gone up.

by physics, we managed to cope with reliability requirements - at higher fields.

Circuits - RLC Review

Parallel RLC:



$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$Z_0 = \sqrt{\frac{L}{C}}$$

(ω_0 for $1mH$ + $1pF$ is $5GHz$)

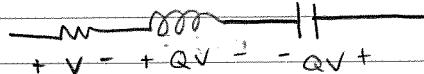
\Rightarrow for example for $9nH$ and $25pF \Rightarrow 0.333 GHz$

$$Q = \frac{\text{Energy Stored}}{\text{Avg. Power Dissipated}} = \frac{\omega_0}{BW} = \# \text{ cycles ringing}$$

$$Q = \frac{R}{\sqrt{LC}} = \frac{R}{\omega_0 L} = \omega_0 RC$$

\leftarrow also applies to

Series RLC:



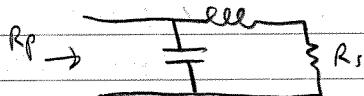
$$Q = \frac{\sqrt{LC}}{R} = \frac{\omega_0 L}{R} = \frac{1}{\omega_0 RC}$$

$$R_p = R_s (Q^2 + 1)$$

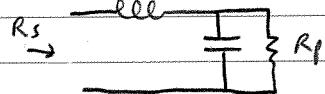
$$X_p = X_s \left(\frac{Q^2 + 1}{Q^2} \right)$$

$\left. \right\} \text{ holds over a narrow bandwidth around } \omega_0.$

Impedance Transformations: L-Match



Upward Impedance Transformer



Downward Transformer.

$$Q \approx \sqrt{\frac{R_p}{R_s}} \quad \text{for } Q \gg 1.$$

$$\text{e.g. } R_2 = 5\Omega \quad R_1 = 50\Omega \quad \omega_0 = 2\pi \cdot 16\text{Hz}$$



$$\frac{1}{\sqrt{LC}} = 2\pi \cdot 16\text{Hz}$$

$$\frac{R_2}{R_1} = Q^2 + 1 \Rightarrow Q = 3 = \frac{50}{\sqrt{LC}} = \omega_0 RC \Rightarrow C = \frac{3}{2\pi \cdot 16\text{Hz} \cdot 50}$$

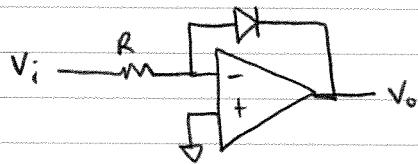
$$\Rightarrow \boxed{C \approx 10\text{pF}}$$

$$\frac{1}{2\pi\sqrt{1mH \cdot 1pF}} = 56\text{Hz} \Rightarrow \frac{1}{2\pi\sqrt{2.5nH \cdot 10\text{pF}}} = 16\text{Hz}$$

$$\Rightarrow \boxed{L \approx 2.5nH}$$

Circuits Clever Opamp Circuits

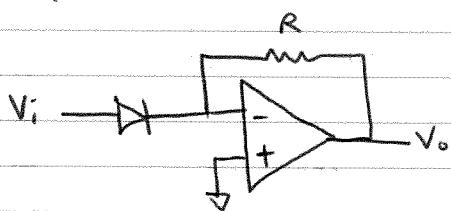
Log Output



$$V_{out} \approx -V_T \ln \left(\frac{V_{in}}{I_s R} \right)$$

(for $V_{in} > 0$)

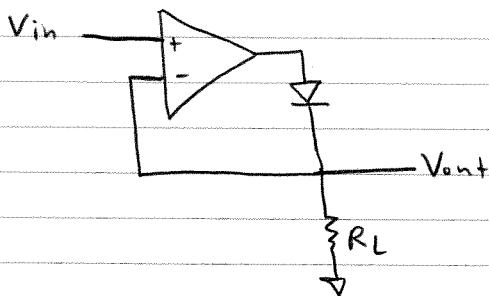
Exponential Output



$$I = I_s (e^{V_i/V_T} - 1) = I_s e^{V_i/V_T}$$

$$\Rightarrow V_{out} = -I_s R e^{V_i/V_T}$$

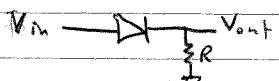
Precision Rectifier



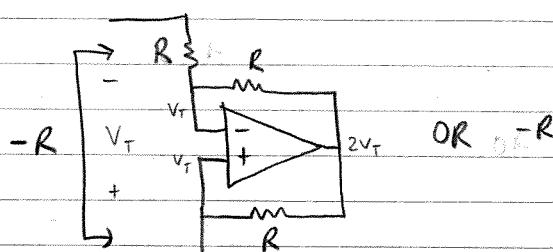
$$V_{out} = \begin{cases} V_{in}, & V_{in} > 0 \\ 0, & V_{in} \leq 0 \end{cases}$$

as opposed to regular rectifier

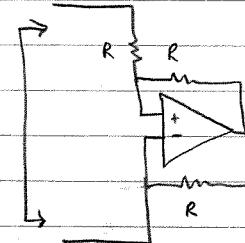
$$V_{out} = \begin{cases} V_{in} - 0.7, & V_{in} > 0.7 \\ 0, & V_{in} \leq 0.7 \end{cases}$$



Negative Resistor



$$i_t = -\frac{V_T}{R} \Rightarrow \frac{V_T}{R_t} = -R$$



Devices Please - Random Facts

- $1 \text{ kg} = 2.2 \text{ lbs}$
- $1 \text{ m} = 3.3 \text{ ft}$
- $1 \text{ km} = 0.62 \text{ mi}$
- $1 \text{ Cal} = 4 \text{ kJ}$

1 lbs of bullets, vs. batteries, vs. beans.

$$\text{Bullets: } KE = \frac{1}{2}mv^2 \quad m = 10g = 10^{-2} \text{ kg} \quad v \approx 300 \text{ m/s} \approx 333 \text{ m/s}$$

$$\Rightarrow KE \approx \frac{1}{2}(10^{-2})(3.33 \cdot 10^2)^2 \approx 0.5 \cdot 10^3 \text{ J} = 0.5 \text{ kJ}$$

$$1 \text{ lb} \approx \frac{1}{2.2} \text{ kg} = 0.45 \text{ kg} \Rightarrow 0.45 \text{ kg} \cdot \frac{0.5 \text{ kJ}}{0.01 \text{ kg}} = 22.5 \text{ kJ}$$

Batteries: Assume 19V lasts 2 hours powering a circuit that draws $\sim 100 \text{ mA}$.

$$= E = \mathcal{E} \cdot t = IV \cdot t = (9V)(0.1A) \cdot (7200s) = 6.5 \text{ kJ/battery.}$$

$$\text{assume } \sim 10 \text{ batteries/lb} \Rightarrow 65 \text{ kJ}$$

Beans: 1-lb of beans. Should be enough to feed a man for a day. \Rightarrow about 2000 Cal.

$$(2000 \text{ Cal})(4 \text{ kJ/cal}) = 8000 \text{ kJ}$$

huge compared to batteries + bullets

Subthreshold Current:

$$\left(\text{diffusion current} \right)$$
$$J_d = q D \frac{dn}{dx}$$

$$I_{dsb} = \mu C_{ox} \frac{W}{L} (m-1) \left(\frac{kT}{q} \right)^2 e^{(V_g - V_t)/(mV_T)} (1 - e^{-qV_{ds}/kT})$$

$$m = 1 + \frac{C_{de}}{C_{ox}} \quad \leftarrow \text{voltage dependence of } V_g$$

$$\frac{I}{I} \frac{V_g}{C_{ox}} \frac{V_g}{m}$$

want m small.

$$S = \left(\frac{\delta(\log I_{dsb})}{\delta V_g} \right)^{-1} = 2.3m \frac{kT}{q} = 60 \text{ mV/dec for } m=1. \quad (C_{de}=0)$$

want S small. so slope is large.

$$S = \frac{\delta V_g}{\delta \psi_s} \frac{\delta \psi_s}{\delta (\log I_{dsb})}$$

↑
gate to channel coupling
60 mV/dec
in MOSFET

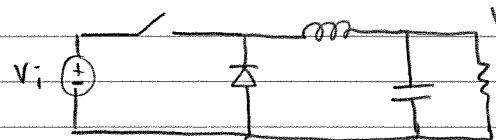
due to
Fermi Dirac
distribution.

Simplified version from Razavi $I_{dsb} = I_s e^{V_g/SV_T} \quad S > 1$

Power Electronics:

DC-DC converters

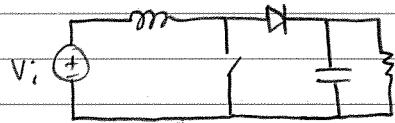
Buck :



$$\frac{V_o}{V_i} = D$$

step down

Boost :

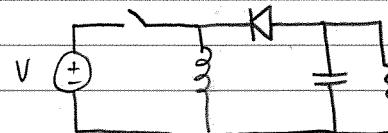


$$\frac{V_o}{V_i} = \frac{1}{1-D}$$

step up

Buck

Boost :



$$\frac{V_o}{V_i} = -\left(\frac{D}{1-D}\right)$$

invert
step
or
down

$$① (V_i - V_o)D - V_o D' = 0 \Rightarrow V_i D = V_o (D' + D) \Rightarrow \frac{V_o}{V_i} = \frac{D}{D' + D} = \frac{D}{1-D+D} = D$$

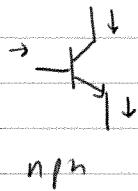
$$② V_i D + (V_i - V_o)D' = 0$$

$$V_i (D + D') = V_o D'$$

$$\frac{V_o}{V_i} = \frac{D + D'}{D'} = \frac{D + 1 - D}{1 - D} = \frac{1}{1 - D}$$

$$③ V_i D + V_o D' = 0 \Rightarrow \frac{V_o}{V_i} = -\frac{D}{D'} = -\frac{D}{1 - D}$$

BJT Review

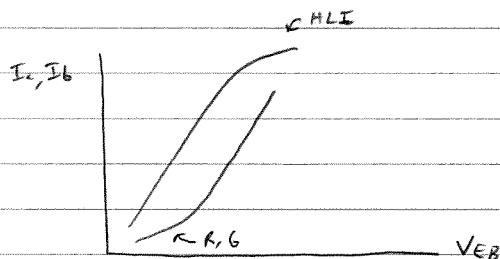


$$\text{for } p-n-p : \quad \gamma = \frac{I_{E_f}}{I_{E_p} + I_{E_n}} = \frac{1}{1 + \frac{D_E}{D_B} \frac{N_B}{N_E} \frac{W}{L_E}}$$

$$\alpha_T = \frac{I_{C_p}}{I_{E_p}} = \frac{1}{1 + \frac{1}{2} \left(\frac{W}{L_B} \right)^2}$$

$$\alpha_{DC} = \gamma \alpha_T$$

$$\beta = \frac{\alpha_{DC}}{1 - \alpha_{DC}} = \frac{1}{\frac{D_E}{D_B} \frac{N_B}{N_E} \frac{W}{L_E} + \frac{1}{2} \left(\frac{W}{L_B} \right)^2} = \frac{I_C}{I_B}$$



$$\text{Law of junction: } n_p = n_i^2 \exp \left(\frac{qV_A}{kT} \right)$$

$$\Delta n_p \Big|_{x_p} = \frac{n_i^2}{N_A} (e^{qV_A/kT} - 1)$$

$$\Delta p_n \Big|_{x_h} = \frac{n_i^2}{N_D} (e^{qV_A/kT} - 1)$$

$$F.S. \quad f(t) = \sum_{n=-\infty}^{\infty} c_n e^{j2\pi n t/T}$$

$$c_n = \frac{1}{T} \int_0^T f(t) e^{-j2\pi n t/T} dt$$

$$F.T. \quad f(t) = \int_{-\infty}^{\infty} F(s) e^{j2\pi s t} ds$$

$$F(s) = \int_{-\infty}^{\infty} f(t) e^{-j2\pi s t} dt$$

$$\overline{Ff} = (Ff)^{-}$$

$$\overline{FF} = f^{-}$$

$$\overline{Ff} = (Ff)^{-}$$

$$\int_{-\infty}^{\infty} f(x) \overline{g(x)} dx = \int_{-\infty}^{\infty} F(s) \overline{G(s)} ds$$

$$F g'(x) = 2\pi i s G(s)$$

$$F g^{(n)}(x) = (2\pi i s)^n G(s)$$

$$F(x^n g(x)) = (\frac{i}{2\pi})^n G(s)$$

$$D.F.T \quad F[m] = \sum_{k=0}^{N-1} f[m] e^{-j2\pi i k m/N}$$

$$f[m] = \frac{1}{N} \sum_{k=0}^{N-1} F[k] e^{j2\pi i k m/N}$$

EE316

TCAD Tool Tutorial - Monday, Jan 30th, 5-6PM Packard 101

V_t is exponentially dependent on channel length L.

Turn HW into bix in 332X

EE316 - Sentaurus Tutorial

emacs, .cshrc

ctrl x s to save

ctrl x c to quit

structure editing: ?

output file is .trd (not .grd anymore)

default units in Sentaurus are in μm .

tecplot_sv ← to visualize script,

→ open files that end in .msh, .dat

Device Simulation

Initial Step refers to percent of total sweep. e.g. 0.01 means 1%.

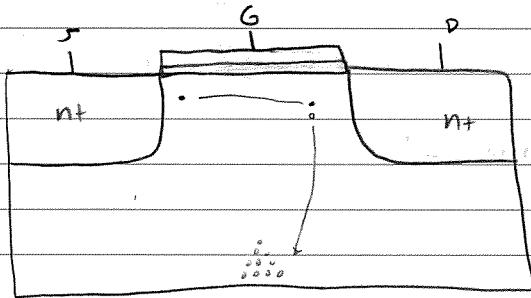
inspect ← to visualize data from a simulation,

file → export → CSV

EE316

PD SOI - main benefit: reduces junction capacitance at S and D.

- Downside: History effect (causes problem for circuit designers)



holes built up. This causes a change in V_t .

$\Rightarrow V_t$ depends on how long the device has been on (history effect).

Parasitic BJT action tends not to occur since L is typically longer than the base width of a BJT.

FD SOI - scale length no longer set by doping. Set by thickness of bulk.

\Rightarrow shorten scale length

- reduced junction capacitance
- Thin BOX (Buried oxide) has less short channel effects than a Thick BOX for a given t_s ; (bulk thickness)

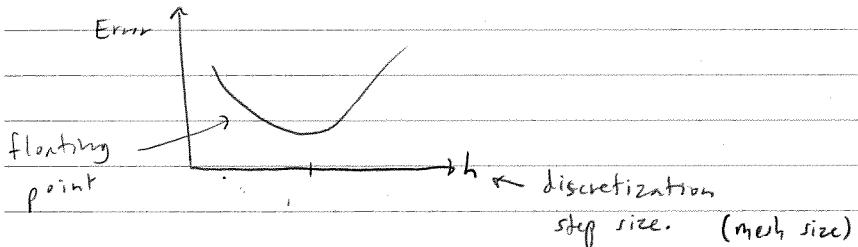
Gradient Channel Approximation : $E_{\text{vert}} \gg E_{\text{horiz}}$ (analytically)
 allows us to solve 1-D Poisson's equation.
 This is not true for short channel devices.
 \Rightarrow we must use TCAD to solve the 2-D
 Poisson's equation numerically.

Quantum Effect : Sheet charge approximation (that all inversion charges are located at the surface like a sheet of charge) no longer holds since quantum confinement causes charges to be located a finite distance away from the interface, which effectively decreases gate capacitance.

Recombination / Generation :

- Shockley-Read-Hall (SRH) recombination/generation (indirect semiconductors)
- Direct recombination/thermal excitation (direct semiconductors)
- Auger recombination/impact ionization
- Band to band tunneling (acts as a generation process)

Which physics to include: see slide 23 of Ximeng Guan's lecture 1.

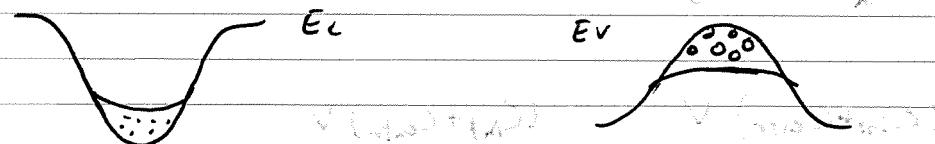
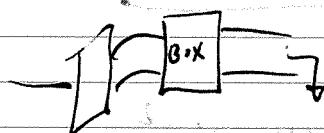


\Rightarrow smaller mesh isn't always better (more accurate).
 Also smaller mesh \Rightarrow longer simulation time.

What makes a good source & drain

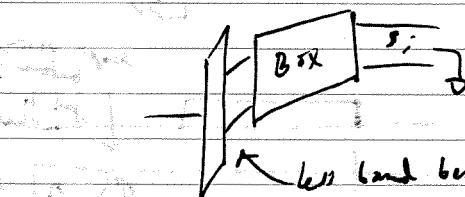
- a good reservoir of carriers
- always in equilibrium (has established fermi level)

7-48 - Nondegenerate $E_F < E_c$



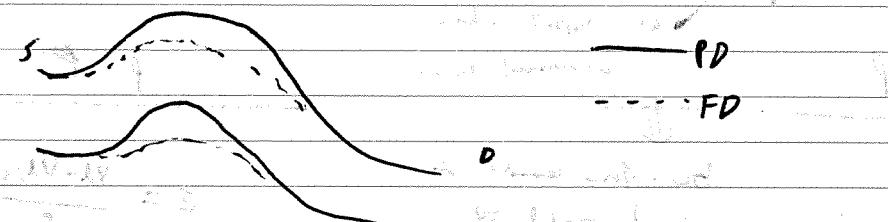
\Rightarrow as you collect holes in the back of the substrate it's a ~~an~~ PDSOI transistor, $V_T \downarrow$ (history effect).

Why does FD SOI not have history effect?



less band bending than for PDSOI.

\Rightarrow

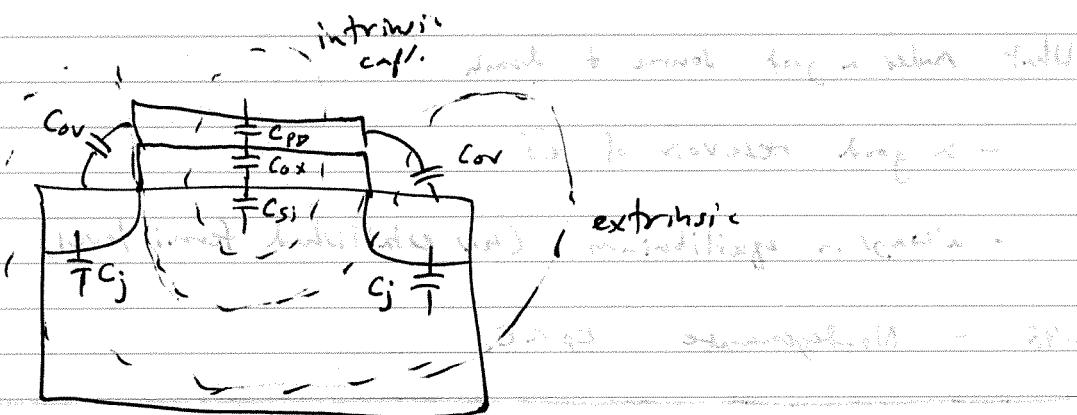


barrier is lower.

\Rightarrow holes can flow out easier \Rightarrow less pronounced history effect.

QUESTION

ANSWER



SOURCE C_{int}

$$I = \mu C_{ox} \frac{w}{L} (V_{GS} - V_t)^2$$

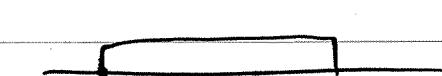
$$\gamma = \frac{(C_{int} + C_{extr}) V}{I} = \frac{(C_{int} + C_{extr}) V}{f(C_{int})}$$

$\Rightarrow C_{int}$ & C_{int} ~~large~~, but C_{extr} small

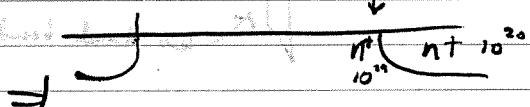
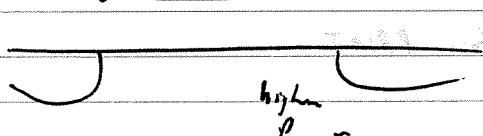
Hot carrier effect - How has industry solved it?

low drain voltage

LDD



drop voltage
before you
get to channel.



P

channel width

but this leads to

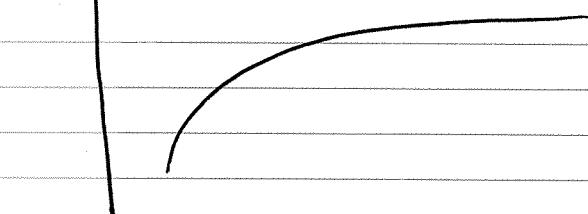
high field \Rightarrow

hot carrier effects.

$$E = \frac{V_d - V_{dsat}}{l}$$

Narrow Width effect:

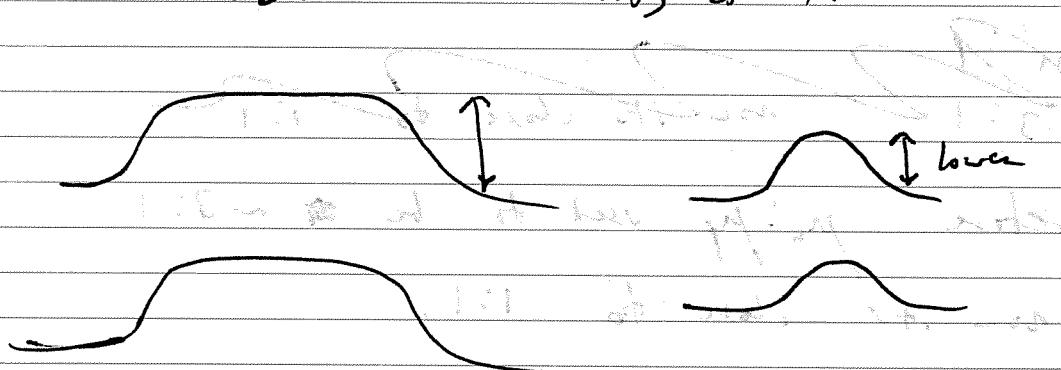
V_t



V_t



SCE - ~~Wide~~ Proximity effect.



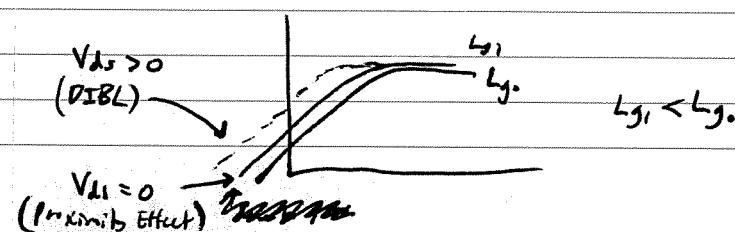
DIBL

SS: depends on C_{ox} + C_{dep}

related to SC

$\sim W_{dm}$

because? how less cont over chan



to first order
SS does not change.

(but in fact it does due to the impact of fringing caps (got worse))

used to put when $L_0 \approx 100\text{nm}$



before

now

Thick BOX: $200-400\text{nm}$, $70-100\text{nm}$ still enough

Thin BOX: ~~20-30nm~~ $20-30\text{nm}$

(currently)
(more common)

Strained Si

By straining Si, you can change the E-k diagram of semiconductor.

p-channel \rightarrow push closer } increases mobility.
n-channel \rightarrow pull out }

for similar amount of stress, hole mobility improves more than electron mobility.

~~before~~ now its close to 1:1

before μ_n/μ_p used to be ~~~~~ $\sim 3:1$

now its close to 1:1.