## Geodesics on Grassmannians

Let  $A, B \in \mathbb{R}^{n \times k}$  be matrices satisfying  $A^T A = B^T B = I_k$ .

- 1) Find orthogonal matrices  $U, V \in O(k)$  such that R = AU and S = BV have the property that  $R^TS$  is a diagonal matrix whose diagonal entries are monotone decreasing and non-negative.
- 2) Goal: Show that if A is skew-symmetric then exp(A) is an orthogonal matrix.
- a) Let A, B be commuting matrices (i.e. AB = BA). Show that exp(A + B) = exp(A)exp(B).
  - b) Find non-commuting matrices A, B with  $exp(A + B) \neq exp(A)exp(B)$ .
  - c) Show that if A is skew-symmetric then A commutes with  $A^T$ .
  - d) Let 0 denote a square matrix of zeros. Show that exp(0) is an identity matrix.
  - e) Show that  $exp(A^T) = exp(A)^T$ .
- f) Recall that a square matrix A is orthogonal if and only if  $A^TA = AA^T = I$ . Show that if A is skew-symmetric then exp(A) is an orthogonal matrix.
- 3) Suppose we know an expression A = exp(S) where S is a skew symmetric matrix. From the above problems, we know that A is an orthogonal matrix.
  - a) How can we use this to parameterize a curve on O(n) from I to A?
  - b) Show that the determinant of an orthogonal matrix is either -1 or 1.
  - c) Show that if S is skew symmetric then exp(S) is in SO(n) (i.e. has determinant 1)
  - d) If B is an orthogonal matrix, how can we parameterize a path from B to BA?
- 4) In Maple, you can exponentiate the square matrix, E, with the command MatrixExponential(E) (from the package "LinearAlgebra"). Recall that A is unitary if A\*A = I where A\* is the conjugate transpose of A.
- a) Let  $E=\begin{bmatrix}0&.23\\-.23&0\end{bmatrix}$ . Find a diagonal matrix D and a unitary matrix U such that  $E=UDU^*$ 
  - b) Compute exp(E) and describe how the entries of E and of exp(E) are related.

- 5) Below is Maple code for finding a geodesic between the subspaces spanned by the columns of A and the columns of B.
  - a) Look at the Maple code below and understand the command syntax and meaning.
  - b) Use the code to find the subspace halfway between the column spaces of A and B.
  - c) Read https://nhigham.com/2020/10/27/what-is-the-cs-decomposition/

```
restart;
with(LinearAlgebra);
with(ArrayTools);
Digits := 30;
R := evalf(RandomMatrix(5, 5));
S := evalf(RandomMatrix(5, 5));
QR := QRDecomposition(R)[1];
QS := QRDecomposition(S)[1];
A := SubMatrix(QR, [1 .. 5], [1, 2]);
AT := SubMatrix(QR, [1 .. 5], [3, 4, 5]);
B := SubMatrix(QS, [1 .. 5], [1, 2]);
BT := SubMatrix(QS, [1 .. 5], [3, 4, 5]);
SVD1 := SingularValues((Transpose(A)) . B, output = ['U', 'S', 'Vt']);
AA := A . (SVD1[1]);
BB := B . (Transpose(SVD1[3]));
(Transpose(AA)) . BB;
SVD2 := SingularValues((Transpose(AT)) . BT, output = ['U', 'S', 'Vt']);
AAT := AT . (SVD2[1]);
BBT := BT . (Transpose(SVD2[3]));
NA := \langle AA \mid AAT \rangle;
NB := \langle BB \mid BBT \rangle;
C := (Transpose(NA)) . NB;
Digits := 20;
CC := evalf(10^{-25})*round^{(10^{25}*C)};
SP1 := Diagonal(CC);
SP2 := CC - DiagonalMatrix(SP1);
X := DiagonalMatrix(cos~(arccos~(SP1)*t)) + sin~(arcsin~(SP2)*t);
eval(NA . X, {t = 0});
```