#### MINORS OF TREE DISTANCE MATRICES

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ABSTRACT. We prove that the principal minors of the distance matrix of a tree satisfy a combinatorial expression involving counts of rooted spanning forests of the underlying tree. This generalizes a result of Graham and Pollak. We also give such an expression for the case of edge-weighted trees.

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## 1. Introduction

Suppose G = (V, E) is a tree with n vertices. Let D denote the distance matrix of G. In [6], Graham and Pollak proved that

(1) 
$$\det D = (-1)^{n-1} 2^{n-2} (n-1).$$

This identity is remarkable in that the result does not depend on the tree structure, beyond the number of vertices. The identity (1) was motivated by a problem in data communication, and inspired much further research on distance matrices.

The main result of this paper is to generalize (1) by replacing det D with any of its principal minors. For a subset  $S \subset V(G)$ , let D[S] denote the submatrix consisting of the S-indexed rows and columns of D.

**Theorem 1.1.** Suppose G is a tree with n vertices, and distance matrix D. Let  $S \subset V(G)$  be a nonempty subset of vertices. Then

(2) 
$$\det D[S] = (-1)^{|S|-1} 2^{|S|-2} \left( (n-1) \kappa(G; S) - \sum_{\mathcal{F}_2(G; S)} (\deg^o(F, *) - 2)^2 \right),$$

where  $\kappa(G; S)$  is the number of S-rooted spanning forests of G,  $\mathcal{F}_2(G; S)$  is the set of (S, \*)-rooted spanning forests of G, and  $\deg^o(F, *)$  denotes the outdegree of the \*-component of F.

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For definitions of (S,\*)-rooted spanning forests and other terminology, see Section 2. When S = V is the full vertex set, the set of V-rooted spanning forests is a singleton, consisting of the subgraph with no edges, so  $\kappa(G;V) = 1$ ; and moreover the set  $\mathcal{F}_2(G;V)$  of (V,\*)-rooted spanning forests is empty. Thus (2) recovers the Graham-Pollak identity (1) when S = V.

1.1. Weighted trees. If  $\{\alpha_e : e \in E\}$  is a collection of positive edge weights, the  $\alpha$ -distance matrix  $D^{(\alpha)}$  is defined by setting the (u, v)-entry to the sum of the weights  $\alpha_e$  along the unique path from u to v. The relation (1) has an analogue for the weighted distance matrix,

(3) 
$$\det D^{(\alpha)} = (-1)^{n-1} 2^{n-2} \sum_{e \in E} \alpha_e \prod_{e \in E} \alpha_e,$$

which was proved by Bapat–Kirkland–Neumann [1]. The weighted identity (3) reduces to (1) when taking all unit weights,  $\alpha_e = 1$ . We also prove the following weighted version of our main theorem.

**Theorem 1.2.** Suppose G = (V, E) is a finite, weighted tree with edge weights  $\{\alpha_e : e \in E\}$ , and corresponding weighted distance matrix  $D = D^{(\alpha)}$ . For any nonempty subset  $S \subset V$ , we have

(4) 
$$\det D^{(\alpha)}[S] = (-1)^{|S|-1} 2^{|S|-2} \left( \sum_{E(G)} \alpha_e \sum_{\mathcal{F}_1(G;S)} w(\overline{T}) - \sum_{\mathcal{F}_2(G;S)} (\deg^o(F,*) - 2)^2 w(\overline{F}) \right),$$

where  $\mathcal{F}_1(G;S)$  is the set of S-rooted spanning forests of G,  $\mathcal{F}_2(G;S)$  is the set of (S,\*)-rooted spanning forests of G,  $w(\overline{T})$  and  $w(\overline{F})$  denote the  $\alpha$ -weights of the forests T and F, and  $\deg^o(F,*)$  is the outdegree of the \*-component of F, as above.

Theorem 1.2 reduces to Theorem 1.1 when taking all unit weights,  $\alpha_e = 1$ .

1.2. **Applications.** Suppose we fix a tree distance matrix D. It is natural to ask, how do the expressions  $\det D[S]$  vary as we vary the vertex subset S? To our knowledge there is no nice behavior among the determinants, but as S varies there is nice behavior of the "normalized" ratios  $\det D[S]/\cot D[S]$  which we describe here.

Given a matrix A, let cof A denote the sum of cofactors of A, i.e.

$$\operatorname{cof} A = \sum_{i=1}^{|S|} \sum_{j=1}^{|S|} (-1)^{i+j} \det A_{i,j}$$

where  $A_{i,j}$  is the submatrix of A that removes the i-th row and the j-th column. If A is invertible, then cof A is related to the sum of entries of the matrix inverse  $A^{-1}$  by a factor of det A, i.e. cof  $A = (\det A)(\mathbf{1}^{\mathsf{T}}A^{-1}\mathbf{1})$ . In [3], Bapat and Sivasubramanian showed the following identity for the sum of cofactors of a distance submatrix D[S] of a tree,

(5) 
$$\operatorname{cof} D[S] = (-2)^{|S|-1} \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}).$$

Using the Bapat–Sivasubramanian identity (5), an immediate corollary to Theorem 1.2 is the following result:

(6) 
$$\frac{\det D[S]}{\cot D[S]} = \frac{1}{2} \left( \sum_{e \in E} \alpha_e - \frac{\sum_{F \in \mathcal{F}_2(G;S)} w(\overline{F}) (\deg^o(F,*) - 2)^2}{\sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T})} \right).$$

The expression (6) satisfies a monotonicity condition as we vary the vertex set  $S \subset V(G)$ .

**Theorem 1.3** (Monotonicity of normalized principal minors). If  $A, B \subset V(G)$  are nonempty subsets with  $A \subset B$ , then

$$\frac{\det D[A]}{\cot D[A]} \le \frac{\det D[B]}{\cot D[B]}.$$

The essential observation behind this result is that  $\det D[S]/\cot D[S]$  is calculated via the following quadratic optimization problem: for all vectors  $\mathbf{m} \in \mathbb{R}^S$ ,

optimize objective function:  $\mathbf{m}^{\mathsf{T}}D[S]\mathbf{m}$  with constraint:  $\mathbf{1}^{\mathsf{T}}\mathbf{m} = 1$ .

This result can be shown using Lagrange multipliers, and relies of knowledge of the signature of D[S]. For details, see Section 3.

If  $S \subset V(G)$  is nonempty, the expression (6) immediately implies the bound

$$0 \le \frac{\det D[S]}{\cot D[S]} \le \frac{1}{2} \sum_{E(G)} \alpha_e.$$

We get refined bounds by making use of the monotonicity property, Theorem 1.3.

**Theorem 1.4** (Bounds on principal minor ratios). Suppose G = (V, E) is a finite, weighted tree with distance matrix  $D^{(\alpha)}$ .

(a) If conv(S,G) denotes the subtree of G consisting of all paths between points of  $S \subset V(G)$ ,

$$\frac{\det D^{(\alpha)}[S]}{\cot D^{(\alpha)}[S]} \le \frac{1}{2} \sum_{E(\operatorname{conv}(S,G))} \alpha_e.$$

(b) If  $\gamma$  is a simple path between vertices  $s_0, s_1 \in S$ , then

$$\frac{1}{2} \sum_{e \in \gamma} \alpha_e \le \frac{\det D^{(\alpha)}[S]}{\cot D^{(\alpha)}[S]}.$$

1.3. Further questions. A formula for the inverse matrix  $D^{-1}$  was found by Graham and Lovász in [5]. Namely,

$$D^{-1} = -\frac{1}{2}L + \frac{1}{2(n-1)}\mathbf{m}\mathbf{m}^{\mathsf{T}}$$

where L is the Laplacian matrix and **m** is the vector  $\mathbf{m}_v = 2 - \deg v$ . Does there exist a nice expression for the inverse of the matrix D[S]?

1.4. **Notation.** G a finite graph, loops and parallel edges allowed, possibly disconnected

E(G) edge set of G

V(G) vertex set of G

 $\mathcal{F}_1(G;S)$  the set of S-rooted spanning forests of G

 $\mathcal{F}_2(G;S)$  the set of (S,\*)-rooted spanning forests of G

### 2. Graphs and matrices

For background on enumeration problems for graphs and trees, see Tutte [11, Chapter VI].

Let G = (V, E) be a graph with edge weights  $\{\alpha_e : e \in E\}$ . For any edge subset  $A \subset E$  we define the weight of A as  $w(A) = \prod_{e \in A} \alpha_e$ . We define the co-weight of A as  $w(\overline{A}) = \prod_{e \notin A} \alpha_e$ . By abuse

of notation, if H is a subgraph of G, we use H to also denote its subset of edges E(H), so e.g.  $w(\overline{H}) = w(\overline{E(H)})$ .

Let M be an  $n \times n$  matrix. For a subset  $S \subset \{1, \ldots, n\}$ , let M[S] denote the submatrix obtained by keeping the S-indexed rows and columns of M. Let  $M[\overline{S}]$  denote the submatrix obtained by deleting the S-indexed rows and columns.

2.1. **Spanning trees and forests.** A spanning tree of a graph G is a subgraph which is connected, has no cycles, and contains all vertices of G. A spanning forest of a graph G is a subgraph which has no cycles and contains all vertices of G. Let  $\kappa(G)$  denote the number of spanning trees of G, and let  $\kappa_T(G)$  denote the number of r-component spanning forests.

Given a set of vertices  $S = \{v_1, v_2, \dots, v_k\}$ , an S-rooted spanning forest of G is a spanning forest which has exactly one vertex  $v_i$  in each connected component. An (S, \*)-rooted spanning forest of G is a spanning forest which has |S| + 1 components, where |S| components each contain one vertex of S, and the additional component is disjoint from S. We call the component disjoint from S the floating component, following terminology in [8]. Given  $s \in S$  and a forest F in  $\mathcal{F}_1(G; S)$  or  $\mathcal{F}_2(G; S)$ , we let F(s) denote the S-component of S, and let S-component the floating component (if S-component).

Let  $\kappa(G; S)$  denote the number of S-rooted spanning forests of G, and let  $\kappa_2(G; S)$  denote the number of (S, \*)-rooted spanning forests. Let  $\mathcal{F}_1(G; S)$  denote the set of S-rooted spanning forests of G, and let  $\mathcal{F}_2(G; S)$  denote the set of (S, \*)-rooted spanning forests of G. Note that  $\kappa(G; S)$  is also the number of spanning trees of the quotient graph G/S, which "glues together" all vertices in S as a single vertex.

Let

$$\kappa_k(v_1|v_2|\cdots|v_k)$$

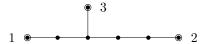
denote the number of k-component spanning trees which have a vertex  $v_i$  in each component. If  $S = \{v_1, \ldots, v_k\}$ , then  $\kappa_k(v_1|\cdots|v_k) = \kappa(G;S) = \kappa(G/S)$ .

If u, v, w are vertices, then let

$$\kappa_2(uv|w)$$

denote the number of two-forests which have u, v in one component and w in the other component.

**Example 2.1.** Suppose G is the tree with unit edge lengths shown below.



Let S be the set of three leaf vertices. Then  $\mathcal{F}_1(G; S)$  contains 11 forests, while  $\mathcal{F}_2(G; S)$  contains 19 forests. Some of these are shown in Figures 1 and 2, respectively.

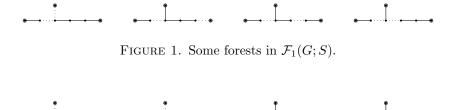


FIGURE 2. Some forests in  $\mathcal{F}_2(G;S)$ , with floating component highlighted.

2.2. **Laplacian matrix.** Given a graph G = (V, E), consider an orientation on the edge set, which consists of a pair of functions head :  $E \to V$  and tail :  $E \to V$ , such that head(e) and tail(e) are the endpoints of e. We abbreviate head(e) as  $e^+$ , and tail(e) as  $e^-$ .

The incidence matrix of G is the matrix  $N \in \mathbb{R}^{V \times E}$  defined by

$$N_{v,e} = \mathbb{1}(v = e^+) - \mathbb{1}(v = e^-).$$

Let  $L \in \mathbb{R}^{V \times V}$  denote the Laplacian matrix of G, which is defined by  $L = NN^{\intercal}$ . If G is a weighted graph with positive edge weights  $\alpha_e$  for  $e \in E$ , let  $L^{(\alpha)}$  denote the weighted Laplacian matrix of G, defined by

$$L^{(\alpha)} = N \begin{pmatrix} \alpha_1^{-1} & & \\ & \ddots & \\ & & \alpha_m^{-1} \end{pmatrix} N^{\mathsf{T}}.$$

It is clear that L and  $L^{(\alpha)}$  are positive semidefinite.

Given  $S \subset V$ , let  $L[\overline{S}]$  denote the matrix obtained from L by removing the rows and columns indexed by S. More generally, let  $L[\overline{S}, \overline{T}]$  denote the matrix obtained from L by removing S-indexed rows and T-indexed columns. Recall that  $\kappa(G; S)$  denotes the number of S-rooted spanning forests of G. The following theorem relates minors of the (weighted) Laplacian to (weighted) counts of rooted spanning forests.

**Theorem 2.2** (Principal-minors matrix tree theorem). Let G = (V, E) be a finite graph.

(a) Let L denote the Laplacian matrix of G. Then for any nonempty vertex set  $S \subset V$ ,

$$\det L[\overline{S}] = \kappa(G; S).$$

(b) Let  $L^{(\alpha)}$  denote the weighted Laplacian matrix of G, with edge weights  $\{\alpha_e\}$ . Then for any nonempty vertex set  $S \subset V$ ,

$$\det L^{(\alpha)}[\overline{S}] = \sum_{T \in \mathcal{F}_1(G;S)} w(T)^{-1} = \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}) \prod_{e \in E} \alpha_e^{-1}.$$

*Proof.* See Tutte [11, Section VI.6, Equation (VI.6.7)] or Chaiken [4] or Bapat [2, Theorem 4.7].  $\Box$ 

Next we recall a connection between minors of the Laplacian matrix and cofactor sums of the distance matrix, when G is a tree. The result is due to Bapat–Sivasubramanian [3]. Recall that  $\operatorname{cof} M$  denotes the sum of cofactors of M, i.e.  $\operatorname{cof} M = \sum_{i=1}^{n} \sum_{j=1}^{n} (-1)^{i+j} \det M[\overline{i}, \overline{j}]$ .

**Theorem 2.3** (Distance submatrix cofactor sums). Given a tree G with edge weights, let D be the weighted distance matrix of G, and L the weighted Laplacian matrix of G. Let  $S \subset V(G)$  be a nonempty subset of vertices of G. Then

$$cof D^{(\alpha)}[S] = (-2)^{|S|-1} \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}).$$

*Proof.* Bapat and Sivasubramanian [3, Theorem 11] show that

$$\operatorname{cof} D^{(\alpha)}[S] = (-2)^{|S|-1} \left( \prod_{e \in E} \alpha_e \right) \det L[\overline{S}].$$

Then combine this equation with the matrix tree theorem, Theorem 2.2 (b).

The following result is a direct consequence of theorems of Bapat–Kirkland–Neumann [1] and Bapat–Sivasubramanian [3].

**Proposition 2.4.** Suppose D is the distance matrix of a weighted tree with edge weights  $\{\alpha_e : e \in E\}$ . Then

$$\frac{\det D^{(\alpha)}}{\cot D^{(\alpha)}} = \frac{1}{2} \sum_{e \in E} \alpha_e.$$

*Proof.* Consider applying Theorem 2.3 with S = V. In this case  $\mathcal{F}_1(G; V)$  consists of the forest with no edges, and for this forest  $w(\overline{T})$  is the product of all edge weights. Thus

$$\operatorname{cof} D^{(\alpha)} = (-2)^{n-1} \prod_{e \in E} \alpha_e.$$

Combining this with the Bapat-Kirkland-Neuman formula (3) yields the result.

2.3. Tree splits and tree distance. In this section we describe the tree splits associated to a tree, and use their associated indicator functions to give an expression for the tree distance.

Given a tree G=(V,E) and an edge  $e\in E$ , the edge deletion  $G\setminus e$  contains two connected components. Using the implicit orientation on  $e=(e^+,e^-)$ , we let  $(G\setminus e)^+$  denote the component that contains endpoint  $e^+$ , and let  $(G\setminus e)^-$  denote the other component. For any  $e\in E$  and  $v\in V$ , we let  $(G\setminus e)^v$  denote the component of  $G\setminus e$  containing v, respectively  $(G\setminus e)^{\overline{v}}$  for the component not containing v.

Tree splits can be used to express the path distance between vertices in a tree. Given an edge  $e \in E$  and vertices  $v, w \in V$ , let

$$\delta(e; v, w) = \begin{cases} 1 & \text{if } e \text{ separates } v \text{ from } w, \\ 0 & \text{otherwise.} \end{cases}$$

In other words,  $\delta(e; v, w) = 1$  if the vertices are in different components of the split  $G \setminus e$ , and  $\delta(e; v, w) = 0$  if they are in the same component. Note that  $\delta(e; v, v) = 0$  for any e and v.

We have the following perspectives on the function  $\delta(e; v, w)$ :

- (i) If we fix e and v, then  $\delta(e; v, -) : V(G) \to \{0, 1\}$  is the indicator function for the component  $(G \setminus e)^{\overline{v}}$  of the tree split  $G \setminus e$  not containing v.
- (ii) On the other hand if we fix v and w, then  $\delta(-; v, w) : E(G) \to \{0, 1\}$  is the indicator function for the unique  $v \sim w$  path in G.

**Proposition 2.5** (Weighted tree distance). For a tree G = (V, E) with weights  $\{\alpha_e : e \in E\}$ , the weighted distance function satisfies

$$D^{(\alpha)}(v,w) = \sum_{e \in E} \alpha_e \, \delta(e;v,w).$$

For an unweighted tree, we can express the tree distance d(v, w) as the unweighted sum

$$d(v, w) = \sum_{e \in E(G)} \delta(e; v, w).$$

2.4. Outdegree of rooted forest. Given a vertex v in a graph, the  $degree \deg(v)$  is the number of edges incident to v. A consequence of the "handshake lemma" of graph theory is that for any tree G, we have

$$\sum_{v \in V(G)} (2 - \deg(v)) = 2.$$

In this section we discuss some generalizations, which will be used later.

Given a connected subgraph  $H \subset G$ , we define the *outdegree*  $\deg^o(H)$  as the number of edges which join H to its complement; i.e.

$$\deg^{o}(H) = \#\{e = (a, b) \in E : a \in V(H), b \notin V(H)\}.$$

We often use the following special case of the outdegree: given a rooted forest F in  $\mathcal{F}_1(G;S)$  and  $s \in S$ , let F(s) denote the s-component of F. We define the outdegree  $\deg^o(F,s)$  as the number of edges which join F(s) to a different component; i.e.

(7) 
$$\deg^{o}(F,s) = \#\{e = (a,b) \in E : a \in F(s), b \notin F(s)\}.$$

If F is a forest in  $\mathcal{F}_2(G; S)$ , let  $\deg^o(F, *)$  denote the outdegree of the floating component.

Lemma 2.6. Suppose G is a tree.

(a) If  $H \subset G$  is a (nonempty) connected subgraph, then

$$\sum_{v \in V(H)} (2 - \deg(v)) = 2 - \deg^{o}(H).$$

(b) For any fixed edge e and fixed vertex u of G, we have

$$\sum_{v \in V(G)} (2 - \deg(v)) \, \delta(e; u, v) = 1.$$

*Proof.* (a) This is straightforward to check by induction on |V(H)|, with base case |V(H)| = 1: if  $H = \{v\}$  consists of a single vertex, then  $\deg^o(H) = \deg(v)$ .

(b) Recall that  $(G \setminus e)^{\overline{u}}$  denotes the component of the tree split  $G \setminus e$  that does not contain u. Its vertices are precisely those v that satisfy  $\delta(e; u, v) = 1$ . Since this component has a single edge separating it from its complement,  $\deg^o((G \setminus e)^{\overline{u}}) = 1$  Using part (a), we have

$$\sum_{v \in V} (2 - \deg(v))\delta(e; u, v) = \sum_{v \in (G \setminus e)^{\overline{u}}} (2 - \deg(v)) = 2 - \deg^{o}((G \setminus e)^{\overline{u}}) = 1.$$

2.5. **Distance matrix.** In this section we recall some results on the distance matrix of a tree. Bapat–Kirkland–Neumann [1, Theorem 2.1] prove that

(8) 
$$(D^{(\alpha)})^{-1} = -\frac{1}{2}L^{(\alpha)} + \frac{1}{2}\left(\sum_{e \in E} \alpha_e\right)^{-1} \mathbf{m} \, \mathbf{m}^{\mathsf{T}}$$

where **m** is the vector with components  $\mathbf{m}_v = 2 - \deg v$ .

**Proposition 2.7.** Let D denote the weighted distance matrix of a tree, and L the weighted Laplacian matrix. Then

$$D^{(\alpha)} = -\frac{1}{2}D^{(\alpha)}L^{(\alpha)}D^{(\alpha)} + \frac{1}{2}\left(\sum_{e \in E} \alpha_e\right)\mathbf{1}\mathbf{1}^{\mathsf{T}}.$$

*Proof.* Multiply (8) by the all-ones vector  $\mathbf{1}$ ; since  $L^{(\alpha)}\mathbf{1} = 0$  and  $\mathbf{m}^{\dagger}\mathbf{1} = 2$ , we obtain  $(D^{(\alpha)})^{-1}\mathbf{1} = \left(\sum_{e \in E} \alpha_e\right)^{-1}\mathbf{m}$ . Hence  $D^{(\alpha)}\mathbf{m} = \left(\sum_{e \in E} \alpha_e\right)\mathbf{1}$ . Then multiply (8) by  $D^{(\alpha)}$  on both sides.

The unweighted version of (8) appeared earlier in Graham–Lovasz [5, Lemma 1].

**Proposition 2.8.** Suppose D is the (weighted) distance matrix of a tree.

- (a) If  $\mathbf{h} \in \mathbb{R}^V$  is a vector whose coordinates sum to zero, then  $\mathbf{h}^{\intercal} D \mathbf{h} \leq 0$ .
- (b) If  $\mathbf{h} \in \mathbb{R}^S$  is a vector whose coordinates sum to zero, then  $\mathbf{h}^{\intercal}D[S]\mathbf{h} \leq 0$ .

*Proof.* (a) By assumption  $\mathbf{1}^{\intercal}\mathbf{h} = 0$ . Using Proposition 2.7,

$$\mathbf{h}^{\mathsf{T}}D\mathbf{h} = -\frac{1}{2}\mathbf{h}^{\mathsf{T}}DLD\mathbf{h} + 0.$$

It is well-known that the Laplacian matrix is positive semidefinite, so  $\mathbf{h}^{\intercal}DLD\mathbf{h} = (D\mathbf{h})^{\intercal}L(D\mathbf{h}) \geq 0$ . Thus  $\mathbf{h}^{\intercal}D\mathbf{h} \leq 0$  as claimed.

(b) This follows from (a) since 
$$\mathbf{h}^{\intercal}D[S]\mathbf{h} = D$$
.

Later we will make use of the fact that a submatrix D[S] of a distance matrix has nonzero determinant, as long as  $|S| \ge 2$ . We prove this fact in this section.

We first recall a result of Cauchy, which states that the eigenvalues of  $M[\bar{i}]$  "interlace" the eigenvalues of M. Recall that  $M[\bar{i}]$  denotes the matrix obtained from M by deleting the i-th row and column.

**Proposition 2.9** (Cauchy interlacing). Suppose M is a symmetric real matrix with ordered eigenvalues  $\lambda_1 \leq \cdots \leq \lambda_n$ , and the submatrix M[i] has ordered eigenvalues  $\mu_1 \leq \cdots \leq \mu_{n-1}$ . Then

$$\lambda_1 \le \mu_1 \le \lambda_2 \le \dots \le \mu_{n-1} \le \lambda_n$$
.

*Proof.* See Horn–Johnson [7, Theorem 4.3.17].

**Lemma 2.10** (Bapat [2, Lemma 8.15]). Suppose  $D^{(\alpha)}$  is the (weighted) distance matrix of a tree with n vertices. Then  $D^{(\alpha)}$  has one positive eigenvalue and n-1 negative eigenvalues.

*Proof.* Lemma 8.15 of [2] is stated for a non-weighted distance matrix; however, the same argument applies to a weighted distance matrix by applying Bapat–Kirkland–Neumann's result (3) on the weighted distance matrix determinant [1, Corollary 2.5].

The following argument was communicated to the author by Bapat, via personal communication.

**Proposition 2.11.** Suppose  $D^{(\alpha)}$  is the weighted distance matrix of a tree G = (V, E) and  $S \subset V$  is a subset of size  $|S| \geq 2$ . Then

- (a)  $D^{(\alpha)}[S]$  has one positive eigenvalue and |S|-1 negative eigenvalues;
- (b)  $\det D^{(\alpha)}[S] \neq 0$ .

Proof. (a) Let n = |V|; assume  $n \ge 3$ . We apply decreasing induction on the size of S. If |S| = n - 1, then Lemma 2.10 and Cauchy interlacing imply that D[S] has at most one positive eigenvalue, and at least one negative eigenvalue. Since all diagonal entries of D[S] are zero, D[S] has zero trace. Thus D[S] has exactly one positive eigenvalue as claimed. The same argument applies for smaller S, as long as  $|S| \ge 2$ .

(b) This follows from (a), since the determinant is the product of eigenvalues.  $\Box$ 

# 2.6. Miscellaneous.

**Remark 2.12.** A key step in the main proof is the use of the map

$$E(G) \times \mathcal{F}_1(G; S) \mapsto S \sqcup \{\text{error}\}\$$

defined by

$$(e,T) \mapsto \begin{cases} s & \text{if } e \in T(s), \\ \text{error} & \text{if } e \not\in T. \end{cases}$$

**Remark 2.13.** For a given spanning forest  $F \in \mathcal{F}_2(G; S)$ , there are exactly  $\deg^o(F, *)$ -many choices of pairs  $(T, e) \in \mathcal{F}_1(G; S) \times E(G)$  such that  $F = T \setminus e$ . Consider the "deletion" map

$$E(G) \times \mathcal{F}_1(G;S) \to \mathcal{F}_2(G;S) \sqcup \mathcal{F}_1(G;S)$$

defined by

$$(e,T) \mapsto \begin{cases} T \setminus e & \text{if } e \in T, \\ T & \text{if } e \notin T. \end{cases}$$

For a forest F in  $\mathcal{F}_2(G;S)$ , the preimage under this map has  $\deg^o(F,*)$  elements.

There is an associated "union" map

$$E(G) \times \mathcal{F}_2(G;S) \longrightarrow \mathcal{F}_1(G;S) \sqcup \mathcal{F}_2(G;S)$$

defined by

$$(e,F) \mapsto \begin{cases} F \cup e & \text{if } e \in \partial F, \\ F & \text{if } e \notin \partial F \end{cases}$$

For a forest T in  $\mathcal{F}_1(G;S)$ , the preimage under this map has |E(T)|-many elements.

## 3. Optimization: Quadratic Programming

In this section, we explain how the quantity  $\frac{\det D[S]}{\cot D[S]}$  arises as the solution of a quadratic optimization problem.

**Proposition 3.1.** If D[S] is a principal submatrix of a distance matrix indexed by S, then

$$\frac{\det D[S]}{\operatorname{cof} D[S]} = \max\{\mathbf{m}^\intercal D[S]\mathbf{m}: \mathbf{m} \in \mathbb{R}^S, \ \mathbf{1}^\intercal \mathbf{m} = 1\}$$

where  $\operatorname{cof} D[S]$  denotes the sum of cofactors of D[S].

Corollary 3.2. If D[S] is a principal submatrix of a distance matrix indexed by S, then

$$\frac{\det D[S]}{\cot D[S]} = \max\{\mathbf{m}^{\intercal} D\mathbf{m} : \mathbf{m} \in \mathbb{R}^{V}, \ \mathbf{1}^{\intercal} \mathbf{m} = 1, \ \mathbf{m}_{v} = 0 \ \textit{if} \ v \not\in S\}$$

where cof D[S] denotes the sum of cofactors of D[S].

*Proof.* If |S| = 1 then D[S] is the zero matrix and the statement is true trivially.

Now assume  $|S| \ge 2$ . Proposition 2.8 implies that the objective function is concave on the domain  $\mathbf{1}^{\mathsf{T}}\mathbf{m} = 1$  so any critical point is a local maximum. The gradient of the objective function is  $2D[S]\mathbf{m}$ , and the gradient of the constraint is  $\mathbf{1}$ . By the theory of Lagrange multipliers, the optimal solution  $\mathbf{m}^*$  is a vector satisfying

$$D[S]\mathbf{m}^* = \lambda \mathbf{1}$$
 for some  $\lambda \in \mathbb{R}$ .

The constant  $\lambda$  is in fact the optimal objective value, since

$$(\mathbf{m}^*)^{\mathsf{T}}D[S]\mathbf{m}^* = (D[S]\mathbf{m}^*)^{\mathsf{T}}\mathbf{m}^* = \lambda(\mathbf{1}^{\mathsf{T}}\mathbf{m}^*) = \lambda.$$

The above computation uses the fact that D[S] is a symmetric matrix, and the given constraint  $\mathbf{1}^{\mathsf{T}}\mathbf{m} = 1$ .

On the other hand, since D[S] is invertible (Proposition 2.11) we have  $\mathbf{m}^* = \lambda(D[S]^{-1}\mathbf{1})$ , so that

$$1 = \mathbf{1}^{\mathsf{T}} \mathbf{m}^* = \lambda (\mathbf{1}^{\mathsf{T}} D[S]^{-1} \mathbf{1}) = \lambda \frac{\operatorname{cof} D[S]}{\det D[S]}.$$

Thus the optimal objective value is  $\lambda = \frac{\det D[S]}{\cot D[S]}$ .

Proof of Theorem 1.3. We are to show that for vertex subsets  $A \subset B$ , we have  $\frac{\det D[A]}{\cot D[A]} \leq \frac{\det D[B]}{\cot D[B]}$ .

By Corollary 3.2, both values  $\frac{\det D[A]}{\cot D[A]}$  and  $\frac{\det D[B]}{\cot D[B]}$  arise from optimizing the same objective function, but the constraint for A is more strict.

Proof of 1.4. (a) To see that

$$\frac{\det D[S]}{\operatorname{cof} D[S]} \le \frac{1}{2} \sum_{E(\operatorname{conv}(S,G))} \alpha_e.$$

take B as the set of all vertices in conv(S,G). Then  $S\subset B$ , and by Proposition 2.4 we have

$$\frac{\det D[B]}{\operatorname{cof} D[B]} = \frac{1}{2} \sum_{E(\operatorname{conv}(S,G))} \alpha_e.$$

(b) Recall that  $\gamma$  is a simple path between vertices  $s_0, s_1 \in S$ . To see that

$$\frac{1}{2} \sum_{e \in \gamma} \alpha_e \le \frac{\det D[S]}{\cot D[S]},$$

take A as the set of endpoints of  $\{s_0, s_1\}$ . Then  $A \subset S$  by assumption, and by Proposition 2.4 we have

$$\frac{\det D[A]}{\cot D[A]} = \frac{1}{2}d(s_0, s_1) = \frac{1}{2}\sum_{e \in \gamma} \alpha_e.$$

## 4. Distance submatrices: Proofs

In this section we prove our main result, Theorem 1.2. Theorem 1.1 follows as an immediate corollary.

- 4.1. Outline of proof. Given a subset  $S \subset V$  and distance submatrix D[S], we will complete the following steps.
  - (i) Find vector  $\mathbf{m} \in \mathbb{R}^S$  such that  $D[S]\mathbf{m} = \lambda \mathbf{1} \in \mathbb{R}^S$ .
- (ii) Compute the sum of entries of  $\mathbf{m}$ , i.e.  $\mathbf{1}^{\mathsf{T}}\mathbf{m}$ , and normalize

$$\mathbf{m}^* = \frac{\mathbf{m}}{\mathbf{1}^\intercal \mathbf{m}}.$$

This solves the optimization problem of Section 3.

(iii) The optimal objective value  $(\mathbf{m}^*)^{\mathsf{T}}D[S]\mathbf{m}^* = \lambda^*$  is

$$\lambda^* = \frac{\lambda}{\mathbf{1}^\mathsf{T} \mathbf{m}}.$$

(iv) Using Theorem 3.1,

$$\frac{\det D[S]}{\cot D[S]} = \lambda^* = \frac{\lambda}{\mathbf{1}^{\mathsf{T}}\mathbf{m}}$$

where cof D[S] is the sum of cofactors of D[S]. Use expression for cof D[S] in Theorem 2.3 to compute det D[S].

It turns out that the entries of  $\mathbf{m}$  are combinatorially meaningful, which also gives combinatorial meaning to the constant  $\lambda$ .

**Example 4.1.** Suppose G is a tree consisting of three paths joined at a central vertex. Let S consist of the central vertex, and the three endpoints of the paths. The corresponding submatrix of the distance matrix is

$$D[S] = \begin{bmatrix} 0 & a & b & c \\ a & 0 & a+b & a+c \\ b & a+b & 0 & b+c \\ c & a+c & b+c & 0 \end{bmatrix}.$$

Following the steps outlined above:

- (i) The vector  $\mathbf{m} = \begin{bmatrix} -1\\1\\1\\1\\1 \end{bmatrix}$  satisfies  $D[S]\mathbf{m} = (a+b+c)\mathbf{1}$
- (ii) The sum of entries of  $\mathbf{m}$  is  $\mathbf{1}^{\mathsf{T}}\mathbf{m} = 2$ , so  $\mathbf{m}^* = \frac{1}{2}\mathbf{m}$ .
- (iii) We have

$$\lambda^* = \frac{\lambda}{1^\mathsf{T} \mathbf{m}} = \frac{a+b+c}{2}.$$

(iv) The cofactor sum cof D[S] is -8abc, so the determinant is

$$\det D[S] = (\lambda^*) \cot A = \frac{a+b+c}{2} (-8abc) = -4(a+b+c)abc.$$

4.2. General case:  $S \subset V$ . Fix a tree G = (V, E) and a nonempty subset  $S \subset V$ .

**Definition 4.2.** Let  $\mathbf{m} = \mathbf{m}(G; S)$  denote the vector in  $\mathbb{R}^S$  be defined by

(9) 
$$\mathbf{m}_{v} = \sum_{T \in \mathcal{F}_{1}(G;S)} (2 - \deg^{o}(T,v)) w(\overline{T}) \quad \text{for each } v \in S.$$

where  $\deg^{o}(T, v)$  is the outdegree of the v-component of T, (7).

Let 1 denote the all-ones vector.

Proposition 4.3. For the vector m defined above,

$$(a) \ \mathbf{1}^{\mathsf{T}}\mathbf{m} = 2 \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T});$$

(b) if all edge weights  $\alpha_e$  are positive, **m** is nonzero.

*Proof.* (a) By Lemma 2.6 we have

$$\mathbf{m}_s = \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T})(2 - \deg^o(T,s)) = \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}) \left( \sum_{v \in T(s)} (2 - \deg(v)) \right).$$

Then exchange the order of summation in  $1^{\mathsf{T}}\mathbf{m}$ ,

$$\mathbf{1}^{\mathsf{T}}\mathbf{m} = \sum_{s \in S} \mathbf{m}_s = \sum_{s \in S} \left( \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}) \sum_{v \in T(s)} (2 - \deg(v)) \right)$$
$$= \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}) \left( \sum_{s \in S} \sum_{v \in T(s)} (2 - \deg(v)) \right).$$

Observe that the inner double sum is simply a sum over  $v \in V$ , since the vertex sets of T(s) for  $s \in S$  form a partition of V by definition of S-rooted spanning forest. Thus

$$\mathbf{1}^{\mathsf{T}}\mathbf{m} = \sum_{T \in \mathcal{F}_1} w(\overline{T}) \left( \sum_{v \in V} (2 - \deg(v)) \right) = \sum_{T \in \mathcal{F}_1} w(\overline{T}) \cdot 2$$

where we again apply Lemma 2.6 for the last equality, as  $\deg^o(G) = 0$ .

(b) If all edge weights are positive, then  $w(\overline{T}) > 0$  for all T, and  $\mathcal{F}_1(G; S)$  is nonempty as long as S is nonempty. Thus part (a) implies that  $\mathbf{1}^{\mathsf{T}} \mathbf{m} > 0$ .

Corollary 4.4. If G is a graph with unit edge weights  $\alpha_e = 1$ , then the vector  $\mathbf{m}$  defined in (9) satisfies  $\mathbf{1}^{\mathsf{T}}\mathbf{m} = 2 \kappa(G; S)$ .

**Theorem 4.5.** With  $\mathbf{m} = \mathbf{m}(G; S)$  defined as in (9),  $D[S]\mathbf{m} = \lambda \mathbf{1}$  for the constant

$$\lambda = \sum_{E(G)} \alpha_e \sum_{\mathcal{F}_1(G;S)} w(\overline{T}) - \sum_{\mathcal{F}_2(G;S)} (2 - \deg^o(F,*))^2 w(\overline{F}).$$

*Proof.* For  $e \in E$  and  $v, w \in V$ , let  $\delta(e; v, w)$  denote the function defined in Section 2.3. For any  $v \in S$ , we have

$$(D[S]\mathbf{m})_{v} = \sum_{s \in S} d(v, s)\mathbf{m}_{s}$$

$$= \sum_{s \in S} \left(\sum_{e \in E(G)} \alpha_{e} \,\delta(e; v, s)\right) \left(\sum_{T \in \mathcal{F}_{1}(G; S)} (2 - \deg^{o}(T, s))w(\overline{T})\right)$$

$$= \sum_{T \in \mathcal{F}_{1}} w(\overline{T}) \sum_{e \in E} \alpha_{e} \left(\sum_{s \in S} \delta(e; v, s)(2 - \deg^{o}(T, s))\right)$$

$$= \sum_{T \in \mathcal{F}_{1}} w(\overline{T}) \sum_{e \in E} \alpha_{e} \left(\sum_{s \in S} \delta(e; v, s) \sum_{u \in T(s)} (2 - \deg(u))\right).$$

$$(10)$$

where in the last equality, we apply Lemma 2.6 to the subgraph H = T(s).

We introduce additional notation to handle the double sum in parentheses in (10). Each S-rooted spanning tree T naturally induces a surjection  $\pi_T: V \to S$ , defined by

$$\pi_T(u) = s$$
 if and only if  $u \in T(s)$ .

Using this notation,

(11) 
$$(D[S]\mathbf{m})_v = \sum_{T \in \mathcal{F}_1} w(\overline{T}) \sum_{e \in E} \alpha_e \left( \sum_{u \in V} (2 - \deg(u)) \delta(e; v, \pi_T(u)) \right)$$

We will compare the above expression with the one obtained after replacing  $\delta(e; v, \pi_T(u))$  with  $\delta(e; v, u)$ . From Lemma 2.6 (b), we have  $\sum_{u \in V} (2 - \deg(u)) \delta(e; v, u) = 1$ . Thus

(12) 
$$\sum_{T \in \mathcal{F}_1} w(\overline{T}) \sum_{e \in E} \alpha_e = \sum_{T \in \mathcal{F}_1} w(\overline{T}) \sum_{e \in E} \alpha_e \left( \sum_{u \in V} (2 - \deg(u)) \delta(e; v, u) \right)$$

By subtracting equation (12) from (11),

$$(D[S]\mathbf{m})_v - \sum_{T \in \mathcal{F}_1} w(\overline{T}) \sum_{e \in E} \alpha_e = \sum_{T \in \mathcal{F}_1} w(\overline{T}) \sum_{e \in E} \alpha_e \sum_{u \in V} (2 - \deg(u)) \Big( \delta(e; v, \pi_T(u)) - \delta(e; v, u) \Big).$$

When  $e \in E$  and  $v \in V$  are fixed,  $u \mapsto \delta(e; v, u)$  is the indicator function of one component of the principal cut  $G \setminus e$ . We have

(13) 
$$\delta(e; v, \pi_T(u)) - \delta(e; v, u) = \begin{cases} 0 & \text{if } \delta(e; \pi_T(u), u) = 0\\ 1 & \text{if } \delta(e; \pi_T(u), u) = 1 \text{ and } \delta(e; v, \pi_T(u)) = 1\\ -1 & \text{if } \delta(e; \pi_T(u), u) = 1 \text{ and } \delta(e; v, \pi_T(u)) = 0 \end{cases}$$

Now consider varying u over all vertices, when e, T, and v are fixed. We have the following three cases:

Case 1: if  $e \notin T$ , then u and  $\pi_T(u)$  are on the same side of the principal cut  $G \setminus e$ , for every vertex u. In this case  $\delta(e; v, \pi_T(\cdot)) - \delta(e; v, \cdot) = 0$ .

Case 2: if  $e \in T(s_0)$  and  $s_0$  is separated from v by e, then  $\delta(e; v, \pi_T(\cdot)) - \delta(e; v, \cdot)$  is the indicator function for the floating component of  $T \setminus e$ . See Figure 3, left.

Case 3: if  $e \in T(s_0)$  and  $s_0$  is on the same component as v from e, then  $\delta(e; v, \pi_T(\cdot)) - \delta(e; v, \cdot)$  is the negative of the indicator function for the floating component of  $T \setminus e$ . See Figure 3, right.



FIGURE 3. Edge  $e \in T(s_0)$  with  $\delta(e; v, s_0) = 1$  (left) and  $\delta(e; v, s_0) = 0$  (right). The floating component of  $T \setminus e$  is highlighted.

Thus when multiplying the term (13) by  $(2 - \deg(u))$  and summing over all vertices u, we obtain

$$\sum_{u \in V} (2 - \deg(u)) \Big( \delta(e; v, \pi_T(u)) - \delta(e; v, u) \Big) = \begin{cases} 0 & \text{if } e \not\in T, \\ 2 - \deg^o(T \setminus e, *) & \text{if } e \in T(s_0) \text{ and } \delta(e; v, s_0) = 1, \\ -(2 - \deg^o(T \setminus e, *)) & \text{if } e \in T(s_0) \text{ and } \delta(e; v, s_0) = 0. \end{cases}$$

Thus

$$(D[S]\mathbf{m})_{v} - \sum_{T \in \mathcal{F}_{1}} w(\overline{T}) \sum_{e \in E} \alpha_{e}$$

$$= \sum_{T \in \mathcal{F}_{1}} w(\overline{T}) \sum_{e \in T} \alpha_{e} (2 - \deg^{o}(T \setminus e, *)) \Big( \mathbb{1}(\delta(e; v, \pi_{T}(e)) = 1) - \mathbb{1}(\delta(e; v, \pi_{T}(e)) = 0) \Big).$$

We now rewrite the above expression in terms of  $\mathcal{F}_2(G;S)$ . For the rest of the argument, let

$$(\star) = (D[S]\mathbf{m})_v - \sum_{T \in \mathcal{F}_1} w(\overline{T}) \sum_{e \in E} \alpha_e.$$

Observe in (14) that the deletion  $T \setminus e$  is an (S,\*)-rooted spanning forest of G, and that the corresponding weights satisfy

$$w(\overline{F}) = \alpha_e \cdot w(\overline{T})$$
 if  $F = T \setminus e$ .

Note that  $F = T \setminus e$  is equivalent to  $T = F \cup e$ , and in particular this only occurs when we choose the edge e to be in the floating boundary  $\partial F(*)$ .

Thus

$$\begin{split} (\star) &= \sum_{F \in \mathcal{F}_2} w(\overline{F})(2 - \deg^o(F, *)) \sum_{e \in \partial F} \Big( \mathbbm{1}(\delta(e; v, \pi_{(F \cup e)}(e)) = 1) - \mathbbm{1}(\delta(e; v, \pi_{(F \cup e)}(e)) = 0) \Big) \\ &= \sum_{F \in \mathcal{F}_2} w(\overline{F})(2 - \deg^o(F, *)) \Bigg( \#\{e \in \partial F : \delta(e; v, \pi_T(e)) = 1 \text{ for } T = F \cup e\} \\ &- \#\{e \in \partial F : \delta(e; v, \pi_T(e)) = 0 \text{ for } T = F \cup e\} \Bigg). \end{split}$$

Now for any  $e \notin F$ , let  $\delta(e; v, F(*)) = \delta(e; v, x)$  for any  $x \in F(*)$ , i.e.

$$\delta(e; v, F(*)) = \begin{cases} 1 & \text{if } e \text{ lies on path from } v \text{ to } F(*), \\ 0 & \text{otherwise.} \end{cases}$$

The condition that  $\delta(e; v, \pi_{(F \cup e)}(e)) = 1$  (respectively  $\delta(e; v, \pi_{(F \cup e)}(e)) = 0$ ) is equivalent to  $\delta(e; v, F(*)) = 0$  (respectively  $\delta(e; v, F(*)) = 1$ ). For an illustration, compare Figure 4 and 5. Thus

$$(\star) = \sum_{F \in \mathcal{F}_2} w(\overline{F})(2 - \deg^o(F, *)) \left( \#\{e \in \partial F(*) : \delta(e; v, F(*)) = 0\} - \#\{e \in \partial F(*) : \delta(e; v, F(*)) = 1\} \right).$$

Finally, we observe that for any forest F in  $\mathcal{F}_2(G;S)$ , there is exactly one edge e in the boundary  $\partial F(*)$  of the floating component which satisfies  $\delta(e;v,F(*))=1$ , namely the unique boundary edge on the path from the floating component F(\*) to v. Hence

$$\#\{e \in \partial F(*) : \delta(e; v, F(*)) = 1\} = 1$$
 and  $\#\{e \in \partial(F, *) : \delta(e; v, F(*)) = 0\} = \deg^{o}(F, *) - 1.$ 

Thus the previous expression  $(\star)$  simplifies as

$$\begin{split} (\star) &= \sum_{F \in \mathcal{F}_2} w(\overline{F})(2 - \deg^o(F, *)) \Big( (\deg^o(F, *) - 1) - (1) \Big) \\ &= - \sum_{F \in \mathcal{F}_2} w(\overline{F})(2 - \deg^o(F, *))^2. \end{split}$$

as desired.

FIGURE 4. Edge  $e \in \partial F(*)$  with  $\delta(e; v, F(*)) = 0$  (left) and  $\delta(e; v, F(*)) = 1$  (right). The floating component F(\*) is highlighted.

FIGURE 5. Edges  $e \in \partial F(*)$  with  $\delta(e; v, \pi_{(F \cup e)}(e)) = 1$  (left) and  $\delta(e; v, \pi_{(F \cup e)}(e)) = 0$  (right).

Finally we can prove our main theorem: for any nonempty subset  $S \subset V(G)$ ,

(15) 
$$\det D[S] = (-1)^{|S|-1} 2^{|S|-2} \left( \sum_{E(G)} \alpha_e \sum_{\mathcal{F}_1(G;S)} w(\overline{T}) - \sum_{\mathcal{F}_2(G;S)} (\deg^o(F,*) - 2)^2 w(\overline{F}) \right).$$

Proof of Theorem 1.2. First, suppose |S|=1. Then D[S] is the zero matrix, and we must show that the right-hand side is zero. Since G is a tree,  $\mathcal{F}_1(G;\{v\})$  consists of the tree G itself, with co-weight  $w(\overline{G})=1$ . Moreover, the subgraphs in  $\mathcal{F}_2(G;\{v\})$  are precisely the tree splits  $G\setminus e$ , and for each  $F=G\setminus e$  we have  $w(\overline{F})=\alpha_e$  and  $\deg^o(F,*)-2=-1$ . This shows that the right-hand size of (15) is zero

Next, suppose  $|S| \ge 2$ . Proposition 2.11 states that D[S] is nonsingular, so we may use the inverse matrix identity

(16) 
$$\mathbf{1}^{\mathsf{T}}D[S]^{-1}\mathbf{1} = \frac{\operatorname{cof}D[S]}{\det D[S]}.$$

Let  $\mathbf{m} = \mathbf{m}(G; S)$  denote the vector (9). By Proposition 4.3 (a) and Theorem 2.3,

$$\mathbf{1}^{\mathsf{T}}\mathbf{m} = 2\sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}) = \frac{\cot D[S]}{(-1)^{1-|S|}2^{2-|S|}}.$$

Theorem 4.5 states that  $D[S]\mathbf{m} = \lambda \mathbf{1}$  for some constant  $\lambda$ , which is nonzero since D[S] is invertible and  $\mathbf{m}$  is nonzero, c.f. Proposition 4.3 (b). Hence

(17) 
$$\mathbf{1}^{\mathsf{T}}D[S]^{-1}\mathbf{1} = \lambda^{-1}\mathbf{1}^{\mathsf{T}}\mathbf{m} = \frac{\cot D[S]}{(-1)^{|S|-1}2^{|S|-1}\lambda}.$$

Comparing (16) with (17) gives the desired result,  $\det D[S] = (-1)^{|S|-1} 2^{|S|-1} \lambda$ .

Proof of Theorem 1.1. Set all weights  $\alpha_e$  to 1 in Theorem 1.2. In this case, the weights  $w(\overline{T}) = 1$  and  $w(\overline{F}) = 2$  for all forests T and F, and

$$\sum_{e \in E} \alpha_e = n - 1, \qquad \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}) = \kappa_1(G;S). \qquad \Box$$

Remark 4.6. It is worth observing that depending on the chosen subset  $S \subset V$ , the distances appearing in the submatrix D[S] may ignore a large part of the ambient tree G. We could instead replace G by the subtree  $\operatorname{conv}(S,G)$  consisting of the union of all paths between vertices in S, which we call the *convex hull* of  $S \subset G$ . To apply formula (2) or (4) "efficiently," we should replace G on the right-hand side with the subtree  $\operatorname{conv}(S,G)$ . However, the formulas as stated are true even without this replacement due to cancellation of terms.

### 5. Physical interpretation

If we consider G as a network of wires with edge e containing a resistor of resistance  $\alpha_e$ , which is grounded at all nodes in S, then the optimal vector  $\mathbf{m}(G;S)$  defined in (9) has an interpretation as current flow: it records the currents exiting at  $s \in S$  when current enters the vertices in the amount  $\deg(v) - 2$  for each  $v \notin S$ .

5.1. Alternate proof. In the outline above, our first goal is to find a "special" vector  $\mathbf{m} \in \mathbb{R}^S$  satisfying  $D[S]\mathbf{m} = \lambda \mathbf{1}$ . We can approach this first goal as follows: consider  $\mathbb{R}^S$  inside the larger vector space  $\mathbb{R}^V = \mathbb{R}^S \oplus \mathbb{R}^{V \setminus S}$ , and let  $\pi_S$  denote the projection from  $\mathbb{R}^V$  to  $\mathbb{R}^S$ . We wish to find vectors  $\mathbf{n}(i) \in \mathbb{R}^V$  satisfying  $\pi_S(D\mathbf{n}(i)) = \lambda_i \mathbf{1}$ . OR,  $D\mathbf{n}_i = \lambda_i \mathbf{1}^S \oplus (-)$ . By finding sufficiently many such vectors  $\mathbf{n}_i$ , we can hope to find a linear combination that lies inside  $\mathbb{R}^S \oplus \{0\}$ .

**Proposition 5.1.** Let  $\mathbf{m} \in \mathbb{R}^V$  be the vector defined by  $\mathbf{m}_v = 2 - \deg v$ , and let D be the distance matrix of G. Then the entries of  $D\mathbf{m}$  are constant on V(G).

*Proof.* It suffices to show that for each edge e, with endpoints  $(e^+, e^-)$ , we have  $(D\mathbf{m})_{(e^+)} = (D\mathbf{m})_{(e^-)}$ . To compute  $(D\mathbf{m})_{(e^+)} - (D\mathbf{m})_{(e^-)}$ , first observe that the distance function on G satisfies

$$d(v, e^+) - d(v, e^-) = \begin{cases} \alpha_e & \text{if } v \text{ is closer to } e^- \text{ than } e^+, \\ -\alpha_e & \text{if } v \text{ is closer to } e^+ \text{ than } e^-. \end{cases}$$

Thus

$$(D\mathbf{m})_{(e^{+})} - (D\mathbf{m})_{(e^{-})} = \sum_{v \in V} (d(v, e^{+}) - d(v, e^{-}))(2 - \deg v)$$

$$= \sum_{v \in (G \setminus e)^{-}} \alpha_{e}(2 - \deg v) - \sum_{v \in (G \setminus e)^{+}} \alpha_{e}(2 - \deg v)$$

$$= \alpha_{e} \left( \sum_{v \in (G \setminus e)^{-}} (2 - \deg v) - \sum_{v \in (G \setminus e)^{+}} (2 - \deg v) \right)$$
(18)

For each sum in (18), we apply Lemma 2.6 to obtain

$$\sum_{v \in (G \setminus e)^{-}} (2 - \deg v) = (2 - \deg^{o}((G \setminus e)^{-}) = 1,$$

since each component of  $(G \setminus e)$  has outdegree one. The same identity applies to the sum over  $(G \setminus e)^+$ , so  $(D\mathbf{m})_{(e^+)} = (D\mathbf{m})_{(e^-)}$  as desired.

**Proposition 5.2.** Fix  $v \in V \setminus S$ . Consider the vector  $\mathbf{n} = \mathbf{n}(G; S, v) \in \mathbb{R}^V$  defined by

$$\mathbf{n} = \sum_{T \in \mathcal{F}_1(G;S)} \left( \boldsymbol{\delta}(v) - \boldsymbol{\delta}(\pi_T(v)) \right).$$

Then  $D\mathbf{n}$  is constant on S, i.e.  $\pi_S(D\mathbf{n}) = \lambda \mathbf{1}$  for some  $\lambda$ .

**Remark 5.3.** For each  $s \in S$ , let  $\mu(v, s)$  denote the current flowing to s when G is grounded at S and one unit of current enters G at v. Then

$$\mu(v,s) = \frac{1}{\kappa(G;S)} \mathbf{n}(v)_s.$$

Explicitly, if  $s = s_i$ , then

$$\mu(v, s_j) = \frac{\sum_{\mathcal{F}_1(G; S)} \mathbb{1}(\pi_T(v) = s_j)}{\kappa(G; S)} = \frac{\kappa_r(s_1 | \dots | s_j v | \dots | s_r)}{\kappa(G; S))}$$

where  $\kappa_r(s_1|\cdots|s_jv|\cdots|s_r)$  is the number of S-rooted spanning forests of G whose  $s_j$ -component contains v.

*Proof sketch.* For any  $s, s' \in S$ , consider tracking the value of  $D\mathbf{n}$  along path from s to s'. The value of  $D\mathbf{n}$  changes according to current flow in the corresponding network, i.e.  $D\mathbf{n}$  records electrical potential. The set S is grounded by assumption, so  $D\mathbf{n}$  takes the same value at s and s'.

**Theorem 5.4.** Let G be a tree, S a nonempty subset of vertices, and D[S] the submatrix of the distance matrix of G. Suppose  $\mathbf{m} = \mathbf{m}(G; S) \in \mathbb{R}^S$  is defined by (9);

$$\mathbf{m}(G;S)_s = \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}) \sum_{u \in T(s)} (2 - \deg u) = \sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T}) (2 - \deg^o(T,s)).$$

Then  $D[S]\mathbf{m} = \lambda \mathbf{1}$  for some constant  $\lambda$ .

*Proof.* The vector  $\mathbf{m} = \mathbf{m}(G; S)$  can be expressed as a linear combination of  $\delta$ -vectors

$$\mathbf{m}(G; S) = \sum_{T \in \mathcal{F}_1(G; S)} w(\overline{T}) \sum_{u \in V} (2 - \deg(u)) \boldsymbol{\delta}(\pi_T(u)).$$

Therefore

$$\mathbf{m}(G; S) = \sum_{T \in \mathcal{F}_1} \sum_{v \in V} (2 - \deg v) \boldsymbol{\delta}(v) - \sum_{T \in \mathcal{F}_1} \sum_{v \in V} (2 - \deg v) (\boldsymbol{\delta}(v) - \boldsymbol{\delta}(\pi_T(v)))$$

$$= \kappa(G; S) \sum_{v \in V} (2 - \deg v) \boldsymbol{\delta}(v) - \sum_{v \in V \setminus S} (2 - \deg v) \mathbf{n}(G; S, v)$$

$$= \kappa(G; S) \mathbf{m}(G; V) - \sum_{v \in V \setminus S} (2 - \deg v) \mathbf{n}(G; S, v).$$

♦ TODO: elaborate on this equation? ♦ From Proposition 5.1 we know that  $D\mathbf{m}(G; V)$  is constant on V, and from Proposition 5.2 we know that for each  $v \in V \setminus S$  the product  $D\mathbf{n}(G; S, v)$  is constant on S. Hence by linearity,  $D\mathbf{m}(G; S)$  is constant on S.

## Example 5.5. If

$$D[S \cup t] = \begin{bmatrix} 0 & a & b & c \\ a & 0 & a+b & a+c \\ b & a+b & 0 & b+c \\ c & a+c & b+c & 0 \end{bmatrix}$$

then

$$\begin{bmatrix} 0 & a & b & c \\ a & 0 & a+b & a+c \\ b & a+b & 0 & b+c \\ c & a+c & b+c & 0 \end{bmatrix} \begin{bmatrix} ab+ac+bc \\ -bc \\ -ac \\ -ab \end{bmatrix} = \begin{bmatrix} -3abc \\ -abc \\ -abc \\ -abc \end{bmatrix}$$

5.2. Symanzik polynomials. We note that the expression in the main theorem, Theorem 1.2, is related to Symanzik polynomials, which we recall here.

Given a graph G = (V, E), the first Symanzik polynomial is the homogeneous polynomial in edge-indexed variables  $\underline{x} = \{x_e : e \in E\}$  defined by

$$\psi_G(\underline{x}) = \sum_{T \in \mathcal{F}_1(G)} \prod_{e \notin T} x_e,$$

where  $\mathcal{F}_1(G)$  denotes the set of spanning trees of G.

Consider a "momentum" function  $p:V\to\mathbb{R}$  which satisfies  $\sum_{v\in V}p(v)=0$ . Then the second Symanzik polynomial is

$$\varphi_G(p; \underline{x}) = \sum_{F \in \mathcal{F}_2(G)} \left( \sum_{v \in F_1} p(v) \right)^2 \prod_{e \notin F} x_e,$$

where  $\mathcal{F}_2(G)$  is the set of two-component spanning forests of G, and  $F_1$  denotes one of the components of F. It doesn't matter which component we label as  $F_1$ , due to the momentum constraint  $\sum_{v \in V} p(v) = 0.$  Theorem statement:

$$\det D[S] = (-1)^{|S|-1} 2^{|S|-2} \left( \sum_{E(G)} \alpha_e \sum_{\mathcal{F}_1(G;S)} w(\overline{T}) - \sum_{\mathcal{F}_2(G;S)} (\deg^o(F,*) - 2)^2 w(\overline{F}) \right).$$

$$\frac{\det D[S]}{\cot D[S]} = \frac{1}{2} \left( \sum_{e \in E} \alpha_e - \frac{\sum_{F \in \mathcal{F}_2(G;S)} w(\overline{F}) (\deg^o(F,*) - 2)^2}{\sum_{T \in \mathcal{F}_1(G;S)} w(\overline{T})} \right)$$

In terms of Symanzik polynomials, let  $\psi$  and  $\varphi$  denote the first and second Symanzik polynomials of the quotient graph G/S. We have

$$\det D[S] = (-1)^{|S|-1} 2^{|S|-2} \left( \sum_{E(G)} \alpha_e \, \psi_{(G/S)}(\underline{\alpha}) - \phi_{(G/S)}(p;\underline{\alpha}) \right).$$

and

$$\frac{\det D[S]}{\cot D[S]} = \frac{1}{2} \left( \sum_{e \in E} \alpha_e - \frac{\varphi_{(G/S)}(p; \underline{\alpha})}{\psi_{(G/S)}(\underline{\alpha})} \right)$$

with momentum function  $p(v) = \deg(v) - 2$  for  $v \notin S$ .

### 6. Examples

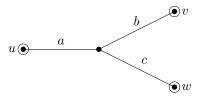
**Example 6.1.** Suppose G is a tree consisting of three paths joined at a central vertex. Let S consist of the central vertex, and the three endpoints of the paths. The corresponding minor of the distance matrix is

$$D[S] = \begin{bmatrix} 0 & a & b & c \\ a & 0 & a+b & a+c \\ b & a+b & 0 & b+c \\ c & a+c & b+c & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & a & b & c \\ a & -a & a & a \\ b & b & -b & b \\ c & c & c & c & -c \end{bmatrix} \sim \begin{bmatrix} 0 & a & b & c \\ a & -2a & 0 & 0 \\ b & 0 & -2b & 0 \\ c & 0 & 0 & -2c \end{bmatrix}.$$

The determinant is

$$\det D[S] = -4(a+b+c)abc.$$

**Example 6.2.** Suppose  $\Gamma$  is a tripod with lengths a, b, c and corresponding leaf vertices u, v, w.



Let  $S = \{u, v, w\}$ . Then

$$D[S] = \begin{bmatrix} 0 & a+b & a+c \\ a+b & 0 & b+c \\ a+c & b+c & 0 \end{bmatrix}.$$

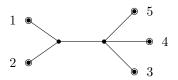
and

$$\det D[S] = 2(a+b)(a+c)(b+c) = 2((a+b+c)(ab+ac+bc) - abc).$$

The "special vector" that satisfies  $D[S]\mathbf{m} = \lambda \mathbf{1}$  in this example is

$$\mathbf{m} = \begin{bmatrix} a(b+c) & b(a+c) & c(a+b) \end{bmatrix}^{\mathsf{T}}.$$

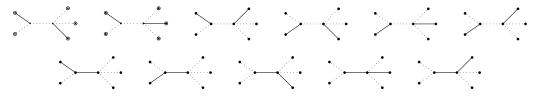
**Example 6.3.** Suppose G is the tree with unit edge lengths shown below, with five leaf vertices.



Let S denote the set of five leaf vertices. Then

$$D[S] = \begin{bmatrix} 0 & 2 & 3 & 3 & 3 \\ 2 & 0 & 3 & 3 & 3 \\ 3 & 3 & 0 & 2 & 2 \\ 3 & 3 & 2 & 0 & 2 \\ 3 & 3 & 2 & 2 & 0 \end{bmatrix}.$$

There are 11 forests in  $\mathcal{F}_1(G; S)$ :

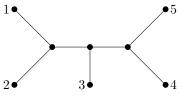


There are 6 forests in  $\mathcal{F}_2(G;S)$ :

and

$$\det D[S] = 368 = (-1)^4 2^3 \left( 6 \cdot 11 - \left( 3 \cdot 1^2 + 2 \cdot 2^2 + 1 \cdot 3^2 \right) \right)$$

**Example 6.4.** Suppose G is the tree with unit edge lengths shown below, with five leaf vertices and three internal vertices.



Let S denote the set of five leaf vertices. Then

$$D[S] = \begin{bmatrix} 0 & 2 & 3 & 4 & 4 \\ 2 & 0 & 3 & 4 & 4 \\ 3 & 3 & 0 & 3 & 3 \\ 4 & 4 & 3 & 0 & 2 \\ 4 & 4 & 3 & 2 & 0 \end{bmatrix}$$

and

$$\det D[S] = 864 = (-1)^4 2^3 \left(7 \cdot 21 - \left(14 \cdot 1^2 + 4 \cdot 2^2 + 1 \cdot 3^2\right)\right)$$

## 7. Further work

It is natural to ask whether these results for trees may be generalized to arbitrary finite graphs. We address this in [10], which involve more technical machinery. See [9].

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