

# Constructing Guaranteed Automatic Numerical Algorithms for Univariate Integration

Yizhi Zhang

Department of Applied Mathematics, Illinois Institute of Technology

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## Expanding from $[0, 1]$ to $[a, b]$

- It is not as straight forward as one may think of. Previously we use the input `ninit` as the initial number of points.
- The algorithm could fail.
- The algorithm may not be efficient.

# Our Solution

initial number of point = ninit

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$$\text{initial number of point} = \text{ninit} = n_{\text{ninit},\text{max}} \left( \frac{n_{\text{ninit},\text{min}}}{n_{\text{ninit},\text{max}}} \right)^{\frac{1}{1+b-a}}$$

# Assumptions

The node set and the linear spline algorithm using  $n$  function values are defined for  $n \in \mathcal{I} := \{2, 3, \dots\}$  as follows:

$$x_i = a + \frac{i-1}{n-1}(b-a), \quad i = 1, \dots, n,$$

$$A_n(f)(x) := \frac{n-1}{b-a} [f(x_i)(x_{i+1} - x) + f(x_{i+1})(x - x_i)]$$

for  $x_i \leq x \leq x_{i+1}$ .

# Assumptions, continued

The problem to be solved is univariate integration on the unit interval,  $S(f) := \text{INT}(f) := \int_a^b f(x) \, dx \in \mathcal{G} := \mathbb{R}$ . The fixed cost building blocks to construct the adaptive integration algorithm are the composite trapezoidal rules based on  $n - 1$  trapezoids:

$$T_n(f) := \int_a^b A_n(f) \, dx = \frac{b-a}{2n-2} [f(x_1) + 2f(x_2) + \cdots + 2f(x_{n-1}) + f(x_n)].$$

# Assumptions, continued

The space of input functions is  $\mathcal{V}$ , the space of functions whose first derivatives have finite variation:

$$\mathcal{V}^1[a, b] = \{f \in C^1[a, b] : \text{Var}(f') < \infty\},$$

The space of outputs is the real space  $\mathbb{R}$ . The stronger semi-norm is  $|f|_{\mathcal{F}} = \text{Var}(f')$ , while the weaker semi-norm is

$$|f|_{\tilde{\mathcal{F}}} := \|f' - A_2(f)'\|_1 = \left\| f' - \frac{f(b) - f(a)}{b - a} \right\|_1 = \text{Var}(f - A_2(f)),$$

The cone of the integrand is defined as

$$\mathcal{C}_{\tau_{a,b}} := \left\{ f \in \mathcal{V}^1 : \text{Var}(f') \leq \tau_{a,b} \left\| f' - \frac{f(b) - f(a)}{b - a} \right\|_1 \right\}.$$

For simplicity, I will denote  $\tau_{a,b}$  as  $\tau$  for the rest of the context.



# Multi-step Automatic Algorithms

## Algorithm (Adaptive Univariate Integration)

Let the sequence of algorithms  $\{T_n\}_{n \in \mathcal{I}}$ ,  $\{\tilde{F}_n\}_{n \in \mathcal{I}}$ , and  $\{F_n\}_{n \in \mathcal{I}}$  be as described above. Choose integer  $n_{\text{lo}}, n_{\text{hi}}$ , such that  $n_{\text{lo}} \leq n_{\text{hi}}$ . Set  $i = 1$ . Let  $n_1 = \max \left\{ \lceil n_{\text{hi}} \left( \frac{n_{\text{lo}}}{n_{\text{hi}}} \right)^{\frac{1}{1+b-a}} \rceil, 3 \right\}$ . Let  $\tau_{a,b} = 2n_1 - 3$ . For any error tolerance  $\varepsilon$  and input function  $f$ , do the following:

Stage 1. Estimate  $\left\| f' - \frac{f(b)-f(a)}{b-a} \right\|_1$  and bound  $\text{Var}(f')$ . Compute  $\tilde{F}_{n_i}(f)$  and  $F_{n_i}(f)$

# Multi-step Automatic Algorithms, continuoued

## Algorithm

Stage 2. Check the necessary condition for  $f \in \mathcal{C}_{\tau_{a,b}}$ . Compute

$$\tau_{\min, n_i} = \frac{F_{n_i}(f)}{\widetilde{F}_{n_i}(f) + (b-a)F_{n_i}(f)/(2n_i-2)}.$$

If  $\tau_{a,b} \geq \tau_{\min, n_i}$ , then go to stage 3. Otherwise, set  $\tau_{a,b} = 2\tau_{\min, n_i}$ . If  $n_i \geq (\tau+1)/2$ , then go to stage 3. Otherwise, choose

$$n_{i+1} = 1 + (n_i - 1) \left\lceil \frac{\tau_{a,b} + 1}{2n_i - 2} \right\rceil.$$

Go to Stage 1.

# Multi-step Automatic Algorithms, continued

## Algorithm

Stage 3. Check for convergence. Check whether  $n_i$  is large enough to satisfy the error tolerance, i.e.

$$\tilde{F}_{n_i}(f) \leq \frac{4\varepsilon(n_i - 1)(2n_i - 2 - \tau_{a,b}(b - a))}{\tau_{a,b}(b - a)^2}.$$

If this is true, then return  $T_{n_i}(f)$  and terminate the algorithm. If this is not true, choose

$$n_{i+1} = 1 + (n_i - 1) \max \left\{ 2, \left\lceil \frac{1}{(n_i - 1)} \sqrt{\frac{\tau_{a,b}(b - a) \tilde{F}_{n_i}(f)}{8\varepsilon}} \right\rceil \right\}.$$

Go to Stage 1.

# Demo

Demo

# Future Work

- Verify my theoretic proof of this case.
- Double check the MATLAB code.
- Polishing and debugging.

# References 1

Clancy N, Ding Y, Hamilton C, Hickernell FJ, Zhang Y (2013) The complexity of guaranteed automatic algorithms: Cones, not balls. DOI 10.1016/j.jco.2013.09.002., arXiv.org:1303.2412 [math.NA]