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Photo-Realistic Single Image Super-Resolution Using a Generative Adversarial Network

Introduction~

This research explains that **super-resolution (SR)** aims to recover high-resolution (HR) images from low-resolution (LR) ones, which is a very **challenging and ill-posed problem**, especially at large upscaling levels (e.g., 4×). Traditional methods often use **mean squared error (MSE)** as the loss function because it boosts **PSNR**, a popular metric. However, MSE and PSNR fail to preserve **fine texture details** and do not reflect how humans perceive image quality. To overcome this, the authors propose **SRGAN**, a **Generative Adversarial Network** that uses a **deep ResNet with skip connections** and a **perceptual loss**.

This section explains why traditional **pixel-wise loss functions like MSE** are not ideal for super-resolution. MSE tends to **average out all possible high-detail variations**, resulting in **blurry and smooth images** that lack realistic textures. That's because it treats every pixel equally and doesn't account for **how humans perceive image quality**. To fix this, researchers started using **GANs (Generative Adversarial Networks)**, which can generate images that lie closer to the **natural image distribution**, making them look more realistic. Instead of just comparing raw pixels, newer methods use **feature-based losses** especially from deep networks like **VGG19** which focus on **high-level image features**. This allows the model to better preserve **textures and structures**.

Method~

To recover a **high-resolution (HR) image** $I\{SR\}$ from a given **low-resolution** $I\{LR\}$

$I\{LR\}$ has shape:

$W \times H \times C$

where:

- W, H width and Height of the LR image
- C : Number of color channels (e.g., 3 for RGB)

$I\{HR\}$ and $I\{SR\}$ have shape:

$rW \times rH \times C$

because they are upsampled by a factor r .

Optimization Formula:

$$\hat{\theta}_G = \arg \min_{\theta_G} \frac{1}{N} \sum_{n=1}^N \ell_{SR}(G_{\theta_G}(I_{LR}^{(n)}), I_{HR}^{(n)})$$

- The model is trained by minimizing the average loss between the predicted super-resolved image $G(I\{LR\})$ and the true high-resolution image $I\{HR\}$, across all N training samples.
- $\arg\min$ means we are looking for the best set of parameters $\theta\{G\}$ that minimizes this average loss.

Goal of Generator G: Generate super-resolved images from low-resolution inputs that **fool the discriminator**.

Goal of Discriminator D: Accurately classify real high-resolution images $I\{HR\}$ as real, and generated ones $G(I\{LR\})$ as fake.

$$\min_{\theta_G} \max_{\theta_D} \mathbb{E}_{I^{HR} \sim p_{\text{train}}(I^{HR})} [\log D_{\theta_D}(I^{HR})] + \mathbb{E}_{I^{LR} \sim p_G(I^{LR})} [\log(1 - D_{\theta_D}(G_{\theta_G}(I^{LR})))]$$

Generator Architecture (SRGAN Generator)

Uses a **deep CNN** with **B residual blocks**, each made of:

- Two 3×3 convolutional layers
- 64 feature maps
- **Batch normalization**
- **Parametric ReLU (PReLU)** activations

Upsampling is done via **two sub-pixel convolution layers** [48], which efficiently increase image size without interpolation

Discriminator Architecture:

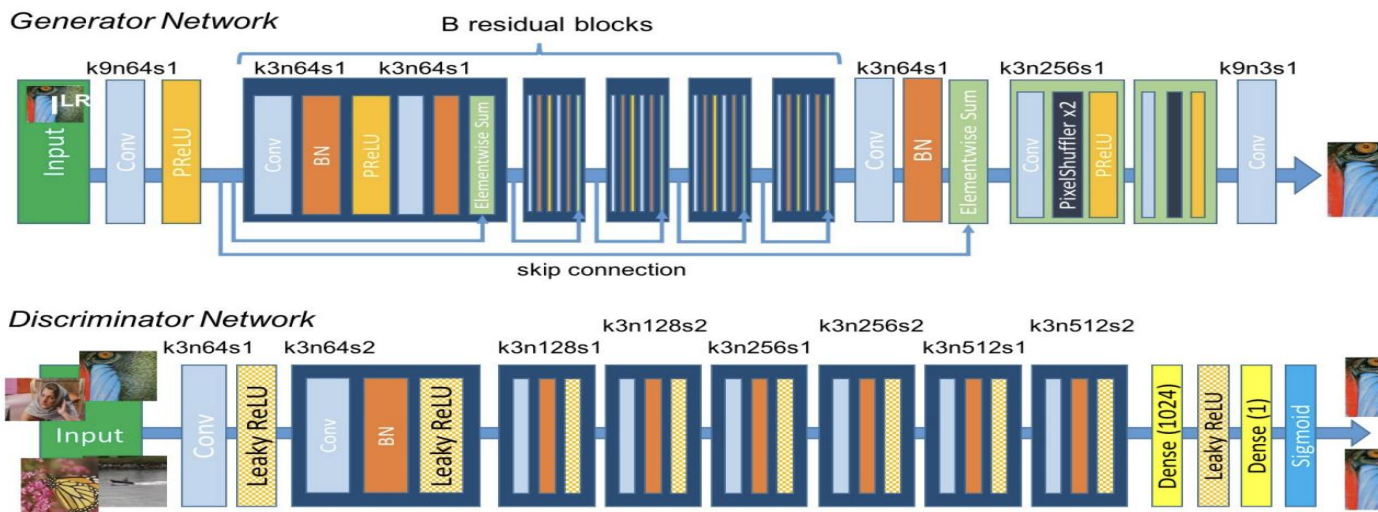
Discriminator is designed following **DCGAN-style guidelines** [44]:

- Uses **Leaky ReLU** activation ($\alpha = 0.2$)
- Avoids **max pooling**

- Has **8 convolutional layers** with 3×3 \times 3×3 filters
- Number of filters increases from 64 to 512 (doubles every few layers)
- Uses **strided convolutions** to downsample instead of pooling

Final part:

- Outputs 512 features
- Passes through **2 dense (fully connected) layers**
- Ends with a **sigmoid activation**, giving a probability (real vs fake)



Perceptual Loss

Instead of using just MSE (which looks at raw pixel differences), the authors create a **better loss function** made of two parts:

$$\ell_{SR} = \underbrace{\ell_{SR}^X}_{\text{Content Loss}} + 10^{-3} \cdot \underbrace{\ell_{SR}^{Gen}}_{\text{Adversarial Loss}}$$

Content Loss ℓ_{SR}^X

1. Measures how **similar the generated image is to the real image** in terms of meaningful features (like texture or structure).
2. Often computed using features from a **VGG network** (a deep CNN trained for image classification).

3. This is more aligned with **how humans judge image quality**, unlike MSE which looks only at per-pixel differences.
- 4.

$$l_{MSE}^{SR} = \frac{1}{r^2 W H} \sum_{x=1}^{rW} \sum_{y=1}^{rH} (I_{x,y}^{HR} - G_{\theta_G}(I^{LR})_{x,y})^2$$

$$l_{VGG/i,j}^{SR} = \frac{1}{W_{i,j} H_{i,j}} \sum_{x=1}^{W_{i,j}} \sum_{y=1}^{H_{i,j}} (\phi_{i,j}(I^{HR})_{x,y} - \phi_{i,j}(G_{\theta_G}(I^{LR}))_{x,y})^2 \quad (5)$$

Here $W_{i,j}$ and $H_{i,j}$ describe the dimensions of the respective feature maps within the VGG network.

Adversarial Loss ℓ_{SRGen}

- Comes from the **discriminator** in the GAN setup .
- Encourages the generator to make images that look **realistic and natural**, so they can **fool the discriminator**.
- It's multiplied by a small factor (**0.001**) to keep it from overpowering the content loss

is defined based on the probabilities of the discriminator $D_{\theta_D}(G_{\theta_G}(I^{LR}))$ over all training samples as:

$$l_{Gen}^{SR} = \sum_{n=1}^N -\log D_{\theta_D}(G_{\theta_G}(I^{LR})) \quad (6)$$

Here, $D_{\theta_D}(G_{\theta_G}(I^{LR}))$ is the probability that the reconstructed image $G_{\theta_G}(I^{LR})$ is a natural HR image. For better gradient behavior we minimize $-\log D_{\theta_D}(G_{\theta_G}(I^{LR}))$ instead of $\log[1 - D_{\theta_D}(G_{\theta_G}(I^{LR}))]$ [22].

Model testing and results

Metrics:

- **PSNR (Peak Signal-to-Noise Ratio):** Measures pixel-wise accuracy. **Higher is better**, but not always aligned with visual quality.
- **SSIM (Structural Similarity Index):** Measures perceptual similarity (structure, contrast). **Higher is better.**
- **MOS (Mean Opinion Score):** Human-rated visual quality. Scores range from 1 (bad) to 5 (excellent). **Higher is better** and reflects **true perceptual quality**.

- **SRResNet** is **technically most accurate** (best PSNR/SSIM) but visually looks smooth/blurry (lower MOS).
- **SRGAN** generates images that **look far better to humans**, scoring **much higher in MOS**, despite lower PSNR.
- So, **SRGAN > SRResNet** for *realistic and perceptual quality*, even though it sacrifices some numerical precision.

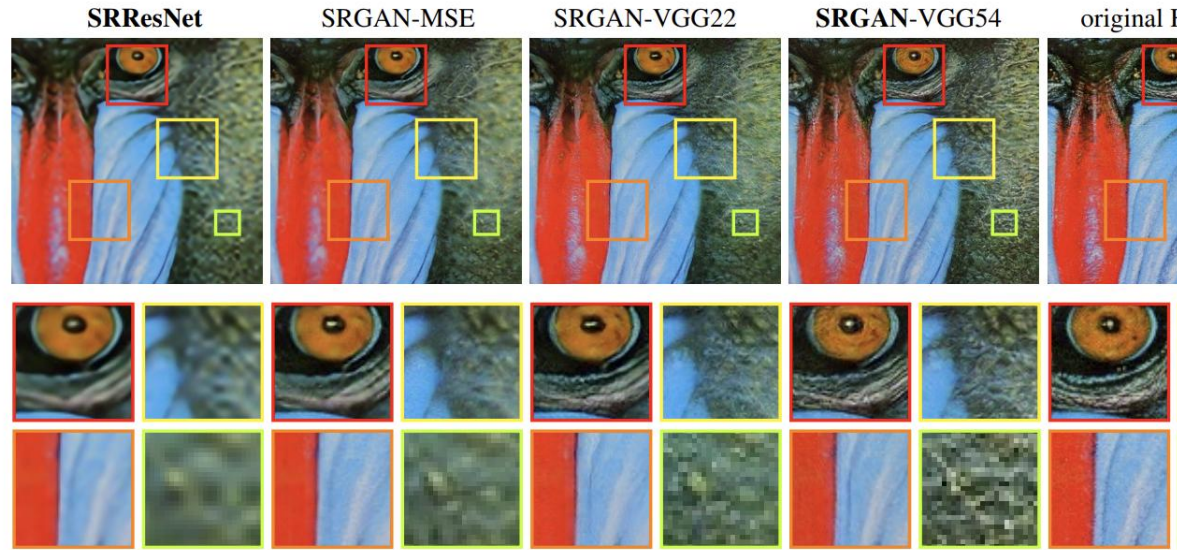


Figure 6: **SRResNet** (left: a,b), **SRGAN-MSE** (middle left: c,d), **SRGAN-VGG2.2** (middle: e,f) and **SRGAN-VGG54** (middle right: g,h) reconstruction results and corresponding reference HR image (right: i,j). [4× upscaling]

Table 2: Comparison of NN, bicubic, SRCNN [9], SelfExSR [31], DRCN [34], ESPCN [48], **SRResNet**, **SRGAN** and the original HR on benchmark data. Highest measures (PSNR [dB], SSIM, MOS) in bold. [4× upscaling]

Set5	nearest	bicubic	SRCNN	SelfExSR	DRCN	ESPCN	SRResNet	SRGAN	HR
PSNR	26.26	28.43	30.07	30.33	31.52	30.76	32.05	29.40	∞
SSIM	0.7552	0.8211	0.8627	0.872	0.8938	0.8784	0.9019	0.8472	1
MOS	1.28	1.97	2.57	2.65	3.26	2.89	3.37	3.58	4.3
Set14									
PSNR	24.64	25.99	27.18	27.45	28.02	27.66	28.49	26.02	∞
SSIM	0.7100	0.7486	0.7861	0.7972	0.8074	0.8004	0.8184	0.7397	1
MOS	1.20	1.80	2.26	2.34	2.84	2.52	2.98	3.72	4.3
BSD100									
PSNR	25.02	25.94	26.68	26.83	27.21	27.02	27.58	25.16	∞
SSIM	0.6606	0.6935	0.7291	0.7387	0.7493	0.7442	0.7620	0.6688	1
MOS	1.11	1.47	1.87	1.89	2.12	2.01	2.29	3.56	4.4

- Shows zoomed-in image patches from different models.
- **SRResNet** looks smooth and lacks texture.
- **SRGAN-VGG54** (final version of SRGAN) produces **sharp and detailed textures**, much closer to the **original HR image**.
- **SRGAN-MSE** is closer to SRResNet and looks blurrier than VGG-based SRGANs.
- **SRGAN-VGG22** is intermediate—better than MSE, but not as good as VGG54.

The best visual result is clearly from **SRGAN-VGG54**, capturing sharp edges and textures that mimic the HR image, while SRResNet and MSE-based outputs are visually smoother and less realistic.

