

Assignment 18

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Abstract—This document explains the representation of transformations by matrix.

Download all python codes from

<https://github.com/harshachinta/EE5609-Matrix-Theory/tree/master/Assignments/Assignment18/code>

and latex-tikz codes from

<https://github.com/harshachinta/EE5609-Matrix-Theory/tree/master/Assignments/Assignment18>

1 PROBLEM

Let \mathbf{F} be a subfield of the field of complex numbers and let \mathbf{V} be any vector space over \mathbf{F} . Suppose that f and g are linear functionals on \mathbf{V} such that the function h defined by $h(\alpha) = f(\alpha)g(\alpha)$ is also a linear functional on \mathbf{V} . Prove that either $f = 0$ or $g = 0$.

2 EXPLANATION

Refer Table 0.

Given	Derivation
f, g, h are linear functionals of \mathbf{V}	<p>By contradiction, let us assume $f \neq 0$ and $g \neq 0$. For all $\mathbf{v} \in \mathbf{V}$</p> $h(\mathbf{v}) = f(\mathbf{v})g(\mathbf{v}) \quad (2.0.1)$ $h(2\mathbf{v}) = f(2\mathbf{v})g(2\mathbf{v}) \quad (2.0.2)$ $= 2f(\mathbf{v})2g(\mathbf{v}) \quad (2.0.3)$ $= 4f(\mathbf{v})g(\mathbf{v}) \quad (2.0.4)$ <p>Similarly,</p> $h(2\mathbf{v}) = 2h(\mathbf{v}) \quad (2.0.5)$ $= 2f(\mathbf{v})g(\mathbf{v}) \quad (2.0.6)$ <p>From equation (2.0.4) and (2.0.6),</p> $\implies 4f(\mathbf{v})g(\mathbf{v}) = 2f(\mathbf{v})g(\mathbf{v}) \quad (2.0.7)$ $\implies f(\mathbf{v}).g(\mathbf{v}) = 0 \quad (2.0.8)$
Choosing Basis	<p>Let \mathbf{B} be a basis for \mathbf{V}. Let,</p> $\mathbf{B}_1 = \{\mathbf{b} \in \mathbf{B} \mid f(\mathbf{b}) = 0\}, \quad (2.0.9)$ $\mathbf{B}_2 = \{\mathbf{b} \in \mathbf{B} \mid g(\mathbf{b}) = 0\} \quad (2.0.10)$ <p>Since,</p> $f(\mathbf{b}).g(\mathbf{b}) = 0 \quad \forall \mathbf{b} \in \mathbf{B} \quad (2.0.11)$ $\implies f(\mathbf{b}) = 0 \text{ or } g(\mathbf{b}) = 0 \quad (2.0.12)$ $\implies \mathbf{b} \in \mathbf{B}_1 \text{ or } \mathbf{b} \in \mathbf{B}_2 \quad (2.0.13)$
Choosing \mathbf{b}_1 and \mathbf{b}_2 from basis	<p>Let us choose $\mathbf{b}_1 \in \mathbf{B}_1 - \mathbf{B}_2$ and $\mathbf{b}_2 \in \mathbf{B}_2 - \mathbf{B}_1$ $\implies f(\mathbf{b}_2) \neq 0$ and $g(\mathbf{b}_1) \neq 0$</p> $f(\mathbf{b}_1 + \mathbf{b}_2).g(\mathbf{b}_1 + \mathbf{b}_2) = (f(\mathbf{b}_1) + f(\mathbf{b}_2)).(g(\mathbf{b}_1) + g(\mathbf{b}_2)) \quad (2.0.14)$ $= f(\mathbf{b}_1).g(\mathbf{b}_1) + f(\mathbf{b}_1).g(\mathbf{b}_2) + f(\mathbf{b}_2).g(\mathbf{b}_1) + f(\mathbf{b}_2).g(\mathbf{b}_2) \quad (2.0.15)$ $= 0 + 0 + f(\mathbf{b}_2).g(\mathbf{b}_1) + 0 \quad (2.0.16)$ $= f(\mathbf{b}_2).g(\mathbf{b}_1) \neq 0 \quad (2.0.17)$ <p>Equation (2.0.17) is contradiction to the fact that $f(\mathbf{v}).g(\mathbf{v}) = 0$. $\implies \boxed{f = 0 \text{ or } g = 0}$</p>

TABLE 0: Expanation