Recorded at time: 1757426769.591 base\_link external camera link Broadcaster: /external camera/realsense2 camera manager Broadcaster: /external camera/realsense2 camera manager Broadcaster: /my\_gen3/robot\_state\_publisher Average rate: 10000.000 Hz Average rate:  $10000.000 \, \text{Hz}$ Average rate: 40.201 Hz Most recent transform: 1757426769.583 (0.008 sec old) Most recent transform: 0.000 (1757426769.591 sec old) Most recent transform: 0.000 (1757426769.591 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.975 sec shoulder\_link external\_camera\_depth\_frame external\_camera\_color\_frame Broadcaster: /my gen3/robot state publisher Broadcaster: /external camera/realsense2 camera manager Broadcaster: /external camera/realsense2 camera manager Average rate:  $10000.000 \, \overline{\text{Hz}}$ Average rate: 10000.000 Hz Average rate: 40.201 Hz Most recent transform: 0.000 (1757426769.591 sec old) Most recent transform: 1757426769.583 (0.008 sec old) Most recent transform: 0.000 (1757426769.591 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.975 sec half\_arm\_1\_link external\_camera\_depth\_optical\_frame external\_camera\_color\_optical\_frame Broadcaster: /my\_gen3/robot\_state\_publisher Average rate: 40.201 Hz Most recent transform: 1757426769.583 ( 0.008 sec old) Buffer length: 4.975 sec half\_arm\_2\_link Broadcaster: /my gen3/robot state publisher Average rate: 40.201 Hz Most recent transform: 1757426769.583 (0.008 sec old) Buffer length: 4.975 sec forearm\_link Broadcaster: /my gen3/robot state publisher Average rate: 40.201 Hz Most recent transform: 1757426769.583 (0.008 sec old) Buffer length: 4.975 sec spherical\_wrist\_1\_link Broadcaster: /my\_gen3/robot state publisher Average rate: 40.201 Hz Most recent transform: 1757426769.583 ( 0.008 sec old) Buffer length: 4.975 sec spherical\_wrist\_2\_link Broadcaster: /my\_gen3/robot state publisher Average rate: 40.201 Hz Most recent transform: 1757426769.583 (0.008 sec old) Buffer length: 4.975 sec bracelet\_link Broadcaster: /my\_gen3/robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1757426769.591 sec old) Buffer length: 0.000 sec end effector link Broadcaster: /my\_gen3/robot state publisher Broadcaster: /my\_gen3/robot\_state\_publisher Average rate: 10000.000 Hz Broadcaster: /my gen3/robot state publisher Broadcaster: /my gen3/robot state publisher Broadcaster: /my\_gen3/robot\_state\_publisher Average rate: 10000.000 Hz

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