Importing Modules

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In [1]: import numpy as np
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Defining Methods

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In [4]: # Getting sliding window
        #img is the image and m is the size of window (eg 3x3, 5x5)
        def sliding window(img, kernel):
                 #make the loop for 3 and 5.
            s = img.shape[0]
            for i in range(int(kernel/2)):
                z = np.zeros([s,1])
                img = np.concatenate((z,img),axis=1)
                z = np.zeros([s,1])
                img = np.concatenate((img,z),axis=1)
                s = s+2
                z = np.zeros([1,s])
                img = np.concatenate((img,z),axis=0)
                z = np.zeros([1,s])
                img = np.concatenate((z,img),axis=0)
            window= []
            stepSize = 1
            w width = kernel
            w height = w width
            for x in range(0, img.shape[1] - w width +1, stepSize):
                for y in range(0, img.shape[0] - w height +1, stepSize):
                    window.append(img[x:x + w width, y:y + w height])
            window = np.array(window)
            return window
        #getting center pixel for every sliding window
        def get center pixel(window):
            x i = int(len(window)/2)
            return window[x i][x i]
        #getting mean of sliding window
        def getMean(window):
            return window.mean()
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#getting stdev of sliding window
def getStdev(window):
    return window.std()
def DVmean(arr,bw,tw):
    s = 0.0
    for i in arr:
        s += i
    return (s/((bw**2)-(tw**2)))
def DVstd(arr,bw,tw,mean):
    s = 0.0
    l = bw^{**}2 - tw^{**}2
    for i in range(l):
        if i > len(arr)-1:
            s += mean**2
        else:
            res = (arr[i] - mean)**2
            s += res
    return np.sqrt(s/(l-1))
#computing threshold for the sliding window
def DetectionVariable(window,arr,bw,tw):
    center_pixel = get_center_pixel(window)
    #print(center pixel)
    win mean = DVmean(arr,bw,tw)
    #win mean = getMean(window)
    #print(win mean)
    win stdev = DVstd(arr,bw,tw,win_mean)
    #win stdev = getStdev(window)
    #print(win stdev)
    return ((center_pixel-win_mean)/win_stdev)
#plotting binary image for the specific threshold.
#here img d always takes ndarray.
def shipDetection binaryImg(img d,threshold):
    for i in range(len(img d)):
        if img d[i] >= threshold:
            img d[i] = 1  #Valid ship
        else:
            img_d[i] = 0 #not a ship
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img_size = int(math.sqrt(len(img_d)))
    img_d_img = img_d.reshape(img size,img size)
    return img d img
#Computing the target window of size 3x3 and returning along with the
#background pixels
def get TargetWindow(img,bw,tw):
    s = []
    i = -int(tw/2)
    #print(i)
    for _ in range(tw):
        \#s = [img[int(bw/2)-1][int(bw/2)-1:int(bw/2)+2], img[int(bw/2)][int(bw/2)-1:int(bw/2)+2], img[int(bw/2)-1:int(bw/2)+2]
        s.append(img[int(bw/2)+i][int(bw/2)-int(tw/2):int(bw/2)+int(tw/2)+1])
        i += 1
    s = (np.array(s))
    background = []
    for z in imq:
        for t in z:
            if t in s:
                 pass
             else:
                 background.append(t)
    background = np.array(background)
    return [s,background]
def get GuardWindow(img,bw,gw):
    s = []
    i = -int(gw/2)
    #print(i)
    for _ in range(gw):
        \#s = [img[int(bw/2)-1][int(bw/2)-1:int(bw/2)+2], img[int(bw/2)][int(bw/2)-1:int(bw/2)+2], img[int(bw/2)-1:int(bw/2)+2]
        s.append(img[int(bw/2)+i][int(bw/2)-int(gw/2):int(bw/2)+int(gw/2)+1])
        i += 1
    s = (np.array(s))
    background = []
    for z in imq:
        for t in z:
             if t in s:
```

```
pass
                    else:
                        background.append(t)
            background = np.array(background)
            return [s,background]
        def noisePower(arr,bw,tw):
            s = 0.0
            for i in arr:
                s += i
            return (s/((bw**2)-(tw**2)))
        def scaleFactor(pfa,backgroundWindow size,targetWindow size):
            N = backgroundWindow size**2 - targetWindow size**2
            alpha = N*(pfa**(-1/N) -1)
            return alpha
In [2]: m = np.array(np.arange(100))
        m = m.reshape(10,10)
In [3]: m
Out[3]: array([[ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9],
               [10, 11, 12, 13, 14, 15, 16, 17, 18, 19],
               [20, 21, 22, 23, 24, 25, 26, 27, 28, 29],
               [30, 31, 32, 33, 34, 35, 36, 37, 38, 39],
               [40, 41, 42, 43, 44, 45, 46, 47, 48, 49],
               [50, 51, 52, 53, 54, 55, 56, 57, 58, 59],
               [60, 61, 62, 63, 64, 65, 66, 67, 68, 69],
               [70, 71, 72, 73, 74, 75, 76, 77, 78, 79],
               [80, 81, 82, 83, 84, 85, 86, 87, 88, 89],
               [90, 91, 92, 93, 94, 95, 96, 97, 98, 99]])
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In [6]: | guard, back = get GuardWindow(m, 10,5)
        guard
Out[6]: array([[33, 34, 35, 36, 37],
               [43, 44, 45, 46, 47],
               [53, 54, 55, 56, 57],
               [63, 64, 65, 66, 67],
               [73, 74, 75, 76, 77]])
In [7]: back
Out[7]: array([ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16,
               17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 38,
               39, 40, 41, 42, 48, 49, 50, 51, 52, 58, 59, 60, 61, 62, 68, 69, 70,
               71, 72, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92,
               93, 94, 95, 96, 97, 98, 99])
In [8]: | target, back2 = get_TargetWindow(guard, 5,3)
        target
Out[8]: array([[44, 45, 46],
               [54, 55, 56],
               [64, 65, 66]])
In [9]: back2
Out[9]: array([33, 34, 35, 36, 37, 43, 47, 53, 57, 63, 67, 73, 74, 75, 76, 77])
In [ ]:
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