

Knowledge and Retrieval

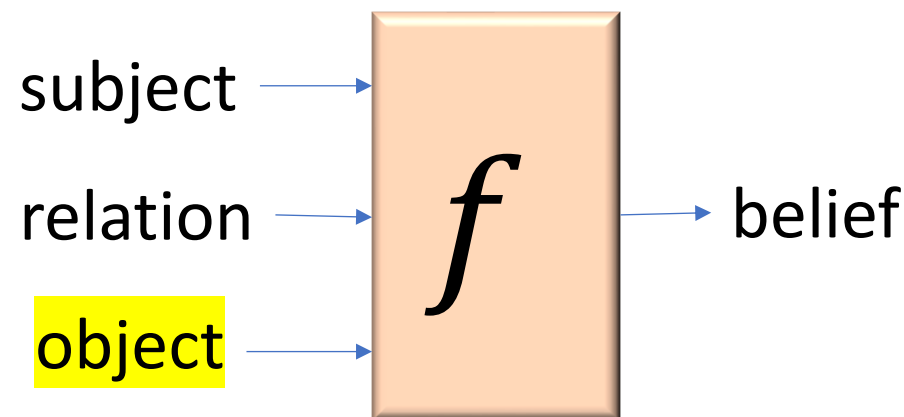
Knowledge Graph Completion and Evaluation

KG completion

- Incomplete KG provided
- Learning system fits embedding representations of entities and relations
 - Based on KG topology alone
 - Supplemented by text aliases
- Apply to KG and infer missing fact triples

Knowledge graph completion (KGC)

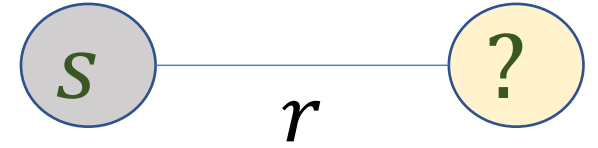
- Represent each entity e and relation r as continuous (geometric) artifacts \vec{e}, \vec{r}
 - Point, vector, displacement, projection, rotation, ...
- Design a scoring function f for the belief in a (subject, relation, object) triple
- Train entity and relation reps using known triples
- Infer unknown triples (aka “link prediction”)
- TransE, HtransE, DistMult, HolE, ComplEx, RotatE, ...



Initial notation

- Entity e , entity embedding \vec{e} or \mathbf{e}
- Entity can be subject s or object o
- With corresponding embeddings \mathbf{s} , \mathbf{o}
- Similarly, relation r has representation \mathbf{r}
- These embeddings may be vectors, matrices or tensors with real or complex elements
- $f(s, r, o) \in \mathbb{R}$ is a raw confidence score
- $(s, r, o) \in \text{KG}$ is a “positive” triple/fact,
 $(s', r', o') \notin \text{KG}$ is a “negative” triple/fact

From score to probability



- Softmax distribution

$$\Pr(\mathbf{o}|s, r) = \frac{\exp(f(s, r, o))}{\sum_{\mathbf{o}'} \exp(f(s, r, \mathbf{o}'))}$$

- Similarly, $\Pr(\mathbf{s}|r, o) = \frac{\exp(f(s, r, o))}{\sum_{\mathbf{s}'} \exp(f(\mathbf{s}', r, o))}$
- (Somehow, sampling \mathbf{r} is relatively rare)
- For $(s, r, o) \in \text{KG}$, want large $\Pr(o|s, r) \approx 1$ and large $\Pr(s|r, o) \approx 1$

Probability to loss function

- A common objective to maximize is

$$\sum_{(s,r,o) \in \text{KG}} \log \Pr(s|r, o) + \sum_{(s,r,o) \in \text{KG}} \log \Pr(o|s, r)$$

- Loss to minimize is negative of above
- Indirectly encourages small $f(s', r', o')$ for negative triples $\langle s', r', o' \rangle$
- Probabilities involve sums over *all* entities in KG (expensive)

Negative sampling

- Take positive fact (s, r, o) and replace s with a randomly sampled entity s'
- Resulting fact (s', r, o) unlikely to be positive
- Similarly sample o' to get (s, r, o')
- “Local closed world” assumption
 - Not really valid, given KG is (very) incomplete
- Helps replace full sum in denominator with sampled estimates

Uniform negative sampling

- Let $A = \sum_{o \in E} \exp(f(s, r, o))$ for fixed s, r
- Sample K out of E entities uniformly at random
- $\mathbb{E}[\sum_{o \in K} \exp(f(s, r, o))] = \frac{K}{E}A$
 - High variance, need fairly large K (thousands)
 - Under-sampling known to degrade accuracy
- In $\frac{\exp(f(s, r, o))}{\frac{E}{K} \sum_{o' \in K} \exp(f(s, r, o'))}$, must include o into denom by force, may further bias estimate

Discriminative training (à la SVM)

- For each positive fact (s, r, o) and each negative fact (s', r', o') , we want

$$f(s, r, o) \geq \text{margin} + f(s', r', o')$$

- Turn into hinge/ReLU loss

$$\max\{0, \text{margin} + f(s'_k, r, o'_k) - f(s, r, o)\}$$

- If there are E entities and R relations

- Number of possible facts is $E^2 R$
- Of which a small fraction is positive

Will use E , $|E|$ and R , $|R|$ interchangeably

- Infeasible number of constraints/loss terms
- Unnecessary for predicting one missing field in a fact triple, e.g., $(s, r, ?)$ or $(?, r, o)$

Sampling for discriminative training

- For each positive fact (s, r, o) in batch, sample K (presumed) negative facts (s'_k, r, o'_k)
- Accumulate to batch loss the average pair loss
$$\frac{1}{K} \sum_k \max\{0, \text{margin} + f(s'_k, r, o'_k) - f(s, r, o)\}$$
- If true f is \gg false f , loss term = 0
- Pairwise hinge/ReLU loss

Score polarity

- Thus far we have assumed
 - Large score $f(s, r, o)$ makes (s, r, o) more likely
 - Small score $f(s, r, o)$ makes (s, r, o) less likely
- Some models work with the opposite polarity
- Probability and losses can usually be adjusted without much trouble

Testing embedding and score quality

- KG completion task
 - KG sampled into train, dev, test folds
 - Given test queries $(s, r, ?)$ and $(?, r, o)$, trained system must provide **ranked list** for blanks
 - Mean (reciprocal) rank, hits@K
- **WN18**: 41k entities (WordNet synsets), 18 relation types (hypernymy, synonymy, . . .), folds 141k/5k/5k
- **FB15k**: 15k Freebase entities, 1345 relation types, folds 483k/50k/59k
- **WN18RR, FB15k-237, YAGO, ...**
- Other tasks (alignment, analogy, QA, ...)

Filtered evaluation

- Query $\langle s, r, ? \rangle$ with ranked system response list $(o_1, o_2, o_3, o_4, o_5, o_6, o_7, o_8, \dots)$
- Suppose o_6, o_8 are test fold gold answers
- $\text{MRR} = 1/6$, $\text{MAP} = \frac{1}{2}(1/6 + 2/8)$
- Suppose o_2 was a train fold gold answer
- Then $\text{MRR} = 1/5$, $\text{MAP} = \frac{1}{2}(1/5 + 2/7)$ is fairer
- A simple but important eval convention